Changes for the Better

FACTORY AUTOMATION

## Mitsubishi Electric Magnetic Starters MS-T/N Series



# GLOBAL IMPACT OF MITSUBISHI ELECTRIC 



Through Mitsubishi Electric's vision, "Changes for the Better" are possible for a brighter future.

## Changes for the Better

We bring together the best minds to create the best technologies. At Mitsubishi Electric, we understand that technology is the driving force of change in our lives. By bringing great-er comfort to daily life, maximizing the efficiency of businesses and keeping things running across society, we integrate technology and innovation to bring changes for the better.

Mitsubishi Electric is involved in many areas including the following

## Energy and Electric Systems

A wide range of power and electrical products from generators to large-scale displays.

## Electronic Devices

A wide portfolio of cutting-edge semiconductor devices for systems and products.

## Home Appliance

Dependable consumer products like air conditioners and home entertain-ment systems.

## Information and Communication Systems

Commercial and consumer-centric equipment, products and systems

Industrial Automation Systems
Maximizing productivity and efficiency with cutting-edge automation technology.

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## Line-up A Wide Variation that Suits User Needs



| MS-T/N Series Magnetic Starters/Contactors |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Delay Open Type |  | Magnetic Starters with Saturable Reactors and Thermal Overload Relays |  | Magnetic Starters with Quick-acting characteristics Thermal Overload Relays |  | Magnetic Starters with Push-Buttons |  |
| MSO/S-TロDL |  | MSO-T■KPSR |  | MSO-TDFSKP |  | 4 <br> MS-T $\square$ PM |  |
| MSO/S-N■DL |  | MSO-N $\square K P S R$ |  | $\text { MSO-N } \square K F$ |  | - |  |
| - By allowing retention of status for a few seconds (1 to 4 seconds) during a momentary power failure or a drop in voltage, there is no need for the magnetic contactors to reactivate when power returns, enabling continuous operation of load. - Applications Temporary Storage Circuits such as Automatic Control Devices |  | Prevents motor overload or restriction when starting time is long or starting current is large, as well as preventing unnecessary thermal overload relay operation. Can be used to protect intermittently operating motors. |  | Ideal for protecting motors with short time allowances for restriction, such as submersible motors or compressors. |  | Because the push-button is integrated with the magnetic starter, operation can be performed without the need for a separate push-button. |  |
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| Contactor Relays |  |  |  |  |  |  | Optional Units |
| DC Operated Type |  | Mechanically Latched Type | Delay Op | oen Type | With Wiring Streamlining Term |  | Failure Detection Units (Contact Welding Detection) |
|  |  | SRL-T <br> SRLD-T |  |  | SR/SRD |  | - |
| - |  | - |  |  | - |  | $\begin{gathered} \frac{46}{46} \\ \frac{46}{4} \end{gathered}$ |
| Can be used if the control circuit is DC. (Contact Areas can be used for both $A C$ and DC) | Beca main open stopp drops | ause it is mechanically intained, it does not in the case of power pages or voltage s. | - By allowing rete a few seconds ( during a momen or a drop in volt need for the con reactivate when enabling signals continuously. | ntion of status for 1 to 4 seconds) tary power failure age, there is no ntactor relay to power returns, to be transmitted | Designed to provide s during maintenance and inspection, for exampl allowing wiring operati be performed more ea by providing protectio electrical shocks with a protective cover, etc | ty y y to and anaint using | - Detects failures (contact welding) that occur to the main circuit contact of a magnetic starter when in conduction mode, and can be used to prevent the running away of load devices by interrupting the power supply by combining a non-fuse breaker or magnetic contactor. |
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| Application Based Name | Magnetic Contactors According to Application | Related Equipment |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Vacuum Magnetic Contactors | Solid State Contactors | Optional Units for Solid State Contactors | Electric Motor Protection Relays |  |
| External <br> Appearance of Representative Model | SH-V | पलक $\square$ <br> US-N <br> US-H | Drive Units with Outputs UA-SH <br> Drive Units UA-DR1 <br> Power Control Units UA-PC | ET-N |  |
| Application/ Function | - A large capacity magnetic contactor with a shut-off within a vacuum valve that does not arc and excellent safety. | A maintenance-free product ideal for applications in which high-frequency switching, long product lifetime, and quiet operation are a priority. Applications <br> - Facilities Such as Hotels or Cleanrooms For Heater Load Switching in Injection Molding Machinery etc. | The range of application is expanded by using in combination with a US-N or US-H Series solid state contactor. <br> Applications <br> UA-DR1: For Control When Using AC Control Circuits <br> UA-PC: For Electrical Control | An electric motor protection relay that can protect against overloads, restriction, and open phase during AC motor start-up or running, as well as detect reciprocal states. |  |
| Page | Page 259 | Page 306 | Page 323 | Page 340 |  |

Magnetic Starters/Contactors/Relays According to Application

| Magnetic Starters/Contactors/Relays According to Application |  |  |  |
| :---: | :---: | :---: | :---: |
| DC Interface Contactors | NC Main Contact Contactors | DC Contactors | Safety Contactors |
| SD-QR (Reversible) |  |  |  |
| Capable of being directly driven by the transistor output (DC24 V 0.1 A) of PLCs etc. | - Main circuit break contact (normally closed contact) can be used for motor control and power switching for lighting circuits. <br> - Applications <br> - For Motor Starting Resistance Shortcircuits - For Cushioned Starting of AC Motors | - Can be used for applications controlling DC motors at 440 V or less and other general DC circuits. <br> - Applications <br> - Variable Speed Motor Control <br> - For Dynamic Brakes | - Suitable for standard products in which the auxiliary break contact is a mirror contact. <br> Can be applied to mechanical safety category 4 circuits. (Can detect malfunction of break contacts) |
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## For Use in Various Industries

Our company's FA product line is employed in various industries manufacturing industry.


## familiar to customers, starting with the

## AutomobfleManufacturing Solutions



Mitsubishi Electric can provide an assortment of controllers and drivers that serve as accessory devices for magnetic starters and that are necessary for system structures, as well as other safety solutions related to these products.

## Contactors with Mirror Contacts

<Auxiliary Break Contact OFF During Main Contact Welding>

- Compliant with TÜV regulations for mirror contacts. Complies with requirements for "control functionality during failures" stipulated in the section "Electrical Devices of Industrial Equipment" in EN regulation EN60204-1 and can be used as an interlocking circuit contact.
(Refer to page 282 for certified models)
- Can be applied to mechanical safety category 4 circuits. (Can detect malfunction of break contacts)
- Features safety contactors and can be used to construct a
 completely safe system using a wide assortment of safe parts.


## Notes for adopting the product

## Before purchasing and using our products, please confirm the following product warranty.

## 1. Period and Scope of Warranty

- Warranty Period
(1) The warranty period for our products shall be one year after purchase or delivery to the designated location. However the maximum warranty period shall be 18 months after production, in consideration that the maximum length of distribution period is to be 6 months after shipping.
(2) This warranty period may not apply in the case where the use environment, use conditions, or the number of open/ close operation times specifically impact the lives of products.
- Scope of Warranty
(1) When any failure occurs during the above warranty period which is clearly our responsibility, we will replace or repair the failed portion of the product free of charge at the location of purchase or delivery. Note that the "failure" mentioned here shall not include such items as scratches and discoloration which do not affect performance.
(2) In the following cases, even during the warranty period, charged repair services shall be applied.
(1) Failures caused by inappropriate conditions, environment, handling, and uses other than those specified in catalogs, instruction manuals or specifications.
(2) Failures caused by inappropriate installation.
(3) Failures caused by the design of customer's equipment or software.
(4) Failures caused by the customer tampering with our products such as reworks without our authorization.
(5) Failures caused by the customer failing to correctly maintain or replace components such as spare parts, as specified by documents such as instruction manuals.
(6) Failures caused by uses of the product other than ordinarily intended.
(7) Failures caused by force majeure such as fire and abnormal voltage accidents, and natural disasters such as earthquake, wind and flood.
(8) Failures caused by reasons that were unforeseeable with the level of technology at the time of shipment.
(3) The warranty that is mentioned here shall mean warranty of the unit of delivery, and any losses induced by the failures of delivered products shall be excluded from our warranty.
- Failure Diagnosis

In principle, primary failure diagnosis shall be conducted by the customer. However this job, if requested by the customer, can be performed by us or by our service company with charge. In this case, a service fee shall be charged to the customer in accordance with our price list.

## 2. Recommendation for Renewal Due to Life

Our magnetic starters and magnetic contactors with contacts and mechanical parts have certain wear life in line with the number of switching operations, while our coil wires and electronic parts have aging degradation life influenced by the use environment and use conditions.
Regarding the use of the products described in this catalog, we recommend that customers replace the products when the number of open/close operations specified in this catalog or instruction manuals is reached or after 10 years of use, whichever comes earlier.
Reference: "Guidance for Replacement of Magnetic Starters and Magnetic Contactors" issued by the Japan Electrical Manufacturers' Association (JEMA)

## 3. Exemption from Warranty Related to Opportunity or Secondary Losses

Regardless of in or out of warranty period, loss of opportunity and lost earnings at the customer side caused by the failures of our products, any damages caused by special situations regardless of our potential foresight, secondary losses, accident compensation, damages to anything other than our products, compensation for jobs including replacement work, readjustment of field machinery equipment, startup test runs, etc. performed by the customer, and damages caused by any reasons for which we are not held responsible, shall be outside the scope of our compensation.

## 4. Applicable Range of Products

(1) The contents of products shown in this catalog are for your selection of models. When you actually use the product, read the "Instruction Manual" carefully beforehand and use correctly.
Please note that exterior views and/or specifications may change without notice, in no way affecting your product selection.
(2) When using a product listed in this catalog, you are constrained to conditions of use such that your applications will not lead to a serious accident even if the product develops a breakdown or failure, and that in the event of a breakdown or failure systematic backups and/or failsafe functions exist outside the device.
(3) The products described in this catalog are designed and manufactured as general products to be used for general industrial fields. For this reason, the products described in this catalog should not be used for applications requiring special quality assurance systems, such as atomic power plants and other power plants owned by power companies which seriously affect the public good, railway applications, and government and public office applications.
Note, however, that the products shall be applicable to such uses if the use is limited and the customer agrees not to require specially high quality.
Furthermore, when the customer is investigating application for the uses where serious impact is foreseen to the human body and assets and therefore high reliability for security and control system is required, such as aviation, medical services, railways, combustion and fuel equipment, manned transportation equipment, entertainment facilities and safety equipment, please contact our representatives and discuss any necessary agreement or specifications.

## 5. Supply Period of Spare Goods After Production Stop

(1) While we do not repair our company's magnetic starters or magnetic contactors, we can supply discontinued main contacts and coils as auxiliary parts for 7 years after their discontinuation (only for models that support auxiliary parts).
Please confirm with our company's sales office for details regarding supply availability.
(2) For the discontinuation of production, we will announce in such media as "sales and service" paper created by us.

## Notes for security related issues

- Before performing the installation, wiring works, operation and maintenance/check for the products described in this catalog, make sure to read the "Instruction Manual" or "Notes for Use" attached to the product for correct usage.
- Do not modify or disassemble the products listed in this catalog. There is a risk of breakdown.
- In spite of our continued efforts to enhance the quality and reliability of our product, the product can fail. The products described in this catalog can bring about serious results, such as malfunctions of machinery, short circuit at power supply, and catching fire), by the malfunction caused by vibration, physical shock and improper wiring. Pay special attention to avoid any secondary accidents such as injuries and fire, as the result of failures or malfunctions.
- When you find any questions or you need more details after reading this catalog, please contact your dealer or our company.
<For using the products described in this catalog, please observe the following items.>


## Danger

- Make sure to disconnect the power before you perform installation, removal, wiring works, or maintenance/checking. There is a risk of receiving an electric shock or occurrence of a malfunction.
- When the product is energized, avoid touching or coming near the product, especially the terminals having electricity. There is a risk of receiving an electric shock or burn injury.
- Prevent wire ends from coming loose. If bare wires come in contact with each other, a phase-to-phase short circuit may occur.


## $\triangle$ Notes

- Use the product in the use environment described in this catalog and Instruction Manual. Do not install the product in any abnormal environment with high temperature, high humidity, dust, corrosive gas or excessive vibration/shock. There is a risk of catching fire, malfunctions, electric shock or failure.
- Avoid applying shocks by dropping or falling the product during transportation and unpacking. This will lead to breakage or failure of products.
- Do not use the product when it has received damage during transportation, installation or wiring. This can cause fire or malfunctions.


## $\triangle$ Notes

- Make sure that only technicians qualified for electric work or wiring should perform installation, wiring works and maintenance/checking of the product.
- Make sure that no foreign objects such as dust, iron powder and wire chips enter the product during installation and wiring works. There is a risk of contact failures and malfunctions leading to damage or fire at the load.
- When you use mounting screws of the wrong size or use a small number of screws than specified, or when the mounting to the rail of IEC 35 mm width is defective, there is a risk that the product may fall.
- When you apply wiring works, be sure to use the wire size that suits the applied voltage, flow current and inrush current, and to fasten wires with the correct torque as specified in this catalog or the instruction manual. Defective wiring can cause fires, accidents and failures.
- To terminal screws and mounting screws, apply the torque as we specify for tightening, and regularly apply retorquing. When the tightening torque is too large, the work can damage terminal screws or mounting screws. When the terminal screws or mounting screws slacken or are broken, they can cause overheat or fire, or the body can fall off to create serious accidents.
- Confirm the rated values and specifications, and make sure to use a product that meets the requirements. When you use a product exceeding the rated/specified values, it may cause insulation breakdown leading to earth fault or short circuit accidents, or create the cause of fire by overheat or breakdown due to inability to shutdown.
- When a product described in this catalog is to be used in a facility where a failure can lead to injury to the human body or serious damage to earnings, make sure to install some safety mechanism.
- Apply regular checks to the product and use safety measures on the sequence to the critical circuits. The contacts of Contactors and Magnetic Starters can develop defective conduction, welding or burnout.
- Contactors and Magnetic Starters can create welding of contacts disabling the opening, due to such causes as switching operation for excessive current, abnormal wearing of contacts, chattering at operational instruction contacts, aging degradation and product life. Also the contacts may fail to open due to unexpected mechanical constraints other than contact adhesion. Since the disability of contact to open can cause the machine to go out of control, secure safety by assuming the mechanical constraints or contact welding leading to inability of open/ close operations. There remains a risk of fire even when an overload protective device (Thermal Overload Relays) is provided.
- The example connection described in this catalog only shows a typical one to run a system. For the protection of each device and safety measures, the customer is requested to consider the connection for each system.
- Do not apply reworks to the product or disassemble the product. These may cause failures.
- When you dispose of the products, treat them as industrial waste products.
<For using the products with spring clamp terminals, observe the following rules as well.>


## $\triangle$ Notes

- Keep enough spaces around the product more than shown in this document. Failure to keep it may result in electric shock or burn.
- Connect according to the wire type.
(a)Solid wire: Insert wire in straight till the core wire hits the bottom.
(b)Ferrule: Insert wire in straight till ferrule hits the bottom. Please confirm that the sleeve should be inside A-side when it's sleeve.
(c)Strand wire: Insert applicable operating tool in insertion slot. Then insert wire and remove applicable operating tool after opening spring.
- Please confirm wire connection by pulling wire lightly after inserting wire.
- Do not use any other tools except for the applicable when inserting wire. May cause damage to the equipment.
- Use the specified wire, ferrule, and crimp tool.
- Do not insert multiple wires in a insertion slot. May cause damage to the equipment.
- Please contact us if you might use other type of wires.
- Do not insert electroscope into other insertion. May cause damage to the equipment.
- Please confirm peeled length of wire. Watch out wire loosing. May cause poor connection, which leads to abnormal heating and fire disaster.
- Do not use any other wires expect for copper wire. May cause abnormal heating and fire disaster.
- Use operating tool properly. May cause damage to the equipment.
- Do not forcibly bend or pull the wire in the side direction of the circuit breaker. May cause damage to the equipment.
- Please insert operating tool sideways. May cause damage to the equipment.
- Please use applicable operating tool for connecting wire when solid wire or strand wire is hard-plug.


## Features

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## MS-T Series Introduction

## Down-sizing

## $\square$

 mall
## 10A frame model is over $16 \%$ smaller with a width of just 36 mm !!

There is a saying that "every bit helps" and now with the industries smallest* general purpose Magnetic Contactor in its class, customers are able to more easily down-size their boards than ever before.
*For AC-operated 10A frame class general-purpose Magnetic Contactor (based on survey conducted by Mitsubishi dated September 2016)


Example: Status where 5 units are arranged

(For mounting details, refer to "Mounting" on page 64)
 structure and arc runner shape streamline the outline dimensions!!

Traditional MS-N Series

<AC Operated Type>

Frame Size
<DC Operated Type>

| Frame Size |  | 13A |  | 18A | 20A | 32A |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Traditional MS-N Series | Front View |  |  | None |  | None |
| New slimline MS-T Series | Front View |  |  |  |  |  |


| Frame Size |  | 35A | 50A | 65A | 80A | 100A |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Traditional MS-N Series | Front View |  |  |  |  |  |
| New slimline MS-T Series | Front View |  |  |  |  |  |

## MS-T Series Introduction

## Standardization

## tandardiza ed terminal covers

## New integrated terminal covers <br> Target Frames: 10 A to 50 A Frame

The perennial issues of remembering to order the terminal covers, fitting them correctly or loosing them in the process are challenges of the past. The integrated terminal cover system means they are always there, on the Magnetic Contactor or its Auxiliary contact, ready to be used.


## Reduce your coil inventory by up to 50\%

Target Frames: 10 A to 35 A Frame
The 13 types of operation coil ratings available with the SN Series have been halved to 7 types with that increasing the applicable voltage range. Users can reduce their inventory, and by integrating the types of coils manufactured, a shorter delivery can be realized.

| Coil designation | Rated Voltage [V] |  |
| :--- | :---: | :---: |
|  | 50 Hz | 60 Hz |
| AC24V | 24 | 24 |
| AC48V | 48 to 50 | 48 to 50 |
| AC100V | 100 | 100 to 110 |
| AC120V | 110 to 120 | 115 to 120 |
| AC127V | 125 to 127 | 127 |
| AC200V | 200 | 200 to 220 |
| AC220V | 208 to 220 | 220 |
| AC230V | 220 to 240 | 230 to 240 |
| AC260V | 240 to 260 | 260 to 280 |
| AC380V | 346 to 380 | 380 |
| AC400V | 380 to 415 | 400 to 440 |
| AC440V | 415 to 440 | 460 to 480 |
| AC500V | 500 | 500 to 550 |


| Coil designation |
| :--- |
|  |
|  |
| RC24V |
|  |
| AC48V |
| AC100V |
| AC200V |
| AC300V |
| AC400V |
| AC500V | | * The conventional 78 to 50 |
| :---: |
| the 50A and larger frames. |

By integrating the electromagnetic field analysis and drive analysis, inconsistency in the electromagnetic attraction force is suppressed and rise of the coil temperature is reduced.


Capable of direct drive with transistor output of PLC, etc Target Frames. 13 Ato 32 A Frame $* D C$ opeated Modeds
The adopted high-efficiency polarized electromagnet greatly reduces the coil power consumption, and enables all models to be directly driven with a DC24 V, 0.1 A rating transistor output. (DC24V coil)

| 13 A Frame <br> (Coil: DC12/24V) | Traditional Model | New Model | Lowering Rate |
| :---: | :---: | :---: | :---: |
| 20 A Frame <br> (Coil: DC12/24V) | 9 W | 2.2 W | $69 \%$ |
| $32 ~ A ~ F r a m e ~$ <br> (Coil: DC12/24V) | - | 2.2 W | $76 \%$ |



* DC48V to 220V: 3.3 W. ©afety \& Quality


## Terminal Covers with Finger Protection Function

Target Frames: 10 A to 50 A Frame
In addition to the Magnetic Contactor, a terminal cover has been provided as a standard for the thermal, magnetic relay and auxiliary contact unit options. This realizes a finger protection function that complies with the DIN and VDE Standards, prevents electric shocks, and increases safety during maintenance and inspections.

## [Finger Protection]

In the provisions regarding worker safety and accident protection during use of low-voltage switchgear and controlgear assemblies set forth with DIN EN 50274/NDE 0660 Teil 514, the range for providing protection against contact of live sections is divided into "Finger Safe (preventing
 finger contact)" and "Back of hand safe (protecting back of hand contact), and standards are provided. The MS-T Series terminal cover satisfies the requirements of these provisions.

## Smart Wiring

## Smart Design Means Smart Wiring

The integrated terminal covers have an additional benefit in that they act as a guide to improve wiring efficiency but also retain the terminal screw in place: no mislaying the screw, no dropping it or having trouble reinserting it in to the terminal block just fast efficient wiring. Fast wiring terminals (model name with suffix "BC" ) are also available to further improve wiring efficiency, workability and hence productivity.


## MS-T Series Introduction

## Easy branch circuit wiring with Motor Circuit Breaker and optional connection conductor unit.

```
Target Frames: 10 A to 32 A Frame
```

Easy wiring is available for the new MS-T Series by using the Motor Circuit Breaker and optional connection conductor unit, contributing your productivity improvement.


## Global Standard

 tandard

## Complies with main International Standards

In addition to certification for use under various countries' standards such as IEC, JIS, UL, CE and CCC, etc., plans are also underway to obtain certification for the standards of other countries.
We aim to contribute to helping customers expand their overseas business.

| Standards | Applicable standard |  |  |  |  | Safety Certification Standard |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | International | Japan | European countries |  | China | U.S. \& Canada |
|  | EC | J.S | EN | Certifying Body | GB | cUus |
|  |  |  | EC Directive |  |  |  |
|  |  |  |  | TÜV Rheinland |  |  |

Note: Compliant with the requirements for mirror contacts in standards such as IEC60947-4-1, and TÜV-certified.

## Higher SCCR values achieved by using with motor circuit breaker.

When the MMP-T Series and the S-T Series are used together, a higher SCCR (UL short-circuit current rating) value can be achieved. This will be a great support for your business in North America.


* Only applicable to the MMP-T series that bear the UL mark. (Refer to page 362 .)


## An Extensive Line of MS-T Series Optional Units

## A Wide Selection of Optional Units

- We offer a wide range of optional units, including auxiliary contact units and surge absorber units, etc.

Application ranges can be expandedby combining with optional units. (The photo shown is just one example of a possible combination.)


## MS-T Series with Spring Clamp Terminals

## Just insert solid wires or ferrules into terminals for wiring! No terminal screws are required, which makes wiring quicker and easier.

No special tools are required. The wiring requires only a flathead screwdriver (manufactured to DIN 5264 standard). Not only ferrules but also stripped solid wires and stranded wires can be directly connected to the terminals. No worry about screw dropping or unfastened screws.


## Significantly Shorter Wiring Time

Comparison with the terminal screw model
(with round crimp terminal)
Wiring with ferrules: Reduced by $22 \%$
Wiring with solid or stranded wire: Reduced by 52\%
*Wiring performed by non-experts (with 2-year experience) (The research conducted by Japan Switchboard \& control system Industries Association)

## Easy Wiring For Whoever Works On

For screw-type wiring, the tightening torque is different from worker to worker, and the same worker does not necessarily tighten screws with the same torque at all times.
However, spring clamp terminals make wiring easy and reliable even for non-experts.

## Less Maintenance

Excellent electrical characteristics can be maintained stably for a long period of time.
The wiring is highly resistant to vibrations and impacts, reducing maintenance labor.
For example, screw tightening is not required at the time of delivery or inspection of the panel or the mechanical system. Products and equipment can be more reliable, reducing the total cost.

## Product line and features

12A and 20A magnetic contactors and contactor relays are available.
AC operated models and DC operated models with low voltage inputs can also be manufactured.
Magnetic contactors: Page 125, Contactor relays: Page 175



## Wiring Features

Elemental wires can be connected directly.


For disconnection of a wire, insert a tool straight into a tool insertion opening on a magnetic contactor/magnetic relay and pull out the wire.


Insert the tool fully into the tool insertion opening.


Pull out the wire.

- Providing the electroscope insertion openings prevents come-off of wires during continuity check.



## Other Features

Whether to use an IEC rail or screws for installation are selectable.

The spring clamp model has almost the same size as the former product. (A 1.7 mm increase in height) * The installation size remains the same.


Solid wires and ferrules can be connected simply by inserting them into the terminals without using any tools


Providing two wire insertion openings for per wiring enables crossover wiring.

Providing the wire holders for control and auxiliary terminals* prevents fall-off of mark tubes.


* The magnetic relays have the wire holders for the outermost poles.


## WAGO PUSH-IN CAGE CLAMP®

* Spring clamp terminals:PUSH-IN CAGE CLAMP® manufactured by WAGO Kontakttechnik GmbH \& Co. KG, Germany



## PUSH-IN CAGE CLAMP®

The wire protrusion is reduced.
The spring clamp terminals have an inclination of about 15 degrees to the front surface of the product, which reduces the protrusion of wires and makes the wiring in the panel neat.
Tools can be inserted straight into the terminals, which makes it easier to connect and disconnect wires.


## MS-N Series Magnetic Contactors

## 125 to 800 A Frame

## Live Part Protection Covers for Finger Protection (125 to 400 A Frame, Optional)

- Attention has been paid to safety in order to provide live part protection covers that offer finger protection and that are easy to handle.
- Various types are offered including those for magnetic contactors, magnetic starters, reversible magnetic contactors, and reversible magnetic starters, etc.
- Installation and removal can be easily performed with one touch.



## Arc Space of Zero Realized <br> (125 to 800 A frame)

- Safety and a long product life have been guaranteed by combining the current capacities of each magnetic contactor to form an ideal arc-suppression structure that effectively interrupts current. Also, by employing HGC arc-suppression ${ }^{(*)}$, an arc space of " 0 " can be achieved, resulting in further improvements to safety and space-saving.
Even in overcurrent interruption conditions (interruptions at 13 times the rated operating current) or short-circuit conditions, the arc space dimensions prevent arc touching for safety.
*HGC (Hot Gas Control) arc suppression method refers to a high-speed arc suppression method that provides control over arc discharge direction, as well as superior interrupting performance.



## $\square$ Realizing Space Saving

OAdoption of HGC Arc Suppression Method

- Because arc space has been reduced to zero by adopting HGC arc suppression, downsizing of control panels has been achieved.
- Required Panel Dimensions for AC

Operated Magnetic Contactor (Depth)

| 0 mm | 100 mm | 150 mm | 200 mm | 250 mm |
| :---: | :---: | :---: | :---: | :---: |
| 125 Frame |  | 88\% |  | : MS-N |
| 150 Frame |  | 89\% |  | : MS-K |
| 180/220 Frame |  | 90\% |  |  |
| 300/400 Frame |  |  | 84\% |  |

- Arc Suppression Structure (HGC Arc Suppression Method)



## A Brightened Board Interior

[^0]$\square$ Featuring an AC Operated DC Excitation Type Magnet
(MS-T Series T65 to T100 also used)

## - Prevention of Buzzing

- Because DC excitation is used, there is no worry that magnetic buzzing sounds will be generated.
Coils that Do Not Give Off Switching Surges
- Because a surge absorber function is built-in, coil switching surges are not generated.
- This simple circuit provides excellent reliability.
- Ultra-wide Dual Rated Coil
- The rated voltage range has been expanded, resulting in the number of coil types being reduced to a third. The mechanical switching durability within the rated voltage range is 5 million cycles.
- Coils Resistant to Voltage Drops
- Because the standard product is a low-voltage compensation type coil (operating will continue without interference even if voltage drops to $65 \%$ of rating during contact (first 1 to 2 cycles)), it has been made resistant to voltage drops.


## Low Power Consumption Coils

- Low power consumption has been realized by adopting an AC operated DC excitation magnet coil.

(Representative operation coil circuit diagram)

| Designation | Rating |
| :--- | :---: |
| AC100V | 100 to $127 \mathrm{~V} 50 / 60 \mathrm{~Hz}$ |
| AC200V | 200 to $240 \mathrm{~V} 50 / 60 \mathrm{~Hz}$ |
| AC300V | 260 to $350 \mathrm{~V} 50 / 60 \mathrm{~Hz}$ |
| AC400V | 380 to $440 \mathrm{~V} 50 / 60 \mathrm{~Hz}$ |
| AC500V | 460 to $550 \mathrm{~V} 50 / 60 \mathrm{~Hz}$ |

We also manufacture those with AC24V and AC48V ratings. (N125, N150)


## SD-Q Series DC Interface Contactors

## Support for Direct Drive Using PLC Transistor Output



SD-Q11 Type
Direct Drive of Contactors Using Semiconductor Output (Transistor Output) Can drive a direct DC interface contactor using DC24 V transistor output without use of an intermediate relay.

Wide Range of Types

| SD-Q11 | AC200V | 2.5 kW | $1 \mathrm{a}(1 \mathrm{~b})$ | Non-Reversible Type |
| :---: | :---: | :--- | :--- | :--- |
| SD-QR11 | AC200V | 2.5 kW | $1 \mathrm{~b} \times 2$ | Reversible Type |
| SD-Q12 | AC200V | 2.5 kW | $1 \mathrm{a} 1 \mathrm{~b}(2 \mathrm{a})$ | Non-Reversible Type |
| SD-QR12 | AC200V | 2.5 kW | $1 \mathrm{a} 1 \mathrm{~b} \times 2$ | Reversible Type |

Can be manufactured with a thermal overload relay (model name: MSOD-Q(R) $\square$ ).
■ An Extensive Line of Installable Optional Units Features auxiliary contact units and a display window.

■ Surge Absorber Comes Standard Built-in Because the built-in surge absorber function controls surge voltage, it serves to prevent the negative effects of surge voltage at coil OFF, such as damage to peripheral devices.


Realizing Large Capacity and Long Product Life Because conventional free air thermal current (rated continuity current) has increased, these are only used for circuit current (for current switching of inverters, servos, etc.). Also, they can be applied to AC440 V circuits despite their compact size.

| Model Name | Rated Capacity (kW) AC-3 |  | Free Air Thermal Current <br> (A) | $\begin{aligned} & \hline \text { Electrical } \\ & \text { Durability } \\ & (\times 10000) \\ & \hline \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: |
|  | 200 to 240 V | 380 to 440 V |  |  |
| SD-Q11/Q12 | 2.5 | 4 | 20 | 100 |

■ Minimal Load for Auxiliary Contacts DC5 V 3 mA By doubling the auxiliary contacts, support for levels as low as DC5 V 3 mA has been made possible. (The failure ratio in normal environments free of dust or corrosive gas is $5 \times 10^{-7} /$ cycle.)

■ Rail Mounting Standardized
Can be mounted on an IEC and DIN regulation compliant 35 mm width rail.

■ Provides Support for a Large Number of International Standards

| Model | Model Name | Applicable Standard |  |  |  | Safety Certified Standard |  | EC Directives <br> CE <br> Mark | $\begin{array}{\|c\|} \hline \text { Certifying Body } \\ \hline \text { TÜV } \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline \text { CCC Certification } \\ \hline \text { GB } \\ \hline \end{array}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\begin{gathered} \hline \text { JIS*1 } \\ \text { JEM } \end{gathered}$ | IEC | DIN <br> VDE <br> Germany | $\begin{aligned} & \mathrm{BS} \\ & \mathrm{EN} \\ & \hline \end{aligned}$ | UL | CSA |  |  |  |
|  |  | Japan |  |  | United | US | Canada | Europe | Germany | China |
|  |  |  |  |  | Kingdom Europe |  |  | $C \in$ | $\triangle$ | (CC) |
| Magnetic Contactors | $\begin{aligned} & \hline \text { SD-Q11, Q12 } \\ & \text { SD-QR11, QR12 } \end{aligned}$ | ( | ( | ( $)$ | ( | ( | ( | ( $)$ | ( $)$ | ( |
| Magnetic Starters | $\begin{aligned} & \text { MSOD-Q11 (BC) KP, Q12 (BC) KP } \\ & \text { MSOD-QR11 (BC) KP, QR12 (BC) KP } \end{aligned}$ | ( $)$ | ( $)$ | ( $)$ | (0) | ( | ( $)$ | ( $)$ | ( $)$ | ( ) |

Note 1 © : Standard product that conforms, is compliant, or for which certification has been obtained
Note $2 \boldsymbol{*}$ 1: If JIS conformity declaration is required, please request.

## US-N and US-H Series Solfd State Contactors

## Maintenance-Free and Noiseless

US-N $\square$ Model Solid State Contactors for Motor/Heater Loads (5 A Frame to 200 A Frame)


High-Frequency Switching and Maintenance-Free No parts subject to electrical or mechanical wear, making them maintenance-free and ideal for use in high-frequency switching (motors, heaters, lighting, condenser switching, etc.).

- Noiseless and Clean Running Can be used comfortably without sound for applications in which switching sounds would be a nuisance (hotels, hospitals, offices, cleanrooms, etc.).
$\square$ Applicable for a Wide Range of Main Circuit Voltages (US-N20 (TE) to N50(TE))
Can be used for a wide range (AC100 to 480 V ) of main circuit voltages.
- Provides Support for a Large Number of International Standards (US-N Series) Our standard products comply with the domestic standards as well as various overseas standards and are certified to meet all the standards.

■ Live Part Protection Covers Provided as Standard Equipment for Improved Safety (US-N Series)
In order to improve safety, live part protection covers with finger protection functionality and compliance with DIN and VDE regulations have been made standard equipment.

- A Wide Range of Types and an Expanded Series <Heater Load>
-2-circuit, 3-circuit Integrated Type
- Cycle Control Type Voltage Adjusters
<Motor Load>
-2-circuit, 3-circuit Integrated Type
<Current Frame>
AC200 V 5 A to 200 A Frame
AC400 V 20 A to 200 A Frame
DC24 to 110 V 8 A Frame

US-H $\square$ Solid State Contactors for Heater Load (20 A Frame to 50 A Frame)


US-H2O Type


US-H40DD Type


US-H2OHZ Type

Ideal for Heater Loads
Ideal for high-frequency switching heater applications, such as injection molding machines or semiconductor manufacturing equipment, etc.

- Applicable for a Wide Range of Main Circuit Voltages Can be used for a wide range (AC24 to 480 V ) of main circuit voltages.
$\square$ Provides Support for a Large Number of International Standards
Our standard products comply with the domestic standards as well as various overseas standards and are certified to meet all the standards.

Display Window for Confirmation of Operation Standardized With indicator lamps on the front surface, the operating voltage input status can be checked at a glance.
$\square$ Realizes a Long Product Lifetime When Used for High-frequency Switching Applications Realizes a long product lifetime when used for high-frequency Switching applications by using a power semiconductor device.

- Live Part Protection Cover can be Mounted for Improved Safety After control panel mounting, a live part protection cover (option: UN-CV501US) can be easily mounted for improved safety.


## MS-T/N Series Specification List

|  | 2.5/11 [2.2/11] | 3.5/13 [2.7/13] | 4.5/18 [3.7/18] | 5.5/25 [4(3.7)/20] | [7.5/30(26) [5.5/26] | 7.5/32 [7.5/32] | 11/40 [7.5/35] | 15/55 (50) [11/50] | 18.5/65 [15/65] |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 4/9 [2.7/7] | 5.5/12 [4/9] | 7.5/18 [7.5/18] | 11/23 [7.5/20] | 15/30(26) [11/25] | 15/32 [15/32] | 18.5/40 [15/32] | 22/50 [22/48] | 30/65 [30/65] |  |
|  | 4/7 [2.7/6] | 5.5/9 [5.5/9] | 7.5/17 [7.5/17] | 11/17 [7.5/17] | 15/24 [11/20] | 15/24 [11/20] | 18.5/32 [15/26] | 25/38 [22/38] | 37/60 [30/45] |  |
|  | 4/5 | 5.5/7 | 7.5/9 | 7.5/9 | 11/12 | 11/12 | 15/17 | 22/26 | 30/38 |  |
| O Convenional |  | 20 |  |  | 32 |  | 60 | 80 | 100 |  |
|  | 1 a | 1 a |  |  | 2b | - | 2a2b | 2a2b | 2a2b |  |
| MS-T/N Type <br> Enclosed <br> Magnetic <br> Starters |  |  | - | MS-T21 | - | - | $\square$ | $\square$ <br> MS-T50 | MS-T65 |  |
| MSO-T/N <br> Type <br> Open <br> Magnetic <br> Starters |  |  |  |  |  | - |  |  | MSO-T65 |  |
| S-T/N Type Magnetic Contactors |  |  |  |  |  | $\begin{gathered} \text { S-T32 } \\ \text { S-T32BC } \end{gathered}$ |  |  |  |  |
| TH-T/N Type Thermal Overload Relays |  |  |  |  | TH-T25(BC) TH-T25(BC)KP |  |  |  |  |  |
| Current Range of Themal Overload Relays [ $A$ ] | 0.1 to 11 | 0.1 to 13 | 0.1 to 18 | 0.2 to 18 | 0.2 to 26 | - | 0.2 to 34 | 0.2 to 50 | 12 to 65 |  |
| Electromagnetic Method |  |  |  | AC Operation/ | /AC Excitation |  |  |  |  |  |
| IEC 35 mm Rail Mounting |  |  |  |  |  |  |  |  |  |  |
| Applicable to AC690 V |  |  |  |  |  |  |  |  |  |  |
| Surge Absorber |  | Externally | y Mounted Un | nits (Model nam | es with "SA" a | are externally m | mounted.) |  |  |  |
| Auxiliay Twin Contacts |  |  |  |  |  |  |  |  |  |  |
| \% DC Operated |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |
| 錇Delayed Release |  |  |  |  |  |  |  |  |  |  |

Note 1. The value in parentheses for the rated operating current is applicable in the case of magnetic contactors.
Note 2. $\square, \square, \square$ stand for "manufactured range", while $\square$ stands for "outside manufactured range".
Note 3. "BC" in the model name refers to "wiring streamlining terminal".
Note 4. The value in parentheses for the motor capacity is applicable in the case of enclosed magnetic starters.

Note 5. Mechanically latched types and delay open types have differing auxiliary contact arrangements.
Refer to page 102 for details about mechanically latched types, or page 111 for delay open types.
Note 6. Because there are products that cannot be mounted, please refer to combination details on page 192 when applying optional products.

## Magnetic Starters, Magnetic Contactors, Thermal Overload Relays



## Introducing MMP-T

What is a motor circuit breaker?
This is a product that integrates a low voltage circuit breaker with thermal overload relay functionality and can be applied to motor circuits. One unit provides protection from overloads, open phase, and short-circuits.


Featuring a Space-saving Design that Results in Downsized Panels Example of Space Saving Application

## Wire Saving

When wiring the motor circuit breaker and contactor, the number of wiring processes can be reduced by using a connecting conductor unit (optional). We also offer a DC interface contactor (SD-Q) and connecting conductor unit (model name: UT-MQ12), as well as a DC operated compact model (SD-T) and connecting conductor (model name: UT-MT20D).

## Ease-of-Use

A wide range of optional units is offered.
This is in order to satisfy the various usage applications of our customers.


Example of Application of Wire Saving
Example of Wiring in Electric Wires



Usage Example
With UT-MQ12

| Number | Product Name | Model Name | Speciricitions | Description |
| :---: | :---: | :---: | :---: | :---: |
| (1) | Auxiliary Contact (Interior) | UT-MAX | 1 l | The contacts of this unit operate in unison with the turning ON/OFF of the main unit. |
|  |  | UT-MAXLLFFor | 1 a |  |
|  |  | Very Small Loads) | 1 b |  |
| (2) | Alarm Contact (Interior) | UT-MAL | 1 a | The contacts of this unit operate (either short-circuits, overloads, open-phase) in unison with the trip operation of the main unit. |
|  |  |  | 1b |  |
|  |  | UT-MALLL(For | 1a |  |
| (3) | Power Supply Block | UT-EP3 |  | This is a terminal block unit that can enable the wiring of bare wires (single core wire/ stranded wire) on the power supply side if the unit is connected in parallel with a bus bar. |
| (4) | Bus Bar | UT-2B4 | $\frac{45 \mathrm{~mm} \text { Clearance }}{\text { Row of }}$ | A unit that can supply power (parallel connection) to 2 or 3 units individually without use of electric wire. |
|  |  | UT-3B4 | 45 mmClearanc |  |
|  |  |  | Row of 3 |  |
|  |  | UT-2B5 | Row of 2 |  |
|  |  | UT-3B5 | $57 \mathrm{~mm} \text { Clearance }$ |  |
| (5) | Power Side Terminal Cover | UT-CV3 |  | Power side terminal cover for UL60947-4-1A, Type E/F. |
| (6) | Short-circuit Display Unit | UT-TU |  | A unit that operates and displays in red only when the unit trips due to a short circuit. Necessary for application to UL60947-4-1A, Type E/F. |
| (7) | Connecting Conductor Unit | UT-MT20 |  | Unit for electrically and mechanically connecting MMP-T32 and a magnetic contactor. |
|  |  | UT-MT32 |  |  |
|  |  | UT-MT20D |  |  |
|  |  | UT-MT32D |  |  |
| (8) | Mounting Base Unit | UT-BT20 |  | Plate for mounting a combination starter by combining MMP-T32 and a magnetic contactor. Can be rail mounted or screw mounted. |
|  |  | UT-BT32D |  |  |
| (9) | Mounting Base Unit | UT-BT32DMP |  |  |
| (10) | Jointing Block Unit | UT-RT10 |  | A block that connects the 2 mounting base units mechanically. |
|  |  | UT-RT20 |  |  |
| (11) | Jointing Block Unit | UT-RT32DMP |  |  |

*For combination model names, please refer to the outline drawings on page 371
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## Selection and Application

### 2.1 Model List



Note 1. The figure in the square brackets indicates the rated current shown on the rating plate of the product at which the category AC-3 opening/closing durability. Note 2. The value between parentheses for the rated operating current is for the magnetic starter (with thermal overload relay).
Note 3. AC operated types T10 to T50, DC operated types T12 to T50 can be manufactured with coil surge absorber ( $\square-\square$ SA type). The UT-SA21 type can be mounted. Note 4. T65 to N800 types have an integrated coil surge absorber rendering a coil surge absorber unit for prevention of coil switching surges unnecessary.
Note 5. 1 million times for T20 class AC-3 380 V or more types for the rating in parentheses and 15,000 times for class AC-4 types. 15 thousand times for T35 to N800 class AC-4 380 V or more types. Note 6. Values are for the ratings in square brackets. The electrical durability for the current values not in parentheses varies inversely with the rough square of the current. Note 7. Mechanically latched types and delay open types have differing auxiliary contact arrangements. Refer to page 102 for details about mechanically latched types, or page 111 for delay open types.


Note 8. The +2 b on the auxiliary contact arrangement of reversible T10 to T20 types indicates the break contact of the integrated UT-ML20 interlock unit. There is no need to specify when ordering.
Note 9. Auxiliary contact arrangements for reversible types are displayed by twos, in a contact arrangement combined with two magnetic contactors. For standard contact arrangements there is no need to specify whe ordering; however, please specify a matching contact arrangement for 2 units if for a special configuration. <Example> For $1 \mathrm{~b} \times 2+2 \mathrm{~b}$ : 2 B
Note 10. Because there are products that cannot be mounted, please refer to combination details on page 192 when applying optional products
Note 11. Not applicable to AC operated types produced before March, 2019.

## 2 <br> Selection and Application

### 2.2 Manufacturing Range List

## - Non-Reversible Type

| Frame |  |  |  | T10 | T12 | T20 | T21 | T25 | T32 | T35 | T50 | T65 | T80 | T100 | N125 | N150 | N180 | N220 | N300 | N400 | N600 | N800 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Category AC-3 <br> Rated Capacity [kW] |  |  |  | 2.5 | 3.5 | 4.5 | 5.5 | 7.5 | 7.5 | 11 | 15 | 18.5 | 22 | 30 | 37 | 45 | 55 | 75 | 90 | 125 | 190 | 220 |
|  |  |  |  | 4 | 5.5 | 7.5 | 11 | 15 | 15 | 18.5 | 22 | 30 | 45 | 55 | 60 | 75 | 90 | 132 | 160 | 220 | 330 | 440 |
|  |  | xiliary C | tact Standard | 1 a | 1a1b | 1a1b | $\leftarrow 2 \mathrm{a} 2 \mathrm{~b} \rightarrow$ |  | - | 2 a 2 b |  |  |  |  |  |  |  |  |  |  |  |  |
|  | del Na |  | (Note 6) Special | 1b | $\left\|\begin{array}{\|c\|c} 2 \mathrm{a} \\ \text { Note } 8) \end{array}\right\|$ | $\left\|\begin{array}{c} 2 \mathrm{a} \\ \text { Note } 8) \end{array}\right\|$ | - | - | - | - | - | - | - | - | - | - | - | - | - | - | - | - |
|  |  | Standard Spectications | MS-■ | O | $\bigcirc$ | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  | $\mid$ | With Push-Button | MS-■PM | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - |
|  | $\left.\begin{array}{\|c\|c\|} \hline 0 \\ \hline 10 \end{array} \right\rvert\,$ | 3-Element (2) Thermal | MS-■KP | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | OpenTme aick Moion Tipe | MS-■QM | - | - | - | - | - | - | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | St | MSO-■ | © | $\bigcirc$ | O | O | $\bigcirc$ | - | O | O | © | O | O | () | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | O | - | - |
|  |  | Specifications | MSOD-■ | - | $\bigcirc$ | 0 | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | 0 | $\bigcirc$ | - | 0 | 0 | $\bigcirc$ | - | - |
|  |  | 3-Element (2E) | MSO-■KP | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | Thermal | MSOD-■KP | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | 0 | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | With Saturable | MSO-■SR | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  |  | MSOD-■SR | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | With 3-Elem | MSO-םKPSR | - | - | - | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | Saturable Reactor | MSOD--KKPSR | - | - | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | 2-Element | MSO-DFS | - | - | - | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - |
|  |  | Characterisicis Thermal | MSOD-■FS | - | - | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - |
|  |  | 3-Element (2E) | MSO-DFSKP | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - |
|  | $\underset{\substack{\underset{\sim}{2}}}{\stackrel{\rightharpoonup}{2}}$ | Characteristics Thermal | MSOD-पFSKP | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - |
|  | 힝 | OpenTme aick Moion Tipe | MSO-■QM | - | - | - | - | - | - | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | Su | MSO--SA | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - | - | - |
|  |  | Mounted Type | MSOD-■SA | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - | - | - |
|  |  | Wiring | MSO--bBC | ( | O | O | O | O | - | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - | - | - |
|  |  | Terminal | MSOD-■BC | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - | - | - |
|  |  | Anticorrosion | MSO-םYS | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | Treatment | MSOD-पYS | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | Delay Open Type | MSO-■DL | - | $\bigcirc$ | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  |  | MSOL-■ | - | - | - | 0 | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | Latched Type | MSOLD-■ | - | - | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | With Terminal | MSO-■CW | - | - | - | - | - | - | - | - | $\bigcirc$ | OMmat] | - | - | - | - | - | - | - | - | - |
|  |  | Cover | MSOD-■CW | - | - | - | - | - | - | - | - | $\bigcirc$ | OMmer] | - | - | - | - | - | - | - | - | - |
|  |  | Standard | S- $\square$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | O | O | $\bigcirc$ | O | $\bigcirc$ | $\bigcirc$ | O | O | O | $\bigcirc$ | O | O |
|  |  | Specifications | SD-■ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | - | O | O | O | $\bigcirc$ | $\bigcirc$ | - | O | O | O | $\bigcirc$ | 0 |
|  |  | Surge | S-पSA(Note3) | $\bigcirc$ | O | O | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - | - | - |
|  |  | Mounted Type | SD-■SA | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - | - | - |
|  |  | Anticorosion Treatment | S-■YS | - | - | - | - | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | 0 | $\bigcirc$ |
|  |  | OpenTre Caick MoionTipe | S-■QM | - | - | - | - | - | - | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | Wiring | S-■BC | $\bigcirc$ | $\bigcirc$ | O | O | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - | - | - |
|  |  | Terminal | SD-DBC | - | O | O | O | - | $\bigcirc$ | O | $\bigcirc$ | - | - | - | - | - | - | - | - | - | - | - |
|  |  | With Sp | S-■SQ | - | $\bigcirc$ | 0 | - | - | - | - | - | - | - | - | - | - | - | - | - | - | - | - |
|  |  | Terminals | SD-■SQ | - | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - | - | - | - | - | - | - | - |
|  |  | With Termin | S-ロCW | - | - | - | - | - | - | - | - | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - |
|  |  | Cover | SD-■CW | - | - | - | - | - | - | - | - | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - |
|  |  | Delay Open Type | S-ロDL | - | $\bigcirc$ | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  |  | SL-प | - | - | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | O | $\bigcirc$ | - | O | O | O | $\bigcirc$ | $\bigcirc$ |
|  |  | Latched Type | SLD-■ | - | - | - | O | - | - | O | O | O | O | O | O | O | - | O | O | O | $\bigcirc$ | $\bigcirc$ |

Reversible Type

| Frame |  |  |  |  | $\begin{array}{r} 2 \times \\ \mathrm{T} 10 \\ \hline \end{array}$ | $\begin{array}{r} 2 \mathrm{x} \\ \mathrm{~T} 12 \\ \hline \end{array}$ | $\begin{array}{\|l\|} \hline 2 x \\ \mathrm{~T} 20 \\ \hline \end{array}$ | $\begin{array}{r} 2 x \\ \mathrm{~T} 21 \\ \hline \end{array}$ | $\begin{array}{r} 2 x \\ \mathrm{~T} 25 \\ \hline \end{array}$ | $\begin{array}{r} 2 x \\ T 32 \\ \hline \end{array}$ | $\begin{array}{\|l\|} \hline 2 x \\ \text { T35 } \\ \hline \end{array}$ | $\begin{array}{r} 2 \times \\ \mathrm{T} 50 \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline 2 x \\ \text { T65 } \\ \hline \end{array}$ | $\begin{array}{\|c} \hline 2 x \\ \text { T80 } \\ \hline \end{array}$ | $\begin{array}{\|c} \hline 2 x \\ T 100 \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline 2 \mathrm{x} \\ \mathrm{~N} 125 \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline 2 x \\ \text { N150 } \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline 2 x \\ \mathrm{~N} 180 \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline 2 x \\ \text { N220 } \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline 2 x \\ \text { N300 } \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline 2 x \\ \text { N400 } \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline 2 x \\ \text { N600 } \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline 2 x \\ \text { N800 } \\ \hline \end{array}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Category AC-3 <br> Rated Capacity [kW] <br> Auxiliary Contact <br> (Note 4 to Note 6) |  |  |  | 220 V | 2.5 | 3.5 | 4.5 | 5.5 | 7.5 | 7.5 | 11 | 15 | 18.5 | 22 | 30 | 37 | 45 | 55 | 75 | 90 | 125 | 190 | 220 |
|  |  |  |  | 440 V | 4 | 5.5 | 7.5 | 11 | 15 | 15 | 18.5 | 22 | 30 | 45 | 55 | 60 | 75 | 90 | 132 | 160 | 220 | 330 | 440 |
|  |  |  |  | Standard | $\begin{gathered} (1 a \times 2) \\ +2 b \end{gathered}$ | $\begin{array}{\|c\|} (1 a 1 b \times 2)+ \\ 2 b \end{array}$ |  | $\longleftarrow 2 \mathrm{a} 2 \mathrm{~b} \times 2 \longrightarrow 3 \mathrm{a} 3 \mathrm{~b} \times 2 \longrightarrow$ |  |  |  |  |  |  |  |  |  |  |  |  |  | $4 a 4 b \times 2$ |  |
|  |  |  |  | Special | $\begin{gathered} (1 b \times 2) \\ +2 b \end{gathered}$ | $\begin{gathered} (2 a \times 2)+ \\ 2 b \end{gathered}$ |  | - | - | - | - | - | - | - | - | - | - | - | - | - | - | - | - |
|  |  | Standard Specifications | MS- $\square$ |  | - | - | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | 3-Element (2E) Thermal | MS- $\square$ KP |  | - | - | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | Standard Specifications | MSO- $\square$ |  | (0) | (0) | (0) | (0) | (0) | - | (0) | (0) | (0) | (0) | (0) | (0) | (0) | (0) | (0) | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  |  | MSOD- $\square$ |  | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | 3-Element (2E) Thermal | MSO-■KP |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  |  | MSOD- $\square \mathrm{KP}$ |  | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | With Saturable Reactor | MSO- $\square$ SR |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  |  | MSOD- $\square$ SR |  | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | With 3-Element (2E) Thermal Saturable Reactor | MSO- $\square$ KPSR |  | - | - | - | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  |  | MSOD-■KPSR |  | - | - | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | 2-Element Quick-acting Characteristics Thermal | MSO-■FS |  | - | - | - | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - |
|  |  |  | MSOD- $\square$ FS |  | - | - | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - |
|  | $\stackrel{n}{2}$ | 3-Element (2E) Quick-acting Characteristics Thermal | MSO-■FSKP |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - |
|  | $\stackrel{\widetilde{\circ}}{\stackrel{\rightharpoonup}{0}}$ |  | MSOD-■FSKP |  | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - |
|  |  | Surge Absorber Mounted Type | MSO-■SA |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - | - | - |
|  |  |  | MSOD- $\square$ SA |  | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - | - | - |
|  |  | Wiring Streamlining Terminal | MSO- $\square$ BC |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - | - | - |
|  |  |  | MSOD-■BC |  | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - | - | - |
|  |  | With Terminal Cover | MSO- $\square$ CW |  | - | - | - | - | - | - | - | - | $\bigcirc$ | O(Nater ${ }^{\text {a }}$ | - | - | - | - | - | - | - | - | - |
|  |  |  | MSOD-■CW |  | - | - | - | - | - | - | - | - | $\bigcirc$ | O(Nater) | - | - | - | - | - | - | - | - | - |
|  |  | Anticorrosion Treatment | MSO-■YS |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  |  | MSOD-■YS |  | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  | Mechanically Latched Type | MSOL- $\square$ |  | - | - | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  |  |  | MSOLD- $\square$ |  | - | - | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |
|  | $\begin{aligned} & \infty \\ & \stackrel{0}{\lambda} \\ & \stackrel{\rightharpoonup}{\infty} \\ & 0.0 \end{aligned}$ | Standard Specifications | S- $\square$ |  | (0) | (0) | (0) | (0) | () | (0) | (0) | ( 0 | (0) | (0) | (0) | (0) | ( 0 | (0) | (0) | ( $)$ | ( 0 | $\bigcirc$ | $\bigcirc$ |
|  |  |  | SD- $\square$ |  | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
|  |  | Surge Absorber Mounted Type | S- $\square$ SA(Note 3) |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - | - | - |
|  |  |  | SD-■SA |  | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - | - | - |
|  |  | Anticorrosion Treatment | S-■YS |  | - | - | - | - | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
|  |  | Wiring <br> Streamlining <br> Terminal | S-■BC |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - | - | - |
|  |  |  | SD- $\square$ BC |  | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - | - | - |
|  |  | With Terminal Cover | S-■CW |  | - | - | - | - | - | - | - | - | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - |
|  |  |  | SD- $\square$ CW |  | - | - | - | - | - | - | - | - | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | - | - | - |
|  |  | Mechanically Latched Type | SL- $\square$ |  | - | - | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
|  |  |  | SLD- $\square$ |  | - | - | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
|  |  | Class 2 Heat Resistance | S- $\square$ FN |  | - | - | - | $\bigcirc$ | - | - | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | - | - | - | $\bigcirc$ | - | - |
|  |  | With Reversing Connecting Conductor (Both Power and Load Sides) | S-■SD |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
|  |  |  | SD- $\square$ SD |  | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
|  |  | With Power Side 3-Pole In-Phase Crossover Conductor | S-■SG |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
|  |  |  | SD- $\square$ SG |  | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
|  |  | With Load Side 3-Pole In-Phase Crossover Conductor | S-■SX |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
|  |  |  | SD- $\square$ SX |  | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
|  |  | With Load Side 3-Pole Reverse-Phase Switching Crossover Conductor | S- $\square$ SF |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
|  |  |  | SD- $\square$ SF |  | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |

## Note 1. © : Permanently in stock, depending on operation coil voltage and heater designation. O : Made to order.

 - : Outside production rangeNote 2. The value between parentheses for the class AC-3 rated capacity applies to an enclosed magnetic starter.
Note 3. T65 to N800 types have an AC control coil integrated surge absorber, rendering a coil surge absorber unit for prevention of coil switching surges unnecessary.
Note 4. The +2 b on the auxiliary contact arrangement of reversible T10 to T20 types indicates the break contact of the integrated UT-ML20 interlock unit. There is no need to specify when ordering.
Note 5. Auxiliary contact arrangements for reversible types are displayed by twos, in a contact arrangement combining two magnetic contactors. For standard contact arrangements there is no need to specify when ordering; however, please specify a matching contact arrangement for 2 units if for a special configuration. <Example> For 1b x $2+2 \mathrm{~b}$ : 2B
Note 6. Mechanically latched types and delay open types have differing auxiliary contact arrangements. Refer to page 102 for details about mechanically latched types, or page 111 for delay open types.
Note 7. MSO(D)-(2x)T80CW(KP) heater designation 67A is not manufactured.
Note 8 . $\mathrm{S}-\mathrm{T} 12 / \mathrm{T} 20$ auxiliary contact 2 b can be manufactured.

## Selection and Application

### 2.3 Type Designation Structure

### 2.3.1 MS-T Magnetic Starters

Note 1. Refer to the Product Model List (page 30) or the individual listed page for details about product manufacturing specifications and target models. Furthermore, some types may be unable to be manufactured depending on the combination of symbols.

## Enclosed Magnetic Starters



## Open Type Magnetic Starters



### 2.3.2 S-T Magnetic Contactors



### 2.3.3 TH-T Thermal Overload Relays



### 2.3.4 SR-T Contactor Relays



### 2.3.5 UT Optional Units



## Selection and Application

### 2.3.6 MS-N Magnetic Starters

- Enclosed Magnetic Starters

Note 1. Refer to the Product Model List (page 30) or the individual listed page for details about product manufacturing specifications and target models. Furthermore, some types may be unable to be manufactured depending on the combination of symbols.
Note 2 . Symbols are indicated on the packaging box, but those marked with an $*$ are not displayed on the product.


Open Type Magnetic Starters


### 2.3.7 S-N Magnetic Contactors



### 2.3.8 TH-N Thermal Overload Relays



Independent Mounting>
N120
<For Magnetic Starters>
N120TA, N220RH, N400RH
<For Independent Mounting>
N120TAHZ, N220HZ, N400HZ, N600

### 2.3.9 SR-K Contactor Relays



### 2.3.10 UN / UA / UQ Optional Units



## Selection and Application

### 2.4 Explanations of Terms

| Item | Application | Terminology Meaning | Typical Model Name/Display ( $\square$ is replaced with a number) |
| :---: | :---: | :---: | :---: |
| 1. Device | (1) Magnetic Starters (Magnetic Switches) | A set containing a magnetic contactor and thermal overload relay. | Enclosed: MS <br> Open Type: MSO(D), MSOL(D) |
|  | (2) Magnetic Contactors (Contactors) | The contactor opens and closes the main contact via a solenoid and comes as both an AC or DC contactor depending on the type of main circuitry to switch (AC or DC). | Main Circuit Dual AC/DC: S(D), SL(D) Main Circuit DC Only: DU(D) |
|  | (3) AC Operated Magnetic Contactors | A magnetic contactor with a solenoid activated by AC current. | S |
|  | (4) DC Operated Magnetic Contactors | A magnetic contactor with a solenoid activated by DC current. | SD |
|  | (5)Mechanically  <br>  Latched Magnetic <br> Contactors  | A magnetic contactor that can close the contact (ON) either electrically (closing coil) or mechanically and has a mechanical latch mechanism that retains the closed state without operational force until a time that it is electrically (opening coil) or mechanically open-circuited (OFF). | SL(D) |
|  | (6) Delay Open Magnetic Contactors | A magnetic contactor that uses the discharge from a capacitor to keep the contact closed for a few seconds even if a voltage drop or momentary power failure occurs in the control circuit. | S-पDL |
|  | (7) Reversible Magnetic Contactors | A magnetic contactor that allows a motor to be reversed via switching the contact connections. | S-(D)-2x $\square, \mathrm{SL}(\mathrm{D})-2 \times \square$ |
|  | (8) Thermal Overload Relays | If the motor is drawing too much current (overloaded) due to a motor overload, constraint or open-phase, then the integrated bi-metal curves due to the heat generated and its output opens the magnetic contactor, preventing heat damage to the motor. | TH |
| 2. Rating | (1) Rated Insulation Voltage | The guaranteed withstanding voltage and the voltage that determines the isolation distance. | $\square \mathrm{V}$ (Both AC/DC) |
|  | (2) Rated Operational Voltage | The voltage that determines applications realing to making capacity, breaking capacity, switching frequency and swithing durability. | $\mathrm{AC} \square$ to $\square \mathrm{V}$, DC $\square \mathrm{V}$ |
|  | (3) Rated Capacity | The maximum applicable load capacity at the rated operational voltage. | Motor $\square \varphi \square \mathrm{kW}$, Resistance $\square \varphi \square \mathrm{kW}$ |
|  | (4) Rated Operating Current | The maximum current for full performance at the rated operational voltage. | AC-3 $\square$ A, AC-4 $\square$ A, DC1 $\square$ A |
|  | (5) Conventional Free Air Thermal Current (Ith) | The current that can flow for 8 hours without causing a temperature rise exceeding the defined value when open/close operations are not being performed. <br> An expression defined in JISC8201-1 specifying the rated continuity current. | Ith= $\square \mathrm{A}$ |
|  | (6) Operation Coil | Magnetizes the solenoid for attractive force, or demagnetizes it for switching operation. | - |
|  | Coil Designation | Shows the typical value of the rated operating current to be specified by symbol when ordering. | AC $\square \mathrm{V}, \mathrm{DC} \square \mathrm{V}$ |
|  | Operation Coil Rating | The rated operational voltage (nominal voltage) range and frequency (for AC) of the operation coil | $\square \mathrm{V} \square \mathrm{Hz}$, DC $\square \mathrm{V}$ |
| 3. Perormance | (1) Making Capacity | The current value that can flow when making ( $\mathrm{ON} \mathrm{)} \mathrm{under} \mathrm{conditions}$ defined by the standards (tested 50 times for JIS and 100 times for JEM) | $\square A$ |
|  | (2) Breaking Capacity | The current value that can flow when breaking (OFF) under conditions defined by the standards (tested 50 times for JIS and 25 times for JEM) | $\square A$ |
|  | (3) Switching Frequency | The number of times swithing can be performed in a 1-hour period under conditions defined by the standards. | $\square$ Times/Hr |
|  | (4) Switching Durability (Lifetime) |  | $\square 10,000$ Times |
|  | . Mechanical Durability | The referenceduraility due to mechanicad wearifswicthed under conditions based on the standards, withoutay curren applied to the man circuit. | $\square 10,000$ Times |
|  | Electrical Durability | The reference durabilit due to electical wearif swiched under conditions based on the standarcs, with curent applied to the man ciccit. | $\square 10,000$ Times |
| 4. Properties | (1) Closing Voltage | The minimum voltage required to close the contact (ON) through excitation of the operation coil. (input voltage and tripping voltage for mechanically latched types) |  |
|  | (2) Opening Voltage | The maximum voltage that can be reached by gradually dropping off the voltage applied to the operation coil before the contact opens(OFF). | $\left.\begin{array}{\|l} \square \text { to } \square \text { V } \\ \binom{\text { Standard Value: 20\% or More of Rated Operational }}{\text { Voltage for AC Operation 10\% or More for DC Operation }} \\ \hline \end{array}\right)$ |
|  | (3) Operating Time | The time taken for the contact to transition (ON or OFF) once the operation coil has been excited or demagnetized. | $\square \mathrm{ms}$ |
|  | (4) Operation Coil | [As per 2.(6)] | - |
|  | - Inrush Input | The momentary capacity (input VA) immediatly ater the operation coil is excited, regular input or below for DC operated types. | AC: $\square \mathrm{VA}, \mathrm{DC}: \square \mathrm{W}(=\square \mathrm{VA})$ |
|  | Regular Input | The coil capacity (consumed electricity) when the operation coil is excited and in the closed-contact state | AC: $\square \mathrm{VA}, \mathrm{DC}: \square \mathrm{W}(=\square \mathrm{VA})$ |
| 5. Operations Actions/Others | (1) Inching (Inching Operation) | Inching, also known as jogging, is a frequent switching of starting current for minor motor rotations. | - |
|  | (2) Plugging (Reverse Phase Braking) | Sudden reversal of the contact connections result in stoppage of the motor. | - |
|  | (3) Self-Retention | Uses the auxiliary make contact of an ON magnetic contactor to continuously apply current to the magnetic contactor operation coil causing it to retain its ON state after the ON command, only releasing via an OFF command or power failure. | (Refer to page 66) |
|  | (4) Interlock | An interlocking system whereby if 2 magnetic contactors are not permitted to be simultaneously turned on, as with reversible types, when one contactor turns ON it prevents the other contactor from reaching the ON state. There is a mechanical interlock via a mechanical mechanism and an electrical interlock via the auxiliary break contact. | (Refer to page 66) |
|  | (5) Make Contact | Normally open, closing when a current is applied to the operation coil. Also known as an NO (Normally Open) contact. | $\bigcirc$ |
|  | (6) Break Contact | Normally closed, opening when a current is applied to the operation coil. Also known as an NC (Normally Closed) contact. | + |
|  | (7) Main Circuit | Switches the main contact (terminal numbers $1 / L 1-2 / T 1,3 / L 2-4 / T 2,5 / L 3-6 / T 3$ ) for circuits with large currents (several A to $1,000 \mathrm{~A}$ or more) such as with motors or illumination circuitry. | , |
|  | (8) Operation (Control) Circuit | Switches via auxiliary make contact or auxiliary break contact for circuits with small currents (several 10 s of mA to several A) such as with operation coils or display circuitry. | - |
|  | (9) Direct Start | The most general type of operation where the full voltage is applied for starting stopping the motor: Also known as sull-volage operation. | - |
|  | (10) Star/Delta Start | To soften the electrical/mechanical shock to the motor when starting, the motor windings are connected in star configuration for $1 / 3$ of the full-voltage current. Once accelerated the windings are switched to delta configuration for the least expensive, reduced-voltage running. | - |
|  | (11) Category AC-3 | Motor reglar startstop swiching duty. (Closed with 6 times the rated curent and breaking with 1 times the rated curent in durabiliy testing) | (Refer to pages 46, 47) |
|  | (12) Category AC-4 | Motor starting current switching duty (Closed with 6 times the rated current and breaking with 6 times the rated current in durability testing) for more severe switching than category $\mathrm{AC}-3$. . This also applies to inching and plugging. | (Refer to pages 46, 47) |
|  | (13) Category AC-1 | Switching duty for electric heating or resistive loads with almost no inrush current when starting. (Closed/breaking with 1 time the rated current in durability testing) | (Refer to pages 46, 51) |
|  | (14) 2E and 3E | 2E: A themal overlad reay or electonic type that protects the moto f fom overoaded constant t open-phase conditions. <br>  | $\begin{aligned} & \text { TH- } \square \mathrm{KP}, \mathrm{ET}-\mathrm{N} \square \\ & \text { ET-N } \square \end{aligned}$ |

### 2.5 Main Contact Rating

## Rated Capacity (JISC8201-4-1, IEC60947-4-1)

The maximum applicable load capacity of magnetic starters/magnetic contactors under standard conditions is as per the table below.

| Application <br> Frame | Rated Capacity [kW] |  |  |  |  |  |  |  |  |  |  | Rated Insulation Voltage [V] |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Standard Sequence |  |  |  |  |  | Inching | g Duty | Three-Phase Resistive Load (Category AC-1) |  |  |  |
|  | Thre | e-Phase Squ (Categor | $\begin{aligned} & \text { irrel-cage } \\ & y \text { y } \mathrm{IC}-3 \text { ) } \end{aligned}$ |  | Single-Phase Motor (Categ | Application Capacity y AC-3) | Three-Phase Squirrel-cage Motor (Category AC-4) |  |  |  |  |  |
|  | 220 to 240V | 380 to 440V | 500 V | 690 V | 100 to 110 V | 220 to 240 V | 220 to 240V | 380 to 500V | 220 to 240 V | 400 to 440V | 500 to 550V |  |
| T10 | 2.5[2.2] | 4[2.7] | 4[2.7] | 4 | 0.4 | 0.8 | 1.5 | 2.7(2.2) | 6.5 | 8 | 7 |  |
| T12 | 3.5[2.7] | 5.5[4] | 5.5[5.5] | 5.5 | 0.55 | 1 | 2.2 | 5.5(4) | 6.5 | 10 | 9.5 |  |
| T20 | 4.5[3.7] | 7.5[7.5] | 7.5[7.5] | 7.5 | 0.75 | 1.5 | 3.7 | 5.5 | 6.5 | 12 | 14.5 |  |
| T21 | 5.5[4] | 11[7.5] | 11[7.5] | 7.5 | 0.9 | 1.8 | 3.7 | 5.5 | 11 | 22 | 25 |  |
| T25 | 7.5[5.5] | 15[11] | 15[11] | 11 | 1.2 | - | 4.5 | 7.5 | 11 | 22 | 25 |  |
| T32 | 7.5[7.5] | 15[15] | 15[11] | 11 | 1.7 | - | 5.5 | 7.5(11) | 11 | 22 | 25 |  |
| T35 | 11[7.5] | 18.5[15] | 18.5[15] | 15 | 1.7 | - | 5.5 | 11 | 20 | 40 | 50 | 690 |
| T50 | 15[11] | 22[22] | 25[22] | 22 | - | - | 7.5 | 15 | 27 | 55 | 50 |  |
| T65 | 18.5[15] | 30[30] | 37[30] | 30 | - | - | 11 | 22 | 34 | 68 | 85 |  |
| T80 | 22[19] | 45[37] | 45[45] | 45 | - | - | 15 | 30 | 41 | 83 | 85 |  |
| T100 | 30[22] | 55[45] | 55[45] | 55 | - | - | 19 | 37 | 50 | 100 | 120 |  |
| N125 | 37[30] | 60[60] | 60[60] | 60 | - | - | 22 | 45 | 50 | 100 | 120 |  |
| N150 | 45[37] | 75[75] | 90[90] | 90 | - | - | 30 | 55 | 65 | 130 | 170 |  |
| N180 | 55[45] | 90[90] | 110[110] | 110 | - | - | 37 | 75 | 90 | 180 | 220 |  |
| N220 | 75[55] | 132[110] | 132[132] | 132 | - | - | 45 | 90 | 90 | 180 | 220 |  |
| N300 | 90[75] | 160[150] | 160[160] | 200 | - | - | 55 | 110 | 120 | 240 | 300 | 690 |
| N400 | 125[110] | 220[200] | 225[200] | 250 | - | - | 75 | 150 | 155 | 310 | 380 | (1000) |
| N600 | 190[160] | 330[300] | 330[300] | 330 | - | - | 110 | 200 | 220 | 440 | 570 |  |
| N800 | 220[200] | 440[400] | 500[400] | 500 | - | - | 160 | 300 | 270 | 540 | 700 |  |

Note 1. The rated values for single-phase class AC-4 motors are the same as for class AC-3.
Note 2. The numbers in parentheses for the inching duty indicate the rated values for 380 to 440 V .
Note 3. The 200 to 240 V ratings for enclosed magnetic starters below have changed ratings in accordance with the Electrical Appliance and Material Safety Law.
MS-T21: 3.7 kW
Note 4. Refer to page 30 for information regarding electrical durability.

## Rated Operating Current and Conventional Free Air Thermal Current (JISC8201-4-1, IEC60947-4-1)

The maximum applicable current that satisfies the making or breaking capacity, switching frequency and switching durability required by the standards is as per the table below.

|  | Motor Load |  |  |  |  |  |  | Resistive Load |  |  | Conventional Free Air Thermal Current (Note 2) lth $[A]$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Category AC-3 Rated Operating Current [A] |  |  |  | Category AC-4 Rated Operating Current [A] |  |  | Category AC-1 Rated Operating Current [A] |  |  |  |
|  | 220 to 240 V | 380 to 440V | 500 V | 690 V | 220 to 240 V | 380 to 440V | 500 V | 220 to 240V | 400 to 440 V | 500 to 550V |  |
| T10 | 11[11] | 9[7] | 7[6] | 5 | 8 | 6 | 6 | 20 | 11 | 8 | 20 |
| T12 | 13[13] | 12[9] | 9[9] | 7 | 11 | 9 | 9 | 20 | 13 | 11 | 20 |
| T20 | 18[18] | 18[18] | 17[17] | 9 | 18 | 13 | 10 | 20 | 18 | 17 | 20 |
| T21 | 25[20] | 23[20] | 17[17] | 9 | 18 | 13 | 10 | 32 | 32 | 32 | 32 |
| T25 | 30(26)[26] | 30(26)[25] | 24[20] | 12 | 20 | 17 | 12 | 32 | 32 | 32 | 32 |
| T32 | 32[32] | 32[32] | 24[20] | 12 | 26 | 24 | 13 | 32 | 32 | 32 | 32 |
| T35 | 40[35] | 40[32] | 32[26] | 17 | 26 | 24 | 17 | 60 | 60 | 60 | 60 |
| T50 | 55(50)[50] | 50[48] | 38[38] | 26 | 35 | 32 | 24 | 80 | 80 | 60 | 80 |
| T65 | 65[65] | 65[65] | 60[45] | 38 | 50 | 47 | 38 | 100 | 100 | 100 | 100 |
| T80 | 85[80] | 85[80] | 75[75] | 52 | 65 | 62 | 45 | 120 | 120 | 100 | 120 |
| T100 | 105[100] | 105[93] | 85[75] | 65 | 80 | 75 | 55 | 150 | 150 | 150 | 150 |
| N125 | 125[125] | 120[120] | 90[90] | 70 | 93 | 90 | 65 | 150 | 150 | 150 | 150 |
| N150 | 150[150] | 150[150] | 140[140] | 100 | 125 | 110 | 80 | 200 | 200 | 200 | 200 |
| N180 | 180[180] | 180[180] | 180[180] | 120 | 150 | 150 | 140 | 260 | 260 | 260 | 260 |
| N220 | 250[220] | 250[220] | 200[200] | 150 | 180 | 180 | 140 | 260 | 260 | 260 | 260 |
| N300 | 300[300] | 300[300] | 250[250] | 220 | 220 | 220 | 200 | 350 | 350 | 350 | 350 |
| N400 | 400[400] | 400[400] | 350[350] | 300 | 300 | 300 | 250 | 450 | 450 | 450 | 450 |
| N600 | 630[630] | 630[630] | 500[500] | 420 | 400 | 400 | 350 | 660 | 660 | 660 | 660(800) |
| N800 | 800[800] | 800[800] | 720[720] | 630 | 630 | 630 | 500 | 800 | 800 | 800 | 800(1000) |

Note 1. The rated operating current indicates the maximum applicable current that satisfies the making capacity or breaking capacity, switching frequency and switching durability at the rated operational voltage.
Note 2. The values in the parentheses for N600 and N800 are applicable for ambient temperature of $40^{\circ} \mathrm{C}$ or less.
Note 3. The value between parentheses for the rated operating current for T21 and T35 is that applicable for the magnetic contactor.
Note 4. The main contact minimum operating voltage and current differ depending on the allowable fault rate. Please refer to page 42 for details.
Note 5. Refer to page 30 for information regarding electrical durability.

## Selection and Application

DC Rating (JEM1038, JISC8201-5-1)

| Frame | Rated Voltage DC (V) | Category DC2, DC4 Rated Operating Current (DC Motor Load) [A] |  | Category DC1 Rated Operating Current (Resistive Load) [A] |  | Category DC-13 Rated Operating Current (DC Coil Load) [A] |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 2-Pole Series | 3-Pole Series | 2-Pole Series | 3-Pole Series | Single Pole | 2-Pole Series | 3-Pole Series |
| T10 | $\begin{gathered} 24 \\ 48 \\ 110 \\ 220 \\ \hline \end{gathered}$ | $\begin{gathered} 8 \\ 4 \\ 2.5 \\ 0.8 \end{gathered}$ | $\begin{aligned} & 8 \\ & 6 \\ & 4 \\ & 2 \\ & \hline \end{aligned}$ | $\begin{aligned} & 10 \\ & 10 \\ & 6 \\ & 3 \\ & \hline \end{aligned}$ | $\begin{aligned} & 10 \\ & 10 \\ & 8 \\ & 8 \end{aligned}$ | $\begin{gathered} 5 \\ 3 \\ 0.6 \\ 0.2 \end{gathered}$ | $\begin{gathered} 8 \\ 4 \\ 2 \\ 0.3 \end{gathered}$ | $\begin{gathered} 8 \\ 6 \\ 3 \\ 0.8 \end{gathered}$ |
| T12 | $\begin{gathered} \hline 24 \\ 48 \\ 110 \\ 220 \\ \hline \end{gathered}$ | $\begin{gathered} 12 \\ 6 \\ 4 \\ 1.2 \\ \hline \end{gathered}$ | $\begin{aligned} & \hline 12 \\ & 10 \\ & 8 \\ & 4 \\ & \hline \end{aligned}$ | $\begin{aligned} & \hline 12 \\ & 12 \\ & 10 \\ & 7 \\ & \hline \end{aligned}$ | $\begin{aligned} & \hline 12 \\ & 12 \\ & 12 \\ & 12 \\ & \hline \end{aligned}$ | $\begin{gathered} \hline 7 \\ 5 \\ 1.2 \\ 0.2 \\ \hline \end{gathered}$ | $\begin{gathered} 12 \\ 6 \\ 3 \\ 0.5 \\ \hline \end{gathered}$ | $\begin{gathered} \hline 12 \\ 10 \\ 5 \\ 2 \\ \hline \end{gathered}$ |
| T20 | $\begin{gathered} 24 \\ 48 \\ 110 \\ 220 \\ \hline \end{gathered}$ | $\begin{gathered} 18 \\ 15 \\ 8 \\ 2 \end{gathered}$ | $\begin{aligned} & 18 \\ & 18 \\ & 15 \\ & 8 \\ & \hline \end{aligned}$ | $\begin{gathered} 18 \\ 18 \\ 13 \\ 8 \end{gathered}$ | $\begin{aligned} & 18 \\ & 18 \\ & 18 \\ & 18 \end{aligned}$ | $\begin{gathered} 10 \\ 5 \\ 5.2 \\ 0.2 \end{gathered}$ | $\begin{gathered} 14 \\ 7 \\ 3 \\ 0.5 \end{gathered}$ | $\begin{aligned} & 15 \\ & 12 \\ & 5 \\ & 2 \end{aligned}$ |
| T21 | $\begin{array}{r} \hline 24 \\ 48 \\ 110 \\ 220 \\ \hline \end{array}$ | $\begin{gathered} \hline 20 \\ 15 \\ 8 \\ 2 \\ \hline \end{gathered}$ | $\begin{gathered} \hline 20 \\ 20 \\ 15 \\ 8 \\ \hline \end{gathered}$ | $\begin{aligned} & \hline 20 \\ & 20 \\ & 15 \\ & 10 \\ & \hline \end{aligned}$ | $\begin{aligned} & 20 \\ & 20 \\ & 20 \\ & 20 \\ & \hline \end{aligned}$ | $\begin{gathered} 12 \\ 8 \\ 1.5 \\ 0.25 \\ \hline \end{gathered}$ | $\begin{gathered} 20 \\ 12 \\ 3 \\ 1.2 \\ \hline \end{gathered}$ | $\begin{aligned} & \hline 20 \\ & 15 \\ & 10 \\ & 4 \\ & \hline \end{aligned}$ |
| T25, T32 | $\begin{array}{r} 24 \\ 48 \\ 110 \\ 220 \\ \hline \end{array}$ | $\begin{gathered} 25 \\ 20 \\ 10 \\ 3 \\ \hline \end{gathered}$ | $\begin{aligned} & 25 \\ & 25 \\ & 20 \\ & 10 \\ & \hline \end{aligned}$ | $\begin{aligned} & 25 \\ & 25 \\ & 25 \\ & 12 \\ & \hline \end{aligned}$ | $\begin{aligned} & 25 \\ & 25 \\ & 25 \\ & 22 \\ & \hline \end{aligned}$ | $\begin{array}{r} 15 \\ 10 \\ 1.5 \\ 0.25 \end{array}$ | $\begin{gathered} 25 \\ 15 \\ 4 \\ 1.2 \end{gathered}$ | $\begin{gathered} 25 \\ 25 \\ 12 \\ 4 \\ \hline \end{gathered}$ |
| T35 | $\begin{array}{r} \hline 24 \\ 48 \\ 110 \\ 220 \\ \hline \end{array}$ | $\begin{gathered} 35 \\ 20 \\ 10 \\ 3 \\ \hline \end{gathered}$ | $\begin{aligned} & \hline 35 \\ & 30 \\ & 20 \\ & 10 \\ & \hline \end{aligned}$ | $\begin{aligned} & 35 \\ & 35 \\ & 25 \\ & 12 \\ & \hline \end{aligned}$ | $\begin{aligned} & 35 \\ & 35 \\ & 35 \\ & 30 \\ & \hline \end{aligned}$ | $\begin{array}{r} 15 \\ 10 \\ 1.5 \\ 0.25 \\ \hline \end{array}$ | $\begin{gathered} 35 \\ 15 \\ 4 \\ 1.2 \\ \hline \end{gathered}$ | $\begin{gathered} 35 \\ 25 \\ 12 \\ 4 \\ \hline \end{gathered}$ |
| T50 | $\begin{gathered} \hline 24 \\ 48 \\ 110 \\ 220 \\ \hline \end{gathered}$ | $\begin{aligned} & 45 \\ & 25 \\ & 15 \\ & 3.5 \end{aligned}$ | $\begin{aligned} & \hline 50 \\ & 35 \\ & 30 \\ & 12 \\ & \hline \end{aligned}$ | $\begin{aligned} & 50 \\ & 40 \\ & 35 \\ & 15 \\ & \hline \end{aligned}$ | $\begin{aligned} & \hline 50 \\ & 50 \\ & 50 \\ & 40 \\ & \hline \end{aligned}$ |  |  |  |
| T65 | $\begin{gathered} \hline 24 \\ 48 \\ 110 \\ 220 \\ \hline \end{gathered}$ | $\begin{aligned} & 45 \\ & 25 \\ & 15 \\ & 3.5 \\ & \hline \end{aligned}$ | $\begin{aligned} & 50 \\ & 35 \\ & 30 \\ & 12 \\ & \hline \end{aligned}$ | $\begin{aligned} & 50 \\ & 40 \\ & 35 \\ & 15 \\ & \hline \end{aligned}$ | $\begin{aligned} & 65 \\ & 65 \\ & 65 \\ & 50 \\ & \hline \end{aligned}$ |  |  |  |
| T80 | $\begin{gathered} 24 \\ 48 \\ 110 \\ 220 \\ \hline \end{gathered}$ | $\begin{gathered} 65 \\ 40 \\ 20 \\ 5 \\ \hline \end{gathered}$ | $\begin{aligned} & 80 \\ & 60 \\ & 50 \\ & 20 \\ & \hline \end{aligned}$ | $\begin{aligned} & 80 \\ & 65 \\ & 50 \\ & 20 \\ & \hline \end{aligned}$ | $\begin{aligned} & 80 \\ & 80 \\ & 80 \\ & 60 \\ & \hline \end{aligned}$ |  |  |  |
| T100 | $\begin{gathered} \hline 24 \\ 48 \\ 110 \\ 220 \\ \hline \end{gathered}$ | 93 60 40 30 | $\begin{aligned} & 93 \\ & 90 \\ & 80 \\ & 50 \\ & \hline \end{aligned}$ | $\begin{aligned} & 93 \\ & 93 \\ & 80 \\ & 50 \\ & \hline \end{aligned}$ | $\begin{aligned} & 93 \\ & 93 \\ & 93 \\ & 70 \\ & \hline \end{aligned}$ |  |  |  |
| N125 | $\begin{array}{r} \hline 24 \\ 48 \\ 110 \\ 220 \\ \hline \end{array}$ | $\begin{gathered} 120 \\ 60 \\ 40 \\ 30 \\ \hline \end{gathered}$ | $\begin{gathered} 120 \\ 90 \\ 80 \\ 50 \\ \hline \end{gathered}$ | $\begin{gathered} 120 \\ 100 \\ 80 \\ 50 \\ \hline \end{gathered}$ | $\begin{aligned} & \hline 120 \\ & 120 \\ & 100 \\ & 80 \\ & \hline \end{aligned}$ | Note 1. Electrical durability of 500,000 operations Note 2. The applicable switching frequency is as follows: <br> <DC2, DC4, DC-13 class> |  |  |
| N150 | $\begin{gathered} \hline 24 \\ 48 \\ 110 \\ 220 \\ \hline \end{gathered}$ | $\begin{gathered} 150 \\ 100 \\ 80 \\ 60 \\ \hline \end{gathered}$ | $\begin{gathered} 150 \\ 130 \\ 120 \\ 80 \\ \hline \end{gathered}$ | $\begin{aligned} & 150 \\ & 120 \\ & 100 \\ & 100 \\ & \hline \end{aligned}$ | $\begin{aligned} & 150 \\ & 150 \\ & 150 \\ & 150 \\ & \hline \end{aligned}$ |  | T35: 1800 times/ 100, N125 to N Ss> | hour 00: 1200 times/ |
| N180(N220) | $\begin{gathered} 24 \\ 48 \\ 110 \\ 220 \end{gathered}$ | $\begin{gathered} 180(220) \\ 150 \\ 120 \\ 80 \end{gathered}$ | $\begin{gathered} 180(220) \\ 180(220) \\ 150 \\ 100 \end{gathered}$ | $\begin{gathered} 180(220) \\ 180 \\ 150 \\ 150 \end{gathered}$ | $\begin{aligned} & 180(220) \\ & 180(220) \\ & 180(220) \\ & 180(220) \end{aligned}$ | T100 and N125 to N800: 600 times/hour <br> Note 3. Connect for use in 2-pole series or 3 -pole series as per the diagram below. |  |  |
| N300 | $\begin{gathered} \hline 24 \\ 48 \\ 110 \\ 220 \\ \hline \end{gathered}$ | $\begin{gathered} \hline 300 \\ 200 \\ 150 \\ 90 \\ \hline \end{gathered}$ | $\begin{aligned} & \hline 300 \\ & 280 \\ & 200 \\ & 150 \\ & \hline \end{aligned}$ | $\begin{aligned} & \hline 300 \\ & 240 \\ & 200 \\ & 200 \\ & \hline \end{aligned}$ | $\begin{aligned} & \hline 300 \\ & 300 \\ & 300 \\ & 300 \\ & \hline \end{aligned}$ | Note 4. The rated operating current increases when connected in series but the reliability of the contacts decreases. |  |  |
| N400 | $\begin{gathered} \hline 24 \\ 48 \\ 110 \\ 220 \\ \hline \end{gathered}$ | $\begin{gathered} 400 \\ 200 \\ 150 \\ 90 \end{gathered}$ | $\begin{aligned} & 400 \\ & 280 \\ & 200 \\ & 150 \end{aligned}$ | $\begin{aligned} & \hline 400 \\ & 240 \\ & 200 \\ & 200 \\ & \hline \end{aligned}$ | $\begin{aligned} & 400 \\ & 400 \\ & 400 \\ & 300 \\ & \hline \end{aligned}$ |  |  |  |
| N600(N800) | $\begin{gathered} 24 \\ 48 \\ 110 \\ 220 \\ \hline \end{gathered}$ | $630(800)$ 630 630 630 | $\begin{gathered} 630(800) \\ 630 \\ 630 \\ 630 \end{gathered}$ | 630(800) 630(800) 630 630 |  |  |  |  |

## Standards for DC Rating

| Standards | Category | Making Capacity Test |  |  | Breaking Capacity Test |  |  | Electrical Durability Test |  |  |  |  |  | Typical Application Example |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | Making | Breaking |  |  |  |
|  |  | Current | Voltage | *1 |  |  |  | Current | Voltage | *1 | Current | Voltage | *1 |  | Current | Voltage | *1 |
|  | DC1 | 1.11 e | 1.1 Ee | $1(\mathrm{~ms})$ | 1.1 le | 1.1 Ee | $1(\mathrm{~ms})$ | le | Ee | $1(\mathrm{~ms})$ | Ie | Ee | 1(ms) | Resistive Load |
| JEM | DC2 | 4 le | 1.1 Ee | $2.5(\mathrm{~ms})$ | 41 e | 1.1 Ee | $2.5(\mathrm{~ms})$ | 2.51 e | Ee | $2(\mathrm{~ms})$ | le | 0.1 Ee | $7.5(\mathrm{~ms})$ | DC Shunt Motor Starting/Stopping |
|  | DC4 | 41 e | 1.1 Ee | $15(\mathrm{~ms})$ | 41 e | 1.1Ee | $15(\mathrm{~ms})$ | 2.5le | Ee | 7.5(ms) | le | 0.3 Ee | $10(\mathrm{~ms})$ | DC Series-Wound Motor Starting/Stopping |
| $\begin{gathered} \hline \text { JIS } \\ \text { C8201 } \\ -5-1 \end{gathered}$ | DC-13 | 1.1le | 1.1Ee | 6P(ms) | 1.1le | 1.1Ee | 6P(ms) | le | Ee | 6P(ms) | le | Ee | 6P(ms) | DC Inductive Load (DC Coil Load Control) |

Note 1. le: Rated Operating Current, Ee: Rated Operational Voltage.
Note 2. *1 For JEM-1038: Time constant,
For JIS C8201-5-1: Time taken to reach 95\% of rated operating current. Maximum $300(\mathrm{~ms})$
$P=$ No. watts consumed at steady state (calculated by Ee $\times$ le).
Note 3. Making capacity tests are performed 100 times, while breaking capacity tests are performed 25 times. (JIS C8201-5-1 calls for making and breaking capacity tests to be performed 10 times.)

### 2.6 Auxiliary Contact Arrangements and Ratings

## - No. of Installed Auxiliary Contacts and Contact Arrangement

- All Auxiliary Contacts Are Twin Contacts

|  | Non-Reversible Magnetic Contactors |  |  |  |  |  |  | Reversible Magnetic Contactor (Note 4) |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Model | T10 | T12 | T32 | T20 | $\begin{gathered} \text { T21 to } \\ \text { T80 } \end{gathered}$ | $\begin{aligned} & \text { T100 } \\ & \text { N125 } \end{aligned}$ | N150 to N800 | $2 \times$ T10 | $\begin{aligned} & 2 \times \text { T12 } \\ & 2 \times \text { T20 } \end{aligned}$ | $2 \times$ T32 <br> (Note 6) | $\left\|\begin{array}{c} 2 \times \text { T21 to } \\ 2 \times T 80 \end{array}\right\|$ | $\begin{aligned} & 2 \times \mathrm{T} 100 \\ & 2 \times \mathrm{N} 125 \end{aligned}$ | $\begin{gathered} 2 \times N 150 \text { to } \\ 2 \times N 400 \end{gathered}$ | $\begin{array}{\|c\|} \hline 2 \times \mathrm{N} 600 \text { to } \\ 2 \times \mathrm{N} 800 \end{array}$ |
| Standard | 1a | 1a1b | - | 1a1b | 2a2b | 2a2b | 2a2b | 1ax2+2b (Note 3) | 1a1bx2+26 ( Note3) | $2 \mathrm{a} 2 \mathrm{~b} \times 2$ | $2 \mathrm{a} 2 \mathrm{~b} \times 2$ | $2 \mathrm{a} 2 \mathrm{~b} \times 2$ | $3 \mathrm{a} 3 \mathrm{x} \times 2$ | $4 \mathrm{a} 4 \mathrm{~b} \times 2$ |
| Special | 1b | 2a (Note 8) | - | 2 a (Note 8) | - | - | - | 1bx22b (Note3) | $2 a \times 22 b$ (Note 3) | - | - | - | - | - |
| Maximum | $\begin{gathered} 5 a \\ 4 a 1 b \\ 3 \mathrm{a} 2 \mathrm{~b} \end{gathered}$ | $\begin{aligned} & 5 a 1 b \\ & 4 a 2 b \\ & 3 a 3 b \end{aligned}$ | $\begin{gathered} 4 a \\ 3 a 1 b \\ 2 a 2 b \end{gathered}$ | $\begin{aligned} & 5 a 1 b \\ & 4 a 2 b \\ & 3 a 3 b \end{aligned}$ | 6a2b <br> 5a3b <br> 4a4b | 4a4b | 4a4b | $\begin{array}{\|c\|} \hline 5 a \times 2+2 b \\ 4 a 1 b \times 2+2 b \\ 3 a 2 b \times 2+2 b \\ (\text { Note } 3) \\ \hline \end{array}$ | $\left\{\begin{array}{c} 5 a 1 b \times 2+2 b \\ 4 a 2 b \times 2+2 b \\ 3 a 3 b \times 2+2 b \\ (\text { Note } 3) \end{array}\right.$ | - | $\begin{aligned} & 6 a 2 b \times 2 \\ & 5 a 3 b \times 2 \\ & 4 a 4 b \times 2 \end{aligned}$ | $3 \mathrm{a} 3 \mathrm{x} \times 2$ | - | - |

Note 1. The 2 auxiliary break contacts of reversible magnetic starters (MS-2x, MSO-2x) are wired as an electrical interlock.
Note 2. No specification needs to be made for standard contact arrangements. Specify only for special arrangements.
Note 3. The $+2 b$ on the auxiliary contact arrangement of reversible T10, T12 and T20 types indicates the break contact of the integrated UT-ML20 interlock unit. There is no need to specify when ordering.
Note 4. Auxiliary contact arrangements for reversible types are displayed by twos, in a contact arrangement combining two magnetic contactors. Please specify a matching contact arrangement for 2 units when ordering. <Example> For 1a1b x $2+2 \mathrm{~b}$ : 2A2B
Note 5. The maximum number of units indicates that when using additional auxiliary contact units available as option parts for the magnetic contactor. The body and auxiliary contact unit can be additionally installed by the customer as a separate arrangement. Refer to page 197 for details about auxiliary contact units.
Mounting of auxiliary contact units to enclosed types or delay open types, and mounting of front clip-on auxiliary contact units to mechanically latched types are not possible.
Note 6. Reversible $2 \times$ T32 type has auxiliary contact unit 2a2b (UT-AX4) x 2 included as standard.
Note 7. Mechanically latched types and delay open types have differing auxiliary contact arrangements as per the table above. Refer to page 102 for details about mechanically latched types, or page 111 for delay open types.
Note 8. S-T12/T20 auxiliary contact 2b can be manufactured.
Rated Operating Current and Conventional Free Air Thermal Current of Auxiliary Contacts (Rated Continuity Current)

| Frame | Rated Operating Current (A) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Conventional <br> Free Air Themal <br> Current Ith $[A]$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Category AC-15 (AC Coil Load) |  |  |  | Category DC-13 (DC Coil Load) |  |  |  | Category AC-12 (AC Resistive Load) |  |  |  | Category DC-12 (DC Resistive Load) |  |  |  |  |
|  | AC120V | AC240V | AC440V | AC500V | DC24V | DC48V | DC110V | DC220V | AC120V | AC240V | AC440V | AC500V | DC24V | DC48V | DC110V | DC220V |  |
| T10 to T100 N125 to N800 | 6 | 3 | 1.5 | 1.2 | 3 | 1.5 | 0.6 | 0.3 | 10 | 8 | 5 | 5 | 10 | 8 | 5 | 1 | 10 |
| T10JH to T100JH N125HM to N800HM | 10(6) | 10(5) | 5(3) | 4(3) | 7[10] | 5 | 1.2 | 0.2 | 20 | 16 | 10 | 10 | 10 | 8 | 5 | 1 | 20 |

Note 1. The minimal applicable load is T10 to T100, N125 to N800: 20V3mA, T10JH to T100JH, N125HM to N800HM: 48V200mA.
Note 2. Electrical durability of 500,000 operations.
Note 3. The rated operating current between parentheses indicate the same-pole make and break contact values for different operating voltage.
Note 4. JISC8201-5-1 classifications are class AC-15 applicable to AC inductive loads (AC coil load (exceeding 72 VA) control)) and class DC-13 applicable to DC inductive loads (DC coil load control).
Note 5. JISC8201-5-1 classifications are class AC-12 applicable to AC resistive loads and class DC-12 applicable to DC resistive loads.
Note 6. T10JH to T100JH and N125HM to N800HM use auxiliary contacts that do not have a twin contact shape. Electrical durability is 200,000 operations at DC24 V [10 A].
Note 7. Reversible T10JH to T20JH (including models with "MSO") can also be manufactured. For reversible T21JH to T100 JH and N125HM to N800HM, magnetic contactors can be manufactured, but models with "MSO" cannot.
Note 8. Do not use the auxiliary contacts of T10JH to T100JH and N125HM to N800HM for self-retaining contacts or reversible electrical interlocks. Using contacts with the minimum applicable load or less will decrease contact reliability.

## Selection and Application

### 2.7 Contact Reliability of Main Contacts and Auxiliary Contacts

The minimum working voltage and current of the main and auxiliary contacts of the $\mathrm{S}, \mathrm{SD}, \mathrm{SL}(\mathrm{D})-\mathrm{T} / \mathrm{N}$ type and $\mathrm{SD}-\mathrm{Q}$ type Magnetic Contactors and the contact of the SR, SRD, SRL(D)-T/K type Contactor Relays vary depending on the allowable failure rate. Apply the following diagrams.

- The contact reliability reduces when a contact is connected in series or when the current is applied and broken at the time of opening and closing the contact.
Prescribe remedies such as connecting the contact in parallel (providing redundancy).
- If a reliability higher than the contact reliability given in Diagram 1 to Diagram 7 is required, the contacts must be connected in parallel (redundant).


## Magnetic Contactors



Fig 1. S, SD, SL(D)-T/N Main Circuit


Fig. 3. S, SD, SL(D)-T/N Auxiliary Contact
UN-AX, UT-AX11


Fig. 2. SD-Q11, Q12, SD-QR11, QR12 Main Contact


Fig. 4. SD-Q11, Q12, SD-QR11, QR12 Auxiliary Contact

Note 1: The contact reliability indicates the failure rate $\lambda 60$ (the number of failures/the number of opening and closing operations, per contact) at 60\% reliability standard. This reliability is applied when the product is in use under a clean atmosphere in the standard specification environment (Refer to page 64).
Note 2: The contact resistance of the contacts may change due to economical corrosion and that may affect the contacts in the case of a light load. It is recommended that regular inspections to be conducted, with load opening and closing performed several times in the inspection, and that consideration be provided on the system side.

## Contactor Relays



Fig. 5. SR, SRD, SRL(D)-K100


Fig. 6. SR/SR-D-T5, T9


Fig. 7. SRD- $\square$ JH (Large Capacity)

### 2.8 Coil Types and Rating

### 2.8.1 AC Operated Type

## - For S-T10 to T50, B-T21, SR-T5/T9 Types

| Coil <br> Designation | Rated Voltage [V] | Coil Indication |
| :---: | :---: | :---: |
|  | $50 \mathrm{~Hz} / 60 \mathrm{~Hz}$ |  |
| AC48V | 24 | Rated Voltage/ |
| AC100V | 48 to 50 |  |
| AC200V | 200 to 240 |  |
| AC300V | 260 to 300 |  |
| AC400V | 380 to 440 |  |
| AC500V | 460 to 550 |  |

Note 1. Coil designation AC100V and AC200V are standard products.
Note 2. Some applicable models, such as the delay open type (S-T $\square D L$ ), have different coil ratings. Please check the individual pages.
Note 3. When ordering you may indicate a single rating (e.g. 200 V 60 Hz ); however, the rated voltage of the product will be as displayed above.

- For S-N38/N48, SR-K100 Types

| Coil | Rated Voltage [V] |  | Coil Indication |
| :---: | :---: | :---: | :---: |
|  | 50 Hz | 60 Hz |  |
| AC24V | 24 | 24 |  |
| AC48V | 48 to 50 | 48 to 50 |  |
| AC100V | 100 | 100 to 110 |  |
| AC120V | 110 to 120 | 115 to 120 |  |
| AC127V | 125 to 127 | 127 |  |
| AC200V | 200 | 200 to 220 | Rated Voltage/ |
| AC220V | 208 to 220 | 220 |  |
| AC230V | 220 to 240 | 230 to 240 |  |
| AC260V | 240 to 260 | 260 to 280 |  |
| AC380V | 346 to 380 | 380 |  |
| AC400V | 380 to 415 | 400 to 440 |  |
| AC440V | 415 to 440 | 460 to 480 |  |
| AC500V | 500 | 500 to 550 |  |


| Coil Designation | Rated Voltage [V] | Coil Indication | Varistor Voltage [V] |
| :---: | :---: | :---: | :---: |
|  | $50 \mathrm{~Hz} / 60 \mathrm{~Hz}$ |  |  |
| AC24V | 24 | Rated Voltage/ Frequency | 120 |
| AC48V | 48 to 50 |  | 120 |
| AC100V | 100 to 127 |  | 470 |
| AC200V | 200 to 240 |  | 470 |
| AC300V | 260 to 300 |  | 910 |
| AC400V | 380 to 440 |  | 910 |

Note 1. Add "SA" to the end of the type name to order the operation coil surge absorber mounted type (varistor). Example: S-T10SA AC100V
Note 2. When ordering you may indicate a single rating (e.g. 200 V 60 Hz ); however, the rated voltage of the product will be as displayed above.

Note 1. Coil designation AC100V and AC200V are standard products.
Note 2. When ordering you may indicate a single rating (e.g. 200 V 60 Hz ); however, the rated values of the product will be as displayed to the left.
Coil designations for the below voltages and frequencies are as follows.
$220 \mathrm{~V} 60 \mathrm{~Hz} \rightarrow$ Coil designation AC200V
$380 \mathrm{~V} 50 \mathrm{~Hz} \rightarrow$ Coil designation AC400V
$240 \mathrm{~V} 50 \mathrm{~Hz} \rightarrow$ Coil designation AC230V
$220 \mathrm{~V} 50 \mathrm{~Hz} \rightarrow$ Coil designation AC230V
$415 \mathrm{~V} 50 \mathrm{~Hz} \rightarrow$ Coil designation AC400V

Note 1. Append "SA" to the end of the model name when ordering for a type with an integrated surge absorber (varistor). E.g. S-N38SA AC100V

Note 2. When ordering you may indicate a single rating (e.g. 200 V 60 Hz ); however, the rated values of the product will be as displayed to the left.
Coil designations for the below voltages and frequencies are as follows.

220 V $60 \mathrm{~Hz} \rightarrow$ Coil designation AC200V
$240 \mathrm{~V} 50 \mathrm{~Hz} \rightarrow$ Coil designation AC230V
$220 \mathrm{~V} 50 \mathrm{~Hz} \rightarrow$ Coil designation AC230V
Note 3. Models other than those on the left are not manufactured.

## For S-T65QM to T100QM Types

 For S-N125QM to N400QM Types| Coil | Rated Voltage [V] | Coil <br> Designation |
| :---: | :---: | :---: |
| Indication |  |  |
| AC100V | $50 \mathrm{~Hz} / 60 \mathrm{~Hz}$ | Rated Voltage/ |
| AC200V | 100 to 127 | Frequency |

Note 1. Models other than AC100V, AC200V are not manufactured.

Refer below for information regarding model names for coils not listed above.
SH-V $\square$ :Page 260

## - For S-N38SA/N48SA Types

| Coil Designation | Rated Voltage [V] |  | Coil Indication | Varistor Voltage [V] |
| :---: | :---: | :---: | :---: | :---: |
|  | 50 Hz | 60 Hz |  |  |
| AC24V | 24 | 24 | Rated <br> Voltage/ <br> Frequency | 120 |
| AC48V | 48 to 50 | 48 to 50 |  | 120 |
| AC100V | 100 | 100 to 110 |  | 470 |
| AC120V | 110 to 120 | 115 to 120 |  | 470 |
| AC127V | 125 to 127 | 127 |  | 470 |
| AC200V | 200 | 200 to 220 |  | 470 |
| AC220V | 208 to 220 | 220 |  | 470 |
| AC230V | 220 to 240 | 230 to 240 |  | 470 |

- For S-T65 to T100 Types

For S-N125 to N800, B-N65/N100, DU-N30 to N260 Types

| Coil <br> Designation | Rated Voltage [V] | Coil <br> Indication |
| :--- | :---: | :---: |
|  | $50 \mathrm{~Hz} / 60 \mathrm{~Hz}$ |  |
| AC48V(Note1) | 24 |  |
| AC100V | 48 to 50 |  |
| AC200V | 100 to 127 | Rated <br> Voltage/ |
| AC300V | 200 to 240 | 260 to 350 |
| Frequency |  |  |
| AC400V | 280 to 440 |  |
| AC500V | 460 to 550 |  |

Note 1. AC24V and AC48V coils for the model names below are not manufactured.
AC24V Coil: S-N180/N220, N300/N400, N600/N800 DU-N180, N260
AC48V Coil: S-N600/N800
Note 2. Some applicable models, such as the delay open type (S-T $\square \mathrm{DL}, \mathrm{S}-\mathrm{N} \square \mathrm{DL}$ ), have different coil ratings. Please check the individual pages.

The coil designation is a symbol to be specified when ordering. Please contact us regarding production capabilities for special nominal coil voltages. Special coils are produced without receiving certification from the various standards. (No Certification Symbols)

## Selection and Application

### 2.8.2 DC Operated Type

- For SD-T12 to T100, BD-T21, SRD-T5/T9 Types

| Coil <br> Designation | Rated Voltage | Coil Indication |
| :--- | :---: | :---: |
| DC12V | DC12 V |  |
| DC24V | DC24 V |  |
| DC48V | DC48 V |  |
| DC100V | DC100 V | Rated Voltage |
| DC110V | DC110 V |  |
| DC125V | DC120 to DC125 V |  |
| DC200V | DC200 V |  |
| DC220V | DC220 V |  |

Note 1. Operation coil terminals have polarity (excluding T35 to T100). Connect terminal number A1 (+) to the positive and A2 (-) to the negative sides.
Note 2. If the operating power supply is rectified, then switch the coil on the DC side.

## - For SD-N125 to SD-N400, BD-N65/N100,

 DUD-N30 to N260 Types For SRD-K100| Coil <br> Designation | Rated Voltage | Coil Indication |
| :--- | :---: | :---: |
| DC12V | DC12 V |  |
| DC24V | DC24 V |  |
| DC48V | DC48 V | Rated Voltage |
| DC100V | DC100 V |  |
| DC110V | DC110 V |  |
| DC125V | DC120 to DC125 V |  |
| DC200V | DC200 V |  |
| DC220V | DC220 V |  |

- For SD-T12SA to T50SA, BD-T21SA, SRD-T5SA/T9SA Types

| Coil <br> Designation | Rated Voltage | Coil Indication | Varistor Voltage |
| :---: | :---: | :---: | :---: |
| DC12V | DC12 V | Rated Voltage | 47 |
| DC24V | DC24 V |  | 47 |
| DC48V | DC48 V |  | 120 |
| DC100V | DC100 V |  | 470 |
| DC110V | DC110 V |  | 470 |
| DC125V | DC120 to 125 V |  | 470 |
| DC200V | DC200 V |  | 470 |
| DC220V | DC220 V |  | 470 |

Note 1. Add "SA" to the end of the type name to order the operation coil surge absorber mounted type (varistor). Example: SD-T21SA DC100V
Note 2. Operation coil terminals have polarity (excluding T35SA to T50SA). Connect terminal number A1 (+) to the positive and A2 (-) to the negative sides.
Note 3. Models other than those above are not manufactured.

Note 1. The coil has no polarity.
Note 2. If the operating power supply is rectified, then switch the coil on the DC side.
Note 3. SD-N125 to N400, DUD-N60 to N260 types have 2 internal coils connected in series.

For SD-N600/N800 Types

| Coil <br> Designation | Rated Voltage | Coil Indication |
| :--- | :---: | :---: |
| DC24V | DC24 V |  |
| DC48V | DC48 V | RC100 to 110 V |
| DC100V | DC1 |  |
| DC125V | DC120 to 125 V |  |
| DC200V | DC200 to 220 V |  |

Note 1. Operation coil terminals have polarity. Connect terminal number A1 (+) to the positive and A2 (-) to the negative sides.
Note 2. If the operating power supply is rectified, then switch the coil on the DC side.
Note 3. DC12V models are not manufactured.

Refer below for information regarding model names for coils not listed above.
SD-Q $\square$ : Page 244
SHD-V $\square$ : Page 260

### 2.8.3 Mechanically Latched Type

For SL(D)-T21 to T100, SL(D)-N125 to SL(D)-N800, SRL(D)-T5 Types

| For AC |  |  |
| :---: | :---: | :---: |
| Coil Designation | Rated Voltage (V) $50 / 60 \mathrm{~Hz}$ | Coil Indication |
| AC100V | 100 to 127 | Rated Voltage/ Frequency |
| AC200V | 200 to 240 |  |
| AC300V | 260 to 350 |  |
| AC400V | 380 to 440 |  |
| AC500V | 460 to 550 |  |


| For DC |  |  |
| :--- | :---: | :---: |
| Coil <br> Designation | Rated Voltage | Coil <br> Indication |
| DC12V (Note 2) | DC12 V |  |
| DC24V | DC24 V | Rated <br> Voltage |
| DC48V | DC48 V |  |
| DC100V | DC100V to 110 V |  |
| DC120V to 125 V |  |  |
| DC200V | DC200V to 220 V |  |

Note 1. AC coils other than those shown to the left can be manufactured with ratings as below.
For SRL-T5 and SL-T21:
AC24V ( $24 \mathrm{~V} 50 / 60 \mathrm{~Hz}$ )
AC48V ( 48 to $50 \mathrm{~V} 50 / 60 \mathrm{~Hz}$ )
Note 2. DC12V models are not manufactured for N125 to N800 types.
Note 3. DC coils have no polarity.

### 2.9 Properties

## AC Operated Type

| Model Name | Input [VA] |  | Power Consumption [W] | Operating Voltage [V] |  | Coil Current [mA] | Operating Time [ms] |  | Operating Transformer Capacity [VA] |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Inrush | Regular |  | Close | Open |  | Coil ON $\rightarrow$ Main Contact ON | Coil OFF $\rightarrow$ Main Contact OFF |  |
| S-T10, T12 | 45 | 7 | 2.2 | 120 to 150 | 75 to 115 | 30 | 12 to 18 | 5 to 20 | 15 to 30 |
| S-T20 | 45 | 7 | 2.2 | 120 to 150 | 75 to 115 | 30 | 12 to 18 | 5 to 20 | 15 to 30 |
| S-T21, T25 | 75 | 7 | 2.4 | 125 to 155 | 80 to 115 | 30 | 13 to 20 | 5 to 15 | 15 to 30 |
| S-T32 | 55 | 4.5 | 1.8 | 125 to 155 | 80 to 115 | 20 | 15 to 22 | 5 to 15 | 15 to 30 |
| S-T35, T50 | 110 | 10 | 3.8 | 120 to 150 | 80 to 115 | 45 | 10 to 20 | 5 to 14 | 30 to 50 |
| S-T65, 780 | 115 | 20 | 2.2 | 110 to 135 | 60 to 100 | 67 | 20 to 30 | 35 to 65 | 30 to 50 |
| S-T100 | 210 | 23 | 2.8 | 110 to 135 | 60 to 100 | 85 | 20 to 35 | 50 to 100 | 50 to 75 |
| S-N125 | 270 | 24 | 2.9 | 110 to 135 | 70 to 105 | 100 | 20 to 30 | 60 to 110 | 75 to 100 |
| S-N150 | 270 | 24 | 2.9 | 110 to 135 | 70 to 105 | 100 | 22 to 32 | 60 to 110 | 75 to 100 |
| S-N180, N220 | 440 | 40 | 4.2 | 110 to 135 | 70 to 105 | 165 | 25 to 35 | 70 to 130 | 100 to 150 |
| S-N300, N400 | 440 | 50 | 6.1 | 110 to 135 | 70 to 105 | 200 | 30 to 40 | 90 to 150 | 100 to 150 |
| S-N600, N800 | 790 | 90 | 17.0 | 108 to 130 | 60 to 90 | 340 | 51 to 80 | 57 to 93 | 150 to 250 |
| T65QM, T80QM | 115 | 20 | 2.2 | 110 to 135 | 60 to 100 | 67 | 20 to 30 | 12 to 30 | 30 to 50 |
| T100QM | 210 | 23 | 2.8 | 110 to 135 | 60 to 100 | 85 | 20 to 35 | 13 to 30 | 50 to 75 |
| S-N125QM | 270 | 24 | 2.9 | 110 to 135 | 70 to 105 | 100 | 20 to 30 | 15 to 30 | 75 to 100 |
| S-N150QM | 270 | 24 | 2.9 | 110 to 135 | 70 to 105 | 100 | 22 to 32 | 15 to 30 | 75 to 100 |
| S-N180QM, N220QM | 440 | 40 | 4.2 | 110 to 135 | 70 to 105 | 165 | 25 to 35 | 20 to 40 | 100 to 150 |
| S-N300QM, N400QM | 440 | 50 | 6.1 | 110 to 135 | 70 to 105 | 200 | 30 to 40 | 20 to 40 | 100 to 150 |

Note 1. The above indicates rough property indices for AC200V coils.
Note 2. The operating voltage is that at a $20^{\circ} \mathrm{C}$ cold state at 60 Hz . Voltages for coils other than AC200V can be calculated proportionately. E.g.: For a AC100V coil, operating voltage $\approx(100 \div 200) \times$ operating voltage in table above

Note 3. The input and power consumption are average values. These are almost the same for coils other than AC200V.
Note 4. The coil current is the average normal value with a $220 \mathrm{~V}, 60 \mathrm{~Hz}$ applied voltage. Divide the regular input by the coil voltage for coils other than AC200V. E.g.: For a AC100V coil, coil current $\approx$ input from table above $\div 100$
Note 5. The drive time is that with $200 \mathrm{~V}, 60 \mathrm{~Hz}$ applied to a standard auxiliary contact arrangement. These are almost the same for coils other than AC200V.
Note 6. S-T $\square$ QM and S-N $\square$ QM are open time quick motion types.
Refer below for information regarding model names for coils other than S-T/N $\square$.
SR-T $\square$ : Page 164
B-T/N $\square$ : Page 250
DU-N $\square$ : Page 254
SH-V $\square$ : Page 260

DC Operated Type

| Model Name | Coil Properties |  |  |  | Operating Voltage [V] |  | Operating Time [ms] |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Coil Current <br> $[\mathrm{A}]$ | Power <br> Consumption WW] | Coil Time <br> Constant [ms] | Close | Open | Coil ON $\rightarrow$ <br> Main Contact ON | Coil OFF $\rightarrow$ <br> Main Contact OFF |  |
|  | 0.033 | $3.3(2.2)$ | $40(45)$ | 60 to 75 | 10 to 30 | $60(85)$ | 10 |  |
| SD-T20 | 0.033 | $3.3(2.2)$ | $40(45)$ | 60 to 75 | 10 to 30 | $60(85)$ | 10 |  |
| SD-T21 | 0.033 | $3.3(2.2)$ | $50(40)$ | 60 to 75 | 10 to 30 | $65(90)$ | 20 |  |
| SD-T32 | 0.033 | $3.3(2.2)$ | $50(40)$ | 60 to 75 | 10 to 30 | $70(95)$ | 20 |  |
| SD-T35, T50 | 0.09 | 9 | 40 | 50 to 65 | 15 to 35 | 50 | 8 |  |
| SD-T65, T80 | 0.18 | 18 | 65 | 52 to 63 | 20 to 35 | 50 | 13 |  |
| SD-T100 | 0.24 | 24 | 80 | 50 to 65 | 15 to 30 | 75 | 18 |  |
| SD-N125 | 0.31 | 31 | 100 | 50 to 63 | 16 to 28 | 125 | 22 |  |
| SD-N150 | 0.31 | 31 | 100 | 50 to 63 | 17 to 30 | 135 | 37 |  |
| SD-N220 | 0.41 | 41 | 125 | 52 to 61 | 12 to 25 | 145 | 40 |  |
| SD-N300, N400 | 0.55 | 55 | 220 | 53 to 62 | 12 to 25 | 175 | 55 |  |
| SD-N600, N800 | $0.72(6.0)$ | $72(600)$ | 50 | 54 to 62 | 23 to 42 | 105 | 80 |  |

Refer below for information regarding model names for coils other than SD-T/N $\square$.
SRD-T $\square$ : Page 166
SD-Q $\square$ : Page 244
BD-T/N $\square$ : Page 250
DUD-N $\square$ : Page 254 SHD-V $\square$ : Page 260

Note 1. The left table indicates rough property indices for DC100V coils.
The values in the parentheses for SD-T12 to T32 indicate rough property indices for DC12V or DC24V coils.
Note 2. The operating voltage is that at a $20^{\circ} \mathrm{C}$ cold state. Voltages for coils other than DC100V can be calculated proportionately.
E.g.: For a DC24V coil, operating voltage $\approx(24 \div 100) \times$ operating voltage in table above
Note 3. The power consumption and coil time constant are average values.
These are almost the same for coils other than DC100V.
Note 4. The coil current is the average normal value with DC100V applied. Divide the power consumption by the coil voltage for coils other than DC100V E.g.: For a DC24V coil, coil current $\approx$ power consumption from table above $\div 24$
Note 5. The drive time is that with DC100V applied to a standard auxiliary contact arrangement. These are almost the same for coils other than DC100V.
Note 6. The value in the parentheses for SD-N600, N800 types indicate the coil inrush current and momentary power consumption. There is no inrush current for other frames.
Note 7. The drive time (coil OFF $\rightarrow$ main contact OFF) slows down when combined with a surge absorber element, so care should be taken with sequence timing. Furthermore, use only after confirming there is no fault with the real-life application.

## Selection and Application

Mechanically Latched Type

| Frame | Inrush Input [VA] |  |  |  | Operating Voltage [V] |  |  |  | Operating Time [ms] |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | AC Operated |  | DC Operated |  | AC Operated |  | DC Operated |  | AC Operated |  | DC Operated |  |
|  | Close | Trip | Close | Trip | Close | Trip | Close | Trip | Close | Trip | Close | Trip |
| SL(D)-T21 | 80*2 | 110*2 | 40*2 | 150*2 | 150 | 95 | 127 | 112 | 15 | 10 | 20 | 9 |
| SL(D)-T35/T50 | 120*2 | 150*2 | 100*2 | 150*2 | 140 | 110 | 115 | 85 | 20 | 14 | 18 | 11 |
| SL(D)-T65/T80 | 120*1 | 250*2 | 120*1 | 200*2 | 130 | 85 | 120 | 75 | 23 | 11 | 18 | 13 |
| SL(D)-T100 | 250*1 | 250*1 | $\begin{aligned} & 250^{* 1} \\ & (400) \\ & \hline \end{aligned}$ | $\begin{aligned} & 300^{* 1} \\ & (500) \\ & \hline \end{aligned}$ | 130 | 95 | 115 | 90 | 30 | 15 | 29 | 18 |
| SL(D)-N125 | 300*1 | 350*1 | $\begin{aligned} & 350^{* 1} \\ & (500) \\ & \hline \end{aligned}$ | $\begin{aligned} & 350^{* 1} \\ & (500) \\ & \hline \end{aligned}$ | 120 | 85 | 110 | 80 | 30 | 14 | 26 | 17 |
| SL(D)-N150 | 300*1 | 350*1 | $\begin{aligned} & 350^{* 1} \\ & (500) \end{aligned}$ | $\begin{aligned} & 350 * 1 \\ & (500) \end{aligned}$ | 140 | 89 | 130 | 85 | 35 | 14 | 31 | 17 |
| SL(D)-N220 | 350*1 | 450*1 | $\begin{aligned} & 450 * 1 \\ & (600) \\ & \hline \end{aligned}$ | $\begin{aligned} & 500^{* 1} \\ & (700) \\ & \hline \end{aligned}$ | 125 | 99 | 110 | 90 | 35 | 18 | 31 | 17 |
| SL(D)-N300, N400 | 400*1 | 800*1 | $\begin{aligned} & 450^{* 1} \\ & (600) \\ & \hline \end{aligned}$ | $\begin{aligned} & \hline 800 * 1 \\ & (1100) \end{aligned}$ | 143 | 112 | 125 | 95 | 50 | 17 | 50 | 17 |
| SL(D)-N600, 800 | 1000*1 | 500*1 | 850*1 | 500*1 | 140 | 120 | 140 | 120 | 65 | 50 | 63 | 50 |

Note 1. The above indicates rough property indices for AC200V coils under AC operation (SL-T/N $\square$ ) and for DC200V coils under DC operation (SLD-T/N $\square$ ).
The Class 2 heat-resistant magnetic contactors SL(D)-T50FN and SL(D)-T50, which have different properties.
Note 2. The operating voltage is the average value at a $20^{\circ} \mathrm{C}$ cold state for both AC (at 60 Hz ) and DC operation. Voltages for coils other than AC200V or DC200V can be calculated proportionately. (E.g.: For a AC100V coil, operating voltage $=(100 \div 200) \times$ operating voltage in table above)
Note 3. The inrush input indicates the average value. However, the value in parentheses is the average value with DC120V applied to the DC125V coil. These values are almost the same for coils other than DC200V or AC200V, excluding DC125V. The values for AC24V and AC 48 V coils differ as per the table above.
Note 4. The drive time is the time taken from when the closing coil or tripping coil energizes until the main contact transitions (ON or OFF) when $220 \mathrm{~V}, 60 \mathrm{~Hz}$ is applied for AC operation or DC200V is applied for DC operation. These are almost the same for coils other than AC200V or DC200V.
Note 5. *1 types have integrated surge absorber function. (Excluding AC/DC 24 or 48V types. SLD-T65/T80 type integrated closing coils are rated for DC100, 125, 200V only) $* 2$ Coil surge absorber units can be additionally mounted.

Refer below for information regarding model names for coils other than SL(D)-T/N $\square$.
SRL(D)-T $\square$ : Page 168
SHL(D)-V $\square$ : Page 260

### 2.10 Performance

## Classification and Making / Breaking Capacity Test Criteria

JISC8201-4-1 Low Voltage Switching and Control Devices and the International Electrotechnical Commission (IEC) implement the following standards to govern the breaking and making capacities of AC contactors.

| Category | Making / Capacity Test JIS, IEC |  | $\begin{array}{\|c\|} \hline \text { Breaking Capacity Test } \\ \hline \text { JIS, IEC } \\ \hline \end{array}$ |  | Typical Application Example |
| :---: | :---: | :---: | :---: | :---: | :---: |
| JIS, IEC | Current | Power Factor | Current | Power Factor |  |
| AC-1 | 1.5le | 0.8 | 1.5le | 0.8 | Non-Inductive Or Low-Inductance Loads, Resistive Heaters |
| AC-2 | 41 e | 0.65 | 4 le | 0.65 | Wound Motor Starting, Running, Stopping |
| AC-3 | 10le | (Note 3) | 81 e | (Note 3) | Cage Induction Motor Starting, Running, Stopping |
| AC-4 | 12le | (Note 3) | 10le | (Note 3) | Cage Induction Motor Starting, Inching, Plugging |
| AC-5a | 31 e | 0.45 | 31 e | 0.45 | Switching Discharge Lamp Control Equipment |
| AC-5b | 1.5le | (Note 4) | 1.5le | (Note 4) | Switching Incandescent Lamps |
| AC-6a |  | 5) |  | 5) | Switching Transformers |
| AC-6b | (N | te 6) |  | te 6) | Switching Capacitor Banks |
| AC-8a | 6 le | (Note 3) | 61 e | (Note 3) | Control of Closed-Type Refrigerant Compressor Motors with Manual Return Overload Tripping Devices |
| AC-8b | 6 le | (Note 3) | 61 e | (Note 3) | Control of Closed-Type Refrigerant Compressor Motors with Automatic Return Overload Tripping Devices |

Note 1. le: Rated operating current. Note 2. Tested at a voltage 1.05 times greater than rated voltage.
Note 3. le $\leq 100$ A: 0.45 , le $>100$ A: 0.35 . Note 4. Carried out with an incandescent load.
Note 5. Class AC-6a le is 0.45 times that of class AC-3 le when switching a transformer with a peak inrush current less than 30 times greater than the rated current.
Note 6. Class AC-6b le can be found from the following formula when switching a single capacitor bank in a circuit with an estimated short-circuit current of ik at the location of the capacitor bank.

$$
\text { Class AC-6b le }=i k \frac{X^{2}}{(X-1)^{2}} \quad \text { Here, } x=13.3 \quad \frac{\text { Class AC-3 le }}{i k}
$$

Category AC-3 Rated Performance

- Performance of Magnetic Contactors

| Frame | Rated Operational Voltage [V] | Rated Operational Current [A] | Making and Breaking Capacities [A] |  | AC Operated Types (S- $\square$ ) |  |  | DC Operated Types (SD- $\square$ ) |  |  | Mechanically Latched Types (SL(D)-■) |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | Switching <br> Frequency <br> [Times/Hour] <br> category AC-3 | Switching Durability [x 10000] |  | Switching <br> Frequency <br> TTimes/four] <br> category $\mathrm{AC}-3$ | Switching Durability [x 10000] |  | Switching Frequency [Timeshthor] category AC-3 | Switching Durability [x 10000] |  |
|  |  |  | Making | Breaking |  | Mechanical | Electrical (category AC-3) |  | Mechanical | Electrical (category AC-3) |  | Mechanical | Electrical (category AC-3) |
| T10 | 220 | 11 | 110 | 88 | 1800 | 1000 | 200 | - | - | - | - | - | - |
|  | 440 | 73 | 90 130 | 72 |  | 1000 | 200 | - |  | - | - | - |  |
| T12 | 440 | 9 | 120 | 96 | 1800 |  | 200 | 1800 | 1000 | 200 | - | - | - |
| T20 | 220 | 18 | 180 | 144 | 1800 | 1000 | 200 | 1800 | 1000 | 200 | - | - | - |
|  | 440 | 18 | 180 | 144 |  |  | 100 |  |  | 100 |  |  |  |
| T21 | 220 | 20 | 250 | 200 | 1800 | 1000 | 200 | 1800 | 1000 | 200 | 1200 | 50 | 50 |
| T25 | 220 | 26 | 300 | 240 | 1800 | 1000 | 200 | - | - | - | - | - | - |
| 125 | 440 | 25 | 300 | 240 |  |  |  |  |  |  |  |  |  |
| T32 | 220 | 32 | 320 | 256 | 1800 | 1000 | 200 | 1800 | 1000 | 200 | - | - | - |
| T35 | 220 | 35 | 400 | 320 | 1800 | 1000 | 200 | 1800 | 1000 | 200 | 1200 | 50 | 50 |
| 135 | 440 | 32 | 400 | 320 |  |  |  |  |  |  |  |  |  |
| T50 | 220 440 | 50 | 550 500 | 440 | 1200 | 1000 | 200 | 1200 | 1000 | 200 | 1200 | 25 | 25 |
| T65 | 220 | 65 | 650 | 520 | 1200 | 500 | 200 | 1200 | 500 | 200 | 1200 | 25 | 25 |
| T65 | 440 | 65 | 650 | 520 |  |  |  |  |  |  |  |  |  |
| T80 | 220 | 80 | 850 | 680 | 1200 | 500 | 100 | 1200 | 500 | 100 | 1200 | 25 | 25 |
|  | 220 | 100 | 1050 | 840 | 1200 | 500 | 100 | 1200 | 500 | 100 | 1200 | 25 | 25 |
| T100 | 440 | 93 | 1050 | 840 |  |  |  |  |  |  |  |  |  |
| N125 | 220 | 125 | 1250 | 1000 | 1200 | 500 | 100 | 1200 | 500 | 100 | 1200 | 25 | 25 |
|  | 440 | 120 | 1200 | 960 |  |  |  |  |  |  |  |  |  |
| N150 | 220 | 150 | 1500 | 1200 | 1200 | 500 | 100 | 1200 | 500 | 100 | 1200 | 25 | 25 |
| 180 | 220 | 180 | 1800 | 1440 | 1200 | 500 | 100 | - | - | - | - | - | - |
| 180 | 440 | 180 | 1800 | 1440 |  |  |  |  |  |  |  |  |  |
| N220 | 220 | 220 | 2500 | 2000 | 1200 | 500 | 100 | 1200 | 500 | 100 | 1200 | 25 | 25 |
| N300 | 220 | 300 | 3000 | 2400 | 1200 | 500 | 100 | 1200 | 500 | 100 | 1200 | 25 | 25 |
| N300 | 440 | 300 | 3000 | 2400 |  |  |  |  |  |  |  |  |  |
| N400 | 220 | 400 | 4000 | 3200 | 1200 | 500 | 50 | 1200 | 500 | 50 | 1200 | 25 | 25 |
| N600 | 220 | 630 | 6300 | 5040 | 1200 | 500 | 50 | 1200 | 500 | 50 | 1200 | 10 | 10 |
| N600 | 440 | 630 | 6300 | 5040 |  |  |  |  |  |  |  |  |  |
| N800 | 440 | 800 | 8000 | 6400 | 1200 | 500 | 50 | 1200 | 500 | 50 | 1200 | 10 | 10 |

Note 1. The number of tests according to JISC8201-4-1 is shown in the table below.

|  | JIS |
| :---: | :---: |
| Making Capacities | 50 times |
| Breaking Capacities | 50 times |

Note 2. It has 13 times the making breaking capacity ( 1 time) of the rated operating current.
Note 3. The electrical durability test is conducted based on JIS C 8201-4-1.


Refer below for information regarding model performance not listed above.

```
SR,SRD,SRL(D)-T\square: Pages 164, 166, 168
SD-Q \(\square\) : Page 243
B(D)-T/N \(\square\) : Page 249
SH,SHD,SHL(D)-V \(\square\) : Page 259

\section*{Selection and Application}

\subsection*{2.11 Application to Motor Loads}

\section*{- Direct Start}

In the case of the standard (not including inching, etc.) direct start, a frame is selected in which the rated capacity of the magnetic starter and magnetic contactor will be equal to or greater than the rated capacity of the motor.
- Application to Standard Three-Phase (3 ø) Cage Motor

It indicates the heater designation of the thermal overload relay for the standard three-phase cage motor and frame of the applicable magnetic starter.


Note 1. The heater designation is a symbol to be specified when ordering.
Note 2. Refer to page 139 for details about selecting voltage and motor capacities for heater designations not listed in the above table.
Note 3. Please use N600/N800 in combination with TH-N600 and separately sold current transformer (Mitsubishi CW- \(\square\) ).

\section*{- Application to Standard Single-Phase (1 ø) Motor}

It indicates the heater designation of the thermal overload relay for the single-phase motor and frame of the applicable magnetic starter.


Note 1. The heater designation is a symbol to be specified when ordering.
Note 2. Refer to page 139 for details about selecting voltage and motor capacities for heater designations not listed in the above table.
Note 3. For the enclosed type (MS-T12), the applicable capacity of the 100 to 110 V motor is 0.4 kW .

\section*{Application to Motor Load Including Capacitor}

When connecting a phase advanced capacitor in parallel to the motor, a series reactor for the inrush current suppression during input should ideally be inserted in the capacitor. For small capacity motors, there are many cases where the reactor has been omitted as shown in the figure at right, and therefore the electrical durability of the magnetic contactor may be shortened. In this case, special attention is necessary for the application of the magnetic contactor. Please consult us when selecting.


Connection Example Figure of Motor Load Including Capacitor

\subsection*{2.12 Application to Star/Delta Starting}

Methods for star/delta starting include the use of 3 magnetic contactors (the 3-contactor type from figure 1), 2 magnetic contactors (the 2-contactor type from figure 2) or resistance insertion when switching from star to delta (the closedtransition type from figure 3).
Electrical interlocks are required to be installed between star (MCS or MCS1) and delta (MCD) magnetic contactors. 3 -contactor types are the most generally used and do not apply voltage to the motor windings when stopped, suppressing damage to the insulation due to leakage currents. 2-contactor types are more economical but continue to apply voltage to the motor windings when stopped, so are not suitable for applications with a lot of downtime such as with fire extinguishing facilities.
Closed-transition types do not cut motor power when switching from star to delta configurations, suppressing inrush current and voltage drops.
The table below compares the various current values for direct start and star/delta starting.
Page 50 shows a selection of various magnetic contactors and thermal overload relays for the connections in figure 1 and figure 2.
Additionally, when applied to the high-frequency motors, the transient inrush current tends to increase during star starting current and delta switching, which may call for a review of the contactor selected.
(Delta Short-Circuit)
(The dashed lines show the recommended circuit when connecting the phase advanced capacitor.)
Fig. 1. Star/Delta Starter Connection Diagram Example (3-Contactor)
\(\triangle\) The motor and equipment may be damaged if it is unable to switch from reduced voltage starting to full voltage running and continues in the reduced voltage starting state.

\section*{Comparison of Direct and Star/Delta Starting}
\begin{tabular}{c|c|c|c|c|c|c|c}
\hline \multirow{2}{*}{\begin{tabular}{c} 
Starting \\
Method
\end{tabular}} & \multicolumn{3}{|c|}{ Starting (Star Magnetic Contactors) } & \multicolumn{3}{c}{ Running (Delta Magnetic Contactors) } \\
\cline { 2 - 8 } & Starting Current & Torque & Contact Current & Contact Voltage & Full-Load Current & Contact Current & Contact Voltage \\
\hline Direct & 61 m & 1.5 T & 61 m & \(\mathrm{Em} / \sqrt{ } 3\) & Im & Im & \(\mathrm{Em} / \sqrt{ } 3\) \\
\hline Star/Delta & 21 m & 0.5 T & 21 m & \(\mathrm{Em} / \sqrt{ } 3\) & Im & \(\mathrm{Im} / \sqrt{ } 3\) & Em \\
\hline
\end{tabular}

Note 1. Im: Full-load current in delta configuration, Em: Line-to-line voltage, T: Rated torque
Note 2. Estimated torque value.

(The dashed lines show the recommended circuit when connecting the phase advanced capacitor.)
Fig. 2. Star/Delta Starter Connection Diagram Example (2-Contactor) (3-contactor types are recommended for applications with a lot of downtime)

Closed Transition Starter

(The dashed lines show the recommended circuit when connecting the phase advanced capacitor.)
Fig. 3. Closed Transition Type Star/Delta Starter Connection Diagram Example

\section*{Selection and Application}

\section*{Star/Delta Starter Model Selection}
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multicolumn{3}{|l|}{Applicable Standard Three-Phase Squirrel-cage Motors} & \multirow[t]{2}{*}{Magnetic Contactors for Main and Delta (MCM, MCD)} & \multirow[t]{2}{*}{\begin{tabular}{l}
Star Magnetic Contactors (MCS) Note 5 \\
Short Circuit Type: Star short circuit (Figs. 1, 2) [Delta short circuit (applicable to Fig. 1)]
\end{tabular}} & \multicolumn{2}{|l|}{Thermal Overload Relays (THR)} \\
\hline Rated Voltage [V] & Rated Capacity [kW] & Rated Current [A] & & & Model Name & Heater Designation \\
\hline \multirow{16}{*}{AC200 to 220 V} & 5.5 & 26 & S-T20 & S-T10 [S-T10] & TH-T25 & 22A \\
\hline & 7.5 & 34 & S-T21 & S-T12 [S-T10] & TH-T65 & 29A \\
\hline & 11 & 48 & S-T35 & S-T20 [S-T10] & TH-T65 & 42A \\
\hline & 15 & 65 & S-T50 & S-T25 [S-T12] & TH-T65 & 54A \\
\hline & 18.5 & 79 & S-T50 & S-T35 [S-T20] & TH-N120 & 67A \\
\hline & 22 & 93 & S-T65 & S-T35 [S-T20] & TH-N120 & 82A \\
\hline & 30 & 124 & S-T80 & S-T50 [S-T25] & TH-N120TAHZ & 105A \\
\hline & 37 & 152 & S-T100 & S-T65 [S-T35] & TH-N120TAHZ & 125A \\
\hline & 45 & 180 & S-N125 & S-T65 [S-T35] & TH-N220HZ & 150A \\
\hline & 55 & 220 & S-N150 & S-T80 [S-T50] & TH-N220HZ & 180A \\
\hline & 75 & 300 & S-N180 & S-T100 [S-T65] & TH-N400HZ & 250A \\
\hline & 90 & 360 & S-N220 & S-N125 [S-T80] & TH-N400HZ & 330A \\
\hline & 110 & 440 & S-N300 & S-N150 [S-T100] & TH-N400HZ & 330 A \\
\hline & 132 & 528 & S-N300 & S-N180 [S-N125] & TH-N600+CT & 500A \\
\hline & 160 & 640 & S-N400 & S-N220 [S-N125] & TH-N600+CT & 660A \\
\hline & 200 & 800 & S-N600 & S-N300 [S-N180] & TH-N600+CT & 660A \\
\hline \multirow{18}{*}{AC400 to 440 V} & 5.5 & 13 & S-T12 & S-T10 [S-T10] & TH-T25 & 11A \\
\hline & 7.5 & 17 & S-T20 & S-T10 [S-T10] & TH-T25 & 15A \\
\hline & 11 & 24 & S-T20 & S-T12 [S-T10] & TH-T25 & 22A \\
\hline & 15 & 32.5 & S-T21 & S-T20 [S-T10] & TH-T65 & 29A \\
\hline & 18.5 & 39.5 & S-T25 & S-T20 [S-T12] & TH-T65 & 35A \\
\hline & 22 & 46.5 & S-T35 & S-T20 [S-T12] & TH-T65 & 42A \\
\hline & 30 & 62 & S-T50 & S-T25 [S-T20] & TH-T65 & 54A \\
\hline & 37 & 76 & S-T50 & S-T35 [S-T20] & TH-N120 & 67A \\
\hline & 45 & 90 & S-T65 & S-T35 [S-T20] & TH-N120 & 82A \\
\hline & 55 & 110 & S-T65 & S-T50 [S-T25] & TH-N120TAHZ & 105A \\
\hline & 75 & 150 & S-T100 & S-T65 [S-T35] & TH-N120TAHZ & 125A \\
\hline & 90 & 180 & S-N125 & S-T65 [S-T50] & TH-N220HZ & 150A \\
\hline & 110 & 220 & S-N150 & S-T80 [S-T50] & TH-N220HZ & 180A \\
\hline & 132 & 264 & S-N180 & S-T100 [S-T65] & TH-N400HZ & 250A \\
\hline & 160 & 320 & S-N220 & S-N125 [S-T65] & TH-N400HZ & 330A \\
\hline & 200 & 400 & S-N300 & S-N150 [S-T80] & TH-N400HZ & 330A \\
\hline & 250 & 500 & S-N300 & S-N180 [S-N125] & TH-N600+CT & 500A \\
\hline & 300 & 600 & S-N400 & S-N220 [S-N125] & TH-N600+CT & 500A \\
\hline
\end{tabular}

Note 1. Star magnetic contactors are fully capable of withstanding a continuity current 2 times the rated current for a running time of 15 seconds, and shut off when the current falls to 0.8 times the motor rated current.
Note 2. The making current of delta contacts is \(6 / \sqrt{ } 3\) times the rated motor current.
Note 3. A saturable reactor (delay trip type, TH-T/N \(\square S R\) ) or thermal overload relay short-circuited during start-up may be required depending on thermal overload relay starting current/time.
Note 4. A timer (RT) for setting the star magnetic contactor running time can be applied as an on-delay timer with momentary contacts by using the control circuit connections shown in Figs. 1 to 3.
Note 5. 2-contactor systems cannot be applied to star magnetic contactors with short-circuited delta connections.
Note 6. Electrical durability of 300,000 operations for 3-contactor types and 100,000 operations for 2-contactor types.
Note 7 . Since 1 b contact is required for internal wiring, select S-T10 with auxiliary contact 1 b or S-T12.
Note 8. The thermal relay is intended for a line current detection. For a phase current detection, select a heater that can be set to \(1 / \sqrt{ } 3\) for the motor rated current.

\subsection*{2.13 Application to Resistive Loads}

Switching resistive loads such as electric heaters or heating equipment have minimal inrush current and large power factor, allowing a larger current value to be applied compared to the magnetic contactor than with motor loads. MS-T/N series magnetic contactors are manufactured based on the standards (JISC8201-4-1, JEM1038) and possess the following properties. If the actual usage conditions differ from these conditions, users are asked to perform evaluations themselves (using the actual equipment). JISC8201-4-1 and JEM1038 standards define the following duties for when applying resistive loads to magnetic contactors.

Standards for Resistive Loads
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow{2}{*}{Applications} & \multirow{2}{*}{Standard} & \multirow{2}{*}{Category} & \multicolumn{2}{|l|}{Making and Breaking Capacities} & \multicolumn{3}{|c|}{Electrical Durability} \\
\hline & & & Making & Breaking & Making & \multicolumn{2}{|r|}{Breaking} \\
\hline \multirow{2}{*}{Switching AC Resistive Loads} & JIS & AC-1 & \(1.5 \mathrm{le}, 1.05 \mathrm{Ee}, \cos _{0.8} \varnothing\) & \(1.5 \mathrm{le}, 1.05 \mathrm{Ee},{ }_{0.8}^{\cos \varnothing}\) & \[
\begin{array}{ll}
\text { le, Ee, } & \cos \varnothing \\
0.95
\end{array}
\] & \(\mathrm{le}, \mathrm{Ee}\), & \[
\begin{aligned}
& \cos \varnothing \\
& 0.95
\end{aligned}
\] \\
\hline & JEM & AC1 & \(1.5 \mathrm{le}, 1.1 \mathrm{Ee}, \begin{aligned} & \cos \varnothing \\ & 0.95\end{aligned}\) & \(1.5 \mathrm{le}, 1.1 \mathrm{Ee},{ }_{0}^{\cos \varnothing}\) & \[
\begin{array}{ll}
\text { le, Ee, } & \cos \varnothing \\
0.95
\end{array}
\] & \(\mathrm{le}, \mathrm{Ee}\), & \[
\begin{aligned}
& \cos \varnothing \\
& 0.95
\end{aligned}
\] \\
\hline \multirow{2}{*}{Switching DC Resistive Loads} & JIS & DC-1 & \(1.5 \mathrm{le}, 1.05 \mathrm{Ee}, \stackrel{\text { L/R }}{1(\mathrm{~ms})}\) & \(1.5 \mathrm{le}, 1.05 \mathrm{Ee}, \stackrel{L}{1 / \mathrm{R}} \mathrm{m}^{(\mathrm{ms})}\) & \[
\begin{array}{ll}
\mathrm{le}, \mathrm{Ee}, & \mathrm{~L} / \mathrm{R} \\
1(\mathrm{~ms})
\end{array}
\] & \(\mathrm{le}, \mathrm{Ee}\), & \[
\begin{aligned}
& \mathrm{L} / \mathrm{R} \\
& 1(\mathrm{~ms})
\end{aligned}
\] \\
\hline & JEM & DC1 & \(1.1 \mathrm{le}, 1.1 \mathrm{Ee}, \stackrel{\mathrm{L}}{1 / \mathrm{R}}\) 1(ms) & \(1.1 \mathrm{le}, 1.1 \mathrm{Ee}, \begin{aligned} & \text { L/R } \\ & 1(\mathrm{~ms})\end{aligned}\) & \[
\begin{array}{ll}
\mathrm{le}, \mathrm{Ee}, & \mathrm{~L} / \mathrm{R} \\
1(\mathrm{~ms})
\end{array}
\] & \(\mathrm{le}, \mathrm{Ee}\), & \[
\begin{aligned}
& \mathrm{L} / \mathrm{R} \\
& 1(\mathrm{~ms})
\end{aligned}
\] \\
\hline
\end{tabular}

Note 1. le: rated operating current, Ee: rated voltage, \(\cos \varphi\) : power factor, L/R: time constant.

\section*{Applying Resistive Loads to Magnetic Contactors}

The table below shows the ratings for when applying resistive loads to MS-T/N series magnetic contactors.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{3}{*}{\begin{tabular}{l}
Application \\
Frame
\end{tabular}} & \multicolumn{3}{|l|}{\multirow[t]{2}{*}{Category AC-1 Rated Operating Current [A]}} & \multicolumn{5}{|l|}{Category AC-1 Rated Capacity [kW]} & \multirow[t]{3}{*}{} & \multicolumn{4}{|l|}{\multirow[t]{2}{*}{Category DC-1 Rated Operating Current 3-Pole Series (2-Pole Series) [A]}} \\
\hline & & & & \multicolumn{3}{|c|}{Three-Phase} & \multicolumn{2}{|l|}{Single-Phase} & & & & & \\
\hline & 100 to 240 V & 400 to 440 V & 500 to 550 V & 200 to 240 V & 400 to 440 V & 500 to 550 V & 100 to 110 V & 200 to 240 V & & 24 V & 48 V & 110 V & 220 V \\
\hline T10 & 20 & 11 & 8 & 6.5 & 8 & 7 & 2 & 4 & 40 & 10(10) & 10(10) & 8(6) & 8(3) \\
\hline T12 & 20 & 13 & 11 & 6.5 & 10 & 9.5 & 2 & 4 & 40 & 12(12) & 12(12) & 12(10) & 12(7) \\
\hline T20 & 20 & 18 & 17 & 6.5 & 12 & 14.5 & 2 & 4 & 40 & 18(18) & 18(18) & 18(13) & 18(8) \\
\hline T21 & 32 & 32 & 32 & 11 & 22 & 25 & 3.2 & 6.4 & 64 & 20(20) & 20(20) & 20(15) & 20(10) \\
\hline T25, T32 & 32 & 32 & 32 & 11 & 22 & 25 & 3.2 & 6.4 & 64 & 25(25) & 25(25) & 25(25) & 22(12) \\
\hline T35 & 60 & 60 & 60 & 20 & 40 & 50 & 6 & 12 & 120 & 35(35) & 35(35) & 35(25) & 30(12) \\
\hline T50 & 80 & 80 & 60 & 27 & 55 & 50 & 8 & 16 & 160 & 50(50) & 50(40) & 50(35) & 40(15) \\
\hline T65 & 100 & 100 & 100 & 34 & 68 & 85 & 10 & 20 & 200 & 65(50) & 65(40) & 65(35) & 50(15) \\
\hline T80 & 120 & 120 & 100 & 41 & 83 & 85 & 12 & 24 & 240 & 80(80) & 80(65) & 80(50) & 60(20) \\
\hline T100 & 150 & 150 & 150 & 50 & 100 & 120 & 15 & 30 & 300 & 93(93) & 93(93) & 93(80) & 70(50) \\
\hline N125 & 150 & 150 & 150 & 50 & 100 & 120 & 15 & 30 & 330 & 120(120) & 120(100) & 100(80) & 80(50) \\
\hline N150 & 200 & 200 & 200 & 65 & 130 & 170 & 20 & 40 & 400 & 150(150) & 150(120) & 150(100) & 150(100) \\
\hline N180 & 260 & 260 & 260 & 90 & 180 & 220 & 26 & 52 & 520 & 180(180) & 180(180) & 180(150) & 180(150) \\
\hline N220 & 260 & 260 & 260 & 90 & 180 & 220 & 26 & 52 & 520 & 220(220) & 220(180) & 220(150) & 220(150) \\
\hline N300 & 350 & 350 & 350 & 120 & 240 & 300 & 35 & 70 & 700 & 300(300) & 300(240) & 300(200) & 300(200) \\
\hline N400 & 450 & 450 & 450 & 155 & 310 & 380 & 45 & 90 & 800 & 400(400) & 400(240) & 400(200) & 300(200) \\
\hline N600 & 660 & 660 & 660 & 220 & 440 & 570 & 63 & 126 & 1200 & 630(630) & 630(630) & 630(630) & 630(630) \\
\hline N800 & 800 & 800 & 800 & 270 & 540 & 700 & 80 & 160 & 1600 & 800(800) & 800(800) & 800(630) & 800(630) \\
\hline
\end{tabular}

Note 1. Use a terminal plate as per the figure below to give a uniform temperature rise on each pole for 3-pole parallel configurations.

Note 2. Connect contacts to both sides of the load for use in DC 2-pole series or 3-pole series applications as per the diagram below.
 Terminal Plate


2-Pole Series
3-Pole Series
Note 3. Electrical durability of 500,000 operations.
(Models with mechanical durability of 500,000 operations or less use the mechanical durability value)
Note 4. De-rate by \(10 \%\) if the current for T100 exceeds \(80 \%\).
Note 5. Switching frequencies are: T10 to T80: 1200 times/hour, T100, N125 to N800: 600 times/ hour.

\section*{Selection and Application}

\subsection*{2.14 Application to Lighting Loads}

When switching fluorescent lights, mercury lights and incandescent lights, the starting current (immediately after the magnetic contactor closes) can be several times greater (10 times for fluorescent lights, 2 times for mercury lights and 10 times for incandescent lights) than the regular current (after settled on). This starting current can be closecircuited and must be capable of withstanding the time until illumination and have a predetermined switching durability. Lighting loads are governed by JIS and IEC standards and defined as class AC-5a
(switching of discharge lamp control equipment) and \(\mathrm{AC}-5 \mathrm{~b}\) (switching incandescent lamps) (see page 46). However, the ratings and performance of class AC-3 can be substituted and the total regular current of the lighting load should be selected such that it is less than the rated operating current of the class AC-3 magnetic contactor. The below notes the number of applicable lamps for single-phase doublepole types per MS-T series magnetic contactor, based on the input current according to internal standards (article \(3-6-3,3-6-4\) ).

\subsection*{2.15 Phase Advanced Capacitor Switching}

\section*{Switching Capacitor Banks}

The following items should be investigated when using switching capacitors for power factor correction with magnetic contactors.
(1) Capacity to withstand the inrush current determined by the impedance of the circuit when switching.
(2) Conventional free air thermal current \(1.3 \times 1.1\) times greater than the capacitor's rated current. (From JISC4901 - Phase Advanced Capacitor Switching Explained)
(3) Zero re-ignition or recurring arcs (arcing after being shut-off) when breaking.

The table below shows the applicable capacity (independent bank switching) of MS-T/N series magnetic contactor with capacitive loads.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{3}{*}{\begin{tabular}{l}
Application \\
Frame
\end{tabular}} & \multicolumn{4}{|l|}{Three-Phase, With 6\% or More Series Reactor (Note 1)} & \multicolumn{4}{|l|}{Three-Phase, Without Series Reactor (Notes 2, 3)} & \multicolumn{4}{|l|}{Single-Phase, Without Series Reactor (Notes 2, 3)} \\
\hline & \multicolumn{2}{|l|}{200 to 240 V} & \multicolumn{2}{|l|}{400 to 440 V} & \multicolumn{2}{|l|}{200 to 240 V} & \multicolumn{2}{|l|}{400 to 440 V} & \multicolumn{2}{|l|}{200 to 240 V} & \multicolumn{2}{|l|}{400 to 440 V} \\
\hline & Capacity [kvar] & Current [A] & Capacity [kvar] & Current [A] & Capacity [kvar] & Current [A] & Capacity [kvar] & Current [A] & Capacity [kvar] & Current [A] & Capacity [kvar] & Current [A] \\
\hline T10 & 3.8 & 11 & 4.8 & 7 & 2 & 6 & 3 & 4.3 & 1.2 & 6 & 1.7 & 4.3 \\
\hline T12 & 4.5 & 13 & 6.2 & 9 & 3 & 9 & 4 & 6 & 1.8 & 9 & 2.4 & 6 \\
\hline T20 & 4.8 & 14 & 9.6 & 14 & 4 & 12 & 8.3 & 12 & 2.4 & 12 & 4.8 & 12 \\
\hline T21 & 6.9 & 20 & 13 & 20 & 5 & 15 & 10 & 15 & 3 & 15 & 6 & 15 \\
\hline T25, T32 & 7.6 & 22 & 15 & 22 & 7.6 & 22 & 15 & 22 & 4.4 & 22 & 8.8 & 22 \\
\hline T35 & 12 & 35 & 22 & 32 & 11 & 32 & 20 & 30 & 6.4 & 32 & 12 & 30 \\
\hline T50 & 17 & 50 & 31 & 46 & 15 & 45 & 27 & 40 & 9 & 45 & 16 & 40 \\
\hline T65 & 22 & 65 & 42 & 62 & 17 & 50 & 34 & 50 & 10 & 50 & 20 & 50 \\
\hline T80 & 27 & 80 & 51 & 75 & 22 & 65 & 40 & 60 & 13 & 65 & 24 & 60 \\
\hline T100 & 32 & 93 & 64 & 93 & 30 & 90 & 60 & 90 & 18 & 90 & 36 & 90 \\
\hline N125 & 36 & 105 & 72 & 105 & 34 & 100 & 69 & 100 & 20 & 100 & 40 & 100 \\
\hline N150 & 48 & 140 & 96 & 140 & 45 & 130 & 90 & 130 & 26 & 130 & 52 & 130 \\
\hline N180 & 62 & 180 & 124 & 180 & 62 & 180 & 124 & 180 & 36 & 180 & 72 & 180 \\
\hline N220 & 62 & 180 & 124 & 180 & 62 & 180 & 124 & 180 & 36 & 180 & 72 & 180 \\
\hline N300 & 84 & 245 & 169 & 245 & 80 & 230 & 160 & 230 & 46 & 230 & 92 & 230 \\
\hline N400 & 109 & 315 & 218 & 315 & 100 & 300 & 200 & 300 & 60 & 300 & 120 & 300 \\
\hline N600 & 159 & 461 & 319 & 461 & 150 & 430 & 300 & 430 & 86 & 430 & 172 & 430 \\
\hline N800 & 193 & 559 & 387 & 559 & 170 & 500 & 350 & 500 & 100 & 500 & 200 & 500 \\
\hline
\end{tabular}

Note 1. Applicable in situations where the series reactor is not saturable, the electrical durability is the same as class AC-3 (see page 47) and there are parallel banks.
Note 2. The peak wave amplitude of the inrush current when close-circuited is within 20 times the capacitor's rated current (actual value) and the electrical durability is approximately 200,000 operations.
Note 3. The applicable capacity is reduced for parallel banks without series reactors as the averaged current (determined by parallel bank capacity and circuit impedance) will flow.

\section*{Application to Lighting Loads/Phase Advanced Capacitor Switching}

\section*{- Motor Load and Simultaneous Switching}

The capacitor connections are as per the figure to the right; however, for Fig. (a) on the right, the thermal overload relay set value may require lowering by the full-load current of the motor according to the power factor correction percentage. Furthermore, for Fig. (c) on the right, the motor starting/ stopping magnetic contactor coil and switching capacitor magnetic contactor coil should be connected in parallel and must be switched simultaneously to prevent becoming a leading power factor when stopped.
When 1 motor and capacitor magnetic contactor is being switched, as per Figs. (a) and (b) on the right, the switching lifetime will be reduced more than if switching a motor alone.


MC: Magnetic Contactor, MCC: Capacitor Switching Magnetic Contactor THR: Thermal Overload Relay, M: Motor, SC: Phase Advanced Capacitor
Phase Advanced Capacitor Connection Location

\section*{Selection and Application}

\subsection*{2.16 Application to PLCs}

MS-T, MS-N and SD-Q series magnetic contactors have a operation coil with a small VA and no width-increasing rail attached; SD-Q types, in particular, can be directly driven by the output of DC 24 V 0.1 A transistors.
Refer to the PLC manual for correct usage, magnetic contactor switching frequency and managing back-emfs from the operation coil (inductive load).
TH-T and TH-N series thermal overload relays adopt 1a1b independent contacts as output contacts. Differing voltages can also be used.
The below table shows whether direct driving from PLCs is applicable.

\section*{- S(D)-T/N, SD-Q Series Magnetic Contactor PLC Direct Drive}


Note 1. o: applicable (1 operation coil per output pole), \(x\) : not applicable.
Note 2. The contact output value shows the electrical durability of the output relay. The transistor output value shows the applicable control circuit voltage.
Note 3. UN-SY \(\square\) and UT-SY \(\square\) are interface units (optional parts).
Note 4. Mechanically latched DC operated types (SRLD, SLD) are not applicable with any model.


\section*{Selection and Application}
- S(D)-T/N, SD-Q Series Magnetic Contactor PLC Direct Drive


Note 1. o: applicable (1 operation coil per output pole), \(x\) : not applicable
Note 2. The contact output value shows the electrical durability of the output relay. The transistor output value shows the applicable control circuit voltage. Note 3. UN-SY \(\square\) and UT-SY \(\square\) are interface units (optional parts).
Note 4. Mechanically latched DC operated types (SRLD, SLD) are not applicable with any model.
Note 5 . Doesn't comply with safety category 3 or above (dual circuitry) so use a separate safety relay.

\subsection*{2.17 Application to Inverter Circuits}

Select from the below items when using a magnetic contactor for input to a Mitsubishi inverter circuit.
Note 1. The motor capacity indicates the selection when using a 4-pole AC200 V/400 V 50 Hz standard Mitsubishi motor.
Note 2. Magnetic contactors are selected at Class AC-1. The electrical durability of magnetic contactors is 500,000 operations. When used for emergency stops while the motor is running, it is 25 operations.
If emergency stop operation or commercial operation is to be used, then a magnetic contactor with a Class AC-3 rated operation current should be selected to suit the motor rated current.
Note 3.55 K or less is the wire size for a maximum continuous allowable temperature of \(75^{\circ} \mathrm{C}\) ( HIV wire [ 600 V double-layer vinyl insulated wire]). This assumes that the ambient temperature is \(50^{\circ} \mathrm{C}\) or less and the wiring distance 20 m or less.
75 K or more is the wire size for a maximum continuous allowable temperature of \(90^{\circ} \mathrm{C}\) (LMFC [Flame-Retardant, Flexible, Cross-Linked Polyethylene Insulated Electric Wire], etc.). This assumes interior control panel wiring and ambient temperature of \(50^{\circ} \mathrm{C}\) or less.
(1) FR-A800 Series
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow{4}{*}{Voltage} & \multirow{4}{*}{\begin{tabular}{l}
Motor \\
Output (Note 1) \\
(kW)
\end{tabular}} & \multirow{4}{*}{Model Name of Applicable Inverter (ND Rating)} & \multicolumn{2}{|l|}{\multirow[t]{3}{*}{\begin{tabular}{l}
Input Magnetic Contactor (Note 2) \\
Power Factor Correction (AC or DC) Reactor Connection
\end{tabular}}} & \multicolumn{3}{|c|}{Recommended Wire Size ( \(\mathrm{mm}^{2}\) ) (Note 3)} \\
\hline & & & & & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{R/L1, S/L2, T/L3
Power Factor Correction (AC or DC)
Reactor Connection}} & \multirow[t]{3}{*}{U, V, W} \\
\hline & & & & & & & \\
\hline & & & No & Yes & No & Yes & \\
\hline \multirow{17}{*}{\begin{tabular}{l}
200 V \\
Class
\end{tabular}} & 0.4 & FR-A820-0.4K(00046) & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 0.75 & FR-A820-0.75K(00077) & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 1.5 & FR-A820-1.5K(00105) & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 2.2 & FR-A820-2.2K(00167) & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 3.7 & FR-A820-3.7K(00250) & S-T21 & S-T10 & 3.5 & 3.5 & 3.5 \\
\hline & 5.5 & FR-A820-5.5K(00340) & S-T35 & S-T21 & 5.5 & 5.5 & 5.5 \\
\hline & 7.5 & FR-A820-7.5K(00490) & S-T35 & S-T35 & 14 & 14 & 8 \\
\hline & 11 & FR-A820-11K(00630) & S-T35 & S-T35 & 14 & 14 & 14 \\
\hline & 15 & FR-A820-15K(00770) & S-T50 & S-T50 & 22 & 22 & 22 \\
\hline & 18.5 & FR-A820-18.5K(00930) & S-T65 & S-T50 & 38 & 22 & 22 \\
\hline & 22 & FR-A820-22K(01250) & S-T100 & S-T65 & 38 & 38 & 38 \\
\hline & 30 & FR-A820-30K(01540) & S-T100 & S-T100 & 60 & 60 & 60 \\
\hline & 37 & FR-A820-37K(01870) & S-N150 & S-N125 & 80 & 60 & 60 \\
\hline & 45 & FR-A820-45K(02330) & S-N180 & S-N150 & 100 & 100 & 100 \\
\hline & 55 & FR-A820-55K(03160) & S-N220 & S-N180 & 100 & 100 & 100 \\
\hline & 75 & FR-A820-75K(03800) & - & S-N300 & - & 125 & 125 \\
\hline & 90 & FR-A820-90K(04750) & - & S-N300 & - & 150 & 150 \\
\hline \multirow{25}{*}{\[
400 \mathrm{~V}
\]
Class} & 0.4 & FR-A840-0.4K(00023) & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 0.75 & FR-A840-0.75K(00038) & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 1.5 & FR-A840-1.5K(00052) & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 2.2 & FR-A840-2.2K(00083) & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 3.7 & FR-A840-3.7K(00126) & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 5.5 & FR-A840-5.5K(00170) & S-T21 & S-T12 & 2 & 2 & 2 \\
\hline & 7.5 & FR-A840-7.5K(00250) & S-T21 & S-T21 & 3.5 & 3.5 & 3.5 \\
\hline & 11 & FR-A840-11K(00310) & S-T21 & S-T21 & 5.5 & 5.5 & 5.5 \\
\hline & 15 & FR-A840-15K(00380) & S-T35 & S-T21 & 8 & 5.5 & 5.5 \\
\hline & 18.5 & FR-A840-18.5K(00470) & S-T35 & S-T35 & 14 & 8 & 8 \\
\hline & 22 & FR-A840-22K(00620) & S-T35 & S-T35 & 14 & 14 & 14 \\
\hline & 30 & FR-A840-30K(00770) & S-T50 & S-T50 & 22 & 22 & 22 \\
\hline & 37 & FR-A840-37K(00930) & S-T65 & S-T50 & 22 & 22 & 22 \\
\hline & 45 & FR-A840-45K(01160) & S-T100 & S-T65 & 38 & 38 & 38 \\
\hline & 55 & FR-A840-55K(01800) & S-T100 & S-T100 & 60 & 60 & 60 \\
\hline & 75 & FR-A840-75K(02160) & - & S-T100 & - & 60 & 60 \\
\hline & 90 & FR-A840-90K(02600) & - & S-N150 & - & 60 & 60 \\
\hline & 110 & FR-A840-110K(03250) & - & S-N180 & - & 80 & 80 \\
\hline & 132 & FR-A840-132K(03610) & - & S-N220 & - & 100 & 100 \\
\hline & 150 & FR-A840-160K(04320) & - & S-N300 & - & 125 & 125 \\
\hline & 160 & FR-A840-160K(04320) & - & S-N300 & - & 125 & 125 \\
\hline & 185 & FR-A840-185K(04810) & - & S-N300 & - & 150 & 150 \\
\hline & 220 & FR-A840-220K(05470) & - & S-N400 & - & \(2 \times 100\) & \(2 \times 100\) \\
\hline & 250 & FR-A840-250K(06100) & - & S-N600 & - & \(2 \times 100\) & \(2 \times 100\) \\
\hline & 280 & FR-A840-280K(06830) & - & S-N600 & - & \(2 \times 125\) & \(2 \times 125\) \\
\hline
\end{tabular}

\section*{Selection and Application}
(2) FR-F800 Series
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Voltage} & \multirow{3}{*}{\[
\begin{gathered}
\text { Motor } \\
\text { Output (Note 1) } \\
\text { (kW) }
\end{gathered}
\]} & \multirow{3}{*}{Model Name of Applicable Inverter (LD Rating)} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{\begin{tabular}{l}
Input Magnetic Contactor (Note 2) \\
Power Factor Correction (AC or DC) Reactor Connection
\end{tabular}}} & \multicolumn{3}{|c|}{Recommended Wire Size ( \(\mathrm{mm}^{2}\) ) ( Note 3 )} \\
\hline & & & & & \multicolumn{2}{|l|}{R/L1, S/L2, T/L3
Power Factor Correction (AC or DC)
Reactor Connection} & \multirow[t]{2}{*}{\(\mathrm{u}, \mathrm{v}, \mathrm{w}\)} \\
\hline & & & No & Yes & No & Yes & \\
\hline \multirow{17}{*}{\[
\begin{aligned}
& 200 \mathrm{~V} \\
& \text { Class }
\end{aligned}
\]} & 0.75 & FR-F820-0.75K(00046) & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 1.5 & FR-F820-1.5K(00077) & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 2.2 & FR-F820-2.2K(00105) & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 3.7 & FR-F820-3.7K(00167) & S-T21 & S-T10 & 3.5 & 3.5 & 3.5 \\
\hline & 5.5 & FR-F820-5.5K(00250) & S-T25 & S-T21 & 5.5 & 5.5 & 5.5 \\
\hline & 7.5 & FR-F820-7.5K(00340) & S-T35 & S-T25 & 8 & 5.5 & 5.5 \\
\hline & 11 & FR-F820-11K(00490) & S-T35 & S-T35 & 14 & 14 & 14 \\
\hline & 15 & FR-F820-15K(00630) & S-T50 & S-T50 & 22 & 22 & 22 \\
\hline & 18.5 & FR-F820-18.5K(00770) & S-T65 & S-T50 & 38 & 22 & 22 \\
\hline & 22 & FR-F820-22K(00930) & S-T100 & S-T65 & 38 & 38 & 38 \\
\hline & 30 & FR-F820-30K(01250) & S-T100 & S-T100 & 60 & 60 & 60 \\
\hline & 37 & FR-F820-37K(01540) & S-N150 & S-N125 & 80 & 60 & 60 \\
\hline & 45 & FR-F820-45K(01870) & S-N180 & S-N150 & 100 & 100 & 100 \\
\hline & 55 & FR-F820-55K(02330) & S-N220 & S-N180 & 100 & 100 & 100 \\
\hline & 75 & FR-F820-75K(03160) & - & S-N300 & - & 125 & 125 \\
\hline & 90 & FR-F820-90K(03800) & - & S-N300 & - & 150 & 150 \\
\hline & 110 & FR-F820-110K(04750) & - & S-N400 & - & 150 & 150 \\
\hline \multirow{25}{*}{\[
\begin{aligned}
& 400 \mathrm{~V} \\
& \text { Class }
\end{aligned}
\]} & 0.75 & FR-F840-0.75K(00023) & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 1.5 & FR-F840-1.5K(00038) & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 2.2 & FR-F840-2.2K(00052) & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 3.7 & FR-F840-3.7K(00083) & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 5.5 & FR-F840-5.5K(00126) & S-T21 & S-T12 & 2 & 2 & 2 \\
\hline & 7.5 & FR-F840-7.5K(00170) & S-T21 & S-T21 & 3.5 & 3.5 & 3.5 \\
\hline & 11 & FR-F840-11K(00250) & S-T21 & S-T21 & 5.5 & 5.5 & 5.5 \\
\hline & 15 & FR-F840-15K(00310) & S-T35 & S-T21 & 8 & 5.5 & 5.5 \\
\hline & 18.5 & FR-F840-18.5K(00380) & S-T35 & S-T35 & 14 & 8 & 8 \\
\hline & 22 & FR-F840-22K(00470) & S-T35 & S-T35 & 14 & 14 & 14 \\
\hline & 30 & FR-F840-30K(00620) & S-T50 & S-T50 & 22 & 22 & 22 \\
\hline & 37 & FR-F840-37K(00770) & S-T65 & S-T50 & 22 & 22 & 22 \\
\hline & 45 & FR-F840-45K(00930) & S-T100 & S-T65 & 38 & 38 & 38 \\
\hline & 55 & FR-F840-55K(01160) & S-T100 & S-T100 & 60 & 60 & 60 \\
\hline & 75 & FR-F840-75K(01800) & - & S-T100 & - & 60 & 60 \\
\hline & 90 & FR-F840-90K(02160) & - & S-N150 & - & 60 & 60 \\
\hline & 110 & FR-F840-110K(02600) & - & S-N180 & - & 80 & 80 \\
\hline & 132 & FR-F840-132K(03250) & - & S-N220 & - & 100 & 100 \\
\hline & 150 & FR-F840-160K(03610) & - & S-N300 & - & 125 & 125 \\
\hline & 160 & FR-F840-160K(03610) & - & S-N300 & - & 125 & 125 \\
\hline & 185 & FR-F840-185K(04320) & - & S-N300 & - & 150 & 150 \\
\hline & 220 & FR-F840-220K(04810) & - & S-N400 & - & \(2 \times 100\) & \(2 \times 100\) \\
\hline & 250 & FR-F840-250K(05470) & - & S-N600 & - & \(2 \times 100\) & \(2 \times 100\) \\
\hline & 280 & FR-F840-280K(06100) & - & S-N600 & - & 2×125 & \(2 \times 125\) \\
\hline & 315 & FR-F840-315K(06830) & - & S-N600 & - & \(2 \times 150\) & \(2 \times 150\) \\
\hline
\end{tabular}
(3) FR-CC2 Series
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Voltage} & \multirow[t]{3}{*}{\begin{tabular}{l}
Motor \\
Output (Note 1) (kW)
\end{tabular}} & \multirow{3}{*}{Model Name of Applicable Inverter} & \multicolumn{2}{|l|}{Input Magnetic Contactor (Note 2)} & \multicolumn{3}{|c|}{Recommended Wire Size ( \(\mathrm{mm}^{2}\) ) (Note 3)} \\
\hline & & & \multicolumn{2}{|l|}{Power Factor Correction (AC or DC) Reactor Connection} & Power & \[
\begin{aligned}
& \text { L3 } \\
& \hline \text { tion or } \mathrm{DC}) \\
& \text { tion }
\end{aligned}
\] & \multirow[t]{2}{*}{U, V, W} \\
\hline & & & No & Yes & No & Yes & \\
\hline \multirow{3}{*}{400 V} & 315 & FR-CC2-H315K & - & S-N600 & - & \(2 \times 150\) & - \\
\hline & 355 & FR-CC2-H355K & - & S-N600 & - & \(2 \times 200\) & - \\
\hline & 400 & FR-CC2-H400K & - & S-N800 & - & \(2 \times 200\) & - \\
\hline
\end{tabular}
(4) FR-E700 Series
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Voltage} & \multirow{3}{*}{Motor Output (Note 1) (kW)} & \multirow{3}{*}{Model Name of Applicable Inverter} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{```
Input Magnetic Contactor (Note 2)
Power Factor Correction (AC or DC)
    Reactor Connection
```}} & \multicolumn{3}{|c|}{Recommended Wire Size ( \(\mathrm{mm}^{2}\) ) (Note 3)} \\
\hline & & & & & \multicolumn{2}{|l|}{R/L1, S/L2, T/L3
Power Factor Correction (AC or DC)
Reactor Connection} & \multirow[t]{2}{*}{U, V, W} \\
\hline & & & No & Yes & No & Yes & \\
\hline \multirow{11}{*}{\begin{tabular}{l}
200 V \\
Class
\end{tabular}} & 0.1 & FR-E720-0.1K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 0.2 & FR-E720-0.2K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 0.4 & FR-E720-0.4K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 0.75 & FR-E720-0.75K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 1.5 & FR-E720-1.5K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 2.2 & FR-E720-2.2K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 3.7 & FR-E720-3.7K & S-T21 & S-T10 & 3.5 & 3.5 & 3.5 \\
\hline & 5.5 & FR-E720-5.5K & S-T35 & S-T21 & 5.5 & 5.5 & 5.5 \\
\hline & 7.5 & FR-E720-7.5K & S-T35 & S-T35 & 14 & 8 & 8 \\
\hline & 11 & FR-E720-11K & S-T35 & S-T35 & 14 & 14 & 14 \\
\hline & 15 & FR-E720-15K & S-T50 & S-T50 & 22 & 22 & 22 \\
\hline \multirow{9}{*}{\begin{tabular}{l}
400 V \\
Class
\end{tabular}} & 0.4 & FR-E740-0.4K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 0.75 & FR-E740-0.75K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 1.5 & FR-E740-1.5K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 2.2 & FR-E740-2.2K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 3.7 & FR-E740-3.7K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 5.5 & FR-E740-5.5K & S-T21 & S-T12 & 3.5 & 2 & 2 \\
\hline & 7.5 & FR-E740-7.5K & S-T21 & S-T21 & 3.5 & 3.5 & 3.5 \\
\hline & 11 & FR-E740-11K & S-T21 & S-T21 & 5.5 & 5.5 & 5.5 \\
\hline & 15 & FR-E740-15K & S-T35 & S-T21 & 8 & 5.5 & 5.5 \\
\hline
\end{tabular}
(5) FR-D700 Series
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Voltage} & \multirow[t]{3}{*}{Motor Output (Note 1) (kW)} & \multirow{3}{*}{Model Name of Applicable Inverter} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{\begin{tabular}{l}
Input Magnetic Contactor (Note 2) \\
Power Factor Correction (AC or DC) Reactor Connection
\end{tabular}}} & \multicolumn{3}{|c|}{Recommended Wire Size ( \(\mathrm{mm}^{2}\) ) (Note 3)} \\
\hline & & & & & \multicolumn{2}{|r|}{R/L1, S/L2, T/L3
Factor Correction (AC or DC)
Reactor Connection} & \multirow[t]{2}{*}{U, V, W} \\
\hline & & & No & Yes & No & Yes & \\
\hline \multirow{11}{*}{\[
\begin{aligned}
& 200 \text { V } \\
& \text { Class }
\end{aligned}
\]} & 0.1 & FR-D720-0.1K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 0.2 & FR-D720-0.2K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 0.4 & FR-D720-0.4K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 0.75 & FR-D720-0.75K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 1.5 & FR-D720-1.5K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 2.2 & FR-D720-2.2K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 3.7 & FR-D720-3.7K & S-T21 & S-T10 & 3.5 & 3.5 & 3.5 \\
\hline & 5.5 & FR-D720-5.5K & S-T35 & S-T21 & 5.5 & 5.5 & 5.5 \\
\hline & 7.5 & FR-D720-7.5K & S-T35 & S-T35 & 14 & 8 & 8 \\
\hline & 11 & FR-D720-11K & S-T35 & S-T35 & 14 & 14 & 14 \\
\hline & 15 & FR-D720-15K & S-T50 & S-T50 & 22 & 22 & 22 \\
\hline \multirow{9}{*}{\[
\begin{aligned}
& 400 \mathrm{~V} \\
& \text { Class }
\end{aligned}
\]} & 0.4 & FR-D740-0.4K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 0.75 & FR-D740-0.75K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 1.5 & FR-D740-1.5K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 2.2 & FR-D740-2.2K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 3.7 & FR-D740-3.7K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 5.5 & FR-D740-5.5K & S-T21 & S-T12 & 3.5 & 2 & 2 \\
\hline & 7.5 & FR-D740-7.5K & S-T21 & S-T21 & 3.5 & 3.5 & 3.5 \\
\hline & 11 & FR-D740-11K & S-T21 & S-T21 & 5.5 & 5.5 & 5.5 \\
\hline & 15 & FR-D740-15K & S-T35 & S-T21 & 8 & 5.5 & 5.5 \\
\hline
\end{tabular}
(6) FR-F700PJ Series
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Voltage} & \multirow[t]{3}{*}{Motor Output (Note 1) (kW)} & \multirow{3}{*}{Model Name of Applicable Inverter} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{\begin{tabular}{l}
Input Magnetic Contactor (Note 2) \\
Reactor or Filter Pack Connection
\end{tabular}}} & \multicolumn{3}{|c|}{Recommended Wire Size ( \(\mathrm{mm}^{2}\) ) (Note 3)} \\
\hline & & & & & \multicolumn{2}{|c|}{R/L1, S/L2, T/L3} & \multirow[t]{2}{*}{U, V, W} \\
\hline & & & No & Yes & No & Yes & \\
\hline \multirow{9}{*}{\begin{tabular}{l}
200 V \\
Class
\end{tabular}} & 0.4 & FR-F720PJ-0.4K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 0.75 & FR-F720PJ-0.75K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 1.5 & FR-F720PJ-1.5K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 2.2 & FR-F720PJ-2.2K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 3.7 & FR-F720PJ-3.7K & S-T21 & S-T10 & 3.5 & 3.5 & 3.5 \\
\hline & 5.5 & FR-F720PJ-5.5K & S-T35 & S-T21 & 5.5 & 5.5 & 5.5 \\
\hline & 7.5 & FR-F720PJ-7.5K & S-T35 & S-T35 & 14 & 8 & 8 \\
\hline & 11 & FR-F720PJ-11K & S-T35 & S-T35 & 14 & 14 & 14 \\
\hline & 15 & FR-F720PJ-15K & S-T50 & S-T50 & 22 & 22 & 22 \\
\hline \multirow{9}{*}{\begin{tabular}{l}
400 V \\
Class
\end{tabular}} & 0.4 & FR-F740PJ-0.4K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 0.75 & FR-F740PJ-0.75K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 1.5 & FR-F740PJ-1.5K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 2.2 & FR-F740PJ-2.2K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 3.7 & FR-F740PJ-3.7K & S-T10 & S-T10 & 2 & 2 & 2 \\
\hline & 5.5 & FR-F740PJ-5.5K & S-T21 & S-T12 & 3.5 & 2 & 2 \\
\hline & 7.5 & FR-F740PJ-7.5K & S-T21 & S-T21 & 3.5 & 3.5 & 3.5 \\
\hline & 11 & FR-F740PJ-11K & S-T21 & S-T21 & 5.5 & 5.5 & 5.5 \\
\hline & 15 & FR-F740PJ-15K & S-T35 & S-T21 & 8 & 5.5 & 5.5 \\
\hline
\end{tabular}

\section*{Selection and Application}

\subsection*{2.18 Application to Servo Circuits}

\subsection*{2.18.1 Selection Examples for MR-J4-GF/MR-J4-B/MR-J4-A}

Selection examples when using 600 V double-layered vinyl insulated wire (HIV wires) are listed below.
The wire size for \(\mathrm{U}, \mathrm{V}, \mathrm{W}\), and \(\oplus\) ) varies depending on the servo motor. For details about wires used for wiring to servo motors, refer to "Selection Example in HIV Wires for Servo Motors" in the catalog of "Mitsubishi Electric General Purpose AC Servo MELSERVO-J4" (L(NA)03056).
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Servo Amplifier Model Name} & \multirow[t]{2}{*}{Magnetic Contactor \({ }^{\text {(Note } 3,6)}\)} & \multicolumn{4}{|c|}{Wire Size \(\left[\mathrm{mm}^{2}\right]^{\text {(Note 5) }}\)} \\
\hline & & L1, L2, L3, \(\oplus\) & L11, L21 & P+, C & U, V, W, \(\oplus\) \\
\hline MR-J4-10GF(1)/B(1)/A(1) & S-T10 & \multirow{10}{*}{2 (AWG 14)} & \multirow{26}{*}{\[
\begin{gathered}
1.25 \text { to } 2 \\
\text { (AWG } 16 \text { to } 14 \text { ) }
\end{gathered}
\]} & \multirow{14}{*}{2 (AWG 14) \({ }^{\text {(Note 1) }}\)} & \multirow{9}{*}{AWG 18 to \(14{ }^{\text {(Note 4) }}\)} \\
\hline MR-J4-20GF/B/A & S-T10 & & & & \\
\hline MR-J4-20GF1/B1/A1 & S-T10 & & & & \\
\hline MR-J4-40GF/B/A & S-T10 & & & & \\
\hline MR-J4-40GF1/B1/A1 & S-T10 & & & & \\
\hline MR-J4-60GF/B/A & S-T10 & & & & \\
\hline MR-J4-70GF/B/A & S-T10 & & & & \\
\hline MR-J4-100GF/B/A (Three-Phase Power Input) & S-T10 & & & & \\
\hline \begin{tabular}{l}
MR-J4-100GF/B/A \\
(Single-Phase Power Input)
\end{tabular} & S-T10 & & & & \\
\hline \begin{tabular}{l}
MR-J4-200GF/B/A \\
(Three-Phase Power Input)
\end{tabular} & S-T21 & & & & \\
\hline MR-J4-200GF/B/A (Single-Phase Power Input) & S-T21 & \multirow[b]{5}{*}{3.5 (AWG 12)
5.5 (AWG 10)
8 (AWG 8)
14 (AWG 6)} & & & AWG 16 to \(10{ }^{(\text {Note 4) }}\) \\
\hline MR-J4-350GF/B/A & S-T21 & & & & \\
\hline MR-J4-500GF/B/A \({ }^{\text {(Note 2) }}\) & S-T35 & & & & \begin{tabular}{l}
2 to 5.5 \\
(AWG 14 to 10)
\end{tabular} \\
\hline MR-J4-700GF/B/A \({ }^{\text {(Note 2) }}\) & S-T50 & & & & 2 to 8 (AWG 14 to 8) \\
\hline MR-J4-11KGF/B/A \({ }^{\text {(Note 2) }}\) & S-T50 & & & 3.5 (AWG 12) \({ }^{\text {(Note 1) }}\) & \[
\begin{gathered}
5.5 \text { (AWG 10), } \\
8 \text { (AWG 8), } \\
14 \text { (AWG 6) }
\end{gathered}
\] \\
\hline MR-J4-15KGF/B/A \({ }^{\text {(Note 2) }}\) & S-T65 & 22 (AWG 4) & & \multirow[t]{2}{*}{5.5 (AWG 10) \({ }^{\text {(Note 1) }}\)} & \[
\begin{aligned}
& 8 \text { (AWG 8), } \\
& 22 \text { (AWG 4) }
\end{aligned}
\] \\
\hline MR-J4-22KGF/B/A \({ }^{\text {(Note 2) }}\) & S-T100 & 38 (AWG 2) & & & 38 (AWG 2) \\
\hline MR-J4-60GF4/B4/A4 & S-T10 & 2 (AWG 14) & & \multirow{7}{*}{2 (AWG 14) \({ }^{\text {(Note 1) }}\)} & \multirow{4}{*}{AWG 16 to \(14{ }^{\text {(Note 4) }}\)} \\
\hline MR-J4-100GF4/B4/A4 & S-T10 & 2 (AWG 14) & & & \\
\hline MR-J4-200GF4/B4/A4 & S-T10 & 2 (AWG 14) & & & \\
\hline MR-J4-350GF4/B4/A4 & S-T21 & 2 (AWG 14) & & & \\
\hline MR-J4-500GF4/B4/A4 \({ }^{\text {(Note 2) }}\) & S-T21 & 2 (AWG 14) & & & 3.5 (AWG 12) \\
\hline MR-J4-700GF4/B4/A4 \({ }^{\text {(Note 2) }}\) & S-T21 & 3.5 (AWG 12) & & & 5.5 (AWG 10) \\
\hline MR-J4-11KGF4/B4/A4 \({ }^{\text {(Note 2) }}\) & S-T35 & 5.5 (AWG 10) & & & \\
\hline MR-J4-15KGF4/B4/A4 \({ }^{\text {(Note 2) }}\) & S-T35 & 8 (AWG 8) & & & (AWG 8) \\
\hline MR-J4-22KGF4/B4/A4 \({ }^{\text {(Note 2) }}\) & S-T50 & 14 (AWG 6) & & 3.5 (AWG 12) \({ }^{\text {(Note 1) }}\) & \[
\begin{gathered}
5.5 \text { (AWG 10), } \\
8 \text { (AWG 8), } \\
14 \text { (AWG 6) }
\end{gathered}
\] \\
\hline
\end{tabular}

Note 1. Keep the wire length for the regenerative option within 5 m .
Note 2. When connecting to a terminal block, be sure to use the screws attached to the terminal block.
Note 3. Use a magnetic contactor with an operation delay time of 80 ms or less (the time from current application to the operation coil until the contact closes).
Note 4. The wire size indicates the applicable size for the servo amplifier connector.
Note 5. When complying with IEC/EN/UL/CSA standards, refer to "MELSERVO-J4 Instructions and Cautions for Safe Use of AC Servos" as enclosed with the servo amplifier.
Note 6. Install one no-fuse breaker and one magnetic contactor for each servo amplifier.

\subsection*{2.18.2 Selection Examples for MR-J4-DU}

Selection examples when using 600 V double-layered vinyl insulated wire (HIV wires) are listed below.
The wire size for \(\mathrm{U}, \mathrm{V}, \mathrm{W}\), and \(\oplus\) varies depending on the servo motor. For details about wires used for wiring to servo motors, refer to "Selection Example in HIV Wires for Servo Motors" in the catalog of "Mitsubishi Electric General Purpose AC Servo MELSERVO-J4" (L(NA)03056).
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Converter Unit Model Name} & \multirow{2}{*}{Drive Unit Model Name} & \multirow[t]{2}{*}{MagneticContactor (Note 1, 7)} & \multicolumn{4}{|c|}{Wire Size \(\left[\mathrm{mm}^{2}\right]^{\text {(Note 8) }}\)} \\
\hline & & & L1, L2, L3, © & L11, L21 & P2, C & P1, P2 \\
\hline MR-CV11K & \multirow[t]{13}{*}{} & S-T35 & 8 (AWG 8) & \multirow{19}{*}{\[
\begin{gathered}
1.25 \text { to } 2 \\
\text { (AWG } 16 \text { to 14) }
\end{gathered}
\]} & \multirow[t]{13}{*}{} & \multirow[t]{13}{*}{} \\
\hline MR-CV18K & & S-T65 & 22 (AWG 4) & & & \\
\hline MR-CV30K & & S-N125 & 38 (AWG 2) & & & \\
\hline MR-CV37K & & S-N125 & 60 (AWG 2/0) & & & \\
\hline MR-CV45K & & S-N150 & 60 (AWG 2/0) & & & \\
\hline MR-CV55K & & S-N220 & 80 (AWG 3/0) & & & \\
\hline MR-CV11K4 & & S-T21 & 5.5 (AWG 10) & & & \\
\hline MR-CV18K4 & & S-T35 & 8 (AWG 8) & & & \\
\hline MR-CV30K4 & & S-T65 & 14 (AWG 6) & & & \\
\hline MR-CV37K4 & & S-T80 & 22 (AWG 4) & & & \\
\hline MR-CV45K4 & & S-T100 & 22 (AWG 4) & & & \\
\hline MR-CV55K4 & & S-N125 & 38 (AWG 2) & & & \\
\hline MR-CV75K4 & & S-N150 & 60 (AWG 2/0) & & & \\
\hline \multirow[t]{2}{*}{MR-CR55K \({ }^{\text {(Note 6) }}\)} & Combined with MR-J4-DU30K_(-RJ) & S-N150 & 38 (AWG 2) & & \multirow{6}{*}{5.5 (AWG 10)} & 60 (AWG 2/0) \\
\hline & Combined with MR-J4-DU37K_(-RJ) & S-N180 & 60 (AWG 2/0) & & & 60 (AWG 2/0) \\
\hline \multirow{4}{*}{MR-CR55K4 \({ }^{\text {(Note 6) }}\)} & Combined with MR-J4-DU30K_4(-RJ) & S-T65 & 22 (AWG 4) & & & 22 (AWG 4) \\
\hline & Combined with MR-J4-DU37K_4(-RJ) & S-T80 & 22 (AWG 4) & & & 38 (AWG 2) \\
\hline & Combined with MR-J4-DU45K_4(-RJ) & S-T100 & 38 (AWG 2) & & & 38 (AWG 2) \\
\hline & Combined with MR-J4-DU55K_4(-RJ) & S-N150 & 38 (AWG 2) & & & 38 (AWG 2) \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|}
\hline \multirow{2}{*}{Drive Unit Model Name} & \multicolumn{2}{|c|}{Wire Size \(\left[\mathrm{mm}^{2}\right]{ }^{\text {(Note 8) }}\)} \\
\hline & U, V, W \(\oplus\) & L11, L21 \\
\hline MR-J4-DU900B(-RJ) & 14 (AWG 6) & \multirow{17}{*}{\[
\begin{gathered}
1.25 \text { to } 2 \\
\text { (AWG } 16 \text { to 14) }
\end{gathered}
\]} \\
\hline MR-J4-DU11KB(-RJ) & 14 (AWG 6) & \\
\hline MR-J4-DU15KB(-RJ) & 22 (AWG 4) & \\
\hline MR-J4-DU22KB(-RJ) & 38 (AWG 2) & \\
\hline \begin{tabular}{l}
MR-J4-DU30KB(-RJ) \\
MR-J4-DU30KA(-RJ)
\end{tabular} & 60 (AWG 2/0) & \\
\hline MR-J4-DU37KB(-RJ) & & \\
\hline MR-J4-DU37KA(-RJ) & 60 (AWG 2/0) & \\
\hline MR-J4-DU900B4(-RJ) & 8 (AWG 8) & \\
\hline MR-J4-DU11KB4(-RJ) & 8 (AWG 8) & \\
\hline MR-J4-DU15KB4(-RJ) & 8 (AWG 8) & \\
\hline MR-J4-DU22KB4(-RJ) & 14 (AWG 6) & \\
\hline MR-J4-DU30KB4(-RJ) & 22 (AWG 4) & \\
\hline MR-J4-DU30KA4(-RJ) & & \\
\hline \[
\begin{aligned}
& \hline \text { MR-J4-DU37KB4(-RJ) } \\
& \text { MR-J4-DU37KA4(-RJ) }
\end{aligned}
\] & 22 (AWG 4) & \\
\hline & 38 (AWG 2) & \\
\hline MR-J4-DU45KA4(-RJ) & 38 (AWG 2) & \\
\hline \begin{tabular}{l}
MR-J4-DU55KB4(-RJ) \\
MR-J4-DU55KA4(-RJ)
\end{tabular} & 38 (AWG 2) & \\
\hline
\end{tabular}

\subsection*{2.18.3 Selection Examples for MR-J4W2-B and MR-J4W3-B}

Selection examples when using 600 V double-layered vinyl insulated wire (HIV wires) are listed below.
The wire size for \(\mathrm{U}, \mathrm{V}, \mathrm{W}\), and \(\oplus\) varies depending on the servo motor. For details about wires used for wiring to servo motors, refer to "Selection Example in HIV Wires for Servo Motors" in the catalog of "Mitsubishi Electric General Purpose AC Servo MELSERVO-J4" (L(NA)03056).
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Servo Amplifier Model Name} & \multirow[t]{2}{*}{Magnetic Contactors} & \multicolumn{4}{|c|}{Wire Size \(\left[\mathrm{mm}^{2}\right]^{\text {(Note 3) }}\)} \\
\hline & & L1, L2, L3, © & L11, L21 & \(\mathrm{P}+, \mathrm{C}^{\text {(Note 5) }}\) & \(\mathrm{U}, \mathrm{V}, \mathrm{W}, \pm\) \\
\hline MR-J4W2-22B & \multirow[b]{4}{*}{Refer to the following table} & \multicolumn{2}{|r|}{\multirow[b]{4}{*}{2 (AWG 14)}} & & \multirow[b]{4}{*}{AWG 18 to \(14^{\text {(Note 2) }}\)} \\
\hline MR-J4W2-44B & & & & & \\
\hline MR-J4W2-77B & & & & & \\
\hline MR-J4W2-1010B & & & & & \\
\hline
\end{tabular}

MR-J4W3-222B following table

\section*{Selection and Application}

Selection Examples for MR-J4W2-B (Note 4)
\begin{tabular}{c|c|c|c}
\hline Total Rotary Servo Motor Output & Total Linear Servo Motor Continuous Thrust & Total Direct Drive Motor Output & Magnetic Contactor \({ }^{\text {Noie } 1,7}\) \\
\hline 300 W or less & - & - & S-T10 \\
\hline Over \(300 \mathrm{~W}, 600 \mathrm{~W}\) or less & 150 N or less & 100 W or less & \(\mathrm{S}-\mathrm{T10}\) \\
\hline Over \(600 \mathrm{~W}, 1 \mathrm{~kW}\) or less & Over \(150 \mathrm{~N}, 300 \mathrm{~N}\) or less & Over \(100 \mathrm{~W}, 252 \mathrm{~W}\) or less & \(\mathrm{S}-\mathrm{T10}\) \\
\hline Over \(1 \mathrm{~kW}, 2 \mathrm{~kW}\) or less & Over \(300 \mathrm{~N}, 720 \mathrm{~N}\) or less & Over \(252 \mathrm{~W}, 838 \mathrm{~W}\) or less & \(\mathrm{S}-\mathrm{T} 21\) \\
\hline
\end{tabular}

Selection Examples for MR-J4W3-B \({ }^{\text {(Note 4) }}\)
\begin{tabular}{c|c|c|c}
\hline Total Rotary Servo Motor Output & Total Linear Servo Motor Continuous Thrust & Total Direct Drive Motor Output & Magnetic Contactor Mee 1,7 \\
\hline 450 W or less & 150 N or less & - & S-T10 \\
\hline Over \(450 \mathrm{~W}, 800 \mathrm{~W}\) or less & Over \(150 \mathrm{~N}, 300 \mathrm{~N}\) or less & 252 W or less & \(\mathrm{S}-\mathrm{T10}\) \\
\hline Over \(800 \mathrm{~W}, 1.5 \mathrm{~kW}\) or less & Over \(300 \mathrm{~N}, 450 \mathrm{~N}\) or less & Over \(252 \mathrm{~W}, 378 \mathrm{~W}\) or less & \(\mathrm{S}-\mathrm{T} 21\) \\
\hline
\end{tabular}

Note 1. Use a magnetic contactor with an operation delay time of 80 ms or less (the time from current application to the operation coil until the contact closes).
Note 2. The wire size indicates the applicable size for the servo amplifier connector.
Note 3. When complying with IEC/EN/UL/CSA standards, refer to "MELSERVO-J4 Instructions and Cautions for Safe Use of AC Servos" as enclosed with the servo amplifier.
Note 4. For details on selection of no-fuse breakers and magnetic contactors used in combination with rotary servo motors, linear servo motors and direct drive motors, refer to "MR-J4W2-_BMR-J4W3-_BMR-J4W2-0303B6 Servo Amplifier Instruction Manual".
Note 5 . Keep the wire length for the regenerative option within 5 m .
Note 6. When connecting to a terminal block, be sure to use the screws attached to the terminal block.
Note 7. Install one no-fuse breaker and one magnetic contactor for each servo amplifier or drive unit.
Note 8. When complying with IEC/EN/UL/CSA standards, refer to "MR-CV_/MR-CR_/MR-J4-DU_ Instructions and Cautions for Safe Use of AC Servos" as enclosed with the power regeneration converter unit, resistance regeneration converter unit, and drive unit.

\subsection*{2.19 Application to Primary Switching of Transformers}

When connecting a transformer to the circuit, a significantly larger inrush current flows than usual.
This is due to the extremely large magnetizing current that flows, generating a maximum of 2 times the regular magnetic flux in order to saturate the iron core and induce the required voltages.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Frame} & \multicolumn{6}{|c|}{Single-Phase Transformer [kVA(A)]} & \multicolumn{6}{|c|}{Three-Phase Transformer [kVA(A)]} \\
\hline & \multicolumn{2}{|c|}{220 V} & \multicolumn{2}{|l|}{440 V} & \multicolumn{2}{|c|}{550 V} & \multicolumn{2}{|c|}{220 V} & \multicolumn{2}{|c|}{440 V} & \multicolumn{2}{|c|}{550 V} \\
\hline T10 & 1.2 & (5.5) & 1.5 & (3.5) & 1.5 & (3) & 2 & (5.5) & 2.5 & (3.5) & 2.5 & (3) \\
\hline T12 & 1.5 & (6.5) & 2 & (4.5) & 2 & (3.5) & 2.5 & (6.5) & 3.5 & (4.5) & 4 & (4.5) \\
\hline T20 & 2 & (9) & 3 & (6.5) & 2.8 & (5) & 3.5 & (9) & 5 & (6.5) & 6 & (6.5) \\
\hline T21 & 2.2 & (10) & 3.3 & (7.5) & 3 & (5.5) & 4 & (10) & 7.5 & (10) & 8 & (8.5) \\
\hline T25 & 3 & (13.5) & 3.5 & (8) & 3.7 & (6.5) & 5.5 & (15) & 11 & (15) & 11 & (12) \\
\hline T32 & 3.5 & (16) & 4.5 & (10) & 3.7 & (6.5) & 5.5 & (15) & 13 & (17) & 11 & (12) \\
\hline T35 & 3.7 & (17) & 4.5 & (10) & 4 & (7.5) & 6 & (17) & 13 & (17) & 13 & (14) \\
\hline T50 & 5.5 & (25) & 7.5 & (17.5) & 7.5 & (14) & 9.5 & (25) & 19 & (25) & 19 & (20) \\
\hline T65 & 7 & (32) & 13 & (30) & 11 & (20) & 12 & (32) & 24 & (32) & 21 & (22) \\
\hline T80 & 7.5 & (35) & 14 & (32) & 14.5 & (27) & 15 & (40) & 30 & (40) & 30 & (32) \\
\hline T100 & 10 & (46) & 18.5 & (42) & 19 & (35) & 19 & (50) & 38 & (50) & 38 & (40) \\
\hline N125 & 11 & (50) & 20 & (45) & 20 & (37) & 23.5 & (62) & 40 & (62) & 50 & (52) \\
\hline N150 & 13.5 & (62) & 24 & (55) & 27 & (50) & 28.5 & (75) & 57 & (75) & 65 & (70) \\
\hline N180, N220 & 22 & (100) & 45 & (100) & 50 & (90) & 42 & (110) & 84 & (110) & 95 & (100) \\
\hline N300 & 30 & (135) & 55 & (120) & 65 & (115) & 57 & (150) & 110 & (150) & 140 & (150) \\
\hline N400 & 35 & (165) & 65 & (150) & 80 & (150) & 76 & (200) & 150 & (200) & 190 & (200) \\
\hline N600 & 65 & (300) & 132 & (300) & 160 & (300) & 110 & (300) & 220 & (300) & 280 & (300) \\
\hline N800 & 88 & (400) & 180 & (400) & 215 & (400) & 150 & (400) & 300 & (400) & 380 & (400) \\
\hline
\end{tabular}

Note 1. Applicable for transformer peak inrush currents less than 20 times greater than the rated current value.
Note 2. If the transformer inrush current exceeds 20 times, select a class AC-3 magnetic contactor such that the current value is less than 10 times the rated operating current. Conversely, if the transformer inrush current is significantly less than 20 times then it can be used at a slightly higher capacity than listed in the table above.
Note 3. The transformer primary switching has an influence on the magnetizing inrush current of the transformer itself, meaning that repetitive switching 1 time per day etc. is not ideal for the transformer. The entire wiring system, including the transformer, should be checked to ensure there are no problem points with this kind of switching before using in an application.
Note 4. Electrical durability of 500,000 operations.

\section*{Handling (Precautions)}

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\section*{Handling (Precautions)}

\subsection*{3.1 Usage Environment}
(1) Ambient Temperature (Applied to the outside of the control board environment)
(2) Maximum temperature : of the inside of the control board
(3) Relative Humidity
(4) Height above sea level:
(5) Vibration
(6) Impact
(7) Atmosphere
(8) Storage Temperature/: Relative Humidity

\section*{\(-10^{\circ} \mathrm{C}\) to \(40^{\circ} \mathrm{C}\)}

Average daily atmospheric temperature: \(35^{\circ} \mathrm{C}\) (Max.), Average yearly atmospheric temperature: \(25^{\circ} \mathrm{C}\) (Max.)
\(55^{\circ} \mathrm{C}\) However, the ambient temperature of boxed MS type is \(40^{\circ} \mathrm{C}\) (Average yearly temperature of the inside of the control board is \(40^{\circ} \mathrm{C}\) or less)
Please note that the operating characteristics of the Magnetic Contactors and Thermal Overload Relays may vary with the ambient temperature.
\(45 \%\) to \(85 \%\) RH (However, dew condensation and freezing should be avoided.)
2000 m or less
10 to \(55 \mathrm{~Hz} 19.6 \mathrm{~m} / \mathrm{s}^{2}\) or less
\(49 \mathrm{~m} / \mathrm{s}^{2}\) or less
Inclusion of dust, smoke, corrosive gas, moisture, salt content and the like in the atmosphere should be avoided as much as possible.
Please note that continuing to use the device in a closed condition for a long period may cause contact failure.
Never use the device under an atmosphere that contains flammable gas.
\(-30^{\circ} \mathrm{C}\) to \(65^{\circ} \mathrm{C} / 45 \%\) to \(85 \% \mathrm{RH}\) (However, dew condensation and freezing should be avoided.)
The storage temperature is ambient temperature during transportation or storage and should be within the usage temperature when starting to use the device.

\subsection*{3.2 Mounting}

The following content applies to MS-T/N Series (including DU-N and B-T/N types). Please consult us regarding other models and special mounting procedures.

\section*{Direct Mounting}
(1) The device should be mounted in a dry location low in dust and vibration.
(2) The normal mounting direction is the direction shown in Fig. 1 on a vertical surface, but mounting the device at an inclination angle of up to 30 degrees in either direction is allowed. (Fig. 2)
(3) Mounting the device on a floor or ceiling is not allowed. (Mounting the device on a floor or ceiling may affect the continuity performance, operation performance, and durability of the contact.)
(4) If mounting the device in a horizontal orientation cannot be avoided, be sure to rotate the device by 90 degrees in a counterclockwise direction from the normal mounting direction as shown in Fig. 3 when mounting it.If the device is mounted in a horizontal orientation, its characteristic is nearly unchanged but mechanical durability may be deteriorated. Horizontal mounting of reversible types, mechanically latched types, or S-N600 and N800 models is not allowed.



Fig. 2 Inclined Mounting


Fig. 3 Horizontal Mounting

\section*{Mounting of Enclosed Types}

Because the lid tightening screws for enclosed type models MS-T10 to T50 are tightened from below, an amount of space equivalent to that shown in Fig. 4 must be secured underneath.

\section*{Tightening torque of mounting screw (Common to all models)}
(1) The device should be mounted by force of tightening torques shown in the right table. (For data on the mounting screws of each model, please refer to the outline drawings.)
(2) If the product is to be installed onto a plastic surface, please use mounting screws with metal washers.
(3) Please use mounting screws with a length of M \(4 \times 14\) to M4×22 for MSO/S-T10 to T20 types (including reversible), SR-T5/T9 types, and SRL(D)-T5 types.

\section*{Mounting of IEC 35mm wide rail}

(1) Names of Models Representative of Rail Mounted Applications
The T10 to T80 types and SR-T/K types can be mounted on the IEC 35 mm wide rail as a standard. In the case of reversible types, rail mounting is possible when a mounting board is used. (MSO-2xT35 to T80, MSOD\(2 \times T 21\) to T50, S-2xT35 to T80, SD-2xT21 to T50)
\begin{tabular}{|c|c|c|c|c|}
\hline Magnetic Starters & Magneicic Contactors & Magnetic Starters & Magnetic Contactors & Contactor Relays \\
\hline \multirow[t]{13}{*}{\[
\begin{aligned}
& \text { MSO-T10 } \\
& \text { MSO-T12 } \\
& \text { MSO-T20 } \\
& \text { MSO-T21 } \\
& \text { MSO-T25 } \\
& \text { MSO-T35 } \\
& \text { MSO-T50 } \\
& \text { MSO-T65 } \\
& \text { MSO-T80 }
\end{aligned}
\]} & \multirow[t]{13}{*}{S-T10
ST12
ST20
S-T21
ST25
S-T32
ST35
S-T50
ST65
S-T80} & MSOD-T12 & SD-T12 & \multirow[t]{13}{*}{SR-T5, T9
SR-K100
SRD-T5
SRD-T9
SRD-K100
SRL(D)-T5
SRL(D)-K100} \\
\hline & & MSOD-T20 & SD-T20 & \\
\hline & & MSOD-T21 & SD-T21 & \\
\hline & & MSOD-T35 & SD-T32 & \\
\hline & & MSOD-T50 & SD-T35 & \\
\hline & & & SD-T50 & \\
\hline & & & SL(D)-T21 & \\
\hline & & & SL(D)-T35 & \\
\hline & & & SL(D)-T50 & \\
\hline & & & SL(D)-T65 & \\
\hline & & & SL(D)-T80 & \\
\hline & & Thermal Ove & erload Relays & \\
\hline & & \[
\begin{array}{|l|l|}
\hline \text { TH-T18+UUT-1 } \\
\text { TH-T25+UINN }
\end{array}
\] & HZ18 & \\
\hline
\end{tabular}
(2) Minimum Clearance \(\ell(\mathrm{mm})\) of Product when Rail Mounted Because of the effect on temperature rise of individual product parts and product life, make sure to ensure that the dimensions equal to that or above those shown in the table below are ensured between parts when performing rail mounting.
\begin{tabular}{|c|c|c|c|c|c|}
\hline Frame & \[
\begin{aligned}
& \hline \text { T10 } \\
& \text { T12 } \\
& \text { T20 } \\
& \text { T21 }
\end{aligned}
\] & \[
\begin{aligned}
& \text { T25 } \\
& \text { T32 } \\
& \text { T35 } \\
& \text { T50 }
\end{aligned}
\] & \[
\begin{aligned}
& \text { TH-T18 + UT-HZ18 } \\
& \text { TH-T25 + UN-RM20 }
\end{aligned}
\] & \[
\begin{aligned}
& \text { SR(D)-T/K } \\
& \text { SRL(D)-T/K }
\end{aligned}
\] & \[
\begin{aligned}
& \mathrm{T} 65 \\
& \mathrm{~T} 80
\end{aligned}
\] \\
\hline Minimum Clearance \(\ell\) & & & 5 & 5 & 10 \\
\hline Close Mounting* & & & OK & OK & OK \\
\hline
\end{tabular}

Note: *Although close mounting is allowed, when continuing to apply current to the device or when mounting products high in switching frequency or utilization on the same rail, the device life may be shortened in terms of temperature rise and shock, while attaching/detaching the auxiliary terminal cover will prove difficult if S-T21 to T50 and UT-AX11 are closely mounted.
Also, because the characteristics of thermal overload relays are also somewhat influenced by the space between device and heater, please keep the space between the devices over the minimum value shown in the above table as much as possible when mounting them.

(3) Applicable Rail

DIN, EN, IEC, and JIS C2812 standards-compliant 35 mm wide rails come in two types: 7.5 mm and 15 mm in rail height. Their shapes and dimensions are as shown in the figure below.
\begin{tabular}{c|c|c}
\hline \multicolumn{2}{c|}{ Rail } & \multicolumn{1}{c}{ Rail Specifications } \\
\hline 1 & TH35-7.5 & Rail Width 35 mm , Rail height 7.5 mm \\
\hline 2 & TH35-15 & Rail Width 35 mm , Rail height 15 mm \\
\hline
\end{tabular}

(4) Maximum Pitch of Rail Mounting Screw L (mm) When mounting a rail on a surface of the board, be sure to keep the rail mounting screw pitch below the dimension shown in the following table in order to secure sufficient mechanical strength.
\begin{tabular}{|c|c|c|c|c|c|}
\hline  & \[
\begin{aligned}
& \text { T10 } \\
& \text { T12 } \\
& \text { T20 } \\
& \text { T21 } \\
& \hline
\end{aligned}
\] & \[
\begin{aligned}
& \mathrm{T} 25 \\
& \mathrm{~T} 32
\end{aligned}
\] & \[
\begin{aligned}
& \text { TH-T18 + UT-HZ18 } \\
& \text { SR(D)-T/K } \\
& \text { SRL(D)-T/K }
\end{aligned}
\] & \[
\begin{aligned}
& \text { T35 } \\
& \text { T50 }
\end{aligned}
\] & \[
\begin{aligned}
& \text { T65 } \\
& \text { T80 }
\end{aligned}
\] \\
\hline TH35-7.5 & & & 250 & 200 & (150) Note 2 \\
\hline TH35-15 & & & 500 & 500 & 500 \\
\hline
\end{tabular}

Note 1. It is also recommended that a minimum pitch be selected when installing multiple devices on the same rail.
Note 2. Use of devices with extreme switching frequencies is not recommended for the dimension values in parentheses.


\section*{Handling (Precautions)}

\section*{Mounting Space and Arc Space}

When mounting the Magnetic Contactors side by side, be sure to keep the devices isolated by a distance longer than the dimension shown in the following table. Also, the Magnetic Contactors and adjacent grounding metal should be isolated by a distance longer than the dimension shown in the following table. The content indicated () in is applied when additionally mounting auxiliary contacts.
Although an arc space is not required in front of the Magnetic Contactors, providing a space longer than the E dimension shown in the following table is recommended in consideration of variation in the Magnetic Contactor's depth dimension, and vibration caused when turning on or releasing the contactor.


Fig. 6 Mounting Space and Arc Space
- Minimal Mounting Space when Attaching UN-CZ
\begin{tabular}{c|c|c}
\hline Frame & B & C \\
\hline T65 to 100, N125 & \({ }^{*} 34\) & \({ }^{*} 32\) \\
\hline N150 to N400 & 64 & 47 \\
\hline
\end{tabular}
*When UN-CZ1251 is used for MSO-N125, use B:43 and C:40.

\subsection*{3.3 Connection}

\section*{Control Circuit Method and Connecting of Operating Switch}

The following figure shows an example diagram for connecting control circuits when automatically or manually operating motors, etc., using an automatic switch and push-button switch.


\section*{Applicable electric wire size and tightening torque and terminal dimension of terminal screw [Screw terminal]}
\(\triangle\) There may cause overheating or fire. Be sure to properly keep the tightening torque and periodically re-tighten the screw. However, please note that tightening the screw under the status where oil is adhered to the terminal portion may damage the terminal screw even within the existing tightening torque.
Electric wires should be properly connected according to the electric wiring diagram. Tightening the terminal screw should be properly conducted within the tightening torque shown in the table below. Insufficient tightening of the terminal screw may cause overheating or cause the electric wire to drop off. Excessive tightening torque may damage the terminal screw. Adhesion of rock paint, thermo-labels, etc. to electric wire connection or contact may cause heat generation due to defective continuity: this is very dangerous.
The main circuit terminals of T10 to T50 and TH-T18 to T50 types may be wired connected by single wire, stranded wire, and crimp lug. The main circuit terminals and operating circuit terminals of T10 to T32 and TH-T18/T25 types are self-lifting terminals that are easy to connect.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline Model & \multicolumn{4}{|l|}{Terminal dimension and size/type of screw} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Applicable electric
wire size
\(\left[ø \mathrm{~mm}, \mathrm{~mm}^{2}\right]\)}} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Applicable Crimp Lug Size}} & & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Tightening torque of termina screw [ \(\mathrm{N} \cdot \mathrm{m}\) ] Parentheses Show Standard Value}} \\
\hline \multirow[t]{2}{*}{\begin{tabular}{l}
Standard type Contactor Relays Magnetic Contactors Thermal Overload Relays \\
(Note 1)
\end{tabular}} & \multicolumn{3}{|c|}{Main circuit} & Operating circuit & & & & & conductor thickness(T) & & \\
\hline & Dimension of terminal portion XxYxZ [mm] (Note 2) & \[
\begin{array}{|c|}
\hline \text { Screw } \\
\text { size }
\end{array}
\] & Screw type & Cross slot screw with pressure plate & Main circuit & Operating circuit & Main circuit & Operating circuit & Main circuit (Note 2) & Main circuit & Operating circuit \\
\hline SR-T5, T9 & - & - & & M3.5x7.6 & - & \multirow{6}{*}{\[
\begin{gathered}
\propto 1.6 \\
0.75 \text { to } 2.5
\end{gathered}
\]} & & \multirow{4}{*}{1.25-3.5 to 2-3.5} & - & & \multirow{4}{*}{0.9 to 1.5} \\
\hline S-T10, T12, T20 & \(7.5 \times 3.7 \times 4.5\) & M3.5x7.6 & \multirow[t]{3}{*}{\begin{tabular}{l}
Self- \\
Lifting \\
Cross- \\
slot \\
Screw
\end{tabular}} & M3.5x7.6 & \[
\begin{array}{|l|}
\hline \varnothing 1.6 \\
0.75 \text { to } 2.5 \\
\hline
\end{array}
\] & & \[
\begin{aligned}
& 1.25-3.5 \text { to } 2-3.5 \\
& 5.5-\mathrm{S3} \text { (Notes } 7,9,10 \text { ) } \\
& \hline
\end{aligned}
\] & & 1.6 & 0.9 to 1.5 & \\
\hline S-T21, T25, T32 & \(10.5 \times 5.2 \times 5.5\) & M4x10.5 & & M3.5x7.6 & \[
\begin{array}{|l|}
\hline \varnothing 1.6 \text { to } 2.6 \\
1.25 \text { to } 6 \\
\hline
\end{array}
\] & & 1.25-4 to 5.5-4 & & 3 & 1.2 to 1.9 & \\
\hline S-T35, T50 & \(13.3 \times 5.5 \times 6.9\) & M5x14.8 & & M3.5x7.6 & \[
\begin{array}{|l|}
\hline \propto 1.6 \text { to } 3.6 \\
1.25 \text { to } 16 \\
\hline
\end{array}
\] & & \[
\begin{array}{|l|}
\hline 1.25-5 \text { to } 14-5 \\
22-\mathrm{S5}(\text { Note } 10) \\
\hline
\end{array}
\] & & 6 & 2.0 to 3.3 & \\
\hline \[
\begin{gathered}
\text { S-T65, T80 } \\
\text { (Note 11) }
\end{gathered}
\] & \(15 \times 7 \times 8.5\) & \multirow[t]{2}{*}{M6x12} & \multirow[t]{2}{*}{Plusminus Screw} & \multirow[t]{2}{*}{M4x10} & \[
\begin{aligned}
& 2 \text { to } 22 \\
& \text { (Note 3) }
\end{aligned}
\] & & 1.25-6 to 22-6
38-S6 (Note 10)
60-S6 (Note 10) & \multirow[t]{2}{*}{\[
\begin{gathered}
1.25-4 \text { to } 2-4 \\
5.5-\mathrm{S} 4
\end{gathered}
\]} & 3.7 & \multirow[t]{2}{*}{3.5 to 5.7} & \multirow[t]{2}{*}{1.2 to 1.9} \\
\hline S-T100 & \(15 \times 7.5 \times 11.5\) & & & & \[
\begin{gathered}
2 \text { to } 38 \\
\text { (Note 3) } \\
\hline
\end{gathered}
\] & & 1.25-6 to 60-6 & & 4 & & \\
\hline SR-K100 & - & - & - & M3.5x7.5 & - & \multirow{6}{*}{\[
\begin{gathered}
\varnothing 1.6 \\
1.25 \text { to } 2
\end{gathered}
\]} & - & 1.25-3.5 to 2-3.5 & - & - & \[
\begin{array}{|c|}
\hline 0.94 \text { to } 1.51 \\
(1.17) \\
\hline
\end{array}
\] \\
\hline S-N125 & \(15 \times 8.5 \times 14\) & M8x20 & \multirow[t]{2}{*}{\begin{tabular}{|l|}
\hline Hex \\
Bolt \\
(With \\
Cross) \\
\hline
\end{tabular}} & \multirow{5}{*}{M4x10} & - & & 5.5-8 to 60-8 & \multirow{5}{*}{\[
\begin{gathered}
1.25-4 \text { to } 2-4 \\
5.5-\mathrm{S} 4
\end{gathered}
\]} & 10.5 & \[
\begin{gathered}
\hline 6.28 \text { to } 10.29 \\
(7.84) \\
\hline
\end{gathered}
\] & \multirow{5}{*}{\[
\begin{gathered}
1.18 \text { to } 1.86 \\
(1.47)
\end{gathered}
\]} \\
\hline S-N150 & \(20 \times 10 \times 15\) & M8x20 & & & - & & 8-8 to 100-8 & & 10.5 & \[
\begin{gathered}
6.28 \text { to } 10.29 \\
(7.84) \\
\hline
\end{gathered}
\] & \\
\hline S-N180, N220 & \(25 \times 12.5 \times 18\) & M10x25 & \multirow{3}{*}{\begin{tabular}{l}
Hex \\
Bolt
\end{tabular}} & & - & & 14-10 to 150-10 & & 13.5 & \[
\begin{gathered}
11.8 \text { to } 19.1 \\
(14.7) \\
\hline
\end{gathered}
\] & \\
\hline S-N300, N400 & \(30 \times 15 \times 22.5\) & M12x30 & & & - & & 22-12 to 200-12 & & 15.5 & \[
\begin{gathered}
19.6 \text { to } 31.3 \\
(24.5) \\
\hline
\end{gathered}
\] & \\
\hline S-N600, N800 & \(40 \times 15 \times 28\) & M16x45 & & & - & & 80-16 to 325-16 & & 25 & \[
\begin{gathered}
62.8 \text { to } 98 \\
(78.4)
\end{gathered}
\] & \\
\hline SD-Q11, Q12 & \(7.5 \times 5.5 \times 4\) & M3.5x7.6 & \multirow{4}{*}{\begin{tabular}{l}
Self- \\
Lifting \\
Cross- \\
slot \\
Screw
\end{tabular}} & M3.5x7.6 & \[
\begin{aligned}
& \hline 61.6 \\
& 1.25 \text { to } 2 \\
& \hline
\end{aligned}
\] & \[
\begin{array}{|c|}
\hline \varnothing 1.6 \\
1.25 \text { to } 2 \\
\hline
\end{array}
\] & 1.25-3.5 to 2-3.5 & \multirow{4}{*}{1.25-3.5 to 2-3.5} & 1.6 & \[
\begin{array}{|c|}
\hline 0.94 \text { to } 1.17 \\
(1.0) \\
\hline
\end{array}
\] & \[
\begin{array}{|c|}
\hline 0.94 \text { to } 1.17 \\
(1.0) \\
\hline
\end{array}
\] \\
\hline \[
\begin{aligned}
& \hline \text { TH-T18 } \\
& \text { (Load Side) }
\end{aligned}
\] & \(7.5 \times 4 \times 4\) & M3.5x7.6 & & \multirow{3}{*}{M3.5x7.6} & \[
\begin{aligned}
& \varnothing 1.6 \\
& 0.75 \text { to } 2.5 \\
& \hline
\end{aligned}
\] & \multirow{3}{*}{\[
\begin{gathered}
\varnothing 1.6 \\
0.75 \text { to } 2.5
\end{gathered}
\]} & \[
\begin{array}{|l|}
\hline 1.25-3.5 \text { to } 2-3.5 \\
5.5-S 3 \text { (Notes } 7,9,10) \\
\hline
\end{array}
\] & & 2 & 0.9 to 1.5 & \multirow{3}{*}{0.9 to 1.5} \\
\hline \begin{tabular}{l}
TH-T25 \\
(Power Side/Load Side)
\end{tabular} & \[
\begin{aligned}
& 10.2 \times 6.8 \times 5 / \\
& 10.2 \times 5.7 \times 5
\end{aligned}
\] & \[
\begin{aligned}
& \mathrm{M} 4 \times 10.5 / \\
& \mathrm{M} 4 \times 10.5 \\
& \hline
\end{aligned}
\] & & & \[
\begin{aligned}
& \varnothing 1.6 \text { to } 2.6 \\
& 1.25 \text { to } 6 \\
& \hline
\end{aligned}
\] & & 1.25-4 to 5.5-4 & & 2.5 & 1.2 to 1.9 & \\
\hline \[
\begin{aligned}
& \text { TH-T50 } \\
& \text { (Load Side) }
\end{aligned}
\] & \(13.3 \times 5.8 \times 6.9\) & M5x14.8 & & & \[
\begin{array}{|l|}
\hline \varnothing 2 \text { to } 3.6 \\
4 \text { to } 14 \\
\hline
\end{array}
\] & & 5.5-5 to 14-5 & & 8 & 2.0 to 3.3 & \\
\hline TH-T65 & \(17 \times 7.5 \times 8.5\) & M6x12 & \multirow[t]{2}{*}{Plusminus Screw} & \multirow[b]{2}{*}{M4x10} & \[
\begin{aligned}
& 2 \text { to } 22 \\
& \text { (Note 3) } \\
& \hline
\end{aligned}
\] & \multirow[t]{2}{*}{\[
\begin{gathered}
\varnothing 1.6 \\
1.25 \text { to } 2
\end{gathered}
\]} & 5.5-6 to 22-6 & \multirow[t]{2}{*}{\[
\begin{gathered}
1.25-4 \text { to } 2-4 \\
5.5-\mathrm{S} 4
\end{gathered}
\]} & 4 & 3.5 to 5.7 & \multirow[b]{2}{*}{1.2 to 1.9} \\
\hline TH-T100 (Load Side) & \(15 \times 7.5 \times 10\) & M6x12 & & & \begin{tabular}{l}
8 to 38 \\
(Note 3)
\end{tabular} & & \[
\begin{array}{|l|}
\hline 14-6 \text { to } 22-6 \\
38-\mathrm{S6} \text { (Note 10) } \\
\hline
\end{array}
\] & & 3.7 & 3.5 to 5.7 & \\
\hline TH-N120 & \(15 \times 10 \times 12\) & M8x20 & \multirow[t]{2}{*}{\begin{tabular}{l} 
Hex \\
Bolt \\
(With \\
Cross) \\
\hline
\end{tabular}} & \multirow{5}{*}{M4x10} & - & \multirow{5}{*}{\[
\begin{gathered}
\varnothing 1.6 \\
1.25 \text { to } 2
\end{gathered}
\]} & 8-8 to 38-8 & \multirow{5}{*}{\[
\begin{aligned}
& 1.25-4 \text { to } 2-4 \\
& 5.5-\mathrm{S} 4
\end{aligned}
\]} & 11.5 & \[
\begin{gathered}
\hline 6.28 \text { to } 10.29 \\
(7.84) \\
\hline
\end{gathered}
\] & \multirow{5}{*}{\[
\begin{array}{|c}
1.18 \text { to } 1.86 \\
(1.47)
\end{array}
\]} \\
\hline TH-N120TA (Load Side) TH-N120TAHZ & \(20 \times 10 \times 15\) & M8x20 & & & - & & 38-8 to 100-8 & & 11.5 & \[
\begin{gathered}
\hline 6.28 \text { to } 10.29 \\
(7.84) \\
\hline
\end{gathered}
\] & \\
\hline \[
\begin{aligned}
& \text { TH-N220RH (Load Side) } \\
& \text { TH-N220HZ } \\
& \text { TH-N22OTAHZ } \\
& \hline
\end{aligned}
\] & \(25 \times 12.5 \times 20\) & M10x25 & \multirow[t]{2}{*}{Hex Bolt} & & - & & 22-10 to 150-10 & & 14.5 & \[
\begin{gathered}
11.8 \text { to } 19.1 \\
(14.7)
\end{gathered}
\] & \\
\hline \[
\begin{aligned}
& \text { TH-N400RH } \\
& \text { (Load Side) } \\
& \text { TH-N400HZ } \\
& \hline
\end{aligned}
\] & \(30 \times 15 \times 22.5\) & M12x30 & & & - & & 22-12 to 200-12 & & 17.5 & \[
\begin{gathered}
19.6 \text { to } 31.3 \\
(24.5)
\end{gathered}
\] & \\
\hline TH-N600 & - & - & - & & - & & - & & - & - & \\
\hline
\end{tabular}

Please read the notes on the following page.
(Continued on Next Page)

\section*{Handling (Precautions)}

Note 1. SD, SL, and SLD-T/N types are the same.
Note 2. The dimension of the main circuit terminal is a dimension for board conductor wiring. (See the right diagram) The board conductor thickness (T dimension) must be below the allowable connection conductor thickness indicated on page 67, because of the length of the terminal screw. In case of wiring with two boards used, the total value of two boards must be below the value ( \(T\) dimension) shown in the table.
Note 3. If wiring to terminals is performed with the insulation coating peeled, please use the designated wire press. In this case, the value between parentheses is the size of electrical wire that can be connected.
- MS-T65 to T100 types include a pressure plate for the main circuit.
- MSO, S-T65 to T100 types do not include a pressure plate for the main circuit.
- MS, MSO, S-N125 to 800 types are dedicated for crimp lug wiring.

Note 4. Control circuits are auxiliary contact terminals or coil terminals of magnetic contactors and control circuit terminals of thermal overload relays.
Note 5. In each terminal, two wires or two crimp lugs may be connected. (One crimp lug and one wire can also be connected)
Note 6. The cross slot screws with pressure plate of T Series and those of \(N\) Series are the same in size but different in pressure plate dimension, so please avoid the mixed use of such screws. This may break the insulation barrier or make the wire likely to fall out.


Crimp Lug Dimensions


Note 7. When using the IEC60529 finger-safe specification for MSO/S-T10(BC) - T50(BC), T65CW, T80CW, and SR-T5/T9(BC), be sure to insulate the crimping part of the crimp lug. However, please insulate 5.5-S3 by a method other than insulated crimp terminal.
Note 8. Tightening the terminal screw excessively without wiring may break the screw and consequently disable the tightening, so please avoid such excessive tightening.
Note 9. When wiring two crimp lugs for T 10 to T 20 BC and \(\mathrm{TH}-\mathrm{T} 18 \mathrm{BC}\), use crimp lugs with an F dimension of 6 mm or more.
Note 10. J.S.T. Mfg. Co., Ltd. model numbers are shown as typical applicable crimp lugs.
Note 11. Ring crimp lugs cannot be used for connection when wiring to T65CW, T80CW auxiliary contact terminals.
Note 12. Do not bring the screwdriver handle close to the product while tightening the terminal screw to secure the auxiliary make contact (stationary contact) of T21 to T50. Doing so may cause the auxiliary make contact (stationary contact) to come off.
Note 13. If there is a difficulty in wiring the product to the panel, the lower terminal can be used for power supply connection. Even in such a case, install the product in either of the directions shown in Section 3.2 on page 64.

\section*{Application to Circuits Exceeding 380 V}
(1) When applying MS/MSO/S-T10, T12, T20, SR-T \(\square / \mathrm{K} \square\), and TH-T18 types to a circuit exceeding 380 V to set crimp lug wiring, be sure to insulate the crimping part. However, please insulate 5.5-S3 by a method other than insulated crimp terminal.
(2) When applying such parts to a Reversing type circuit exceeding 500V, please use an SR-T type Contactor Relays (XF, XR) as shown in the right figure to set the switching time allowance.
(3) For application to a circuit exceeding 380 V for crimp lug 22-S5 with MS/ MSO/S-T35, T50 or crimp lug 60-S6 with MS/MSO/S-T65, T80, use the insulation cap attachment.

\section*{Break Contact Terminals}

When removing break contact terminals for the auxiliary contacts and contactor relays of magnetic contactors during wiring or when reinstalling after inspection, make sure to do so after ensuring that the Connectable Carrier (Crossbar) is pushed in. (If reinstallation is performed without the cross bar pushed in, the movable terminal contact of the break contact may come off inside,
 malfunction, or suffer contact failure).

\section*{Applicable wires and ferrules [Spring clamp terminals]}
(1) Applicable wire size
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Wire Ferrule} & \multirow[b]{2}{*}{Terminals} & \multicolumn{2}{|c|}{Size} & \multirow[t]{2}{*}{Length of peeled} & \multirow[t]{2}{*}{Maximum coated diameter} \\
\hline & & \(\times 1\) & \(\times 2\) & & \\
\hline Solid wire & \multirow{4}{*}{Main Accessory Control terminals} & \[
\begin{gathered}
\varphi 0.8-\varphi 2.0 \\
\text { AWG20-AWG14 }
\end{gathered}
\] & \[
\begin{gathered}
\varphi 0.8-\varphi 2.0 \\
\text { AWG20-AWG14 }
\end{gathered}
\] & \multirow[b]{2}{*}{\[
\underset{* 3}{13 \mathrm{~mm}}
\]} & \multirow[b]{2}{*}{\[
\underset{* 5}{\operatorname{Max}_{*} \varphi 4.1}
\]} \\
\hline \begin{tabular}{c|}
\hline Stranded wire, \\
Flexible stranded wire (Not UL Certified)
\end{tabular} & & \[
\begin{gathered}
0.5 \mathrm{~mm}^{2}-4 \mathrm{~mm}^{2} \\
\text { AWG20 - AWG12 }
\end{gathered}
\] & \[
\begin{gathered}
0.5 \mathrm{~mm}^{2}-4 \mathrm{~mm}^{2} \\
\text { AWG20 - AWG12 }
\end{gathered}
\] & & \\
\hline Ferrule with insulating cover & & \[
\begin{gathered}
0.25 \mathrm{~mm}^{2}-2.5 \mathrm{~mm}^{2} \\
\text { AWG24 - AWG14 }
\end{gathered}
\] & \begin{tabular}{l}
\(0.25 \mathrm{~mm}^{2}-2 \mathrm{~mm}^{2}\) \\
AWG24 - AWG14 *2
\end{tabular} & \multirow[t]{2}{*}{*4} & \[
\operatorname{Max}_{* 6} \varphi 4.2
\] \\
\hline Ferrule without insulating cover & & \[
\begin{aligned}
& 0.5 \mathrm{~mm}^{2}-2.5 \mathrm{~mm}^{2} \\
& \text { AWG20 - AWG14 }
\end{aligned}
\] & \[
\begin{aligned}
& 0.5 \mathrm{~mm}^{2}-2.5 \mathrm{~mm}^{2} \\
& \text { AWG20 - AWG14 }
\end{aligned}
\] & & \[
\operatorname{Max}_{\star 5} \varphi 4.1
\] \\
\hline
\end{tabular}
*1. Put one of wire in one of insertion hole.
*2. If you use two wires of \(2 \mathrm{~mm}^{2}\) or AWG14 at one terminal, apply only the ferrule 216-205(FE-2.08-8N-YE) made by WAGO.
\({ }^{*} 3\). In case of the coated diameter of the wire is lower than \(\varphi 3.4\), length of peeled is 9 mm .
*4. Follow a rule of each manufacturer's catalog.
\({ }^{*} 5\). When the coated diameter is below the \(\varphi 4.6\) beyond \(\varphi 4.1\), even 1 wire is applied.
\({ }^{*} 6\). Maximum outside diameter of sleeve. When the wire size \(2.1-2.5 \mathrm{~mm}^{2}\), maximum sleeve outside diameter is \(\varphi 4.8\).
\({ }^{*}\) 6. Maximum outside diameter of sleeve. When the
*8. Refert to wire strip gauge on top of product.
8. Refer to wire strip gauge on top of product.
*9. Do not put the Wire cover and insulating cov
\({ }^{*} 9\). Do not put the Wire cover and insulating cover in the spring terminal.
(2) Applicable ferrule size
\begin{tabular}{c|c|c}
\hline \multicolumn{3}{c}{ Main, Accessory Control terminals } \\
\hline L1 & 8 mm & 10 mm \\
\hline L2 & \(12.5-15 \mathrm{~mm}\) & \(14.5-17 \mathrm{~mm}\) \\
\hline\(\varphi\) & \(2.5-4.8 \mathrm{~mm}\) & \(2.5-4.8 \mathrm{~mm}\) \\
\hline D & \(\leqq 2.3 \mathrm{~mm}\) & \(\leqq 2.3 \mathrm{~mm}\) \\
\hline
\end{tabular}
*1. Take the tip of the wire out of the ferrule a little.


Fig. 1

\section*{The ferrules and tools}
(1) WAGO Kontakttechnik GMBH \& CO.KG
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|c|}{Wire size} & \multicolumn{2}{|l|}{Ferrule with insulating cover} & \multicolumn{2}{|l|}{Ferrule without insulating cover} & \multirow[b]{2}{*}{Crimping tool} & \multirow[b]{2}{*}{Operating tools} \\
\hline \(\mathrm{mm}^{2}\) & AWG & Model Number & Product Description & Model Number & Product Description & & \\
\hline 0.25 & 24 & 216-301 & (FE-0.25-8N-YE) & - & - & \multirow{8}{*}{Variocrimp4} & \multirow[b]{3}{*}{210-719} \\
\hline 0.34 & 24-22 & 216-302 & (FE-0.34-8N-TQ) & - & - & & \\
\hline 0.5 & 22-20 & \[
\begin{aligned}
& \hline 216-201 \\
& 216-241
\end{aligned}
\] & \[
\begin{aligned}
& \text { (FE-0.5-8N-WH) } \\
& \text { (FE-0.5-10N-WH) }
\end{aligned}
\] & 216-141 & (F-0.5-10) & & \\
\hline 0.75 & 20-18 & \[
\begin{aligned}
& \hline 216-202 \\
& 216-242
\end{aligned}
\] & \[
\begin{gathered}
\text { (FE-0.75-8N-GY) } \\
\text { (FE-0.75-10N-GY) }
\end{gathered}
\] & 216-142 & (F-0.75-10) & & \[
210-647
\] \\
\hline 1.0 & 18 & \[
\begin{aligned}
& 216-203 \\
& 216-243
\end{aligned}
\] & \[
\begin{aligned}
& \text { (FE-1.0-8N-RD) } \\
& \text { (FE-1.0-10N-RD) }
\end{aligned}
\] & 216-143 & (F-1.0-10) & & \[
210-648
\] \\
\hline 1.5 & 16 & \[
\begin{aligned}
& \hline 216-204 \\
& 216-244
\end{aligned}
\] & \[
\begin{aligned}
& \text { (FE-1.5-8N-BK) } \\
& \text { (FE-1.5-10N-BK) }
\end{aligned}
\] & 216-144 & (F-1.5-10) & & 210-119SB \\
\hline 2.08 & 14 & 216-205 & (FE-2.08-8N-YE) & 216-105 & (F-2.08-10) & & \\
\hline 2.5 & 14 & \[
\begin{aligned}
& \hline 216-206 \\
& 216-246
\end{aligned}
\] & \[
\begin{aligned}
& \text { (FE-2.5-8N-BU) } \\
& \text { (FE-2.5-10N-BU) }
\end{aligned}
\] & 216-106 & (F-2.5-10) & & \\
\hline
\end{tabular}
(2) Weidmuller Interface GMBH \& CO.KG
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|c|}{Wire size} & \multicolumn{2}{|l|}{Ferrule with insulating cover} & \multicolumn{2}{|l|}{Ferrule without insulating cover} & \multirow[b]{2}{*}{Crimping tool} & \multirow[b]{2}{*}{Operating tools} \\
\hline \(\mathrm{mm}^{2}\) & AWG & Part Number & Type & Part Number & Type & & \\
\hline 0.25 & 24 & 9025760000 & (H0.25/12 HBL) & - & - & \multirow{7}{*}{PZ 10 SQR} & \multirow{7}{*}{\[
\begin{gathered}
\text { SDI } \\
0.4 \times 2.5 \times 75 \\
\text { SDS } \\
0.4 \times 2.5 \times 75
\end{gathered}
\]} \\
\hline 0.34 & 22 & 9025770000 & (H0.34/12 TK) & - & - & & \\
\hline 0.5 & 20 & \[
\begin{aligned}
& \hline 0690700000 \\
& 9025870000
\end{aligned}
\] & \[
\begin{aligned}
& \text { (H0.5/14 OR) } \\
& \text { (H0.5/16 OR) }
\end{aligned}
\] & 9004050000 & (H0.5/10) & & \\
\hline 0.75 & 18 & \[
\begin{aligned}
& \hline 0462900000 \\
& 9025860000
\end{aligned}
\] & \[
\begin{aligned}
& \text { (H0.75/14 W) } \\
& \text { (H0.75/16 W) }
\end{aligned}
\] & 0542500000 & (H0.75/10) & & \\
\hline 1.0 & 17 & \[
\begin{aligned}
& \hline 0463000000 \\
& 9025950000
\end{aligned}
\] & \[
\begin{aligned}
& \text { (H1.0/14 GE) } \\
& \text { (H1.0/16 GE) }
\end{aligned}
\] & 0282800000 & (H1.0/10) & & \\
\hline 1.5 & 16 & \[
\begin{aligned}
& 0463100000 \\
& 0635100000
\end{aligned}
\] & \[
\begin{aligned}
& \text { (H1.5/14 R) } \\
& \text { (H1.5/16 R) }
\end{aligned}
\] & 0186500000 & (H1.5/10) & & \\
\hline 2.5 & 14 & 9019160000 & (H2.5/15D BL) & 9004080000 & (H2.5/10) & & \\
\hline
\end{tabular}
(3) Phoenix Contact GMBH \& CO.KG
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|c|}{Wire size} & \multicolumn{2}{|l|}{Ferrule with insulating cover} & \multicolumn{2}{|l|}{Ferrule without insulating cover} & \multirow[b]{2}{*}{Crimping tool} & \multirow[b]{2}{*}{Operating tools} \\
\hline \(\mathrm{mm}^{2}\) & AWG & Part Number & Type & Part Number & Type & & \\
\hline 0.25 & 24 & \[
\begin{aligned}
& 3203037 \\
& 3241128
\end{aligned}
\] & \[
\begin{gathered}
\text { (AI 0.25-8 YE) } \\
\text { (AI 0.25-10 YE) }
\end{gathered}
\] & - & - & \multirow[b]{3}{*}{CRIMPFOX CENTRUS 6 S} & \multirow[b]{3}{*}{\[
\begin{gathered}
\text { SZF } \\
0-0.4 \times 2.5
\end{gathered}
\]} \\
\hline \[
\begin{gathered}
\hline 0.3 \\
0.34
\end{gathered}
\] & 22 & \[
\begin{aligned}
& 3203066 \\
& 3241129
\end{aligned}
\] & \[
\begin{gathered}
\text { (Al 0.34-8 TQ) } \\
\text { (AI 0.34-10 TQ) } \\
\hline
\end{gathered}
\] & - & - & & \\
\hline 0.5 & 20 & \[
\begin{aligned}
& 3200014 \\
& 3201275
\end{aligned}
\] & (AI 0.5-8 WH) (Al 0.5-10 WH) & 3202494 & (A 0.5-10) & & \\
\hline 0.75 & 18 & \[
\begin{aligned}
& 3200519 \\
& 3201288 \\
& \hline
\end{aligned}
\] & \[
\begin{aligned}
& \hline \text { (Al 0.75-8 GY) } \\
& \text { (Al 0.75-10 GY) }
\end{aligned}
\] & 3200234 & (A 0.75-10) & \multirow{4}{*}{CRIMPFOX CENTRUS 10S} & \multirow[t]{4}{*}{\[
\begin{gathered}
\text { SZS } \\
0.4 \times 2.5
\end{gathered}
\]} \\
\hline 1.0 & 18 & \[
\begin{aligned}
& 3200030 \\
& 3200182
\end{aligned}
\] & \begin{tabular}{l}
(Al 1-8 RD) \\
(Al 1-10 RD)
\end{tabular} & 3200250 & (A 1-10) & & \\
\hline \[
\begin{gathered}
1.25 \\
1.5
\end{gathered}
\] & 16 & \[
\begin{aligned}
& 3200043 \\
& 3200195
\end{aligned}
\] & \begin{tabular}{l}
(Al 1.5-8 BK) \\
(Al 1.5-10 BK)
\end{tabular} & 3200276 & (A 1.5-10) & & \\
\hline \[
\begin{aligned}
& \hline 2.0 \\
& 2.5
\end{aligned}
\] & 14 & \[
\begin{aligned}
& 3200522 \\
& 3202533
\end{aligned}
\] & \begin{tabular}{l}
(AI 2.5-8 BU) \\
(Al 2.5-10 BU)
\end{tabular} & - & - & & \\
\hline
\end{tabular}
*1. We recommend the ferrules and the tools based upon the standard.
Ferrule with insulating cover : DIN 46228-4/09.90
Ferrule without insulating cover : DIN 46228-1/08.92
Operating tool : DIN 5264
*2. Follow the applicable wire rule of each manufacturer's catalog.


Fig. 2

\section*{Handling (Precautions)}

Wiring, remove method
(1) Wiring remove method
\begin{tabular}{c|c|c}
\hline & Wiring & Removing \\
\hline Solid wire, Ferrule & \begin{tabular}{c}
II or \\
\(\mathrm{I} \rightarrow \mathrm{II} \rightarrow \mathrm{IV}\)
\end{tabular} & \multirow{2}{*}{\(\mathrm{I} \rightarrow \mathrm{III} \rightarrow \mathrm{IV}\)} \\
\cline { 1 - 2 } \begin{tabular}{c} 
Stranded wire, Flexible \\
stranded wire
\end{tabular} & \(\mathrm{I} \rightarrow \mathrm{II} \rightarrow \mathrm{IV}\) & \\
\hline
\end{tabular}
*1. When the wire is difficult to remove, the operating tool is tilted to the wire side a little, max. \(5^{\circ}\).
*2. Do not remove while turning the wire.
*3. Do not push probe hard.
*4. Operate the wire after completely inserting operating tool.


\section*{- Wire holders}
- The wire holder restrains disconnection of the wire and maintain the mark tube.
- Push the wire into the direction of the arrow, Fig.7.
- Do not spread the wire holder too much.
- Do not bend wires at an acute angle when inserting them from the wire insertion slots into the wire holders. For information on the permissible bending radius of wires, follow the directions provided by the wire manufacturer.
- May put the cable tie in the hole of * Fig. 8 if you do not adding the strong power. We may use the hole of * Fig. 8 with other products and parts.


Fig. 7. Location of wire holders and wire insertion direction


Fig. 8

\subsection*{3.4 Operating Circuits}
\(\triangle\) Applying a low voltage that does not operate the Magnetic Contactors to the operating circuit may cause overcurrent to the coil, which may cause the coil to be burned in a short time.
\(\triangle\) If the operating circuit wiring is too long, when the coil's instantaneous current flows, the wiring impedance may cause a reduction in the coil voltage, so that the operating circuit may fail to be activated. Also, the stray capacitance of the wired line may cause the coil's excitation not to be released even when releasing the excitation.
© Use in a circuit (inverter) with high harmonics and high frequency levels can cause buzzing of electromagnetic parts or burn the operation coil or surge absorber with CR.

Power Supply Voltage Fluctuation Range for Operating Circuit
(1) Closing Voltage

When the rated voltage and frequency are applied to the coil at an ambient temperature of \(40^{\circ} \mathrm{C}\) (Inside temperature of the board: \(55^{\circ} \mathrm{C}\) ), the device operates without any problem at 85 to \(110 \%\) of the rated voltage of the coil after the temperature increases and becomes saturated.
(2) Voltage/Frequency and Coil Rating of Operating Circuit

The rated voltage/frequency of the operating circuit and that of the control coil must be matched.
Applying a voltage exceeding \(100 \%\) of the rated voltage to the control circuit when using the coil may acceleratedly deteriorate of the coil insulation and consequently reduced mechanical durability, so set the coil's average voltage to 95 to \(100 \%\) of the rated voltage when using the coil.

\section*{- Selection of Operating Transformer Capacity}

Please refer to the following page for operating transformer capacities for magnetic contactors.
S-T/N Type Magnetic Contactors: Page 45
SL(D)-T/N Type Magnetic Contactors: Page 103

\section*{- Driving Magnetic Contactor with Triac Control}

The electromagnet in the S-T65 to T100, N125 to N800 type Magnetic Contactor incorporates the capacitor-drop type AC operated DC excited method using the capacitor drop. Thus, a Triac with voltage resistance that is \(2 \cdot 2\)-fold the circuit voltage must be selected. If the Triac voltage resistance is low, use of a varistor in parallel with the Triac is recommended.

\section*{- Using with Square Wave Power Supply}

The electromagnet in the S-T65 to T100, N125 to N800 type Magnetic Contactor incorporates the AC operated DC exciting method using the capacitor drop. It cannot be used with a square wave as the coil's exciting current will increase greatly.

\section*{- Precautions for DC Contactor Use}

As shown in Fig. A to the right, if the area of the DC circuit where the minus side of the coil opens and closes at the control contact is high in humidity and is at a location where condensation forms easily, the coil may become disconnected due to electrical corrosion*. As shown in Fig. B, it is recommended that the control contact open and close on the plus side of the coil.
*Electrical Corrosion: A phenomenon where the surface of metals chemically undergoes corrosive wear due to the surrounding environment or electrochemical reactions

\section*{Connecting Multiple Units in Row}

If using with multiple S-T65 to T100 and N125 to N800 type magnetic contactor control circuits connected in a row, the open time may be roughly doubled due to influence from the built-in capacitor.
In the case of failure, please arrange the circuit as shown to the right.

\subsection*{3.5 Application to Special Environments}
\(\triangle\) Please note that the operation characteristics of Magnetic Contactor and Thermal Overload Relay may vary with the ambient temperature.


Fig. A


Fig. B


\section*{- High Temperatures}

When using Magnetic Starters or Magnetic Contactors at high ambient temperature, the temperature may mainly affect the insulation life (continuous electric conduction life) of the operation coil and the aging variation of the molding component. MS-T/N types, open MSO and S-T/N types without a box are standard products available even at the inside temperature of \(55^{\circ} \mathrm{C}\).

\section*{- Low Temperatures}

Although the Magnetic Contactors may be transported to a cold region or used in such a cold region or under cold conditions such as those found in a refrigerator with the contactor incorporated in a switchboard the S-T type Magnetic Contactors is applicable as a standard product. The S-N type magnetic contactor series feature the low-temperature specification S-N \(\square\) LT type. Except for those shown below, we do not manufacture low-temperature specification magnetic starters, magnetic contactors, or thermal overload relays. Low-temperature-based products: S-N \(\square \mathrm{LT}, \mathrm{S}-2 \times \mathrm{N} \square \mathrm{LT}\) Types
Applicable temperature range of low-temperature product: Operating temperature -50 to \(55^{\circ} \mathrm{C}\)

\section*{Handling (Precautions)}

\section*{Corrosive Gas}

Corrosive gases that exist in an environment with Magnetic Starters or Magnetic Contactors used are gases such as sulfurous acid \(\left(\mathrm{SO}_{2}\right)\), hydrogen sulfide \(\left(\mathrm{H}_{2} \mathrm{~S}\right)\), chlorine \(\left(\mathrm{Cl}_{2}\right)\), and ammonia \(\left(\mathrm{NH}_{3}\right)\), and conductive portions can be protected by plating a metal resistant to such gases on the portion. However, because there is no adequate corrosion prevention method for the contact, such gases may increase the contact resistance, resulting in increased temperature.
Additionally, if the environment contains some corrosive gas but is under dry conditions, this may delay the progression of corrosion, so using the switchboard with the inside kept as dry as possible is also one of the corrosion prevention methods.
In the Magnetic Starters and Thermal Overload Relays, corrosion-prevented products (MS-T/N \(\square \mathrm{YS}, \mathrm{MSO}(\mathrm{D})\)-T/N \(\square \mathrm{YS}, \mathrm{S}(\mathrm{D})\)-T/N \(\square \mathrm{YS}\), TH-T/N■YS types) of the specification with increased corrosion resistance to such corrosive gases are also manufactured.
Additionally, S-T10 to T32 and SD-T12 to T32 type Magnetic Contactors is of corrosion resistance-increased specification as a standard product.

\section*{Dust}

Magnetic Starters and Magnetic Contactors used in an iron foundry, construction site, or powder conveying machine tend to be subject to a relatively large amount of dust. When using the control board in such locations, the board must be dust-preventionstructured. Also, using the board under hermetically-sealed condition for a long period may cause contact failure.

\section*{Export of the Products to Tropical Regions}

The environment of exported products which pass through tropical regions tends to be of high temperature and high humidity, and humidity is the environmental factor that affects the Magnetic Starters and Magnetic Contactors most severely. Humidity is the biggest rust-generating factor and the exported products must be in a structure resistant to humidity.
Although the standard products have sufficient mold resistance, for exports that pass through the tropics, it is recommended to add a moisture absorbent (silica gel) in an amount of 3 kg or more per \(1 \mathrm{~m}^{3}\), so as to lower the humidity and conform to JIS Z1402 export-use packing stipulations.

\subsection*{3.6 Precautions for Use}

Ⓑe sure to periodically check the Magnetic Starters and apply danger prevention measures on the sequence of important circuits.
(The Magnetic Starters contacts may suffer from defective continuity, welding, and burning.)
© When performing installation, wiring, and maintenance \& inspection, be sure to disconnect the Magnetic Starters from the power supply. It may cause electric shock. In addition, the malfunction attributable to vibration, impact, and false wiring may exert serious results (machine malfunction, short-circuiting of power supply, etc.) on the Magnetic Contactors.

\section*{Performance}

The performance described in this catalog is based on the result of a test conducted under the conditions specified in the Standard (JEM1038 "Magnetic Contactors", JISC8201-4-1 "Low Voltage Switching Devices and Control Devices", etc.). If actual use condition is different from this test condition, the user must evaluate the condition (by using an actual device).

\section*{- Use Conditions}

Although the device can operate without any problem when under the conditions described in this chapter, be careful regarding the following.
(1) Ambient Temperature

Even under normal usage, deterioration of the insulation will progress.
In particular, as the ambient temperature rises, the insulation life is shortened. In general, it is said that every time the ambient temperature rises by 6 to \(10^{\circ} \mathrm{C}\), the insulation life decreases by half (Arrhenius' law). In a case where the ambient temperature is high and voltage exceeding the rated voltage is continuously applied to coil, the coil temperature rises and life may be shortened dramatically.
(2) Vibration/Shock

Although vibration of \(19.6 \mathrm{~m} / \mathrm{s}^{2}\) and shock of \(49 \mathrm{~m} / \mathrm{s}^{2}\) do not cause contact malfunction, there may be trouble due to fatigue damage etc. when the vibration and shock are below these values but are applied continuously.
In particular, please note that the resonance of an installed board may exert a large vibration on the product.

\subsection*{3.7 Maintenance, Inspection and Part Replacement}

Please refer to the operation manual or maintenance manual for information on the correct maintenance and inspection, as well as part replacement (coils, contacts).
Because the following parts cannot be replaced, never perform disassembly.
(1) MS-T Series Magnetic Contactors and Contactor Relays
(S(D)-T10 to T32, SR(D)-T5/T9)
(2) Mechanically Latched Contactors, Contactor Relays
(SL(D)- \(\square\), SRL(D)- \(\square\) )
(3) Delay Open Type Magnetic Contactors and Relays
(S-T/NロDL, SR-TDDL)
(4) DC Interface Contactors (SD-Q \(\square / Q R \square\) )
(5) Because heat-resistant magnetic contactors and contactor relays (Classes 1 and 2), as well as MS-T/N \(\square\) type enclosed magnetic starters are products for the Electrical Appliance and Material Safety Law in Japan, please do not modify them.
MS-T/N Series Magnetic
Starters/Magnetic Contactors
4.1 Standard (AC Operated) Magnetic Starters/Magnetic Contactors MS/MSO/S- \(\square\) ..... 74
4.2 Reversible Magnetic Starters/Magnetic Contactors MS/MSO/S-2x \(\square\) ..... 75
4.3 DC Operated Magnetic Starters/Magnetic Contactors MSOD/SD- \(\square\) ..... 91
4.4 Mechanically Latched Magnetic Starters/Magnetic Contactors MSOL(D)/SL(D)- ..... 102
4.5 Delay Open Magnetic Starters/Magnetic Contactors MSO/S-■DL ..... 111
4.6 Magnetic Starters with Saturable Reactors and Thermal Overload Relays MSO- \(\square(K P) S R\) ..... 114
4.7 Magnetic Starters with Quick-acting Characteristics Thermal Overload Relays MSO- \(\square F S(K P)\) ..... 116
4.8 Magnetic Starters with Push-Buttons MS-■PM ..... 117
4.9 Magnetic Starters/Magnetic Contactors with Wiring Streamining Terminals MSO/S-T \(\square \mathrm{BC}\) ..... 119
4.10 Magnetic Contactors with Spring Clamp Terminals S-T \(\square\) SQ, SD-T \(\square S Q\) ..... 125
4.11 Main Circuit 3-Pole Magnetic Contactors S(D)-T32, S-N \(\square 8\) ..... 127
4.12 How to Order ..... 130

\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

\subsection*{4.1 MS/MSO/S-■Standard (AC Operated) Magnetic Starters/Magnetic Contactors}

\section*{A high quality product that supports the various needs of our customers on a global scale.}
- Usable in general applications such as motor starting, stopping, and burnout protection.
- Adopts twin contacts for the auxiliary contacts across all series for high reliability.
- Our standard products comply with the domestic standards as well as various overseas standards and are certified as meeting all standards.


S-T10
 (Refer to page 266 for details.)
Ratings/Specifications (Standard Applicability)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{3}{*}{Magnetic Contactors} & \multirow[b]{3}{*}{Magnetic Starters (Note 12)} & \multicolumn{4}{|l|}{\multirow[t]{2}{*}{\begin{tabular}{|c} 
Rated Capacity [kW] \\
\hline \begin{tabular}{c} 
Three-Phase Squirrel-cage Motor \\
(Category AC-3)
\end{tabular} \\
\hline \multicolumn{1}{|l}{}
\end{tabular}}} & \multicolumn{6}{|c|}{Rated Operating Current [A]} & \multirow[t]{3}{*}{\begin{tabular}{l}
Conventional \\
Free Air \\
Thermal \\
Current \\
Ith \\
[A]
\end{tabular}} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Auxiliary Contact}} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Compatible Thermal Overload Relays}} \\
\hline & & & & & & \multicolumn{4}{|l|}{Three-Phase Squirrel-cage Motor (Category AC-3)} & \multicolumn{2}{|l|}{\[
\begin{array}{|c|}
\hline \text { Resistive Load } \\
\text { (Category AC-1) } \\
\hline
\end{array}
\]} & & & & & \\
\hline & & \[
\left|\begin{array}{l}
\mathrm{AC220} \\
\text { to } 240 \mathrm{~V}
\end{array}\right|
\] & \[
\begin{aligned}
& \text { AC380 } \\
& \text { to } 440 \mathrm{~V}
\end{aligned}
\] & AC500 V & AC600 V & \[
\begin{aligned}
& \text { AC220 } \\
& \text { to } 240 \mathrm{~V}
\end{aligned}
\] & \[
\left|\begin{array}{c}
\text { AC380 } \\
\text { to } 440 \mathrm{~V}
\end{array}\right|
\] & AC500 V & AC690 V & \[
\left|\begin{array}{l}
\text { AC100 } \\
\text { to } 240 \mathrm{~V}
\end{array}\right|
\] & \[
\begin{array}{|l|}
\mathrm{AC380} \\
\text { to } 440 \mathrm{~V}
\end{array}
\] & & Standard (Special) & Additional Unit Model Names \(x\) Pieces & Model Name & \begin{tabular}{l}
Heater \\
Designation Range \\
[A]
\end{tabular} \\
\hline S-T10(BC) & MSO-T10(BC)KP & 2.5[2.2] & 4[2.7] & 4[2.7] & 4 & 11[11] & 9[7] & 7[6] & 5 & 20 & 11 & 20 & 1a(1b) & \multirow{8}{*}{\(U T-A X 2,4 B C) \times 10 r\)
\(U T-A X 11(B C) \times 2\)} & \multirow{3}{*}{TH-T18(BC)KP} & 0.12 to 9 \\
\hline S-T12(BC) & MSO-T12(BC)KP & 3.5[2.7] & 5.5[4] & 5.5[5.5] & 5.5 & 13[13] & 12[9] & 9[9] & 7 & 20 & 13 & 20 & \multirow[t]{2}{*}{\[
\begin{gathered}
1 \mathrm{a} 1 \mathrm{~b} \\
(2 \mathrm{a}, 2 \mathrm{~b})
\end{gathered}
\]} & & & 0.12 to 11 \\
\hline S-T20(BC) & MSO-T20(BC)KP & 4.5[3.7] & 7.5[7.5] & 7.5[7.5] & 7.5 & 18[18] & 18[18] & 17[17] & 9 & 20 & 18 & 20 & & & & 0.12 to 15 \\
\hline S-T21(BC) & MSO-T21(BC)KP & \[
\begin{aligned}
& 5.5[4] \\
& \text { (Note 3) }
\end{aligned}
\] & 11[7.5] & 11[7.5] & 7.5 & 25[20] & 23[20] & 17[17] & 9 & 32 & 32 & 32 & 2a2b & & \multirow[t]{2}{*}{TH-T25(BC)KP} & 0.24 to 22 \\
\hline S-T25(BC) & MSO-T25(BC)KP & 7.5 [5.5] & 15[11] & 15[11] & 11 & \[
\begin{aligned}
& 30(26[26] \\
& \text { (Note 1) }
\end{aligned}
\] & \[
\begin{array}{|l|}
30(266 \mid[25] \\
\text { (Note 1) }
\end{array}
\] & 24[20] & 12 & 32 & 32 & 32 & 2a2b & & & 0.24 to 22 \\
\hline S-T32(BC) & - & \(7.5[7.5]\) & 15[15] & 15[11] & 11 & 32[32] & 32[32] & 24[20] & 12 & 32 & 32 & 32 & - & & - & - \\
\hline S-T35(BC) & MSO-T35(BC)KP & 11[7.5] & 18.5[15] & 18.5[15] & 15 & 40[35] & 40[32] & \(32[26]\) & 17 & 60 & 60 & 60 & \multirow{13}{*}{2a2b} & & TH-T25(BC)KP & \(\frac{0.24 \text { to } 22}{29}\) \\
\hline S-T50(BC) & MSO-T50(BC)KP & 15[11] & 22[22] & 25[22] & 22 & \[
\begin{aligned}
& 55(50)[50] \\
& (\text { Note 1) }
\end{aligned}
\] & 50[48] & 38[38] & 26 & 80 & 80 & 80 & & & \[
\begin{array}{|l|}
\hline \text { TH-T25(BC)KP } \\
\hline \text { TH-T50(BC)KP } \\
\hline
\end{array}
\] & \(\frac{0.24 \text { to } 22}{29 \text { to } 42}\) \\
\hline S-T65(CW) & MSO-T65(CW)KP & 18.5[15] & 30[30] & 37[30] & 30 & 65[65] & 65[65] & 60[45] & 38 & 100 & 100 & 100 & & & TH-T65KP & 15 to 54 \\
\hline S-T80(CW) & \begin{tabular}{l}
MSO-T80(CW)KP \\
(Note 10)
\end{tabular} & 22[19] & 45[37] & 45[45] & 45 & 85[80] & 85[80] & 75[75] & 52 & 120 & 120 & 120 & & \[
\text { UN-AX11 x } 2
\] & \[
\begin{array}{|c|}
\hline \text { TH-T100KP } \\
\text { (Note 4) }
\end{array}
\] & 67 \\
\hline S-T100 & MSO-T100KP & 30[22] & 55[45] & 55[45] & 55 & 105[100] & 105[93] & 85[75] & 65 & 150 & 150 & 150 & & & TH-T65KP & 15 to 54 \\
\hline S-N125 & MSO-N125KP & 37[30] & 60[60] & 60[60] & 60 & 125[125] & 120[120] & 90[90] & 70 & 150 & 150 & 150 & & & TH-N120KP & 42 to 105 \\
\hline S-N150 & MSO-N150KP & 45[37] & 75[75] & 90[90] & 90 & 150[150] & 150[150] & 140[140] & 100 & 200 & 200 & 200 & & \multirow{5}{*}{UN-AX150 x 2} & (TA) & 42 to 125 \\
\hline S-N180 & MSO-N180KP & 55[45] & 90[90] & 110[110] & 110 & 180[180] & 180[180] & 180[180] & 120 & 260 & 260 & 260 & & & \multirow[b]{2}{*}{TH-N22OKPRH} & 82 to 150 \\
\hline S-N220 & MSO-N220KP & 75[55] & 132[110] & 132[132] & 132 & 250[220] & 250[220] & 200[200] & 150 & 260 & 260 & 260 & & & & 82 to 180 \\
\hline S-N300 & MSO-N300KP & 90[75] & 160[150] & 160[160] & 200 & 300[300] & 300[300] & 250[250] & 220 & 350 & 350 & 350 & & & \multirow[b]{2}{*}{TH-N400KPRH} & 105 to 250 \\
\hline S-N400 & MSO-N400KP & 125[110] & 220[200] & 225[200] & 250 & 400[400] & 400[400] & 350[350] & 300 & 450 & 450 & 450 & & & & 105 to 330 \\
\hline S-N600 & - & 190[160] & 330[300] & 330[300] & 330 & 630[630] & 630[630] & 500[500] & 420 & 660 & 660 & 660 & & \multirow[b]{2}{*}{-AX600 \(\times 1\)} & \multirow[t]{2}{*}{\[
\begin{gathered}
\hline \text { TH-N600KP } \\
\text { (Note 5) }
\end{gathered}
\]} & 250 to 500 \\
\hline S-N800 & - & 220[200] & 440[400] & 500[400] & 500 & 800[800] & 800[800] & 720[720] & 630 & 800 & 800 & 800 & & & & 250 to 660 \\
\hline
\end{tabular}

Note 1. The value in parentheses for the rated operating current is applicable in the case of magnetic contactors.
Note 2. Enclosed type magnetic starters are of MS- \(\square\) type. T20, T25, T32 and N600, N800 types are outside production range. It should be noted that auxiliary contact units cannot be additionally installed to enclosed types. MS-TDDP is for single-phase motors. Refer to page 267 article 10.3 for details about production range or applicable capacities.
Note 3. MS-T21 type with 200 to 220 V ratings are 3.7 kW , in accordance with the Electrical Appliance and Material Safety Law.
Note 4. Enclosed type heater designation 67A uses a thermal overload relay dedicated for enclosed types.
Note 5. Please use TH-N600 in combination with a separately sold current transformer (Mitsubishi CW-■).
Note 6. Refer to page 51 for information regarding application to resistive loads and capacitive loads.
Note 7. The main contact minimum operating voltage and current differ depending on the allowable fault rate. Refer to page 42 for details.
Note 8. "BC" in the model name refers to "wiring streamlining terminal".
Note 9. T65 to T100 and N125 to N800 are AC operated, DC energizing types, which may become unusable or undergo property alteration depending on the control circuit conditions. Carefully read page 71 before use.
Note 10. MSO-T80CW heater designation 67A is not manufactured.
Note 11. MSO-T \(\square\) and MSO-N \(\square\) types can also be manufactured.
Note 12. S-T12 and S-T20 with spring clamp terminals (SQ) can also be manufactured.
\begin{tabular}{|c|c|c|c|}
\hline \multirow{9}{*}{} & Item & Reference Page & Remarks \\
\hline & - Main Contact Rating & Page 39 & - \\
\hline & - Auxiliary Contact Rating & Page 41 & - \\
\hline & - Operation Coil & Page 43 & - \\
\hline & - Properties & Page 45 & - \\
\hline & - Performance & Page 46 & - \\
\hline & - Outline Drawings/Contact Arrangements & Page 77 & - \\
\hline & - How to Order & Page 130 & - \\
\hline & - Combining with Optional Units & Page 194 & - \\
\hline
\end{tabular}

\subsection*{4.2 MS/MSO/S-2x \(\square\) Reversible Magnetic Starters/ Magnetic Contactors}

\section*{Ideal for forward/reverse operation of AC motors}
- Ideal for forward rotation, reverse rotation, or plugging, as well as for the switching of normal and emergency power supplies.
- A highly reliable mechanical interlock is equipped as standard.


MSO- \(2 \times\) T21KP

\section*{Ratings/Specifications (Standard Applicability)}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{3}{*}{Magnetic Contactors} & \multirow[b]{3}{*}{\begin{tabular}{l}
Magnetic \\
Starters \\
(Note 12)
\end{tabular}} & \multicolumn{4}{|l|}{\multirow[t]{2}{*}{\begin{tabular}{|c|} 
Rated Capacity \([\mathrm{kW}]\) \\
\hline Three-Phase Squirrel-cage Motor \\
(Category AC-3)
\end{tabular}}} & \multicolumn{6}{|c|}{Rated Operating Current [A]} & \multirow[t]{3}{*}{\begin{tabular}{l}
Conventiona \\
Free Air \\
Themal \\
Curent \\
Ith \\
[A]
\end{tabular}} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Auxiliary Contact}} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Compatible Thermal Overload Relays}} \\
\hline & & & & & & \multicolumn{4}{|l|}{Three-Phase Squirrel-cage Motor (Category AC-3)} & \multicolumn{2}{|l|}{Resistive Load (Category AC-1)} & & & & & \\
\hline & &  & \(\square\) & AC500 V & AC600 V &  &  & AC500 V & AC690 V & \begin{tabular}{l}
AC100 \\
to 240 V
\end{tabular} &  & & Standard (Special) & \[
\begin{array}{|c|}
\hline \text { Additional } \\
\text { UnitModel Names } \\
\text { xPieces }
\end{array}
\] & Model Name & \begin{tabular}{l}
Heater \\
Designation Range [A]
\end{tabular} \\
\hline S-2xT10(BC) & MSO-2xT10(BC)KP & 2.5[2.2] & 4[2.7] & 4[2.7] & 4 & 11[11] & 9[7] & 7[6] & 5 & 20 & 11 & 20 & \[
\begin{gathered}
1 a \times 2+2 b \\
(1 b \times 2+2 b)
\end{gathered}
\] & \multirow{5}{*}{UTAX2, \(4 B C\) C \(\times 20 r\) UT-AX11 (BC) x 2} & \multirow{3}{*}{TH-T18(BC)KP} & 0.12 to 9 \\
\hline S-2xT12(BC) & MSO-2xT12(BC)KP & 3.5[2.7] & 5.5[4] & 5.5[5.5] & 5.5 & 13[13] & 12[9] & 9[9] & 7 & 20 & 13 & 20 & \[
\begin{aligned}
& 1 a 1 b \times 2+2 b \\
& (2 a \times 2+2 b)
\end{aligned}
\] & & & 0.12 to 11 \\
\hline S-2xT20(BC) & MSO-2xT20(BC)KP & 4.5[3.7] & 7.5[7.5] & 7.5[7.5] & 7.5 & 18[18] & 18[18] & 17[17] & 9 & 20 & 18 & 20 & \[
\begin{aligned}
& 1 a 1 b \times 2+2 b \\
& (2 a \times 2+2 b)
\end{aligned}
\] & & & 0.12 to 15 \\
\hline S-2×T21(BC) & MSO-2xT21(BC)KP & \[
\begin{gathered}
5.5[4] \\
(\text { Note 3) }
\end{gathered}
\] & 11[7.5] & 11[7.5] & 7.5 & 25[20] & 23[20] & 17[17] & 9 & 32 & 32 & 32 & \multirow{10}{*}{\(2 \mathrm{a} 2 \mathrm{~b} \times 2\)} & & \multirow[t]{2}{*}{TH-T25(BC)KP} & 0.24 to 22 \\
\hline S-2xT25(BC) & MSO-2xT25(BC)KP & 7.5[5.5] & 15[11] & 15[11] & 11 & \[
\begin{aligned}
& 30(26 \mid[26] \\
& \text { (Note 1) }
\end{aligned}
\] & \[
\left.\begin{array}{l}
30(26[25] \\
(\text { Note 1) }
\end{array}\right]
\] & 24[20] & 12 & 32 & 32 & 32 & & & & 0.24 to 22 \\
\hline S-2xT32(BC) & - & 7.5[7 & 15[15] & 15[11 & 11 & 32[32] & 32[32] & 24[20 & 12 & 32 & 32 & 32 & & - & - & - \\
\hline S-2xT35(BC) & MSO-2xT35(BC)KP & 11[7.5] & 18.5[15] & 18.5[15] & 15 & 40[35] & 40[32] & 32[26] & 17 & 60 & 60 & 60 & & \multirow{3}{*}{\[
\begin{aligned}
& U T A X 2,4 B C) \times 20 r \\
& U T-A X 11(B C) \times 2
\end{aligned}
\]} & TH-T25(BC)KP & 0.24 to 22 \\
\hline & & & & & & & & & & & & & & & TH-T25(BC)KP & 0.24 to 22 \\
\hline S-2×T50(BC) & MSO-2xT50(BC)KP & 15[11] & 22[22] & 25[22] & 22 & (Note 1) & 50[48] & 38[38] & 26 & 80 & 80 & 80 & & & TH-T50(BC)KP & 29 to 42 \\
\hline S-2xT65(CW) & MS0-2xT65(CW)KP & 18.5[15] & 30[30] & 37[30] & 30 & 65[65] & 65[65] & 60[45] & 38 & 100 & 100 & 100 & & \multirow[t]{2}{*}{UN-AX2, \(4 \times 2\) or UN-AX11 \(\times 2\)} & TH-T65KP & 15 to 54 \\
\hline S-2xT80(CW) & \[
\begin{aligned}
& \text { MSO-2xT80(CW)KP } \\
& \text { (Note 11) }
\end{aligned}
\] & 22[19] & 45[37] & 45[45] & 45 & 85[80] & 85[80] & 75[75] & 52 & 120 & 120 & 120 & & & TH-T100KP & 67 \\
\hline S-2×T100 & MSO-2xT100KP & 30[22] & 55[45] & 55[45] & 55 & 105[100] & 105[93] & 85[75] & 65 & 150 & 150 & 150 & & UN-AX80 2 & TH-T65KP & 15 to 54 \\
\hline S-2xN125 & MSO-2xN125KP & 37[30] & 60[60] & 60[60] & 60 & 125[125] & 120[120] & 90[90] & 70 & 150 & 150 & 150 & & & TH-N120KP & 42 to 105 \\
\hline S-2×N150 & MSO-2xN150KP & 45[37] & 75[75] & 90[90] & 90 & 150[150] & 150[150] & 140[140] & 100 & 200 & 200 & 200 & \multirow{5}{*}{\(3 \mathrm{a} 3 \mathrm{~b} \times 2\)} & \multirow{5}{*}{-} & (TA) & 42 to 125 \\
\hline S-2×N180 & MSO-2xN180KP & 55[45] & 90[90] & 110[110] & 110 & 180[180] & 180[180] & 180[180] & 120 & 260 & 260 & 260 & & & \multirow[t]{2}{*}{TH-N22OKPRH} & 82 to 150 \\
\hline S-2×N220 & MSO-2xN220KP & 75[55] & 132[110] & 132[132] & 132 & 250[220] & 250[220] & 200[200] & 150 & 260 & 260 & 260 & & & & 82 to 180 \\
\hline S-2×N300 & MSO-2xN300KP & 90[75] & 160[150] & 160[160] & 200 & 300[300] & 300[300] & 250[250] & 220 & 350 & 350 & 350 & & & \multirow[t]{2}{*}{TH-N400KPRH} & 105 to 250 \\
\hline S-2×N400 & MSO-2xN400KP & 125[110] & 220[200] & 225[200] & 250 & 400[400] & 400[400] & 350[350] & 300 & 450 & 450 & 450 & & & & 105 to 330 \\
\hline S-2×N600 & - & 190[160] & 330[300] & 330[300] & 330 & 630[630] & 630[630] & 500[500] & 420 & 660 & 660 & 660 & \multirow[t]{2}{*}{\(4 \mathrm{a} 4 \mathrm{~b} \times 2\)} & \multirow[t]{2}{*}{-} & \multirow[t]{2}{*}{\[
\begin{gathered}
\text { TH-N600KP } \\
\text { (Note 5) }
\end{gathered}
\]} & 250 to 500 \\
\hline S-2×N800 & - & 220[200] & 440[400] & 500[400] & 500 & 800[800] & 800[800] & 720[720] & 630 & 800 & 800 & 800 & & & & 250 to 660 \\
\hline
\end{tabular}

Note 1. The value in parentheses for the rated operating current is applicable in the case of magnetic contactors.
Note 2. Enclosed type magnetic starters are of MS-2x \(\square\) type. T10, T12, T20, T25, T32 and N600, N800 types are outside production range. It should be noted that auxiliary contact units cannot be additionally installed to enclosed types.
Note 3. MS-2 x T21 types with 200 to 220 V ratings are 3.7 kW , in accordance with the Electrical Appliance and Material Safety Law.
Note 4. Enclosed type heater designation 67A uses a thermal overload relay dedicated for enclosed types.
Note 5. Please use TH-N600 in combination with a separately sold current transformer (Mitsubishi CW- \(\square\) ).
Note 6. Refer to page 51 for information regarding application to resistive loads and capacitive loads.
Note 7. The main contact minimum operating voltage and current differ depending on the allowable fault rate. Refer to page 42 for details.
Note 8. The +2 b on the auxiliary contact arrangement of reversible T10, T12 and T20 types indicates the break contact of the integrated UT-ML20 interlock unit. There is no need to specify when ordering.
Note 9. Auxiliary contact arrangements are displayed by twos, in a contact arrangement combined with two magnetic contactors. For standard contact arrangements there is no need to specify when ordering; however, please specify a matching contact arrangement for 2 units if for a special configuration. <Example> \(1 \mathrm{~b} \times 2+2 \mathrm{~b}: 2 \mathrm{~B}, 2 \mathrm{a} \times 2+2 \mathrm{~b}\) : 4A
Note 10. "BC" in the model name refers to "wiring streamlining terminal".
Note 11. MSO-2xT80CW heater designation 67A is not manufactured.
Note 12. MSO-2xT \(\square\) and MSO-2xN \(\square\) types can also be manufactured.

\section*{Connecting Conductor Included}

Standard reversible magnetic contactors do not have a connecting conductor installed on the main circuit; however, products with connecting conductors (3-pole) on the main circuit can be manufactured. The 4 types below are available. (For information on whether an additional thermal overload relay can be connected, refer to page 216.)
(1) Mountable on Both Power/Load Side ... For Reversing Operation : S-2xT \(\square\) SD, S-2xN \(\square\) SD
(2) Mountable Only on Power Side (3-Pole In-Phase) ... For 2 Load Circuits
: S-2xT \(\square S G, S-2 x N \square S G\)
(3) Mountable Only on Load Side (3-Pole In-Phase) ... For 2 Power Systems

S-2xT \(\square \mathrm{SX}, \mathrm{S}-2 \times N \square \mathrm{SX}\)
(4) Mountable Only on Load Side (Reverse Phase Switchable)
\(S-2 x T \square S F, S-2 x N \square S F\)
Note 1. If a connecting conductor is required, refer to page 216 to order a main circuit conductor kit.

\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

Connecting Conductor Wiring Diagram


SX Type


SF Type


\section*{- Structure/Operation}
- Structure
(1) MSO-2 \(\times \mathrm{T} \square, \mathrm{S}-2 \times \mathrm{T} \square\) and MSO- \(2 \times \mathrm{N} \square\) types have the same mounting pitch as \(\mathrm{S}-2 \times \mathrm{N} \square\) types.
(2) Reversible MSO/S-2xT10 to T25 types can be mounted to IEC 35 mm rails as-is, while T35 to T80 types can be mounted by removing the mounting plate.
- Operation
(1) Open State (Fig. 1, 2(a), 3(a))

When both the left and right contactors are in the OFF state, the lever tip is retained in the open state via the return spring.
(2) Closed State (Fig. 2(b) and Fig. 3(b))

When the contactor of one side is energized (closed), the cross bar causes the lever pin (or lever system) to be pushed downward, rotating the interlock lever so that the lever tips cross each other.
When this happens, even if an energizing operation is attempted on the other contactor, as the lever tips are crossed over the operation will be prevented.
(3) Opening

When the energizing current to a contact on one side is halted, the cross bar returns to its original state via the contactor tripping spring.
This action of the cross bar raises the interlock lever with the help of the return spring, returning the interlock lever to its correct position.


Fig. 1. Structural and Operational Diagram (T10 to T80)


Fig. 2. Interlock Internal Structure (T10 to T80)


Fig. 3. Structural and Operational Diagram (T100, N125 to N400)

\section*{Handling}
(1) Be sure to release the electrical interlock via the break contact of the left and right magnetic contactors.
(2) The electrical interlock uses the break contact on the inner side (the mechanical interlock side).
(3) Horizontal mounting of the product is not available.
\begin{tabular}{|c|c|c|c|}
\hline \multirow{9}{*}{} & Item & Reference Page & Remarks \\
\hline & - Main Contact Rating & Page 39 & - \\
\hline & - Auxiliary Contact Rating & Page 41 & - \\
\hline & - Operation Coil & Page 43 & - \\
\hline & - Properties & Page 45 & - \\
\hline & - Performance & Page 46 & - \\
\hline & - Outline Drawings/Contact Arrangements & Page 77 & - \\
\hline & - How to Order & Page 130 & - \\
\hline & - Combining with Optional Units & Page 194 & - \\
\hline
\end{tabular}

Outline Drawings/Contact Arrangements (AC Operated Magnetic Starters/Magnetic Contactors) T10 (The diagrams show models without "BC".)



\section*{MS－T／N Series Magnetic Starters／Magnetic Contactors}

T12／T20（The diagrams show models without＂BC＂．）

\begin{tabular}{|l|}
\hline Reversing \\
MSO－2xT12（BC）KP \\
MSO－2xT20（BC）KP \\
\hline 0.7 kg \\
\hline
\end{tabular}


Non－Reversing
S－T12（BC）
\begin{tabular}{|c|c|}
\hline Model Name & Model Name \\
\hline S－T12 & S－T12BC \\
\hline S－T20 & S－T20BC \\
\hline
\end{tabular}
0.27 kg
＊1 寸法：ヘッドオン補助接点ユーット（UT－AX2（BC），UT－AX4（BC））付
\(* 3\) ，\(* 4\) 寸法：サイドオン補助接点ユニット（UT－AX11（BC））付 \(\cdots * 3\) は1個，\(* 4\) は2個（両側）付

\section*{Reversing}

S－2×T12（BC）
\(\mathrm{S}-2 \times \mathrm{T} 20(\mathrm{BC})\)


\section*{T21/T25 (The diagrams show models without "BC".)}


\section*{Non-Reversing}

S-T21(BC)
S-T25(BC)


\section*{Reversing}

S-2 \(\times\) T21(BC)


\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

T32 (The diagrams show models without "BC".)


T35／T50（The diagrams show models without＂BC＂．）


\section*{Non－Reversing}

S－T35（BC）
S－T50（BC）


Reversing
S－2 \(\times\) T35（BC）
S－2 \(\times\) T50（BC）


160（173．5＊2）（187＊3） ＊2，＊3寸法：サイドオン補助接点ユニット（UT－AX11（BC））付


\begin{tabular}{|c|c|}
\hline Model Name & Model Name \\
\hline S－2xT35 & S－2xT35BC \\
\hline S－2xT50 & S－2xT50BC \\
\hline
\end{tabular}

\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

T65/T80 (The diagrams show models without "CW".)


Reversing
S-2 \(\times\) T65(CW)
S-2 \(\times\) T80(CW)


\section*{T100}


\section*{Reversing}

MSO-2 \(\times\) T100KP
4.6 kg


Non-Reversing
S-T100


\section*{Reversing}

S-2 \(\times\) T100


\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

Note 1. The terminal numbers in parentheses for the S, SD, SL(D) auxiliary contacts in the center contact arrangement example are indicated along with the product, and represent the numbers of the old version (A Series).

N125


\section*{Non-Reversing}


\section*{Reversing}

\section*{S-2×N125}


Note 1. The terminal numbers in parentheses for the S, SD, SL(D) auxiliary contacts in the center contact arrangement example are indicated along with the product, and represent the numbers of the old version (A Series).

\section*{N150}


\section*{Non-Reversing}

S-N150


Reversing
S-2×N150


\section*{MS－T／N Series Magnetic Starters／Magnetic Contactors}

Note 1．The terminal numbers in parentheses for the S，SD，SL（D）auxiliary contacts in the center contact arrangement example are indicated along with the product，and represent the numbers of the old version（A Series）．

\section*{N180／N220}


\section*{Reversing}

S－2×N180
S－2×N220


Note 1. The terminal numbers in parentheses for the \(S, S D, S L(D)\) auxiliary contacts in the center contact arrangement example are indicated along with the product, and represent the numbers of the old version (A Series).

\section*{N300/N400}


\section*{Reversing}
\(S-2 \times N 300\)
\(S-2 \times N 400\)


\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

N600/N800


\section*{Non－Reversing Magnetic Starter（Enclosed）}

Enclosure（Case）：Steel
Paint Color：Munsell 5Y7／1
Protective Structure：IP20


Fig 4．MS－T10KP（ 0.74 kg ） MS－T12KP（ 0.76 kg ）


Fig 5．MS－T21KP（ 1.12 kg ）


Fig 6．MS－T35KP／T50KP（1．9 kg）

Note 1．Leave 100 mm space at the bottom of the enclosure when mounting MS－T10KP to T50KP types． Note 2． 3 rubber bushings are included for MS－T10KP to T50KP types．
Note 3．MS－T \(\square\) and MS－N \(\square\) types can also be manufactured．


Fig．8．MS－N300KP／N400KP（ \(27.5 \mathrm{~kg} / 28 \mathrm{~kg}\) ）
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Model} & \multicolumn{11}{|c|}{Dimensions} & \multirow[t]{2}{*}{\[
\begin{aligned}
& \hline \text { Weight } \\
& {[\mathrm{kg}]} \\
& \hline
\end{aligned}
\]} \\
\hline & A & AA & AB & B & BA & BB & C & CA & M & N & P & \\
\hline MS－T65KP／T80KP & 160 & 120 & 80 & 270 & 220 & 25 & 145 & 45 & M5 & 22 to 35 & M4 & 2.9 \\
\hline MS－T100KP & 190 & 150 & 100 & 305 & 260 & 25 & 163 & 67 & M6 & 22 to 35 & M4 & 4.0 \\
\hline MS－N125KP & 230 & 170 & 90 & 384 & 330 & 29 & 190 & 80 & M8 & 44 to 50 & M6 & 8.0 \\
\hline MS－N150KP／N180KP／N220KP & 270 & 200 & 120 & 484 & 400 & 44 & 209 & 85 & M8 & 44 to 50 & M6 & 12．8／16．2／16．2 \\
\hline
\end{tabular}


Fig．7．MS－T65KP to T100KP MS－N125KP to N220KP


\[
\begin{aligned}
& \text { OFF } \\
& \text { on }
\end{aligned}
\]

Note 1）The figure above shows the same power supply for both the main circuit and control circuit．
The solid lines show completed wiring while the broken lines and double－dashed lines are still in need of wiring．（For the double－ dashed lines，use the power supply attached to the unit）
Note 2）If the power supplies for the main circuit and control circuit differ，power wiring between the 1／L1－OFF button broken lines and the 3／L2－TH95 double－dashed lines is unnecessary，but the OFF button and TH95 terminal should be wired from the separate control circuit power supply．
\begin{tabular}{|l||l||l||l|}
\hline Model Name & Model Name & Model Name & Model Name \\
\hline MS－T10KP & MS－T65KP & MS－N125KP & MS－N400KP \\
\hline MS－T12KP & MS－T80KP & MS－－N150KP & \\
\hline MSST211KP & MS－T100KP & MSS－N18KKP & \\
\hline MS－T35KP & & MS－N220KP & \\
\hline MS－T50KP & & MS－N300KP & \\
\hline
\end{tabular}

\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

Reversing Magnetic Starters (Enclosed Type)
Enclosure (Case): Steel
Paint Color: Munsell 5Y7/1
Protective Structure: IP20


Fig. 9. MS-2xT21KP (2.0 kg)


Fig. 10. MS-2xT35KP to T100KP, MS-2xN125KP to N400KP

Note 1. 3 rubber bushings are included for MS-2xT21 to T50. Note 2. MS-2xT \(\square\) and MS-2xN \(\square\) types can also be manufactured.


Note 1) The figure above shows the same power supply for both the main circuit and control circuit.
The solid lines show completed wiring while the broken lines and double-dashed lines are still in need of wiring. (For the double-dashed lines, use the power supply attached to the unit)
Note 2) If the power supplies for the main circuit and control circuit differ, power wiring between the 1/L1-STOP button broken lines and the 3/L2-TH95
double-dashed lines is unnecessary, but the STOP button and TH95 terminal should be wired from the separate control circuit power supply.


\subsection*{4.3 MSOD/SD- \(\square\) DC Operated Magnetic Starters/Magnetic Contactors}

The operation coil is dedicated for DC
- The operation coil can be used with a separate power supply for DC operation.
(Main circuit can use both AC and DC)
- Electromagnet buzzing does not occur.
- The coil doesn't use saving resistance so there is no inrush current. (Excluding N600, N800)
- SD-T12 to T32 and SD-N600, N800 type operation coil terminals have polarity.
Connect terminal number A1 (+) to the positive and A2 (-) to the negative sides.

\section*{Ratings/Specifications (Standard Applicability)}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{3}{*}{Magnetic Contactors} & \multirow[b]{3}{*}{Magnetic Starters (Note 10)} & \multicolumn{4}{|l|}{\multirow[t]{2}{*}{\begin{tabular}{|c|}
\hline Rated Capacity [kW] \\
\hline \begin{tabular}{c} 
Three-Phase Squirrel-cage Motor \\
(Category AC-3)
\end{tabular} \\
\hline
\end{tabular}}} & \multicolumn{6}{|c|}{Rated Operating Current [A]} & \multirow[t]{3}{*}{\begin{tabular}{|c|}
\hline \\
Converitional \\
Free Air \\
Themal \\
Curent \\
Cith \\
Ith \\
[A]
\end{tabular}} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Auxiliary Contact}} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Compatible Thermal Overload Relays}} \\
\hline & & & & & & \multicolumn{4}{|l|}{Three-Phase Squirrel-cage Motor (Category AC-3)} & \multicolumn{2}{|l|}{\[
\begin{aligned}
& \text { Resistive Load } \\
& \text { (Category AC-1) }
\end{aligned}
\]} & & & & & \\
\hline & & \[
\left.\begin{aligned}
& \text { AC220 } \\
& \text { to } 240 \mathrm{~V}
\end{aligned} \right\rvert\,
\] & \[
\begin{aligned}
& \text { AC380 } \\
& \text { to } 440 \mathrm{~V}
\end{aligned}
\] & AC500 V & AC690 V & \[
\left|\begin{array}{l}
A C 220 \\
\text { to } 240 \mathrm{~V}
\end{array}\right|
\] & \[
\begin{aligned}
& \text { AC380 } \\
& \text { to } 440 \mathrm{~V}
\end{aligned}
\] & AC500 V & AC690 V & \[
\begin{aligned}
& \text { AC100 } \\
& \text { to } 240 \mathrm{~V}
\end{aligned}
\] & \[
\begin{aligned}
& \text { AC380 } \\
& \text { to } 440 \mathrm{~V}
\end{aligned}
\] & & \begin{tabular}{l}
Standard \\
(Special)
\end{tabular} & \[
\begin{array}{|c|}
\hline \text { Additional } \\
\text { Unit Model Names } \\
\text { x Pieces }
\end{array}
\] & Model Name & Heater Designation Range [A] \\
\hline SD-T12(BC) & MSOD-T12(BC)KP & 3.5[2.7] & 5.5[4] & 5.5[5.5] & 5.5 & 13[13] & 12[9] & 9[9] & 7 & 20 & 13 & 20 & \multirow[b]{2}{*}{1a1b(2a)} & \multirow{6}{*}{\[
\left\{\begin{array}{c}
U T-A X 2,4(B C) \times 1 \\
\text { or } \\
U T-A X 11(B C) \times 2
\end{array}\right.
\]} & \multirow[b]{2}{*}{TH-T18(BC)KP} & 0.12 to 11 \\
\hline SD-T20(BC) & MSOD-T2OBC)KP & 4.5[3.7] & 7.5[7.5] & 7.5[7.5] & 7.5 & 18[18] & 18[18] & 17[17] & 9 & 20 & 18 & 20 & & & & 0.12 to 15 \\
\hline SD-T21(BC) & MSOD-T21(BC)KP & 5.5[4] & 11[7.5] & 11[7.5] & 7.5 & 25[20] & 23[20] & 17[17] & 9 & 32 & 32 & 32 & 2a2b & & TH-T25(BC)KP & 0.24 to 22 \\
\hline SD-T32(BC) & - & 7.5[7.5] & 15[15] & 15[11 & 11 & 32[32] & 32[32] & 24[20] & 12 & 32 & 32 & 32 & - & & - & - \\
\hline SD-T35(BC) & MSOD-T35(BC)KP & 11[7.5] & 18.5[15] & 18.5[15] & 15 & 40[35] & 40[32] & 32[26] & 17 & 60 & 60 & 60 & \multirow{6}{*}{2a2b} & & \begin{tabular}{|l|}
\hline TH-T25(BC)KP \\
\hline TH-T50(BC)KP \\
\hline TH \\
\hline
\end{tabular} & \(\frac{0.24 \text { to } 22}{29}\) \\
\hline SD-T50(BC) & MSOD-T50(BC)KP & 15[11] & 22[22] & 25[22] & 22 & \[
\begin{gathered}
55(500|50| \\
\text { Note 1) }
\end{gathered}
\] & 50[48] & 38[38] & 26 & 80 & 80 & 80 & & & \begin{tabular}{|l|}
\hline TH-T25(BC)KP \\
\hline TH-T50(BC)KP \\
\hline
\end{tabular} & 0.24 to 22 \\
\hline SD-T65(CW) & MSOD-T65(CW)KP & 18.5[15] & 30[3 & 37[30 & 30 & 65[65] & 65[65] & 60[4 & 38 & 100 & 100 & 100 & & \multirow[b]{2}{*}{\[
\begin{array}{|c|}
\hline \text { UN-AX2, } 4 \times 1 \text { or } \\
\text { UN-AX11 } \times 2
\end{array}
\]} & & \\
\hline SD-T80(CW) & \[
\begin{gathered}
\text { MSOD-T80(CW)KP } \\
\text { (Note 8) }
\end{gathered}
\] & 22[19] & 45[37] & 45[45] & 45 & 85[80] & 85[80] & 75[75] & 52 & 120 & 120 & 120 & & & TH-T100KP & 67 \\
\hline SD-T100 & MSOD-T100KP & 30[22] & 55[45] & 55[45] & 55 & 105[100] & 105[93] & 85[75] & 65 & 150 & 150 & 150 & & \multirow{3}{*}{UN-AX80 \(\times 2\)} & TH-T65KP & 15 to 54 \\
\hline & & & & & & & & & & & & 150 & & & TH-T100KP & 67, 82 \\
\hline SD-N125 & MSOD-N125KP & 37[30] & 60[60] & 60[60] & 60 & 125[125] & 120[120] & 90[90] & 70 & 150 & 150 & 150 & \multirow{8}{*}{2a2b} & & TH-N120KP & 42 to 105 \\
\hline SD-N150 & MSOD-N150KP & 45[37] & 75[75] & 90[90] & 90 & 150[150] & 150[150] & 140[140] & 100 & 200 & 200 & 200 & & \multirow{5}{*}{UN-AX150 \(\times 2\)} & (TA) & 42 to 125 \\
\hline SD-N180 & MSOD-N180KP & 55[45] & 90[90] & 110[110] & 110 & 180[180] & 180[180] & 180[180] & 120 & 260 & 260 & 260 & & & \multirow[t]{2}{*}{TH-N22OKPRH} & 82 to 150 \\
\hline SD-N220 & MSOD-N220KP & 75[55] & 132[110] & 132[132] & 132 & 250[220] & 250[220] & 200[200] & 150 & 260 & 260 & 260 & & & & 82 to 180 \\
\hline SD-N300 & MSOD-N300KP & 90[75] & 160[150] & 160[160] & 200 & 300[300] & 300[300] & 250[250] & 220 & 350 & 350 & 350 & & & \multirow[t]{2}{*}{TH-N400KPRH} & 105 to 250 \\
\hline SD-N400 & MSOD-N400KP & 125[110] & 220[200] & 225[200] & 250 & 400[400] & 400[400] & 350[350] & 300 & 450 & 450 & 450 & & & & 105 to 330 \\
\hline SD-N600 & - & 190[160] & 330[300] & 330[300] & 330 & 630[630] & 630[630] & 500[500] & 420 & 660 & 660 & 660 & & \multirow[t]{2}{*}{UN-AX600 x 1} & \multirow[t]{2}{*}{\[
\begin{array}{c|}
\hline \text { TH-N600KP } \\
\text { (Note 4) } \\
\hline
\end{array}
\]} & 250 to 500 \\
\hline SD-N800 & - & 220[200] & 440[400] & 500[400] & 500 & 800[800] & 800[800] & 720[720] & 630 & 800 & 800 & 800 & & & & 250 to 600 \\
\hline
\end{tabular}

Note 1. The value in parentheses for the rated operating current is applicable in the case of magnetic contactors.
Note 2. Enclosed types are not manufactured.
Note 3. Also manufactured as reversible types (MSOD-2x \(\square\) types excluding SD-2x \(\square\), T32 and N600/N800).
Note 4. Use TH-N600 in combination with a separately sold current transformer (Mitsubishi CW- \(\square\) ).
Note 5. The magnetic starters listed below are also manufactured.
- Models with 2E Thermal Overload Relay: MSOD-T12KP to T100KP, MSOD-N125KP to N400KP
- Models with Quick Trip Thermal Overload Relay: MSOD-T12FSKP to T100FSKP, MSOD-T21FS to T100FS
- Models with Delayed Trip Thermal Overload Relay: MSOD-T12SR to T100SR, MSOD-T21KPSR to T100KPSR, MSOD-N125SR to N400SR, MSOD-N125KPSR to N400KPSR
Note 6. Refer to page 51 for information regarding application to resistive loads and capacitive loads.
Note 7. The main contact minimum operating Voltage and current differ depending on the allowable fault rate. Refer to page 42 for details.
Note 8. MSOD-T80CW heater designation 67A is not manufactured.
Note 9. MSOD-T \(\square\) and MSOD-N \(\square\) types can also be manufactured.
Note 10. SD-T12 and SD-T20 with spring clamp terminals (SQ) can also be manufactured.

\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

\section*{Handling}
(1) T65 to T100 type and N125 to N800 type coils of DC100V or more cannot be switched by the auxiliary contacts of thermal overload relays (TH- \(\square\) types). Switch using the contactor relay (SR or SRD type) contacts as per the figure below.

(2) Connecting differing DC operated magnetic contactor control circuits in parallel and simultaneously switching OFF can cause flip-flopping. As such, use one of the circuits listed below.
(MC1: Small Frame, MC2: Large Frame)

Circuit Example 1


Circuit Example 2


Circuit Example 3


Effect of Changing Circuit - It is necessary to restrict the polarity of the control circuit power supply. The open time of MC2 increases. the polarity of the control circuit power supply. The open time of MC2 increases.

The time until MC2 is activated increases.
\begin{tabular}{|c|c|c|c|}
\hline \multirow{9}{*}{} & Item & Reference Page & Remarks \\
\hline & - Main Contact Rating & Page 39 & - \\
\hline & - Auxiliary Contact Rating & Page 41 & - \\
\hline & - Operation Coil & Page 44 & - \\
\hline & - Properties & Page 45 & - \\
\hline & - Performance & Page 46 & - \\
\hline & - Outline Drawings/Contact Arrangements & Page 93 & - \\
\hline & - How to Order & Page 130 & - \\
\hline & - Combining with Optional Units & Page 194 & - \\
\hline
\end{tabular}

Outline Drawings／Contact Arrangements（DC Operated Magnetic Starters／Magnetic Contactors） T12／T20（The diagrams show models without＂BC＂．）
Non－Reversing

SD－T12（BC）


Non－Reversing
MSOD－T12（BC）KP MSOD－T20（BC）KP
0.53 kg
－




Reversing
MSOD－2 \(\times\) T12（BC）KP MSOD－ \(2 \times\) T2O（BC）KP



Mounting Dimensions Also Allow
For \(35 \times 50\) to \(52,34 \times 52\) Mounting



\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

T21 (The diagrams show models without "BC".)


\section*{T32（The diagrams show models without＂BC＂．）}
Non－Reversing

SD－T32（BC）



＊3．\(* 4\) 寸法：サイドオン補助接点ユニット（UT－AX11（BC））付‥＊3は1個，＊4は2個（両側）付


\section*{Reversing}

SD－2 \(\times\) T32（BC）


\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

T35/T50 (The diagrams show models without "BC".)

Reversing

SD-2 \(\times\) T35(BC) SD-2 \(\times\) T50(BC)


1.96 kg


\begin{tabular}{|c|c|}
\hline Model Name & Model Name \\
\hline SD-2xT35 & SD-2xT35BC \\
\hline SD-2xT50 & SD-2xT50BC \\
\hline
\end{tabular}


\section*{T65／T80（The diagrams show models without＂CW＂．）}
\begin{tabular}{|l|}
\hline Non－Reversing \\
SD－T65（CW） \\
SD－T80（CW） \\
2.1 kg \\
\hline
\end{tabular}


\section*{Reversing}

SD－2 \(\times\) T65（CW） SD－2 \(\times\) T80（CW）


\section*{4.6 kg}


Mounting Dimensions Also Allow Mounting Dimensions Also Allow
For \(77 \times 82\)（M5 Screw）Mounting


\section*{Reversing}

MSOD－2 \(\times\) T65（CW）KP MSOD－2 x T80（CW）KP

＊1才法はヘッドオン補助接点ユニット（UN－AX2，UN－AX4）付を示します。
＊2 寸法はヒータ呼び54A以下の寸法を示します。
＊3 寸法はヒータ呼び 67 A の寸法を示します。（MSOD－ \(2 \times\) T80CW 67A は製作不可）

\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

T100

\section*{Non-Reversing}


\section*{Reversing}

SD-2xT100
6.9 kg



Note 1. The terminal numbers in parentheses for the \(S, S D, S L(D)\) auxiliary contacts in the center contact arrangement example are indicated along with the product, and represent the numbers of the old version (A Series).
N125
Non-Reversing
SD-N125


\section*{Reversing}

SD-2xN125


N150

\section*{Non-Reversing}


\section*{Reversing}

SD-2xN150


\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

Note 1. The terminal numbers in parentheses for the \(S, S D, S L(D)\) auxiliary contacts in the center contact arrangement example are indicated along with the product, and represent the numbers of the old version (A Series).
N220
Non-Reversing
SD-N220


\section*{Reversing}

SD-2×N220


17 kg

\section*{N300/N400}

\section*{Non-Reversing}

SD-N300


\section*{Reversing}

SD-2×N300 SD-2×N400

\begin{tabular}{|l|}
\hline 28 kg \\
29 kg \\
\hline
\end{tabular}

Note 1. The terminal numbers in parentheses for the S, SD, SL(D) auxiliary contacts in the center contact arrangement example are indicated along with the product, and represent the numbers of the old version (A Series).

\section*{N600/N800}

\section*{Non-Reversing}


\section*{Reversing}

SD-2 \(\times\) N600 SD- \(2 \times\) N800


\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

\subsection*{4.4 MSOL(D)/SL(D)- \(\square\) Mechanically Latched Magnetic Starters/ Magnetic Contactors}

\section*{Contact doesn't open when power failures or voltage drops occur}
- Installing a reliable mechanical latch mechanism to magnetic contactors and using the equipped closing and opening coils allows mechanical retention in the closed state.
(Can also be operated manually)
- The magnetic contactor will not release due to power failures, momentary power failures or voltage drops.
- Power saving and no noise type as the coil is only momentarily energized and doesn't consume power in the regular state.


SL-T21
- Suitable for distribution panels, street lights, important facilities within buildings or the memory circuits of plants and more.
- Suitable for AC/DC power supply switching and power purchasing/self-generated power supply switching, with 2 units combined.
(Applicable with MSOL(D)/SL(D)-2x \(\square\) types that have a mechanical interlock equipped as standard)

\section*{Ratings/Specifications (Standard Applicability)}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{3}{*}{Magnetic Contactors} & \multirow[b]{3}{*}{Magnetic Starters (Note 8)} & \multicolumn{4}{|l|}{\multirow[t]{2}{*}{\begin{tabular}{|c|}
\hline Rated Capacity [kW] \\
\hline \begin{tabular}{c} 
Three-Phase Squirrel-cage Motor \\
(Category AC-3)
\end{tabular} \\
\hline
\end{tabular}}} & \multicolumn{6}{|c|}{Rated Operating Current [A]} & \multirow[t]{3}{*}{} & \multicolumn{3}{|l|}{\multirow[b]{2}{*}{Auxiliary Contact (for Reversing)}} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Compatible Thermal Overload Relays}} \\
\hline & & & & & & \multicolumn{4}{|l|}{Three-Phase Squirrel-cage Motor (Category AC-3)} & \multicolumn{2}{|l|}{\[
\begin{aligned}
& \text { Resistive Load } \\
& \text { (Category AC-1) }
\end{aligned}
\]} & & & & & & \\
\hline & & \[
\begin{gathered}
220 \\
\text { to } \\
240 \mathrm{~V}
\end{gathered}
\] & \[
\begin{gathered}
380 \\
\text { to } \\
440 \mathrm{~V}
\end{gathered}
\] & 500 V & 690 V & \[
\begin{gathered}
220 \\
\text { to } \\
240 \mathrm{~V}
\end{gathered}
\] & \[
\left.\begin{gathered}
380 \\
\text { to } \\
440 \mathrm{~V}
\end{gathered} \right\rvert\,
\] & 500 V & 690 V & \[
\left.\begin{gathered}
200 \\
\text { to } \\
240 \mathrm{~V}
\end{gathered} \right\rvert\,
\] & \[
\begin{gathered}
380 \\
\text { to } \\
440 \mathrm{~V}
\end{gathered}
\] & & Valid &  & Additional Unit Model Names \(x\) Pieces & Model Name & Heater Designation Range [A] \\
\hline SL & MS & 5.5 [4] & 11 [7.5] & 11 & 7.5 & 25 & 23 [20] & 17 & 9 & 32 & 32 & 32 & \multirow{6}{*}{\[
\left|\begin{array}{c}
2 a 2 b \\
(2 a 2 b \times 2)
\end{array}\right|
\]} & \multirow{15}{*}{\begin{tabular}{l}
1a1b \\
(1a1b \\
\(\times 2)\)
\end{tabular}} & \multirow{4}{*}{\[
\underset{\text { X2 }}{\text { UT-AX11 } \mathrm{BC})}
\]} & \multirow[b]{2}{*}{TH-T25(BC)KP} & 0.24 to 22 \\
\hline SL-T35(BC) & MSOL-T35(BC)KP & 11 [7.5] & 18.5 [15] & 18.5 [15] & 15 & 40 [35] & 40 [32] & 32 [26] & 17 & 60 & \multirow[t]{2}{*}{60} & \multirow[t]{2}{*}{60} & & & & & 0.24 to 22 \\
\hline & & & & & & & & & & & & & & & & 25(BC)KP & 0.24 to 22 \\
\hline SL-T50(BC) & MSOL-T50(BC)KP & 15 [11] & 22 [22] & 25 [22] & 22 & 55 (50)/50] & 50 [48] & 38 [38] & 26 & 80 & 80 & 80 & & & & TH-T50(BC)KP & 29 to 42 \\
\hline SL-T65 & MSOL-T65KP & 18.5 [15] & 30 & 37 & 30 & 65 & 65 [65] & 60 & 38 & 100 & 100 & 100 & & & \multirow[b]{2}{*}{UN-AX11x2} & TH-T65KP & 15 to 54 \\
\hline SL-T80 & MSOL-T80KP & 22 [19] & 45 [37] & 45 [45] & 45 & 85 [80] & 85 [80] & 75 [75] & 52 & 120 & 120 & 120 & & & & TH-T100KP & 67 \\
\hline & & & & & & & & & & & & 150 & 1a2b & & \multirow[b]{3}{*}{UN-AX80x2 (UN-AX80x2)} & TH-T65KP & 15 to 54 \\
\hline SL-T100 & & 30 [22] & 55 [45] & 55 [45] & 55 & 105 (100) & 105 [93] & 85 (75] & 65 & 150 & 150 & 150 & (1a2b \(\times 2\) ) & & & TH-T100KP & 67, 82 \\
\hline SL-N125 & MSOL-N125KP & 37[30] & 60[60] & 60[60] & 60 & 125[125] & 120[120] & 90[90] & 70 & 150 & 150 & 150 & \[
\begin{array}{|c|}
\hline 1 \mathrm{a} 2 \mathrm{~b} \\
(1 \mathrm{a} 2 \mathrm{~b} \times 2) \\
\hline
\end{array}
\] & & & \multirow[t]{2}{*}{TH-N12OKP(TA)} & 42 to 105 \\
\hline SL-N150 & MSOL-N150KP & 45[37] & 75[75] & 90[90] & 90 & 150[150] & 150[150] & 140[140] & 100 & 200 & 200 & 200 & \multirow{4}{*}{\[
\left|\begin{array}{c}
1 a 2 b \\
(2 a 3 b \times 2)
\end{array}\right|
\]} & & \multirow{4}{*}{\begin{tabular}{l}
UN-AX150x2 \\
(-)
\end{tabular}} & & 42 to 125 \\
\hline SL-N220 & MSOL-N22OKP & 75[55] & 132[110] & 132[132] & 132 & 250[220] & 250[220] & 200[200] & 150 & 260 & 260 & 260 & & & & TH-N22OKPRH & 82 to 180 \\
\hline SL-N300 & MSOL-N300KP & 90[75] & 160[150] & 160[160] & 200 & 300[300] & 300[300] & 250[250] & 220 & 350 & 350 & 350 & & & & TH-N40OKPR & 105 to 250 \\
\hline SL-N400 & MSOL-N400KP & 125[110] & 220[200] & 225[200] & 250 & 400[400] & 400[400] & 350[350] & 300 & 450 & 450 & 450 & & & & TH-N400kP & 105 to 330 \\
\hline SL-N600 & - & 190[160] & 330[300] & 330[300] & 330 & 630[630] & 630[630] & 500[500] & 420 & 660 & 660 & 660 & 1a2b & & UN-AX600x1 & TH-N600KP & 250 to 500 \\
\hline SL-N800 & - & 220[200] & 440[400] & 500[400] & 500 & 800[800] & 800[800] & 720[720] & 630 & 800 & 800 & 800 & (3a4b \(\times 2)\) & & (-) & (Note 3) & 250 to 660 \\
\hline
\end{tabular}

Note 1. The value in parentheses for the rated operating current is applicable in the case of magnetic contactors.
Note 2. Use model names SLD-T \(\square\), SLD-N \(\square\) or MSOLD-T \(\square\), MSOLD-N \(\square\) for DC closing coils.
Note 3. Use TH-N600 in combination with a separately sold current transformer (Mitsubishi CW- \(\square\) ).
Note 4. Reversing (SL(D) \(-2 \times \mathrm{T} \square\), \(\mathrm{SL}(\mathrm{D})-2 \times \mathrm{N} \square\) or MSOL(D) \(-2 \times \mathrm{T} \square, \mathrm{MSOL}(\mathrm{D})-2 \times \mathrm{N} \square\) types) can also be manufactured.
Note 5. Refer to page 51 for information regarding application to resistive loads and capacitive loads.
Note 6. The main contact minimum operating voltage and current differ depending on the allowable fault rate. Please refer to page 42 for details.
Note 7. No specification needs to be made for contact arrangements that are valid and self-demagnetizing.
Note 8. MSOL(D)-T \(\square\) and MSOL(D)-N \(\square\) types can also be manufactured.

\section*{Operating Transformer Capacity, Capacitive Tripping}
\begin{tabular}{|c|c|c|c|c|}
\hline Frame & Operating Transformer Capacity (For AC Operation) & Minimum Capacitance For Capacitive Tripping (For AC200 V) ( \(\mu \mathrm{F}\) ) & \multicolumn{2}{|l|}{Capacitive Tripping Device Model Name Note 2} \\
\hline & (VA) & Note 1 & AC100V & AC200V \\
\hline T21 & 75 to 100 & 40 & \multirow{3}{*}{CTU-A1} & \multirow{3}{*}{CTU-A2} \\
\hline T35 & 75 to 100 & 40 & & \\
\hline T50 & 75 to 100 & 40 & & \\
\hline T65 & 75 to 100 & 150 & \multirow{8}{*}{CTU-B1} & \multirow{8}{*}{CTU-B2} \\
\hline T80 & 75 to 100 & 150 & & \\
\hline T100 & 100 to 150 & 150 & & \\
\hline N125 & 100 to 150 & 150 & & \\
\hline N150 & 100 to 150 & 150 & & \\
\hline N220 & 150 to 200 & 150 & & \\
\hline N300 & 200 to 300 & 150 & & \\
\hline N400 & 200 to 300 & 150 & & \\
\hline N600 & 300 to 400 & 600 & \multirow[b]{2}{*}{CTU-C1} & \multirow[b]{2}{*}{CTU-C2} \\
\hline N800 & 300 to 400 & 600 & & \\
\hline
\end{tabular}

Note 1. The minimum capacitance for capacitive tripping is the value required to trip the circuit within 5 seconds of a power failure.
Note 2. CTU type capacitive tripping device specifications. Charging for at least 10 seconds at the rated voltage allows for tripping up to 30 seconds after a power failure.
- Tripping Coil Rated Voltage/Frequency

For AC100 V: 100 to \(110 \mathrm{~V}, 50 / 60 \mathrm{~Hz}\)
For AC200 V: 200 to 220 V, \(50 / 60 \mathrm{~Hz}\)
- Uses an electrolytic capacitor, so the capacity should be checked periodically.
Note 3. An electrolytic capacitor is used. Touching the conductive portion may cause an electric shock even if the rated voltage is OFF. Check if the product has been completely discharged by using methods such as shorting terminals 1 and 2 through the resistor before starting maintenance.

\section*{- Structure/Operation}
- Structure

The latch is installed above the unit for T21 to T80 types and beneath the power supply side the unit for T100 and N125 to N800 types. The figure below shows a typical application.


\section*{MS－T／N Series Magnetic Starters／Magnetic Contactors}

\section*{－Operation}

\section*{Closing}
（1）Energizing the closing coil attracts the movable core， engaging lever A or the latch receiver to the latch while simultaneously close－circuiting the main contact．
（2）When the latch engages the self－demagnetizing contact is open－circuited，stopping current to the closing coil and completing the close．
Tripping
（1）Energizing the tripping coil attracts the movable core， freeing lever A or the latch receiver from the latch．
（2）When the latch is released the movable core returns to its original position and the main contact is opened．

\section*{－Manual Operation}

The contactors can be manually operated for the purpose of sequence checking．Manually close or trip the contactor using a screwdriver as per figures 2 to 5 ．However，do not operate manually if a current is flowing through the main circuit，as there is a risk of electric shock due to arcing．
－Control Command Duration（Minimum Energize Time） The command duration of external switches that direct the closing coil or tripping coil must be 0.3 seconds or more for T21 to T100 and N125 to N220 types and 0.5 seconds or more for N300 to N800 types．


Fig．1．Circuit Example

（SL（D）－T21 to T50）


Fig．4．Manual Operation
（SL（D）－T100，SL（D）－N125 to N400）


注．図は右側のカバーを外した状態で部分的に断面にしたものです。

Fig．5．Manual Operation（SL（D）－N600／N800）

\section*{Handling}
- Model Name

An SL in the model name indicates an AC closing coil while SLD indicates a DC closing coil. Magnetic starter (with thermal overload relay) model names are either MSOL type or MSOLD type.

\section*{- Operation Coils}

S and SD types have different coil rated operational voltage ranges for both closing and tripping coils. The closing and tripping coils are both short-rated for 15 second operation, so be sure to connect a self-demagnetizing contact in series with the coil.The allowable range of the applied voltage is 85 to \(110 \%\) of the rated voltage.
- Operating Switch Contact Capacity

Caution is required as the coil input to SL and SLD types is greater than that for \(S\) and SD types. Coil breaking in regular operation is done by the self-demagnetizing contact, so operation is possible using a closing relay or operating switch with making capacity equivalent to the coil input. However, in some cases the command duration is too short (approx. 0.5 seconds required), or breaking may be triggered by external shocks, so a contact with breaking capacity should be used.
- Closing and Tripping Commands Configure your system such that the closing switch and tripping switch command signals never overlap (simultaneous contact).
- Power Supply Capacity

Caution is required as the momentary input to the operation coil is greater than that for S and SD types.
- Control Circuit Wiring

Do not remove the wiring for the operation coil and selfdemagnetizing contact (bold lines in figure below) but wire according to the caution nameplate attached to the unit.
\begin{tabular}{|lll}
\hline \begin{tabular}{l} 
The standard product is wired \\
between the control coil and \\
self-demagnetizing contact. \\
(Bold Line Parts)
\end{tabular} & & \\
Circuit Example
\end{tabular}
- Disassembly

Mechanically latched magnetic contactors are calibrated assembled products, so the coil cannot be replaced or disassembled. (Do not disassemble.)

\section*{Application Example}

Fig. 6. shows an example using a latched type for both regular and backup use with switched power supplies. Fig. 7. shows an example using a latched type for regular operation and a standard type (without latch) for backup use. When switching with a timer use periods of 0.2 seconds or more.

MC1 : Regular Power Supply Magnetic Contactor SL-T/N
MC2 : Backup Power Supply Magnetic Contactor SL-T/N
VSR : Voltage Relay SRE
RT1 : Regular/Backup Period Timer (Off Delay)
RT2 : Backup/Regular Timer (Off Delay)
F : Fuse


Fig. 6. Application Example (Latched Type For Both Regular And Backup)

MC1 : Regular Power Supply Magnetic Contactor SL-T/N
MC2 : Backup Power Supply Magnetic Contactor S-T/N
VSR : Voltage Relay SRE
RT1 : Regular/Backup Period Timer (Off Delay)
RT2 : Backup/Regular Timer (Off Delay)
F : Fuse


Fig. 7. Application Example (Latched Type For Regular, Standard Type For Backup)

Note. * contacts are self-demagnetizing contacts wired to the closing coil (MC1, MC2) or tripping coil (MT1, MT2).
\begin{tabular}{|c|c|c|c|}
\hline \multirow{9}{*}{\begin{tabular}{l}
Related \\
Reference Page
\end{tabular}} & Item & Reference Page & Remarks \\
\hline & - Main Contact Rating & Page 39 & - \\
\hline & - Auxiliary Contact Rating & Page 41 & - \\
\hline & - Operation Coil & Page 44 & - \\
\hline & - Properties & Page 46 & - \\
\hline & - Performance & Page 46 & - \\
\hline & - Outline Drawings/Contact Arrangements & Page 106 & - \\
\hline & - How to Order & Page 130 & - \\
\hline & - Combining with Optional Units & Page 194 & - \\
\hline
\end{tabular}

\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

Outline Drawings/Contact Arrangements (Mechanically Latched Magnetic Starters/Magnetic Contactors)
T21 (The diagrams show models without "BC".)
Non-Reversing

SL(D)-T21(BC)


T35/T50 (The diagrams show models without "BC".)
\begin{tabular}{|c|c|}
\hline Model Name & Model Name \\
\hline SL-2xT35 & SLD-2xT35 \\
\hline SL-2xT50 & SLD-2xT50 \\
\hline
\end{tabular}

T65/T80


\section*{T100}


\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

Note 1. The terminal numbers in parentheses for the \(S, S D, S L(D)\) auxiliary contacts in the center contact arrangement example are indicated along with the product, and represent the numbers of the old version (A Series).
N125


N150


\section*{Reversing}

SL(D)-2xN150


Note 1. The terminal numbers in parentheses for the S, SD, SL(D) auxiliary contacts in the center contact arrangement example are indicated along with the product, and represent the numbers of the old version (A Series).
N220
Non-Reversing


\section*{Reversing}

SL(D)-2xN220


\section*{14 kg}

\section*{N300/N400}

\section*{Non-Reversing}

SL(D)-N300
SL(D)-N400


\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

Note 1. The terminal numbers in parentheses for the S, SD, SL(D) auxiliary contacts in the center contact arrangement example are indicated along with the product, and represent the numbers of the old version (A Series).

\section*{N600/N800}


\subsection*{4.5 MSO/S- \(\square\) DL Delay Open Magnetic Starters/Magnetic Contactors}

\section*{Retains the closed state for \(2_{-1}^{+2}\) seconds during a momentary power failure}
- In cases of momentary power failures or momentary voltage drops due to lightning strikes on wiring etc., the discharge from a capacitor allows the closed state to be retained for \(2^{2+1}\) seconds.
- No re-closing operations for magnetic contactors are required when power is restored, which makes continuous load operation possible.
- Suitable for temporary storage circuitry in illumination equipment or automatic control devices.


Ratings/Specifications (Standard Applicability)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{3}{*}{Magnetic Contactors} & \multirow[b]{3}{*}{Magnetic Starters (Note 8)} & \multicolumn{4}{|l|}{\multirow[t]{2}{*}{Rated Capacity [kW] Three-Phase Squirrel-cage Motor (Category AC-3)}} & \multicolumn{6}{|c|}{Rated Operating Current [A]} & \multirow[t]{3}{*}{\begin{tabular}{l}
Converional Free \\
Air Thermal Current \\
Ith \\
[A]
\end{tabular}} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Auxiliary Contact}} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Compatible Thermal Overload Relays}} \\
\hline & & & & & & \multicolumn{4}{|l|}{Three-Phase Squirrel-cage Motor (Category AC-3)} & \multicolumn{2}{|l|}{\[
\begin{array}{|l|}
\hline \begin{array}{l}
\text { Resistive Load } \\
\text { (Category AC-1) }
\end{array} \\
\hline
\end{array}
\]} & & & & & \\
\hline & & \[
\begin{aligned}
& 220 \text { to } \\
& 240 \mathrm{~V}
\end{aligned}
\] & \[
\begin{aligned}
& 380 \mathrm{to} \\
& 440 \mathrm{~V}
\end{aligned}
\] & 500 V & 690 V & \[
\begin{aligned}
& 220 \text { to } \\
& 240 \mathrm{~V}
\end{aligned}
\] & \[
\begin{aligned}
& 380 \mathrm{to} \\
& 440 \mathrm{~V}
\end{aligned}
\] & 500 V & 690 V & \[
\begin{aligned}
& 200 \text { to } \\
& 240 \mathrm{~V}
\end{aligned}
\] & \[
\begin{aligned}
& 380 \mathrm{to} \\
& 440 \mathrm{~V}
\end{aligned}
\] & & Valid & Additional Unit Model Names x Pieces & Model Name & Heater Designation Range [A] \\
\hline S-T12DL & MSO-T12DLKP & 3.5 [2.7] & 5.5 [4] & 5.5 [5.5] & 5.5 & 13 [13] & 12 [9] & 9 [9] & 7 & 20 & 13 & 20 & - & \multirow{9}{*}{- Note 3} & TH-T18KP & 0.12 to 11 \\
\hline S-T21DL & MSO-T21DLKP & 5.5 [4] & 11 [7.5] & 11 [7.5] & 7.5 & 25 [20] & 23 [20] & 17 [17] & 9 & 32 & 32 & 32 & 1a1b & & TH-T25KP & 0.24 to 22 \\
\hline S-T35DL & MSO-T35DLKP & 11 [7.5] & 18.5 [15] & 18.5 [15] & 15 & 40 [35] & 40 [32] & 32 [26] & 17 & 60 & 60 & 60 & \multirow{7}{*}{1a1b} & & TH-T25KP & ( 0.24 to 22 \\
\hline S-T50DL & MSO-T50DLKP & 15 [11] & 22 [22] & 25 [22] & 22 & \[
55(50)[50]
\] & 50 [48] & 38 [38] & 26 & 80 & 80 & 80 & & & TH-T25KP & 0.24 to 22 \\
\hline S-T65DL & MS0-T65DLK & 18.5 [15] & 30 [30] & 37 [30] & 30 & (Note 1) & 65 [65] & 60 [45] & 38 & 100 & 100 & 100 & & & TH-T50KP & 29 to 42 \\
\hline & & & & & & & & & & & & & & & TH-T65KP & 15 to 54 \\
\hline S-T80DL & MSO-T80DLKP & 22 [19] & 45 [37] & 45 [45] & 45 & 85 [80] & 85 [80] & 75 [75] & 52 & 120 & 120 & 120 & & & (Note 8) & 67 \\
\hline S-T100DL & MSO-T100DLKP & 30 [22] & 55 [45] & 55 [45] & 55 & 105 [100] & 105 [93] & 85 [75] & 65 & 150 & 150 & 150 & & & TH-T65KP & 15 to 54 \\
\hline & & \(30[22]\) & 55[45] & 55 [4] & & & 105 [3] & [5] & 65 & 150 & 150 & 150 & & & TH-T100KP & 67, 82 \\
\hline S-N150DL & MSO-N150DLKP & 45[37] & 75[75] & 90[90] & 90 & 150[150] & 150[150] & 140[140] & 100 & 200 & 200 & 200 & \multirow{4}{*}{1a1b} & \multirow{4}{*}{\[
\begin{array}{r}
\text { UN-AX150x1 } \\
\text { Note } 3
\end{array}
\]} & TH-N12OKP(TA) & 42 to 125 \\
\hline S-N220DL & MSO-N220DLKP & 75[55] & 132[110] & 132[132] & 132 & 250[220] & 250[220] & 200[200] & 150 & 260 & 260 & 260 & & & TH-N22OKPRH & 82 to 180 \\
\hline S-N300DL & MSO-N300DLKP & 90[75] & 160[150] & 160[160] & 200 & 300[300] & 300[300] & 250[250] & 220 & 350 & 350 & 350 & & & TH-N400kPRH & 105 to 250 \\
\hline S-N400DL & MSO-N400DLKP & 125[110] & 220[200] & 225[200] & 250 & 400[400] & 400[400] & 350[350] & 300 & 450 & 450 & 450 & & & TH-N400krrn & 105 to 330 \\
\hline
\end{tabular}

Note 1. The value in parentheses for the rated operating current is applicable in the case of magnetic contactors.
Note 2. The combining magnetic contactor is dedicated for use with T50 or less AC operated type (S type), or T65 to 100 and N125 or greater DC operated type (SD type), and cannot be replaced alone.
Note 3. Auxiliary contact units UN-AX150 can be installed on the left side for N150DL to N400DL types; however, T12DL to T100DL types cannot be used to mount additional auxiliary contact units
Note 4. Magnetic starters can be manufactured to have 3-element (2E) thermal overload relays (MSO- \(\square\) DLKP) included.
Note 5. MSO-T12 to T100DL(KP)SR (with saturable reactors and thermal overload relays) cannot be manufactured.
Note 6. Instantaneous stop/restart relays (UA-DL2) are also available as related products. Refer to page 346.
Note 7. Cannot be used with live part protection covers. Furthermore, types with wiring streamlining terminals (BC) cannot be manufactured.
Note 8. Thermal overload relay dedicated for MSO-T80DL 67 A. S-T80DL and the standard TH-T100 67 A cannot be combined for use as a magnetic starter.
Note 9. MSO-T \(\square\) DL and MSO-N \(\square\) DL types can also be manufactured

\section*{Properties/Performance/Operation Coil}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Frame} & \multicolumn{2}{|l|}{Input [VA]} & \multicolumn{2}{|l|}{Operating Voltage [V]} & \multicolumn{2}{|l|}{Operating Time [ms]} & \multicolumn{2}{|l|}{Operation Coils} & \multirow[t]{2}{*}{\begin{tabular}{|c|}
\hline Making and \\
Breaking Current \\
Capacities
\end{tabular}} & \multirow[b]{2}{*}{\begin{tabular}{l}
Switching \\
Frequency
\end{tabular}} & \multicolumn{2}{|l|}{Switching Durability [x 10000]} & \multirow[b]{2}{*}{Delay Time} \\
\hline & Inrush & Normal & Close & Open & \[
\begin{aligned}
& \text { Operating Power ON } \\
& \rightarrow \text { Main Contact ON }
\end{aligned}
\] & \[
\begin{aligned}
& \text { Operating Power OfF } \\
& \rightarrow \text { Nain Contact OFF }
\end{aligned}
\] & Designation & Rated Voltage & & & Mechanical & Electrical
(Category AC-3) & \\
\hline T12DL & 70 & 13 & \multirow{11}{*}{\begin{tabular}{l}
85\% or \\
Less of Operation Coil Rated Voltage
\end{tabular}} & \multirow{11}{*}{\begin{tabular}{l}
\(10 \%\) or \\
More of Operation Coil Rated Voltage
\end{tabular}} & \multirow[b]{2}{*}{7 to 100} & \multirow{11}{*}{10 to 100} & \multirow{7}{*}{AC100V} & \multirow{6}{*}{\[
\begin{array}{|c}
100 \text { to } 110 \mathrm{~V} \\
50 / 60 \mathrm{~Hz}
\end{array}
\]} & \multirow[t]{4}{*}{10 Times Class AC-3 Rated Operating Current} & \multirow{11}{*}{\begin{tabular}{l}
1200 \\
Times/ Hour
\end{tabular}} & & \multirow{10}{*}{100} & \multirow{11}{*}{\begin{tabular}{l}
\(2_{-1}^{+2}\) \\
Seconds (Fixed)
\end{tabular}} \\
\hline T21DL & 100 & 15 & & & & & & & & & 100 & & \\
\hline T35DL & 113 & 24 & & & 7 t & & & & & & 20 & & \\
\hline T50DL & 113 & 24 & & & 7 to 100 & & & & & & 20 & & \\
\hline T65DL & 55 & 26 & & & \multirow{7}{*}{30 to 100} & & & & - & & & & \\
\hline T80DL & 55 & 26 & & & & & & & & & & & \\
\hline T100DL & 66 & 27 & & & & & & 200 to 220V & & & & & \\
\hline N150DL & 76 & 55 & & & & & AC200V & \(50 / 60 \mathrm{~Hz}\) & 8 Times & & 500 & & \\
\hline N220DL & 100 & 66 & & & & & & & \begin{tabular}{l}
Class AC-3 \\
Rated
\end{tabular} & & & & \\
\hline N300DL & 140 & 85 & & & & & & & Operating & & & & \\
\hline N400DL & 140 & 85 & & & & & & & Current & & & 50 & \\
\hline
\end{tabular}

\footnotetext{
Note 1. The above indicates rough property indices for AC200V coils.
Note 2. The input is the average when applying 220 V at 60 Hz . Values for AC100V coils are approximately the same.
Note 3. The operating time is the value when applying 200 V at 60 Hz . Values for AC100V coils are approximately the same.
Note 4. Operation coils are only AC100V or AC200V.
}

\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

\section*{Connecting}


Deployment Connection Diagram


MSO-T12DL(KP) Actual Wiring Diagram

Note 1. The figure to the left is for MSO- \(\square\) DL
Note 2. The MCCB, ON and OFF buttons in the figure to the left are not provided.
Note 3. If connecting an external magnetic coil or indicator lamp, connect between the R/1 and S/3 terminals.


MSO-T21DL(KP) Actual Wiring Diagram

The connections shown with single-dashed lines between the L1-R/1 and L2-S/3 terminals are not wired if the control circuit voltage is AC 100 V or if the main circuit and control circuit voltages differ.

\section*{- Operation Description (Deployment Connection Diagram)}

\section*{- Power Supply Closing}

Closing the power supply with \(M C C B\) causes \(C\) to charge via \(\mathrm{RF}^{2}\) and \(\mathrm{R}_{1}\)

\section*{- Closing Magnetic Contactors}

Pressing the ON button causes MC to energize via MCb , closing the contactor.
When MC has completed closing, MCb opens and, in the order of \(\mathrm{MCa} \rightarrow \mathrm{R}_{2} \rightarrow \mathrm{MC}\), the current flows to retain the contactor.

\section*{- Opening Magnetic Contactors}

Pressing the OFF button cuts off current to MC, instantly opening the magnetic contactor.
- When Power Supply Voltage Drops and Momentary Power Failures Occur
Charge accumulated in C discharges via \(\mathrm{R}_{1} \rightarrow \mathrm{R}_{2} \rightarrow\) \(M C\) circuits, opening \(M C\) after a predetermined time (after the delay time).

\section*{- Handling (Deployment Connection Diagram)}
- If ON and OFF for MCCB are repeated at short intervals (or when momentary power failures occur several times in quick succession) the following may occur
(1) The inrush current to RF and \(R_{1}\) repeatedly flows, causing overloading.
(2) Sufficient charge is not provided to C , causing damage to components or insufficient retention time.
- Even when the power is OFF (MCCB is OFF), charge may still reside within C, so necessary precautions should be taken to avoid electric shocks.
- ON and OFF operations should be conducted using the push-button switch located as in the figure above. The magnetic contactor may flip-flop when the power is switched ON or OFF. Also, when switching the power to perform sequence checks etc., the operator should allow at least 5 seconds for the capacitor to charge.
- Uses an electrolytic capacitor so the delay time should be checked periodically.

\section*{Outline Drawings}


MSO/S-T12, T21, T35, T50DL


MSO/S-T65 to T100DL
MSO/S-N125 to N400DL
- Caution Do not install wiring or other equipment in the vicinity of the resistor (refer to the figure above) as it reaches high temperatures (approx. \(100^{\circ} \mathrm{C}\) temperature rise).

\section*{Variable Dimensions Table}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline  & A & AB & AC & AD & AE & B & BA & BC & BD & BE & BF & BG & BH & C & CA & CB & CD & CE & CF & CG & CH & D & E & F & G \\
\hline T12DL & 132 & 40 & 49 & 69 & 29.8 & 110 & 100 & 5 & 11.2 & 83 & 41.6 & - & 12.5 & 113 & 65 & 6 & - & 43 & - & 85 & 5 & M3.5 & M3.5 & - & 3-M4 \\
\hline T21DL & 137 & 60 & 43 & 73 & 34 & 125 & 100 & 19 & 10.5 & 94.5 & 49 & - & 11 & 113 & 65 & 6 & - & 65 & - & 88 & 5 & M4 & M3.5 & - & 3-M4 \\
\hline T35/T50DL & 134 & 50 & 42 & 67 & 38.5 & 162 & 150 & 6 & 23 & 103 & 55 & 21.5 & - & 114 & 70.5 & 8 & 69.5 & 67 & - & 89 & 5 & M5 & M3.5 & M5 & 3-M4 \\
\hline T65/T80DL & 150 & 50 & 56 & 81 & 50 & 168 & 150 & 9 & 27 & 126 & 74 & - & - & 141 & 103.5 & 8 & - & 95.5 & - & 118 & 5 & M6 & M4 & M6 & 3-M5 \\
\hline T100DL & 170 & 100 & 35 & 85 & 53 & 220 & 200 & 10 & 35.5 & 148 & 93 & 20 & - & 165 & 127 & 8 & 109 & 118.5 & 133 & 141 & 10 & M6 & M4 & M6 & 3-M6 \\
\hline N150DL & 210 & 140 & 26 & 105 & 80 & 270 & 250 & 10 & 33 & 200 & 130 & 25 & - & 177.5 & 136.5 & 8 & - & 99.5 & 102 & 133.5 & 10 & M8 & M4 & M8 & 3-M8 \\
\hline N220DL & 230 & 140 & 20 & 90 & 90 & 290 & 250 & 12 & 31 & 246.5 & 158 & - & - & 208.5 & 156.5 & 8 & - & 103.5 & - & 214 & 10 & M10 & M4 & - & 3-M8 \\
\hline N300/N400DL & 300 & 200 & 10 & - & 110 & 363.5 & 200 & 25 & 30 & 318.5 & 190 & - & - & 229 & 170 & 8 & - & 122.5 & - & 227 & 10 & M12 & M4 & - & 4-M8 \\
\hline
\end{tabular}

Weight Table
\begin{tabular}{l|c|c}
\hline & S- & MSO- \\
\hline T12DL & 0.73 & 0.84 \\
\hline T21DL & 0.98 & 1.2 \\
\hline T35/T50DL & 1.20 & 1.44 \\
\hline T65/T80DL & 2.8 & 3.1 \\
\hline T100DL & 3.9 & 4.4 \\
\hline N150DL & 6.3 & 7.6 \\
\hline N220DL & 9.1 & 11.6 \\
\hline N300/N400DL & \(15 / 15.5\) & \(17.5 / 18\) \\
\hline
\end{tabular}

Note 1. *1: "CH" is the arc space.
Note 2. Below indicates the case when using TH-T50/T100 and TH-N \(\square\) TA thermal overload relays. *2: "BG" has extended terminal pitch, "F Screw" has a terminal screw on the load side *3: "CD" has load side 4/T2 terminal height
*4: "CF" has load side 2/T1, 6/T3 terminal height
Note 3. The F screw for MSO-T35/T50DL is M4 with heater designations of 22A or below.
Note 4. The maximum outline drawings ( \(\mathrm{A} \times \mathrm{B} \times \mathrm{C}\) ) of \(\mathrm{S}-\square \mathrm{DL}\) and MSO- \(\square\) DL are the same. However, S-N300/N400DL has a "B" dimension of 250.
Note 5 . The power connector protrudes from the product on the power supply side by approximately 15 mm .
\begin{tabular}{|c|c|c|c|}
\hline \multirow{5}{*}{} & Item & Reference Page & Remarks \\
\hline & - Main Contact Rating & Page 39 & - \\
\hline & - Auxiliary Contact Rating & Page 41 & - \\
\hline & - How to Order & Page 133 & Be sure to specify main circuit specifications and operation coil designation as both MSO-ZDL and S- \(\square\) DL may or may not require wiring from the main circuit. \\
\hline & - Combining with Optional Units & Page 194 & - \\
\hline
\end{tabular}

\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

\subsection*{4.6 MSO- \(\square(\mathrm{KP})\) SR Magnetic Starters with Saturable Reactors and Thermal Overload Relays \\ Capable of protecting motors with a long starting time from burnout \\ - Thermal overload relays with saturable reactors and magnetic contactors can be used in combination. \\ - Prevents motor overload or restriction when starting time is long or starting current is especially large, as well as preventing unnecessary thermal overload relay operation. \\ - Can be used to protect motors that are run intermittently. \\  \\ MSO-T25KPSR}

\section*{Ratings/Specifications (Standard Applicability)}


Note 1. Enclosed magnetic starters are not manufactured.
Note 2. Reversible types can also be manufactured for MSO-2x \(\square\) SR, T21, N125 or greater, as well as for MSO-2x \(\square\) KPSR types. MSO-2XT10 to T20SR use a thermal overload relay TH-T18HZSR.
Note 3. Only 1 UT-AX11 type unit can be installed on the right side of MSO-T21 to T50KPSR types.
Note 4. Cannot be used with live part protection covers (UT-CW, UN-CZ).
Note 5. MSO-T10SR to T50(KP)SR can also be manufactured to have wiring streamlining terminals (BC).
Note 6. MSO-T10 to T20BCSR have no screw holder attached to the main circuit terminal (3-pole) on the magnetic contactor load side.
Note 7. MSO-T35, T50BC(KP)SR with heater designation of 29 A or more and MSO-2xT21 to T50BC(KP)SR have no screw holder in the main circuit terminal (3-pole) on the thermal relay power supply side.

\begin{tabular}{|c|c|c|}
\hline Item & Reference Page & Remarks \\
\hline - Main Contact Rating & Page 39 & - \\
\hline - Auxiliary Contact Rating & Page 41 & - \\
\hline - Operation Coil & Page 43 & Same as MSO/S- \(\square\) types. \\
\hline - Properties & Page 45 & \begin{tabular}{l}
Same as MSO/S- \(\square\) types. \\
Refer to pages 136,145 for information about thermal overload relays.
\end{tabular} \\
\hline - Performance & Page 46 & \begin{tabular}{l}
Same as MSO/S- \(\square\) types. \\
However, the switching frequency of MSO-T10SR to T50(KP)SR types is 1200 times/hour, with a mechanical durability of 2.5 million operations. Refer to pages 136, 145 for information about thermal overload relays
\end{tabular} \\
\hline - How to Order & Page 133 & - \\
\hline - Combining with Optional Units & Page 194 & - \\
\hline
\end{tabular}

\section*{Application}
- Protecting Motors with Long Starting Time

Prevents starting malfunctions when running with a load with large inertia. Use with motors that have a starting current of 5
to 8 times the full-load current and a starting time of 10 to 25 seconds.
- Protecting Motors with Large Starting Current

Use with motors that have a starting current greater than 8 times but no more than 20 times the full-load current. Capable of starting the motor without causing the heater of the thermal overload relay to melt. However, the magnetic starter should be selected such that the motor starting current is no more than 6 times the rated operating current of the class AC- 3 magnetic starter.
- Protecting Motors Running Intermittently

Capable of protecting motors without sacrificing overload protection functionality when periodically running motors intermittently or when wanting to make use of the maximum motor output over short periods.
Note 1. In either case, consideration is required to find a balance between the motor and protection to suit the desired motor properties.

\section*{Outline Drawings}


Fig. a. MSO-T10 to T50(KP)SR Types


Fig. b. MSO-T65 to T100(KP)SR Types


Fig. c. MSO-N125 to N400(KP)SR Type
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline Frame & No. Thermal Elements & A & AB & AC & B & BA & BC & D & G & Weight [kg] & Reference Diagram (Above Figure) \\
\hline T10SR & \multirow{10}{*}{2} & 94 & 28 & 30.5 & 150 & 60 & 10.5 & 79 & M4 & 0.54 & \multirow{4}{*}{Fig. a} \\
\hline T12/T20SR & & 94 & 35 & 30.3 & 150 & 60 & 10.5 & 79 & M4 & 0.56 & \\
\hline T21/T25SR & & 97.5 & 54 & 4.5 & 162.5 & 60 & 16 & 82 & M4 & 0.78 & \\
\hline T35/T50SR & & 97.5 & 65 & 5 & 170.5 & 70 & 13.8 & 91 & M4 & 0.99 & \\
\hline T65/T80SR & & 140 & 70 & 26 & 189.5 & 75 & 15.5 & 106 & M4 & 1.25 & \multirow[b]{2}{*}{Fig. b} \\
\hline T100SR & & 140 & 80 & 25 & 211 & 110 & 7 & 127 & M5 & 2.5 & \\
\hline N125SR & & 164 & 90 & 30 & 239 & 125 & 12.5 & 137 & M4 & 3.9 & \multirow{4}{*}{Fig. c} \\
\hline N150SR & & 164 & 100 & 32 & 250 & 130 & 15 & 145 & M5 & 5 & \\
\hline N180/N220SR & & 144 & 120 & 12 & 282 & 190 & 7 & 180.5 & M6 & 8.2 & \\
\hline N300/N400SR & & 163 & 145 & 9 & 360 & 225 & 9 & 195 & M8 & 11.7/12.2 & \\
\hline T21/T25KPSR & \multirow{8}{*}{3} & 97.5 & 54 & 4.5 & 162.5 & 60 & 16 & 82 & M4 & 0.86 & \multirow[b]{2}{*}{Fig. a} \\
\hline T35/T50KPSR & & 97.5 & 65 & 5 & 170.5 & 70 & 13.8 & 91 & M4 & 1.07 & \\
\hline T65/T80KPSR & & 140 & 70 & 26 & 189.5 & 75 & 15.5 & 120.5 & M4 & 1.35 & \multirow[b]{2}{*}{Fig. b} \\
\hline T100KPSR & & 140 & 80 & 25 & 211 & 110 & 7 & 145 & M5 & 2.6 & \\
\hline N125KPSR & & 164 & 90 & 30 & 269 & 125 & 12.5 & 137 & M4 & 4.1 & \multirow{4}{*}{Fig. c} \\
\hline N150KPSR & & 164 & 100 & 34 & 273 & 130 & 15 & 145 & M5 & 5.2 & \\
\hline N180/N220KPSR & & 168 & 120 & 36 & 282 & 190 & 7 & 180.5 & M6 & 8.5 & \\
\hline N300/N400KPSR & & 178 & 145 & 24 & 360 & 225 & 9 & 195 & M8 & 11.8/12.3 & \\
\hline
\end{tabular}
4.7 MSO- \(\square\) FS(KP) Magnetic Starters with Quick-acting Characteristics Thermal Overload Relays Capable of protecting motors with small heat capacity
- Quick-acting characteristics thermal overload relays and magnetic contactors can be used in combination with each other.
- Suitable for protecting motors such as submersible motors or compressors that have short allowable time during constraint.


MSO-T25FSKP

Ratings/Specifications (Standard Applicability)


Note 1. Thermal overload relays are manufactured for the 1.7 A to 93 A (heater designation 2.1 A to 82 A ) range.
Note 2. Reversible types can also be manufactured for MSO-T21 to T100FS and for MSO-T10 to T100FSKP types.
Note 3. T10 to T50 can also be manufactured to have wiring streamlining terminals (BC).
Note 4. Enclosed MS-TDFS/FSKP types can also be manufactured.
Note 5. Enclosed type heater designation 67A uses a thermal overload relay dedicated for enclosed types.

\begin{tabular}{|l|c|c}
\multicolumn{1}{c|}{ Item } & Reference Page & Remarks \\
\hline\(\cdot\) Main Contact Rating & Page 39 & - \\
\hline\(\cdot\) Auxiliary Contact Rating & Page 41 & - \\
\hline\(\cdot\) Operation Coil & Page 43 & Same as MSO/S- \(\square\) types. \\
\hline\(\cdot\) Performance & Page 46 45 & \begin{tabular}{l} 
Same as MSO/S- \(\square\) types. \\
Refer to pages 136, 147 for information about thermal overload relays.
\end{tabular} \\
\hline\(\frac{\text { Rame as MSO/S- } \square \text { types. }}{\text { Refer to pages 136, 147 for information about thermal overload relays. }}\) \\
\hline\(\cdot\) How to Order & Page 77 & Same as MSO- \(\square\) type. \\
\hline\(\cdot\) Combining with Optional Units & Page 194 & - \\
\hline
\end{tabular}

\subsection*{4.8 MS- \(\square\) PM Magnetic Starters with Push-Buttons}

\section*{ON and OFF control is possible with the power supply and load connections alone}
- The ON and OFF push-button switch is mounted to the surface of the enclosure.
- MS-T10PM and MS-T12PM have a reset button, while MS-T21PM and greater have an OFF button that also resets the thermal overload relay.


MS-T10PM

Ratings/Specifications (Standard Applicability)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Magnetic Starters} & \multicolumn{4}{|c|}{Rated Capacity [kW]} & \multicolumn{4}{|l|}{Rated Operating Current [A]} & \multirow[b]{2}{*}{Auxiliary Contact (Note 5)} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Combinable Thermal Overload Relays}} \\
\hline & \multicolumn{4}{|l|}{Three-Phase Squirrel-cage Motor (Category AC-3)} & \multicolumn{4}{|l|}{Three-Phase Squirrel-cage Motor (Category AC-3)} & & & \\
\hline With ON, OFF and Reset Buttons (Note 8) & \[
\begin{gathered}
\text { AC220 } \\
\text { to } 240 \mathrm{~V}
\end{gathered}
\] & \[
\begin{gathered}
\mathrm{AC} 380 \\
\text { to } 440 \mathrm{~V}
\end{gathered}
\] & AC500 V & AC690 V & \[
\left|\begin{array}{c}
\mathrm{AC} 220 \\
\text { to } 240 \mathrm{~V}
\end{array}\right|
\] & AC380 & AC500 V & AC690 V & Standard (Special) & Model Name & Heater Designation Range [A] \\
\hline MS-T10KPPM & 2.5[2.2] & 4[2.7] & 4[2.7] & 4 & 11[11] & 9[7] & 7[6] & 5 & 1a(1b) & \multirow[b]{2}{*}{TH-T18KP} & 0.12 to 9 \\
\hline MS-T12KPPM & 3.5[2.7] & 5.5[4] & 5.5[5.5] & 5.5 & 13[13] & 12[9] & 9[9] & 7 & 1a1b(2a) & & 0.12 to 11 \\
\hline MS-T21KPPM & 5.54|/Note 4) & 11[7.5] & 11[7.5] & 7.5 & 25[20] & 23[20] & 17[17] & 9 & \multirow{9}{*}{2a2b} & TH-T25KP & 0.24 to 15 \\
\hline \multirow[t]{2}{*}{MS-T35KPPM} & \multirow[t]{2}{*}{11[7.5]} & \multirow[t]{2}{*}{18.5[15]} & \multirow[t]{2}{*}{18.5[15]} & \multirow[t]{2}{*}{15} & \multirow[t]{2}{*}{40[35]} & \multirow[t]{2}{*}{40[15]} & \multirow[t]{2}{*}{32[26]} & \multirow[t]{2}{*}{17} & & TH-T25KP & 0.24 to 22 \\
\hline & & & & & & & & & & TH-T50KP & 29 \\
\hline \multirow[t]{2}{*}{MS-T50KPPM} & \multirow[t]{2}{*}{15[11]} & \multirow[t]{2}{*}{22[22]} & \multirow[t]{2}{*}{25[22]} & \multirow[t]{2}{*}{22} & \multirow[t]{2}{*}{55(50)[50]} & \multirow[t]{2}{*}{50[48]} & \multirow[t]{2}{*}{38[38]} & \multirow[t]{2}{*}{26} & & TH-T25KP & 0.24 to 22 \\
\hline & & & & & & & & & & TH-T50KP & 29 to 42 \\
\hline MS-T65KPPM & 18.5[15] & 30[30] & 37[30] & 30 & 65[65] & 65[65] & 60[45] & 38 & & TH-T65KP & 15 to 54 \\
\hline MS-T80KPPM & 22[19] & 45[37] & 45[45] & 45 & 85[80] & 85[80] & 75[75] & 52 & & (Note 7) & 67 \\
\hline \multirow[t]{2}{*}{MS-T100KPPM} & \multirow[t]{2}{*}{30[22]} & \multirow[t]{2}{*}{55[45]} & \multirow[t]{2}{*}{55[45]} & \multirow[t]{2}{*}{55} & \multirow[t]{2}{*}{105[100]} & \multirow[t]{2}{*}{105[93]} & \multirow[t]{2}{*}{85[75]} & \multirow[t]{2}{*}{65} & & TH-T65KP & 15 to 54 \\
\hline & & & & & & & & & & TH-T100KP & 67, 82 \\
\hline
\end{tabular}

Note 1. Auxiliary contact units cannot be installed.
Note 2. Can be manufactured to have 3-element (2E) thermal overload relays (MS- \(\square \mathrm{KPPM}\) ) included.
Note 3. Can be manufactured to have thermal overload relays that cannot be reset at the surface of the enclosure (MS- \(\square \mathrm{PS}\) ).
Note 4. MS-T21PM types with 200 to 220 V ratings are 3.7 kW , in accordance with the Electrical Appliance and Material Safety Law.
Note 5. Among the auxiliary contacts of MS-T21PM or greater, 1 a is internally wired as a self-retaining contact.
Note 6. MS-T \(\square\) DPPM(PS) is for single-phase motors. Refer to page 267 article 10.2 for details about production scope and applicable capacities.
Note 7. Heater designation 67A uses a thermal overload relay dedicated for enclosed types.
Note 8. MS-T \(\square\) PM and MS-N \(\square\) PM types can also be manufactured.
\begin{tabular}{|c|c|c|c|}
\hline & Item & Reference Page & Remarks \\
\hline & - Main Contact Rating & Page 39 & - \\
\hline \(\square\) & - Auxiliary Contact Rating & Page 41 & - \\
\hline Related & - Operation Coil & Page 43 & Same as MS/MSO/S- \(\square\) types. \\
\hline  & - Properties & Page 45 & \begin{tabular}{l}
Same as MS/MSO/S- \(\square\) types. \\
Refer to pages 136,145 for information about thermal overload relays.
\end{tabular} \\
\hline & - Performance & Page 46 & Same As Above \\
\hline & - How to Order & Page 131 & - \\
\hline
\end{tabular}

\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

Outline Drawings


Note 1. Leave 100 mm space at the bottom of the enclosure when mounting MS-T10KP to T50KP types.
Note 2. 3 rubber bushings are included for MS-T10KP to T50KP types.
Note 3. MS-T \(\square\) and MS-N \(\square\) types can also be manufactured.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Frame} & \multicolumn{11}{|c|}{Variable Dimensions} & \multirow[t]{2}{*}{Weight [kg]} \\
\hline & A & AA & AB & B & BA & BB & BC & C & CA & M & N & \\
\hline T35, T50 & 135 & 95 & 50 & 225 & 165 & 30 & 6 & 126 & 45 & M5 & 28 & 1.9 \\
\hline T65, T80 & 160 & 120 & 80 & 270 & 220 & 25 & 12 & 145 & 45 & M5 & 35 & 2.9 \\
\hline T100 & 190 & 150 & 100 & 300 & 260 & 20 & 12 & 163 & 67 & M6 & 35 & 4.0 \\
\hline
\end{tabular}

\section*{Connection Diagram}


Note 1. The connections in the figure above differ if the main circuit voltage and control circuit voltage differ.

\subsection*{4.9 MSO/S-T \(\square\) BC Magnetic Starters/Magnetic Contactors with Wiring Streamlining Terminals} Equipped with wiring streamlining terminal function and finger safe specifications compliant with DIN EN 50274/ VDE 0660 Teil 514.
- Improved Smart Wiring

Wiring is possible without having to remove the terminal cover, which leads to further improvements in wiring efficiency, workability, and hence productivity. - Abundant Model Range

Both non-reversible and reversible type magnetic starters/magnetic contactors are available for frames up to 10 A to 50 A .


MSO-T10BCKP

Note 1. Terminal numbers are compliant with EN standards (EN50005 and EN50012).
Note 2. The 2 auxiliary break contacts of reversible magnetic starters are wired as an electrical interlock.
Note 3. S/SD-2 x T32BC type has auxiliary contact unit 2 a 2 b (UT-AX4BC) x 2 included as standard.
Note 4. Magnetic starters model names indicate when 3-element (2E) thermal overload relays are included. Remove KP from the model name for 2-element types.
Note 5. DC operated types (SD, MSOD) can also be manufactured. However, T10 and T25 types are not manufactured.
Note 6. Mechanically latched types (SL, SLD) can only be manufactured for T21, T35 and T50.
Note 7. The \(+2 b\) on the auxiliary contact arrangement of reversible T10, T12 and T20 types indicates the break contact of the integrated UT-ML20BC interlock unit. There is no need to specify when ordering.

\section*{Applicable Thermal Overload Relays}
\begin{tabular}{c|cc}
\hline Magnetic Starter Frame & Thermal Overload Relay Model Name \\
\hline T10, T12, T20 & TH-T18BC(KP) \\
\hline T21, T25 & TH-T25BC(KP) & \(* 1\) \\
\hline T35, T50 & TH-T25BC(KP) & \(* 2\) \\
& TH-T50BC(KP) & \(* 2\) \\
\hline
\end{tabular}
*1: Separately arrange a UN-TH21 connecting conductor kit.
*2: Separately arrange a UT-TH50 connecting conductor kit.

\section*{- Connection Diagram/Contact Arrangement Diagram}
- Terminal numbers are compliant with EN50005 and JIS C8201-4-1 standards.
- MSO type connection is the same as the standard type.
\begin{tabular}{|c|c|c|c|}
\hline \multirow{8}{*}{} & Item & Reference Page & Remarks \\
\hline & - Main Contact Rating & Page 39 & - \\
\hline & - Auxiliary Contact Rating & Page 41 & - \\
\hline & - Operation Coil & Page 43 & Same as MSO/S- \(\square\) types. \\
\hline & - Properties & Page 45 & \begin{tabular}{l}
Same as MSO/S- \(\square\) types. \\
Refer to pages 136, 145 for information about thermal overload relays.
\end{tabular} \\
\hline & - Performance & Page 46 & Same As Above \\
\hline & - How to Order & Page 131 & - \\
\hline & - Combining with Optional Units & Page 194 & Auxiliary contact units, interface units, front clip-on timer units and surge absorber units can be mounted. \\
\hline
\end{tabular}

\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

Outline Drawings/Contact Arrangements (AC Operated Magnetic Starters/Magnetic Contactors)
T10BC

\begin{tabular}{|c|c|}
\hline Auxilany Contact & Contact Arrangement \\
\hline \[
\left\lvert\, \begin{gathered}
1 \mathrm{a} \times 2 \\
+ \\
2 \mathrm{~b}
\end{gathered}\right.
\] &  \\
\hline & Model Name \\
\hline & S-2xT10BC \\
\hline
\end{tabular}

\section*{T12/T20BC}



\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

T21/T25BC



Non-Reversing


T32BC


\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

T35/T50BC



Reversing
S-2 \(\times\) T35BC S-2 \(\times\) T50BC

*1 Dimension: Including Head-On Auxiliary Contact Unit (UT-AX2(BC), UT-AX4(BC)) *2,*3 Dimension: Including Side-On Auxiliary Contact Unit (UT-AX11(BC))

It should be noted that it cannot be used with the head-on and side-on
auxiliary contact units mounted at the same time.


\subsection*{4.10 S-T \(\square S Q, ~ S D-T \square S Q\) Magnetic Contactors with Spring Clamp Terminals}

\section*{Just insert solid wires or ferrules into terminals. No terminal screws are required, which makes wiring quicker and easier.}
- Shorter Wiring Time

Wiring time becomes shorter than the time required for tightening screws. No worry about loss of screws.
Solid wires, stranded wires, and ferrules can be connected to the terminals.
- Easier Maintenance

No worry about loose screws. Conventionally, terminal screws come loose due to vibrations, impacts, or long-time use, and must be tightened when products come in or during inspection.

\section*{- Manufacturing Range List}
\begin{tabular}{|c|c|c|c}
\multirow{3}{*}{ Model } & \multicolumn{2}{|c|}{ Non-Reversing } & \multirow{3}{*}{ Terminal } \\
\cline { 2 - 3 } & \multicolumn{2}{|c|}{ Magnetic Contactors } & \\
\hline \multirow{3}{*}{ Frame } & Model Name & Auxiliary Contact & \\
\hline \multirow{2}{*}{ T12 } & S-T12SQ & \(1 \mathrm{a} 1 \mathrm{~b}, 2 \mathrm{a}, 2 \mathrm{~b}\) & \\
\cline { 2 - 3 } & SD-T12SQ & \(1 \mathrm{a} 1 \mathrm{~b}, 2 \mathrm{a}\) & \multirow{2}{*}{ Spring Clamp Terminals } \\
\hline \multirow{2}{*}{ T20 } & S-T20SQ & \(1 \mathrm{a} 1 \mathrm{~b}, 2 \mathrm{a}, 2 \mathrm{~b}\) & \\
\cline { 2 - 3 } & SD-T20SQ & \(1 \mathrm{a} 1 \mathrm{~b}, 2 \mathrm{a}\) & \\
\hline
\end{tabular}


Note 1. Terminal numbers are compliant with EN standards (EN50005 and EN50012).
\begin{tabular}{|c|c|c|c|}
\hline \multirow{9}{*}{} & Item & Reference Page & Remarks \\
\hline & - Main Contact Rating & Page 39 & - \\
\hline & - Auxiliary Contact Rating & Page 41 & - \\
\hline & - Operation Coil & Page 43 & \\
\hline & - Properties & Page 45 & - \\
\hline & - Performance & Page 46 & - \\
\hline & - Applicable wires & Page 68 & - \\
\hline & - How to Order & Page 131 & - \\
\hline & - Combining with Optional Units & Page 194 & Devices such as coil surge absorbers and manual operation prevention covers can be installed. \\
\hline
\end{tabular}

\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

Outline Drawings/Contact Arrangements


\subsection*{4.11 S(D)-T32, S-N \(\square 8\) Main Circuit 3-Pole Magnetic Contactors}

\section*{Dramatically reduces panel installation area required}
- A space-saving type without auxiliary contacts equipped and just 3-pole main contacts.
- If auxiliary contacts are required, auxiliary contact units can be installed.
(Reversing types have \(2 \mathrm{a} 2 \mathrm{~b} \times 2\) installed)


S-T32


S-N48

Ratings/Specifications (Standard Applicability)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Magnetic Contactors}} & \multicolumn{4}{|l|}{\multirow[t]{2}{*}{\begin{tabular}{|c} 
Rated Capacity [kW] \\
\hline \(\begin{array}{c}\text { Three-Phase Squirel-cage Motor } \\
\text { (Category AC-3) }\end{array}\) \\
\hline
\end{tabular}}} & \multicolumn{6}{|r|}{Rated Operating Current [A]} & \multirow[b]{3}{*}{\begin{tabular}{l}
Coverational
Frees Air
Thema Curen \\
Ith \\
[A]
\end{tabular}} & \multirow[t]{3}{*}{\begin{tabular}{l}
Additional Auxiliary Contact Unit Model Name x Pieces \\
(Note 2)
\end{tabular}} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{\[
\begin{gathered}
\text { Terminal Screw Size } \\
\left(\begin{array}{c}
\text { Standard Tightening Torque } \\
N \cdot m \\
\text { Parenteses Stow Standard Vaue }
\end{array}\right)
\end{gathered}
\]}} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Recommended Crimp Lug Size Compatible with Teminal}} \\
\hline & & & & & & \multicolumn{4}{|l|}{Three-Phase Squirrel-cage Motor (Category AC-3)} & \multicolumn{2}{|l|}{\[
\begin{gathered}
\text { Resistive Load } \\
\text { (Category AC-1) }
\end{gathered}
\]} & & & & & & \\
\hline Non-Reversing & Reversing & \[
\begin{array}{|c|}
\hline 220 \\
\text { to } \\
240 \\
V \\
\hline
\end{array}
\] & \[
\begin{array}{|c|}
\hline 380 \\
\text { to } \\
440 \\
\mathrm{~V} \\
\hline
\end{array}
\] & \[
\begin{gathered}
500 \\
\mathrm{~V}
\end{gathered}
\] & \[
\begin{gathered}
690 \\
\mathrm{~V}
\end{gathered}
\] & \[
\begin{array}{|c|}
\hline 220 \\
\text { to } \\
240 \\
V \\
\hline
\end{array}
\] & \[
\begin{array}{|c|}
\hline 380 \\
\text { to } \\
440 \\
\mathrm{~V} \\
\hline
\end{array}
\] & \[
\begin{gathered}
500 \\
\mathrm{~V}
\end{gathered}
\] & \[
\begin{gathered}
690 \\
\mathrm{~V}
\end{gathered}
\] & \[
\begin{gathered}
200 \\
\text { to } \\
220 \\
\mathrm{~V} \\
\hline
\end{gathered}
\] & \[
\begin{array}{|c|}
\hline 380 \\
\text { to } \\
440 \\
\mathrm{~V} \\
\hline
\end{array}
\] & & & Main Circuit & Control Circuit & Main Circuit & Control Circuit \\
\hline \[
\begin{aligned}
& \text { S-T32(BC) } \\
& \text { SD-T32(BC) }
\end{aligned}
\] & \[
\left|\begin{array}{l}
\mathrm{S}-2 \times \mathrm{T} 32(\mathrm{BC}) \\
\mathrm{SD}-2 \times \mathrm{T} 32(B C)
\end{array}\right|
\] & 7.5 & 15 & 15 & 11 & 32 & 32 & 24 & 12 & 32 & 32 & 32 & \[
\begin{aligned}
& \text { UT-AX2, } 4 \times 1 \\
& \text { UT-AX11 x }
\end{aligned}
\] & \[
\begin{array}{|c|}
\hline \text { M4 } \\
1.18-1.86 \\
(1.47) \\
\hline
\end{array}
\] & \[
\begin{array}{c|}
\hline \mathrm{M} 3.5 \\
0.94-1.51 \\
(1.17) \\
\hline
\end{array}
\] & \[
\begin{aligned}
& 1.25-4 \\
& \text { to } 5.5-4
\end{aligned}
\] & \[
\left\lvert\, \begin{gathered}
1.25-3.5 \\
\text { to } 2-3.5
\end{gathered}\right.
\] \\
\hline S-N38(CX) & S-2 2 N38(CX) & 7.5 & 15 & 15 & & 35 & 32 & 24 & & 60 & 60 & 60 & UN-AX2, \(4 \times 1\) & M5 & M3.5 & 1.25-5 & 1.25-3.5 \\
\hline S-N48(CX) & S-2 \(\times\) N48(CX) & 11 & 15 & 15 & & 50 & 35 & 24 & & 80 & 80 & 80 & (Front Clip-on) & & \(\xrightarrow{0.94-1.151}\) & to 14-5 & to 2-3.5 \\
\hline
\end{tabular}

Note 1. The M4 main circuit terminal screw size for T32 types makes it unsuitable for applications exceeding 20 A in accordance with the Electrical Appliance and Material Safety Law.
Note 2. Reversing types already have 2 UT/UN-AX4 units installed so no more can be mounted. Furthermore, all side clip-on units (UT/UN-AX11) are not applicable.
Note 3. Types including thermal overload relays (MSO) are not manufactured.
Note 4. A "BC" in the model name indicates a wiring streamlining terminal, "CX" indicates a CAN terminal.
Note 5. Please note that SD-T32 type operation coil terminals have polarity. A1 (+), A2 (-)

\section*{Properties/Performance}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Model Name} & \multicolumn{2}{|r|}{Input [VA]} & \multirow[b]{2}{*}{Power Consumption [W]} & \multirow[b]{2}{*}{} & \multicolumn{2}{|l|}{Operating Voltage [V]} & \multicolumn{2}{|l|}{Operating Time [ms]} & \multirow[t]{2}{*}{Making Current Capacity [A] \(\binom{\) Peak }{0.5 ms}} & \multirow[b]{2}{*}{\begin{tabular}{l}
Switching \\
Frequency
\end{tabular}} & \multicolumn{2}{|l|}{Switching Durability [ x 10000 ]} \\
\hline & Momentary & Regular & & & Close & Open & Coil \(\mathrm{ON} \rightarrow\) Main Contact ON & \begin{tabular}{l}
Coil OFF \(\rightarrow\) \\
Man Contact OFF
\end{tabular} & & & Mechanical & Electrical (Category AC-3) \\
\hline SD-T32 & - & - & 3.3 (2.2) & 0.033 & 60 to 75 & 10 to 30 & 70 (95) & 20 & 400 & & 000 & \\
\hline S-T32 & 55 & 4.5 & 1.8 & 20 & 125 to 155 & 80 to 115 & 15 to 22 & 5 to 15 & 400 & & & \\
\hline S-N38 & 110 & 13 & 4.3 & 80 & 120 to 145 & 90 to 115 & 10 to 20 & 5 to 14 & 500 & & & \\
\hline S-N48 & 110 & 13 & 4.3 & 80 & 120 to 145 & 90 to 115 & 10 to 20 & 5 to 14 & 670 & 1200 Times/Hour & 500 & \\
\hline
\end{tabular}

Note 1. The above table indicates rough property indices for DC100V coils for DC operated types and AC200V coils for AC operated types. The values in the parentheses for SD-T32 indicate rough property indices for DC12V or DC24V coils.
Note 2. The operating voltage is that at a \(20^{\circ} \mathrm{C}\) cold state. (AC operated type values are for 60 Hz )
Note 3. The coil current is the average regular value with DC100V (DC operated type) or AC220 V at 60 Hz (AC operated type) applied.
Note 4. The operating time is the value with DC100V (DC operated type) or AC220 V at 60 Hz (AC operated type) applied.
Note 5. The coil input and power consumption are the average values.
Note 6. The electrical durability at the making current capacity lasts 100,000 operations.
\begin{tabular}{|l|l|c|c}
\hline & \multicolumn{1}{|c|}{ Item } & Reference Page & Remarks \\
\cline { 2 - 4 } \begin{tabular}{c} 
Related \\
Reference Page
\end{tabular} & \begin{tabular}{l} 
•Main Contact Rating \\
\hline - Operation Coil \\
\hline How to Order \\
\hline - Combining with Optional Units
\end{tabular} & Page 194 & - \\
\hline
\end{tabular}

\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

Outline Drawings/Contact Arrangements (The diagrams show models without "BC" or "CX".)


S-2×T32(BC)


SD-T32(BC)


SD-2×T32(BC)



\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

\subsection*{4.12 How to Order}

\section*{MS-T Series}
1. Standard (AC Operated) Magnetic Starters

\section*{Precautions}

Follow the steps below when ordering. Enter a space in
If there are multiple 2 letter symbols (SA, BC, KP etc.) appended to the model name frame size (T10 etc.) then specify them in alphabetical order. (E.g.: MSO-T10BCKPSA) (If not in alphabetical order, the model name displayed will change automatically.)

2. Standard (AC Operated) Magnetic Contactors

\section*{S-T Type, S-2xT Type}


\section*{3. DC Operated Magnetic Starters/Contactors}

MSOD-T Type


\section*{4. Mechanically Latched Magnetic Starters/Contactors}

\section*{MSOL-T Type}


\section*{5. Delay Open Magnetic Starters/Contactors}

6. Magnetic Starters with Delay Trip Thermal Overload Relays \(\square\) MSO-T \(\square\) SR Type

7. Magnetic Starters with Quick Trip Thermal Overload Relays

\section*{\(\square\) MSO-T \(\square\) FS/FSKP Type}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|}
\hline Model Name & \multirow{3}{*}{4} & Motor Capacity or Heater Designation (Knob Setpoint) & \multirow{3}{*}{4} & Main Circuit Voltage & & Operation Coil Designation or Control Circuit Voltage/Frequency & \multirow[t]{3}{*}{-} & & (Note) Auxiliary Contact \\
\hline MSO-T12FSKP & & 2.2kW & & 200 V & & AC200V & & & \\
\hline Specify from page 116. & & Select from page 48 or 139. & & Do not apply AC voltage to the main circuit. & & Select the coil designation from page 43 or specify the control circuit voltage and frequency used. & & & Specify if using a special contact arrangement. Refer to page 41. \\
\hline
\end{tabular}

\section*{8. Magnetic Starters with Push-Buttons}

\section*{\(\square\) MS-T \(\square\) KPPM Type}

9. Magnetic Starters/Magnetic Contactors with Wiring Streamlining Terminals

\section*{\(\square\) MSO-T \(\square\) BC Type}

10. Magnetic Contactors with Spring Clamp Terminals
\(\square\) S-T \(\square\) SQ Type

11. Main Circuit 3-Pole Magnetic Contactors

S-T Type, S-2xT Type


\section*{MS-T/N Series Magnetic Starters/Magnetic Contactors}

\section*{MS-N Series}
1. Standard (AC Operated) Magnetic Starters
-MS-(2x)N Type (Enclosed Type)

2. Standard (AC Operated) Magnetic Contactors

S-N Type, S-2xN Type


\section*{3. DC Operated Magnetic Starters/Contactors}

4. Mechanically Latched Magnetic Starters/Contactors

MSOL-N Type


\section*{5. Capacitive Tripping Device}
-CTU-ロपType
\begin{tabular}{|l|}
\hline \multicolumn{1}{|c|}{ Model Name } \\
\hline CTU-A \\
\hline \begin{tabular}{l} 
Refer to page 103. \\
Combinable Mechanically \\
Latched Magnetic Starters \\
- Model names differ depending \\
on contactor frame. \\
\hline
\end{tabular} \\
\hline
\end{tabular}
\begin{tabular}{|l|}
\hline \multicolumn{1}{|c|}{ Operating Voltage Symbol } \\
\hline 2 \\
\hline Operating Voltage is AC100V or \\
AC200V \\
1: AC100V \\
2: AC200V \\
\hline
\end{tabular}

\section*{6. Delay Open Magnetic Starters/Contactors}
-MSO-N \(\square\) DLKP, S-N D DL Type


\section*{7. Magnetic Starters with Delay Trip Thermal Overload Relays} \(\square\) MSO-N \(\square\) KPSR Type

8. Main Circuit 3-Pole Magnetic Contactors

S-N Type, S-2xN Type
\begin{tabular}{|c|c|}
\hline Model Name & Operation Coil Designation or Control Circuit Voltage and Frequency \\
\hline S-N48 & AC200V \\
\hline Specify from page 127 & Select the coil designation from page 43 or specify the control circuit voltage and frequency used. \\
\hline
\end{tabular}

MEMO
TH-T/N Type Thermal Overload Relays
5.1 Model List ..... 136
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5.3 Operating Properties ..... 138
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5.12 How to Order ..... 158

\title{
TH-T/N Type Thermal Overload Relays
}

\subsection*{5.1 Model List}


Note 1. All model names come with ambient temperature compensation device.
Note 2. © indicates standard type (standard equipment), \(\bigcirc\) indicates semi-standard type, \(\triangle\) indicates special products and - indicates products outside production range.
\begin{tabular}{|c|c|c|c|c|c|}
\hline & N120 & N120TA & N220 & N400 & N600 \\
\hline &  &  &  &  &  \\
\hline & \multirow[t]{2}{*}{TH-N120} & TH-N120TA & TH-N220RH & TH-N400RH & - \\
\hline & & TH-N120TAHZ & TH-N220HZ & TH-N400HZ & TH-N600(Note 3) \\
\hline & \multirow[b]{2}{*}{TH-N120KP} & TH-N120TAKP & TH-N220RHKP & TH-N400RHKP & - \\
\hline & & TH-N120TAHZKP & TH-N220HZKP & TH-N400HZKP & TH-N600KP(Note 3) \\
\hline & \multirow{2}{*}{\(103 \times 67 \times 105\)} & \(112 \times 87 \times 105\) & \(144 \times 114 \times 179\) & \(144 \times 160 \times 193\) & - \\
\hline & & \(112 \times 103 \times 105\) & \(144 \times 104 \times 166.5\) & \(144 \times 173 \times 166.5\) & \(63 \times 42 \times 83.5\) \\
\hline & \multicolumn{5}{|c|}{JIS, JEM, IEC, VDE, BS, UL, GB} \\
\hline & \multicolumn{5}{|c|}{-10 to +40 (Standard is \(20^{\circ} \mathrm{C}\), Inner Panel Maximum Temperature is \(55^{\circ} \mathrm{C}\) )} \\
\hline & \multicolumn{2}{|l|}{0 (DC) to 400} & \multicolumn{3}{|c|}{50 to 60} \\
\hline & \multicolumn{5}{|c|}{690} \\
\hline & \multicolumn{5}{|c|}{6} \\
\hline & \multicolumn{5}{|c|}{3} \\
\hline & \multirow[t]{5}{*}{\[
\begin{aligned}
& 42(34 \text { to } 50) \\
& 54(43 \text { to } 65) \\
& 67(54 \text { to } 80) \\
& 82(65 \text { to } 100)
\end{aligned}
\]} & \multirow[t]{5}{*}{\[
\begin{aligned}
& \hline 105(85 \text { to } 125) \\
& \hdashline 125(100 \text { to } 150)
\end{aligned}
\]} & \multirow[t]{5}{*}{\begin{tabular}{|l}
\(82(65\) to 100\()\) \\
\(105(85\) to 125\()\) \\
\(125(100\) to 150\()\) \\
\(150(120\) to 180\()\) \\
\(180(140\) to 200\()\) \\
\(210(170\) to 250\()\)
\end{tabular}} & \multirow[t]{3}{*}{\[
\begin{aligned}
& 105(85 \text { to } 125) \\
& 125(100 \text { to } 150) \\
& 150(120 \text { to } 180) \\
& 180(140 \text { to } 220) \\
& 250(200 \text { to } 300)
\end{aligned}
\]} & 250 (200 to 300) \\
\hline & & & & & \[
\begin{aligned}
& \text { CUurent Transfomen Ratio: } \\
& 4005 A \text { A) } \\
& 330(260 \text { to } 400)
\end{aligned}
\] \\
\hline & & & & & (Curent Transformer Ratio: 50015 A) \\
\hline & & & & 330 (260 to 400) & \(5005 \mathrm{~A})\)
\(500(400\) to 600\()\)
(Curenent Transiomer Ratio:
\(7505 \mathrm{~A})\)
\(660(520\) to 800\()\)
\((\) Curenent Transomme Ratio:
\(10005 \mathrm{~A})\) \\
\hline & & & & *The thermal overload relay with the heater designation of 180 A or less is the same as the N220 frame. & (Curent Transformer Ratio: 10005 A) \\
\hline & 3.0/7.1 & 3.8/8.6 & 1.0/2.3 (Note 4) & 1.0/2.3 (Note 4) & 1.0/2.3 (Note 4) \\
\hline & M8 & M8 & M10 & M12 & - \\
\hline & - & - & - & - & - \\
\hline & 8-8 to 38-8 & 38-8 to 100-8 & 22-10 to 150-10 & 22-12 to 200-12 & - \\
\hline & 1a1b & 1a1b & 1a1b & 1a1b & 1a1b \\
\hline & 5 & 5 & 5 & 5 & 5 \\
\hline & 2(0.5)/3(0.5) & 2(0.5)/3(0.5) & 2(0.5)/3(0.5) & 2(0.5)/3(0.5) & 2(0.5)/3(0.5) \\
\hline & 2(0.5)/3(0.5) & 2(0.5)/3(0.5) & 2(0.5)/3(0.5) & 2(0.5)/3(0.5) & 2(0.5)/3(0.5) \\
\hline & 1(0.5)/2(0.5) & 1(0.5)/2(0.5) & 1(0.5)/2(0.5) & 1(0.5)/2(0.5) & 1(0.5)/2(0.5) \\
\hline & 0.5(0.5)/1(0.5) & 0.5(0.5)/1(0.5) & 0.5(0.5)/1(0.5) & 0.5(0.5)/1(0.5) & 0.5(0.5)/1(0.5) \\
\hline & 1(0.3) & 1(0.3) & 1(0.3) & 1(0.3) & 1(0.3) \\
\hline & 0.2(0.2) & 0.2(0.2) & 0.2(0.2) & 0.2(0.2) & 0.2(0.2) \\
\hline & 0.1(0.1) & 0.1(0.1) & 0.1(0.1) & 0.1(0.1) & 0.1(0.1) \\
\hline & 20V 5mA & 20V 5mA & 20V 5mA & 20 V 5 mA & 20V 5mA \\
\hline & M4 & M4 & M4 & M4 & M4 \\
\hline & \(\varphi 1.6,1.25\) to 2 & \(\varphi 1.6,1.25\) to 2 & \(\varphi 1.6,1.25\) to 2 & \(\varphi 1.6,1.25\) to 2 & \(\varphi 1.6,1.25\) to 2 \\
\hline & 1.25-4 to 2-4, 5.5-S4 & 1.25-4 to 2-4, 5.5-S4 & 1.25-4 to 2-4, 5.5-S4 & 1.25-4 to 2-4, 5.5-S4 & 1.25-4 to 2-4, 5.5-S4 \\
\hline & \multicolumn{2}{|l|}{156} & \multicolumn{2}{|r|}{156} & 156 \\
\hline & \multicolumn{5}{|c|}{10 to \(55 \mathrm{~Hz} 19.6 \mathrm{~m} / \mathrm{s}^{2}\)} \\
\hline & (0) & (0) & ( \()\) & (0) & (0) \\
\hline & Manual/Automatic Switchable & Manual/Automatic Switchable & Manual/Automatic Switchable & Manual/Automatic Swithable & Manual/Automatic Swithable \\
\hline & ( 0 & ( \()\) & (0) & ( \()\) & ( \()\) \\
\hline & () & ( & ( & () & ( \\
\hline & \multirow[t]{2}{*}{N125, N150} & N125, N150 & N180, N220 & N300, N400 & \multirow[b]{2}{*}{N600, N800} \\
\hline & & N150 & N220 & N400 & \\
\hline & O (TH-N120SR) & O (TH-N120TASR) & O (TH-N220■SR) & O (TH-N400■SR) & O (TH-N600SR) \\
\hline & O (TH-N120KPSR) & O (TH-N120TAKPSR) & O (TH-N220口KPSR) & O (TH-N400口KPSR) & O (TH-N600KPSR) \\
\hline & - & - & - & - & - \\
\hline & - & - & - & - & - \\
\hline & - & - & - & - & - \\
\hline & O (UN-RR \(\square 6\) ) & O (UN-RR \(\square 6\) ) & O (UN-RR \(\square 6\) ) & O (UN-RR■6) & O (UN-RR■6) \\
\hline & ( (UN-TL60) & O) (UN-TL60) & () (UN-TL60) & O) (UN-TL60) & O (UN-TL60) \\
\hline & - & - & - & - & - \\
\hline & O (UN-CV603) & () (UN-CV603) & O (UN-CV603) & (0) (UN-CV603) & O (UN-CV603) \\
\hline
\end{tabular}

Note 3. Use TH-N600(KP) in combination with current transformer for measuring instruments (rated secondary load of 15 VA or more). The recommended model names are CW-15LM or CW-15L for 250, 330 and 500 A , and CW-40LM for 660 A . The ratio of current transformation is as shown in the heater designation field in the table.
Note 4. The power consumption indicates the amount consumed by the heater element only. (The current transformer consumption amounts of the N220 to N600 frames are not included.)

\subsection*{5.2 Contact Rating}
- Main circuit specifications... as shown on page136 Specifications of the control circuit (contact) The contact rating is as shown in the following table
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{Frame} & \multicolumn{2}{|c|}{T18} & \multicolumn{2}{|c|}{T25,T50} & \multicolumn{2}{|l|}{T65,T100,N120 to N600} \\
\hline Conta & & Break Contact & Make Contact & Break Contact & Make Contact & Break Contact & Make Contact \\
\hline Conventional Free Air The & ermal Current Ith \([A]\) & 2 & 2 & 5 & 5 & 5 & 5 \\
\hline Class AC-15 & AC24V & 2 (0.5) & 2 (0.5) & 3 (0.5) & 2 (0.5) & 3 (0.5) & 2 (0.5) \\
\hline Rated Operating & AC120V & 2 (0.5) & 2 (0.5) & 3 (0.5) & 2 (0.5) & 3 (0.5) & 2 (0.5) \\
\hline Current & AC240V & 1 (0.5) & 1 (0.5) & 2 (0.5) & 1 (0.5) & 2 (0.5) & 1 (0.5) \\
\hline [ A ] & AC550V & 0.3 (0.3) & 0.3 (0.3) & 0.3 (0.3) & 0.3 (0.3) & 1 (0.5) & 0.5 (0.5) \\
\hline Class DC-13 Rated & DC24V & 0.5 (0.3) & 0.5 (0.3) & 1 (0.3) & 1 (0.3) & 1 (0.3) & 1 (0.3) \\
\hline Operating Current & DC110V & 0.2 (0.2) & 0.2 (0.2) & 0.2 (0.2) & 0.2 (0.2) & 0.2 (0.2) & 0.2 (0.2) \\
\hline [A] & DC220V & 0.1 (0.1) & 0.1 (0.1) & 0.1 (0.1) & 0.1 (0.1) & 0.1 (0.1) & 0.1 (0.1) \\
\hline
\end{tabular}

Note 1. The withstand voltage is AC2500 V for 1 minute.
Note 2. The contact arrangement is 1a1b.
Note 4. The minimum available voltage and current level in a clean atmosphere is 20 V 5 mA .
Note 3. If the coil current of the DC operated magnetic contactor (SD) exceeds
Note 5 . The value in parentheses is the rating during auto reset.
0.2 A at DC110 V or 0.1 A at DC220 V (SD-N125 or higher), conduct
through the SR or SRD contactor relay. (Refer to the figure on the right)

\subsection*{5.3 Operating Properties (Standard Value)}

The operating properties of the thermal overload relays are specified as shown in the table below according to the standards.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Standard} & \multirow{3}{*}{Conditions} & \multicolumn{4}{|c|}{Operation in Balanced Circuit} & \multicolumn{2}{|l|}{Operation in Unbalanced Circuit} & \multirow[b]{3}{*}{Ambient Temperature} \\
\hline & & \multicolumn{2}{|l|}{Limit Operations} & Operation During Overload & Operation During Constraint & Non-Operation & Operation & \\
\hline & & A (Cold Start) & B (Continued From A) & C (Hot Start) & D (Cold Start) & A (Cold Start) & B (Continued From A) & \\
\hline \multirow{7}{*}{JIS C8201-4-1} & \multirow[b]{2}{*}{Muliple of Setting Curent} & \multirow[t]{2}{*}{1.05} & \multirow[t]{2}{*}{1.2} & \multirow[t]{2}{*}{1.5} & \multirow[t]{2}{*}{7.2} & 2-Pole 1.0 & 2-Pole1.15 & \multirow{7}{*}{\(20^{\circ} \mathrm{C}\)} \\
\hline & & & & & & 1-Pole 0.9 & 1-Pole 0 & \\
\hline & \multirow{5}{*}{\begin{tabular}{l}
Operating \\
Time
\end{tabular}} & \multirow{5}{*}{NonOperation (2 Hours)} & \multirow{5}{*}{Within 2 Hours} & (5) Less Than 2 Minutes & (5) Tp \(\leq 5\) Seconds & \multirow{5}{*}{NonOperation (2 Hours)} & \multirow{5}{*}{Within 2 Hours} & \\
\hline & & & & (10A) Less Than 2 Minutes & (10A) \(2<T p \leq 10\) Seconds & & & \\
\hline & & & & (10) Less Than 4 Minutes & (10) \(4<T p \leq 10\) Seconds & & & \\
\hline & & & & (20) Less Than 8 Minutes & (20) \(6<T p \leq 20\) Seconds & & & \\
\hline & & & & (30) Less Than 12 Minutes & (30) \(9<T p \leq 30\) Seconds & & & \\
\hline \multirow{6}{*}{IEC 60947-4-1} & \multirow[t]{2}{*}{Mutiple of Setting Curent} & \multirow[t]{2}{*}{1.05} & \multirow[t]{2}{*}{1.2} & \multirow[t]{2}{*}{1.5} & \multirow[t]{2}{*}{7.2} & 2-Pole 1.0 & 2-Pole1.15 & \multirow{6}{*}{\(20^{\circ} \mathrm{C}\)} \\
\hline & & & & & & 1-Pole 0.9 & 1-Pole 0 & \\
\hline & \multirow{4}{*}{\begin{tabular}{l}
Operating \\
Time
\end{tabular}} & \multirow[t]{4}{*}{NonOperation (2 Hours)} & \multirow{4}{*}{Within 2 Hours} & (100) Less Than 2 Minutes & (10A) \(2<T p \leq 10\) Seconds & \multirow[t]{4}{*}{NonOperation (2 Hours)} & \multirow{4}{*}{Within 2 Hours} & \\
\hline & & & & (10) Less Than 4 Minutes & (10) \(4<\mathrm{Tp} \leq 10\) Seconds & & & \\
\hline & & & & (20) Less Than 8 Minutes & (20) \(6<T p \leq 20\) Seconds & & & \\
\hline & & & & (30) Less Than 12 Minutes & (30) \(9<T p \leq 30\) Seconds & & & \\
\hline \multirow{5}{*}{JEM 1356} & \multirow[b]{2}{*}{Multiple of Setting Current} & \multirow[t]{2}{*}{1.05} & \multirow[t]{2}{*}{1.2} & \multirow[t]{2}{*}{1.5} & \multirow[t]{2}{*}{7.2} & 2-Pole 1.0 & 2-Pole1.15 & \multirow{5}{*}{\(20^{\circ} \mathrm{C}\)} \\
\hline & & & & & & 1-Pole 0.9 & 1-Pole 0 & \\
\hline & \multirow[t]{3}{*}{Operating Time} & \multirow[t]{3}{*}{Non-Operation (2 Hours)} & \multirow[t]{3}{*}{Within 2 Hours} & (Quick) Within 4 Minutes & (Quick) \(\quad \mathrm{Tp} \leq 5\) Seconds & \multirow[t]{3}{*}{Non-Operation (2 Hours)} & \multirow[t]{3}{*}{Within 2 Hours} & \\
\hline & & & & (Standard) Within 8 Minutes & (Standara) \(2 \leq T p \leq 15\) Seconds & & & \\
\hline & & & & (Delay) Within 12 Minutes & (Delay) \(9 \leq T p \leq 30\) Seconds & & & \\
\hline
\end{tabular}

Note 1. It shows the case of the thermal overload relay with ambient temperature compensation and open phase detection.
Note 2. Tp shows the operating time while restrained.
Note 3. The operating time field () of the operation during overload and constraint represents the trip class in JIS and IEC, and type in JEM.

\subsection*{5.4 Selection and Application}

\section*{Selecting Thermal Overload Relays}

The principles in the selection of the thermal overload relay are that its operating characteristic curve falls below the thermal properties (overcurrent - service lifetime properties) of the motor, and exceeds the startup properties (startup current - time properties) curve of the motor. Judge the suitability of the thermal properties and starting properties of the motor by superposing them on the operating characteristic curve (see page 153) of the thermal overload relay. (Refer to Figure 4 on page 143)
\begin{tabular}{|c|c|c|c|}
\hline \multirow[t]{2}{*}{Motor, Running, Protection Conditions, etc.} & \multirow[b]{2}{*}{Selection} & \multicolumn{2}{|l|}{Applicable Thermal Overload Relays} \\
\hline & & With 2-Element & With 3-Element (2E) \\
\hline Standard Start, Stop (Low Frequency) & Standard Thermal Overload Relays & TH-■Type & TH-■KP Type \\
\hline Fan, blower, etc. with long start-up time & Thermal Overload Relays With Saturable Reactor & TH- \(\square\) SR Type & TH-पKPSR Type \\
\hline Submersible motor and compressor motor with short allowable constraint time & Quick-acting Characteristics Thermal Overload Relays & TH-■FS Type & TH-TDFSKP Type \\
\hline Inching, High Frequency Intermittent Running & Although unnecessary trips may be avoided by the thermal overload relay with a saturable reactor to provide the adequate protection, detailed consideration is required & Consideration Required & Consideration Required \\
\hline For Open-Phase Protection & Thermal Overload Relays With 3-Element (2E) & - & TH-■KP Type \\
\hline Reverse-Phase and OpenPhase Protection Dual Use & Electronic Motor Protection Relays (3E) & - & (ET- \(\square\) Type) \\
\hline
\end{tabular}

\section*{- Thermal Overload Relay Heater Designation Selection Table}

Guidelines for the selection of general thermal overload relays are shown in the following table.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{} & \multicolumn{8}{|c|}{Three-Phase Motors} & \multicolumn{4}{|c|}{Single-Phase Motors} & \multirow[t]{2}{*}{} \\
\hline & 200 to 220 V & 230 to 240 V & 346 to 350V & 380V & 400 to 440V & 460 to 500 V & 550 to 600 V & 660V & 100 to 110V & 115 to 120V & 200 to 220V & 230 to 240 V & \\
\hline 0.03 & 0.24A & 0.24A & - & - & - & - & - & - & & & & & 0.03 \\
\hline 0.035 & 0.35A & 0.24A & 0.24A & 0.24A & - & - & - & - & 1.7A & & 0.9A & & 0.035 \\
\hline 0.05 & 0.35A & 0.35A & 0.24A & 0.24A & 0.24A & - & - & - & & & & & 0.05 \\
\hline 0.06 to 0.065 & 0.5A & 0.35A & 0.35A & 0.24A & 0.24A & 0.24A & - & - & 2.5A & & 1.3A & & 0.06 to 0.065 \\
\hline 0.07 & 0.5A & 0.5A & 0.35A & 0.35A & 0.35A & 0.24A & - & - & & & & & 0.07 \\
\hline 0.09 & 0.7A & 0.7A & 0.35A & 0.35A & 0.35A & 0.24A & 0.24A & - & & & & & 0.09 \\
\hline 0.1 & 0.7A & 0.7A & 0.35A & 0.35A & 0.35A & 0.35A & 0.24A & - & 3.6A & & 1.7A & & 0.1 \\
\hline 0.12 & 0.9A & 0.7A & 0.5A & 0.5A & 0.5A & 0.35A & 0.24A & - & & 3.6A & & 2.1 A & 0.12 \\
\hline 0.15 & 0.9A & 0.9A & 0.7A & 0.7A & 0.5A & 0.5A & 0.35A & - & 5A & & 2.5A & & 0.15 \\
\hline 0.18 & 1.3A & 0.9A & 0.7A & 0.7A & 0.7A & 0.5A & 0.5A & - & 5A & 5A & & 2.5A & 0.18 \\
\hline 0.2 & 1.3 A & 0.9A & 0.7A & 0.7A & 0.7A & 0.7A & 0.5A & - & 5A & & 2.5A & & 0.2 \\
\hline 0.25 & 1.7A & 1.3A & 0.9A & 0.9A & 0.7A & 0.7A & 0.5A & - & 6.6A & 6.6A & 3.6A & 3.6A & 0.25 \\
\hline 0.3 & 1.7A & 1.3 A & 0.9A & 0.9A & 0.9A & 0.9A & 0.7A & - & 6.6A & & 3.6A & & 0.3 \\
\hline 0.37 to 0.4 & 2.1A & 2.1A & 1.3A & 1.3A & 1.3A & 0.9A & 0.7A & - & 9A & 9A & 5A & 5A & 0.37 to 0.4 \\
\hline 0.55 & 2.5A & 2.5A & 1.7A & 1.7A & 1.3A & 1.3A & 0.9A & - & 11A & 11A & 5A & 6.6A & 0.55 \\
\hline 0.75 & 3.6A & 3.6A & 2.1 A & 2.1 A & 1.7A & 1.7A & 1.3 A & 1.3A & 15A & 15A & 6.6A & 9A & 0.75 \\
\hline 1.0 & 5A & 5A & 2.5A & 2.5A & 2.5A & 2.1A & 1.7A & 1.7A & & & & & 1.0 \\
\hline 1.1 & 5A & 5A & 3.6A & 2.5A & 2.5A & 2.1A & 1.7A & 1.7A & 22A & 22A & 9A & 9A & 1.1 \\
\hline 1.3 & 6.6A & 5A & 3.6A & 3.6A & 2.5A & 2.5A & 2.1 A & 2.1 A & & & & & 1.3 \\
\hline 1.5 & 6.6A & 6.6A & 3.6A & 3.6A & 3.6A & 2.5A & 2.5A & 2.1A & 29A & 22A & 15A & 11A & 1.5 \\
\hline 2.2 & 9A & 9A & 5A & 5A & 5A & 3.6A & 3.6A & 3.6A & & & & & 2.2 \\
\hline 3 & 11A & 11A & 6.6A & 6.6A & 6.6A & 5A & 5A & 3.6A & & 35A & & 15A & 3 \\
\hline 3.7 to 4 & 15A & 15A & 9A & 9A & 6.6A & 6.6A & 5A & 5A & & 54A & & 29A & 3.7 to 4 \\
\hline 5.5 & 22A & 22A & 15A & 11A & 11A & 9A & 9A & 6.6A & & 82A & & 42A & 5.5 \\
\hline 7.5 & 29A & 29A & 15A & 15A & 15A & 11A & 9A & 9A & & 105A & & 54A & 7.5 \\
\hline 9 & 35A & 29A & 22A & 22A & 15A & 15A & 11A & 11A & & & & & 9 \\
\hline 11 & 42A & 42A & 22A & 22A & 22A & 22A & 15A & 15A & & & & & 11 \\
\hline 15 & 54A & 54A & 35A & 29A & 29A & 22A & 22A & 15A & & & & & 15 \\
\hline 18.5 to 19 & 67A & 67A & 42A & 35A & 35A & 29A & 22A & 22A & & & & & 18.5 to 19 \\
\hline 22 & 82A & 82A & 54A & 42A & 42A & 35A & 29A & 22A & & & & & 22 \\
\hline 25 & 82A & 82A & 54A & 54A & 54A & 35A & 35A & 29A & & & & & 25 \\
\hline 30 & 105A & 105A & 67A & 54A & 54A & 42A & 42A & 35A & & & & & 30 \\
\hline 37 & 125A & 125A & 82A & 67A & 67A & 54A & 54A & 42A & & & & & 37 \\
\hline 45 & 150A & 150A & 105A & 82A & 82A & 67A & 54A & 54A & & & & & 45 \\
\hline 55 to 60 & 180A & 180A & 125A & 105A & 105A & 82A & 67A & 67A & & & & & 55 to 60 \\
\hline 75 & 250A & 250A & 150A & 125A & 125A & 105A & 105A & 82A & & & & & 75 \\
\hline 90 & 330A & 330A & 180A & 150A & 150A & 125A & 105A & 105A & & & & & 90 \\
\hline 110 & 330A & 330A & 250A & 180A & 180A & 150A & 125A & 105A & & & & & 110 \\
\hline 132 & 500A & 500A & 250A & 250A & 250A & 180A & 150A & 150A & & & & & 132 \\
\hline 150 to 160 & 500A & 500A & 330A & 250A & 250A & 250A & 180A & 180A & & & & & 150 to 160 \\
\hline 185 & 660A & 500A & 330A & 330A & 330A & 250A & 250A & 180A & & & & & 185 \\
\hline 200 & 660A & 660A & 500A & 330A & 330A & 330A & 250A & 180A & & & & & 200 \\
\hline 220 & 660A & 660A & 500A & 500A & 500A & 330A & 250A & 250A & & & & & 220 \\
\hline 250 & - & - & 500A & 500A & 500A & 330A & 330A & 250A & & & & & 250 \\
\hline 300 to 315 & - & - & 660A & 500A & 500A & 500A & 330A & 330A & & & & & 300 to 315 \\
\hline 370 to 400 & - & - & - & 660A & 660A & 500A & 500A & 500A & & & & & 370 to 400 \\
\hline
\end{tabular}

Note 1. The table above shows the selection of heater designation based on the full-load current value of the 4 -pole standard three-phase motor and single-phase motor manufactured by Mitsubishi Electric.
When ordering by motor capacity, determine the heater designation of the thermal overload relay with this table. Specify the voltage and capacity accurately.
Note 2. If the number of poles in the three-phase motor is different, or in the case of special motors, the full-load current value may be different.
In such a case, specify by the heater designation upon investigating the full-load current of the motor.

Note 3. For single-phase motors, the full-load current varies depending on the start-up and running methods. Therefore, treat the values in the above table as guidelines, and specify the appropriate heater designation upon checking the full-load current for actual use. For single-phase motors, connect as shown in the figure below.


\section*{TH-T/N Type Thermal Overload Relays}

\section*{Application of Various Thermal Overload Relays}
- TH (standard/with 2-element): General overload and constraint protection of the motor
- TH-KP (with 3-element [2E]):

Overload, constraint and open-phase protection of the motor
- TH-SR (with saturable reactor)

Motors with long startup time, applications with frequent inching and intermittent running.

\section*{Application to Standard Three-Phase Motors}

Select the frame and heater designation from the table below. Refer to page 139 for details.


Note 1. The connecting electric wire size indicates the selection of HIV wire based on indoor wiring regulations (Section 1340) when performing metal tube wiring at the ambient temperature of \(40^{\circ} \mathrm{C}\).

\section*{Startup Time of Motor and Application of TH Thermal Overload Relays}

An overview of the application classifications for the standard TH and TH-SR with saturable reactor by motor start-up time is shown in the table below.


Note 1. The above table is a measure of the central value of the heater designation when the motor startup current is 500 to \(600 \%\). Check the characteristic curve for details.

\section*{Application to Single-Phase Circuits}

When applying a thermal overload relay (TH-■KP, etc.) with 3-element (2E) to a single-phase circuit, it will not operate normally if only 2 elements are energized. As in Fig. (b) on page 139, make sure that all 3 elements can be energized.

\subsection*{5.5 Structure}

TH-T18


Fig. 1. Structure of the Thermal Overload Relay (with 2-Element)

\section*{Reset Method}

All models of TH-T/N Series thermal overload relays have a structure that allows manual/automatic reset switching. The factory default (standard) is manual reset.

\section*{Structure of the Thermal Overload Relay With Open-Phase Protection Function}

The push plate of the thermal overload relay with overload and open-phase protection (TH-■KP) has a differential amplification mechanism that transmits the action of the bimetal to the contact mechanism as shown in Figure 2. Its design is suitable for protection during open phase.
Non-Energized
(1)

\section*{TH-T/N Type Thermal Overload Relays}

\subsection*{5.6 Precautions for Use}

\section*{Model Name Identification by Mounting Method}

Note 1. T25, T65 and N120 can be independently mounted as standard.
Note 2. T18, T50, T100, N120TA, N220RH and N400RH are for magnetic starters. (No Independent Mounting) N120TAHZ, N220HZ and N400HZ are for independent mounting.
Note 3. For T18, independent mounting and IEC 35 mm rail mounting may be enabled by combining with UT-HZ18. For T25, IEC 35 mm rail mounting may be enabled by combining with UN-RM20.

\section*{Disassembly}

The Thermal Overload Relays are adjusted at the time of assembly. Do not disassemble it.
Do not use with the terminal removed, as the properties may change.

\section*{Ambient Temperature Compensation}

The TH-T/N type Thermal Overload Relays are adjusted with the Magnetic Starters in the standard box (the MS type) relative to the ambient temperature of \(20^{\circ} \mathrm{C}\) (The temperature on the control board of the MSO type Magnetic Starters is \(35^{\circ} \mathrm{C}\) ). The ambient temperature compensator is mounted on the TH-T/N type Thermal Overload Relays. Therefore, the ambient temperature less affects the operational characteristic change. The minimum operating current change according to the ambient temperature change relative to the ambient temperature of \(20^{\circ} \mathrm{C}\) (the temperature on the control board of \(35^{\circ} \mathrm{C}\) ) generally depends on the characteristics in the diagrams 1 and 2. The Thermal Overload Relays have a characteristic that the operating current becomes high when the ambient temperature is low and becomes low when the ambient temperature is high. If the ambient temperature of the installation site is significantly different from \(20^{\circ} \mathrm{C}\) (the temperature on the control board of \(35^{\circ} \mathrm{C}\) ), the setting current of the Thermal Overload Relays needs to be corrected as shown in diagrams 1 and 2 . In addition, note that the compensation factor has a characteristic to be the minimum scale>middle scale>maximum scale at the adjustment knob location. (Note that the Thermal Overload Relays may operate at a current of less than \(100 \%\) stabilized current if in use at temperatures exceeding the allowable working temperature of \(40^{\circ} \mathrm{C}\left(55^{\circ} \mathrm{C}\right)\). )

Fig. 3.1 Ambient temperature compensation curve (T18 frame)


Fig. 3.3 Ambient temperature compensation curve (N120 frame)


Fig. 3.5 Ambient temperature compensation curve (N600 frame)


Note 1. The ambient temperature applied to MS type indicates the outside temperature of the box.

Fig. 3.2 Ambient temperature compensation curve (T25/T50/T65/T100 frame)


Fig. 3.4 Ambient temperature compensation curve (N220/N400 frame)


Compensation factor: Percentage of the minimum operating current at the ambient temperature of \(20^{\circ} \mathrm{C}\) (the temperature on the control board of \(35^{\circ} \mathrm{C}\) )
<Compensation procedure of setting current>
Determine the compensation factor of the working ambient
temperature according to the curves in diagrams 3.1 and 3.5
and use the value of all load currents of the motor divided by
the determined compensation factor as the stabilization value.
(Example: The ambient temperature compensation factor
for TH-T50 at the ambient temperature of \(40^{\circ} \mathrm{C}\) (the
temperature on the control board of \(55^{\circ} \mathrm{C}\) ) is \(97 \%\) at the
minimum scale according to diagram 3.2. If the motor rated
current is 43A, the stabilization value is \(44.3 \mathrm{~A}(=43 / 0.97)\).)
Note 2. The temperature including the temperature increase on the control board applied to the MSO type is indicated.

Note 2. When the thermal overload relay is independently mounted, divide the settling value obtained in Figure 3.1 to 3.5 by the compensation factors in the table below.
- Compensation factor when using the thermal overload relay independently
\begin{tabular}{c|c}
\hline \multicolumn{1}{c|}{ Model Name } & \begin{tabular}{c} 
Independent Thermal \\
Overload Relays TH-
\end{tabular} \\
\hline TH-T18(BC)(KP) 0.12 to 2.5A & 1.04 \\
\hline TH-T18(BC)(KP) 3.6A & 1.05 \\
\hline TH-T18(BC)(KP) 5 to 15A & 1.06 \\
\hline TH-T25(BC)(KP) & 1.06 \\
\hline TH-T65(KP) & 1.05 \\
\hline
\end{tabular}
\begin{tabular}{l|c}
\hline Model Name & \begin{tabular}{c} 
Independent Thermal \\
Overload Relays TH-
\end{tabular} \\
\hline TH-N120(KP) 42A 54A & 1.08 \\
\hline TH-N120(KP) 67A 82A & 1.16 \\
\hline TH-N220(KP)/N400(KP) & 1.01 \\
\hline TH-N600(KP) & 1.02 \\
\hline
\end{tabular}

\section*{Connecting Electric Wire Size And Operating Current}

The minimum operating current of \(\mathrm{TH}-\mathrm{T} / \mathrm{N}\) has been adjusted by the standard wire size as shown in the table below. If the electric wire is thicker or thinner than this standard electric wire size, the operating current becomes high or low, respectively. Therefore, correct the stabilized current (divide it by the change rate of the minimum operating current) to use a size different from the standard connecting electric wire size.
- Connecting Electric Wire Size and Minimum Operating Current
\begin{tabular}{|c|c|c|c|c|}
\hline Model Name & \(\qquad\) & Standard Electric Wire Size [ \(\mathrm{mm}^{2}\) ] & \begin{tabular}{l}
Connecting \\
Electric Wire \\
Size \(\left[\mathrm{mm}^{2}\right]\)
\end{tabular} & Change Rate of Minimum Operating Current [\%] \\
\hline TH-T18(KP) & 0.12 to 15 & \multirow{2}{*}{2} & \multirow[t]{2}{*}{\[
\begin{gathered}
1.25 \\
2.5
\end{gathered}
\]} & \multirow[t]{2}{*}{\[
\begin{gathered}
98 \\
103
\end{gathered}
\]} \\
\hline TH-T25(KP) & 0.24 to 11 & & & \\
\hline TH-T25(KP) & 15, 22 & 3.5 & \[
\begin{aligned}
& 2 \\
& 6 \\
& \hline
\end{aligned}
\] & \[
\begin{gathered}
\hline 97 \\
104 \\
\hline
\end{gathered}
\] \\
\hline \multirow{3}{*}{TH-T50(KP)} & 29 & \multirow{2}{*}{8} & \multirow[t]{2}{*}{\[
\begin{aligned}
& 5.5 \\
& 14
\end{aligned}
\]} & \multirow[t]{2}{*}{\[
\begin{gathered}
96 \\
104
\end{gathered}
\]} \\
\hline & 35 & & & \\
\hline & 42 & 14 & 8 & 95 \\
\hline \multirow{5}{*}{TH-T65(KP)} & 15 & 3.5 & \[
\begin{gathered}
2 \\
5.5
\end{gathered}
\] & \[
\begin{gathered}
95 \\
105
\end{gathered}
\] \\
\hline & 22, 29 & 5.5 & \[
\begin{gathered}
\hline 3.5 \\
8 \\
\hline
\end{gathered}
\] & \[
\begin{gathered}
\hline 96 \\
105 \\
\hline
\end{gathered}
\] \\
\hline & 35 & 8 & \[
\begin{aligned}
& 5.5 \\
& 14
\end{aligned}
\] & \[
\begin{gathered}
95 \\
105 \\
\hline
\end{gathered}
\] \\
\hline & 42 & 14 & \[
\begin{gathered}
\hline 8 \\
22
\end{gathered}
\] & \[
\begin{gathered}
\hline 95 \\
104 \\
\hline
\end{gathered}
\] \\
\hline & 54 & 22 & \[
\begin{aligned}
& 14 \\
& 30 \\
& \hline
\end{aligned}
\] & \[
\begin{gathered}
\hline 96 \\
104 \\
\hline
\end{gathered}
\] \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|c|}
\hline Model Name & Heater Designation [A] & \begin{tabular}{l}
Standard Electric \\
Wire Size \\
[ \(\mathrm{mm}^{2}\) ]
\end{tabular} & \begin{tabular}{l}
Connecting \\
Electric Wire \\
Size \(\left[\mathrm{mm}^{2}\right]\)
\end{tabular} & Change Rate of Minimum Operating Current [\%] \\
\hline \multirow[t]{2}{*}{TH-T100(KP)} & 67 & 22 & \[
\begin{array}{r}
14 \\
30
\end{array}
\] & \[
\begin{gathered}
97 \\
103
\end{gathered}
\] \\
\hline & 82 & 38 & 30 & 97 \\
\hline \multirow{3}{*}{TH-N120(KP)} & 42 & 14 & \[
\begin{gathered}
\hline 8 \\
22
\end{gathered}
\] & \[
\begin{gathered}
95 \\
104
\end{gathered}
\] \\
\hline & 54, 67 & 22 & \[
\begin{aligned}
& 14 \\
& 30
\end{aligned}
\] & \[
\begin{gathered}
96 \\
104
\end{gathered}
\] \\
\hline & 82 & 38 & \[
\begin{aligned}
& \hline 30 \\
& 50 \\
& \hline
\end{aligned}
\] & \[
\begin{gathered}
\hline 97 \\
103 \\
\hline
\end{gathered}
\] \\
\hline \multirow[t]{2}{*}{TH-N120TA(KP)} & 105 & 60 & \[
\begin{aligned}
& 38 \\
& 60
\end{aligned}
\] & \[
\begin{gathered}
97 \\
103
\end{gathered}
\] \\
\hline & 125 & 60 & \[
\begin{aligned}
& 50 \\
& 80 \\
& \hline
\end{aligned}
\] & \[
\begin{gathered}
98 \\
103 \\
\hline
\end{gathered}
\] \\
\hline
\end{tabular}

\section*{Combination With No-Fuse Breaker (Protection Coordination)}

Magnetic starters are responsible for the starting and stopping of motors, and protection from burnout due to overload, constraint or open-phase. Short-circuit protection devices such as nofuse breakers are responsible for the current larger than the interruption capability of the magnetic starter caused by a short circuit, etc.
Properly performing these allocations is called protection coordination and the principles are as follows (see Figure 4)
(1) The combined operating properties of the thermal overload relay and no-fuse breaker must be on the lower side of the thermal properties of the motor, which are on the upper side (right side) of the start-up properties and full-load current of the motor.
(2) For overload current of less than the constraint (startup) current, the thermal overload relay must operate earlier than the no-fuse breaker.
(3) The no-fuse breaker must operate if the current is larger than the interruption capability of the magnetic starter.
(4) The no-fuse breaker should operate if the current is less than the overload resistance of the magnetic starter.
(5) The operating properties of the no-fuse breaker must be lower than the allowable current - time properties of the wire.

For more information, refer to the catalog and technical documents of the no-fuse breaker.

\section*{Handling (Precautions)}
(1) When restarting the tripped thermal overload relay, remove the cause of the trip.

When the automatic reset method is used, in order to prevent the motor from automatically restarting due to reset, implement measures such as adopting a self-retaining circuit. Regardless of the method, the resettable time will be from about 10 seconds to 10 minutes depending on the heating temperature of the bimetal.
Furthermore, to cool the bimetal to the surrounding temperature, use equipment such as fans for about 30 minutes.
(2) Never touch the inside of the thermal overload relay.
(3) The heater wire of the thermal overload relay may blow before tripping if it is charged with a current of 13 times higher than the rating.
(4) The reset method is changed as follows.

Changing the reset method of TH-T18
- Manual \(\rightarrow\) automatic switching method:

After removing the stopper by cutting it with a nipper or the like, slide the switching plate to the right and align it with A as shown in Figure 5 .
(In the state as shown in Figure 6.2)
- Automatic \(\rightarrow\) manual switching method:

Slide the switching plate to the left to align with H .
(In the state as shown in Figure 6.1)


Fig. 5. Cutting the stopper


Note 1. Take precautions as follows when cutting off the stopper.
- Be careful not to let fragments enter the eyes.
(5) Manual tripping

Manual tripping is enabled by inserting a screwdriver or the like into the display window in manual reset. (Fig. 10)


Note.For TH-T18, do not perform manual tripping in the automatic reset mode, as this leads to internal component failure. When performing a sequence check, be sure that the automatic reset is

\section*{Changing the reset method of TH-T25 to T100, TH-N120 to N600}
- Manual \(\rightarrow\) automatic switching method:

After cutting off the stopper on the tip of the reset bar, fully push it in, then rotate it in the direction of A. (Figs. 7, 8) - Automatic \(\rightarrow\) manual switching method:

Rotate the reset bar in the direction of H , to pop out the reset bar. (Fig. 9)


Note 1.Take precautions as follows when cutting off the stopper on the tip of the reset bar.
-Make sure that segments do not enter from the display window.
The display lever may stop moving.
Block the display window when cutting off the stopper to prevent segments from entering it. Be careful not to let fragments enter the eyes.

(6) Precautions When Combining With the Magnetic Contactor
For the assembling method and precautions when using in combination with the thermal overload relay and magnetic contactor, refer to page 231.

\subsection*{5.7 Standard/Overload and Open-Phase Protection Type Thermal Overload Relays TH- \(\square / K P\)}

TH (standard with 2-element) is suitable for the overload and constraint protection of standard motors, and TH-KP (with 3 -element (2E)) is suitable for the overload, constraint and open-phase protection of motors.

TH-KP has the same shape and size as TH (standard with 2-element), and can be easily combined with magnetic contactors.

\section*{Features}
- Extensive lineup

- Changing the reset method Changing between the manual reset and automatic reset is easy
- Easy wiring


TH-N120
Features of the TH Thermal Overload Relay
- Easy current setting

The motor current direct setting can be adjusted by both Phillips and flathead screwdrivers
- Can be manually checked Allows manual tripping from the surface using a screwdriver
- With operation indicator
- Trip-Free structure
- With 1a1b contact

Make and break contacts with different voltage can be used

\section*{Application}

For the selection of heater designation for the capacity of the standard three-phase motor, refer to page 48 or 139.
The manufactured model name, heater designation and combined magnetic contactor frame are shown in the table below.
- Manufactured model name, heater designation and combined magnetic contactor frame (standard 2-element, 3 -element, and overload and open-phase protection type)


Note 1.For TH-T18(KP), independent mounting and IEC 35 mm rail mounting may be enabled by combining with UT-HZ18.
Note 2.For TH-T25(KP), IEC 35 mm rail mounting may be enabled by combining with UN-RM20.
Note 3.Use TH-N600(KP) in combination with current transformer for measuring instruments (rated secondary load of 15 VA or more: recommended model names are CW-15LM,
CW-15L or CW-40LM).
The ratio of current transformation is as shown in the heater designation field in the table.
Note 4.The - mark in the model name field indicates that it is outside production range.
Note 5.TH-T18(KP), T25(KP), T50(KP) with BC and TH-T65(KP) with CW can also be manufactured.
However, TH-T50BC(KP) has no screw holder attached to the main circuit terminal (3-pole) on the power supply side.
Note 6.It is standardly used at the commercial frequency of \(50 / 60 \mathrm{~Hz}\). Make sure that the protection coordination with motor characteristics is possible before use.

\subsection*{5.8 Thermal Overload Relays with Saturable Reactor TH- \(\square\) (KP)SR}

As the standard thermal overload relay operates at startup, suitable protective properties may not be obtained for motors that take a long time to start, such as those that are started with a large inertial load.
The thermal overload relay with saturable reactor has a structure with a small reactor with an iron-containing core connected in parallel with the heater. It causes little change to the operating properties in the current range of up to about \(200 \%\) of settling current, and in the current range beyond that, the iron core of the reactor is saturated to increase the shunt current to the reactor and limit the current to the heater in order to increase the operating time limit.
In addition, it helps achieve protection coordination with a low voltage circuit breaker.

\section*{Application}


TH-T25KPSR

For selection of heater designation for the capacity of the standard three-phase motor, refer to pages 48 and 139. Selection guidelines for motor start-up time are shown on page 140. The manufactured model name, heater designation and combined magnetic contactor frame are indicated in the table below.
- Manufactured model name, heater designation and combined magnetic contactor frame (with saturable reactor)


Note 1. For TH-T18HZSR, independent mounting and IEC 35 mm rail mounting may be enabled by combining with UT-HZ18.
Note 2. Use TH-N600(KP)SR in combination with current transformer for measuring instruments (rated secondary load of 15 VA or more: recommended model names are CW-15LM, CW-15L or CW-40LM).
The alternating current ratio is as shown in the heater designation field in the table
Note 3. The - mark in the model name field indicates that it is outside production range.
Note 4. TH-T18(HZ)SR, T25(KP)SR, T50(KP)SR with BC can also be manufactured.
However, TH-T50BC(KP)SR has no screw holder attached to the main circuit terminal (3-pole) on the power supply side.
Note 5. TH-T25BC (KP) SR with wiring streamlining terminal and S(D)-2 \(\times\) T21 to T50BC cannot be combined. Order with MSO(D) (MSO(D)-2 \(\times\) T21 to T50BC (KP) SR).

\subsection*{5.9 Quick-acting Characteristics Thermal Overload Relays TH- \(\square\) FS(KP) \\ TH-FSKP and FS quick-acting characteristics thermal overload relays have quicker operation time than the standard TH type, so that they can be applied to motors such as submersible motors that have short allowable time during constraint. \\ Please note that TH-T \(\square F S K P\) has 3 elements and can be used for 2E thermal, while TH-FS has 2 elements. \\ TH-T25FSKP \\ }

\section*{Application}

The manufactured model name, heater designation and combined magnetic contactor frame are shown in the table below.
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow{4}{*}{Model Name} & With 2-Element & For Magnetic Starters & - & \multirow[b]{2}{*}{TH-T25FS} & TH-T50FS & \multirow[t]{2}{*}{TH-T65FS} & TH-T100FS \\
\hline & Win 2-Element & For Independent Mounting & - & & - & & - \\
\hline & \multirow[b]{2}{*}{With 3-Element (2E)} & For Magnetic Starters & TH-T18FSKP & \multirow[t]{2}{*}{TH-T25FSKP} & TH-T50FSKP & \multirow[b]{2}{*}{TH-T65FSKP} & TH-T100FSKP \\
\hline & & For Independent Mounting & (See Note 1) & & - & & - \\
\hline \multicolumn{3}{|r|}{Operating Frequency Range [Hz]} & \multicolumn{5}{|c|}{0 (DC) to 400 (Note 4)} \\
\hline \multicolumn{3}{|l|}{\multirow[b]{7}{*}{\begin{tabular}{l}
Heater Designation \\
(Adjustment Range of Settling Current) [A] \\
(The --- line in the table on the right represents the correspondence between the magnetic contactor and frame to be combined)
\end{tabular}}} & \multirow[t]{5}{*}{\[
\begin{aligned}
& \hline 2.1(1.7 \text { to } 2.5) \\
& 3.6(2.8 \text { to } 4.4) \\
& 5(4 \text { to } 6) \\
& 6.6(5.2 \text { to } 8) \\
& 9(7 \text { to } 11)
\end{aligned}
\]} & \multirow[t]{7}{*}{\[
\begin{array}{|l}
\hline 2.1(1.7 \text { to } 2.5) \\
3.6(2.8 \text { to } 4.4) \\
5(4 \text { to } 6) \\
6.6(5.2 \text { to } 8) \\
9(7 \text { to } 11) \\
11(9 \text { to } 13) \\
15(12 \text { to } 18) \\
22(18 \text { to } 26) \\
\hline
\end{array}
\]} & \multirow[t]{7}{*}{\[
\begin{aligned}
& \hline 29(24 \text { to } 34) \\
& 35(30 \text { to } 40) \\
& 42(34 \text { to } 50)
\end{aligned}
\]} & \multirow[t]{7}{*}{\[
\begin{aligned}
& \hline 42(34 \text { to } 50) \\
& 54(43 \text { to } 65)
\end{aligned}
\]} & \multirow[t]{7}{*}{\[
\begin{aligned}
& \hline 67(54 \text { to } 80) \\
& 82(65 \text { to } 93)
\end{aligned}
\]} \\
\hline & & & & & & & \\
\hline & & & & & & & \\
\hline & & & & & & & \\
\hline & & & & & & & \\
\hline & & & 119 9 to 13) & & & & \\
\hline & & & 15(12 to 18) & & & & \\
\hline \multicolumn{3}{|c|}{Trip Class
(see page 138)} & 5 & 5 & 5 & 5 & 5 \\
\hline \multicolumn{3}{|r|}{Frame of the Combined Magnetic Contactor} & \begin{tabular}{r} 
T10, T12, T20 \\
\hdashline------12, T20
\end{tabular} & \[
\begin{gathered}
\mathrm{T} 21, \mathrm{~T} 25, \\
\mathrm{~T} 35, \mathrm{~T} 50 \\
\mathrm{~T} 25, \mathrm{~T} 35, \mathrm{~T} 50
\end{gathered}
\] & T35, T50 & \[
\begin{gathered}
\text { T65, T80, } \\
\text { T100 }
\end{gathered}
\] & T80, T100 \\
\hline
\end{tabular}

Note 1. For TH-T18FSKP, independent mounting and IEC 35 mm rail mounting may be enabled by combining with UT-HZ18. For TH-T25FS(KP), IEC 35 mm rail mounting may be enabled by combining with UN-RM20.
Note 2. TH-T18FSKP, T25FS(KP), T50FS(KP) with BC can also be manufactured.
Note 3. The - mark in the model name field indicates that it is outside production range.
Note 4. It is standardly used at the commercial frequency of \(50 / 60 \mathrm{~Hz}\). Make sure that the protection coordination with motor characteristics is possible before use.

\section*{Outline Drawings}

The same as the standard (with 2-element and 3-element (2E)). Refer to page 148.

\section*{5 \\ TH-T/N Type Thermal Overload Relays}
5.10 Outline Drawings/Contact Arrangements

T18 (The diagrams show models without "BC".)


TH-T18(HZ)SR



For combination with the following magnetic contactors
TH-T18SR: S-T10, T12, T20 SD-T12, T20
TH-T18HZSR can be used independently whe


T25 (The diagrams show models without "BC".)


T50 (The diagrams show models without "BC".)


\section*{TH-T50(BC)(KP)SR}


T65 (The diagrams show models without "CW".)

\begin{tabular}{|c|c|}
\hline \multicolumn{2}{|r|}{Contact Arrangement} \\
\hline TH-T65 &  \\
\hline TH-T65KP &  \\
\hline & Model Name \\
\hline & TH-T65 \({ }^{\text {a }}\) ( 15 A to 54A \\
\hline
\end{tabular}

\section*{TH-T65(KP)SR}


T100
TH-T100(KP)


Can Screw (Self-Lititing)
Chen be used in independent mounting
Cannot be used in independent mounting
When combining with a magnetic contactor, the
Combination with S(D)-T8: BH559N350
Combination with S \(T 100:\) BH569N350
Combination with S-T100: BH569N350
Combination with SD-T100: BH569N352


TH-T100(KP)SR



\section*{5 \\ TH-T/N Type Thermal Overload Relays}

N120/N120TA
TH-N120(KP)

\begin{tabular}{|c|l|}
\hline Model Name & Model Number \\
\hline TH-N120 & THN65 \(\square \square\) \\
\hline
\end{tabular}
 Combination with S(D)-N125, SLD(D)-N1225: BE57593355


N220RH/N220HZ

 TH-N220RHSR


N400RH/N400HZ

\section*{TH-N400RH(KP)}

2.2 (2.5) kg


Cannot be used in independent mounting
Attached M5 screw and wiring screws for \(m\) nagnetic contactor are used when combining with S(D)-N300/N400 and SL(D)-N300/N400

\begin{tabular}{|c|l|}
\hline Model Name & Model Number \\
\hline TH-N400RH & THN75 \(\square \square\) \\
\hline
\end{tabular}

\section*{5}


TH-N600(KP)SR


\subsection*{5.11 Operating Characteristic of Thermal Over Relay (Ambient Temperature of \(20^{\circ} \mathrm{C}\) )}

Refer to page 143 regarding the connecting electric wire size.

TH-T18, T18KP


TH-T50, T50KP


TH-T25, T25KP


TH-T65, T65KP,
TH-T100, T100KP


TH-T18SR


TH-T50SR, T50KPSR


TH-T25SR, T25KPSR


TH-T65SR, T65KPSR,
TH-T100SR, T100KPSR


TH-T18FSKP


TH-T25FS, TH-T25FSKP, TH-T50FS, TH-T50FSKP


TH-T65FS, T65FSKP,
TH-T100FS, T100FSKP


TH-N120, N120TA, N120KP, N120TAKP


TH-N600, N600KP


TH-N220RH/HZ(KP), N400RH/HZ(KP)


TH-N120SR, N120TASR, N120KPSR, N120TAKPSR


TH-N220RH/HZ(KP)SR, N400RH/HZ(KP)SR


TH-N600SR, N600KPSR


\section*{TH-T/N Type Thermal Overload Relays}

\subsection*{5.12 How to Order}

Follow the steps below when ordering. (Enter a space in \(\mathbf{\Delta}\).)

\section*{TH-T Thermal Overload Relays}
\begin{tabular}{l|l|}
\hline \multicolumn{1}{|c|}{ Model Name } & \begin{tabular}{|l|}
\hline \multicolumn{1}{|c|}{ Heater Designation } \\
\hline \begin{tabular}{|l|l|}
\hline TH-T25
\end{tabular} \\
\begin{tabular}{ll} 
Specify from the \\
following model name \\
codes.
\end{tabular} \\
\hline
\end{tabular} \\
\begin{tabular}{l} 
Specify the heater designation from pages 145, 146 or 147. \\
When the full-load current of the motor is included in 2 heater \\
designations, give priority to the heaters listed in the table on \\
page 48.
\end{tabular} \\
\hline
\end{tabular}

Model Name Codes of Thermal Overload Relays
\begin{tabular}{cc|}
\hline TH & \(-\quad\) T18 \\
\hline Frame \\
\hline T18 \\
\hline T25 \\
\hline T50 \\
\hline T65 \\
\hline T100 \\
\hline
\end{tabular}
\begin{tabular}{|c|c|}
\hline \multicolumn{2}{|c|}{KP} \\
\multicolumn{2}{|c}{\(\boldsymbol{A}\)} \\
\hline Symbol & Heater Designation \\
\hline None & Specifications \\
\hline KP & With 2-Element \\
\hline FS & Quick Trip Type \\
\hline SR & With Saturable Reactor \\
\hline BC & Wiring Streamlining Terminal \\
\hline AR & Automatic Reset \\
\hline
\end{tabular}

\section*{TH-N Thermal Overload Relays}


Model Name Codes of Thermal Overload Relays
\begin{tabular}{|c|c|c|c|c|}
\hline TH & - & N220 & KP & - Heater Designation \\
\hline \multicolumn{3}{|c|}{Frame} & Symbol & Specifications \\
\hline \multicolumn{3}{|c|}{N120} & None & With 2-Element \\
\hline \multicolumn{3}{|c|}{N120TA} & KP & With 3-Element (2E) \\
\hline \multicolumn{3}{|c|}{N220} & RH & For Magnetic Starter \\
\hline \multicolumn{3}{|c|}{N400} & HZ & For Independent Mounting \\
\hline \multicolumn{3}{|c|}{N600} & SR & With Saturable Reactor \\
\hline & & & AR & Automatic Reset \\
\hline
\end{tabular}

Note 1. Model names that correspond to mounting methods (for magnetic starters, independent mounting and DIN rail mounting) are shown in the table below.
\begin{tabular}{cc|c|c}
\hline \multicolumn{2}{c|}{ For Magnetic Starters } & For Independent Mounting & For DIN Rail Mounting \\
\hline TH-T18 & \(* 1\) & TH-T18 + UT-HZ18 \(* 2\) & TH-T18+UT-HZ18 \(\quad * 2\) \\
\hline TH-T25 & & TH-T25 & TH-T25 + UN-RM20 \\
\hline TH-T50 \\
\hline TH-T65 & \(* 1\) & - & - \\
\hline TH-T100 & \(* 1\) & TH-T65 & - \\
\hline TH-N120 & - & - \\
\hline TH-N120TA & \(* 1\) & TH-N120 & - \\
\hline TH-N220RH & \(* 1\) & TH-N120TAHZ & - \\
\hline TH-N400RH & \(* 1\) & TH-N22OHZ & - \\
\hline- & & TH-N400HZ & - \\
\hline
\end{tabular}
*1 Cannot be independently mounted.
*2 Order UT-HZ18 and UN-RM20 separately from the thermal overload relay body (TH-T18 and TH-T25). (Refer to page 230)
*3 Use TH-N600 in combination with current transformer for measuring instruments (rated secondary load of 15 VA or more).
(Refer to page 136)
MS-T Series Contactor Type Contactor Relays
6.1 Model List ..... 160
6.2 Selection and Application ..... 161
6.3 Standard Type (AC Operated) Contactor Relays SR-T \(\square\) ..... 163
6.4 DC Operated Contactor Relays SRD-T \(\square\) ..... 166
6.5 Mechanically Latched Contactor Relays SRL-TD, SRLD-T \(\square\) ..... 168
6.6 Contactor Relays with Large Rated Auxiliary Contacts SR-T \(\square J H\), SRD-T \(\square J H\) ..... 170
6.7 Contactor Relays with Overlap Contacts SR-T \(\square L C\), SRD-T \(\square L C\) ..... 171
6.8 Delay Open Contactor Relays SR-T \(\square\) DL ..... 172
6.9 Contactor Relays with Wiring Streamlining Terminals SR-T \(\square B C\), SRD-T \(\square B C\) ..... 173
6.10 Contactor Relays with Spring Clamp Terminals SR-T \(\square S Q\), SRD-T \(\square S Q\) ..... 175
6.11 How to Order ..... 177

\section*{MS-T Series Contactor Type Contactor Relays}

\subsection*{6.1 Model List}
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multicolumn{4}{|c|}{Appearance} &  & SR-T9 \\
\hline \multicolumn{4}{|c|}{Frame} & T5 & T9 \\
\hline \multicolumn{4}{|c|}{Number of Contacts} & 5 & 9 \\
\hline \multicolumn{4}{|c|}{\multirow{3}{*}{Contact Arrangement}} & 5 a & 9 a \\
\hline & & & & 4a1b & 7 a 2 b \\
\hline & & & & 3a2b & 5a4b \\
\hline \multicolumn{4}{|r|}{Rated Insulation Voltage [V]} & \multicolumn{2}{|c|}{690} \\
\hline \multicolumn{4}{|c|}{Applicable Standard} & \multicolumn{2}{|l|}{JIS C8201-5-1, IEC60947-5-1, EN60947-5-1, GB14048.5} \\
\hline \multicolumn{4}{|r|}{Rated Impulse Withstand Voltage [kV]} & \multicolumn{2}{|c|}{6} \\
\hline \multicolumn{4}{|r|}{Rated Frequency [Hz]} & \multicolumn{2}{|c|}{50/60} \\
\hline \multicolumn{4}{|c|}{Pollution Degree} & \multicolumn{2}{|c|}{3} \\
\hline \multicolumn{4}{|r|}{Conventional Free Air Thermal Current Ith [A]} & \multicolumn{2}{|c|}{10} \\
\hline \multirow{5}{*}{} &  & Category AC-15 (Coil Load) & AC120 V AC240 V AC440 V AC550 V & \multicolumn{2}{|c|}{1.2} \\
\hline &  & \begin{tabular}{l}
Category AC-12 \\
(Resistive Load)
\end{tabular} & \[
\begin{aligned}
& \text { AC120 V } \\
& \text { AC240 V } \\
& \text { AC440 V } \\
& \text { AC550 V } \\
& \hline
\end{aligned}
\] & & \\
\hline & \multirow[t]{2}{*}{} & Category DC-13 (Coil Load) & \[
\begin{aligned}
& \hline \text { DC24 V } \\
& \text { DC48 V } \\
& \text { DC110 V } \\
& \text { DC220 V } \\
& \hline
\end{aligned}
\] & \multicolumn{2}{|c|}{\[
\begin{gathered}
1.5 \\
0.6(2) \\
0.3(0.8) \\
\hline
\end{gathered}
\]} \\
\hline & & Category DC-12 (Resistive Load) & \[
\begin{aligned}
& \hline \text { DC24 V } \\
& \text { DC48 V } \\
& \text { DC110 V } \\
& \text { DC220 V } \\
& \hline
\end{aligned}
\] & \multicolumn{2}{|c|}{\[
\begin{gathered}
10 \\
8 \\
5(8) \\
1 \text { (3) } \\
\hline
\end{gathered}
\]} \\
\hline & \multicolumn{3}{|l|}{Minimum Applicable Load Level} & \multicolumn{2}{|c|}{20 V 3 mA (Note 5)} \\
\hline \multicolumn{3}{|r|}{Standard Type} & SR-■ & O & O \\
\hline \multicolumn{3}{|r|}{DC Operated Type} & SRD- \(\square\) & 0 & O \\
\hline \multicolumn{3}{|r|}{\multirow[t]{2}{*}{Mechanically Latched Type}} & \multirow[t]{2}{*}{\[
\begin{aligned}
& \text { SRL- } \square \\
& \text { SRLD- } \square
\end{aligned}
\]} & O & - \\
\hline & & & & O & - \\
\hline \multicolumn{3}{|r|}{\multirow[t]{2}{*}{With Large Rated Auxiliary Contacts}} & \multirow[t]{2}{*}{\[
\begin{aligned}
& \hline \text { SR- } \square J H \\
& \text { SRD- } \square J H
\end{aligned}
\]} & \(\bigcirc\) & \(\bigcirc\) \\
\hline & & & & \(\bigcirc\) & \(\bigcirc\) \\
\hline \multicolumn{3}{|r|}{\multirow[b]{2}{*}{With Overlap Contacts}} & \multirow[t]{2}{*}{\begin{tabular}{l}
SR-DLC \\
SRD-DLC
\end{tabular}} & \(\bigcirc\) & \(\bigcirc\) \\
\hline & & & & \(\bigcirc\) & \(\bigcirc\) \\
\hline \multicolumn{3}{|r|}{Delay Open Type} & SR-पDL & \(\bigcirc\) & \(\bigcirc\) \\
\hline \multicolumn{3}{|r|}{\multirow[t]{2}{*}{With Wiring Streamlining Terminals}} & \multirow[t]{2}{*}{\[
\begin{aligned}
& \hline \text { SR- } \square B C \\
& \text { SRD- } \square B C
\end{aligned}
\]} & \(\bigcirc\) & \(\bigcirc\) \\
\hline & & & & \(\bigcirc\) & \(\bigcirc\) \\
\hline \multicolumn{3}{|r|}{\multirow[t]{2}{*}{With Spring Clamp Terminals}} & \multirow[t]{2}{*}{\[
\begin{aligned}
& \hline \text { SR- } \square S Q \\
& \text { SRD- } \square S Q
\end{aligned}
\]} & \(\bigcirc\) & - \\
\hline & & & & \(\bigcirc\) & - \\
\hline \multicolumn{3}{|r|}{\multirow[t]{2}{*}{With Surge Absorbers (Varistors)}} & \multirow[t]{2}{*}{\[
\begin{aligned}
& \text { SR- } \square S A \\
& \text { SRD- } \square \text { SA }
\end{aligned}
\]} & \(\bigcirc\) & \(\bigcirc\) \\
\hline & & & & \(\bigcirc\) & \(\bigcirc\) \\
\hline \multirow[t]{4}{*}{\%} & \multicolumn{2}{|l|}{Surge Absorber} & (Note 3) & \(\bigcirc\) & \(\bigcirc\) \\
\hline & \multicolumn{3}{|l|}{Additional Auxiliary Contact (Note 4)} & \(\bigcirc\) & - \\
\hline & \multicolumn{3}{|l|}{DC/AC Interface} & \(\bigcirc\) & \(\bigcirc\) \\
\hline & \multicolumn{3}{|l|}{IEC 35 mm Rail Mounting} & \(\bigcirc\) & \(\bigcirc\) \\
\hline
\end{tabular}

Note 1. © indicates standard, ○ indicates semi-standard and - indicates products outside production range.
Note 2. Refer to the individual ratings chart for the contact ratings of large rated auxiliary contacts and overlap contacts. The value in parentheses indicates that when switching a 2-pole load in series.
Note 3. For the mechanically latched type (SRL-T \(\square\), SRLD-T \(\square\) ), 1 piece can be mounted on each closing coil and tripping coil.
Note 4. For the mechanically latched type SRL-T5 and SRLD-T5 only the side clip-on auxiliary contact unit UT-AX11 can be mounted.
Note 5. The contact minimum applicable load level of the front clip-on (4 upper terminals) of SR (D)-T9 is the same as that of UT-AX2/4.

\subsection*{6.2 Selection and Application \\ - Features}
- Rail mounting is fully adopted

IEC 35 mm rail mounting mechanism that dramatically reduces assembly time has been fully adopted.
- High contact reliability The full adoption of twin contacts improves the contact reliability.


Clearly visible coil rating
- The make and break contacts can be used at different voltages
Strengthened insulation between poles and between upper and lower contacts of the same pole.
- Easy wiring

Uses self-lifting terminal screws that can reliably tighten wires, ring crimp lugs and square-tip crimp lugs.
- Live part protection covers are standard equipment
- Wide range of types In addition to the basic frame, extensive applied products such as the DC operated type and the mechanically latched type are also available.
- A wide selection of optional units auxiliary contact units (UT-AX \(\square\) )
The 2-pole and 4-pole contact units can be easily added to SR-T5.
Surge Absorber Units (UT-SA \(\square\) )
For the surge absorber unit that can be mounted in onetouch, the C-R type and indicator type are available aside from the varistor type. With Wiring Streamlining Terminal (SR-TロBC)
The terminal screw does not fall off and wiring is easy (open-tip crimp lugs and bare wires, ring crimp lugs can be used).

\section*{- Type Designations}

MS-T Series


\section*{MS-T Series Contactor Type Contactor Relays}

Function and Operation Classification by Application Type
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline Model Name & Opeation Cateon] & Application & Reference Page & Model Name & Opataio Categoy & Application & Reference Page \\
\hline SR-T \(\square\) & AC & \multirow[t]{2}{*}{General control circuit sequence relay for magnetic contactor command contacts etc.} & Page 163 & \[
\begin{aligned}
& \hline \text { SR-TDLC } \\
& \text { SRD-TDLC }
\end{aligned}
\] & \[
\begin{aligned}
& \mathrm{AC} \\
& \mathrm{DC}
\end{aligned}
\] & Applications that require the overlap switching of the make and break contacts & Page 171 \\
\hline SRD-T \(\square\) & DC & & Page 166 & SR-TロDL & AC & For 2 \({ }_{-1}^{+2}\)-Second Delayed Release & Page 172 \\
\hline \begin{tabular}{l}
SRL-T \(\square\) \\
SRLD-T \(\square\)
\end{tabular} & \[
\begin{aligned}
& \text { AC } \\
& \text { DC }
\end{aligned}
\] & Same applications as SR and SRD types and also those requiring memory functionality & Page 168 & \[
\begin{aligned}
& \text { SR-T } \square B C \\
& \text { SRD-T■BC }
\end{aligned}
\] & \[
\begin{aligned}
& \text { AC } \\
& \text { DC }
\end{aligned}
\] & With Wiring Streamlining Terminal & Page 173 \\
\hline \[
\begin{aligned}
& \text { SR-T } \square \mathrm{JH} \\
& \text { SRD-T } \square \mathrm{JH}
\end{aligned}
\] & \[
\begin{aligned}
& \mathrm{AC} \\
& \mathrm{DC}
\end{aligned}
\] & AC100 to \(220 \mathrm{~V}, 3\) to 10 A control of large breakers and solenoids & Page 170 & \[
\begin{aligned}
& \text { SR-TロSQ } \\
& \text { SRD-T } \square S Q
\end{aligned}
\] & \[
\begin{aligned}
& \text { AC } \\
& \text { DC }
\end{aligned}
\] & With Spring Clamp Terminals & Page 175 \\
\hline & & & & \[
\begin{aligned}
& \hline \text { SR-T } \square \text { SA } \\
& \text { SRD-T } \square S A
\end{aligned}
\] & \[
\begin{aligned}
& \mathrm{AC} \\
& \mathrm{DC}
\end{aligned}
\] & Surge Absorber Mounted Type (Varistor) & \begin{tabular}{l}
Page 43 \\
Page 44
\end{tabular} \\
\hline
\end{tabular}

Application by Contact Voltage, Current, Electrical Durability and Contact Reliability For applications requiring greater contact reliability than indicated in Figs. 1 to 3, parallel contact connections (redundancy) are required. The reliability of the contacts decreases for contacts connected in series.


Note 1. The contact reliability indicates a \(60 \%\) confidence rate for a \(\lambda 60\) failure rate (no. of faults/times switching, no. of contacts)
\begin{tabular}{|c|c|c|c|}
\hline \multirow{6}{*}{} & Item & Reference Page & Remarks \\
\hline & - Working Environment & Page 64 & - \\
\hline & - Mounting & Page 64 & - \\
\hline & - Wiring & Page 68 & - \\
\hline & - Contro C Circuit Power Supply Voltage Fluctuation Range & Page 71 & - \\
\hline & - Applicable Wire Size and Terminal Screw Tightening Torque & Page 67 & - \\
\hline
\end{tabular}

\subsection*{6.3 SR-T \(\square\) Standard Type (AC Operated) Contactor Relays \\ Features}
- Rail mounting is fully adopted IEC 35 mm rail mounting mechanism that dramatically reduces assembly time has been fully adopted.
- High contact reliability The full adoption of twin contacts improves the contact reliability.

- Clearly visible coil rating
- The make and break contacts can be used at different voltages Strengthened insulation between poles and between upper and lower contacts of the same pole.
- Live part protection covers are standard equipment


SR-T9
- Easy wiring Uses self-lifting terminal screws that can reliably tighten wires, ring crimp lugs and square-tip crimp lugs.
- Extensive contact arrangements Selectable according to the required number of contacts.
- A Wide selection of optional units Auxiliary Contact Units (UT-AX \(\square\) )
The 2-pole and 4-pole contact units can be easily added to SR-T5.
Surge Absorber Units (UT-SA \(\square\) )

Rating (SR, SRD, SRL, SRLD, SR-T \(\square D L, ~ S R-T \square B C, S R D-T \square B C, S R-T \square S Q\) and SRD-T \(\square S Q)\)
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multicolumn{4}{|c|}{Frame} & T5 & T9 \\
\hline \multicolumn{4}{|c|}{No. of Contacts} & 5 & 9 \\
\hline \multicolumn{4}{|c|}{\multirow{3}{*}{Contact Arrangement}} & 5a & 9a \\
\hline & & & & 4a1b & 7a2b \\
\hline & & & & 3a2b & 5a4b \\
\hline \multirow{18}{*}{} & \multicolumn{3}{|r|}{Rated Insulation Voltage [V]} & \multicolumn{2}{|c|}{690} \\
\hline & \multicolumn{3}{|l|}{Conventional Free Air Thermal Current Ith [A]} & \multicolumn{2}{|c|}{10} \\
\hline & \multirow[t]{8}{*}{} & \multirow{4}{*}{Category AC-15 (Coil Load)} & AC120V & \multicolumn{2}{|c|}{\multirow[t]{4}{*}{\[
\begin{gathered}
6 \\
3 \\
1.5 \\
1.2
\end{gathered}
\]}} \\
\hline & & & AC240V & & \\
\hline & & & AC440V & & \\
\hline & & & AC550V & & \\
\hline & & \multirow{4}{*}{Category AC-12 (Resistive Load)} & AC120V & \multicolumn{2}{|c|}{10} \\
\hline & & & AC240V & \multicolumn{2}{|c|}{8} \\
\hline & & & AC440V & \multicolumn{2}{|c|}{5} \\
\hline & & & AC550V & \multicolumn{2}{|c|}{5} \\
\hline & \multirow[t]{8}{*}{} & \multirow{4}{*}{Category DC-13 (Coil Load)} & DC24V & \multicolumn{2}{|c|}{3} \\
\hline & & & DC48V & \multicolumn{2}{|c|}{1.5} \\
\hline & & & DC110V & \multicolumn{2}{|c|}{\[
0.6(2)
\]} \\
\hline & & & DC220V & \multicolumn{2}{|c|}{0.3(0.8)} \\
\hline & & \multirow{4}{*}{\begin{tabular}{l}
Category DC-12 \\
(Resistive Load)
\end{tabular}} & DC24V & \multicolumn{2}{|c|}{10} \\
\hline & & & DC48V & \multicolumn{2}{|c|}{8} \\
\hline & & & DC110V & \multicolumn{2}{|c|}{5(8)} \\
\hline & & & DC220V & \multicolumn{2}{|c|}{1(3)} \\
\hline
\end{tabular}

Note 1. JIS C8201-5-1 classifications are class AC-15 applicable to AC solenoid and class DC-13 applicable to DC solenoid switching. JIS C8201-5-1 classifications are class AC-12 applicable to AC resistive load switching and class DC-12 applicable to DC resistive load switching.
Note 2. The value in parentheses for the DC rated operational current indicates the rated operating current when switching a 2-pole load in series.
Note 3. The making and breaking capacities are 10 times with AC-15 and 1.1 times with DC-13.
Note 4. Electrical durability of 500,000 operations. (For AC-15, it is 1 million times at 220 V 2 A and 3 million times at 1 A .)
Note 5. The minimum operating voltage and current differ depending on the allowable fault rate. Select them from Figure 1 on page 162.
Note 6. The withstand voltage is AC2500 V for 1 minute.
Note 7. SR-T5 and SRD-T5 with spring clamp terminals (SQ) can also be manufactured.

\section*{MS-T Series Contactor Type Contactor Relays}

Performance (SR, SRD, SRL, SRLD, SR-T \(\square D L\), SR-T \(\square B C, S R D-T \square B C, S R-T \square S Q\) and SRD-T \(\square S Q\) )
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{\multirow[t]{2}{*}{Frame}} & \multicolumn{4}{|c|}{Making and Breaking Capacities} & \multirow[t]{2}{*}{Switching Frequency} & \multicolumn{2}{|l|}{Switching Durability} \\
\hline & & Category & Rated Operational Voltage & Making Current [A] & Breaking Current [A] & & Electrical & Mechanical \\
\hline \multirow{7}{*}{} & \multirow{7}{*}{\[
\begin{aligned}
& \text { T5 } \\
& \text { T9 }
\end{aligned}
\]} & & AC120V & 66 & 66 & \multirow{7}{*}{1800 Times/Hour [Standard Type] 1200 Times/Hour \(\left[\begin{array}{l}\text { Mechanically Latched } \\ \text { Delay Open Type }\end{array}\right]\)} & \multirow[t]{7}{*}{Class AC-15 (AC Coil Load) \(240 \mathrm{~V} 3 \mathrm{~A}, \quad 0.5\) mil. times 240 V 2 A, 1 mil. times 440 V 1.5 A, 0.5 mil. times Class DC-13 (DC Coil Load) \(110 \mathrm{~V} 0.6 \mathrm{~A}, 0.5\) mil. times \(220 \mathrm{~V} 0.3 \mathrm{~A}, 0.5\) mil. times} & \multirow[t]{7}{*}{\begin{tabular}{l}
10 mil. times \\
[Standard Type] \\
0.5 mil. times \\
[Mechanically Latched Type] \\
0.5 mil. times \\
[Delay Open Type]
\end{tabular}} \\
\hline & & AC-15 & AC240V & 55 & 55 & & & \\
\hline & & & AC550V & 33 & 33 & & & \\
\hline & & \multirow{4}{*}{DC-13} & DC24V & 20 & 20 & & & \\
\hline & & & DC48V & 10 & 10 & & & \\
\hline & & & DC110V & 2(5) & 2(5) & & & \\
\hline & & & DC220V & 0.4(1.5) & 0.4(1.5) & & & \\
\hline
\end{tabular}

Note 1. The DC values in parentheses are the making and breaking capacities when using 2-poles in series.
Note 2. Making current capacity tests are performed 100 times, while breaking current capacity tests are performed 25 times.
Properties (SR-T \(\square\), SR-T \(\square J H\), SR-T \(\square\) BC and SR-T \(\square\) SQ)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Frame} & \multicolumn{2}{|l|}{Coil Input [VA]} & \multirow[t]{2}{*}{\begin{tabular}{|c|} 
Coil \\
Power \\
Consumption \\
{\([W]\)}
\end{tabular}} & \multirow[t]{2}{*}{Coil Current [A]} & \multirow[b]{2}{*}{Contact Arrangement} & \multicolumn{2}{|l|}{Operating Voltage [V]} & \multicolumn{4}{|c|}{Operating Time [ms]} \\
\hline & Inrush & Normal & & & & Close & Open & \[
\begin{array}{|l|}
\hline \text { Coil ON } \\
\rightarrow \text { Make } \\
\text { Contact ON }
\end{array}
\] & \[
\begin{aligned}
& \hline \text { Coil ON } \\
& \rightarrow \text { Break } \\
& \text { Contact OFF }
\end{aligned}
\] & \[
\begin{aligned}
& \hline \text { Coil OFF } \\
& \rightarrow \text { Make } \\
& \text { Contact OFF }
\end{aligned}
\] & \begin{tabular}{l}
Coil OFF \\
\(\rightarrow\) Break \\
Contact ON
\end{tabular} \\
\hline T5 & \multirow{4}{*}{45} & \multirow{4}{*}{7} & \multirow{4}{*}{2.2} & \multirow{4}{*}{0.03} & 5 a & 115 to 145 & 75 to 115 & 12 to 20 & - & 4 to 16 & - \\
\hline T & & & & & 3a2b & 120 to 150 & 75 to 115 & 12 to 20 & 7 to 14 & 4 to 16 & 6 to 17 \\
\hline \multirow[b]{2}{*}{T9} & & & & & 9a & 125 to 156 & 85 to 125 & 12 to 20 & - & 4 to 16 & - \\
\hline & & & & & 5a4b & 130 to 160 & 80 to 120 & 12 to 20 & 7 to 15 & 4 to 16 & 5 to 16 \\
\hline
\end{tabular}

Note 1. The above indicates rough property indices for AC200V coils.
Note 2. The operating voltage is that at a \(20^{\circ} \mathrm{C}\) cold state at 60 Hz . Voltages for coils other than AC200V can be calculated proportionately.
Note 3. The input and power consumption are average values. These are almost the same for coils other than AC200V.
Note 4. The operating time is the value when applying 200 V at 60 Hz . These are almost the same for coils other than AC200V.
Make contacts and break contacts cannot be overlapped in time.
Note 5. The coil current is the average normal value with a \(220 \mathrm{~V}, 60 \mathrm{~Hz}\) applied voltage. Divide the regular input by the coil voltage for coils other than AC200V.

\section*{- Contact Arrangement/Contact Placement}
\begin{tabular}{|c|c|c|}
\hline Frame & T5 & T9 \\
\hline \multirow[b]{3}{*}{\begin{tabular}{l}
Contact \\
Arrangement
\end{tabular}} & 5 a & 9a \\
\hline & 4a1b & 7a2b \\
\hline & 3a2b & 5a4b \\
\hline \multirow{3}{*}{\begin{tabular}{l}
Contact \\
Placement
\end{tabular}} & 5a &  \\
\hline & 4a1b &  \\
\hline &  &  \\
\hline
\end{tabular}
\begin{tabular}{|l|c|c}
\multicolumn{1}{|c|}{ Item } & Reference Page & Remarks \\
\hline\(\cdot\) Operation Coil & Page 43 & - \\
\hline\(\cdot\) How to Order & Page 177 & - \\
\hline\(\cdot\) Combining with Optional Units & Pages 165,196 & - \\
\hline
\end{tabular}

\section*{Combining With Additional Auxiliary Contact Block}

The SR-T Series contactor type Contactor Relay is usable in combination with the following additional auxiliary contact blocks.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Auxiliary Contact Blocks}} & \multicolumn{6}{|c|}{Front clip-on} & \multicolumn{2}{|c|}{Side clip-on} \\
\hline & & \multicolumn{3}{|c|}{UT-AX4(BC)} & \multicolumn{3}{|c|}{UT-AX2(BC)} & UT-AX11(BC) & UT-AX11(BC) \\
\hline Model Name & Contact Arangement & 4a & 3a1b & 2a2b & 2a & 1a1b & 2b & 1a1b + 1a1b & 1a1b \\
\hline & 5a & 9 a & 8a1b & 7a2b & 7 a & 6a1b & 5a2b & 7a2b & 6a1b \\
\hline & 4a1b & 8a1b & 7a2b & 6a3b & 6a1b & 5a2b & 4a3b & 6a3b & 5a2b \\
\hline SRD-TS(BC) & 3a2b & 7a2b & 6a3b & 5a4b & 5a2b & 4a3b & 3a4b & 5a4b & 4a3b \\
\hline
\end{tabular}

Note 1. The auxiliary contact blocks cannot be mounted on \(\mathrm{SR}(\mathrm{D})-\mathrm{T9}(\mathrm{BC})\).
Note 2. The Contactor Relay is not usable with front clip-on blocks mounted at the same time.
Note 3. The contact arrangements in \(\square\) are the standard combinations.
Outline Drawings (The diagrams show models without "BC".)

\section*{SR-T5(BC)}


\[
\xrightarrow{+(56 * 3)(68 * 4)}
\]

*1 Dimension: Including Head-On Auxiliary Contact Unit (UT-AX2(BC)/UT-AX4(BC)) *2 Dimension: Width Dimension from Center of IEC 35 mm Rail
\(* 2\) Dimension: Width Dimension from Center of IEC 35 mm Rail
\(* 3, * 4\) Dimension: Including Side-On Auxiliary Contact Unit (UTAX11(BC)) -
\(* 3\) Has 1 Piece, \(* 4\) Has 2 Pieces (Both Sides)
(For 7.5 mm Rail Height)



\section*{MS-T Series Contactor Type Contactor Relays}

\subsection*{6.4 SRD-T \(\square\) DC Operated Contactor Relays}

\section*{Features}
- IEC 35 mm rail mounting is adopted
- High contact reliability The adoption of twin contacts improves the contact reliability.
- Excellent operational reliability and high frequency switching capacity Uses a DC full-applied voltage type solenoid.
- Live part protection covers are standard equipment


SRD-T9
- No buzzing sound
- No coil inrush current The coil doesn't use saving resistance so there is no inrush current.
- Extensive options Auxiliary Contact Units (UT-AX■)
Surge Absorber Units
(UT-SA \(\square\) )

Properties (SRD-T \(\square\), SRD-T \(\square J H\), SRD-T \(\square\) BC and SRD-T \(\square\) SQ)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Frame} & \multicolumn{3}{|c|}{Coil} & \multicolumn{2}{|l|}{Operating Voltage [V]} & \multicolumn{4}{|c|}{Operating Time [ms]} \\
\hline & Current [A] & \[
\begin{array}{|c|}
\hline \text { Power Consumption } \\
{[\mathrm{W}]}
\end{array}
\] & Time Constant [ms] & Close & Open & Coil ON \(\rightarrow\) Make Contact ON & Coil ON \(\rightarrow\) Break Contact OFF & Coil OFF \(\rightarrow\) Make Contact OFF & Coil OFF \(\rightarrow\) Break Contact ON \\
\hline T5 & \multirow[b]{2}{*}{0.033} & \multirow[b]{2}{*}{3.3(2.2)} & \multirow[b]{2}{*}{40(45)} & 60 to 75 & 10 to 30 & 55 to 75(75 to 95) & 50 to 70(70 to 90) & 5 to 15 & 10 to 20 \\
\hline T9 & & & & 60 to 75 & 10 to 30 & 55 to 75(75 to 95) & 50 to 70(70 to 90) & 5 to 15 & 10 to 20 \\
\hline
\end{tabular}

Note 1. The above indicates rough property indices for DC100V coils. The values in the parentheses for SRD-T5, T9 indicate rough property indices for DC12V or DC24V coils.
Note 2. The operating voltage is that at a \(40^{\circ} \mathrm{C}\) cold state. Voltages for coils other than DC100V can be calculated proportionately.
Note 3. The power consumption and coil time constant are average values. These are almost the same for coils other than DC100V.
Note 4. The coil current value is the average of the current when DC100V is applied to the coil. For coils other than DC100V coils, obtain the coil current value by dividing the power consumption by the coil voltage.
E.g.: For DC24V coils, the coil current value \(\approx 2.2 \mathrm{~W} \div 24 \mathrm{~V}\)

Note 5. The operating time is the value when applying DC100V (with \(5 \%\) or less ripple). These are almost the same for coils other than DC100V. Make contacts and break contacts cannot be overlapped in time.
Note 6. The drive time (coil OFF \(\rightarrow\) make contact OFF/break contact ON) slows down when combined with a surge absorber element, so care should be taken with sequence timing. Furthermore, use only after confirming there is no fault with the real-life application.
Note 7. Note that operation coil terminals have polarity. A1 (+), A2 (-)
\begin{tabular}{|c|c|c|c|}
\hline \multirow{7}{*}{} & Item & Reference Page & Remarks \\
\hline & - Operation Coil & Page 44 & - \\
\hline & - Rating & Pages 160, 163 & - \\
\hline & - Performance & Page 164 & - \\
\hline & - Contact Arrangement/Contact Placement & Page 164 & - \\
\hline & - How to Order & Page 177 & - \\
\hline & - Combining with Optional Units & Pages 165, 196 & - \\
\hline
\end{tabular}

\section*{Outline Drawings (The diagrams show models without "BC".)}


\section*{MS-T Series Contactor Type Contactor Relays}

\subsection*{6.5 SRL-T \(\square\), SRLD-T \(\square\) Mechanically Latched Contactor Relays}

SRL is SR with a mechanical latch mechanism attached at the top. The closed state is mechanically maintained by simply exciting the closing coil for 0.3 seconds or more, and tripping is done by energizing the tripping coil. Closing coils are available as SRL AC operated types or SRLD DC operated types. These are sometimes called keep relays or momentary energizing relays.

\section*{- Features}
- Can be used as a memory relay The mechanical retention prevents opening due to power failures or voltage drops.
- Reduced coil power consumption The constant power consumption of the solenoid of the operation coil can be reduced.
- Allows manual closing
- Allows manual tripping
- Live part protection covers are standard equipment


SRL-T
- No buzzing sound
- Stable operation The self-demagnetizing break contact of the closing coil has been built into the latch mechanism.
- High contact reliability The adoption of twin contacts improves the contact reliability.
- IEC 35 mm rail mounting is fully adopted

\section*{Performance}
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Closing Coil Operation Category} & \multirow[t]{2}{*}{Model Name} & \multirow[t]{2}{*}{Tripping Coil SelfDemagnetizing} & \multirow[t]{2}{*}{Closing Coil SelfDemagnetizing} & \multirow[t]{2}{*}{Contact Arrangement (Valid)} & \multirow[t]{2}{*}{Swithing Frequency [Times/Hour]} & \multicolumn{2}{|l|}{Switching Durability (Ten Thousand Times)} \\
\hline & & & & & & Electrical & Mechanical \\
\hline AC Operated & SRL-T5(BC) & \multirow[b]{2}{*}{Incl.} & \multirow[b]{2}{*}{Incl.} & \multirow[b]{2}{*}{5a, 4a1b, 3a2b} & \multirow[t]{2}{*}{1200} & \multirow[t]{2}{*}{50} & \multirow[t]{2}{*}{50} \\
\hline DC Operated & SRLD-T5(BC) & & & & & & \\
\hline
\end{tabular}

Properties
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{\multirow[b]{2}{*}{Frame}} & \multirow[b]{2}{*}{Operation Coil Input [VA]} & \multirow[b]{2}{*}{\begin{tabular}{l}
Contact \\
Arrangement
\end{tabular}} & \multicolumn{2}{|l|}{Operating Voltage [V]} & \multicolumn{4}{|c|}{Operating Time [ms]} \\
\hline & & & & Close & Trip & Closing Coil ON \(\rightarrow\) Make Contact ON & Closing Coil ON \(\rightarrow\) Break Contact OFF & Tripping Coil ON \(\rightarrow\) Make Contact OFF & Tripping Coil ON \(\rightarrow\) Break Contact ON \\
\hline \multirow[t]{2}{*}{} & \multirow[b]{2}{*}{SRL-T5(BC)} & \multirow[t]{2}{*}{\(\begin{array}{lr}\text { Closing } & 80 \\ \text { Tripping } & 110\end{array}\)} & 5a & 122 to 128 & 90 to 96 & 10 to 16 & - & 9 to 14 & - \\
\hline & & & 3a2b & 139 to 147 & 90 to 94 & 10 to 15 & 8 to 13 & 8 to 13 & 10 to 15 \\
\hline \[
\] & \multirow{2}{*}{SRLD-T5(BC)} & \multirow[t]{2}{*}{\(\begin{array}{lr}\text { Closing } & 90 \\ \text { Tripping } & 180\end{array}\)} & 5a & 60 to 70 & 44 to 60 & 10 to 20 & - & 8 to 15 & - \\
\hline \[
\begin{array}{r}
\square \\
\hline \stackrel{\circ}{\circ} \\
\\
\hline
\end{array}
\] & & & 3a2b & 60 to 70 & 44 to 60 & 10 to 20 & 9 to 16 & 8 to 15 & 10 to 20 \\
\hline
\end{tabular}

Note 1. The above indicates rough property indices for AC200V coils under AC operation (SRL-T \(\square\) ) and for DC100V coils under DC operation (SRLD-T \(\square\) ).
Note 2. The operating voltage is the value at a \(20^{\circ} \mathrm{C}\) cold state for both AC (at 60 Hz ) and DC operation. Voltages for coils other than AC200V or DC100V can be calculated proportionately.
Note 3. The coil input indicates the average value. These are almost the same for coils other than AC200V or DC100V.
Note 4. The drive time is the time taken from when the closing coil or tripping coil is excited until the contact transitions (ON or OFF) when \(200 \mathrm{~V}, 60 \mathrm{~Hz}\) is applied for AC operation or DC100V is applied for DC operation. These are almost the same for coils other than AC200V or DC100V.
Make contacts and break contacts cannot be overlapped in time.
Note 5. The closing coil and tripping coil have the 15-second rating.
\begin{tabular}{|c|c|c|c|}
\hline \multirow[t]{5}{*}{} & Item & Reference Page & Remarks \\
\hline & - Rating & Pages 160, 163 & Same as SR- \(\square\). \\
\hline & - Operation Coil of SRL/SRLD- \(\square\) & Page 44 & - \\
\hline & - How to Order & Page 177 & - \\
\hline & - Combining with Optional Units & Page 196 & - \\
\hline
\end{tabular}

\section*{- Handling}
- Set the excitation time of the closing coil and tripping coil to 0.3 seconds.

When the excitation time is less than 0.3 seconds (circuit example at left), in order to avoid malfunction, change to the circuit at right.
(1) The closing coil \#1MC is excited only by 10 ms by the break contact of the \#2 relay.
(2) The closing coil \#1MC is excited only by 10 ms by the tripping of \#2MT.

(3) A pulse with operating switch LS contact time of 0.3 seconds or less.


Fig. 6. Excitation time of 0.3 seconds or more
- Do not apply the closing command and tripping command at the same time

To avoid giving the closing command and tripping command at the same time or giving the tripping command (or closing command) during the closing command (or tripping command), use an interlock for the closing and tripping commands.
(1) Turn the tripping operating switch LS2 ON before turning the closing operating switch LS1 OFF.
(2) The tripping command is given during the closing command.



Fig. 7. Prevention of simultaneous excitation
- Capacitor trip

The capacitor trip unit (see page 103) can also be used for SRL-T5.
When the coil designation is AC100V: CTU-A1
When the coil designation is AC200V: CTU-A2

Contact Arrangement/Contact Placement
\begin{tabular}{|c|c|c|}
\hline SRL-T5(BC) \({ }^{\text {S }}\) SRLD-T5(BC) & SRL-T5(BC) \({ }^{\text {a }}\) SRLD-T5(BC) & SRL-T5(BC) \(\quad\) SRLD-T5(BC) \\
\hline 5a & 4a1b & 3a2b \\
\hline  &  &  \\
\hline
\end{tabular}

Outline Drawings (The diagrams show models without "BC".)


\section*{MS-T Series Contactor Type Contactor Relays}

\subsection*{6.6 SR-T \(\square\) JH, SRD-T \(\square\) JH Contactor Relays with Large Rated Auxiliary Contacts}

Through the use of S-T12 magnetic contactor contacts, the \(\mathrm{SR}(\mathrm{D})-\mathrm{T} \square \mathrm{JH}\) type is suitable for applications requiring use of comparatively large currents and great electrical durability.

Rating
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multicolumn{4}{|c|}{Model Name} & \[
\begin{aligned}
& \text { SR-T5JH } \\
& \text { SRD-T5JH }
\end{aligned}
\] & \[
\begin{aligned}
& \text { SR-T9JH } \\
& \text { SRD-T9JH }
\end{aligned}
\] \\
\hline \multicolumn{4}{|c|}{\multirow{3}{*}{Contact Arrangement}} & 5 a & 9a \\
\hline & & & & 4a1b & 7a2b \\
\hline & & & & 3a2b & 5a4b \\
\hline \multirow{6}{*}{} & \multicolumn{3}{|r|}{Rated Insulation Voltage [V]} & & \\
\hline & \multicolumn{3}{|l|}{Conventional Free Air Thermal Current lth [A]} & & \\
\hline & \multirow[t]{4}{*}{} & Category AC-15 (Coil Load) & \begin{tabular}{l}
AC120V \\
AC240V \\
AC440V \\
AC550V
\end{tabular} & & \\
\hline & & \begin{tabular}{l}
Category AC-12 \\
(Resistive Load)
\end{tabular} & \begin{tabular}{l}
AC120V \\
AC240V \\
AC440V \\
AC550V
\end{tabular} & & \\
\hline & & Category DC-13 (Coil Load) & \[
\begin{aligned}
& \hline \text { DC24V } \\
& \text { DC48V } \\
& \text { DC110V } \\
& \text { DC220V }
\end{aligned}
\] & & \\
\hline & & \begin{tabular}{l}
Category DC-12 \\
(Resistive Load)
\end{tabular} & \[
\begin{aligned}
& \hline \text { DC24V } \\
& \text { DC48V } \\
& \text { DC110V } \\
& \text { DC220V }
\end{aligned}
\] & & \\
\hline
\end{tabular}

Note 1. Electrical durability of 500,000 operations.
Note 2. The value in parentheses for the AC rated operational current indicates the rated operating current when using different voltages.
Note 3. The minimum operating voltage and current differ depending on the allowable fault rate. Select from Figure 2 on page 162.
\begin{tabular}{|c|c|c|c|}
\hline \multirow{7}{*}{} & Item & Reference Page & Remarks \\
\hline & - Operation Coil & Pages 43, 44 & Same as SR- \(\square\) and SRD- \(\square\). \\
\hline & - Properties & Pages 164, 166 & Same as SR- \(\square\) and SRD- \(\square\). \\
\hline & - Contact Arrangement/Contact Placement & Page 164 & Same as SR- \(\square\) and SRD- \(\square\). \\
\hline & - Outline Drawings & Pages 165, 167 & Same as SR- \(\square\) and SRD- \(\square\). \\
\hline & - How to Order & Page 177 & - \\
\hline & - Combining with Optional Units & Pages 165, 196 & - \\
\hline
\end{tabular}

\section*{6．7 SR－T \(\square L C\), SRD－T \(\square\) LC Contactor Relays with Overlap Contacts}

SR（D）－\(\square \mathrm{LC}\) types with overlap contacts turn off the break contact after the make contact turns on．

Rating（SR，SRD）
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multicolumn{4}{|c|}{Frame} & T5LC & T9LC \\
\hline \multicolumn{4}{|c|}{\multirow[b]{2}{*}{Contact Arrangement}} & 4a1b & 7a2b \\
\hline & & & & 3a2b & 5a4b \\
\hline \multirow{18}{*}{} & \multicolumn{3}{|r|}{Rated Insulation Voltage［V］} & \multicolumn{2}{|c|}{690} \\
\hline & \multicolumn{3}{|l|}{Conventional Free Air Thermal Current Ith［A］} & \multicolumn{2}{|c|}{16} \\
\hline & 建 & \multirow{4}{*}{Category AC－15 （Coil Load）} & AC120 V & \multicolumn{2}{|c|}{6} \\
\hline & 言 & & AC240 V & \multicolumn{2}{|c|}{5} \\
\hline & O & & AC440 V & \multicolumn{2}{|c|}{3} \\
\hline & 든 & & AC550 V & \multicolumn{2}{|c|}{3} \\
\hline & 彦 & \multirow{4}{*}{Category AC－12 （Resistive Load）} & AC120 V & \multicolumn{2}{|c|}{16} \\
\hline & － & & AC240 V & \multicolumn{2}{|c|}{12} \\
\hline & 莖 & & AC440 V & \multicolumn{2}{|c|}{5} \\
\hline & ¢ & & AC550 V & \multicolumn{2}{|c|}{5} \\
\hline & 要 & \multirow{4}{*}{Category DC－13 （Coil Load）} & DC24 V & \multicolumn{2}{|c|}{3} \\
\hline & 는 & & DC48 V & \multicolumn{2}{|c|}{2} \\
\hline & O & & DC110 V & \multicolumn{2}{|c|}{0.5} \\
\hline & 든 & & DC220 V & \multicolumn{2}{|c|}{0.1} \\
\hline & \multirow[t]{4}{*}{} & \multirow{4}{*}{Category DC－12 （Resistive Load）} & DC24 V & \multicolumn{2}{|c|}{8} \\
\hline & & & DC48 V & \multicolumn{2}{|c|}{5} \\
\hline & & & DC110 V & \multicolumn{2}{|c|}{3} \\
\hline & & & DC220 V & \multicolumn{2}{|c|}{0.5} \\
\hline
\end{tabular}

Note 1．The AC rated operational current for the make contact is shown in the table above．
The break contact rated making current is 20 A and the rated breaking current AC 24 to 550 V 3 A ．（However， \(\operatorname{COS} \varphi=0.3\) to 1．0） Note 2．The contacts may not overlap when worn out through current switching and chattering．Take sufficient precautions．

\section*{Contact Arrangement／Contact Placement}
\begin{tabular}{|c|c|}
\hline \[
\begin{aligned}
& \hline \text { SR-T5LC } \\
& \text { SRD-T5LC }
\end{aligned}
\] & \[
\begin{aligned}
& \hline \text { SR-T9LC } \\
& \text { SRD-T9LC }
\end{aligned}
\] \\
\hline 4a1b & 7a2b \\
\hline 3a2b & 5a4b \\
\hline 4a1b &  \\
\hline 3a2b &  \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|}
\hline \multirow{6}{*}{} & Item & Reference Page & Remarks \\
\hline & －Operation Coil & Pages 43， 44 & Same as SR－\(\square\) and SRD－\(\square\) ． \\
\hline & －Properties & Pages 164， 166 & Same as SR－\(\square\) and SRD－\(\square\) ．However，break contact operating times differ． \\
\hline & －Outline Drawings & Pages 165， 167 & Same as SR－\(\square\) and SRD－\(\square\) ． \\
\hline & －How to Order & Page 177 & － \\
\hline & －Combining with Optional Units & Page 196 & Auxiliary contact units and front clip－on timer units cannot be combined together． \\
\hline
\end{tabular}

\section*{MS-T Series Contactor Type Contactor Relays}

\subsection*{6.8 SR-T \(\square\) DL Delay Open Contactor Relays}

SR-TDDL functions to hold the contactor relay for \(2_{-1}^{+2}\) seconds with the use of a capacitor, so that the relay does not open due to a momentary power failure or voltage drop caused by lightning, etc.

\section*{Specifications (SR-T \(\square\) DL Delay Open Contactor Relays)}
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Model Name} & \multirow[t]{2}{*}{Contact Arrangement (Valid)} & \multirow[t]{2}{*}{Designation (Rated Voltage)} & \multirow[t]{2}{*}{\begin{tabular}{l}
Switching \\
Frequency
\end{tabular}} & \multicolumn{2}{|l|}{Switching Durability [x 10000]} & \multirow[t]{2}{*}{Retention Time} \\
\hline & & & & Mechanical & Electrical & \\
\hline SR-T5DL & 2a1b & \multirow[t]{2}{*}{\[
\begin{aligned}
& \text { AC100V (100 to } 110 \mathrm{~V} 50 \mathrm{~Hz} / \\
& 100 \text { to } 110 \mathrm{~V} 60 \mathrm{~Hz}) \\
& \text { AC200V (200 to } 220 \mathrm{~V} 50 \mathrm{~Hz} / \\
& 200 \text { to } 220 \mathrm{~V} 60 \mathrm{~Hz})
\end{aligned}
\]} & \multirow[t]{2}{*}{1800 Times/Hour} & \multirow[t]{2}{*}{50} & \multirow[t]{2}{*}{50} & \multirow[t]{2}{*}{\(2_{-1}^{+2}\) Seconds (Fixed)} \\
\hline SR-T9DL & 6a1b, 4a3b & & & & & \\
\hline
\end{tabular}

Note 1. The rating is the same as that on pages 160 and 163.
Note 2. The retention time is a value where the rated voltage is applied.
Note 3. Uses an electrolytic capacitor, so the retention time should be checked periodically.
Note 4. The contactor relay to be combined is an exclusive product that uses the AC operated type, and cannot be replaced by itself. Note 5. For the operation coil, only AC100V and AC200V can be manufactured.
Note 6. An additional auxiliary contact unit cannot be installed.

\section*{Coil Properties}
\begin{tabular}{c|c|c|c|c|c|c}
\hline \multirow{2}{*}{ Model Name } & \multicolumn{2}{|c|}{ Input [VA] } & \multicolumn{3}{c|}{ Operating Voltage [V] } & \multicolumn{2}{c}{ Operating Time [ms] } \\
\cline { 2 - 7 } & Momentary & Normal & Close & Open & \begin{tabular}{c} 
Operating Power ON \\
Contact a ON
\end{tabular} & \begin{tabular}{c} 
Operating Power OFF --> \\
Contact a OFF
\end{tabular} \\
\hline \begin{tabular}{c} 
SR-T5DL \\
SR-T9DL
\end{tabular} & 70 & 13 & \begin{tabular}{c}
\(85 \%\) or Less of Control \\
Coil Rated Voltage
\end{tabular} & \begin{tabular}{c}
\(10 \%\) or More of Control \\
Coil Rated Voltage
\end{tabular} & 7 to 100 & 10 to 100 \\
\hline
\end{tabular}

Outline Drawings


\section*{SR-T■DL}

\section*{Contact Arrangement}
\begin{tabular}{|c|c|c|}
\hline SR-T5DL &  &  \\
\hline SR-T9DL & 6a1b &  \\
\hline
\end{tabular}

Note: 43-44 and 51-52 terminals are internally wired.

\section*{Connection Diagram}


Note. Operate the relay with the push button in the figure above. The contactor relay may flip-flop when the power is switched ON or OFF.

\subsection*{6.9 SR-T \(\square B C\), SRD-T \(\square B C\) Contactor Relays with Wiring Streamlining Terminals}

\section*{SR(D)-T \(\square B C\)}

SR-T \(\square B C\) with wiring streamlining terminal is capable of crimp lug wiring and bare wire wiring without removing the terminal cover.


\section*{Specifications}
(1) Specifications of the Contactor Relay With Wiring Streamlining Terminal

SR-T5BC
\begin{tabular}{l|c}
\hline \multicolumn{2}{c}{ Standard Specifications (Terminal Cover) + Wiring Streamlining Terminal } \\
\hline Model Name & Contact Arrangement \\
\hline SR-T5BC & \(5 \mathrm{a}, 4 \mathrm{a} 1 \mathrm{~b}\) \\
SRD-T5BC & 3 a 2 b \\
\hline SR-T9BC & 9 a \\
SRD-T9BC & 7 a 2 b \\
& 5 a 4 b \\
\hline
\end{tabular}
(2) Specifications of the Auxiliary Contact Unit With Wiring Streamlining Terminal
\begin{tabular}{c|c|c}
\hline & Standard Specifications (Terminal Cover) & \\
\hline Model Name & Contact Arrangement & Combinable Contactor Relay Model Name \\
\hline \multirow{3}{*}{ UT-AX2BC } & 2 a & \\
& \(1 a 1 \mathrm{~b}\) & \\
\hline UT-AX4BC & 2 b & \\
& 4 a & SR, SRD-T5BC \\
& \(3 a 1 \mathrm{~b}\) & \\
\hline UT-AX11BC & 2 a 2 b & \\
\hline
\end{tabular}

\section*{Application}

Although all terminals are for the insertion wiring, it is also possible to wire using open-tip crimp lugs. (Ring crimp lugs can also be wired.)
To comply with DIN EN 50274/VDE 0660 Teil 514 finger safe specifications, be sure to completely cover the entire crimp portion of the crimp lug with an insulating sleeve.
\begin{tabular}{|c|c|c|c|}
\hline \multirow{6}{*}{} & Item & Reference Page & Remarks \\
\hline & - Operation Coil & Page 43 & Same as SR-■. \\
\hline & - Rating & Pages 160, 163 & Same as SR-■. \\
\hline & - Properties & Page 164 & Same as SR-■. \\
\hline & - How to Order & Page 177 & - \\
\hline & - Combining with Optional Units & Page 196 & - \\
\hline
\end{tabular}

\section*{6 \\ MS-T Series Contactor Type Contactor Relays}

Outline Drawings


SRD-T9BC

*1 Dimension: Width Dimension from Center of IEC 35 mm Rail

\subsection*{6.10 SR-T \(\square\) SQ, SRD-T \(\square\) SQ Contactor Relays with Spring Clamp Terminals}

Just insert solid wires or ferrules into terminals. No terminal screws are required, which makes wiring quicker and easier.

\section*{- Shorter Wiring Time}

Wiring time becomes shorter than the time required for tightening screws. No worry about loss of screws.
Solid wires, stranded wires, and ferrules can be connected to the terminals.
- Easier Maintenance

No worry about loose screws. Conventionally, terminal screws come loose due to vibrations, impacts, or long-time use, and must be tightened when products come in or during inspection.
- Manufacturing Range List
\begin{tabular}{l|c|c|c}
\hline Frame & Model Name & Auxiliary Contact & Terminal \\
\hline \multirow{2}{*}{ T5 } & SR-T5SQ & 5a, 4a1b & Spring Clamp Terminals \\
\hline
\end{tabular}


SR-T5SQ
\begin{tabular}{|c|c|c|c|}
\hline \multirow{8}{*}{Related Reference Page} & Item & Reference Page & Remarks \\
\hline & - Rating & Pages 160, 163 & - \\
\hline & - Operation Coil & Page 43 & - \\
\hline & - Properties & Page 166 & - \\
\hline & - Contact Arrangement/Contact Placement & Page 164 & \\
\hline & - Applicable wires & Page 68 & - \\
\hline & - How to Order & Page 177 & - \\
\hline & - Combining with Optional Units & Page 196 & Devices such as coil surge absorbers and manual operation prevention covers can be installed. \\
\hline
\end{tabular}

\section*{6 \\ MS-T Series Contactor Type Contactor Relays}

Outline Drawings


\subsection*{6.11 How to Order}

Follow the steps below when ordering. (Enter a space in \(\mathbf{\Delta}\).)

SR, SRD-T(BC) Contactor Relays
\begin{tabular}{|c|c|c|c|c|}
\hline Model Name & \multirow[b]{3}{*}{4} & Operation Coil Designation & \multirow[b]{3}{*}{\(\triangle\)} & Contact Arrangement \\
\hline SR-T5 & & AC200V & & 3A2B \\
\hline SRD-T5 & & DC100V & & 4 A 1 B \\
\hline Specify from pages 163 and 166. & & Select the coil designation from page 43 or specify the control circuit voltage and frequency used. & & Specify the contact arrangement described on pages 160, 168, 169 and 171. \\
\hline
\end{tabular}

SRL, SRLD-T(BC) Contactor Relays
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline Model Name & & Closing Control Coil & \multicolumn{2}{|l|}{\multirow[t]{3}{*}{Tripping Control Coil
M MT-DC100V
^ MT-DC100V}} & \multirow{4}{*}{-} & Contact Arrangement \\
\hline SRL-T5BC & & MC-AC200V & & & & 3 A 2 B \\
\hline SRLD-T5BC & \multirow[t]{2}{*}{\(\triangle\)} & MC-DC100V & & & & 3A2B \\
\hline Specify from page 168. & & Specify the closing (MC) designation (or coil volt ratings on pages 44 and & & pping (MT) operation coil frequency) from the & & Specify a (valid) contact arrangement from page 169. \\
\hline
\end{tabular}

SR, SRD-T \(\square\) SQ Contactor Relays


SR-T \(\square\) DL Delay Open Contactor Relays


Operation Coil Designation
\(\Delta\) The operation coil
designation is available
in AC100V and AC200V.
-
Contact Arrangement

Specify from the contact arrangement on page 172.

MEMO
MS-K Series Contactor Type Contactor Relays
7.1 Model List ..... 180
7.2 Selection and Application ..... 181
7.3 Standard Type (AC Operated) Contactor Relays SR-K100 ..... 182
7.4 DC Operated Contactor Relays SRD-K100 ..... 185
7.5 Mechanically Latched Contactor Relays SRL-K100, SRLD-K100 ..... 186
7.6 Contactor Relays with Large Rated Auxiliary Contacts SR/SRD-K100JH ..... 188
7.7 Contactor Relays with Overlap Contacts SR/SRD-K100LC ..... 189
7.8 How to Order ..... 190

\section*{MS-K Series Contactor Type Contactor Relays}

\subsection*{7.1 Model List}


Note 1. © indicates standard, O indicates semi-standard and - indicates products outside production range.
Note 2. Refer to the individual ratings chart for the contact ratings of large rated auxiliary contacts and overlap contacts. The value in parentheses indicates that when switching a 2 -pole load in series.
Note 3. For the mechanically latched type (SRL-K100, SRLD-K100), 1 piece can be mounted on each closing coil and tripping coil. Note 4. The coil terminal of the contactor relay does not allow the attachment of both the surge absorber and DC/AC interface unit.

\subsection*{7.2 Selection and Application}
- Type Designations


Function and Operation Classification by Application Type
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline Model Name & Operation Category & Application & Reference Page & Model Name & Operation Category & Application & Reference Page \\
\hline SRD-K100 & DC & General control circuit sequence relay for magnetic contactor command contacts etc & Page 185 & \[
\begin{aligned}
& \text { SR-K100LC } \\
& \text { SRD-K100LC }
\end{aligned}
\] & \[
\begin{aligned}
& \mathrm{AC} \\
& \mathrm{DC}
\end{aligned}
\] & Applications that require the overlap switching of the make and break contacts & Page 189 \\
\hline \[
\begin{aligned}
& \text { SRL-K100 } \\
& \text { SRLD-K100 }
\end{aligned}
\] & \[
\begin{aligned}
& \mathrm{AC} \\
& \mathrm{DC}
\end{aligned}
\] & Same applications as SR and SRD types and also those requiring memory functionality & Page 186 & & & & \\
\hline SR-K100JH SRD-K100JH & \[
\begin{aligned}
& \mathrm{AC} \\
& \mathrm{DC}
\end{aligned}
\] & AC100 to \(220 \mathrm{~V}, 3\) to 10 A control of large breakers and solenoids & Page 188 & & & & \\
\hline
\end{tabular}

Application by Contact Voltage, Current, Electrical Durability and Contact Reliability
For applications requiring greater contact reliability than indicated in Figs. 1 to 2, parallel contact connections (redundancy) are required. The reliability of the contacts decreases for contacts connected in series.

- Note 1. The contact reliability indicates a \(60 \%\) confidence rate for a \(\lambda 60\) failure rate (no. of faults/times switching, no. of contacts)
\begin{tabular}{|c|c|c|c|}
\hline \multirow{6}{*}{Related Reference Page
\(\qquad\)} & Item & Reference Page & Remarks \\
\hline & - Working Environment & Page 64 & - \\
\hline & - Mounting & Page 64 & - \\
\hline & - Wiring & Page 68 & - \\
\hline & - Control Circuit Power Supply Voltage Fluctuation Range & Page 71 & - \\
\hline & - Applicable Wire Size and Terminal Screw Tightening Torque & Page 67 & - \\
\hline
\end{tabular}

\section*{MS-K Series Contactor Type Contactor Relays}

\subsection*{7.3 SR-K100 Standard Type (AC Operated) Contactor Relays \\ - Features}
- Rail mounting is fully adopted IEC 35 mm rail mounting mechanism that dramatically reduces assembly time has been fully adopted.
- High contact reliability The full adoption of twin contacts improves the contact reliability.


Ratings (SR, SRD-K100/SRL, SRLD-K100)
\begin{tabular}{|c|c|c|c|c|}
\hline \multicolumn{4}{|c|}{Frame} & K100 Note 7 \\
\hline \multicolumn{4}{|c|}{\multirow{3}{*}{Contact Arrangement}} & 10a, 9a1b (9a, 8a1b) \\
\hline & & & & 8a2b, 7a3b (7a2b, 6a3b) \\
\hline & & & & 6a4b, 5a5b (5a4b, 4a5b) \\
\hline \multirow{18}{*}{} & \multicolumn{3}{|l|}{Rated Insulation Voltage [V]} & 660 \\
\hline & \multicolumn{3}{|l|}{Conventional Free Air Thermal Current Ith [A]} & 16 \\
\hline & \multirow[t]{8}{*}{} & \multirow{4}{*}{Category AC-15 (Coil Load)} & AC110 V & 6 \\
\hline & & & AC220 V & 5 \\
\hline & & & AC440 V & 3 \\
\hline & & & AC550 V & 3 \\
\hline & & \multirow{4}{*}{\begin{tabular}{l}
Category AC-12 \\
(Resistive Load)
\end{tabular}} & AC110 V & 16 \\
\hline & & & AC220 V & 12 \\
\hline & & & AC440 V & 5 \\
\hline & & & AC550 V & 5 \\
\hline & \multirow[t]{8}{*}{} & \multirow{4}{*}{Category DC-13 (Coil Load)} & DC24 V & 5 \\
\hline & & & DC48 V & 3 \\
\hline & & & DC110 V & 0.8 (2) \\
\hline & & & DC220 V & 0.2 (0.8) \\
\hline & & \multirow{4}{*}{Category DC-12 (Resistive Load)} & DC24 V & 10 \\
\hline & & & DC48 V & 8 \\
\hline & & & DC110 V & 5 (8) \\
\hline & & & DC220 V & 1 (3) \\
\hline
\end{tabular}
- Easy wiring Uses self-lifting terminal screws that can reliably tighten wires, ring crimp lugs and square-tip crimp lugs.
- Clearly visible coil rating
- The make and break contacts can be used in different voltages
Strengthened insulation between poles and between upper and lower contacts of the same pole.

Note 1. JIS C8201-5-1 classifications are class AC-15 applicable to AC solenoid and class DC-13 applicable to DC solenoid switching. JIS C8201-5-1 classifications are class AC-12 applicable to AC resistive load switching and class DC-12 applicable to DC resistive load switching.
Note 2. The value in parentheses for the DC rated operational current indicates the rated operating current when switching a 2-pole load in series.
Note 3. The making and breaking capacities are 10 times with AC-15 and 1.1 times with DC-13.
Note 4. Electrical durability of 500,000 operations. (Class AC-15 at 220 V 3 A is 1 million operations, or 5 million operations at 1 A.)
Note 5. The minimum opereting voltage and current differ depending on the allowable fault rate. Refer to Figure 1 and 2 on page 181 for details.
Note 6. The withstand voltage is AC2500 V for 1 minute.
Note 7. The contact arrangement for latched SRL-K100 and SRLD-K100 types is shown in parentheses.

\section*{Performance (SR, SRD-K100/SRL, SRLD-K100)}
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Frame} & \multicolumn{4}{|c|}{Making and Breaking Capacities} & \multirow[t]{2}{*}{\begin{tabular}{l}
Switching \\
Frequency
\end{tabular}} & \multicolumn{2}{|l|}{Switching Durability} \\
\hline & Category & Rated Operational Voltage & Making Current [ \(A\) ] & Breaking Current [ A ] & & Electrical & Mechanical \\
\hline \multirow{8}{*}{K100} & & AC110V & 66 & 66 & \multirow{8}{*}{1800 Times/Hour \(\left[\begin{array}{l}\text { Standard Type } \\ \text { DC Operated Type }\end{array}\right]\) 1200 Times/Hour [Mechanically Latched Type]} & \multirow{8}{*}{\begin{tabular}{cr} 
Class AC-15 (AC Coil Load) \\
220 V 5 A, & 0.5 mil. times \\
220 V 3 A, & 1 mil. times \\
440 V 3 A, & 0.5 mil. times \\
Class DC-13 (DC Coil Load) \\
110 V 0.8 A, & 0.5 mil. times \\
220 V 0.2 A, & 0.5 mil. times
\end{tabular}} & \multirow{8}{*}{\begin{tabular}{l}
10 mil. times \\
[Standard Type, DC \\
Operated Type] \\
1 mil. times \\
[Mechanically \\
Latched Type]
\end{tabular}} \\
\hline & AC-15 & AC220V & 55 & 55 & & & \\
\hline & & AC550V & 33 & 33 & & & \\
\hline & & & & & & & \\
\hline & & DC24V & 20 & 20 & & & \\
\hline & DC-13 & DC48V & 10 & 10 & & & \\
\hline & DC-13 & DC110V & 2(5) & 2(5) & & & \\
\hline & & DC220V & 0.4(1.5) & 0.4(1.5) & & & \\
\hline
\end{tabular}

Note 1. The DC values in parentheses are the making and breaking capacities when using 2-poles in series.
Note 2. Making current capacity tests are performed 100 times, while breaking current capacity tests are performed 25 times.

\section*{Properties (SR, SR-K100JH)}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Frame} & \multicolumn{2}{|l|}{Coil Input [VA]} & \multirow[b]{2}{*}{Coil Power Consumption [W]} & \multirow[b]{2}{*}{Contact Arrangement} & \multicolumn{2}{|l|}{Operating Voltage [V]} & \multicolumn{4}{|c|}{Operating Time [ms]} \\
\hline & Inrush & Normal & & & Close & Open & \begin{tabular}{l}
\[
\text { Coil ON } \rightarrow
\] \\
Make \\
Contact ON
\end{tabular} & \begin{tabular}{l}
\[
\text { Coil ON } \rightarrow
\] \\
Break \\
Contact OFF
\end{tabular} & \begin{tabular}{l}
\[
\text { Coil OFF } \rightarrow
\] \\
Make \\
Contact OFF
\end{tabular} & \begin{tabular}{l}
\[
\text { Coil OFF } \rightarrow
\] \\
Break \\
Contact ON
\end{tabular} \\
\hline & & & & 10a & 125 to 156 & 85 to 120 & 9 to 17 & - & 4 to 13 & - \\
\hline & & & & 5a5b & 120 to 153 & 87 to 123 & 9 to 17 & 7 to 14 & 4 to 12 & 5 to 14 \\
\hline
\end{tabular}

Note 1. The above indicates rough property indices for AC200V coils.
Note 2. The operating voltage is that at a \(20^{\circ} \mathrm{C}\) cold state at 60 Hz . Voltages for coils other than AC 200 V can be calculated proportionately. Note 3. The input and power consumption are average values. These are almost the same for coils other than AC200V.
Note 4. The operating time is the value when applying 200 V at 60 Hz . These are almost the same for coils other than AC200V. Make contacts and break contacts cannot be overlapped in time.
\begin{tabular}{|l|l|c|c}
\hline \begin{tabular}{c} 
Related \\
Reference Page
\end{tabular} & \multicolumn{1}{|c|}{ Item } & Reference Page & Remarks \\
\cline { 2 - 4 } & •Operation Coil & Page 43 & - \\
\hline •How to Order & Page 190 & - \\
\hline
\end{tabular}

\section*{MS-K Series Contactor Type Contactor Relays}

Contact Arrangement/Contact Placement


Outline Drawings

- mark indicates that it can be mounted on IEC 35 mm rails.

\subsection*{7.4 SRD-K100 DC Operated Contactor Relays}

\section*{Features}
- IEC 35 mm rail mounting is adopted
- High contact reliability The adoption of twin contacts improves the contact reliability.
- Excellent operational reliability and high frequency switching capacity Uses a DC full-applied voltage type solenoid.

- No buzzing sound
- No coil inrush current The coil doesn't use saving resistance so there is no inrush current.

\section*{- Properties (SRD, SRD-K100JH)}
\begin{tabular}{c|c|c|c|c|c|c|c|c|c}
\hline \multirow{2}{*}{ Frame } & \multicolumn{3}{|c|}{ Coil } & \multicolumn{2}{c|}{ Operating Voltage [V] } & \multicolumn{3}{c}{ Operating Time [ms] } \\
\cline { 2 - 11 } & \begin{tabular}{c} 
Current \\
{\([\mathrm{A}]\)}
\end{tabular} & \begin{tabular}{c} 
Power \\
Consumption \((\mathrm{M})\)
\end{tabular} & \begin{tabular}{c} 
Time \\
Constant \([\mathrm{ms}]\)
\end{tabular} & Close & Open & \begin{tabular}{l} 
Coil ON \(\rightarrow\) \\
Make Contact ON
\end{tabular} & \begin{tabular}{l} 
Coil ON \(\rightarrow\) \\
Break Contact OFF
\end{tabular} & \begin{tabular}{l} 
Coil OFF \(\rightarrow\) \\
Make Contact OFF
\end{tabular} & \begin{tabular}{l} 
Coil OFF \(\rightarrow\) \\
Break Contact ON
\end{tabular} \\
\hline K100 & 0.067 & 7 & 40 & 52 to 70 & 12 to 30 & 40 to 63 & 37 to 53 & 7 to 15 & 11 to 20 \\
\hline
\end{tabular}

Note 1. The above indicates rough property indices for DC100V coils.
Note 2. The operating voltage is that at a \(40^{\circ} \mathrm{C}\) cold state. Voltages for coils other than DC100V can be calculated proportionately.
Note 3. The power consumption and coil time constant are average values. These are almost the same for coils other than DC100V.
Note 4. The coil current value is the average of the current when DC100V is applied to the coil. For coils other than DC100V coils, obtain the coil current value by dividing the power consumption by the coil voltage.
E.g.: For DC24V coils, the coil current value \(\approx 7 \mathrm{~W} \div 24 \mathrm{~V}\)

Note 5. The operating time is the value when applying DC100V (with 5\% or less ripple). These are almost the same for coils other than DC100V. Make contacts and break contacts cannot be overlapped in time.
\begin{tabular}{|c|c|c|c|}
\hline \multirow{7}{*}{} & Item & Reference Page & Remarks \\
\hline & - Operation Coil & Page 44 & - \\
\hline & - Rating & Pages 180, 182 & - \\
\hline & - Performance & Page 183 & - \\
\hline & - Contact Arrangement/Contact Placement & Page 184 & - \\
\hline & - How to Order & Page 190 & - \\
\hline & - Combining with Optional Units & Page 196 & - \\
\hline
\end{tabular}

\section*{Outline Drawings}


\section*{MS-K Series Contactor Type Contactor Relays}

\subsection*{7.5 SRL-K100, SRLD-K100 Mechanically Latched Contactor Relays}

SRL is SR with a mechanical latch mechanism attached at the top. Simply energizing the closing coil for approximately 0.5 seconds causes mechanical retention in the closed state, tripping only when the tripping coil is energized. Closing coils are available as SRL AC operated types or SRLD DC operated types. These are sometimes called keep relays or momentary energizing relays.

\section*{Features}
- Can be used as a memory relay The mechanical retention prevents opening due to power failures or voltage drops.
- Reduced coil power consumption The constant power consumption of the solenoid of the operation coil can be reduced.
- Allows manual closing
- Allows manual tripping


SRL-K100
- No buzzing sound
- Stable operation

The self-demagnetizing break contact of the closing coil has been built into the latch mechanism.
- High contact reliability The adoption of twin contacts improves the contact reliability.
- IEC 35 mm rail mounting is fully adopted

\section*{Performance}
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline ClosingCor & Model & Top & Closing Coilsar & Contact Arrangement & Switching Frequency & Swid & ) \\
\hline Operation Category & Name & Demagnetizing & Demagnetizing & (Valid) & [Times/Hour] & Electrical & Mechanical \\
\hline AC Operated & SRL-K100 & \multirow[t]{2}{*}{Incl.} & \multirow[t]{2}{*}{Incl.} & \multirow[t]{2}{*}{9a, 8a1b, 7a2b, 6a3b, 5a4b, 4a5b} & \multirow[t]{2}{*}{1200} & \multirow[t]{2}{*}{50} & \multirow[t]{2}{*}{100} \\
\hline DC Operated & SRLD-K100 & & & & & & \\
\hline
\end{tabular}

\section*{Properties}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{\multirow[b]{2}{*}{Frame}} & \multirow[t]{2}{*}{Operation Coil Input [VA]} & \multirow[b]{2}{*}{Contact Arrangement} & \multicolumn{2}{|l|}{Operating Voltage [V]} & \multicolumn{4}{|c|}{Operating Time [ms]} \\
\hline & & & & Close & Trip & Closing Coil \(\mathrm{ON} \rightarrow\) Make Contact ON & Closing Coil \(\mathrm{ON} \rightarrow\) Break Contact OFF & \begin{tabular}{l}
Tripping Coil ON \(\rightarrow\) \\
Make Contact OFF
\end{tabular} & \begin{tabular}{l}
Tripping Coil \(\mathrm{ON} \rightarrow\) \\
Break Contact ON
\end{tabular} \\
\hline \multirow[t]{2}{*}{} & \multirow[t]{2}{*}{SRL-K100} & \multirow[t]{2}{*}{\[
\begin{array}{|lr}
\hline \text { Closing } & 100 \\
\text { Tripping } & 90
\end{array}
\]} & 8a1b & 115 to 156 & 68 to 110 & 8 to 16 & 6 to 15 & 10 to 18 & 11 to 20 \\
\hline & & & 4a5b & 115 to 155 & 70 to 115 & 8 to 16 & 6 to 15 & 10 to 18 & 11 to 20 \\
\hline \multirow[t]{2}{*}{} & \multirow[b]{2}{*}{SRLD-K100} & \multirow[t]{2}{*}{\(\begin{array}{lr}\text { Closing } & 90 \\ \text { Tripping } 100\end{array}\)} & 8a1b & 50 to 80 & 35 to 75 & 10 to 18 & 10 to 19 & 10 to 18 & 10 to 19 \\
\hline & & & 4a5b & 45 to 80 & 35 to 80 & 10 to 20 & 10 to 19 & 10 to 18 & 10 to 19 \\
\hline
\end{tabular}

Note 1. The above indicates rough property indices for AC200 V coils under AC operation (SRL-K100) and for DC100 V coils under DC operation (SRLD-K100).
Note 2. The operating voltage is the value at a \(20^{\circ} \mathrm{C}\) cold state for both AC (at 60 Hz ) and DC operation. Voltages for coils other than AC200V or DC100V can be calculated proportionately.
Note 3. The coil input indicates the average value. These are almost the same for coils other than AC200V or DC100V.
Note 4. The drive time is the time taken from when the closing coil or tripping coil is excited until the contact transitions (ON or OFF) when \(200 \mathrm{~V}, 60 \mathrm{~Hz}\) is applied for AC operation or DC100V is applied for DC operation. These are almost the same for coils other than AC200V or DC100V.
Make contacts and break contacts cannot be overlapped in time.
Note 5. The closing coil and tripping coil have the 15 -second rating.
Operation Coil Rating (SRL, SRLD-K100)
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multicolumn{4}{|c|}{For AC} & \multicolumn{3}{|c|}{For DC} \\
\hline \multirow[t]{2}{*}{Coil Designation} & \multicolumn{2}{|c|}{Rated Voltage [V]} & \multirow[t]{2}{*}{Coil Indicator} & Coil & Rated Voltage & \multirow[t]{2}{*}{Coil Indicator} \\
\hline & 50 Hz & 60 Hz & & Designation & Rated Voltage & \\
\hline AC24V & 24 & 24 & \multirow[b]{7}{*}{Rated Voltage/ Frequency} & DC12V & DC12 V & \multirow{6}{*}{Rated Voltage} \\
\hline AC48V & 48 to 50 & 48 to 50 & & DC24V & DC24 V & \\
\hline AC100V & 100 & 100 to 110 & & DC48V & DC48 V & \\
\hline AC120V & 110 to 120 & 115 to 120 & & DC100V & DC100V to 110 V & \\
\hline AC200V & 200 & 200 to 220 & & DC125V & DC120V to 125 V & \\
\hline AC220V & 208 to 220 & 220 & & DC200V & DC200V to 220 V & \\
\hline AC260V & 240 to 260 & 260 to 280 & & & & \\
\hline
\end{tabular}

Note 1. DC coils have no polarity.

Contact Arrangement/Contact Placement


\section*{Outline Drawings}


\section*{MS-K Series Contactor Type Contactor Relays}

\subsection*{7.6 SR/SRD-K100JH Contactor Relays with Large Rated Auxiliary Contacts}

SR- \(\square\) JH type uses S-N11, S-N12 magnetic contactor contacts to be suitable for applications requiring use of comparatively large currents and great electrical durability.

Rating
\begin{tabular}{|c|c|c|c|c|}
\hline \multicolumn{4}{|c|}{Model Name} & \[
\begin{aligned}
& \hline \text { SR-K100JH } \\
& \text { SRD-K100JH }
\end{aligned}
\] \\
\hline \multicolumn{4}{|c|}{\multirow{3}{*}{Contact Arrangement}} & 10a, 9a1b \\
\hline & & & & 8a2b, 7a3b \\
\hline & & & & 6a4b, 5a5b \\
\hline \multicolumn{4}{|r|}{Rated Insulation Voltage [V]} & 660 \\
\hline \multirow{5}{*}{0
.0
0
0
0
\(\overleftarrow{0}\)
0
0
0
0
0} & \multicolumn{3}{|l|}{Conventional Free Air Thermal Current Ith [A]} & 20 \\
\hline & \multirow[t]{2}{*}{} & Category AC-15 (Coil Load) & \[
\begin{aligned}
& \hline \mathrm{AC} 110 \mathrm{~V} \\
& \mathrm{AC} 220 \mathrm{~V} \\
& \mathrm{AC} 440 \mathrm{~V} \\
& \mathrm{AC} 550 \mathrm{~V}
\end{aligned}
\] & \[
\begin{gathered}
10(6) \\
10(5) \\
5(3) \\
4(3)
\end{gathered}
\] \\
\hline & & \begin{tabular}{l}
Category AC-12 \\
(Resistive Load)
\end{tabular} & \[
\begin{aligned}
& \text { AC110 V } \\
& \text { AC220 V } \\
& \text { AC440 V } \\
& \text { AC550 V }
\end{aligned}
\] & \[
\begin{aligned}
& 20 \\
& 16 \\
& 10 \\
& 10
\end{aligned}
\] \\
\hline & \multirow[t]{2}{*}{} & Category DC-13 (Coil Load) & \[
\begin{aligned}
& \hline \text { DC24 V } \\
& \text { DC48 V } \\
& \text { DC110 V } \\
& \text { DC220 V }
\end{aligned}
\] & \[
\begin{gathered}
5 \\
3 \\
0.8 \\
0.2
\end{gathered}
\] \\
\hline & & Category DC-12 (Resistive Load) & \[
\begin{aligned}
& \text { DC24 V } \\
& \text { DC48 V } \\
& \text { DC110 V } \\
& \text { DC220 V }
\end{aligned}
\] & \[
\begin{gathered}
10 \\
8 \\
5 \\
1
\end{gathered}
\] \\
\hline
\end{tabular}

Note 1. Electrical durability of 500,000 operations.
Note 2. The value in parentheses for the AC rated operational current indicates the rated operating current when using different voltages.
Note 3. The minimum operating voltage and current differ depending on the allowable fault rate. Select from Figure 2 on page 181.
\begin{tabular}{|c|c|c|c|}
\hline \multirow{7}{*}{} & Item & Reference Page & Remarks \\
\hline & - Operation Coil & Pages 43, 44 & Same as SR- \(\square\) and SRD- \(\square\). \\
\hline & - Properties & Pages 183, 185 & Same as SR- \(\square\) and SRD- \(\square\). \\
\hline & - Contact Arrangement/Contact Placement & Page 184 & Same as SR- \(\square\) and SRD- \(\square\). \\
\hline & - Outline Drawings & Pages 184, 185 & Same as SR- \(\square\) and SRD- \(\square\). \\
\hline & - How to Order & Page 190 & - \\
\hline & - Combining with Optional Units & Page 196 & - \\
\hline
\end{tabular}

\subsection*{7.7 SR/SRD-K100LC Contactor Relays with Overlap Contacts}

SR- \(\square L C\) types with overlap contacts overlap operation by turning the break contact OFF after the make contact turns ON.

\section*{- Rating (SR, SRD)}
\begin{tabular}{|c|c|c|c|c|}
\hline \multicolumn{4}{|c|}{Model Name} & K100LC \\
\hline \multicolumn{4}{|c|}{\multirow[b]{2}{*}{Contact Arrangement}} & 8a2b \\
\hline & & & & 6a4b, 5a5b \\
\hline \multicolumn{4}{|r|}{Rated Insulation Voltage [V]} & 600 \\
\hline \multicolumn{4}{|r|}{Conventional Free Air Thermal Current lth [A]} & 16 \\
\hline \multirow{16}{*}{} & \multirow[t]{8}{*}{} & & AC110 V & 6 \\
\hline & & Category AC-15 & AC220 V & 5 \\
\hline & & (Coil Load) & AC440 V & 3 \\
\hline & & & AC550 V & 3 \\
\hline & & \multirow{4}{*}{\begin{tabular}{l}
Category AC-12 \\
(Resistive Load)
\end{tabular}} & AC110 V & 16 \\
\hline & & & AC220 V & 12 \\
\hline & & & AC440 V & 5 \\
\hline & & & AC550 V & 5 \\
\hline & \multirow[t]{8}{*}{} & \multirow{4}{*}{Category DC-13 (Coil Load)} & DC24 V & 3 \\
\hline & & & DC48 V & 2 \\
\hline & & & DC110 V & 0.5 \\
\hline & & & DC220 V & 0.1 \\
\hline & & \multirow{4}{*}{Category DC-12 (Resistive Load)} & DC24 V & 8 \\
\hline & & & DC48 V & 5 \\
\hline & & & DC110 V & 3 \\
\hline & & & DC220 V & 0.5 \\
\hline
\end{tabular}

Note 1. The AC rated operational current for the make contact is shown in the table above.
The break contact rated making current is 20 A and the rated breaking current AC 24 to 550 V 3 A . (However, \(\mathrm{COS} \varphi=0.3\) to 1.0)
Note 2. The contacts may wear out through current switching and may not overlap. Take sufficient precautions.

\section*{Contact Arrangement/Contact Placement}
\begin{tabular}{|c|c|c|}
\hline \multicolumn{3}{|c|}{\[
\begin{aligned}
& \hline \text { SR-K100LC } \\
& \text { SRD-K100LC }
\end{aligned}
\]} \\
\hline 8a2b & 6a4b & 5a5b \\
\hline  &  &  \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|}
\hline \multirow{6}{*}{Related Reference Page} & Item & Reference Page & Remarks \\
\hline & Operation Coil & Pages 43, 44 & Same as SR- \(\square\) and SRD-■. \\
\hline & - Properties & Pages 183, 185 & Same as SR- \(\square\) and SRD- \(\square\). However, break contact operating times differ. \\
\hline & - Outline Drawings & Pages 184, 185 & Same as SR- \(\square\) and SRD- \(\square\). \\
\hline & - How to Order & Page 190 & - \\
\hline & - Combining with Optional Units & Page 196 & Auxiliary contact units and front clip-on timer units cannot be combined together. \\
\hline
\end{tabular}

\section*{MS-K Series Contactor Type Contactor Relays}

\subsection*{7.8 How to Order}

Follow the steps below when ordering. (Enter a space in \(\mathbf{\Delta}\).)
SR, SRD-K Type Contactor Relays
\begin{tabular}{|c|c|c|c|c|}
\hline Model Name & \multirow[b]{2}{*}{\(\triangle\)} & Operation Coil and Designation & \multirow[b]{2}{*}{\(\triangle\)} & Contact Arrangement \\
\hline SR-K100 & & AC200V & & 5A1B \\
\hline SRD-K100 & \(\triangle\) & DC100V & \(\pm\) & 5A5B \\
\hline Specify from pages 180 and 181. & & Select the operation coil designation (or coil voltage and frequency) from the ratings on pages 43 and 44. & & Specify from the contact arrangement on page 184. \\
\hline
\end{tabular}

SRL, SRLD-K Type Mechanically Latched Contactor Relays


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\section*{8 \\ Optional Units}

\section*{8．1 Model List（for MS－T／N Series）}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline Model Name & \multicolumn{9}{|c|}{Auxiliary Contact Blocks} & Auxiliary Contact Units for Low－level Signals & \\
\hline Type & UT－AX2（BC） & UT－AX4（BC） & UT－AX11（BC） & UN－AX2（CX） & UN－AX4（CX） & UN－AX11（CX） & UN－AX80 & UN－AX150 & UN－AX600 & UN－LL22（CX） & \\
\hline Mounting & \multicolumn{2}{|r|}{Front Clip－on} & Side Clip－on & \multicolumn{2}{|r|}{Front Clip－on} & \multicolumn{4}{|c|}{Side Clip－on} & Front Clip－on & \\
\hline Specification／ Functions & \begin{tabular}{l}
Twin \\
Contact \\
Built－in \\
2－Pole \\
Auxiliary \\
Contact \\
（2a，1a1b， \\
2b）
\end{tabular} & Twin Contact Built－in 4－Pole Auxiliary Contact （4a，2a2b， 3a1b） & Twin Contact Built－in 2－Pole Auxiliary Contact （1a1b） & Twin Contact Built－in 2－Pole Auxiliary Contact （2a，1a1b， 2b） & Twin Contact Built－in 4－Pole Auxiliary Contact （4a，2a2b， 3a1b） &  & Twin
Contact Built－in 2－Pole Auxiliary Contact （1a1b） & Twin Contact Built－in 2－Pole Auxiliary Contact （1a1b） & Twin Contact Built－in 4－Pole Auxiliary Contact （2a2b） & \begin{tabular}{l}
Total 4－Pole Structure Auxiliary Contacts for Low－Level Signal and Twin（Standard）Types \\
For Low－Level Signals 1a1b \\
（ 5 V 5 mA ） \\
Twin Contact \\
1a1b \\
（20 V 5 mA\()\)
\end{tabular} & \\
\hline \begin{tabular}{l}
Appearance \\
（Typical Example）
\end{tabular} & UT－AX2 & UT－AX4 & \begin{tabular}{l}
 \\
UT－AX11
\end{tabular} & UN－AX2 & UN－AX4 & UN－AX11 & UN－AX80 & UN-AX150 & UN－AX600 & UN－LL22 & \\
\hline Other & Cannot be used with UT－AX & d in combination AX11（BC）． & \[
\begin{gathered}
\text { Cannotbe Isedin combination } \\
\text { with UT-AX2or } 4 B C \text { ). }
\end{gathered}
\] & Cannot be used with UN－A & d in combination AX11（CX）． & Cannotbe ssed in combination with UN－AX2， 4 or LL22 2 CX）． & & － & & Cannot be used in combination with UN－AX11（CX）． & \\
\hline Reference Page & & & & & 197 & & & & & 203 & \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline Model Name & \multicolumn{8}{|c|}{DC／AC Interface Units for Operation Coils} & \multicolumn{9}{|c|}{Protection Cover Units} \\
\hline Type & UT－SY21（BC） & UT－SY22（BC） & UN－SY11 & UN－SY12 & UN－SY21（CX） & UN－SY22（CX） & UN－SY31 & UN－SY32 & UN－CV■0 & UN－CZ605 & UN－CZप0 & UN－CZロ2 & UN－CZロ1 & UN－CZロ4 & UT－CVI， UN－CVI & UT－CWD & \\
\hline Mounting & \multicolumn{2}{|l|}{Top－On} & \multicolumn{2}{|l|}{For Independent Mounting} & \multicolumn{4}{|c|}{Top－On} & \multicolumn{9}{|c|}{Front Clip－on} \\
\hline & \multicolumn{8}{|l|}{Enables AC－operated magnetic contactors and relays to be operated at DC24 V} & \multicolumn{6}{|c|}{Live Part Protection Cover} & Misoperation Prevertion Cover & Terminal Cover & \\
\hline Specification／ Functions & \begin{tabular}{l}
Triac Output \\
Input \\
DC24 V \\
15 mA
\end{tabular} & \begin{tabular}{l}
Relay Output \\
Input \\
DC24 V \\
10 mA
\end{tabular} & \begin{tabular}{l}
Triac Output \\
Input \\
DC24 V \\
15 mA
\end{tabular} & \begin{tabular}{l}
Relay Output \\
Input \\
DC24 V \\
10 mA
\end{tabular} & \begin{tabular}{l}
Triac Output \\
Input DC24 V 15 mA
\end{tabular} & \begin{tabular}{l}
Relay Output \\
Input \\
DC24 V \\
10 mA
\end{tabular} & \[
\left.\begin{array}{|l|}
\text { Triac } \\
\text { Output }
\end{array} \right\rvert\,
\] & \begin{tabular}{l}
Relay Output \\
Input \\
DC24 V \\
10 mA
\end{tabular} & \begin{tabular}{l}
For \\
Magnetic Contactors For Contactor Relays
\end{tabular} & For
Therma Overload Relays （TH－T65， TH－N60） & \begin{tabular}{l}
For Magnetic \\
Contactors \\
（Power \\
Supply Side， \\
Load Side） \\
For Magnetic \\
Starters \\
（Power \\
Supply Side）
\end{tabular} & For Reversible Magnetic Contactors & For Magnetic Starters （Load Side） &  & \begin{tabular}{l}
UT－CV107 \\
For Magnetic \\
Contactors／ \\
Contactor \\
Relays \\
UN－CVI3 \\
For Thermal \\
Overload \\
Relays \\
（TH－）
\end{tabular} & \multicolumn{2}{|l|}{\begin{tabular}{|c|}
\hline For Magnetic \\
Contactors \\
For Magnetic \\
Starters \\
For Thermal \\
Overload \\
Relays \\
\hline
\end{tabular}} \\
\hline \begin{tabular}{l}
Appearance \\
（Typical Example）
\end{tabular} & \multicolumn{2}{|l|}{} & \multicolumn{2}{|l|}{UN－SY11} & \multicolumn{2}{|l|}{UN－SY21} & \multicolumn{2}{|l|}{UN－SY32} & UN－CV250 &  & UN－C & CZ500 & UN-C & CZ501 & UN－CV203 & UT－CW800 & \\
\hline Other & \multicolumn{8}{|c|}{－} & \multicolumn{9}{|c|}{－} \\
\hline Reference Page & \multicolumn{8}{|c|}{218} & \multicolumn{7}{|c|}{221} & 227 & \\
\hline
\end{tabular}

Note 1．There are limitations on models，rated voltage and combined use．

- Type Designation Structure

\begin{tabular}{c|c|}
\hline Symbol & Product Name \\
\hline AX & Auxiliary Contact Units \\
\hline LL & \begin{tabular}{c} 
Auxiliary Contact Units with \\
Contact for Low-level Signals
\end{tabular} \\
\hline SA & \begin{tabular}{c} 
For Operation Coils or Main \\
Circuit Surge Absorber Units
\end{tabular} \\
\hline SY & \begin{tabular}{c} 
DC24 V \(\rightarrow\) AC100 to 240 V \\
DC/AC Interface Units for \\
Operation Coils
\end{tabular} \\
\hline CV & \begin{tabular}{c} 
Live Part Protection Covers \\
CZ \\
(Magnetic Starters, Contactor Relays)
\end{tabular} \\
\hline CV & \begin{tabular}{c} 
Misoperation Prevention Covers (Magnetic \\
Contactors, Relays, Thermal Overload Relays)
\end{tabular} \\
\hline
\end{tabular}
\begin{tabular}{|c|c}
\hline Simbol & Product Name \\
\hline ML & Mechanical Interlock Units \\
\hline SD & Reversing Main Circuit Conductor Kits \\
\hline SG & Main Circuit Conductor Kits for Crossover \\
\hline YG & 3-Pole Short Circuit Main Circuit Conductor Kits
\end{tabular}\(|\)\begin{tabular}{|c|c}
\hline YD & 2-Pole Short Circuit Main Circuit Conductor Kits
\end{tabular}

\subsection*{8.2 Applicable Model List}

Those with an \(x\) in the Applicable Models column cannot be combined.
The units that can be used with the spring clamp terminal models are marked with "SQ" in the Applicable Models column.
For the spring clamp terminal models, refer to pages 127 and 175.
Magnetic Starters/Magnetic Contactors
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{3}{*}{Section} & \multirow[b]{3}{*}{Product Name} & \multirow{3}{*}{Model Name} & \multirow[b]{3}{*}{Specifications} & \multirow[b]{3}{*}{See Page} & \multicolumn{6}{|c|}{Applicable Models} \\
\hline & & & & & \multicolumn{6}{|c|}{Magnetic Starters, Magnetic Contactors} \\
\hline & & & & & AC Operated & DC Operated & Latched Type & Enclosed Type (MS-ND) & Delay Open Type (S-NロDL) & With Saturable Reactor (MSO-NDSR) \\
\hline \multirow{9}{*}{1} & \multirow{9}{*}{Auxiliary Contact Units} & UT-AX2 & 2-Pole & \multirow{9}{*}{197} & \multirow{3}{*}{S-T10 to T50} & \multirow{3}{*}{SD-T12 to T50} & \multirow[b]{2}{*}{X} & \multirow{3}{*}{x} & \multirow{3}{*}{X} & \multirow{3}{*}{MSO-T10SR to T50SR} \\
\hline & & UT-AX4 & 4-Pole & & & & & & & \\
\hline & & UT-AX11 & 2-Pole 1A1B & & & & SL(D)-T21 & & & \\
\hline & & UN-AX2 & 2-Pole & & \multirow[t]{2}{*}{\[
\begin{aligned}
& \hline \text { S-T65, T80 } \\
& \text { S-N38, N48 } \\
& \text { DU-N30 }
\end{aligned}
\]} & \multirow[t]{2}{*}{\[
\begin{aligned}
& \text { SD-T65, T80 } \\
& \text { DUD-N30 }
\end{aligned}
\]} & \multirow[b]{2}{*}{X} & \multirow[b]{2}{*}{X} & \multirow[b]{2}{*}{X} & \multirow[b]{2}{*}{MSO-T65SR, T80SR} \\
\hline & & UN-AX4 & 4-Pole & & & & & & & \\
\hline & & UN-AX11 & 2-Pole 1A1B & & S-T65, T80
DU-N30 & \[
\begin{aligned}
& \text { SD-T65, T80 } \\
& \text { DUD-N30 }
\end{aligned}
\] & \[
\begin{aligned}
& \text { SL(D)-T65, } \\
& \text { T80 }
\end{aligned}
\] & x & x & MSO-T65SR, T80SR \\
\hline & & UN-AX80 & 2-Pole 1A1B & & \[
\begin{aligned}
& \text { S-T100, S-N125 } \\
& \text { DU-N6O }
\end{aligned}
\] & \[
\begin{aligned}
& \text { SD-T100, SD-N125 } \\
& \text { DUD-N60 }
\end{aligned}
\] & \[
\begin{aligned}
& \text { SL(D)-T100 } \\
& \text { SL(D)-N125 }
\end{aligned}
\] & x & X & MSO-T100SR MSO-N125SR \\
\hline & & UN-AX150 & 2-Pole 1A1B & & S-N150 to N400 DU-N120, N180, N260 & SD-N150 to N400 DUD-N120, N180, N260 & \[
\begin{aligned}
& \text { SL(D)-N150 to } \\
& \text { N400 }
\end{aligned}
\] & MS-N150 to N400 & S-N150DL to N400DL (Left Side Only) & MSO-N150SR to N400SR \\
\hline & & UN-AX600 & 4-Pole 2A2B & & S-N600, N800 & SD-N600, N800 & SL(D)-N600, N800 & X & X & X \\
\hline 2 & Auxiliary Contact Units with Contact for Low-level Signals & UN-LL22 & \[
\begin{gathered}
\text { 4-Pole 1A1B (Low-Level) } \\
+1 \text { 1A1B } \\
\text { (Standard Contact) } \\
\hline
\end{gathered}
\] & 203 & S-T65, T80 DU-N30 & \[
\begin{aligned}
& \text { SD-T65, T80 } \\
& \text { DUD-N30 }
\end{aligned}
\] & x & x & x & MSO-T65SR to T80SR \\
\hline \multirow{11}{*}{3} & \multirow{11}{*}{Operation Coil Surge Absorber Units} & UT-SA13 & C + R & \multirow{11}{*}{205} & X & \multirow[b]{3}{*}{\[
\left|\begin{array}{|r}
\text { SD-T12 to } \\
\mathrm{BD}-\mathrm{T} 21 \\
\text { SQ }
\end{array}\right|
\]} & SLD-T21 to T50 (Cosing Coil) & X & X & x \\
\hline & & UT-SA21 & Varistor & & \multirow[b]{4}{*}{\[
\begin{array}{|r|}
\hline \text { S-T10 to T50 } \\
\text { B-T21 } \\
\text { S-N38, N48 } \\
\text { SQ } \\
\hline
\end{array}
\]} & & \multirow[t]{2}{*}{SL[D-T21 to 750 (Cosing Coil)} & MS-T10SA to T50SA & X & \multirow{4}{*}{MSO-T10SR to T50SR} \\
\hline & & UT-SA22 & Varistor + Indicator Lamp & & & & & \multirow[b]{3}{*}{x} & X & \\
\hline & & UT-SA23 & C + R & & & x & SL-T21 to 750 (Closing Coii) & & X & \\
\hline & & UT-SA25 & Varistor + CR & & & \begin{tabular}{|lr|}
\hline SD-T12 to T50 \\
BD-T21 & SQ \\
\hline \multicolumn{1}{c|}{\(x\)}
\end{tabular} & SLDO-T2 to 750 (Cosing Coil) & & X & \\
\hline & & UN-SA712 & Varistor + Indicator Lamp & & X & X & SL[0-T21 to 750 (Tipping Coil) & X & X & x \\
\hline & & UN-SA713 & C + R & & X & \multirow{3}{*}{\[
\begin{aligned}
& \text { SD-T65, T80 } \\
& \text { DUD-N30 }
\end{aligned}
\]} & SLD-T21 to 780 (ripping Coil) & X & X & X \\
\hline & & UN-SA721 & Varistor & & X & & SLLD-T21 to 780 (Tipping Coil) & X & X & X \\
\hline & & UN-SA722 & Varistor + Indicator Lamp & & X & & SLLD)-76, 780 (Tippoing Coil) & X & X & X \\
\hline & & UN-SA723 & C + R & & X & X & SLLD)-765, 780 (Tippoing Coil) & \multirow[b]{2}{*}{x} & X & \multirow[b]{2}{*}{X} \\
\hline & & UN-SA725 & Varistor + C + R & & X & \[
\begin{aligned}
& \text { SD-T65, T80 } \\
& \text { DUD-N30 }
\end{aligned}
\] & SLID-21 to 780 (Tipping Coil) & & X & \\
\hline \multirow{3}{*}{4} & \multirow[t]{3}{*}{Main Circuit Surge Absorber Units} & UT-SA3320 & \multirow{3}{*}{\begin{tabular}{l}
\[
C+R
\] \\
Delta Connection
\end{tabular}} & \multirow{3}{*}{212} & S-T10 to T20 & SD-T12, T20 & x & x & S-T12DL & MSO-T10SR to T20SR \\
\hline & & UT-SA3332 & & & S-T21 to T32 & SD-T21, T32 & x & X & S-T21DL & MSO-T21SR to T25SR \\
\hline & & UN-SA33 & & & S-T10 to T100 S-N125 to N800 & \[
\begin{aligned}
& \text { SD-T12 to T100 } \\
& \text { SD-N125 to N800 }
\end{aligned}
\] & \[
\begin{aligned}
& \begin{array}{l}
\text { SL(D)-T21 to T100 } \\
\text { SL(D)-N125 to N800 }
\end{array}
\end{aligned}
\] & MSS-T10 to T100 (Extemal) MS-N125 to N400 Exxerna) & \[
\begin{array}{|l|l|}
\hline \text { S-T12DL to T1000DL } \\
\text { S-N125DL to N400DL }
\end{array}
\] & MSO-TIOSR to T100SR MSO-N125 to N400SR \\
\hline \multirow{8}{*}{5} & \multirow{8}{*}{\begin{tabular}{l}
DC/AC \\
Interface \\
Units for \\
Operation \\
Coils
\end{tabular}} & UT-SY21 & Triac Output & \multirow{8}{*}{218} & S-T10 to T50 & \multirow{8}{*}{X} & \multirow[t]{8}{*}{x} & \multirow{8}{*}{X} & \multirow{8}{*}{x} & MSO-T10SR to T50SR \\
\hline & & UT-SY22 & Contact Output & & B-T21 & & & & & MSO-TIOSR to TJ0SR \\
\hline & & UN-SY11 & Triac Output & & S-T10 to T100 & & & & & \multirow{6}{*}{MSO-N125SR to N40OSR} \\
\hline & & UN-SY12 & Contact Output & & S-N125 to N400 & & & & & \\
\hline & & UN-SY21 & Triac Output & & S-N38, N48 & & & & & \\
\hline & & UN-SY22 & Contact Output & & S-N38, N48 & & & & & \\
\hline & & UN-SY31 & Triac Output & & \multirow[b]{2}{*}{S-T65, T80} & & & & & \\
\hline & & UN-SY32 & Contact Output & & & & & & & \\
\hline
\end{tabular}


Thermal Overload Relays (Including ET-N Electronic Thermal)
\begin{tabular}{|c|c|c|c|c|c|}
\hline Section & Product Name & Model Name & Specifications & \[
\begin{gathered}
\text { See } \\
\text { Page }
\end{gathered}
\] & Applicable Models Thermal Overload Relays \\
\hline \multirow[t]{4}{*}{} & \multirow{4}{*}{Protection Cover (Note 1) Units} & UN-CZ605 & Live Part Protection Cover & \multirow{4}{*}{\[
\begin{aligned}
& 221, \\
& 343
\end{aligned}
\]} & TH-T65 \\
\hline & & UN-CV203 & \multirow[t]{2}{*}{Current Setting Dial Misoperation Prevention Covers} & & TH-T25/T50 \\
\hline & & UN-CV603 (Note 2) & & & \[
\begin{gathered}
\text { TH-T65/T100, } \\
\text { TH-N120 to N600 }
\end{gathered}
\] \\
\hline & & UN-CV602 & Terminal Cover & & ET-N60 \\
\hline \multirow{3}{*}{11} & \multirow{3}{*}{\begin{tabular}{l}
Reset \\
Releases
\end{tabular}} & UT-RRロ5 & \multirow{3}{*}{```
Release Length
    200 mm
        to
    700 mm
```} & \multirow{3}{*}{228} & TH-T18 \\
\hline & & UN-RRワ0 & & & TH-T25/T50 \\
\hline & & UN-RR \(\square 6\) (Note 3) & & & \[
\begin{aligned}
& \text { TH-T65/T100 } \\
& \text { TH-N120 to N600 }
\end{aligned}
\] \\
\hline \multirow{3}{*}{12} & \multirow[b]{3}{*}{Fluorescent Display Lamps} & UN-TL12 & \multirow{3}{*}{Tripping Display} & \multirow{3}{*}{229} & TH-T18 \\
\hline & & UN-TL20 & & & TH-T25, T50 \\
\hline & & UN-TL60 (Note 4) & & & TH-T65, T100 \\
\hline \multirow[b]{2}{*}{13} & \multirow[b]{2}{*}{Independent Mounting Units} & UT-HZ18 & Screw Mounting, EC 35 mm Mounting & \multirow[b]{2}{*}{230} & TH-T18 \\
\hline & & UN-RM20 & \[
\begin{aligned}
& \hline \text { IEC } 35 \mathrm{~mm} \text { Rail } \\
& \text { Mounting } \\
& \hline
\end{aligned}
\] & & TH-T25 \\
\hline
\end{tabular}

Note 1. Protective covers cannot be combined with saturable reactor attached types (TH- \(\square S R\) ).
Note 2. UN-CV603 cannot be combined with TH-N120TAHZ.
Note 3. UN-RR \(\square \square 6\) cannot be combined with TH-N120TAHZ.
Note 4. UN-TL60 cannot be combined with TH-N120TAHZ.

\section*{- Contactor Relays}
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Section} & \multirow{3}{*}{Product Name} & \multirow{3}{*}{Model Name} & \multirow{3}{*}{Specifications} & \multirow{3}{*}{\[
\begin{array}{|c|}
\hline \text { See } \\
\text { Page } \\
\hline
\end{array}
\]} & \multicolumn{3}{|c|}{Applicable Models} \\
\hline & & & & & \multicolumn{3}{|c|}{Contactor Relays} \\
\hline & & & & & AC Operated & DC Operated & Latched Type \\
\hline \multirow{3}{*}{1} & \multirow{3}{*}{Auxiliary Contact Units} & UT-AX2 & 2-Pole & \multirow{3}{*}{197} & \multirow{3}{*}{SR-T5} & \multirow{3}{*}{SRD-T5} & \multirow[b]{2}{*}{x} \\
\hline & & UT-AX4 & 4-Pole & & & & \\
\hline & & UT-AX11 & 2-Pole 1A1B & & & & SRL(D)-T5 \\
\hline \multirow{10}{*}{3} & \multirow{10}{*}{Operation Coil Surge Absorber Units} & UT-SA21 & Varistor & \multirow{10}{*}{205} & \multirow[b]{2}{*}{SR-T5, T9
\(\qquad\)} & \multirow[b]{2}{*}{SRD-T5, T9} & \multirow{5}{*}{SRL(D)-T5 (Closing Coil)} \\
\hline & & UT-SA22 & Varistor + Indicator Lamp & & & & \\
\hline & & UT-SA13 & \(\mathrm{C}+\mathrm{R}\) & & x & SQ & \\
\hline & & UT-SA23 & \(\mathrm{C}+\mathrm{R}\) & & \multirow[b]{2}{*}{SR-T5, T9
\(\qquad\)} & x & \\
\hline & & UT-SA25 & Varistor + CR & & & SRD-T5, T9 SQ & \\
\hline & & UN-SA712 & Varistor + Indicator Lamp & & SR-K100 & \multirow{3}{*}{SRD-K100} & SRL(D)-K100(Closing Coil), SRL(D)-K100(Tripping Coil) SRL(D)-T5(Tripping Coil) \\
\hline & & UN-SA713 & \(C+R\) & & x & & SRLD-K100(Closing Coil), SRLD-K100(Tripping Coil) SRL(D)-T5(Tripping Coil) \\
\hline & & UN-SA721 & Varistor & & SR-K100 & & SRL(D)-K100(Closing Coil), SRL(D)-K100(Tripping Coil) SRL(D)-T5(Tripping Coil) \\
\hline & & UN-SA723 & \(C+R\) & & \multirow[b]{2}{*}{SR-K100} & x & SRL-K100(Closing Coil), SRL-K100(Tripping Coil) SRL(D)-T5(Tripping Coil) \\
\hline & & UN-SA725 & Varistor + C + R & & & SRD-K100 & \[
\begin{aligned}
& \hline \text { SRL(D)-K100(Closing Coil), } \\
& \text { SRL(D)-K100(Tripping Coil) } \\
& \text { SRL(D)-T5(Tripping Coil) }
\end{aligned}
\] \\
\hline \multirow{6}{*}{5} & \multirow{6}{*}{\begin{tabular}{l}
DC/AC Interface Units \\
for Operation Coils
\end{tabular}} & UT-SY21 & Triac Output & \multirow{4}{*}{218} & \multirow[b]{2}{*}{SR-T5, T9} & x & x \\
\hline & & UT-SY22 & Contact Output & & & x & x \\
\hline & & UN-SY11 & Triac Output & & \multirow[t]{2}{*}{\[
\begin{aligned}
& \text { SR-T5, T9 } \\
& \text { SR-K100 }
\end{aligned}
\]} & x & x \\
\hline & & UN-SY12 & Contact Output & & & x & x \\
\hline & & UA-SY21 & Triac Output & \multirow[b]{2}{*}{236} & \multirow[t]{2}{*}{SR-K100} & x & x \\
\hline & & UA-SY22 & Contact Output & & & x & x \\
\hline 6 & Protection Cover Units & UT-CV107 &  & 221 & SR-T5 SQ & SRD-T5 SQ & x \\
\hline 9 & Conductor Kits & UT-YD20 & For 2-Pole Short-Circuit & 216 & SR-T5, T9 & SRD-T5, T9 & SRL(D)-T5, T9 \\
\hline
\end{tabular}

\subsection*{8.3 UT/UN-AX \(\square\) Auxiliary Contact Units}

Auxiliary contacts can be easily expanded from compact relays to large contactors.
All contacts adopt twin contacts, providing high contact reliability.
- Auxiliary contacts can be added to almost all series of contactor relays and magnetic contactors.
- Highly effective for on-site modifications etc., as mounting does not require special tools.
- As both side clip-on and front clip-on types are thin and require less mounting area, they greatly contribute to the miniaturization of panel area.
- The use of twin contacts achieves high contact reliability and allows application for low-level signals.


UN-AX4


\section*{- Type}
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Unit Model Name} & \multirow[t]{2}{*}{Contact Arrangement Per Unit} & \multirow[t]{2}{*}{Unit Mounting Method} & \multicolumn{3}{|l|}{Model Names of Applicable Magnetic Contactors and Contactor Relays} & \multirow[t]{2}{*}{Total Number of Units That Can Be Added to Non-Reversible Type} \\
\hline & & & AC Operated & DC Operated & Mechanically Latched Type & \\
\hline \multirow[t]{3}{*}{UT-AX2 UT-AX2BC} & 2a & \multirow{3}{*}{Front Clip-on} & \multirow{7}{*}{\[
\begin{aligned}
& \text { S-T10 to T50 } \\
& \text { SR-T5 }
\end{aligned}
\]} & \multirow{7}{*}{\[
\begin{gathered}
\text { SD-T12 to T50, } \\
\text { SRD-T5 }
\end{gathered}
\]} & \multirow{4}{*}{-} & \multirow{4}{*}{1} \\
\hline & 1a1b & & & & & \\
\hline & 2b & & & & & \\
\hline \multirow[t]{3}{*}{UT-AX4 UT-AX4BC} & 4a & \multirow{3}{*}{Front Clip-on} & & & & \\
\hline & 3 a 1 b & & & & - & 1 \\
\hline & 2a2b & & & & & 1 \\
\hline \[
\begin{aligned}
& \text { UT-AX11 } \\
& \text { UT-AX11BC } \\
& \hline
\end{aligned}
\] & 1a1b & Side Clip-on & & & \[
\begin{gathered}
\hline \text { SL(D)-T21,T35,T50 } \\
\text { SRL(D)-T5 } \\
\hline
\end{gathered}
\] & 2(Note 2) \\
\hline \multirow[t]{3}{*}{UN-AX2 UN-AX2CX} & 2a & \multirow{3}{*}{Front Clip-on} & \multirow[b]{5}{*}{\[
\begin{aligned}
& \text { S-T65, T80 } \\
& \text { S-N38, N48 } \\
& \text { DU-N30 }
\end{aligned}
\]} & \multirow[b]{4}{*}{\[
\begin{aligned}
& \text { SD-T65, T80 } \\
& \text { DUD-N30 }
\end{aligned}
\]} & \multirow[t]{3}{*}{-} & \multirow{3}{*}{1} \\
\hline & 1a1b & & & & & \\
\hline & 2b & & & & & \\
\hline \multirow{3}{*}{\[
\begin{aligned}
& \text { UN-AX4 } \\
& \text { UN-AX4CX }
\end{aligned}
\]} & 4a & \multirow{3}{*}{Front Clip-on} & & & \multirow[b]{3}{*}{-} & \multirow{3}{*}{1} \\
\hline & \(3 \mathrm{a1b}\) & & & & & \\
\hline & 2a2b & & (Note 6) & (Note 6) & & \\
\hline \[
\begin{aligned}
& \hline \text { UN-AX11 } \\
& \text { UN-AX11CX }
\end{aligned}
\] & 1a1b & Side Clip-on & S-T65, T80
DU-N30 (Note 6) & SD-T65, T80
DUD-N30 (Note 6) & \[
\begin{array}{r}
\hline \mathrm{SL}(\mathrm{D})-\mathrm{T} 65, \mathrm{~T} 80 \\
(\text { Note 6) }
\end{array}
\] & 2 (Note 2) \\
\hline UN-AX80 & 1a1b & Side Clip-on & \[
\begin{gathered}
\text { S-T100, S-N125, } \\
\text { DU-N60 } \\
\hline
\end{gathered}
\] & \[
\begin{gathered}
\hline \text { SD-T100, SD-N125, } \\
\text { DUD-N60 } \\
\hline
\end{gathered}
\] & \[
\begin{aligned}
& \text { SL(D)-T100 } \\
& \text { SL(D)-N125 } \\
& \hline
\end{aligned}
\] & 2 (Note 4) \\
\hline UN-AX150 & 1a1b & Side Clip-on & S-N150,
S-N180, N220,
S-N300, N400,
DU-N120, N180, N260 & SD-N150
SD-N220
SD-N300, N400,
DUD-N120, N180, N260 & \[
\begin{gathered}
\text { SL(D)-N150 } \\
\text { SL(D)-N220 } \\
\text { SL(D)-N300, N400 }
\end{gathered}
\] & 2 (Note 4) \\
\hline UN-AX600 & 2a2b & Side Clip-on & S-N600, N800 & SD-N600, N800 & SL(D)-N600, N800 & 1 (Note 5) \\
\hline
\end{tabular}

Note 1. Front clip-on and side clip-on cannot be mounted on the same body.
Note 2. For the reversible type, 1 unit each can be mounted on the left and right exterior, for a total of 2 units.
Note 3. UT-AX \(\square B C\) is the model name with wiring streamlining terminals, while UN-AX \(\square C X\) is with CAN terminals.
Note 4. 1 unit each can be mounted on the left and right sides for a total of 2 units. (For the reversible type, additional mounting is not possible for UN-AX150, while 1 unit each can be additionally mounted on the left and right exterior for a total of 2 units for UN-AX80.)
Note 5. Mount on the right side. ( \(4 \mathrm{a} 4 \mathrm{~b} \times 2\) are mounted on the reversible type and additional mounting is not allowed.)
Note 6. When applied to T65 or T80, the auxiliary terminal screw size for the T65 and T80 body will be M4, and the terminal screw size of the auxiliary contact unit will be M3.5. As the screw sizes are different, they cannot be used interchangeably.

\section*{Rating}


Note 1. The value in parentheses for the DC rated operational current indicates the rated operating current when switching a 2-pole load in series.
Note 2. AC-15, AC-12, DC-13 and DC-12 are the classifications of JISC8201-5-1.
Note 3. Electrical durability of 500,000 operations.
Note 4. The mechanical durability and switching frequency depend on the magnetic contactor and contactor relay to be applied.

\section*{Combination With Contactor Relays}

Contactor relays and auxiliary contact units can be used in the contact arrangements of the following combinations.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{\multirow[t]{2}{*}{\begin{tabular}{rr}
\hline & Auxiliary Contact \\
\hline Unit \\
\hline
\end{tabular}}} & \multicolumn{6}{|c|}{Front Clip-on} & \multicolumn{2}{|c|}{Side Clip-on} \\
\hline & & \multicolumn{3}{|c|}{UT-AX4(BC)} & \multicolumn{3}{|l|}{UT-AX2(BC)} & UT-AX11(BC) & UT-AX11(BC) \\
\hline Model & Contact Arrangement & 4a & 3a1b & 2a2b & 2a & 1a1b & 2b & 1a1b + 1a1b & 1a1b \\
\hline & 5 a & 9a & 8a1b & 7a2b & 7a & 6a1b & 5a2b & 7a2b & 6a1b \\
\hline  & 4a1b & 8a1b & 7a2b & 6a3b & 6 a 1 b & 5a2b & 4a3b & 6a3b & 5a2b \\
\hline & 3a2b & 7a2b & 6a3b & 5a4b & 5a2b & 4a3b & 3a4b & 5a4b & 4a3b \\
\hline
\end{tabular}

Note 1. The auxiliary contact unit cannot be mounted on \(\operatorname{SR}(\mathrm{D})-\mathrm{T}(\mathrm{BC})\).
Note 2. Front clip-on and side clip-on cannot be mounted simultaneously.
Note 3. The contact arrangement inside the \(\square\) is the standard combination.

\section*{Mounting Method/Removal Method}


UN-AX2 (CX), UN-AX4 (CX)
- Mounting Method

Mount according to the guidelines below.
(1) Place the auxiliary contact unit on the head of the magnetic contactor, about 10 mm off center toward the power supply side.
(2) Slide the unit to the load side to engage the stopper of the unit and groove of the arc cover.

- Removal Method
(3) Pull up the stopper of the unit.
(4) Remove the unit by sliding to the power supply side.

\section*{UN-AX11 (CX) \\ - Mounting Method}

Mount according to the guidelines below.
(1) Pinch the hooks (in 2 places) with your fingers and push into the case of UN-AX11.
(2) While aligning the protrusion (* mark) of the UN-AX11 case with the unit mounting hole on the magnetic contactor side, engage the claw of the hook to the rail on the bottom of the magnetic contactor.


Note: Confirm the following after mounting.
1. Lightly pull the UN-AX11 body to make sure that it is securely mounted.
2. Make sure that the cross bar on the front of the magnetic contactor is pushed in.
- Removal Method
(3)Remove by pinching the hooks (in 2 places) with fingers.

\section*{Mounting Method}

\section*{UN-AX80}
(1) Press the head of the cross bar.

(2) Insert the lever of the auxiliary contact unit (UN-AX80) into the window of the contactor side, and bring it into close contact with the contactor.

(3) Tighten the screws. Push in the cross bar after mounting

\section*{UN-AX150}
(1) Remove the dust cover from the place where additional mounting is to take place.

(2) Push down the head of the cross bar. (Press until the main contact touches)

(3) Push in the auxiliary contact unit (UN-AX150).

(4) Tighten the screws. Push in the cross bar after mounting.


\section*{UN-AX600}


\section*{- Removal Method}

Remove in reverse order to that described above.
- Mounting Screw Tightening Torque
\begin{tabular}{|c|c|}
\hline Auxiliary Contact Units & Tightening Torque (N•m) \\
\hline UN-AX80 & 1.47 to 1.96 \\
\hline UN-AX150 & 1.18 to 1.86 \\
\hline UN-AX600 & 1.18 to 1.86 \\
\hline
\end{tabular}

\section*{Optional Units}

\section*{MS-T Series}

Outline Drawings (Figure Has No BC)
UT-AX2(BC)

Contact Arrangement

Contact Arrangement

\begin{tabular}{|c|c|c|}
\hline \begin{tabular}{c} 
Applicable Terminal \\
Wire Size \(\left[\varphi \mathrm{mm}, \mathrm{mm}^{2}\right]\)
\end{tabular} & \begin{tabular}{c} 
Applicable Crimp \\
Lug Size
\end{tabular} & \begin{tabular}{c} 
Terminal Screw \\
Tightening Torque \(\mathrm{N} \cdot \mathrm{m}\)
\end{tabular} \\
\hline \begin{tabular}{c}
\(\varphi 1.6\) \\
0.75 to 2.5
\end{tabular} & \(1.25-3.5\) to \(2-3.5\) & 0.9 to 1.5 \\
\hline
\end{tabular}

Contact Arrangement
\begin{tabular}{|c|}
\hline When mounted on \\
the left side of the body \\
\hline 93 \\
\hline When mounted on \\
the right side of the body \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|}
\hline \begin{tabular}{c} 
Applicable Terminal \\
Wire Size \(\left[\varphi \mathrm{mm}, \mathrm{mm}^{2}\right]\)
\end{tabular} & \begin{tabular}{c} 
Applicable Crimp \\
Lug Size
\end{tabular} & \begin{tabular}{c} 
Terminal Screw \\
Tightening Torque N•m
\end{tabular} \\
\hline \begin{tabular}{c}
\(\varphi 1.6\) \\
0.75 to 2.5
\end{tabular} & \(1.25-3.5\) to \(2-3.5\) & 0.9 to 1.5 \\
\hline
\end{tabular}
\begin{tabular}{|c|l|}
\hline Model Name & Model Name \\
\hline UT-AX2 & UT-AX2BC \\
\hline UT-AX4 & UT-AX4BC \\
\hline UT-AX11 & UT-AX11BC \\
\hline
\end{tabular}

\section*{MS-N Series}

Outline Drawings (Figure Has No CX)

\begin{tabular}{|c|l|}
\hline Model Name & Model Name \\
\hline UN-AX2 & UN-AX2CX \\
\hline UN-AX4 & UN-AX4CX \\
\hline UN-AX11 & UN-AX11CX \\
\hline
\end{tabular}

\section*{Optional Units}

\section*{Outline Drawings}



This unit is to be mounted to the right side of the magnetic contactor. The addition of this unit does not change the maximum outline drawings of the magnetic contactor.
\begin{tabular}{|c|}
\hline Model Name \\
\hline UN-AX80 \\
\hline UN-AX150 \\
\hline UN-AX600 \\
\hline
\end{tabular}

\subsection*{8.4 UN-LL22 Auxiliary Contact Units with Contact for Low-Level Signals}

\section*{Capable of controlling DC5 V 5 mA .}
-This is an auxiliary contact unit with built-in low-level contacts that are capable of switching the low voltage and small current of electronic control circuits.
- It can be mounted with a single touch on a magnetic contactor or contactor relay that performs power switching of a motor or the like, eliminating the need for a relay for switching low voltage and small current, thus making it ideal for switching the electronic input circuits of PLCs etc.
- Compact micro switches are used for the low-level contacts.
- Since it has built-in 1a1b low-level contacts and 1a1b standard contacts, a single unit allows switching of AC200 V and DC24 V, for example.


UN-LL22

\section*{Type}
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Unit Model Name} & \multicolumn{2}{|l|}{Contact Arrangement} & \multirow[t]{2}{*}{Unit Mounting Method} & \multicolumn{2}{|l|}{Model Names of Applicable Magnetic Contactors and Contactor Relays} & \multirow[t]{2}{*}{Total Number of Addable Units} \\
\hline & Name & Contact & & AC Operated & DC Operated & \\
\hline \multirow[t]{2}{*}{\[
\begin{aligned}
& \text { UN-LL22 } \\
& \text { UN-LL22CX }
\end{aligned}
\]} & Low-Level Contact & 1a1b & \multirow{2}{*}{Front Clip-on} & \multirow[t]{2}{*}{\[
\begin{aligned}
& \text { S-T65, T80 } \\
& \text { S-N38, N48 } \\
& \text { DU-N30 }
\end{aligned}
\]} & \multirow[t]{2}{*}{\[
\begin{aligned}
& \text { SD-T65,T80 } \\
& \text { DUD-N30 }
\end{aligned}
\]} & \multirow{2}{*}{1 (Note 1)} \\
\hline & Standard Contact & 1a1b & & & & \\
\hline
\end{tabular}

Note 1. UN-LL22 (CX) and UN-AX11 (CX) cannot be mounted on the same body.
Note 2. UN-LL22CX is the model name with CAN terminals.
Note 3. When applied to T65 or T80, the auxiliary contact terminal screws of the T65 and T80 body will be M4, and the terminal screws of UN-LL22 will be M3.5.
As the screw sizes are different, they cannot be used interchangeably.

\section*{Rating}
\begin{tabular}{|c|c|c|c|c|}
\hline \multicolumn{3}{|l|}{\multirow[t]{2}{*}{Minimum Rated Capacity 1 mil. times (Note 1)}} & Low-Level Contact & Standard Contact \\
\hline & & & 5 V 5 mA & 20 V 5 mA \\
\hline \multirow[t]{4}{*}{} & Category DC-12 & Resistive Load & DC24 V 100 mA , DC48 V 100 mA & DC110 V 1.5 A, DC220 V 0.25 A \\
\hline & Category DC-13 & Large Coil Load & - & DC110 V 0.6 A, DC220 V 0.3 A \\
\hline & Category AC-12 & Resistive Load & AC48 V 200 mA , AC240 V 20 mA & AC110 V \(10 \mathrm{~A}, \mathrm{AC} 220 \mathrm{~V} 8 \mathrm{~A}\) \\
\hline & Category AC-15 & Large Coil Load & - & AC110 V 6 A, AC220 V 3 A \\
\hline \multicolumn{3}{|l|}{Conventional Free Air Thermal Current Ith} & 1 A & 10 A \\
\hline \multicolumn{3}{|r|}{Rated Insulation Voltage} & AC250 V & AC500 V \\
\hline \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Switching Durability}} & Electrical & 0.5 mil. times & 0.5 mil. times \\
\hline & & Mechanical & \multicolumn{2}{|c|}{2.5 mil. times} \\
\hline \multicolumn{3}{|c|}{Compliant Standards} & & \\
\hline
\end{tabular}

Note 1. The contact reliability may decrease if it exceeds 1 million times.
The contact reliability when the input circuit of the PLC is switched is shown in the table below.
- Failure Rate at Confidence Rate \(60 \% \lambda_{60} \quad\) (No. of faults/times switching, no. of contacts)
\begin{tabular}{c|c|c}
\hline \begin{tabular}{c} 
PLC MELSEC \\
Input Circuit Rating
\end{tabular} & Low-Level Contact & Standard Contact \\
\hline DC24 V 10 mA, DC24 V5 mA & \(5 \times 10^{-8}\) & \(5 \times 10^{-7}\) \\
\hline DC12 V 5 mA & \(1 \times 10^{-7}\) & - \\
\hline DC 5 V 5 mA & \(1 \times 10^{-6}\) & - \\
\hline AC100 V 10 mA & \(1 \times 10^{-8}\) & \(5 \times 10^{-8}\) \\
\hline
\end{tabular}
[Conditions] 1. One million times switching.
2. In a typical environment without a large amount of dust or corrosive gas.
3. Contact failure is detected by the PLC program.

Note 2. The classification of the maximum rated capacity is the classification of JISC8201-5-1.

\section*{- Mounting Method}

The mounting method is the same as UN-AX4 (CX). Refer to page 198.

\section*{Outline Drawings (Figure Has No CX)}

\section*{UN-LL22(CX)}


\section*{Contact Arrangement}


\footnotetext{
(When viewed from the front)
}
\begin{tabular}{|l|}
\hline Model Name \\
\hline UN-LL22 \\
\hline UN-LL22CX \\
\hline
\end{tabular}

\subsection*{8.5 UT/UN-SA \(\square\) Operation Coil Surge Absorber Units}

It suppresses noise during coil current interruption, and reduces malfunction, damage and the like of electronic circuits.
- It can be mounted on a magnetic contactor or contactor relay with a single touch. UT-SA13 to SA25 are space-saving types that utilize the dead space of the lower side of the coil terminal.
- A wide variety is available, allowing easy selection according to the application.


UT-SA21

\section*{Proper Use}
Surge Suppressing Element

\section*{Optional Units}

\section*{Types and Ratings}


Note 1. The surge suppression effect for the applied circuit is smaller in the \(\square\) (applicable voltage) than in the \(\square\) (recommended voltage) range.
2. Even in the \(\square\) (recommended voltage) range, the surge suppression effect may not be enough depending on the characteristics of the connected device. (Check the influence of surge using the actual device in advance.)
3. Refer to page 43 for the surge absorber mounted type and built-in magnetic contactors and contactor relays.

\section*{Application and Selection}
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multirow[t]{3}{*}{} & \multirow{3}{*}{AC Operated} & \multirow{3}{*}{DC Operated} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Mechanically Latched Type (AC Operated)}} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Mechanically Latched (DC Operated)}} \\
\hline & & & & & & \\
\hline & & & Closing Coil & Tripping Coil & Closing Coil & Tripping Coil \\
\hline UT-SA21 & \[
\begin{array}{|lr|}
\hline \text { S-T10 to T50, B-T21 } \\
\text { S-N38, N48 } \\
\text { SR-T5, T9 } & \\
\hline
\end{array}
\] & \[
\begin{array}{|lr|}
\hline \text { SD-T12 to T50, } \\
\text { BD-T21 } & \\
\text { SRD-T5, T9 } & \text { SQ } \\
\hline
\end{array}
\] & \[
\begin{aligned}
& \text { SL-T21 to T50 } \\
& \text { SRL-T5 }
\end{aligned}
\] & - & \[
\begin{aligned}
& \text { SLD-T21 to T50 } \\
& \text { SRLD-T5 }
\end{aligned}
\] & - \\
\hline UT-SA22 & \[
\begin{array}{|lr}
\hline \text { S-T10 to T50, B-T21 } \\
\text { S-N38, N48 } \\
\text { SR-T5, T9 SQ } \\
\hline
\end{array}
\] & \[
\begin{aligned}
& \text { SD-T12 to T50, } \\
& \text { BD-T21 } \\
& \text { SRD-T5, T9 }
\end{aligned}
\] & \[
\begin{aligned}
& \text { SL-T21 to T50 } \\
& \text { SRL-T5 }
\end{aligned}
\] & - & \[
\begin{aligned}
& \text { SLD-T21 to T50 } \\
& \text { SRLD-T5 }
\end{aligned}
\] & - \\
\hline UT-SA13 & - & \[
\begin{array}{|lr|}
\hline \text { SD-T12 to T50, } \\
\text { BD-T21 } & \\
\text { SRD-T5, T9 } & \text { SQ } \\
\hline
\end{array}
\] & - & - & \[
\begin{aligned}
& \text { SLD-T21 to T50 } \\
& \text { SRLD-T5 }
\end{aligned}
\] & - \\
\hline UT-SA23 & \begin{tabular}{lr}
\hline \begin{tabular}{l} 
S-T10 to T50, B-T21 \\
S-N38, N48 \\
SR-T5, T9
\end{tabular} \\
\hline
\end{tabular} & - & \[
\begin{aligned}
& \text { SL-T21 to T50 } \\
& \text { SRL-T5 }
\end{aligned}
\] & - & - & - \\
\hline UT-SA25 & \[
\begin{array}{|lr}
\text { S-T10 to T50, B-T21 } \\
\text { S-N38, N48 } \\
\text { SR-T5, T9 SQ } \\
\hline
\end{array}
\] & \[
\begin{array}{|lr}
\hline \text { SD-T12 to T50, } \\
\text { BD-T21 } \\
\text { SRD-T5, T9 } & \\
\hline
\end{array}
\] & \[
\begin{aligned}
& \text { SL-T21 to T50 } \\
& \text { SRL-T5 }
\end{aligned}
\] & - & \[
\begin{aligned}
& \text { SLD-T21 to T50 } \\
& \text { SRLD-T5 }
\end{aligned}
\] & - \\
\hline UN-SA721 & SR-K100 & \[
\begin{aligned}
& \text { SD-T65, T80 } \\
& \text { SRD-K100, DUD-N30 }
\end{aligned}
\] & SRL-K100 & \[
\begin{aligned}
& \text { SL-T21 to T80 } \\
& \text { SRL-T5, K100 }
\end{aligned}
\] & SRLD-K100 & \[
\begin{array}{|l}
\text { SLD-T21 to T80 } \\
\text { SRLD-T5, K100 }
\end{array}
\] \\
\hline UN-SA712 & SR-K100 & SRD-K100 & SRL-K100 & \[
\begin{aligned}
& \text { SL-T21 to T50 } \\
& \text { SRL-T5, K100 }
\end{aligned}
\] & SRLD-K100 & \[
\begin{aligned}
& \text { SLD-T21 to T50 } \\
& \text { SRLD-T5, K100 }
\end{aligned}
\] \\
\hline UN-SA722 & - & SD-T65, T80 DUD-N30 & - & SL-T65, 880 & - & SLD-T65, 880 \\
\hline UN-SA713 & - & \[
\begin{aligned}
& \text { SD-T65, T80 } \\
& \text { SRD-K100, DUD-N30 }
\end{aligned}
\] & - & - & SRLD-K100 & \[
\begin{array}{|l}
\text { SLD-T21 to T80 } \\
\text { SRLD-T5, K100 }
\end{array}
\] \\
\hline UN-SA723 & SR-K100 & - & SRL-K100 & \[
\begin{aligned}
& \text { SL-T21 to T80 } \\
& \text { SRL-T5, K100 }
\end{aligned}
\] & - & - \\
\hline UN-SA725 & SR-K100 & \[
\begin{aligned}
& \text { SD-T65, T80 } \\
& \text { SRD-K100, DUD-N30 }
\end{aligned}
\] & SRL-K100 & \[
\begin{aligned}
& \text { SL-T21 to T80 } \\
& \text { SRL-T5, K100 }
\end{aligned}
\] & SRLD-K100 & \[
\begin{array}{|l}
\text { SLD-T21 to T80 } \\
\text { SRLD-T5, K100 }
\end{array}
\] \\
\hline
\end{tabular}

\section*{- Precautions for Application}
(1) Connect the terminals of surge absorber units in parallel with the operation coils of magnetic contactors or contactor relays.
(2) As only the surge absorber units with operation indicators (UT-SA22, UN-SA712 and SA722) have polarity, pay attention to the polarity when applying to the DC circuit. If the wrong polarity is used, the operation indicator will not turn on. (The surge suppression function is not affected, but the magnetic contactor of UT-SA22 will not work.)
(3) When used in combination with the surge absorber, the opening time of the magnetic contactor or contactor relay may be 1.5 to 3 times longer. (Excluding the mechanically latched type.)
(4) As the bodies of magnetic contactors and contactor relays have common mounting grooves, if the additional mounting type UN-SY21, SY22, SY31 and SY32 DC/ AC interface units for operation coils are mounted, surge absorber units cannot be mounted.
(However, combinations with UT-SY21, SY22 and UT-SA21, SA13, SA23 allow for mounting)
(5) Since the operation coils of the S-T65 to T100 and S-N125 to N800 AC-operated constant excitation type magnetic contactors use an AC-operated DC excitation system that does not generate switching surge, an exterior surge absorber is not required.
(6) Refer to Note 5 on page 46 for the SL-T65 to T100 and N125 to N800 mechanically latched contactors.
(7) The lead terminals of UN-SA7 \(\square\) are square-tipped crimp lugs.
(8) The surge absorber is designed to suppress the surge from magnetic contactors. The warranty does not cover external surges. Extreme external surges may damage the product.
(9) The units that can be used with the spring clamp terminal models are marked with "SQ" in the Applicable Models column.
For the spring clamp terminal models, refer to pages 125 and 175.

\section*{Optional Units}

\section*{Outline Drawings}


When attached to the body of a magnetic contactor or contactor relay, the body exterior becomes larger by the following dimensions.
\begin{tabular}{l|c|c}
\hline \multicolumn{1}{c|}{ Applicable Models } & L1 Dimension & L2 Dimension \\
\hline \begin{tabular}{l|c|} 
SL(D)-T21 to T50 (Tripping Coil)
\end{tabular} & & 7 \\
\hline SRL(D)-T5 (Tripping Coil) & & \\
\hline SR-K100 & 17.5 & \\
\hline SRD-K100 & 11.5 & \\
\hline SRL(D)-K100 & 17.5 & 5.5 \\
\hline
\end{tabular}



When attached to the body of a magnetic contactor, the body exterior becomes larger by the following dimensions
\begin{tabular}{l|c}
\hline \multicolumn{1}{c|}{ Applicable Models } & L1 Dimension \\
\hline SD-T65, T80 & \\
DUD-N30 & 9.5 \\
SL(D)-T65, T80 (Tripping Coil) & \\
\hline
\end{tabular}

\section*{Optional Units}

UN-SA713

0.02 kg

UN-SA725


Connection Example (Connection Diagram)


When attached to the body of a magnetic contactor or contactor relay, the body exterior becomes larger by the following dimensions.
\begin{tabular}{|c|c|c|}
\hline Applicable Models & L1 Dimension & L2 Dimension \\
\hline SL(D)-T21 to T50 (Tripping Coil) SRL(D)-T5 (Tripping Coil) &  & 7 \\
\hline SD-T65, T80
DUD-N30
SL(D)-T65, 180 (Tripping Coil) & 4.5 &  \\
\hline SRD-K100 & 11.5 &  \\
\hline SRLD-K100 & 17.5 & 5.5 \\
\hline
\end{tabular}

Connection Example (Connection Diagram)


When attached to the body of a magnetic contactor or contactor relay, the body exterior becomes larger by the following dimensions.
\begin{tabular}{l|c|c}
\hline \multicolumn{1}{c|}{ Applicable Models } & L1 Dimension & L2 Dimension \\
\hline SL(D)-T21 to T50 (Tripping Coil) & & \\
SRL(D)-T5 (Tripping Coil) & & 2 \\
SL(D)-T65, T80 (Tripping Coil) & & \\
\hline SR-K100 & 12.5 & \\
\hline SRL-K100 & 12.5 & 0.5 \\
\hline
\end{tabular}

Connection Example (Connection Diagram)


When attached to the body of a magnetic contactor, the body exterior becomes
larger by the following dimensions.
\begin{tabular}{|c|c|c|}
\hline Applicable Models & L1 Dimension & L2 Dimension \\
\hline SL(D)-T21 to T50 (Tripping Coil) SRL(D)-T5 (Tripping Coil) &  & 7 \\
\hline SD-T65, T80
DUD-N30
SL(D)-T65, T80 (Tripping Coil) & 9.5 &  \\
\hline SR-K100 & 17.5 & \\
\hline SRD-K100 & 11.5 & \\
\hline SRL(D)-K100 & 17.5 & 5.5 \\
\hline
\end{tabular}

\section*{Mounting Method}
(1) UT-SA13, SA21, SA22, SA23, SA25


Removing Rod

[Note]
Co-fasten the terminal of the surge absorber and the coil terminal

Note. Loosen the screws of the coil terminals A1 and A2 of the magnetic contactor or contactor relay (not necessary for models with wiring streamlining terminals (model names "BC" and "CX"), then insert in the direction of the arrow as shown in the figure above (insert the protrusion into the groove after the conductor is inserted into the coil terminal).

(2) UN-SA712, SA713, SA721, SA722, SA723, SA725
(1) The body of the surge absorber is pushed into the groove provided in the upper part of the magnetic contactor or contactor relay in the direction of the arrow as shown in the figure below.

(2) Mount the magnetic contactor or contactor relay on the mounting surface of the panel.
(3) Co-fasten the terminal of the surge absorber to the operation coil terminal. (As the lead wire of the surge absorber is made long, bundle it, etc. as needed.)
\begin{tabular}{|c|c|}
\hline Model Name & Model Name \\
\hline UT-SA13 & UN-SA712 \\
\hline UT-SA21 & UN-SA713 \\
\hline UT-SA22 & UN-SA721 \\
\hline UT-SA23 & UN-SA722 \\
\hline UT-SA25 & UN-SA723 \\
\hline & UN-SA725 \\
\hline
\end{tabular}

\section*{8 Optional Units}

\subsection*{8.6 UT/UN-SA33 \(\square\) Main Circuit Surge Absorber Units}

Connect to the load side of the magnetic starter or magnetic contactor that switches a three-phase or single-phase motor to suppress the surge voltage and noise generated when switching the contact and to reduce adverse effects on electronic circuits and the like.
- Front clip-on type and independent mounting type (allows both IEC 35 mm rail mounting and screw mounting) are available.
- The Front clip-on type can be mounted on the magnetic contactor with a single touch, while the contact pin simultaneously contacts and connects to the terminal screw.
Type
\begin{tabular}{|c|c|c|c|c|}
\hline Model Name & Mounting Method & Itenand Emenen Specificiorns & Rated Voltage/frequency & Applicable Models \\
\hline UT-SA3320 & Front Clip-on & \((0.3 \mu \mathrm{~F}+600 \mathrm{O}) \times 3\) & \multirow[b]{2}{*}{AC240V} & \[
\begin{aligned}
& \text { S-T10, T12, T20(BC) } \\
& \text { SD-T12, T20(BC) }
\end{aligned}
\] \\
\hline UT-SA3332 & Front Clip-on & (0.34F+600) \(\times 3\) & & S-T21, T25, T32(BC) SD-T21, T32(BC) \\
\hline UN-SA33 & Independent Mounting & (0.54F + 500) \(\times 3\) & 50/60Hz & S-T10 to T100 SD-T12 to T100 S-N125 to N800 SD-N125 to N800 SD-Q11, SD-Q12 \\
\hline
\end{tabular}

\section*{Connecting}


Specifications

Precautions for Use
(1) Try to connect UN-SA33 near the source of surges, noise and the like.
(2) Do not use it for circuits with a large amount of highfrequency components such as an inverter circuit.
(3) Do not use it on the load side of a device with a small contact capacity such as a relay.
\begin{tabular}{|c|c|c|}
\hline \multirow[t]{2}{*}{Internal Connection} & \multicolumn{2}{|c|}{Connection Example} \\
\hline & Three-Phase Circuit & Single-Phase Circuit \\
\hline  &  &  \\
\hline
\end{tabular}

\section*{Outline Drawings}


\subsection*{8.7 UT/UN-ML \(\square\) Mechanical Interlock Units}

A reversible magnetic contactor can be configured.
- The mechanical interlock prevents the simultaneous energization of 2 magnetic contactors by mechanically locking them. It can be combined with a main circuit conductor kit (UT/UN-SDC, SGD) to easily configure the reversible magnetic contactor and magnetic contactor for power switching.
- UT-ML20(BC) has 2 built-in break contacts, which can be used to configure an electrical interlock. Do not use these break contacts for applications other than the electrical interlock.
As models other than UT-ML20(BC) have no built-in break contact, be sure to use the auxiliary break contacts of the magnetic contactor for the electrical interlock.

\section*{Format}
\begin{tabular}{|c|c|c|c|}
\hline \multirow[t]{2}{*}{Mechanical Interlock Model Name} & \multicolumn{3}{|c|}{Applicable Magnetic Contactor Model} \\
\hline & AC Operated & DC Operated & Mechanically Latched Type \\
\hline UT-ML20 & S-T10,T12,T20 (Note 3) & SD-T12,T20 & - \\
\hline UT-ML20BC & S-T10BC,T12BC,T20BC (Note 3) & SD-T12BC,T20BC & - \\
\hline UN-ML21 & \[
\begin{aligned}
& \hline \text { S-T21 to T80 } \\
& \text { S-T21BC to T50BC } \\
& \text { S-N38,N48 } \\
& \text { DU-N30 }
\end{aligned}
\] & \begin{tabular}{l}
SD-T21 to T80 \\
SD-T21BC to T50BC \\
DUD-N30
\end{tabular} & \[
\begin{aligned}
& \text { SL(D)-T21 to T80 } \\
& \text { SL(D)-T21 to T50BC }
\end{aligned}
\] \\
\hline UN-ML80 & S-T100 S-N125 DU-N60 & \[
\begin{aligned}
& \hline \text { SD-T100 } \\
& \text { SD-N125 } \\
& \text { DUD-N60 }
\end{aligned}
\] & \[
\begin{aligned}
& \text { SL(D)-T100 } \\
& \text { SL(D)-N125 }
\end{aligned}
\] \\
\hline UN-ML150 & S-N150,DU-N120 & SD-N150,DUD-N120 & SL(D)-N150 \\
\hline UN-ML220 & S-N180,N220,N300,N400 DU-N180,N260 & \[
\begin{aligned}
& \text { SD-N220,N300,N400 } \\
& \text { DUD-N180,N260 }
\end{aligned}
\] & \[
\begin{array}{|l|}
\hline \text { SL(D)-N220 } \\
\text { SL(D)-N300,N400 } \\
\hline
\end{array}
\] \\
\hline
\end{tabular}


UT-ML20


UN-ML21

Note 1. "-" indicates outside production range.
Note 2. UT-ML11BC and UT-ML20BC are the model names with wiring streamlining terminals.
Note 3. The units can be combined with the contactors produced in March, 2019 and later.
- Mounting
- Hole Drilling Dimension
(Drilling of holes is not required when mounting the IEC 35 mm rail mountable model is mounted to the IEC 35 mm rail for reversing.)

- UT-ML20(BC)
(1) Hook the load side barrier of the magnetic contactor to the load side claw A of the interlock unit.
(2) Allot the lever (1) of the interlock unit to the lever insert hole (2) of the magnetic contactor side, and the insert protrusion (3) to the unit mounting hole (4).
(3) Press the interlock unit and magnetic contactor against each other, and hook up the power supply side claw B and power supply side barrier of the magnetic contactor.

\section*{Important Matters}

In this state, make sure that the cross bar head (5) on one side moves smoothly when pressed. Similarly, check the other magnetic contactor. If the cross bar head is constrained and does not move, rearrange.
(4) Align the rail (7) of the connecting plate in the groove (6) at the bottom of the left and right magnetic contactors, and push until you hear a click.
(5) Connect the lead wire (8) of the interlock unit to the coil terminal A1.
Lead RO2 (Red) \(\rightarrow\) To Right Magnetic Contactor Coil Terminal A1
Lead LO2 (Black) \(\rightarrow\) To Left Magnetic Contactor Coil Terminal A1
(6) Wire the control circuit as follows.
\(\underset{\text { Terminal A2 }}{\underset{\text { Right Coil }}{\text { Left Coil }} \leftarrow \underset{\text { Control Circuit }}{\text { Right Contactor }} \rightarrow \underset{\text { Left Contactor }}{\text { Lerminal A2 }} \rightarrow \underset{\text { Control Circuit }}{\text { Linterlock }}\)\begin{tabular}{c}
\text { Unit } \\
\text { Terminal R01 } \\
\text { Interlock } \\
\text { Unit } \\
\text { Terminal L01 }
\end{tabular}\(}\) Important Matters

When the cross bar head (5) of one of the magnetic contactors is pushed in, if it moves smoothly and one side is pushed in, make sure for both left and right that the other side is not pushed in.


\section*{Mounting Method}
- UN-ML21[See Fig. 2]
(1) Allot the lever (1) of the interlock unit to the lever insert hole (2) of the magnetic contactor side, and the insert protrusion (3) to the unit mounting hole (4), then sandwich the interlock unit with the left and right magnetic contactors without a gap.
(2) Align the rail (7) of the connecting plate in the groove (6) at the bottom of the left and right magnetic contactors, and push the connecting plate until the protrusion (9) fits into the hook (8) of the interlock and you hear a click.

\section*{Important Matters}

When the cross bar head (5) of one of the magnetic contactors is pushed in, if it moves smoothly and one side is pushed in, make sure for both left and right that the other side is not pushed in.

(4) Mount the panel on the other magnetic contactor to sandwich the mechanical interlock unit. Make sure that the mechanical interlock unit is sandwiched by the left and right magnetic contactors without a gap.

\section*{Important Matters}

When the cross bar head of one of the magnetic contactors is pushed in, if it moves smoothly and one side is pushed in, make sure for both left and right that the other side is not pushed in.
- UN-ML80, ML150, ML220
(1) Drill holes for the mounting screws of the magnetic contactor in the panel.
(2) Mount one of the magnetic contactors on the panel.
(3) Insert the lever of the mechanical interlock unit into the square hole provided on the magnetic contactor side, and insert the fitting portion provided at the bottom into the mounting groove of the magnetic contactor side.

\section*{Outline Drawings}

Refer to the reversible types on pages 77, 93 and 106 for the outline drawings when combined with a magnetic contactor.
\begin{tabular}{|l|l|l|}
\hline Model Name & Model Name & Model Name \\
\hline UT-ML20 & UN-ML21 & UN-ML150 \\
\hline UT-ML20BC & UN-ML80 & UN-ML220 \\
\hline
\end{tabular}

Magnetic Contactor Fitting Part


\subsection*{8.8 UT/UN-SD \(\square\), SG \(\square\), YD \(\square\), UN-YG \(\square\) Main Circuit Conductor Kits}

Main circuit conductor kits can be used for the wiring rationalization of reversible magnetic contactors, power switches, star-delta starters, etc.
Combine the mechanical interlock unit (UT/UN-MLD) and electrical interlock when configuring the reversible type.

\begin{tabular}{|c|c|c|c|c|}
\hline \begin{tabular}{l}
Applicable \\
Magnetic \\
Contactor Frame
\end{tabular} & Reversing Type & Crossover Type & 3-Pole Short-Circuit Type & 2-Pole Short-Circuit Type \\
\hline T10 & UT-SD10 & UT-SG10 & - & \\
\hline T12,T20 & UT-SD20 & UT-SG20 & - & \\
\hline T21,T25 & UT-SD25 & UT-SG25 & UN-YG21 & UN-YD21 \\
\hline T32 & UN-SD18CX & UN-SG18CX & UN-YG21 & UN-YD21 \\
\hline T35,T50 & UN-SD25CX & UN-SG25CX & & \\
\hline N38,N48 & - & - & & \\
\hline T65,T80 & UN-SD50 & UN-SG50 & UN-YG50 & UN-YD50 \\
\hline T100 & UN-SD80 & UN-SG80 & UN-YG80 & UN-YD80 \\
\hline N125 & UN-SD125 & UN-SG125 & UN-YG80 & UN-YD80 \\
\hline N150 & UN-SD150 & UN-SG150 & UN-YG150 & UN-YD150 \\
\hline N180,N220 & UN-SD220 & UN-SG220 & UN-YG220 & UN-YD220 \\
\hline N300,N400 & UN-SD300 & UN-SG300 & UN-YG300 & UN-YD300 \\
\hline N600,N800 & UN-SD600 & UN-SG600 & - & - \\
\hline Remarks & The kit contains six conductors per set. Power supply side and load side conductors are available, and therefore care should be taken when connecting. & \begin{tabular}{l}
The kit contains three conductors per set. \\
The conductors can be connected to the power supply terminal.
\end{tabular} & \begin{tabular}{l}
2 conductors are required when configuring the 3-pole parallel circuit. \\
When using on the power supply s
\end{tabular} & 2 conductors are required when configuring the 3-pole series circuit. ide, mount after wiring the coil. \\
\hline
\end{tabular}

Note 1. For UN-SD \(\square\) CX/SG \(\square\) CX, ring crimp lugs have insulation tubes.
Note 2. UN-YG \(\square\) and UN-YD \(\square\) are to be purchased separately from the magnetic contactor and mounted by the customer. While UN-YG21 to YG80 and UN-YD21 to YD80 can be mounted directly to the magnetic contactor terminal, perform the following procedure when mounting UN-YG150 to YG300 and UN-YD150 to YD300.
(1) Loosen the arc box mounting screws (2 pcs.) and remove the arc box.
(2) Remove the insulation barrier of the terminal where the conductor will be mounted.
(3) Mount the arc box.
(4) Mount the conductor.

Note 3. UT/UN-SD \(\square\) and SG \(\square\) are for magnetic contactors. A thermal overload relay cannot be added after mounting. (Excluding UT-SD10 to SD25, UN-SD18CX, UN-SD50 and SD80)
Note 4. When using UN-YG \(\square\) and YD \(\square\), UN-CZ \(\square\) live part protection cover cannot be mounted.
\begin{tabular}{|c|c|c|c|}
\hline Model Name & Minimum Order Unit & Model Name & Minimum Order Unit \\
\hline UT-SD10 & 5 (for 5 Units) & UT-SG10 & 5 \\
\hline UT-SD20 & 5 (for 5 Units) & UT-SG20 & 5 \\
\hline UT-SD25 & 5 (for 5 Units) & UT-SG25 & 5 \\
\hline UN-SD18CX & 5 (for 5 Units) & UN-SG18CX & 5 \\
\hline UN-SD25CX & 5 (for 5 Units) & UN-SG25CX & 5 \\
\hline UN-SD50 & 1 (for 1 Unit) & UN-SG50 & 1 \\
\hline UN-SD80 & 1 (for 1 Unit) & UN-SG80 & 1 \\
\hline UN-SD125 & 1 (for 1 Unit) & UN-SG125 & 1 \\
\hline UN-SD150 & 1 (for 1 Unit) & UN-SG150 & 1 \\
\hline UN-SD220 & 1 (for 1 Unit) & UN-SG220 & 1 \\
\hline UN-SD300 & 1 (for 1 Unit) & UN-SG300 & 1 \\
\hline UN-SD600 & 1 (for 1 Unit) & UN-SG600 & 1 \\
\hline UN-YG21 & 20 & UT-YD20 & 20 \\
\hline UN-YG25 & 20 & UN-YD21 & 20 \\
\hline UN-YG50 & 10 & UN-YD25 & 20 \\
\hline UN-YG80 & 10 & UN-YD50 & 10 \\
\hline UN-YG150 & 10 & UN-YD80 & 10 \\
\hline UN-YG220 & 5 & UN-YD150 & 10 \\
\hline UN-YG300 & 5 & UN-YD220 & 5 \\
\hline
\end{tabular}

\subsection*{8.9 UT/UN-YY \(\square\) 3-Pole Array Connection Units}

Ideal for single-phase resistive loads of power supply devices, electric heaters, water heaters, etc.
By attaching a 3-pole array connection unit to the main circuit terminal (power supply side, load side) of the standard type magnetic contactor, it can be used as a magnetic contactor for single-phase resistive loads.

\section*{- Model Name}
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Unit Model Name} & \multicolumn{3}{|c|}{Applicable Models} & Rating [A] & \multirow[t]{2}{*}{Terminal Screw Size} & \multirow[t]{2}{*}{\[
\begin{aligned}
& \hline \text { Switching } \\
& \text { Life } \\
& {[\times 10000]} \\
& \hline
\end{aligned}
\]} \\
\hline & AC Operated Product & DC Operated Product & Latched Type & \[
\begin{gathered}
\mathrm{AC}-1 \\
\text { AC100 to } 220 \mathrm{~V}
\end{gathered}
\] & & \\
\hline UT-YY20 & S-T10/T12/T20 & SD-T12/T20 & - & 40 & \multirow{4}{*}{M6} & \multirow{5}{*}{50} \\
\hline \multirow{3}{*}{UN-YY21} & S-T21 & SD-T21 & SL(D)-T21 & 65 & & \\
\hline & S-T25 & - & - & 80 & & \\
\hline & S-T32 & SD-T32 & - & 100 & & \\
\hline \multirow[b]{2}{*}{UN-YY35} & S-T35 & SD-T35 & SL(D)-T35 & 125 & \multirow{4}{*}{M8} & \\
\hline & S-T50 & SD-T50 & SL(D)-T50 & 200 & & \multirow{6}{*}{25} \\
\hline \multirow[b]{2}{*}{UN-YY50} & S-T65 & SD-T65 & SL(D)-T65 & 250 & & \\
\hline & S-T80 & SD-T80 & SL(D)-T80 & \multirow[b]{2}{*}{315} & & \\
\hline UN-YY80 & S-T100 & SD-T100 & SL(D)-T100 & & M8×2 & \\
\hline UN-YY125 & S-N125 & SD-N125 & SL(D)-N125 & 400 & M10×2 & \\
\hline UN-YY150 & S-N150 & SD-N150 & SL(D)-N150 & 500 & \(\mathrm{M} 12 \times 2\) & \\
\hline
\end{tabular}


UN-YY35

Note 1. Please consult us regarding the combination of models other than the above.
Note 2. The power supply side and load side make up a set of 2.
Note 3. When installing UN-YY150, follow the steps below.
(1) Loosen the arc box mounting screws (2 pcs.) and remove the arc box.
(2) Remove the insulation barrier of the terminal where the conductor will be mounted.
(3) Mount the arc box.
(4) Mount the conductor.

Note 4. Minimum Order Unit 1 (for 1 Unit)

\section*{Outline Drawing}
\begin{tabular}{|c|c|c|}
\hline When Combining UT-YY20 & When Combining UN-YY21 & When Combining UN-YY35 \\
\hline  &  &  \\
\hline When Combining UN-YY50 & When Combining UN-YY80 & When Combining UN-YY125 \\
\hline  &  &  \\
\hline When Combining UN-YY150 & \multicolumn{2}{|r|}{\multirow[b]{2}{*}{\begin{tabular}{l}
*1 : Install the 3-pole array connection unit once the coil terminal has been tightened. \\
*2 : A live part protection cover cannot be attached. \\
*3: UN-YY21 and UN-YY35 cannot be installed together with UT-SY \(\square\).
\end{tabular}}} \\
\hline  & & \\
\hline & & - Terminal Screw Tightening Torque \\
\hline Model Name \(\quad\) Model Name & & Screw Size \({ }^{\text {Tightening Torque ( } \mathrm{N} \cdot \mathrm{m} \text { ) }}\) \\
\hline UT-YY20 UN-YY50 & & M6 \(\quad 3.53\) to 5.78 \\
\hline UN-YY21 & & M8 \(\quad 6.28\) to 10.29 \\
\hline UN-YY35 \({ }^{\text {U }}\) UN-YY125 & & M10 11.8 to 19.1 \\
\hline UN-YY150 & & M12 19.6 to 31.3 \\
\hline
\end{tabular}

\section*{8 \\ Optional Units}

\subsection*{8.10 UT/UN-SY \(\square\) DC/AC Interface Units for Operation Coils}

DC/AC interface unit for operation coils that switches AC-operated magnetic contactors and contactor relays at the output (DC24 V) of electronics such as PLCs. Both contactless (triac) output and contact (relay) output are available.

Model
\begin{tabular}{|c|c|c|c|}
\hline Unit Model & Output Method & Unit Mounting Method & Applicable Magnetic Contactor, Contactor Relay Model \\
\hline UT-SY21 & \multirow[t]{2}{*}{Contactless Output (Triac Output)} & \multirow{4}{*}{Top-On Additional Mounting} & \\
\hline UT-SY21BC & & & S-T10 to T50 \\
\hline UT-SY22 & \multirow[t]{2}{*}{Contact Output (Relay Output)} & & SR-T5, T9 \\
\hline UT-SY22BC & & & \\
\hline UN-SY11 & Contactless Output (Triac Output) & Independent & \[
\begin{aligned}
& \hline \text { S-T10 to T100 } \\
& \text { SR-T5, T9 }
\end{aligned}
\] \\
\hline UN-SY12 & Contact Output (Relay Output) & Mounting & \[
\begin{aligned}
& \text { S-N125 to N400 } \\
& \text { SR-K100 }
\end{aligned}
\] \\
\hline UN-SY21 & \multirow[t]{3}{*}{Contactless Output (Triac Output)} & \multirow{6}{*}{Top-On Additional Mounting} & S-N38, N48 \\
\hline UN-SY21CX & & & S-N38CX, N48CX \\
\hline UN-SY31 & & & S-T65, T80 \\
\hline UN-SY22 & \multirow[t]{3}{*}{Contact Output (Relay Output)} & & S-N38, N48 \\
\hline UN-SY22CX & & & S-N38CX, N48CX \\
\hline UN-SY32 & & & S-T65, T80 \\
\hline
\end{tabular}


UN-SY21


UT-SY21

Note 1. The coil voltage designation of AC100V or AC200V can be applied for the operation coil.
Note 2. UT-SY \(\square\) BC is the model name with wiring streamlining terminals.
Note 3. UN-SY \(\square C X\) is the model name with CAN terminals.

\section*{Specifications}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{3}{|c|}{Model} & UT-SY21(BC) & UT-SY22(BC) & UN-SY11 & UN-SY21(CX) & UN-SY31 & UN-SY12 & UN-SY22(CX) & UN-SY32 \\
\hline \multirow{6}{*}{} & \multicolumn{2}{|l|}{Rated Operational Voltage} & \multicolumn{2}{|l|}{DC24 V} & \multicolumn{6}{|c|}{DC24 V} \\
\hline & \multicolumn{2}{|l|}{Tolerable Voltage Fluctuation} & \multicolumn{2}{|l|}{85 to \(110 \%\) of Rated Operational Voltage} & \multicolumn{6}{|c|}{85 to 110\% of Rated Operational Voltage} \\
\hline & Current & & 15 mA & 10 mA & \multicolumn{3}{|c|}{15 mA} & \multicolumn{3}{|c|}{10 mA} \\
\hline & Power Cons & sumption & 0.4 W & 0.24 W & \multicolumn{3}{|c|}{0.4 W} & \multicolumn{3}{|c|}{0.24 W} \\
\hline & Minimum Closin & sing Voltage & 18 V & 18 V & \multicolumn{3}{|c|}{18 V} & \multicolumn{3}{|c|}{18 V} \\
\hline & Maximum Open & ning Voltage & 4 V & 1 V & & 4 V & & \multicolumn{3}{|c|}{1 V} \\
\hline \multirow{7}{*}{} & Output Spe & cifications & Contactless Output(Triac Output) & Contact Output & Conta & ess Output (Triac & utput) & & Contact Output & \\
\hline & Rated workin & ng Voltage & \multicolumn{2}{|l|}{AC100 to AC240 V 50/60 Hz} & \multicolumn{6}{|c|}{AC100 to AC240 V 50/60 Hz} \\
\hline & \multicolumn{2}{|l|}{Rated Operational Current} & \multicolumn{2}{|l|}{\(0.5 \mathrm{~A}, \mathrm{AC}-15\)} & \multicolumn{6}{|c|}{\(0.5 \mathrm{~A}, \mathrm{AC}-15\)} \\
\hline & Leakage Curren & at when open & \(5 \mathrm{~mA} / 240 \mathrm{~V}\) & None & \multicolumn{3}{|c|}{\(5 \mathrm{~mA} / 240 \mathrm{~V}\)} & \multicolumn{3}{|c|}{None} \\
\hline & Operating & Time & \[
\begin{array}{|l|}
\hline \begin{array}{l}
\text { ms in Operation } 0.5 \text { Cycles } \\
+1 \\
+1 \text { ms or Less in Open Circait }
\end{array} \\
\hline
\end{array}
\] & 10 ms or less & \multicolumn{3}{|l|}{1 ms in Operation, 0.5 Cycles +1 ms or Less in Open Circuit} & \multicolumn{3}{|c|}{10 ms or less} \\
\hline & \multirow[t]{2}{*}{Durability} & Mechanical & - & 5 mil. times & \multicolumn{3}{|l|}{-} & \multicolumn{3}{|c|}{5 mil. times} \\
\hline & & Electrical & - & 5 mil. times & \multicolumn{3}{|c|}{-} & 1 mil. times (Note 1) & 5 mil. times & 1 mil. times \\
\hline \multicolumn{3}{|r|}{Working Temperature} & \multicolumn{2}{|l|}{\(-10^{\circ} \mathrm{C}\) to \(55^{\circ} \mathrm{C}\)} & \multicolumn{6}{|c|}{\(-10^{\circ} \mathrm{C}\) to \(55^{\circ} \mathrm{C}\)} \\
\hline \multicolumn{2}{|l|}{\multirow{3}{*}{Applicable Terminal Wire}} & Wire & \multicolumn{2}{|l|}{\(\varphi 1.6 \mathrm{~mm}, 0.75\) to \(2.5 \mathrm{~mm}^{2}\)} & \multicolumn{6}{|c|}{\(\varphi 1.6 \mathrm{~mm}, 1.25\) to \(2 \mathrm{~mm}^{2}\)} \\
\hline & & Crimp minal & \multicolumn{2}{|l|}{1.25-3.5, 2-3.5} & \multicolumn{6}{|c|}{1.25-3.5, 2-3.5} \\
\hline & & Tightening Toque & \multicolumn{2}{|l|}{0.9 to \(1.5 \mathrm{~N} \cdot \mathrm{~m}\)} & \multicolumn{6}{|c|}{0.9 to \(1.5 \mathrm{~N} \cdot \mathrm{~m}\)} \\
\hline
\end{tabular}

Note 1. Using UN-SY12 and SR-K100 in combination achieves 5 million times.

\section*{Connection Example (Connection Diagram)}
\begin{tabular}{|c|c|c|}
\hline UT-SY21(BC) & UN-SY21(CX) & UN-SY22(CX) \\
\hline  &  &  \\
\hline UT-SY22(BC) & UN-SY11, SY31 & UN-SY12, SY32 \\
\hline  &  &  \\
\hline
\end{tabular}

\section*{Outline Drawings/Mounting}
(1) UN-SY11, SY12 (Independent Mounting)

Cannot be directly attached to a magnetic contactor or contactor relay: screw-mount into holes drilled at the following dimensions near the magnetic contactor.

(2) UT-SY21, SY22


UN-SY21(CX), SY22(CX) [Figure Has No CX]

<Mounting Method> Loosen the screws of the coil terminals A1 and A2 of the magnetic contactor or contactor relay, insert the protrusion of the DC/AC interface unit into the groove, then insert and fasten the conductor into the coil terminal.

\section*{Optional Units}

(3) UN-SY31, SY32

<Mounting Method>
Remove the screws of the coil terminal A2 of the magnetic contactor, align the protrusion of the DC/AC interface unit and groove of the magnetic contactor while the supplied connecting conductor is mounted on the A1 terminal of the DC/AC interface unit, then tighten the connecting conductor with the removed coil terminal screws.


Dimensions After Additional Mounting
\begin{tabular}{|l|c|l|}
\hline Model Name & Model Name & Model Name \\
\hline UT-SY21 & UN-SY11 & UN-SY12 \\
\hline UT-SY21BC & UN-SY21 & UN-SY21CX \\
\hline UT-SY22 & UN-SY22 & UN-SY22CX \\
\hline UT-SY22BC & UN-SY31 & UN-SY32 \\
\hline
\end{tabular}

\subsection*{8.11 UT/UN-CV \(\square\) and CZ \(\square\) Live Part Protection Cover Units}

Covers for preventing inadvertent contact with live parts after wiring in panel mounting.

\section*{Applicable Models \(\rightarrow\) Model Names for Live Part Protection Covers}
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline & & \multicolumn{3}{|c|}{Applicable Models} & \multicolumn{2}{|l|}{Model Names for Live Part Protection Covers} \\
\hline & & AC Operated & DC Operated & Mechanically Latched Type & For Magnetic Contactors & For Thermal Overload Relays \\
\hline \multirow{25}{*}{} & \multirow{13}{*}{} & S-N38/N48 & - & - & UN-CV250 & - \\
\hline & & S-T65/T80, DU-N30 & SD-T65/T80, DUD-N30 & SL(D)-T65/T80 & UN-CZ500 (2 Units Required for Power Supply and Load Sides) (Note 8 *') & - \\
\hline & & \[
\begin{aligned}
& \hline S-T 100, \\
& B-N 65
\end{aligned}
\] & \[
\begin{aligned}
& \hline \begin{array}{l}
\text { SD-T100, } \\
\text { BD-N65 }
\end{array} \\
& \hline
\end{aligned}
\] & SL(D)-T100 & \[
\begin{array}{|c|}
\hline \text { UN-CZ800 (2 Units Required for } \\
\text { Power Supply and Load Sides) (Note } 8 * 2 \text { ) }
\end{array}
\] & - \\
\hline & & S-N125,B-N100,DU-N60 & \[
\begin{aligned}
& \text { SD-N125,BD-N100, } \\
& \text { DUD-N60 }
\end{aligned}
\] & SL(D)-N125 & UN-CZ1250 (2 Units Required for Power Supply and Load Sides) (Note \(8{ }^{* 2}\) ) & - \\
\hline & & S-N150,DU-N120 & SD-N150,DUD-N120 & SL(D)-N150 & UN-CZ1500(2 Units Required for Pover Supply and Load Sides) Mote 8*) & - \\
\hline & & S-N180/N220,DU-N180 & SD-N220,DUD-N180 & SL(D)-N220 & UN-Cz22002 U Units Required for Pover Supply and Load Sides) Note 8*) & - \\
\hline & & S-N300/N400,DU-N260 & \[
\begin{array}{|l|}
\hline \text { SD-N300/ } \\
\text { N400,DUD-N260 }
\end{array}
\] & SL(D)-N300/N400 & UN-CZ3000 (2 Units Required for Power Supply and Load Sides)(Note \(8{ }^{* 2}\) ) & - \\
\hline & & MSO-T65/T80 & MSOD-T65/T80 & MSOL(D)-T65/T80 & UN-CZ250 (Power Supply Side), UN-C2501 (Load Side) (Note 8*) & - \\
\hline & & MSO-T100 & MSOD-T100 & MSOL(D)-T100 & UN-CC880) (Power Supply Side), UN-C7801 (Load Side) (Note 8*) & - \\
\hline & & MSO-N125 & MSOD-N125 & MSOL(D)-N125 & UN:CZ1150 (Power Suppl) Side), UN-CZ71251 (Load Side) (Note \(8^{\text {*) }}\) & - \\
\hline & & MSO-N150 & MSOD-N150 & MSOL(D)-N150 & UN:CZ1500 (Power Supply Side), UN-CZ1501 (Load Side) (Note 8*) & - \\
\hline & & MSO-N180/N220 & MSOD-N220 & MSOL(D)-220 & UN-CZ2200 (Power Supply Side), UN-CZ2201 (Load Side) (Note \(8^{\text {**) }}\) & - \\
\hline & & MSO-N300/N400 & MSOD-N300/N400 & MSOL(D)-N300/N400 & UN:CZ3300 (Power Suppl) Side), UN-Cz301 (Load Side) (Note \(8^{\text {* }}\) ) & - \\
\hline & \multirow{12}{*}{} & \[
\begin{aligned}
& \hline \text { S- } 2 \times \mathrm{T} 65 / \mathrm{T} 80, \\
& \text { DU- } 2 \times \mathrm{N} 30 \\
& \hline
\end{aligned}
\] & \[
\begin{aligned}
& \hline \text { SD-2 x T65/T80, } \\
& \text { DUD-2 } 2 \times \text { N30 } \\
& \hline
\end{aligned}
\] & SL(D)-2 x T65/T80 & UN-CZ502 (Note \(8{ }^{* 3}\) ) & - \\
\hline & & S-2 x T100 & SD-2 \(\times\) T100 & SL(D)-2 \(\times\) T100 & UN-CZ802 (Note \(8{ }^{* 4}\) ) & - \\
\hline & & \[
\begin{array}{|l|}
\hline S-2 \times N 125, \\
\text { DU-2 x N60 } \\
\hline
\end{array}
\] & \[
\begin{aligned}
& \hline \text { SD-2 x N125, } \\
& \text { DUD-2 x N60 }
\end{aligned}
\] & SL(D)-2 \(\times\) N125 & UN-CZ1252 (Note \(8{ }^{* 4}\) ) & - \\
\hline & & S-2 x N150, DU-2 x N120 & SD-2 x N150, DUD-2 x N120 & SL(D)-2 \(\times\) N150 & UN-CZ1502 (Note \(8{ }^{* 4}\) ) & - \\
\hline & & \[
\begin{array}{|l}
\hline \text { S-2 x N180/N220, } \\
\text { DU-2 x N180 } \\
\hline
\end{array}
\] & \[
\begin{aligned}
& \text { SD-2 x N220, } \\
& \text { DUD-2 } 2 \text { N180 }
\end{aligned}
\] & SL(D)-2 x N220 & UN-CZ2202 (Note \(8{ }^{* 4}\) ) & - \\
\hline & & \[
\begin{aligned}
& \text { S-2 x N300/N400, } \\
& \text { DU-2 x N260 }
\end{aligned}
\] & \[
\begin{aligned}
& \text { SD-2 } \times \text { N300/N400, } \\
& \text { DUD-2 } 2 \text { N260 }
\end{aligned}
\] & SL(D)-2 \(\times\) N300/N400 & UN-CZ3002 (Note \(8{ }^{* 4}\) ) & - \\
\hline & & MSO-2 \(\times\) T65/T80 & MSOD-2 \(\times\) T65/T80 & MSOL(D)-2 \(\times\) T65/T80 & UN-CZ504 & (Note 8 *) \\
\hline & & MSO-2 x T100 & MSOD-2 \(\times\) T100 & MSOL(D) \(-2 \times\) T100 & UN-CZ804 & (Note \(8{ }^{* 4}\) ) \\
\hline & & MSO-2 x N125 & MSOD-2 x N125 & MSOL(D)-2 \(\times\) N125 & UN-CZ1254 & (Note \(8{ }^{* 4}\) ) \\
\hline & & MSO-2 x N150 & MSOD-2 x N150 & MSOL(D)-2 \(\times\) N150 & UN-CZ1504 & (Note \(8{ }^{* 4}\) ) \\
\hline & & MSO-2 x N180/N220 & MSOD-2 x N220 & MSOL(D)-2 \(\times\) N220 & UN-CZ2204 & (Note \(8{ }^{* 4}\) ) \\
\hline & & MSO-2 x N300/N400 & MSOD-2 \(\times\) N300/N400 & MSOL(D)-2 \(\times\) N300/N400 & UN-CZ3004 & (Note \(8{ }^{* 4}\) ) \\
\hline \multicolumn{2}{|l|}{\multirow{4}{*}{Thermal Overload Relays}} & \multicolumn{3}{|c|}{TH-T65 (Not available with SR)} & - & UN-CZ605 (Live Part Protection Cover) \\
\hline & & \multicolumn{3}{|c|}{TH-T25/T50} & - & UN-CV203 (Current Setting Dial M Misperation Perenerion Cove) (Note 10) \\
\hline & & \multicolumn{3}{|c|}{TH-T65/T100,TH-N120 to N600} & - & UNCVV603 (Current Seting Dial Mispenation Preverition Cover) (Note 10) \\
\hline & & \multicolumn{3}{|c|}{ET-N60} & - & UN-CV602(Live Part Protection Cover) \\
\hline \multicolumn{2}{|c|}{\multirow{6}{*}{Other}} & \multicolumn{2}{|r|}{UN-AX2} & - & \multicolumn{2}{|l|}{\multirow{3}{*}{UN-CV20}} \\
\hline & & \multicolumn{2}{|r|}{UN-AX4} & - & & \\
\hline & & \multicolumn{2}{|r|}{UN-LL22} & - & & \\
\hline & & \multicolumn{3}{|c|}{UN-AX80} & \multicolumn{2}{|l|}{UN-CZ808} \\
\hline & & S-T65/T80 & SD-T65/T80 & - & \multicolumn{2}{|l|}{UN-CV117 (Magnetic Contactor Manual Operation Prevention Cover)} \\
\hline & & S-T10 to T50/B-T21/SR-T5 SQ & SD-T12 to T50/BD-T21/SRD-T5 SQ & - & \multicolumn{2}{|l|}{UT-CV107 (Magnetic Contactor/Contactor Relay Manual Operation Prevention Cover)} \\
\hline
\end{tabular}

Note 1. Refer to page 194 for model names \(\rightarrow\) applicable models for live part protection covers.
Note 2. UN-CZ \(\square 1\) collectively covers the load-side terminals and thermal overload relays of magnetic contactors. Since it is used by mounting on the magnetic contactor side, it cannot be used for the thermal overload relay alone.
Note 3. Avoid solvents such as strong alkali, aromatic hydrocarbons and chlorine, adhesion of oil or use in an excessively gaseous atmosphere.
Note 4. Since deformation may occur due to humidity, avoid use under high humidity as much as possible.
Note 5. UN-CZ \(\square 2\) and CZ \(\square 4\) come in a set as 4 covers that are necessary for the reversible magnetic contactor and reversible magnetic starter.
Note 6. When the live part protection covers UN-CV \(\square\) and CZ \(\square\) are used, the reset release UN-RR \(\square\) for thermal overload relays cannot be used.
Note 7. Refer to page 343 regarding the live part protection cover UN-CV602 for ET-N60.
Note 8 . Use the following live part protection covers for the mechanical latch mechanism of the mechanically latched type.
* 1: UN-CZ506 (1 pc) *2: UN-CZ806 (1 pc) *3: UN-CZ506 (2 pcs) *4: UN-CZ806 (2 pcs)

Note 9. UN-CV603 cannot be combined with TH-N120TAHZ.
Note 10. This is a misoperation prevention cover and not a live part protection cover.
Note 11. The units that can be used with the spring clamp terminal models are marked with "SQ" in the Applicable Models column.
For the spring clamp terminal models, refer to pages 125 and 175.

\section*{Potential Combinations of Live Part Protection Covers and Other Optional Units}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{Live Part Protection/Misoperation Prevention Covers} & \multicolumn{4}{|c|}{Auxiliary Contact Units (Including Low-Level Signals)} & Main Circuit Surge Absorber Units & Reset Releases & Fluorescent Display Lamps & \multicolumn{2}{|l|}{Main Circuit Conductor Kits} \\
\hline Type & Model Name & \[
\begin{array}{|c|}
\hline \text { UN-AX2 } \\
\text { UN-AX4 } \\
\text { UN-LL22 }
\end{array}
\] & UN-AX11 & UN-AX80 & UN-AX150 & \[
\begin{aligned}
& \text { UT-SA3320 } \\
& \text { UT-SA3332 }
\end{aligned}
\] & UTUN-RRDI & UN-TLD & UTUN-SDEI UT/UN-SGEC & UN-YGDI
UT/UN-YDID
UT/UN-YYDI \\
\hline Contactor Manual Operation Prevention Cover & UT-CV107/UN-CV117 & x & \(\bigcirc\) & - & - & x/- & - & - & \(\bigcirc\) & \(\bigcirc\) \\
\hline Live Part Protection Cover for UN-AX2/4 & UN-CV20 & \(\bigcirc\) & -*1 & - & - & - & x & x & - & - \\
\hline \multirow{3}{*}{Contactor Live Part Protection Cover} & UN-CZ500 & \({ }^{*}{ }^{2}\) & -*1 & - & - & - & - & - & - & x \\
\hline & UN-CZ800, CZ1250 & - & - & O*3 & - & - & - & - & - & x \\
\hline & \[
\begin{aligned}
& \text { UN-CZ1500, CZ2200, } \\
& \text { CZ3000 }
\end{aligned}
\] & - & - & - & \(\bigcirc\) & - & - & - & - & x \\
\hline \multirow[b]{3}{*}{Contactor/Thermal Relay Live Part Protection Cover} & UN-CZ501 & O*2 & ○*1 & - & - & - & x & x & - & - \\
\hline & UN-CZ801, CZ1251 & - & - & O*3 & - & - & x & x & - & - \\
\hline & \[
\begin{aligned}
& \text { UN-CZ1501, CZ2201, } \\
& \text { CZ3001 }
\end{aligned}
\] & - & - & - & \(\bigcirc\) & - & x & x & - & - \\
\hline \multirow{3}{*}{Contactor Live Part Protection Cover} & UN-CZ502 & O*2 & -*1 & - & - & - & - & - & \(\bigcirc\) & - \\
\hline & UN-CZ802, CZ1252 & - & - & O*3 & - & - & - & - & \(\bigcirc\) & - \\
\hline & \[
\begin{aligned}
& \text { UN-CZ1502, CZ2202, } \\
& \text { CZ3002 }
\end{aligned}
\] & - & - & - & \(\bigcirc\) & - & - & - & \(\bigcirc\) & - \\
\hline \multirow{3}{*}{\begin{tabular}{l}
Contactor/Thermal Relay \\
Live Part \\
Protection Cover
\end{tabular}} & UN-CZ504 & O*2 & O*1 & - & - & - & x & x & - & - \\
\hline & UN-CZ804, CZ1254 & - & - & ○*3 & - & - & x & x & - & - \\
\hline & \[
\begin{aligned}
& \hline \text { UN-CZ1504, CZ2204, } \\
& \text { CZ3004 } \\
& \hline
\end{aligned}
\] & - & - & - & \(\bigcirc\) & - & x & x & - & - \\
\hline \multirow[b]{2}{*}{Latch Mechanism Live Part Protection Cover} & UN-CZ506 & x & O*1 & - & - & - & - & - & x & x \\
\hline & UN-CZ806 & - & - & ○*3 & - & - & - & - & x & x \\
\hline TH-T65 Live Part Protection Cover & UN-CZ605 & - & - & - & - & - & x & x & - & - \\
\hline Thermal Dial Misoperation Prevention Cover & UN-CV203, CV603 & - & - & - & - & - & x & x & - & - \\
\hline
\end{tabular}

Note 1. Meaning of the Symbols: \(\bigcirc\) : Applicable, \(x\) : Not Applicable, -: Not Combinable
Note 2. Models with * have the following conditions.
\({ }^{*}\) 1: Since the body side is protected by a live part protection cover but UN-AX11 is not, use UN-AX11CX.
\({ }^{*} 2\) : Since the body side is protected by a live part protection cover but UN-AX2/4 is not, use UN-AX2/4CX or UN-CV20.
*3: Since the body side is protected by a live part protection cover but UN-AX80 is not, use the UN-CZ808 protection cover for UN-AX80.
Note 3. The following units other than the ones in the above table can be combined regardless of whether there is a live part protection cover.
(1) Operation Coil Surge Absorber Units: UN-SA721, SA712, SA722, SA713, SA723, SA725
(2) Interface Units: SY21(CX), SY31, SY22(CX), SY32

However, the live part of UN-SY21, SY22, SY31, and SY32 cannot be protected.
(3) Reversing Units: UN-ML21, ML80, ML150, ML220

\section*{Outline Drawings}
(1) UN-CV \(\square \square\) (Table at right)

Cover Outline Drawings: A x B x C
Outline Drawings of Applicable Models: AB x BA
Depth that increases when the cover is attached: D
(- indicates that there is no change in the depth when the cover is attached.)

\begin{tabular}{l|c|c|c|c|c|c|c|c}
\hline \multirow{2}{*}{ Model Name } & \multicolumn{9}{|c}{ Variable Dimensions } \\
\cline { 2 - 9 } & A & B & C & D & AB & BA & AC & BC \\
\hline UN-CV20 & 43 & 80 & 6 & 1 & 43 & 78 & 0 & 0 \\
\hline UN-CV250 & 75 & 107 & 2.8 & - & 75 & 91 & 0 & 7.5 \\
\hline UN-CV203 & 27 & 28 & 20 & 5.5 & & & & \\
\hline UN-CV603 & 29 & 27.5 & 19.2 & 5.5 & & & & \\
\hline UN-CV117 & 23 & 29 & 7 & 2 & & & & \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline & \multicolumn{2}{|l|}{Combined Unit Name} & \multicolumn{11}{|c|}{Outline Drawings} \\
\hline & Power Supply Side Unit & Load Side Unit & C & D & E & F & G & H & S/MSO & \[
1
\] & \[
\underset{(B o d y)}{J}
\] & K & L \\
\hline \multirow[t]{6}{*}{} & UN-CZ500 & UN-CZ500 & 32.5 & 75 & 140 & 92 & -3.5 & 60.5 & 45.5 & 72.5 & 88 & 2 & 2 \\
\hline & UN-CZ800 & UN-CZ800 & 36.5 & 110 & 183 & 104 & 2 & 67.5 & 59.5 & 89.5 & 100 & 2 & 2 \\
\hline & UN-CZ1250 & UN-CZ1250 & 34.5 & 125 & 204 & 104 & 6.5 & 86 & 51 & 76 & 100 & 2 & 2 \\
\hline & UN-CZ1500 & UN-CZ1500 & 49.51052 & 12510130 & 229 & 154 & 7 & 96 & 49 & 73.5 & 120 & 17 & 17 \\
\hline & UN-CZ2200 & UN-CZ2200 & 42 & 190 & 274 & 170 & 7 & 113 & 62 & 87.5 & 138 & 16 & 16 \\
\hline & UN-CZ3000 & UN-CZ3000 & 46.5 & 225 & 318 & 192 & 7 & 126 & 69 & 95 & 163 & 14.5 & 14.5 \\
\hline \multirow[t]{6}{*}{} & UN-CZ500 & UN-CZ501 & 32.5 & 75 & 188 & 96 & -3.5 & 60.5 & 45.5 & 72.5 & 90 & 4 & 2 \\
\hline & UN-CZ800 & UN-CZ801 & 36.5 & 110 & 254 & 104 & 2 & 67.5 & 59.5 & 89.5 & 100 & 2 & 2 \\
\hline & UN-CZ1250 & UN-CZ1251 & 34.5 & 125 & 296 & 125 & 6.5 & 86 & 51 & 76 & *112 & *9.8 & *3.2 \\
\hline & UN-CZ1500 & UN-CZ1501 & 49.51052 & 12550130 & 325 & 154 & 7 & 96 & 49 & 73.5 & 120 & 17 & 17 \\
\hline & UN-CZ2200 & UN-CZ2201 & 42 & 190 & 363 & 170 & 10 & 128 & 47 & 72.5 & 144 & 13 & 13 \\
\hline & UN-CZ3000 & UN-CZ3001 & 46.5 & 225 & 445 & 192 & 7 & 135 & 60 & 86 & 163 & 14.5 & 14.5 \\
\hline
\end{tabular}
*Dimensions shown are that of TH-N120TA.
(5) UN-CZ504 to CZ3004 (Table below)



Note 1. The model name display is UN-CZ \(\square 0\) for units A, B and C, and UN-CZ \(\square 1\) for unit D.
Note 2. Since the mounting position of the reversing connecting conductor is processed, units \(A, B, C\) and \(D\) are respectively stamped with "A", "B", "C" and "D" for identification.
(4) UN-CZ502 to CZ3002 (Table below)

\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline & \multirow{3}{*}{Frame} & \multirow[t]{3}{*}{\begin{tabular}{l}
Set \\
Model Name
\end{tabular}} & \multicolumn{10}{|c|}{Outline Drawings} \\
\hline & & & \multirow{2}{*}{C} & \multirow{2}{*}{D} & \multirow{2}{*}{E} & \multirow{2}{*}{F} & \multirow[b]{2}{*}{G} & \multirow[t]{2}{*}{H} & \multicolumn{2}{|r|}{I} & \multirow[b]{2}{*}{J} & \multirow[b]{2}{*}{K} \\
\hline & & & & & & & & & S & SD & & \\
\hline \multirow[t]{6}{*}{} & T65/780 & UN-CZ502 & 23 & 100 & 140 & 190 & -3.5 & 60.5 & 51.5 & 78.5 & 216 & -13 \\
\hline & T100 & UN-CZ802 & 58.5 & 100 & 183 & 241 & 2 & 67.5 & 69.5 & 99.5 & 270 & 14.5 \\
\hline & N125 & UN-CZ1252 & 34.5 & 125 & 204 & 243 & 6.5 & 86 & 62 & 87 & 276 & 16.5 \\
\hline & N150 & UN-CZ1502 & 52 & 125 & 229 & 294 & 7 & 96 & 60 & 84.5 & 296 & 1 \\
\hline & N180/N200 & UN-CZ2202 & 42 & 190 & 274 & 330 & 7 & 113 & 76 & 101.5 & 370 & -20 \\
\hline & N300/N400 & UN-CZ3002 & 46.5 & 225 & 318 & 374 & 7 & 126 & 83 & 109 & 395 & -10.5 \\
\hline
\end{tabular}

Note 1. The model name display of the units is UN-CZ \(\square 0\)
Note 2. Since the mounting position of the reversing connecting conductor is processed, units \(A\) and \(B\) are respectively stamped with " \(A\) " and " \(B\) " for identification.

\section*{8 Optional Units}
(6) UN-CZ605

(10) UN-CV602

- Mounting Method
\begin{tabular}{|l|l|l|l|l|}
\hline Live Part Protection Cover & & Mounting Method \\
\hline
\end{tabular}
(8) UN-CZ506

(7)

\begin{tabular}{|l|c|}
\hline Applicable Magnetic Contactors & A \\
\hline S, SL(D)-T100 & 7.5 \\
\hline SD-T100 & 37.5 \\
\hline S, SL(D)-N125 & 9 \\
\hline SD-N125 & 34 \\
\hline
\end{tabular}
(9) UN-CZ806 (Table at right)
- Dimensions when mounted on the magnetic contactor (figure at left shows SL-N125.)
Magnetic Contactor (figure at left shows
\begin{tabular}{|l|c|c|c|c|}
\hline SL-N125.) \\
\hline \begin{tabular}{c} 
Applicable Magnetic \\
Contactors
\end{tabular} & \multicolumn{4}{|c|}{ Outline Drawing } \\
\cline { 2 - 5 } & A & B & C & D \\
\hline SL(D)-T100 & 63.5 & 8.5 & 74 & 101.5 \\
\hline SL(D)-N125 & 65 & 8.5 & 76 & 125 \\
\hline SL(D)-N150 & 67 to 69.5 & 8.5 & 76 & 125 to 130 \\
\hline SL(D)-N220 & 38.5 & 8.5 & 78 & 190 \\
\hline SL(D)-N300/N400 & 36.5 & 8.5 & 81 & 225 \\
\hline
\end{tabular}


\begin{tabular}{|c|c|c|c|c|c|c|}
\hline Live Part Protection Cover & \multicolumn{6}{|c|}{Mounting Method} \\
\hline UN-CZ506 & \multicolumn{4}{|c|}{} & \multicolumn{2}{|l|}{Tighten the enclosed two M3 screws, then attach the cover.} \\
\hline & \multirow[t]{3}{*}{} & \multicolumn{5}{|l|}{[A Detailed View]} \\
\hline & & \multicolumn{3}{|l|}{With Rectifier} & \multicolumn{2}{|l|}{Without Rectifier} \\
\hline UN-CZ806 & &  & & left, loosen the are tightening the Ce UN-CZ806 under n of the rectifier, then screws. &  & Tighten using the provided screws and washers. (Place the washer between the screw and UN-CZ806.) \\
\hline UN-CV602 & Fig. (1) &  & & \multicolumn{3}{|l|}{\begin{tabular}{l}
1. Insert protrusion \(A\) of the live part protection cover into groove A of the ET-N upper surface. (Figs. (1) and (2)) \\
2. Press the live part protection cover B claw in the direction of the arrow and insert it into the B groove of the ET-N lower surface. (Figs. (1) and (2))
\end{tabular}} \\
\hline
\end{tabular}
Misoperation Prevention Cover

Removal Method
\begin{tabular}{|c|c|c|}
\hline Live Part Protection Cover & \multicolumn{2}{|c|}{Removal Method} \\
\hline \begin{tabular}{l}
UN-CZ500 \\
UN-CZ501 \\
UN-CZ502 \\
UN-CZ504
\end{tabular} &  & \begin{tabular}{l}
Insert a flat head screwdriver into the square hole with the UNLOCK arrow in the cover center and move the screwdriver in the direction as shown on the left to remove the cover. \\
(Arrow Direction in Figure at Left)
\end{tabular} \\
\hline \begin{tabular}{l}
UN-CZ800 \\
UN-CZ801 \\
UN-CZ802 \\
UN-CZ804 \\
UN-CZ605
\end{tabular} &  & Hold the cover with both hands and remove it. (Arrow Direction in Figure at Left) \\
\hline \begin{tabular}{l}
UN-CZ1250 \\
UN-CZ1251 \\
UN-CZ1252 \\
UN-CZ1254 \\
UN-CZ1500 \\
UN-CZ1501 \\
UN-CZ1502 \\
UN-CZ1504 \\
UN-CZ2200 \\
UN-CZ2201 \\
UN-CZ2202 \\
UN-CZ2204 \\
UN-CZ3000 \\
UN-CZ3001 \\
UN-CZ3002 \\
UN-CZ3004
\end{tabular} & \begin{tabular}{l}
(1) \\
(2)
\end{tabular} & \begin{tabular}{l}
Slide (in the direction of the arrow at left) the stopper to the UNLOCK position to remove the lock of the cover. \\
Make sure that the stopper of the cover is in the UNLOCK position, then remove the cover while supporting it by hand. \\
(Arrow Direction in Figure at Left)
\end{tabular} \\
\hline
\end{tabular}

\section*{- Minimum Order Unit}
\begin{tabular}{|l|c|l|c|}
\hline Model Name & Minimum Order Unit (Sheet or Piece) & Model Name & Minimum Order Unit (Sheet or Piece) \\
\hline UN-CV20 & 10 & UN-CZ802 & 1 \\
\hline UN-CZ500 & 1 & UN-CZ1502 & 1 \\
\hline UN-CZ800 & 1 & UN-CZ2202 & 1 \\
\hline UN-CZ1250 & 1 & UN-CZ3002 & 1 \\
\hline UN-CZ1500 & 1 & UN-CZ504 & 1 \\
\hline UN-CZ2200 & 1 & UN-CZ804 & 1 \\
\hline UN-CZ3000 & 1 & UN-CZ1254 & 1 \\
\hline UN-CZ501 & 1 & UN-CZ1504 & 1 \\
\hline UN-CZ801 & 1 & UN-CZ2204 & 1 \\
\hline UN-CZ506 & 1 & UN-CZ3004 & 1 \\
\hline UN-CZ806 & 1 & UN-CZ605 & 1 \\
\hline UN-CZ808 & 1 & UN-CV203 & 1 \\
\hline UN-CZ1251 & 1 & UN-CV603 & 1 \\
\hline UN-CZ1501 & 1 & UN-CV117 & 10 \\
\hline UN-CZ2201 & 1 & UT-CV107 & 10 \\
\hline UN-CZ3001 & 1 & \multicolumn{4}{|c}{} \\
\hline UN-CZ502 & 1 & & \\
\cline { 1 - 2 }
\end{tabular}

Note 1. Those with the minimum order unit of 10 will be shipped with 10 (sheets or pieces) per bag.
Note 2. Order those with the minimum order unit of 10 in a multiple of 10.

\subsection*{8.12 UT-CW \(\square\) Terminal Cover Units}

Terminal cover with high safety that can be attached later.
- Finger protection function that complies with the DIN and VDE standards, improving electric shock prevention and safety during maintenance and inspection.
- The auxiliary terminal cover of the UT-CW \(\square\) terminal protection cover cannot be installed after wiring work. Also, ring crimp lugs wiring to the auxiliary contact terminal cannot be applied.

\section*{Applicable Models}
\begin{tabular}{l|c|c}
\hline \multirow{2}{*}{ Model Name } & \multicolumn{2}{|c}{ Applicable Models: Magnetic Contactors } \\
\cline { 2 - 3 } & AC Operated & DC Operated \\
\hline UT-CW800 & S-T65,T80 & SD-T65,T80 \\
\hline
\end{tabular}
\begin{tabular}{l|c}
\hline Model Name & \begin{tabular}{c} 
Applicable Models: Thermal \\
Overload Relays
\end{tabular} \\
\hline UT-CW655 & TH-T65 (Not available with SR) \\
\hline
\end{tabular}

- Mounting Example


\section*{Packaging Type}
\begin{tabular}{c|c|c}
\hline Model Name & Package Contents (Per Set) & Minimum Order Unit \\
\hline UT-CW800 & \begin{tabular}{l} 
Main Terminal Cover x 2, Auxiliary Terminal \\
Cover x 2, Coil Terminal Cover x 1
\end{tabular} & 1 Set \\
\hline
\end{tabular}
\begin{tabular}{c|c|c}
\hline Model Name & Package Contents (Per Set) & Minimum Order Unit \\
\hline UT-CW655 & Main Terminal Cover x 1, Auxiliary Terminal Cover x 1 & 1 Set \\
\hline
\end{tabular}

\subsection*{8.13 UT/UN-RR \(\square\) Thermal Overload Relays Reset Release}

Performs thermal reset from outside the control panel.
- A reset release can be additionally mounted.

As the release length indicates the length from the back of a door or the like to the attachment, specify the length from the table below.
- Although the release can be bent, minimize the bend and keep the minimum bending radius greater than 50 mm . Although the bend is covered with an insulating material, arrange it so as not to touch the bare live parts.
- As transparent plastic is used for the attachment, it is easy to check the operation of the thermal overload relay as well as the set current value even after the reset release is attached.

\begin{tabular}{c|c|c|c}
\hline \multicolumn{3}{c|}{ Model Name } & \multirow{2}{*}{ Release Length } \\
\hline For TH-T18 Note 2 & For TH-T25/T50 & For TH-T65/T100, TH-N120 to N600 & \\
\hline UT-RR204 & UN-RR200 & UN-RR206 & 200 mm \\
\hline UT-RR404 & UN-RR400 & UN-RR406 & 400 mm \\
\hline UT-RR554 & UN-RR550 & UN-RR556 & 550 mm \\
\hline UT-RR704 & UN-RR700 & UN-RR706 & 700 mm \\
\hline
\end{tabular}

Note 1. UN-RR206, RR406, RR556 and RR706 cannot be combined with TH-N120TAHZ.
Note 2. Cannot be combined with TH-T18 model numbers earlier than August 2017 (178W).

\section*{Mounting Method}


Note 1. When using UN-RR206 to RR706, the live part terminal cover/protection cover units cannot be used.

\section*{Outline Drawings}


Figure shows UT-RR \(\square \square 4\)
\begin{tabular}{|c|}
\hline Model Name \\
\hline UT-RR204 \\
\hline UT-RR404 \\
\hline UT-RR554 \\
\hline UT-RR704 \\
\hline UN-RR200 \\
\hline UN-RR400 \\
\hline UN-RR550 \\
\hline UN-RR700 \\
\hline UN-RR206 \\
\hline UN-RR406 \\
\hline UN-RR556 \\
\hline UN-RR706 \\
\hline
\end{tabular}

\subsection*{8.14 UN-TL \(\square\) Fluorescent Display Lamps for Thermal Overload Relays}

Displays the trip state of the thermal overload relay with a light-emitting diode.
- Can be easily mounted on thermal overload relays.
\begin{tabular}{|c|c|c|c|}
\hline Model Name & Rated Voltage & Applicable Models & Power Consumption \\
\hline UN-TL12 DC24V & AC24 V/DC24 V & \multirow{3}{*}{TH-T18} & 0.2 W \\
\hline UN-TL12 AC100V & AC100 to 127 V & & 0.18 W \\
\hline UN-TL12 AC200V & AC200 to 240 V & & 0.2 W \\
\hline UN-TL20 DC24V & AC24 V/DC24 V & \multirow{3}{*}{TH-T25/T50} & 0.2 W \\
\hline UN-TL20 AC100V & AC100 to 127 V & & 0.18 W \\
\hline UN-TL20 AC200V & AC200 to 240 V & & 0.2 W \\
\hline UN-TL60 DC24V & AC24 V/DC24 V & \multirow[t]{3}{*}{TH-T65/T100 TH-N120 to N600} & 0.2 W \\
\hline UN-TL60 AC100V & AC100 to 127 V & & 0.18 W \\
\hline UN-TL60 AC200V & AC200 to 240 V & & 0.2 W \\
\hline
\end{tabular}

Note 1. UN-TL60 cannot be combined with TH-N120TAHZ.


UN-TL12

Outline Drawings
UN-TL12


\section*{UN-TL20}


Note. UN-TL20 fluorescent display lamp is a combination of UN-TL12 and operation prevention cover (UN-CV203).

\begin{tabular}{l|l|c|c|c|c|c}
\hline Indicator Lamps & Applicable Models & \multicolumn{6}{|c}{ Variable Dimensions } \\
\cline { 3 - 7 } \begin{tabular}{l} 
Model Names
\end{tabular} & Thermal Overload Relays & A & AB & B & C & CA \\
\hline \multirow{5}{*}{ UN-TL60 } & TH-N220 & & & & & \\
& TH-N400 & 77.5 & 63 & 42 & 89 & 83.5 \\
\cline { 2 - 7 } & TH-N600 & & & & & \\
\cline { 2 - 7 } & TH-T65,T100 & 103.5 & 88 & 53 & 89 & 83.5 \\
\cline { 2 - 7 } & TH-N120 & 117.5 & 103 & 67 & 105 & 105 \\
\hline
\end{tabular}
\begin{tabular}{|c|c|}
\hline Model Name & Model Name \\
\hline UN-TL12 & UN-TL20 \\
\hline UN-TL60 & \multicolumn{1}{|c}{} \\
\cline { 1 - 1 } &
\end{tabular}

Note. Minimum Order Unit UN-TL12, TL20 : 5 (5-Piece Set) UN-TL60 : 1

\section*{8 Optional Units}

\subsection*{8.15 UT-HZ18 and UN-RM20 Independent Mounting Units for Thermal Overload Relays}

\section*{- Features}

Screw mounting and IEC 35 mm rail mounting are enabled by combining with a thermal overload relay.
In addition, UT-HZ18BC can be combined with TH-T18BC to form an independent mounting thermal overload relay with wiring streamlining terminals.

\section*{Types and Applicable Models}
\begin{tabular}{l|c|c}
\hline \multicolumn{1}{c|}{ Model Name } & Mounting & Applicable Models \\
\hline UT-HZ18 & Screw Mounting & TH-T18(KP), TH-T18HZSR \\
& IEC 35 mm Rail Mounting & TH-T18BC(KP), TH-T18BCHZSR \\
\hline UT-HZ18BC & UN-RM20 & IEC 35 mm Rail Mounting \\
\hline
\end{tabular}

Note \(1 . \square \mathrm{BC}\) is the model name with wiring streamlining terminals.


\section*{Outline Drawings}

\begin{tabular}{|c|c|}
\hline Model Name & Model Name \\
\hline UT-HZ18 & UN-RM20 \\
\hline UT-HZ18BC & \\
\hline
\end{tabular}

\subsection*{8.16 UT/UN-TH \(\square\) Connecting Conductor Kits for Magnetic Starters}

\section*{A magnetic contactor and thermal overload relay can be combined to configure the magnetic starter.}
- Can be mounted on a thermal overload relay to combine with a magnetic contactor.
- Kit with connecting conductors, connecting conductor covers, terminal screws and the like needed for combination.

\section*{- Types and Applicable Models}
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Kit Model Name} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Parts Included in the Kit}} & \multicolumn{4}{|l|}{Model Names of Applicable Thermal Overload Relays and Magnetic Contactors} \\
\hline & & & \multirow[t]{2}{*}{Thermal Overload Relays} & \multicolumn{3}{|c|}{Magnetic Contactors} \\
\hline & Part Name & Quantity & & AC Operated & DC Operated & Mechanically Latched Type \\
\hline UN-TH21 & Connecting Conductors Connecting Conductor Covers & \[
\begin{aligned}
& \hline 3 \\
& 1 \\
& \hline
\end{aligned}
\] & TH-T25(BC)(FS)(KP)(SR) & S-T21(BC),T25(BC) & SD-T21(BC) & SL(D)-T21(BC) \\
\hline UT-TH50 & Connecting Conductors Connecting Conductor Covers & \[
\begin{aligned}
& \hline 3 \\
& 1 \\
& \hline
\end{aligned}
\] & \[
\begin{array}{|l|}
\hline \text { TH-T25(BC)(FS)(KP)(SR) } \\
\text { TH-T50(BC)(FS)(KP)(SR) } \\
\hline
\end{array}
\] & \[
\begin{array}{|l|}
\hline \text { S-T35(BC) } \\
\text { S-T50(BC) } \\
\hline
\end{array}
\] & \[
\begin{array}{|l|}
\hline \text { SD-T35(BC) } \\
\text { SD-T50(BC) } \\
\hline
\end{array}
\] & \[
\begin{aligned}
& \hline \text { SL(D)-T35(BC) } \\
& \text { SL(D)-T50(BC) } \\
& \hline
\end{aligned}
\] \\
\hline
\end{tabular}

Note 1. "BC" in the model names of the applicable thermal overload relays and magnetic contactors refers to "wiring streamlining terminal".
Note 2. Since TH-T18(BC)(KP) used for magnetic contactors with T10 to T20 frames is for magnetic starters with connecting conductor and conductor cover integrated, a kit is not required.
Note 3. For connecting conductor kits of TH-T65 or higher and TH-N120 or higher, refer to the thermal overload relay outline drawings.

\section*{- Outline Drawings}

UN-TH21


Connecting Conductors and Connecting Conductor Covers

UN-TH21: Connecting Conductor x 3, Connecting Conductor Cover x 1

UT-TH50


UT-TH50: Connecting Conductor \(\times 3\), Connecting Conductor Cover \(\times 1\)

\section*{- Mounting Method}
- For MSO-T10/T12/T20
(1) Loosen the 3 main terminal screws of the magnetic contactor ( \(2 / \mathrm{T} 1,4 / \mathrm{T} 2\) and \(6 / \mathrm{T} 3\) ).
(2) Tilt the thermal overload relay, guide the notch A of the thermal overload relay ( 2 places) into the indent of the magnetic contactor (2 places), then position the 3 main circuit conductors of the thermal overload relay so that they are at the left side of the main terminal screws. (Fig. 1)
(3) Push in the thermal overload relay in the B direction so that the notch A of the thermal overload relay and indent of the magnetic contactor are engaged. (Fig. 2)
(4) Rotate the thermal overload relay in the direction of Arrow C, and rotate the protrusion \(D\) of the thermal overload relay up to the E surface of the magnetic contactor. (Figs. 3, 4)
(5) While pressing the thermal overload relay to the magnetic contactor side, tighten the main terminal screws ( \(2 / \mathrm{T} 1,4 / \mathrm{T} 2\) and \(6 / \mathrm{T} 3\) ).
- For MSO-T21/T25/T35/T50(BC)
(1) Attach the connecting conductor (3-pole integral product) to the power supply side terminal of the thermal overload relay with screws. (Fig. 1)
(2) Loosen the 3 main terminal screws of the magnetic contactor (2) T1, 4/T2 and 6/T3).
(3) Tilt the thermal overload relay and set the notch A of the thermal overload relay ( 2 places) to the indent of the magnetic contactor (2 places). (Fig. 2)
(4) Rotate the thermal overload relay in the direction of Arrow B, and confirm that the notch C of the thermal overload relay ( 1 point) has been inserted into the square hole of the indent of the magnetic contactor. (Fig. 3)
(5) While pressing the thermal overload relay to the magnetic contactor side, tighten the main terminal screws.



Fig.


\subsection*{8.17 UN-FD and UN-FD4 Fault Detection Units (Contact Weld Detection Relays)}

Detects faults (contact welding) that occur to the main circuit contact of a magnetic starter when in conduction mode, and can be used to prevent load devices running out of control by interrupting the power supply by combining a no-fuse breaker or magnetic contactor. For fault detection units, UN-FD for the 200 V main circuit and UN-FD4 for the 400 V main circuit are available.

Outline Drawings


\section*{- Ratings/Specifications}
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Application} & \multicolumn{2}{|l|}{For 200 V Main Circuit} & \multicolumn{4}{|c|}{For 400 V Main Circuit} \\
\hline \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Model Name}} & UN-FD AC100V & UN-FD AC200V & UN-FD4 AC100V 1A & UN-FD4 AC100V 1B & UN-FD4 AC200V 1A & UN-FD4 AC200V 1B \\
\hline & & UN-FDCX AC100V & UN-FDCX AC200V & UN-FD4CX AC100V 1A & UN-FD4CX AC100V 1B & UN-FD4CX AC200V 1A & UN-FD4CX AC200V 1B \\
\hline \multicolumn{2}{|l|}{Rated Operational Voltage (Note 1)} & AC100 to \(120 \mathrm{~V} 50 / 60 \mathrm{~Hz}\) & AC200 to \(240 \mathrm{~V} 50 / 60 \mathrm{~Hz}\) & \multicolumn{2}{|l|}{AC100 to \(120 \mathrm{~V} 50 / 60 \mathrm{~Hz}\)} & \multicolumn{2}{|l|}{AC200 to \(240 \mathrm{~V} 50 / 60 \mathrm{~Hz}\)} \\
\hline \multicolumn{2}{|l|}{Rated Main Circuit Voltage} & \multicolumn{2}{|l|}{AC200 to \(24050 / 60 \mathrm{~Hz}\)} & \multicolumn{4}{|c|}{AC380 to \(440 \mathrm{~V} 50 / 60 \mathrm{~Hz}\)} \\
\hline \multicolumn{2}{|l|}{Input Current} & \multicolumn{2}{|c|}{17 mA} & \multicolumn{4}{|c|}{Operation (A1-A2): 17 mA , Signal (24): 10 mA} \\
\hline \multirow[b]{2}{*}{Output} & Coriact Arangenent & \multicolumn{2}{|c|}{1 c} & 1a & 1b & 1 a & 1b \\
\hline & Contact Rating & \multicolumn{2}{|l|}{AC120 V 1.5 A, AC240 V 1 A (AC-15)} & \multicolumn{4}{|c|}{AC120 V 1.5 A, AC240 V 1 A (AC-15)} \\
\hline \multicolumn{2}{|l|}{Minimum Control Input Time} & \multicolumn{2}{|c|}{20 ms} & \multicolumn{4}{|c|}{20 ms} \\
\hline \multicolumn{2}{|l|}{Detection Time} & \multicolumn{2}{|c|}{0.2 to 0.5 s} & \multicolumn{4}{|c|}{0.2 to 0.5 s} \\
\hline \multicolumn{2}{|l|}{Allowable Detection Retention Time} & \multicolumn{2}{|l|}{1 s (Short Time Rating)} & \multicolumn{4}{|c|}{Continuous Rating} \\
\hline \multicolumn{2}{|l|}{Allowable Voltage Fluctuation} & \multicolumn{2}{|l|}{85 to 110\% of Rated Voltage (Both Main Circuit and Control Circuit)} & \multicolumn{4}{|l|}{85 to 110\% of Rated Voltage (Both Main Circuit and Control Circuit)} \\
\hline \multicolumn{2}{|l|}{Operating Temperature/Humidity} & \multicolumn{2}{|l|}{-10 to \(60^{\circ} \mathrm{C} / 45\) to \(85 \% \mathrm{RH}\)} & \multicolumn{4}{|c|}{-10 to \(50^{\circ} \mathrm{C} / 45\) to \(85 \% \mathrm{RH}\)} \\
\hline \multicolumn{2}{|l|}{Operation Indicator} & \multicolumn{2}{|c|}{None} & \multicolumn{4}{|c|}{Lights When Power is Applied (LED Green) Lights in Fault Condition (LED Red)} \\
\hline Combined De & Protection ices & \multicolumn{2}{|l|}{\begin{tabular}{l}
- No-Fuse Breaker With Voltage Tripping Device \\
- Magnetic Contactors
\end{tabular}} & No-Fuse Breaker With Voltage Tripping Device & Magnetic Contactors & No-Fuse Breaker With Voltage Tripping Device & Magnetic Contactors \\
\hline \multicolumn{2}{|l|}{Fault Detection Retention} & \multicolumn{2}{|l|}{No Retention Function} & \multicolumn{4}{|c|}{Electric Retention via Operating Power Supply} \\
\hline \multicolumn{2}{|l|}{Fault Detection Reset} & \multicolumn{2}{|l|}{When Main Circuit Power Supply Is Open} & \multicolumn{4}{|c|}{When Operating Power Supply is Turned Off} \\
\hline
\end{tabular}

Note 1. The DC24 V rated operational voltage specification can also be manufactured.
Note 2. \(\square\) CX is the model name with the CAN terminal.
Note 3. Refer to page 327 when using in combination with a solid state contactor.
Connecting
\begin{tabular}{|c|c|c|c|}
\hline Model Name & UN-FD \(\square\) & UN-FD4 \(\square 1\) A & UN-FD4 \(\square 1 \mathrm{~B}\) \\
\hline \begin{tabular}{l}
Internal \\
Connection and Connection Method
\end{tabular} &  &  &  \\
\hline
\end{tabular}

\section*{- Handling}
(1) As UN-FD and UN-FD4 have different functions, take care during use.
(2) UN-FD and UN-FD4 have a fault detection time of 0.2 to 0.5 seconds. UN-FD and UN-FD4 may malfunction when applied to a magnetic starter for motors with a long residual voltage decay time. Therefore, consider using a system that allows operation input signals to be delayed or another device to detect faults.
(3) Fault detection units cannot be used for capacitor load circuits, star-delta starting circuits or inverter circuits.
(4) A no-fuse breaker or magnetic contactor should be configured to open-circuit the main circuit after fault detection. When combining with a no-fuse breaker with a voltage tripping device, use the output make contact of the fault detection unit to trip the no-fuse breaker during fault detection. When combining with a magnetic contactor, run the magnetic contactor in the self-retaining state using the self-retaining circuit, cancel the self-retaining state with the break contact of the fault detection unit during fault detection, and make a connection so that the magnetic contactor is opened.
(5) UN-FD units are rated for only short periods of time, so the detection state should not be maintained for more than 1 second.
(6) Although UN-FD is reset when the main circuit power supply is opened, UN-FD4 is not reset until the operating power supply is turned off. When resetting, turn off the operating power supply with a switch, etc.
(7) When applying to the reversing running circuit, enter the forward and reverse signals to the input circuit of the fault detection unit.

\section*{Operation}

The UN-FD fault detection unit determines that the magnetic starter is abnormal when the load-side voltage and coil voltage of the magnetic starter are input and the 2 signals are mismatched, and detects contact welding failure and non-operation failure. (Inactive fault detection is only possible with UN-FD4.)
(1) If voltage is applied to the load device while the operating input signal is being input, it is determined as the normal state.
(2) Fault detection operation starts when voltage is applied (2 or more poles energized) to the load device while the operating input signal is off.
(3) For UN-FD4, fault detection operation also starts if voltage is not applied to the load device while the operating input signal is being input (non-operation of the magnetic starter).


\section*{Operating Circuit}
(1) Connect the input circuit (UN-FD: A1 and A2 terminals, UN-FD4: 24 and A2 terminals) in parallel with the coil of the magnetic starter.
(2) Apply the rated operational voltage to the control circuit (A1 and A2 terminals) of UN-FD4 at all times.
(3) Connect the main circuit voltage input circuit (15, 16 and 18 terminals) to the load side of the magnetic starter.



Connection Between UN-FD and No-Fuse Breaker (For Reversible Magnetic Starters)


Connection Between UN-FD4 \(\square 1\) A and No-Fuse Breaker (For Reversible Magnetic Starters)

Note 1. When applying to the reversible type, be sure to use the mechanical interlock at the same time.
Note 2. Use the auxiliary relay ( \(A X\) ) to configure the self-retaining circuit.
\begin{tabular}{|c|}
\hline Model Name \\
\hline UN-FD \\
\hline UN-FDCX \\
\hline UN-FD4 \\
\hline UN-FD4CX \\
\hline
\end{tabular}

\section*{Optional Units}

\subsection*{8.18 How to Order}

Follow the steps below when ordering. ( Enter a space in \(\mathbf{A}\).)
- UT-AX Auxiliary Contact Units
\begin{tabular}{|c|c|}
\hline Model Name & Contact Arrangement \\
\hline UT-AX4 & - 2A2B \\
\hline Refer to page 197 & For UT-AX2/AX4, specify the contact arrangement described on page 197. UT-AX11 does not need to be specified as it has fixed 1A1B. \\
\hline \multicolumn{2}{|l|}{- UT-SA Operation Coil Surge Absorber Units} \\
\hline Model Name & Voltage Designation \\
\hline UT-SA21 & \multirow[t]{3}{*}{\begin{tabular}{l}
\(\triangle\) AC400V \\
A AC200V \\
- AC48V
\end{tabular}} \\
\hline UT-SA22 & \\
\hline UT-SA25 & \\
\hline Refer to page 206 & Select according to the control circuit voltage. \\
\hline
\end{tabular}

■ UT-ML Mechanical Interlock Units
\begin{tabular}{|c|}
\hline Model Name \\
UT-ML20 \\
\hline Refer to page 213 \\
\hline
\end{tabular}
\(\square\) UT-SY \(\square(B C)\) DC/AC Interface Units for Operation Coils

\(\square\) UN-AX \(\square(C X)\) Auxiliary Contact Units
\begin{tabular}{|c|c|}
\hline Model Name & Contact Arrangement \\
\hline UN-AX4 UN-AX11CX & \[
\triangle 2 \mathrm{~A} 2 \mathrm{~B}
\] \\
\hline Refer to page 197 & The default for UN-AX11 (CX), AX80, AX150 is 1a1b and that for UN-AX600 is 2a2b, meaning specification is not required \\
\hline \multicolumn{2}{|l|}{UN-LL22(CX) Auxiliary Contact Units With Contact for Low-level Signals} \\
\hline Model Name & \\
\hline \multicolumn{2}{|l|}{\[
\begin{aligned}
& \text { UN-LL22 } \\
& \text { UN-LL22CX }
\end{aligned}
\]} \\
\hline Refer to page 203 & Default contact arrangement is 1A1B low-level
contact plus 1A1B standard contact. \\
\hline \multicolumn{2}{|l|}{\(\square\) UN-SA \(\square\) Operation Coil Surge Absorber Units} \\
\hline Model Name & Voltage Designation \\
\hline UN-SA721 UN-SA722 UN-SA725 & \begin{tabular}{l}
- AC400V \\
\(\triangle\) AC200V \\
A AC48V
\end{tabular} \\
\hline Refer to page 206 & Select according to the control circuit voltage \\
\hline
\end{tabular}
\(\square\) UT-SA33 \(\square\), UN-SA33 Main Circuit Surge Absorber Units
Model Name

UT-SA3320
UT-SA3332
UN-SA33
Refer to page 212
■ UT-SY \(\square(B C)\), UN-SY \(\square(C X)\) DC/AC Interface Units for Operation Coils

Model Name
UT-SY21
UT-SY21BC
UN-SY21
\(\square\) UT-CV \(\square\), UN-CV \(\square\), CZ \(\square\) Live Part Protection Cover Units

Model Name

UN-ML21
\[
\text { Refer to page } 213
\]
\(\square\) UT/UN- \(\square\) Main Circuit Conductor Kits

\begin{tabular}{l}
\multicolumn{1}{|c|}{ Model Name } \\
UT-YY21 \\
UN-YY35 \\
\hline Refer to page 217 \\
\hline
\end{tabular}
- UN-FD \(\square\) (CX) Fault Detection Units


UT/UN-RR \(\square\) Thermal Overload Relay Reset Releases

\begin{tabular}{|c|c|}
\hline Model Name & Voltage Designation \\
\begin{tabular}{|c|c|}
\hline UN-TL20 & AC100V \\
\hline Refer to page 229 & \begin{tabular}{c} 
Select according to the \\
control circuit voltage
\end{tabular} \\
\hline
\end{tabular}
\end{tabular}

UT-HZ18(BC)/UN-RM20 Independent Mounting Units for Thermal Overload Relays

UT-HZ18
UN-RM20

\subsection*{8.19 Model List (for MS-K Series)}
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Product Name} & \multicolumn{4}{|c|}{DC/AC Interface Units for Operation Coils} \\
\hline & Format & UN-SY11 & UN-SY12 & UA-SY21 & UA-SY22 \\
\hline & Mounting & \multicolumn{2}{|l|}{Independent Mounting} & \multicolumn{2}{|c|}{Top-On} \\
\hline \multicolumn{2}{|r|}{\multirow[b]{2}{*}{Specifications/ Functions}} & \multicolumn{4}{|l|}{Enables AC-operated contactor relays and contactors to be operated at DC24 V} \\
\hline & & Triac Output Input DC24 V 15 mA & \begin{tabular}{l}
Relay Output \\
Input
\[
\text { DC24 V } 10 \text { mA }
\]
\end{tabular} & \begin{tabular}{l}
Triac \\
Output Input DC24 V 15 mA
\end{tabular} & \begin{tabular}{l}
Relay Output \\
Input DC24 V 10 mA
\end{tabular} \\
\hline \multicolumn{6}{|l|}{Acquired Standards} \\
\hline & Mass (g) & \multicolumn{2}{|c|}{60} & \multicolumn{2}{|c|}{40} \\
\hline \% & Contactor Relays & \multicolumn{2}{|c|}{SR-K100} & \multicolumn{2}{|c|}{SR-K100} \\
\hline 宕 & Thermal Overload Relays & \multicolumn{2}{|c|}{-} & \multicolumn{2}{|c|}{-} \\
\hline \multicolumn{2}{|r|}{Reference Page} & \multicolumn{4}{|c|}{218} \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|c|c|}
\hline Product Name & \multicolumn{5}{|c|}{Operation Coil Surge Absorber Units} \\
\hline Format & UN-SA721 & UN-SA712 & UN-SA713 & UN-SA723 & UN-SA725 \\
\hline Mounting & \multicolumn{5}{|c|}{Top-On} \\
\hline Specifications/ Functions & \begin{tabular}{l}
With Varistor \\
For Both AC and DC Operation \\
AC48 V/AC100 V \\
AC200 V/AC400 V
\end{tabular} & With Varistor + Indicator Lamp For Both AC and DC Operation AC100 V AC200 V & \begin{tabular}{l}
With CR \\
For DC Operation
DC200 V
\end{tabular} & \begin{tabular}{l}
With CR \\
For AC Operation \\
AC200 V
\end{tabular} & \begin{tabular}{l}
With Varistor + CR \\
For Both AC and DC Operation \\
AC48 V/AC100 V \\
AC200 V
\end{tabular} \\
\hline Acquired Standards & UL/CSA & & & & UL/CSA \\
\hline Mass (g) & 20 & 25 & 25 & 20 & 25 \\
\hline  & \[
\begin{aligned}
& \text { SR(D)-K100 } \\
& \text { SRL(D)-K100 } \\
& \hline
\end{aligned}
\] & \[
\begin{aligned}
& \text { SR(D)-K100 } \\
& \text { SRL(D)-K100 } \\
& \hline
\end{aligned}
\] & \[
\begin{aligned}
& \hline \text { SRD-K100 } \\
& \text { SRLD-K100 }
\end{aligned}
\] & \[
\begin{aligned}
& \hline \text { SR-K100 } \\
& \text { SRL-K100 } \\
& \hline
\end{aligned}
\] & \[
\begin{aligned}
& \text { SR(D)-K100 } \\
& \text { SRL(D)-K100 } \\
& \hline
\end{aligned}
\] \\
\hline  & - & - & - & - & - \\
\hline Reference Page & \multicolumn{5}{|c|}{205} \\
\hline
\end{tabular}

\subsection*{8.20 Applicable Model List (for MS-K Series)}
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{\[
\begin{aligned}
& \text { 듬 } \\
& \stackrel{\rightharpoonup}{\otimes} \\
& \text { © }
\end{aligned}
\]} & \multirow{3}{*}{Product Name} & \multirow{3}{*}{Model Name} & \multirow{3}{*}{Specifications} & \multicolumn{3}{|c|}{Applicable Models} \\
\hline & & & & \multicolumn{3}{|c|}{Contactor Relays} \\
\hline & & & & AC Operated & DC Operated & Mechanically Latched Type \\
\hline \multirow{5}{*}{1} & \multirow{5}{*}{Operation Coil Surge Absorber Units} & UN-SA712 & Varistor + Indicator Lamp & K100 & SRD-K100 & SRL(D)-K100 \\
\hline & & UN-SA713 & \(C+R\) & & SRD-K100 & SRLD-K100 \\
\hline & & UN-SA721 & Varistor & K100 & SRD-K100 & SRL(D)-K100 \\
\hline & & UN-SA723 & C + R & K100 & & SRL-K100 \\
\hline & & UN-SA725 & Varistor + C + R & K100 & SRD-K100 & SRL(D)-K100 \\
\hline \multirow{4}{*}{2} & \multirow{4}{*}{\begin{tabular}{l}
DC/AC \\
Interface \\
Units for Operation Coils
\end{tabular}} & UN-SY11 & Triac Output & K100 & & \\
\hline & & UN-SY12 & Contact Output & K100 & & \\
\hline & & UA-SY21 & Triac Output & K100 & & \\
\hline & & UA-SY22 & Contact Output & K100 & & \\
\hline
\end{tabular}

Note. UN- \(\square\) indicates shared application with MS-N Series optional units. For more information, refer to the MS-N Series optional units.
- Type Designations


\section*{Optional Units}

\subsection*{8.21 UA-SY \(\square\) DC/AC Interface Units for Operation Coils}

\section*{DC/AC interface unit for operation coils that switches AC-operated contactor relays at the output (DC24 V) of electronics such as PLCs}

A thin unit that can be mounted to the main body of the SR-K contactor relay and an independent mounting unit are available. Both contactless output and contact (relay) output are also available.

\section*{- Model Name}
\(\begin{array}{c|c|c|c}\hline \text { Unit Model Name } & \text { Output Method } & \text { Unit Mounting Method } & \text { Model Names of Applicable Contactor Relays } \\ \hline \text { UN-SY11 } & \text { Contactless Output } & \text { Independent Mounting } & \text { SR-K100 } \\\)\cline { 4 - 5 }\(n n & \text { (Triac Output) }\end{array}\) Top-On Additional Mounting \()\)

Note 1. The coil voltage designation of AC100V or AC200V can be applied for the operation coil.
Note 2. Refer to page 218 for information regarding UN-SY11 and SY12.
- Specifications
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multicolumn{3}{|c|}{Model Name} & UN-SY11 & UA-SY21 & UN-SY12 & UA-SY22 \\
\hline \multirow{6}{*}{\[
\begin{aligned}
& \stackrel{\rightharpoonup}{5} \\
& \vdots \\
& \text { 士믈 }
\end{aligned}
\]} & \multicolumn{2}{|l|}{Rated Operational Voltage} & \multicolumn{4}{|c|}{DC24 V} \\
\hline & \multicolumn{2}{|l|}{Allowable Voltage Fluctuation} & \multicolumn{4}{|c|}{85 to \(110 \%\) of Rated Operational Voltage} \\
\hline & \multicolumn{2}{|c|}{Current} & \multicolumn{2}{|l|}{15 mA} & \multicolumn{2}{|c|}{10 mA} \\
\hline & \multicolumn{2}{|c|}{Power Consumption} & \multicolumn{2}{|l|}{0.4 W} & \multicolumn{2}{|c|}{0.24 W} \\
\hline & \multicolumn{2}{|l|}{Minimum Closing Voltage} & \multicolumn{2}{|l|}{18 V} & \multicolumn{2}{|c|}{18 V} \\
\hline & \multicolumn{2}{|l|}{Maximum Openning Voltage} & \multicolumn{2}{|l|}{4 V} & \multicolumn{2}{|c|}{1 V} \\
\hline \multirow{7}{*}{\[
\begin{aligned}
& \text { 늗 } \\
& \vdots \\
& \frac{1}{訁} \\
& \text { 를 }
\end{aligned}
\]} & \multicolumn{2}{|c|}{Output Specifications} & \multicolumn{2}{|l|}{Contactless Output (Triac Output)} & \multicolumn{2}{|c|}{Contact Output} \\
\hline & \multicolumn{2}{|l|}{Rated Operational Voltage} & \multicolumn{4}{|c|}{AC100 to AC240 V 50/60 Hz} \\
\hline & \multicolumn{2}{|c|}{Output Current} & \multicolumn{4}{|c|}{0.5 A, AC-15} \\
\hline & \multicolumn{2}{|l|}{Open Circuit Leakage Current} & \multicolumn{2}{|l|}{\(5 \mathrm{~mA} / 240 \mathrm{~V}\)} & \multicolumn{2}{|c|}{None} \\
\hline & \multicolumn{2}{|c|}{Operating Time} & \multicolumn{2}{|l|}{1 ms in Operation, 0.5 Cycles +1 ms or Less in Open Circuit} & \multicolumn{2}{|c|}{10 ms or less} \\
\hline & \multirow[b]{2}{*}{Switching Durability} & Mechanical & \multicolumn{2}{|l|}{-} & \multicolumn{2}{|c|}{5 mil. times} \\
\hline & & Electrical & \multicolumn{2}{|l|}{-} & 1 mil. times (Note 1) & 5 mil. times \\
\hline \multicolumn{3}{|c|}{Operating Temperature} & \multicolumn{4}{|c|}{\(-10^{\circ} \mathrm{Cto} 55^{\circ} \mathrm{C}\)} \\
\hline \multicolumn{2}{|r|}{\multirow[b]{2}{*}{Applicable Terminal Wires}} & Electric Wires & \multicolumn{4}{|c|}{\(\varphi 1.6 \mathrm{~mm}, 1.25\) to \(2 \mathrm{~mm}^{2}\)} \\
\hline & & Crimp Lugs & \multicolumn{4}{|c|}{1.25-3.5,2-3.5} \\
\hline
\end{tabular}

Note 1. Using UN-SY12 and SR-K100 in combination achieves 5 million times.

\section*{Connection Example (Connection Diagram)}
\begin{tabular}{|c|c|}
\hline UN-SY11, UA-SY21 & UN-SY12, UA-SY22 \\
\hline  &  \\
\hline
\end{tabular}

\section*{Outline Drawings/Mounting}

UA-SY21, SY22 (Additional Mounting)
Mount according to the guidelines below.
Remove the screws of the coil terminal A 1 of the contactor relay, align the protrusion of the \(\mathrm{DC} / \mathrm{AC}\) interface unit and groove of the magnetic contactor or contactor relay while the supplied connecting conductor is mounted on the A1 terminal of the DC/AC interface unit, then tighten the connecting conductor with the removed coil terminal screws.

UA-SY21, SY22


Outline Drawings


Included Connecting Conductor

for SR-K100

Dimensions After Additional Mounting

\section*{Optional Units}

\subsection*{8.22 How to Order}

Follow the steps below when ordering. (Enter a space in \(\mathbf{\Delta}\).)
\(\square\) UN-SA \(\square\) Operation Coil Surge Absorber Units
\begin{tabular}{l|l|}
\begin{tabular}{|c|c|}
\hline Model Name & \multicolumn{1}{c|}{ Voltage Designation } \\
\begin{tabular}{|cc|}
\hline UN-SA721 & \\
\hline Refer to page 206 AC24V \\
\hline
\end{tabular} & \begin{tabular}{l} 
Select according to the control \\
circuit voltage
\end{tabular} \\
\hline
\end{tabular}
\end{tabular}

■ UA-SY \(\square\) DC/AC Interface Units for Operation Coils
\begin{tabular}{|c|}
\hline Model Name \\
\hline UA-SY21 \\
\hline Refer to page 236 \\
\hline
\end{tabular}

\title{
Magnetic Starters/Magnetic Contactors/Contactor Relays According to Application
}
9.1 Model List ..... 240
9.2 DC Interface Contactors
SD/MSOD-Q \(\square\) ..... 242
9.3 NC Main Contact Contactors B-T/N ..... 249
9.4 Magnetic Contactors for DC DU-N \(\square\) ..... 253
9.5 Magnetic Contactors for High-Frequency Switching S-N■KG ..... 258
9.6 Vacuum Magnetic Contactors SH-V \(\square\) ..... 259
9.7 How to Order ..... 263

\subsection*{9.1 Model List}



\subsection*{9.2 SD/MSOD-Q \(\square\) DC Interface Contactors}

Compact, high-performance DC operated type contactors that are capable of being directly driven by the transistor output (DC24 V 0.1 A) of PLCs etc.

\section*{Features}
(1) Non-reversible type: DC interface contactors compatible with up to \(3 \varphi 220 \mathrm{~V} 2.5 \mathrm{~kW}\) motor loads.

SD-Q11, SD-Q12 / With Thermal Overload Relay: MSOD-Q11, MSOD-Q12
- Direct Drive of Contactors Using

Semiconductor Output (Transistor Output) Adopts a high-sensitivity polar solenoid that allows all models to be directly driven by output of DC24 V 0.1 A rated transistors
- Minimal Load for Auxiliary Contacts DC5 V 3 mA
By doubling the auxiliary contacts, support for levels as low as DC5 V 3 mA has been made possible. (The failure rate in normal environments free of dust or corrosive gas is \(5 \times 10^{-7} /\) cycle.)
- An Extensive Line of Installable Optional Units
- Auxiliary Contact Units: \((Q(R) 11\) Only) UQ-AX2 (For Left-Side of Single and Reversible Types) UQ-AX2KR (For Right-Side of Reversible Types)
- Indicator Lamp Unit

UQ-PL
- Rail Mounting Standardized

Can be mounted on an IEC and DIN
regulation compliant 35 mm width rail
- Provides Support for a Large Number of International Standards
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow{4}{*}{Model} & \multirow{4}{*}{Model Name} & \multicolumn{4}{|r|}{Applicable Standard} & \multicolumn{2}{|l|}{Safety Ceritified Standard} & EC Directives & Ceritiying Body & CCC Certification \\
\hline & & \[
\begin{array}{|l|}
\hline \text { JIS*1 } \\
\text { JEM }
\end{array}
\] & IEC & DIN VDE & \[
\begin{aligned}
& \mathrm{BS} \\
& \mathrm{EN}
\end{aligned}
\] & UL & CSA & CE Mark & TÜV & GB \\
\hline & & Japan & Intendiona & Germany & United & US & Canada & Europe & Germany & China \\
\hline & & & & & Kingdom Europe & & & CE & \(\pm\) & (CC) \\
\hline Magnetic Contactors & \[
\begin{aligned}
& \hline \text { SD-Q11, Q12 } \\
& \text { SD-QR11, QR12 } \\
& \hline
\end{aligned}
\] & ( \({ }^{\text {) }}\) & ( \({ }^{\text {a }}\) & ( 0 & ( 0 & (0) & ( \({ }^{\text {a }}\) & ( 0 & ( \({ }^{\text {a }}\) & ( \({ }^{\text {* }}\) \\
\hline Magnetic Starters & \[
\begin{array}{|}
\hline \text { MSOD-Q11(BC)KP to } \\
\text { Q12(BC)KP } \\
\text { MSOD-QR11(BC)KP to } \\
\text { QR12(BC)KP } \\
\hline
\end{array}
\] & ( \({ }^{\text {* } 2}\) & ( 0 & ( \({ }^{\text {a }}\) & ( 0 & * \({ }^{(1)}\) & ( \({ }^{( } 2\) & ( \({ }^{\text {a }}\) & ( \({ }^{\text {a }}\) & * \({ }^{\text {® }}\) \\
\hline
\end{tabular}
-(0):Standard product that conforms, is compliant, or for which certification has been obtained. .*1:If JIS conformity declaration is required, please request.
- *2:Compliance, conformity and certification have been obtained for 2-element models (MSOD-Q \(\square\) (BC), MSOD-QR \(\square\) (BC)) as well. .*3:Excluding the coil designation of DC12V.
.UL(CSA) can be used in applications rated up to AC480 V and TÜV rated up to AC440 V. .Certification mark is displayed on the product's name plate.


SD-Q11
- Achieves Large Capacity/Long Lifespan SD-Q types have an increased conventional free air thermal current (rated continuity current).(SD-M11/M12 15A
\(\rightarrow\) SD-Q11/Q12 20A)
Suitable only for circuit continuity duty. Also, they can be applied to AC440 V circuits despite their compact size.
\begin{tabular}{l|l|l|l|}
\hline \multirow{2}{*}{ Model Name } & Rated Capacity (kW) AC-3 & Conventional Free Air & Electrical Durability \\
& 200 & \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Model Name} & & & & \\
\hline & 200 to 240 V & 380 to 440 V & Themal Curent (A) & ( x 10000 ) \\
\hline SD-Q11/Q12 & 2.5 & 4 & 20 & \\
\hline
\end{tabular}
- Surge Absorber Comes Standard Built-in
- The integrated surge absorber function suppresses coil surge voltages
- Suppresses damage to peripheral electronic devices due to the harmful surge voltages generated when switching the coil OFF
- Mirror contacts (Turning off the auxiliary break contact when the main contact is welded)
Complies with requirements for "control functionality during failures" stipulated in the section "Electrical Devices of Industrial Equipment" in EN regulation EN60204-1 and can be used as an interlocking circuit contact. (TÜV Compliant Certification Acquired)
- Thermal Overload Relays Mountable Without Adapter
Can be directly mounted to contactors allowing for conversion to a magnetic starter by simply purchasing a thermal overload relay
- Magnetic Contactors Equipped With Terminal Covers As Standard
- Easily attachable terminal covers are equipped as standard, separating the body and units - Improved maintenance and inspection safety and electric shock prevention due to the finger protection functionality
(2) Reversible type:Reversible integrated DC interface contactors suitable for the forward/reverse operation of three-phase motors. SD-QR11, SD-QR12 Types / Models with Thermal Overload Relay: MSOD-QR11, MSOD-QR12 Types
- Integrated Mechanical Interlock -
- Electrical Interlock Wiring Included
- \(1 \mathrm{~b} \times 2\) or 1a1b \(\times 2\) Auxiliary Contacts Standardly equipped with an electrically interlocked break contact with twin contacts for high contact reliability auxiliary contacts
- Powerful and Compact

Has the same outline drawing as 2 SD-Q11 or SD-Q12 units and the same ratings as non-reversible types

Capable of preventing both left and right contactors from being closed simultaneously

SD-QR11

- Surge Absorber Comes Standard Built-in
- The integrated surge absorber function suppresses surge voltages
- Suppresses damage to peripheral electronic devices due to the harmful surge voltages generated when switching the coil OFF
- Magnetic Contactors Equipped With Terminal Covers As Standard
- Easily attachable terminal covers are equipped as standard, separating the body and units
- Auxiliary units can be mounted without removing the body's terminal cover
- Rail Mounting Standardized

Can be mounted on an IEC and DIN regulation compliant 35 mm width rail

\section*{Manufactured Model List}
\begin{tabular}{|c|c|c|c|}
\hline \multicolumn{3}{|r|}{\multirow[t]{2}{*}{Model}} & Model Name \\
\hline & & & Q11/Q12 \\
\hline \multirow{4}{*}{Magnetic Contactors} & Non-Reversible & Auxiliary Contact 1-Pole & SD-Q11 \\
\hline & Type & Auxiliary Contact 2-Pole & SD-Q12 \\
\hline & Reversible & Auxiliary Contact 2-Pole & SD-QR11 \\
\hline & Type & Auxiliary Contact 4-Pole & SD-QR12 \\
\hline \multirow{8}{*}{Magnetic Starters} & \multirow[t]{4}{*}{\begin{tabular}{l}
Non- \\
Reversible \\
Type
\end{tabular}} & Auxiliary Contact 1-Pole & MSOD-Q11 \\
\hline & & Auxiliary Contact 2-Pole & MSOD-Q12 \\
\hline & & With 2E Thermal & MSOD-QDKP Note 1 \\
\hline & & With Thermal Wiring Streamlining Terminal (with 2E Thermal) Note 4 & MSOD-QDBC(KP) Note 1 \\
\hline & \multirow{4}{*}{Reversible Type} & Auxiliary Contact 2-Pole & MSOD-QR11 \\
\hline & & Auxiliary Contact 4-Pole & MSOD-QR12 \\
\hline & & With 2E Thermal & MSOD-QRDKP Note 1 \\
\hline & & With Thermal Wiring Streamlining Terminal (with 2E Thermal) Note 4 & MSOD-QR■BC(KP) Note 1 \\
\hline \multirow{3}{*}{Units} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Front Clip-on Auxiliary Contact Unit}} & UQ-AX2 Note 2 \\
\hline & & & UQ-AX2KR Note 3 \\
\hline & \multicolumn{2}{|l|}{Indicator Lamp Unit} & UQ-PL \\
\hline
\end{tabular}

Note 1. The \(\square\) in the model name column is a placeholder for 11 or 12 Note 2. Q11 or QR11 are only applicable to the left side of UQ-AX2.
Note 3. QR11 are only applicable to the right side of UQ-AX2KR.

Note 4.Thermal overload relays have wiring streamlining terminals, but contactors (SD-Q \(\square\) ) use an all-pole integrated terminal cover with no wiring streamlining terminal. (Model Name: MSOD-Q \(\square B C(K P), M S O D-Q R \square B C(K P))\)

\section*{Rating/Performance}
(1) Ratings and Performance
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Model Name} & \multicolumn{3}{|c|}{Type} & \multicolumn{2}{|r|}{Non-Reversing} & \multicolumn{2}{|c|}{Reversing} \\
\hline & \multicolumn{3}{|c|}{Magnetic Contactor SD-} & Q11 & Q12 & QR11 & QR12 \\
\hline & \multicolumn{3}{|c|}{Magnetic Starter MSOD-} & Q11 & Q12 & QR11 & QR12 \\
\hline \multicolumn{4}{|c|}{Rated Insulation Voltage [V]} & \multicolumn{4}{|c|}{690} \\
\hline \multirow{25}{*}{\begin{tabular}{l}
Rated Operating Current \\
[A]
\end{tabular}} & \multicolumn{2}{|l|}{\multirow[b]{3}{*}{\begin{tabular}{l}
Three-Phase Squirrel-cage \\
Motor (Category AC-3)
\end{tabular}}} & 200 to 240 V & \multicolumn{4}{|c|}{12} \\
\hline & & & 380 to 440 V & \multicolumn{4}{|c|}{9} \\
\hline & & & 500 to 550 V & \multicolumn{4}{|c|}{7} \\
\hline & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Single-Phase Motor (Category AC-3)}} & 100 to 110 V & \multicolumn{4}{|c|}{8} \\
\hline & & & 200 to 220 V & \multicolumn{4}{|c|}{6} \\
\hline & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Resistive Load (Category AC-1)}} & 100 to 220 V & \multicolumn{4}{|c|}{10 (15)} \\
\hline & & & 380 to 440 V & \multicolumn{4}{|c|}{10} \\
\hline & \multirow{6}{*}{\begin{tabular}{l}
DC Motor \\
(Category DC2, DC4)
\end{tabular}} & \multirow{3}{*}{2-Pole Series} & 24 V & \multicolumn{4}{|c|}{12} \\
\hline & & & 48 V & \multicolumn{4}{|c|}{6} \\
\hline & & & 100 to 110 V & \multicolumn{4}{|c|}{1.2} \\
\hline & & \multirow{3}{*}{3-Pole Series} & 24 V & \multicolumn{4}{|c|}{12} \\
\hline & & & 48 V & \multicolumn{4}{|c|}{10} \\
\hline & & & 100 to 110 V & \multicolumn{4}{|c|}{2.5} \\
\hline & \multirow{12}{*}{DC Solenoid (Category DC-13)} & \multirow{4}{*}{Single Pole} & 24 V & \multicolumn{4}{|c|}{3} \\
\hline & & & 48 V & \multicolumn{4}{|c|}{1.5} \\
\hline & & & 100 to 110 V & \multicolumn{4}{|c|}{0.6} \\
\hline & & & 200 to 220 V & \multicolumn{4}{|c|}{0.3} \\
\hline & & \multirow{4}{*}{2-Pole Series} & 24 V & \multicolumn{4}{|c|}{5} \\
\hline & & & 48 V & \multicolumn{4}{|c|}{2.5} \\
\hline & & & 100 to 110 V & \multicolumn{4}{|c|}{1.2} \\
\hline & & & 200 to 220 V & \multicolumn{4}{|c|}{0.6} \\
\hline & & \multirow{4}{*}{3-Pole Series} & 24 V & \multicolumn{4}{|c|}{5} \\
\hline & & & 48 V & \multicolumn{4}{|c|}{2.5} \\
\hline & & & 100 to 110 V & \multicolumn{4}{|c|}{2} \\
\hline & & & 200 to 220 V & \multicolumn{4}{|c|}{1} \\
\hline \multirow{5}{*}{Rated Capacity [kW]} & \multicolumn{2}{|l|}{\multirow[t]{3}{*}{\begin{tabular}{l}
Three-Phase Squirrel-cage \\
Motor (Category AC-3)
\end{tabular}}} & 200 to 240 V & \multicolumn{4}{|c|}{2.5} \\
\hline & & & 380 to 440 V & \multicolumn{4}{|c|}{4} \\
\hline & & & 500 to 550 V & \multicolumn{4}{|c|}{4} \\
\hline & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Single-Phase Motor (Category AC-3)}} & 100 to 110 V & \multicolumn{4}{|c|}{0.2} \\
\hline & & & 200 to 220 V & \multicolumn{4}{|c|}{0.4} \\
\hline \multicolumn{4}{|c|}{Conventional Free Air Thermal Current [A]} & \multicolumn{4}{|c|}{20} \\
\hline \multicolumn{3}{|c|}{\multirow[t]{2}{*}{\begin{tabular}{l}
Breaking Capacity \\
[A]
\end{tabular}}} & 220 V & \multicolumn{4}{|c|}{120} \\
\hline & & & 440 V & \multicolumn{4}{|c|}{90} \\
\hline \multicolumn{3}{|c|}{\multirow[t]{2}{*}{\begin{tabular}{l}
Making Current Capacity \\
[A]
\end{tabular}}} & 220 V & & & & \\
\hline & & & 440 V & \multicolumn{4}{|c|}{90} \\
\hline \multicolumn{4}{|l|}{Switching Frequency [Times/Hour]} & & & & \\
\hline \multirow[t]{2}{*}{Switching Durability [ x 10000]} & \multicolumn{3}{|l|}{Electrical (Category AC-3)} & \multicolumn{4}{|c|}{100} \\
\hline & \multicolumn{3}{|c|}{Mechanical} & \multicolumn{4}{|c|}{1000} \\
\hline
\end{tabular}

Note 1. Electrical durability when operated with the following ripple rate after three-phase full-wave rectification. 0.8 mil. times for singlephase full-wave rectification. The electrical durability for three-phase cage motors (class AC-3) is listed below.
Class AC-1: 0.5 mil. times (however, the rating for 200 to 220 V resistive loads shown in parentheses is 0.25 mil. times), Class DC2/DC4: 0.5 mil. times, Class DC-13: 0.25 mil. times
Note 2. Compliant Standards: JIS C8201-4-1, JIS C8201-5-1, IEC 60947-4-1, IEC 60947-5-1 (* symbol indicates class DC2, DC4 are JEM 1038 only) Note 3. Refer to page 42 for details about applications at main contact low voltage and current.

\section*{Magnetic Starters/Magnetic Contactors/Contactor Relays According to Application}
(2) Auxiliary Contact Rating
\begin{tabular}{c|c|c|c|c}
\hline \multicolumn{2}{c|}{ Type } & Body & \begin{tabular}{c} 
Front Clip-on Auxiliary \\
Contact Unit
\end{tabular} \\
\hline \multicolumn{3}{c|}{ Model Name } & \begin{tabular}{c} 
SD-Q11/Q12/ \\
QR11/QR12
\end{tabular} & UQ-AX2(KR) \\
\hline \multirow{3}{*}{\begin{tabular}{c} 
Rated \\
Operating \\
Current \\
{\([A]\)}
\end{tabular}} & Category & AC240V & 3 & 3 \\
\cline { 2 - 5 } & AC-15 & AC440V & 1 & 1 \\
\cline { 2 - 5 } & Category DC-12 & DC24V & 10 & 10 \\
\cline { 2 - 4 } \begin{tabular}{c} 
Conventegory DC-13
\end{tabular} & DC110V & 0.6 & 0.6 \\
\hline \multicolumn{2}{c|}{\begin{tabular}{c} 
Electrical
\end{tabular}} \\
\hline
\end{tabular}

Note 1. The minimal applicable load is \(5 \mathrm{~V}, 3 \mathrm{~mA}\). (Refer to page 42 for details.)
Note 2. JISC8201-5-1 classifications are class AC-15 applicable to AC inductive loads (AC coil load (exceeding 72 VA ) control), class DC-12 applicable to DC resistive loads, and class DC-13 applicable to DC coil loads.
(3) No. of Installed Auxiliary Contacts and Contact Arrangement
\begin{tabular}{c|c|c|c|c}
\hline \multirow{2}{*}{\begin{tabular}{c} 
Frame \\
Model
\end{tabular}} & \multicolumn{2}{|c|}{ Non-Reversible Type } & \multicolumn{2}{c}{ Reversible Type } \\
\cline { 2 - 5 } Q11 & Q12 & QR11 & QR12 \\
\hline Standard & 1a & 1a1b & \(1 \mathrm{~b} \times 2\) & \(1 \mathrm{a} 1 \mathrm{~b} \times 2\) \\
\hline Special & 1b & 2 a & - & - \\
\hline Maximum & \begin{tabular}{c} 
2a1b \\
1a2b
\end{tabular} & - & \(1 \mathrm{a} 2 \mathrm{~b} \times 2\) & - \\
\hline
\end{tabular}

Note 1. The auxiliary break contacts of reversible types are wired as an electrical interlock.
Note 2. Auxiliary contact arrangements for reversible types are displayed by twos, in a contact arrangement combining two contactors.
Note 3. No specification needs to be made for standard contact arrangements. Specify only for special arrangements.
Note 4. The maximum number of units is shown when mounting front clip-on UQ-AX2(KR) auxiliary contact units. The body and auxiliary contact unit can be additionally installed by the customer as a separate arrangement. Refer to notes 2 and 3 of the Manufactured Model List on page 243 for details about auxiliary contact unit combination.

\section*{Properties}
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Model Name} & \multirow[t]{2}{*}{Type} & \multicolumn{2}{|c|}{Non-Reversing} & \multicolumn{2}{|c|}{Reversing} \\
\hline & & Q11 & Q12 & QR11 & QR12 \\
\hline \multicolumn{2}{|r|}{Closing Voltage} & \multicolumn{4}{|c|}{85\% or Less of Rated Voltage} \\
\hline \multicolumn{2}{|r|}{Openning Voltage} & \multicolumn{4}{|c|}{10\% or More of Rated Voltage} \\
\hline \multirow[t]{2}{*}{Operating Time} & Coil ON \(\rightarrow\) Main Contact ON & \multicolumn{4}{|c|}{50 ms or less} \\
\hline & Coil OFF \(\rightarrow\) Main Contact OFF & \multicolumn{4}{|c|}{20 ms or less} \\
\hline \multirow[b]{3}{*}{Operation Coil Properties} & Average Coil Current & \multicolumn{4}{|c|}{55 mA} \\
\hline & Average Power Consumption & \multicolumn{4}{|c|}{1.3 W (1.65 W)} \\
\hline & Coil Time Constant & \multicolumn{4}{|c|}{10 ms} \\
\hline
\end{tabular}

Note 1. The above indicates rough property indices for DC24V coils. The values in the parentheses for the operation coil properties indicate rough property indices for DC48V coils.
Note 2. Operable Range: Applying the rated voltage to the coil at \(40^{\circ} \mathrm{C}\) ambient temperature allows operation without trouble at 85 to \(120 \%\) of rated voltage after temperature rise saturation.
Note 3. Voltage For Continuous Use: 95 to 100\% of coil rated voltage
Note 4. The operating time is the value when applying DC24V at a \(20^{\circ} \mathrm{C}\) cold state.

\section*{Rated Operation Coil}
\begin{tabular}{c|c}
\hline Coil Designation & Rated Voltage \\
\hline DC12V & DC12 V \\
\hline DC24V & DC24 V \\
\hline DC48V & DC48 V \\
\hline
\end{tabular}

Note 1. Please note that operation coil terminals have polarity. A1 (+), A2 (-)

\section*{Thermal Overload Relay Model Names and Heater Types Combinable With Magnetic Contactors}
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Magnetic Starter Model Name} & \multirow[t]{2}{*}{\begin{tabular}{l}
Compatible \\
Thermal Overload Relay Model Name
\end{tabular}} & \multirow[t]{2}{*}{Heater Designation [A]} & \multirow[t]{2}{*}{Adjustment Range of Settling Current [A]} & \multicolumn{2}{|l|}{Standard Three-Phase Motor Capacity [kW]} & \multicolumn{2}{|l|}{Control Circuit (Contact)} \\
\hline & & & & 200 to 220 V & 380 to 440 V & Contact Arrangement & Rating \\
\hline \multirow{10}{*}{\[
\begin{aligned}
& \text { MSOD-Q11(KP) } \\
& \text { MSOD-Q12(KP) } \\
& \text { MSOD-QR11(KP) } \\
& \text { MSOD-QR12(KP) }
\end{aligned}
\]} & \multirow{9}{*}{TH-T18(KP)} & 0.12 & 0.1 to 0.16 & & & \multirow{16}{*}{1a1b} & \multirow{16}{*}{\begin{tabular}{l}
Class AC-15 \\
AC110 V: 2 A \\
AC220 V: 1 A \\
Class DC-13 \\
DC110 V: 0.2 A
\end{tabular}} \\
\hline & & 0.17 & 0.14 to 0.22 & & & & \\
\hline & & 0.24 & 0.2 to 0.32 & 0.03 & 0.05 & & \\
\hline & & 0.35 & 0.28 to 0.42 & 0.05 & 0.1 & & \\
\hline & & 0.5 & 0.4 to 0.6 & 0.07 & & & \\
\hline & & 0.7 & 0.55 to 0.85 & 0.1 & 0.2 & & \\
\hline & & 0.9 & 0.7 to 1.1 & & & & \\
\hline & & 1.3 & 1 to 1.6 & 0.2 & 0.4 & & \\
\hline & & 1.7 & 1.4 to 2 & & 0.75 & & \\
\hline & \multirow{7}{*}{TH-T18BC(KP)} & 2.1 & 1.7 to 2.5 & 0.4 & & & \\
\hline \multirow[t]{6}{*}{\begin{tabular}{l}
MSOD-Q11BC(KP) \\
MSOD-Q12BC(KP) \\
MSOD-QR11BC(KP) \\
MSOD-QR12BC(KP)
\end{tabular}} & & 2.5 & 2 to 3 & & 1 & & \\
\hline & & 3.6 & 2.8 to 4.4 & 0.75 & 1.5 & & \\
\hline & & 5 & 4 to 6 & 1 & 2.2 & & \\
\hline & & 6.6 & 5.2 to 8 & 1.5 & 3.7 & & \\
\hline & & 9 & 7 to 11 & 2.2 & & & \\
\hline & & 11 & 9 to 13 & & & & \\
\hline
\end{tabular}

Note 1. KP includes 3-element 2E function
Note 2. Delay trip thermal overload relays are not manufactured

\section*{- Handling}
- Mounting

See below for the correct mounting method. Standard mounting puts the power terminal at the top and the load terminal at the bottom, but the mounting methods in the table below are also possible. Horizontal mounting is not possible.
Furthermore, MSOD-Q11, Q12, QR11 and QR12 type magnetic starters use only standard, diagonal, or floor mounting.
Be sure to securely fasten both the left and right of the units to the rail when rail-mounting reversible types (MSOD-QR11,
QR12, SD-QR11, QR12).
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multicolumn{6}{|r|}{Mounting Direction} \\
\hline  &  & \begin{tabular}{l}
Top \\
Bottom
\end{tabular} & Bottom &  & \begin{tabular}{l}
Top \\
Bottom
\end{tabular} \\
\hline Standard Mounting & Diagonal Mounting & Horizontal Mounting & Reverse Mounting & Floor Mounting & Ceiling Mounting \\
\hline \(\bigcirc\) & \(\bigcirc\) & x & O (MSOD: x ) & \(\bigcirc\) & O (MSOD: x ) \\
\hline
\end{tabular}
- Connecting
\begin{tabular}{c|c|c|c|c|c|c}
\hline \multirow{2}{*}{ Model Name } & \multicolumn{3}{|c|}{ Main Circuit } & \multicolumn{3}{c}{ Control Circuit } \\
\cline { 2 - 7 } & \begin{tabular}{c} 
Applicable Wire \\
Size
\end{tabular} & \begin{tabular}{c} 
Applicable Crimp \\
Lug Size
\end{tabular} & \begin{tabular}{c} 
Tightening Torque N.m Parentheses \\
show standard value
\end{tabular} & \begin{tabular}{c} 
Applicable Wire \\
Size
\end{tabular} & \begin{tabular}{c} 
Applicable Crimp \\
Lug Size
\end{tabular} & \begin{tabular}{c} 
Tightening Torque N•m \\
Parentheses show standard value
\end{tabular} \\
\hline Q11 & Q1.6, & \(1.25-3.5\) to & 0.94 to 1.17 & \begin{tabular}{c}
\(\varphi 1.6\),
\end{tabular} & \begin{tabular}{c}
\(1.25-3.5\) to \\
Q12
\end{tabular} & \begin{tabular}{c} 
to
\end{tabular} \\
QR11 & 1.25 to \(2 \mathrm{~mm}^{2}\) & \(2-3.5\) & \((1.0)\) & 1.25 to \(2 \mathrm{~mm}^{2}\) & 0.94 to 1.17 \\
QR12 & & & & \((1.0)\)
\end{tabular}

Note 1. Use a crimp terminal with insulation tube if using crimp lugs at voltages exceeding 380 V .
Note 2. Remove the terminal cover for wiring if using ring crimp lugs. Be sure to reattach the terminal cover once wiring is completed. (Not required for thermal overload relays with MSOD-Q \(\square \mathrm{BC}\), as wiring streamlining terminals are included.)
Note 3. This is a compact product that may deform if terminal screws are tightened with a greater torque than listed above. Take care when tightening as this may affect the product's properties.
- Disassembly

SD-Q contactors are calibrated when assembled, so the coil and contacts cannot be replaced. (Do not disassemble.)

\section*{- Connection Method}
- Connecting Various Models
(1) SD-Q11, Q12 types have integrated surge absorber function.
(DC12V, DC24V Coil: Varistor Voltage 68 V, DC48V Coil: Varistor Voltage 100 V )
There is no need to connect external surge absorbers to regular sequence circuits.
(2) The integrated surge protection element increases the return time when connected to various DC output type devices.

The figure below shows the connections when connecting to transistor output type devices.
\begin{tabular}{|c|c|c|c|}
\hline Output Type & Transistor Output (Sink Type) & Transistor Output (Source Type) & Transistor Output (Sink Type) \\
\hline Protection Method & \multicolumn{2}{|r|}{Zener Diode or Varistor} & Protection Diode \\
\hline Connection Method &  &  &  \\
\hline \[
\begin{array}{c|c}
\hline \frac{0}{O} & \text { Mitsubishi PLC } \\
& \text { A, Q Series (Typical) } \\
\hline
\end{array}
\] & \begin{tabular}{l}
AY50, 51, AY60 \\
AISY40P, 41P, 42P, AISY50, AISY60 Output Unit QY40P, 41P, 42P, QY50
\end{tabular} & \begin{tabular}{l}
AY60E \\
AISY60E, AISY80, AISY81 Output Unit QY80, QY81P
\end{tabular} & AY40, 41, 42 Output Unit \\
\hline Other & Proximity Switches Photoelectric Switches & Proximity Switches Photoelectric Switches & Various Programmable Controllers etc. \\
\hline Return Time & \multicolumn{2}{|r|}{Approx. 10 ms longer} & Approx. 30 ms longer \\
\hline
\end{tabular}

\footnotetext{
(3) Operation coil terminals have polarity. Refer to the Precautions in the Outline Drawings/Contact Arrangements column.
}

\section*{Magnetic Starters/Magnetic Contactors/Contactor Relays According to Application}

\section*{Outline Drawings}


\section*{SD-QR11}

\(* 1\) dimension is the length from the center of the IEC 35 mm rail.
\(* 2\) dimension includes the head-on auxiliary contact unit (UQ-AX2, AX2KR).


SD-QR12


Note 1. The contact arrangement and coil terminal location differ between non-reversible and reversible types.Reversible types, in particular, have reversed coil polarity so extra care should be taken when wiring.
Note 2. The 2 auxiliary break contacts of reversible types are wired as an electrical interlock so should be used in an electrically interlocked state.
Note 3. Operation coil terminals have polarity.
Connect terminal number A1 (+) to the positive and A2 (-) to the negative sides.
- Magnetic Starters


Note 1. The contact arrangement and coil terminal location differ between non-reversible and reversible types.Reversible types, in particular, have reversed coil polarity so extra care should be taken when wiring.
Note 2. The 2 auxiliary break contacts of reversible types are wired as an electrical interlock so should be used in an electrically interlocked state.
Note 3. Operation coil terminals have polarity.
Connect terminal number A1 (+) to the positive and A2 (-) to the negative sides.
- Optional

UQ-AX2
UQ-AX2KR


UQ-PL


Connect terminals A1 (+) and A2(-) of the main coil to terminals A1(+) and A2(-)
of the unit, respectively.

Note 1. The contact arrangement and coil terminal location differ between non-reversible and reversible types.Reversible types, in particular, have reversed coil polarity so extra care should be taken when wiring.
Note 2. The 2 auxiliary break contacts of reversible types are wired as an electrical interlock so should be used in an electrically interlocked state.
Note 3. Operation coil terminals have polarity.
Connect terminal number A1 (+) to the positive and A2 (-) to the negative sides.

\section*{\(9.3 \mathrm{~B}-\mathrm{T} / \mathrm{N} \square \mathrm{NC}\) Main Contact Contactors \\ Can be used for motor control and power switching for lighting circuits}

B-T/N type magnetic contactors have a break contact as the main contact (normally closed contact) that is suited for use shorting motor starting resistance, cushion-starting AC motors, power generation (dynamic braking) and AC/DC power switching for lighting circuits. AC operated types are B-T/N type, DC operated types are BD-T/N type.

\section*{- Features}
- Compact and Space-Saving

Dramatically reduced outline drawings and mounting area compared to conventional products
- Featuring an AC Operated DC Excitation Type Magnet (B-N65/N100)
- Completely eliminates buzzing
- Wide range rated coil (designation

AC200V: rated AC200 to \(240 \mathrm{~V} 50 / 60 \mathrm{~Hz}\) )
- Surge absorber comes built-in
- Dramatically reduced power consumption


B-T21
- Supports Live Part Protection
- Live part protection covers are standard equipment (B(D)-T21)
- Applicable with live part protection cover units UN-CV/CZ \(\square\) (B(D)-N \(\square\) )
- Adopts Auxiliary Twin Contacts All auxiliary contacts are high contact reliability twin contacts that can be applied with 20 V 5 mA loads
- Improved Safety

A main circuit inter-phase barrier is equipped as standard
- Improved Environmental Applicability Materials used are indicated on main plastic components

\section*{Rating/Performance}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Operating Method} & \multirow{3}{*}{Model Name} & \multirow{3}{*}{\begin{tabular}{l}
Main Contact \\
Arrangement
\end{tabular}} & \multicolumn{4}{|c|}{DC Rated Operational Current [A]} & \multirow[t]{3}{*}{\begin{tabular}{|c|}
\hline Conventional \\
Free Air Thermal \\
Current \\
lth \([\mathrm{A}]\) \\
\hline
\end{tabular}} & \multirow[t]{3}{*}{Rated
Insulation
Voltage
[V]} & \multirow[b]{3}{*}{\begin{tabular}{l}
Auxiliary \\
Contact Arrangement
\end{tabular}} \\
\hline & & & \multicolumn{2}{|l|}{\[
\begin{gathered}
\text { DC Motor Load } \\
\text { (Category DC-3, DC-5, DC2, DC4) }
\end{gathered}
\]} & \multicolumn{2}{|l|}{DC Resistive Load (Category DC-1, DC1)} & & & \\
\hline & & & 100 to 110 V & 200 to 220 V & 100 to 110 V & 200 to 220 V & & & \\
\hline \multirow{3}{*}{AC Operated} & B-T21(BC) & & 8 (15) & 1 (5) & 15 (20) & 5 (10) & 25 & \multirow{6}{*}{690} & 2a2b \\
\hline & B-N65 & & 20 (50) & 3 (20) & 30 (65) & 10 (30) & 80 & & \\
\hline & B-N100 & 1a2b & 30 & 3 & 40 & 20 & 120 & & 2a2b \\
\hline \multirow{3}{*}{DC Operated} & BD-T21(BC) & \multirow{3}{*}{1a2b} & 8 & 1 & 15 & 5 & 25 & & 2a2b \\
\hline & BD-N65 & & 20 & 3 & 30 & 10 & 80 & & \\
\hline & BD-N100 & & 30 & 3 & 40 & 20 & 120 & & a2 \\
\hline
\end{tabular}

Note 1. The DC rating indicated is for 2-poles in series. The value in parentheses is for 3-poles in series.
Note 2. Electrical durability of 500,000 operations, mechanical durability of 5 million operations and switching frequency of 1200 times/hour
Note 3. Auxiliary contact ratings are the same as N35 to N800 types or greater. (Refer to page 41)
Note 4. Use the following table when applying AC to main circuit contacts.
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow{4}{*}{Operating Method} & \multirow{4}{*}{Model Name} & \multirow{4}{*}{Main Contact Arrangement} & \multicolumn{5}{|c|}{AC Rated Operational Current [A]} \\
\hline & & & \multicolumn{4}{|c|}{Break Contact} & Make Contact \\
\hline & & & \multicolumn{2}{|c|}{Three-Phase} & 2-Pole Series Single Phase & 1-Pole Single Phase & 1-Pole Single Phase \\
\hline & & & 200 to 220 V & 380 to 440 V & 200 to 220 V & 200 to 220 V & 200 to 220 V \\
\hline \multirow{3}{*}{AC Operated} & B-T21(BC) & \multirow[t]{2}{*}{1a2b, 3b} & 18 & 13 & 18 & 18 & 18 \\
\hline & B-N65 & & 50 & 35 & 50 & 50 & 50 \\
\hline & B-N100 & 1a2b & 80 & 55 & 80 & 80 & 80 \\
\hline \multirow{3}{*}{DC Operated} & BD-T21(BC) & \multirow{3}{*}{1a2b} & 18 & 13 & 18 & 18 & 18 \\
\hline & BD-N65 & & 50 & 35 & 50 & 50 & 50 \\
\hline & BD-N100 & & 80 & 55 & 80 & 80 & 80 \\
\hline \multicolumn{3}{|l|}{Making/Breaking Duty Conditions/ Switching Durability} & \multicolumn{2}{|l|}{Making Only, Without Breaking/
500,000 Times} & Making and Breaking/
500,000 Times & Making Only, Without Breaking/500,000 Times & Making and Breaking/
500,000 Times \\
\hline
\end{tabular}

Note 1. Switching durability is the value when making at 6 times the rated current, breaking at 1 time the rated current or without breaking.
\begin{tabular}{|c|c|c|c|}
\hline \multirow[t]{5}{*}{Related Reference Page} & Item & Reference Page & Remarks \\
\hline & - Auxiliary Contact Rating & Page 41 & - \\
\hline & - Operation Coil & Pages 43, 44 & - \\
\hline & - How to Order & Page 263 & - \\
\hline & - Combining with Optional Units & Page 194 & - \\
\hline
\end{tabular}

\section*{Magnetic Starters/Magnetic Contactors/Contactor Relays According to Application}

\section*{Properties}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Model Name} & \multicolumn{2}{|c|}{Input [VA]} & \multirow[t]{2}{*}{Power Consumption (W)} & \multicolumn{2}{|l|}{Operating Voltage [V]} & \multirow[t]{2}{*}{Coil Current [mA]} & \multicolumn{2}{|c|}{Operating Time [ms]} \\
\hline & Inrush & Normal & & Close & Open & & Coil ON \(\rightarrow\) Main Break OFF & Coil OFF \(\rightarrow\) Main Break ON \\
\hline B-T21 & 75 & 7 & 2.4 & 125 to 155 & 75 to 110 & 30 & 7 to 15 & 13 to 25 \\
\hline B-N65 & 210 & 23 & 2.8 & 110 to 140 & 50 to 100 & 85 & 12 to 28 & 45 to 105 \\
\hline B-N100 & 270 & 24 & 2.9 & 110 to 140 & 60 to 130 & 100 & 20 to 25 & 110 to 130 \\
\hline BD-T21 & \multicolumn{2}{|c|}{-} & \[
\begin{gathered}
\hline 3.3 \\
(2.2)
\end{gathered}
\] & 50 to 65 & 10 to 30 & 33 & \[
\begin{aligned}
& 45 \text { to } 60 \\
& (70 \text { to } 85)
\end{aligned}
\] & 10 to 30 \\
\hline BD-N65 & \multicolumn{2}{|c|}{-} & 24 & 55 to 65 & 12 to 30 & 240 & 68 to 92 & 13 to 29 \\
\hline BD-N100 & \multicolumn{2}{|c|}{-} & 31 & 50 to 65 & 12 to 30 & 310 & 104 to 156 & 30 to 70 \\
\hline
\end{tabular}

Note 1. The above indicates rough property indices for \(A C 200 \mathrm{~V}\) coils under \(A C\) operation ( \(B-T / N \square\) ) and for DC100V coils under DC operation (BD-T/N \(\square\) ).
The values in the parentheses for BD-T21 indicate rough property indices for DC12V or DC24V coils.
Note 2. The operating voltage is the value at a \(20^{\circ} \mathrm{C}\) cold state for both \(\mathrm{AC}(\mathrm{at} 60 \mathrm{~Hz}\) ) and DC operation. Voltages for coils other than AC200V or DC100V can be calculated proportionately.
Note 3. The input and power consumption indicated are average values. These are almost the same for coils other than AC200V or DC100V.
Note 4. The coil current is the average normal value with 220 V 60 Hz applied for AC operated types and DC100V applied for DC operated types. Divide the regular input for coils other than AC200V, or the power consumption for coils other than DC100V, by the coil voltage.
Note 5. The operating time is the value with 220 V 60 Hz applied for AC operated types and DC100 V applied for DC operated types. These are almost the same for coils other than AC200V or DC100V.

Contact Arrangement
\begin{tabular}{|c|c|c|c|c|c|}
\hline Model Name & Main 1a2b & Main 3b & Model Name & Main 1a2b & Main 3b \\
\hline B-T21 & Aux. 2a2b & Aux. 2a2b & BD-T21 & \begin{tabular}{l}
 \\
Aux. 2a2b
\end{tabular} & - \\
\hline B-N65 & Aux. 2a2b & Aux. 2a2b & BD-N65 & Aux. 2a2b & - \\
\hline B-N100 & Aux. 2a2b & - & BD-N100 & Aux. 2a2b & - \\
\hline
\end{tabular}

Handling
- Applicable Wire Size and Terminal Screw Tightening Torque
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Model Name} & \multicolumn{3}{|c|}{Terminal Dimensions} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Applicable Wire Size [ \(\mathrm{mm}^{2}\) ]}} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Applicable Crimp Lug Size}} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Terminal Screw Tightening Torque N.m Parentheses show standard value}} \\
\hline & \multicolumn{2}{|r|}{Main Circuit} & \multirow[t]{2}{*}{\begin{tabular}{l}
Control Circuit \\
Screw Size
\end{tabular}} & & & & & & \\
\hline & Screw Size & Terminal Dimensions \(A \times B \times C[m m]\) & & Main Circuit & Control Circuit & Main Circuit & Control Circuit & Main Circuit & Control Circuit \\
\hline B-T21, BD-T21 & M4 & \(10.5 \times 5.2 \times 5.5\) & M3.5 & Q 1.6to 2.6, 1.25 to 6 & \(\varphi\) 1.6, 0.75 to 2.5 & 1.25-4 to 5.5-4 & 1.25-3.5 to 2-3.5 & 1.2 to 1.9 & 0.9 to 1.5 \\
\hline B-N65, BD-N65 & M6 & \(15 \times 7.5 \times 11.5\) & M4 & - & \(\varphi 1.6\) & 1.25-6 to 60-6 & 1.25-4 to 2-4 & 3.53 to 5.78(4.41) & 1.18 to 1.86(1.47) \\
\hline B-N100, BD-N100 & M8 & \(15 \times 8.5 \times 16\) & M4 & - & 1.25 to 2 & 5.5-8 to 60-8 & 5.5-S4 & 6.28 to 10.29(7.84) & 1.18 to \(1.86(1.47)\) \\
\hline
\end{tabular}

Note 1. The terminal dimension is a dimension for bus bar connection. (Refer to the figure on the right)
Note 2. Control circuits are auxiliary contact terminals or coil terminals of magnetic contactors.
Note 3. In each terminal, a wire or two crimp lugs may be connected.


\section*{Outline Drawings}
\begin{tabular}{|c|c|c|c|}
\hline Model Name/Appearance & Outline Drawings & Hole Drilling Dimensions & Weight [kg] \\
\hline  &  &  & 0.41 \\
\hline  &  &  & 1.7 \\
\hline  &  &  & 2.7 \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|}
\hline Model Name/Appearance & Outline Drawings & Hole Drilling Dimensions & Weight [kg] \\
\hline  &  &  & 0.59 \\
\hline  & Auxiliary contact units are not applicable. &  & 3.0 \\
\hline  &  &  & 4.3 \\
\hline
\end{tabular}

\subsection*{9.4 DU-N \(\square\) Magnetic Contactors for DC Ideal for controlling DC motors of 440 V or less, or for switching general DC circuits}

DU-N types are compact, high-performance DC contactors applicable with voltages DC440 V or less. Can be used for variable speed DC motor control and other general DC circuits and available as AC operated type DU-N (main contact 2a1b) and DC operated type DUD-N (main contact 2a).

\section*{Features}
- Compact and Space-Saving

Dramatically reduced outline drawings and mounting area compared to conventional products
- Featuring an AC Operated DC Excitation Type Magnet (DU-ND)
- Completely eliminates buzzing
- Wide range rated coil (designation AC200V: rated AC200 to 240 V 50/60 Hz)
- Surge absorber comes built-in
- Dramatically reduced power consumption (DU-N30: 2.2 W, DU-N120: 2.9 W)
- Supports Finger Protection

Applicable with live part protection
cover units UN-CZ \(\square\) used by MS-N series


DU-N30
- Adopts Auxiliary Twin Contacts Auxiliary contacts are high contact reliability twin contacts that can be applied with DC20 V 5 mA loads
- Additional Auxiliary Contact Units Applicable
Applicable with auxiliary contact units UN-AX \(\square\) used by MS-N series
- Improved Environmental Applicability Materials used are indicated on main plastic components
- Improved Plastic Component Strength (DU/DUD-N30)
Adopts thermoplastic resin around the terminals

\section*{Rating}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Operating Method} & \multirow{3}{*}{Model Name} & \multirow{3}{*}{Main Contact Arrangement} & \multicolumn{2}{|l|}{\multirow{3}{*}{Main Contact Series Connection}} & \multicolumn{6}{|c|}{Rated Operating Current [A]} & \multicolumn{3}{|l|}{\multirow[t]{2}{*}{\begin{tabular}{c} 
Rated Capacity [kW] \\
\hline General DC Motors \\
(Category DC2 and DC4) \\
\hline
\end{tabular}}} & \multirow[t]{3}{*}{Conventional Free Air Thermal Current lth \([A]\)} & \multirow[b]{3}{*}{Rated Insulation Voltage} & \multirow{3}{*}{Auxiliary Contact Arrangement} \\
\hline & & & & & \multicolumn{3}{|l|}{Variable Speed Motor Control: Make Contact Dynamic Braking: Break Contact} & \multicolumn{3}{|l|}{General DC Motors (Category DC2 and DC4)} & & & & & & \\
\hline & & & & & DC110V & DC220V & DC440V & DC110V & DC220V & DC440V & DC110V & DC220V & DC440V & & & \\
\hline \multirow{15}{*}{\begin{tabular}{l}
AC \\
Operated
\end{tabular}} & \multirow{3}{*}{DU-N30} & \multirow{15}{*}{2a1b} & Make & Single Pole & 40 & 40 & 15 & 30 & 20 & - & 2.2 & 3.7 & - & \multirow[b]{2}{*}{60} & \multirow{15}{*}{660 V} & \multirow{15}{*}{2 a 2 b} \\
\hline & & & Contact & 2-Pole & 50 & 50 & 40 & 40 & 30 & 20 & 3.7 & 5.5 & 7.5 & & & \\
\hline & & & \multicolumn{2}{|l|}{Break Contact Single-Pole} & 120 * 1 & 120 * 1 & \(120 * 1\) & 20 & 15 & - & 1.5 & 2.2 & - & 50 & & \\
\hline & \multirow{3}{*}{DU-N60} & & Make & Single Pole & 80 & 80 & 30 & 60 & 40 & - & 5.5 & 7.5 & - & \multirow[t]{2}{*}{120} & & \\
\hline & & & Contact & 2-Pole & 90 & 90 & 80 & 80 & 60 & 40 & 7.5 & 11 & 15 & & & \\
\hline & & & \multicolumn{2}{|l|}{Break Contact Single-Pole} & 240 *1 & \(240 * 1\) & 240 * 1 & 40 & 30 & - & 3.7 & 5.5 & - & 100 & & \\
\hline & \multirow{3}{*}{DU-N120} & & Make & Single Pole & 160 & 160 & 60 & 120 & 80 & - & 11 & 15 & - & \multirow{3}{*}{160} & & \\
\hline & & & Contact & 2-Pole & 160 & 160 & 160 & 160 & 120 & 80 & 15 & 22 & 30 & & & \\
\hline & & & \multicolumn{2}{|l|}{Break Contact Single-Pole} & 480 * 1 & \(480 * 1\) & 480 * 1 & 80 & 60 & - & 7.5 & 11 & - & & & \\
\hline & \multirow{3}{*}{DU-N180} & & Make & Single Pole & 260 & 260 & 90 & 180 & 120 & - & 15 & 22 & - & \multirow[b]{2}{*}{270} & & \\
\hline & & & Contact & 2-Pole & 260 & 260 & 260 & 240 & 180 & 120 & 22 & 35 & 45 & & & \\
\hline & & & \multicolumn{2}{|l|}{Break Contact Single-Pole} & 720 * 1 & 720 * 1 & 720 * 1 & 100 & 75 & - & 7.5 & 11 & - & 260 & & \\
\hline & \multirow{3}{*}{DU-N260} & & Make & Single Pole & 360 & 360 & 130 & 260 & 175 & - & 22 & 30 & - & \multirow{3}{*}{360} & & \\
\hline & & & Contact & 2-Pole & 360 & 360 & 360 & 350 & 260 & 175 & 30 & 45 & 55 & & & \\
\hline & & & \multicolumn{2}{|l|}{Break Contact Single-Pole} & 1040 *1 & 1040 * 1 & 1040 * 1 & 150 & 100 & - & 11 & 18.5 & - & & & \\
\hline \multirow{10}{*}{DC Operated} & \multirow[t]{2}{*}{DUD-N30} & \multirow{10}{*}{2 a} & Make & Single Pole & 40 & 40 & 15 & 30 & 20 & - & 2.2 & 3.7 & - & \multirow[t]{2}{*}{60} & \multirow{10}{*}{660V} & \multirow{10}{*}{2 a 2 b} \\
\hline & & & Contact & 2-Pole & 50 & 50 & 40 & 40 & 30 & 20 & 3.7 & 5.5 & 7.5 & & & \\
\hline & \multirow[t]{2}{*}{DUD-N60} & & Make & Single Pole & 80 & 80 & 30 & 60 & 40 & - & 5.5 & 7.5 & - & \multirow[t]{2}{*}{120} & & \\
\hline & & & Contact & 2-Pole & 90 & 90 & 80 & 80 & 60 & 40 & 7.5 & 11 & 15 & & & \\
\hline & \multirow[t]{2}{*}{DUD-N120} & & Make & Single Pole & 160 & 160 & 60 & 120 & 80 & - & 11 & 15 & - & \multirow[t]{2}{*}{160} & & \\
\hline & & & Contact & 2-Pole & 160 & 160 & 160 & 160 & 120 & 80 & 15 & 22 & 30 & & & \\
\hline & \multirow[t]{2}{*}{DUD-N180} & & Make & Single Pole & 260 & 260 & 90 & 180 & 120 & - & 15 & 22 & - & \multirow[t]{2}{*}{270} & & \\
\hline & & & Contact & 2-Pole & 260 & 260 & 260 & 240 & 180 & 120 & 22 & 35 & 45 & & & \\
\hline & \multirow[t]{2}{*}{DUD-N260} & & Make & Single Pole & 360 & 360 & 130 & 260 & 175 & - & 22 & 30 & - & \multirow[t]{2}{*}{360} & & \\
\hline & & & Contact & 2-Pole & 360 & 360 & 360 & 350 & 260 & 175 & 30 & 45 & 55 & & & \\
\hline
\end{tabular}

Note 1. Variable speed motor control (make contact) duty applied 2 times tripping/no voltage open-circuit, dynamic braking (break contact) duty applied 1 times tripping/no voltage open-circuit.
Note 2. General DC motors are applicable with JEM1038 class DC2 (shunt motor starting/stopping), class DC4 (series-wound motor starting/stopping) motor loads.
Note 3. Allowable continuity current of \(* 1\) is for 30 seconds. Inching operations should be conducted at the rated operating current of general DC motors.
Note 4. Auxiliary contact ratings are the same as N125 to N800 types. (Refer to page 41)
Note 5. Reversible types (DU-2xN \(\square\), DUD-2xN \(\square\) ) can also be manufactured.

\title{
Magnetic Starters/Magnetic Contactors/Contactor Relays According to Application
}

\section*{Performance}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Model Name} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Main Contact Series Connection}} & \multicolumn{3}{|l|}{Breaking Capacities [A] Note 1} & \multirow[t]{2}{*}{Making Current Capacity [A] Note 2} & \multirow[t]{2}{*}{Switching Frequency [Times/Hour]} & \multicolumn{2}{|l|}{Switching Durability [x 10000]} \\
\hline & & & DC110 V & DC220 V & DC440 V & & & Mechanical & Electrical \\
\hline \multirow[b]{2}{*}{DUD-N30} & Make & Single Pole & 120 & 80 & - & \multirow{3}{*}{160} & \multirow{15}{*}{1200} & \multirow{15}{*}{250} & \multirow{15}{*}{50} \\
\hline & Contact & 2-Pole & 160 & 120 & 80 & & & & \\
\hline DU-N30 & \multicolumn{2}{|l|}{Break Contact Single-Pole} & 80 & 60 & - & & & & \\
\hline DUD-N60 & Make & Single Pole & 240 & 160 & - & \multirow{3}{*}{320} & & & \\
\hline & Contact & 2-Pole & 320 & 240 & 160 & & & & \\
\hline DU-N60 & \multicolumn{2}{|l|}{Break Contact Single-Pole} & 160 & 120 & - & & & & \\
\hline DUD-N120 & Make & Single Pole & 480 & 320 & - & \multirow{3}{*}{640} & & & \\
\hline DUD-N120 & Contact & 2-Pole & 640 & 480 & 320 & & & & \\
\hline DU-N120 & \multicolumn{2}{|l|}{Break Contact Single-Pole} & 320 & 240 & - & & & & \\
\hline DUD- & Make & Single Pole & 720 & 480 & - & \multirow{3}{*}{960} & & & \\
\hline DUD- & Contact & 2-Pole & 960 & 720 & 480 & & & & \\
\hline DU-N180 & \multicolumn{2}{|l|}{Break Contact Single-Pole} & 400 & 300 & - & & & & \\
\hline DU & Make & Single Pole & 1040 & 700 & - & \multirow{3}{*}{1400} & & & \\
\hline DUD-N260 & Contact & 2-Pole & 1400 & 1040 & 700 & & & & \\
\hline DU-N260 & \multicolumn{2}{|l|}{Break Contact Single-Pole} & 600 & 400 & - & & & & \\
\hline
\end{tabular}

Note 1. Time constant L/R \(=15 \mathrm{~ms}, 25\) shut-off transitions.
Note 2. Time constant L/R = \(15 \mathrm{~ms}, 100\) closings

\section*{- Properties}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{\begin{tabular}{l}
Model \\
Name
\end{tabular}} & \multicolumn{2}{|l|}{Input [VA]} & \multirow[t]{2}{*}{Power Consumption MI} & \multicolumn{2}{|l|}{Operating Voltage [V]} & \multirow[t]{2}{*}{Coil Current [mA]} & \multicolumn{4}{|c|}{Operating Time [ms]} \\
\hline & Inrush & Normal & & Close & Open & & Coil ON \(\rightarrow\) Main Make ON & Coil ON \(\rightarrow\) Main Break OFF & Coil OFF \(\rightarrow\) Main Make OFF & Coil OFF \(\rightarrow\) Main Break ON \\
\hline DU-N30 & 115 & 20 & 2.2 & 133 & 57 & 67 & 12 to 15 & 10 to 13 & 66 to 72 & 65 to 76 \\
\hline DU-N60 & 270 & 24 & 2.9 & 112 & 68 & 100 & 20 to 23 & 17 to 20 & 75 to 103 & 78 to 108 \\
\hline DU-N120 & 270 & 24 & 2.9 & 125 & 76 & 100 & 25 to 27 & 20 to 22 & 75 to 103 & 80 to 110 \\
\hline DU-N180 & 440 & 40 & 4.2 & 109 & 76 & 165 & 32 to 34 & 24 to 26 & 85 to 105 & 90 to 140 \\
\hline DU-N260 & 440 & 50 & 6.1 & 112 & 58 & 200 & 37 to 39 & 29 to 31 & 100 to 130 & 105 to 140 \\
\hline DUD-N30 & - & - & 18 & 61 & 22 & 180 & 42 to 52 & - & 14 to 17 & - \\
\hline DUD-N60 & - & - & 31 & 52 & 18 & 310 & 100 to 103 & - & 16 to 18 & - \\
\hline DUD-N120 & - & - & 31 & 54 & 16 & 310 & 102 to 110 & - & 18 to 20 & - \\
\hline DUD-N180 & - & - & 41 & 56 & 15 & 410 & 112 to 120 & - & 20 to 25 & - \\
\hline DUD-N260 & - & - & 55 & 54 & 13 & 550 & 140 to 150 & - & 30 to 50 & - \\
\hline
\end{tabular}

Note 1. The above indicates rough property indices for AC200V coils under AC operation (DU-N \(\square\) ) and for DC100V coils under DC operation (DUD-N \(\square\) ).
Note 2. The operating voltage is the average value at a \(20^{\circ} \mathrm{C}\) cold state for both AC (at 60 Hz ) and DC operation. Voltages for coils other than AC200V or DC100V can be calculated proportionately.
Note 3. The input and power consumption indicated are average values. These are almost the same for coils other than AC200V or DC100V.
Note 4. The coil current is the average value with 220 V 60 Hz applied for AC operated types and DC100V applied for DC operated types. Divide the regular input for coils other than AC200V, or the power consumption for coils other than DC100V, by the coil voltage.
Note 5. The operating time is the value with 220 V 60 Hz applied for AC operated types and DC100V applied for DC operated types. These are almost the same for coils other than AC200V or DC100V.
\begin{tabular}{|c|c|c|c|}
\hline \multirow[t]{5}{*}{Related Reference Page} & Item & Reference Page & Remarks \\
\hline & - Auxiliary Contact Rating & Page 41 & - \\
\hline & - Operation Coil & Pages 43, 44 & - \\
\hline & - How to Order & Page 263 & - \\
\hline & - Combining with Optional Units & Page 194 & - \\
\hline
\end{tabular}

\section*{Outline Drawings}
\begin{tabular}{|c|c|c|c|}
\hline Model Name/Appearance & Outline Drawings & Hole Drilling Dimensions & Weight [kg] \\
\hline DU-N30 &  &  & 0.77 \\
\hline  &  &  & 2.6 \\
\hline  & 2 auxiliary contact units (UN-AX150) can be installed. &  & 3.2 \\
\hline DU-N180 &  &  & 5.3 \\
\hline  &  &  & 9.0 \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|}
\hline Model Name/Appearance & Outine Drawings & Hole Drilling Dimensions & Weight [kg] \\
\hline DUD-N30 & *1 dimension includes the head-on auxiliary contact unit (UN-AX2, AX4).
*2, *3 dimensions indicate when using a side-on auxiliary contact unit (UN-AX11) - *2 indicates 1 piece,
\(* 3\) indicates 2 pieces (both sides). It should be noted that it cannot be used with the head-on and side-on auxiliary *3 indicates 2 pieces (both sides). It sho &  & 2.1 \\
\hline  &  &  & 4.3 \\
\hline DUD-N120 &  &  & 4.9 \\
\hline  &  &  & 7.4 \\
\hline  & 2 auxiliary contact units (UN-AX150) can be installed. &  & 12.3 \\
\hline
\end{tabular}

\section*{Contact Arrangement/Connection Diagram}

Main 2a1b + Aux. 2a2b


Fig. 1. DU-N30, N60, N120
DU-N180, N260

Main 2a + Aux. 2a2b


Fig. 2. DUD-N30, N60, N120 DUD-N180, N260

Note 1. The main contact terminals have \(\ominus\) negative or \(\oplus\) positive polarity. Be sure tomake connections with the correct polarity. If the polarity is incorrect then breaking isn't possible.

\section*{- Handling}
- Applicable Wire Size and Terminal Screw Tightening Torque
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Model Name} & \multicolumn{3}{|c|}{Terminal Dimensions} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Applicable Wire Size [ \(\mathrm{mm}^{2}\) ]}} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Applicable Crimp Lug Size}} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{\begin{tabular}{l}
Terminal Screw Tightening Torque N•m \\
Parentheses show standard value
\end{tabular}}} \\
\hline & \multicolumn{2}{|r|}{Main Circuit} & \multirow[t]{2}{*}{\begin{tabular}{l}
Control Circuit \\
Screw Size
\end{tabular}} & & & & & & \\
\hline & Screw Size & Terminal Dimensions \(A \times B \times C[m m]\) & & Main Circuit & Control Circuit & Main Circuit & Control Circuit & Main Circuit & Control Circuit \\
\hline DU-N30, DUD-N30 & M6 & \(15 \times 7 \times 8.5\) & M4 & - & & \[
\begin{array}{|r|}
\hline 1.25-6 \text { to } 22-6 \\
38-\mathrm{S} 6
\end{array}
\] & & 3.53 to 5.78(4.41) & \\
\hline DU-N60, DUD-N60 & M8 & \(15 \times 8.5 \times 16\) & M4 & - & \(\varphi 1.6\) & 5.5-8 to 60-8 & \[
1.25-4 \text { to }
\] & 6.28 to 10.29(7.84) & 1.18 to 1.86 \\
\hline DU-N120, DUD-N120 & M8 & \(20 \times 10 \times 16\) & M4 & - & 1.25 to 2 & 8-8 to 100-8 & & 6.28 to 10.29(7.84) & (1.47) \\
\hline DU-N180, DUD-N180 & M10 & \(25 \times 12.5 \times 18\) & M4 & - & & 14-10 to 150-10 & & 11.8 to 19.1(14.7) & \\
\hline DU-N260, DUD-N260 & M12 & \(30 \times 15 \times 22.5\) & M4 & - & & 22-12 to 200-12 & & 19.6 to 31.3(24.5) & \\
\hline
\end{tabular}

Note 1. The terminal dimension is a dimension for bus bar connection. (Refer to the figure on the right)
Note 2. Control circuits are auxiliary contact terminals or coil terminals of magnetic contactors.
Note 3. In each terminal, a wire or two crimp lugs may be connected.


\subsection*{9.5 S-N \(\square K G\) Magnetic Contactors for High-Frequency Switching}

\section*{Ideal for applications with frequent inching operations such as hoists and cranes}

S-N \(\square K G\) type magnetic contactors have a reinforced main contact compared to standard magnetic contactors (adopts a large, hardened silver alloy contact) to be suitable for applications with frequent inching operations such as hoists and cranes.
- Rated Capacity, Rated Operating Current and Rated Continuity Current (JISC8201-4-1)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{3}{*}{\begin{tabular}{l}
Application \\
Model Name
\end{tabular}} & \multicolumn{4}{|c|}{Inching Duty - Category AC-4} & \multicolumn{4}{|c|}{Standard Duty - Category AC-3} & \multirow[t]{3}{*}{Conventional Free Air Thermal Current Ith [A]} \\
\hline & \multicolumn{2}{|l|}{Rated Capacity [kW]} & \multicolumn{2}{|l|}{Rated Operating Current [A]} & \multicolumn{2}{|l|}{Rated Capacity [kW]} & \multicolumn{2}{|l|}{Rated Operating Current [A]} & \\
\hline & 200 to 220 V & 380 to 440 V & 200 to 220 V & 380 to 440 V & 200 to 220 V & 380 to 440 V & 200 to 220 V & 380 to 440 V & \\
\hline S-N125KG & 15 & 22 & 65 & 47 & 30 & 60 & 125 & 120 & 150 \\
\hline S-N220KG & 30 & 45 & 125 & 90 & 55 & 110 & 220 & 220 & 260 \\
\hline
\end{tabular}

Note 1. Reversible types are also manufactured. In this case, the model name is \(\mathrm{S}-2 \times \mathrm{N} \square \mathrm{KG}\).
Note 2. Electrical durability of Class AC-4 is 100,000 operations.
Electrical durability of Class AC-3 is 1.5 mil. operations.
Note 3. Magnetic starters (combined with thermal overload relay: MSO-N \(\square K G\) ) can also be manufactured.
Note 4. DC operated types can also be manufactured.
\begin{tabular}{|c|}
\hline Model Name \\
\hline S-N125KG \\
\hline S-N220KG \\
\hline
\end{tabular}
- Operation Coil/Properties/Contact Arrangement/Outline Drawings

The above are the same as the standard product, so refer to pages 41,43 and 43 for the operation coil, properties and contact arrangements, and page 84, 86 for outline drawings.

\subsection*{9.6 SH-V \(\square\) Vacuum Magnetic Contactors \\ Large capacity vacuum magnetic contactors with excellent safety properties}

A large-capacity vacuum magnetic contactor boasting high-performance, long lifespan and maintenance-free characteristics through combination of a vacuum switch and AC operated, DC energizing solenoid. SH-V160 to V600 types are UL standard recognized and CSA standard accredited products.

\section*{- Features}


Rating/Performance


Note 1. Surge absorbers are not required for SH-V series models with motor loads of 7.5 kW or more, but should be used for motor loads of 5.5 kW or less.

\title{
Magnetic Starters/Magnetic Contactors/Contactor Relays According to Application
}

\section*{Properties}
(1) Constant Excitation Type


Note 1. The above indicates rough property indices for AC200V coils under AC operation (SH-V \(\square\) ) and for DC100V coils under DC operation (SHD-V \(\square\) ).
Note 2. The input indicates the average value. These are almost the same for coils other than AC200V or DC100V.
Note 3. The operating time is the average value with 220 V 60 Hz applied for AC operated types and DC100V applied for DC operated types.
These are almost the same for coils other than AC200V or DC100V.
(2) Mechanically Latched Type


Note 1. The above indicates rough property indices for AC200V coils under AC operation (SHL-V \(\square\) ) and for DC100V coils under DC operation (SHLD-V \(\square\) ).
Note 2. The momentary input indicates the average value. These are almost the same for coils other than AC200V or DC100V.
Note 3. The drive time is the time taken from when the closing coil or tripping coil is excited until the main contact transitions (ON or OFF) when \(220 \mathrm{~V}, 60 \mathrm{~Hz}\) is applied for AC operation or DC100V is applied for DC operation. These are almost the same for coils other than AC200V or DC100V.

\section*{Rated Operation Coil}
(1) SH-V AC Operation Coils, SHL-V Closing/Tripping Coils
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multicolumn{4}{|l|}{SH-V160, 320, 400 AC Operation Coils SH-V160, 320, 400 Closing/Tripping Coils} & \multicolumn{4}{|c|}{SH-V600 AC Operation Coil} \\
\hline Coil & \multicolumn{2}{|l|}{Rated Voltage [V]} & \multirow[t]{2}{*}{Coil Indicator} & \multirow[t]{2}{*}{Coil
Designation} & \multicolumn{2}{|l|}{Rated Voltage [V]} & \multirow[t]{2}{*}{Coil Indicator} \\
\hline Designation & 50 Hz & 60 Hz & & & 50 Hz & 60 Hz & \\
\hline AC100V & 100 to 127 & 100 to 127 & & AC100V & 100 to 127 & 100 to 127 & \\
\hline AC200V & 200 to 240 & 200 to 240 & & AC200V & 200 to 240 & 200 to 240 & Frequency \\
\hline AC300V & 260 to 350 & 260 to 350 & Rated Voltage/ & & & & \\
\hline
\end{tabular}
\begin{tabular}{l|l|l|}
\hline AC300V & 260 to 350 & 260 to 350 \\
\hline AC400V & 380 to 440 & 380 to 440 \\
\hline AC500V & 460 to 550 & 460 to 550 \\
\hline
\end{tabular}
(2) SHD-V160, 320, 400 DC Operation Coils SHLD-V160, 320, 400 Closing/Tripping Coils
\begin{tabular}{c|c|c}
\hline Coil Designation & Rated Voltage & \multirow{2}{*}{ Coil Indicator } \\
\hline DC100V & DC100 to 110V & \multirow{2}{*}{ Rated Voltage } \\
\hline DC200V & DC200 to 220 V & \\
\hline
\end{tabular}

\section*{Outline Drawings}
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multicolumn{4}{|c|}{Model Name} & Outline Drawings & Hole Drilling Dimensions & Weight [kg] \\
\hline \multirow[b]{2}{*}{} & \multicolumn{3}{|l|}{\[
\begin{aligned}
& \text { SH-V160 } \\
& \text { SH-V320 } \\
& \text { SH-V400 }
\end{aligned}
\]} &  &  & 11 \\
\hline & SH-V600 & & &  &  & 22 \\
\hline  & \[
\begin{aligned}
& \text { SHD-V160 } \\
& \text { SHD-V320 } \\
& \text { SHD-V400 }
\end{aligned}
\]
\[
\left(\begin{array}{l}
\text { A separate control unit } \\
\text { same outline drawings } \\
\text { SH-V160/V320/N400 t } \\
\text { body as per the figure }
\end{array}\right.
\] & is installed (above fig ypes is ins to the righ & with the e) as led to the \(\qquad\) & (Control Unit) & 4-M8 Screw Mounting Hole & 13 \\
\hline  & \[
\begin{aligned}
& \text { SHL-V160, SHLI } \\
& \text { SHL-V320, SHLI } \\
& \text { SHL-V400, SHLI } \\
& \\
& \hline \text { Model Name } \\
& \hline \text { SHL(D)-V160 } \\
& \hline \text { SHL(D)-V320 } \\
& \hline \text { SHL(D)-V400 } \\
& \hline
\end{aligned}
\] & \[
\begin{aligned}
& \text { D-V160 } \\
& \text { D-V320 } \\
& \text { D-V400 }
\end{aligned}
\]
\begin{tabular}{|c|}
\hline \multicolumn{2}{|c}{ Variable D } \\
\hline\(N\) \\
\hline M 8 \\
\hline M 10 \\
\hline M 10 \\
\hline
\end{tabular} & \begin{tabular}{c}
\(\frac{\text { mensions }}{\mathrm{A}}\) \\
\(\frac{10}{12.5}\) \\
\hline 12.5
\end{tabular} &  &  & 13 \\
\hline
\end{tabular}

\section*{Contact Arrangement/Connection Diagram}


Fig. 1. SH-V160, SH-V320, SH-V400, SH-V600 Types


Fig. 2. SHD-V160, SHD-V320, SHD-V400 Types


Fig. 3. SHL-V160, SHL-V320, SHL-V400 Types


Fig. 4. SHLD-V160, SHLD-V320, SHLD-V400 Types

Note. Auxiliary contact arrangements are \(2 a 2 b\) as standard but can be manufactured as \(4 a 4 b\) (broken line in figure above) upon request. (Excluding SHLD-V. SHLD-V auxiliary contact arrangement is fixed as 2a4b)

\section*{- Model Name Structure/Production Range}

- Production Range
\begin{tabular}{c|c|c|c|c|c}
\hline \multicolumn{2}{c|}{ Frame } & 160 A & 320 A & 400 A & 600 A \\
\hline Constant & AC Operated & 0 (Note 3) & 0 (Note 3) & 0 (Note 3) & 0 (Note 2) \\
\cline { 2 - 6 } \begin{tabular}{c} 
Exitation Type \\
\hline Latched \\
Type Operated \\
Type
\end{tabular} & 0 (Note 3) & 0 (Note 3) & 0 (Note 3) & - \\
\cline { 2 - 6 } & AC Operated & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & - \\
\hline
\end{tabular}

Note 1. O: Manufactured, -: Not Manufactured
Note 2. Coil designation AC100V or AC200V only can be manufactured.
Note 3. Reversible types can also be manufactured for constant excitation types with 160, 320 and 400 A frames.

\subsection*{9.7 How to Order \\ Follow the steps below when ordering. (Enter a space in \(\mathbf{\Delta}\).)}

\section*{1. DC Interface Contactors}
\begin{tabular}{|c|c|c|}
\hline Model Name & Operation Coil Designation or Control Circuit Voltage & (Note) Auxiliary Contact \\
\hline \begin{tabular}{l}
SD-Q11 \\
SD-QR12
\end{tabular} & \[
\begin{aligned}
& \mathbf{\Delta} \mathrm{DC} 24 \mathrm{~V} \\
& \mathbf{\Delta} \mathrm{DC} 24 \mathrm{~V}
\end{aligned}
\] & \\
\hline Refer to page 242. & Select the coil designation from page 244 or specify the control circuit voltage used. & \begin{tabular}{l}
Specify if using a special contact arrangement. \\
If not specified, then the standard contact arrangement will be used. Refer to page 244.
\end{tabular} \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|c|}
\hline Model Name & Motor Capacity or Heater Designation (Knob Setpoint) & Main Circuit Voltage & Operation Coil Designation or Control Circuit Voltage & (Note) Auxiliary Contact \\
\hline MSOD-Q11KP MSOD-QR12KP & \[
\begin{array}{r}
\triangle 9 \mathrm{~A} \\
\triangle 9 \mathrm{~A}
\end{array}
\] & \[
\begin{aligned}
& \Delta_{200 V}^{200 V}
\end{aligned}
\] & \[
\begin{aligned}
& \mathbf{\Delta} \text { DC24V } \\
& \mathbf{\Delta} \text { DC24V }
\end{aligned}
\] & \\
\hline Refer to page 242. & Select from page 244. & \begin{tabular}{l}
Do not apply AC voltage to the main circuit. \\
(To distinguish it from the control circuit voltage.)
\end{tabular} & Select the coil designation from page 244 or specify the control circuit voltage used. & \begin{tabular}{l}
Specify if using a special contact arrangement. \\
If not specified, then the standard contact arrangement will be used. Refer to page 244.
\end{tabular} \\
\hline
\end{tabular}
\(\square\) UQ-AX2 \(\square\) Type (Auxiliary Contact Units for DC Interface Contactors)


■ UQ-PL Type (Indicator Lamp Units for DC Interface Contactors)


\section*{2. NC Main Contact Contactors}
\begin{tabular}{|c|c|c|}
\hline Model Name & Operation Coil Designation or Control Circuit Voltage and Frequency & (Note) Main Contact \\
\hline B-T21 BD-N100 & \(\triangle \mathrm{AC} 200 \mathrm{~V}\) ADC100V & \\
\hline Refer to page 249. & Refer to pages 43, 44. & B-T21 or B-N65 type contactors are available with 1A2B and 3B main contacts. If not specified then the 1A2B contact arrangement will be used. Refer to page 249. \\
\hline
\end{tabular}

\section*{3. DC Contactors}
\begin{tabular}{|c|c|}
\hline Model Name & Operation Coil Designation or Control Circuit Voltage and Frequency \\
\hline \[
\begin{aligned}
& \text { DU-N30 } \\
& \text { DUD-N180 }
\end{aligned}
\] & \begin{tabular}{l}
- AC200V \\
- DC110V
\end{tabular} \\
\hline Refer to page 253. & Select the coil designation from the ratings on page 43 for AC coils or page 44 for DC coils, or else specify the control circuit voltage and frequency used. \\
\hline
\end{tabular}

Magnetic Starters/Magnetic Contactors/Contactor Relays According to Application

\section*{4. Magnetic Contactors For High Frequency Switching}

\section*{- S-NGKG Type}
\begin{tabular}{|c|c|c|}
\hline Model Name & Operation Coil Designation or Control Circuit Voltage and Frequency & (Note) Auxiliary Contact \\
\hline S-N125KG & \(\triangle \mathrm{AC200V}\) & - \\
\hline Refer to page 258. & Select the coil designation from page 43 or specify the control circuit voltage and frequency used. & Specify if using a special contact arrangement. Refer to page 41. \\
\hline
\end{tabular}

\section*{5. Vacuum Magnetic Contactors}
\(\square\) SH-V \(\square\), SHD-V \(\square\) Types

\(\square\) SHL-V \(\square\), SHLD-V \(\square\) Types
\begin{tabular}{|c|c|c|}
\hline Model Name & Closing Coil Designation Tripping Coil Designation & (Note) Auxiliary Contact \\
\hline SHL-V160
SHLD-V320 & \begin{tabular}{ll}
\(\mathbf{\Delta M C - A C 2 0 0 V}\) & \(\mathbf{\Delta M T - A C 2 0 0 V}\) \\
\(\mathbf{\Delta M C - D C 1 0 0 V}\) & \(\mathbf{\Delta M T}-D C 100 \mathrm{~V}\)
\end{tabular} & - \\
\hline \begin{tabular}{l}
Refer to page 259. \\
The model name is SHLD if using a DC operated closing coil.
\end{tabular} & Specify the closing (MC) and tripping (MT) operation coil designation from the ratings on page 260. & Specify only if using the 4a4b contact arrangement. If not specified then 2 a 2 b will be used. \\
\hline
\end{tabular}
Application to Domestic and International Standards
10.1 Standards Application List ..... 266
10.2 Applicable Standard ..... 267
10.3 Targeted Electrical Appliances ..... 267
10.4 MS-T/N Series Certification Standards/ CE Mark List ..... 268
10.5 UL/CSA Standards Certified Products ..... 269
10.6 Compliance with EC Directives ..... 280
10.7 TÜV Certified Products ..... 282
10.8 CCC Certified Products (China) ..... 285
10.9 KC Certified Products (South Korea) ..... 294
10.10 Selection by Global Rating ..... 295
10.11 Short-Circuit Current Rating (SCCR) UL Standards Certified Products ..... 296
10.12 Marine Certification Standard Products (NK, KR, Lloyd, BV) ..... 301
10.13 How to Order ..... 302

\section*{10 Application to Domestic and International Standards}

\subsection*{10.1 Standards Application List}

\section*{- Application to Domestic and International Standards}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline & \multicolumn{2}{|r|}{\multirow{3}{*}{Model}} & \multirow{3}{*}{Format} & \multicolumn{5}{|l|}{Compliance and Applicable Standards} & \multicolumn{4}{|l|}{Safety Certification Standards Note 5} & \multirow[t]{2}{*}{\begin{tabular}{|c|}
\hline EC \\
Directives \\
CE \\
Mark \\
\hline
\end{tabular}} & \multirow[t]{2}{*}{} & \multirow[t]{2}{*}{\(\substack{\text { Note } 5 \\ \text { ccccatifion }}\)
GB} & \multicolumn{5}{|c|}{Marine Certification Standards Note 5} & \multirow[t]{2}{*}{\begin{tabular}{l}
Heat Resistance \({ }^{\text {lves } 5}\) Cerification Standards \\
Class 2 Heat Resistant
\end{tabular}} \\
\hline \[
\begin{gathered}
\stackrel{e}{\circ} \\
\stackrel{0}{0}
\end{gathered}
\] & & & & \[
\begin{aligned}
& \text { Note } 4 \\
& \text { JIS }
\end{aligned}
\] & JEM & IEC & \[
\begin{gathered}
\text { DIN } \\
\text { VDE }
\end{gathered}
\] & \[
\begin{aligned}
& \mathrm{BS} \\
& \mathrm{EN}
\end{aligned}
\] & \[
\left.\begin{array}{|l|l|}
\hline \text { Electrical } \\
\text { Applance }
\end{array} \right\rvert\,
\] & & L & CSA & & & & NK & KR & BV & LR & CCS & \\
\hline © & & & & Japan & Japan & ntiendional & Germany & United Kingdom Europe & Japan &  & \[
\begin{aligned}
& \hline \text { JS } \\
& \mid \underset{\text { ULITED }}{ } \\
& \hline \text { UL }
\end{aligned}
\] & \[
\begin{array}{|c|}
\hline \text { Canada } \\
\text { c(ULILTED } \\
\text { LISTE }
\end{array}
\] & Europe & \[
\triangle
\] & \begin{tabular}{l}
China \\
(CCC)
\end{tabular} &  &  & \begin{tabular}{l}
France \\
馀景
\end{tabular} & \begin{tabular}{l}
United \\
Kingdom \\

\end{tabular} &  & Japan \\
\hline \multicolumn{2}{|r|}{\multirow{4}{*}{Magnetic Contactors}} & Non-Reversing & S-T10 to T100 & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & ( \()\) & ( \()\) & \(\bigcirc\) & ( \()\) & ( & ( & ( & ( \()\) & ( \()\) & - & is \\
\hline & & Reversing & S-2xT10 to T100 & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & Note 7 & Note 7 & \(\bigcirc\) & - & () & - & - & - & - & - & i \\
\hline & & DC Operated & SD-T12 to T100 & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & ( \()\) & (0) & \(\bigcirc\) & ( \()\) & () & ( \()\) & - & (0) & ( \()\) & \(\bigcirc\) & - \\
\hline & & Mechanically Lathed Type & SL(D)-T21 to T100 & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & \# & \# & - & - & () & - & - & - & - & - & \# \\
\hline \multicolumn{2}{|r|}{\multirow{6}{*}{Open Type Magnetic Starters}} & Non-Reversing 2-Element & MSO-T10 to T100 & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & - & - & - & - & - & - & - & - & - \\
\hline & & NonRevessing3-Elenent 2 2. & MSO-T10KP to T100KP & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & \(\bigcirc\) & - & () & - & - & - & - & - & - \\
\hline & & Reversing 2-Element & MSO-2xT10 to T100 & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & - & - & - & - & - & - & - & - & - \\
\hline & & Reversing 3-Element (2E) & MSO-2xT10KP to T100KP & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & \(\bigcirc\) & - & (0) & - & - & - & - & - & - \\
\hline & & OCO Opateed Type2-Eenener & MSOD-T12 to T100 & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & - & - & - & - & - & - & - & - & - \\
\hline \[
\stackrel{\circ}{\stackrel{\circ}{\partial}}
\] & &  & MSOD-T12KP to T100KP & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & \(\bigcirc\) & - & () & - & - & - & - & - & - \\
\hline \[
\stackrel{\infty}{\infty} \stackrel{+}{\bullet}
\] & \multirow[t]{2}{*}{\begin{tabular}{l}
Enclosed \\
Magnetic Starters
\end{tabular}} & Non-Reversing 2-Element & MS-T10 to T100 & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & - & - & - & - & - & - & - & - & - & - & - & - \\
\hline \[
\frac{\overline{5}}{\bar{n}}
\] & & Nor-Pevesing3-Elenent 2 2. & MS-T10KP to T100KP & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & - & - & - & - & - & - & - & - & - & - & - & - \\
\hline \multicolumn{2}{|l|}{\multirow[t]{3}{*}{Thermal Overload Relays}} & 2-Element & TH-T18 to T100 & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & - & - & - & * & * & - & - & - & - \\
\hline & & \multirow[b]{2}{*}{3-Element (2E)} & TH-T18KP to T50KP & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & ( ) & () & \(\bigcirc\) & ( \()\) & © & * & * & () & () & - & - \\
\hline & & & TH-T65KP to T100KP & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & ( \()\) & (0) & \(\bigcirc\) & ( \()\) & () & * & * & () & () & \(\bigcirc\) & - \\
\hline \multicolumn{2}{|r|}{\multirow[b]{3}{*}{Contactor Relays}} & AC Operated & SR-T5/T9 & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & Note 7 & Note 7 & \(\bigcirc\) & ( \()\) & () & * & * & (0) & ( \()\) & - & H \\
\hline & & DC Operated & SRD-T5/T9 & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & Note 7 & Note 7 & \(\bigcirc\) & ( \()\) & () & * & * & ( \()\) & ( \()\) & - & - \\
\hline & & Mechanicall Latched Type & SRL(D)-T5 & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & - & - & () & - & - & - & - & - & H \\
\hline \multicolumn{2}{|r|}{\multirow{3}{*}{Optional Units}} & Additiona Auxiliay Cortact & UT-AX2, 4, 11 & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & Note 7 & - & - & \(\bigcirc\) & () & ( ) & * & * & ( \()\) & O & \(\bigcirc\) & - \\
\hline & & Surge Absorber & UT-SA13 to 25 & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & ( 0 & - & - & - & - & * & * & * & - & - & - & - \\
\hline & & Mechanical Interlock & UT-ML20 & \(\bigcirc\) & - & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & ( ) & - & - & \(\bigcirc\) & - & * & * & * & - & - & - & - \\
\hline \multirow[t]{2}{*}{} & \multirow[t]{2}{*}{NC Main Contact Type} & AC Operated & B-T & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & - & - & O & - & - & - & - & - & - \\
\hline & & DC Operated & BD-T & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & - & - & () & - & - & - & - & - & - \\
\hline \multicolumn{2}{|r|}{\multirow[t]{4}{*}{Magnetic Contactors}} & Non-Reversing & S-N125 to N400 & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & (0) & (0) & (0) & \(\bigcirc\) & () & () & ( \()\) & (0) & (0) & () & \(\bigcirc\) & \% \\
\hline & & Reversing & S-2xN125 to N400 & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & ( \()\) & ( \()\) & ( \()\) & \(\bigcirc\) & - & () & - & - & - & - & - & M \\
\hline & & DC Operated & SD-N125 to N400 & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & () & (0) & () & \(\bigcirc\) & (0) & () & () & - & (0) & (0) & \(\bigcirc\) & - \\
\hline & & Mechanicall Latched Type & SL-N125 to N400 & \(\bigcirc\) & 0 & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & H & - & - & - & - & () & \# & - & - & - & - & 3 \\
\hline \multicolumn{2}{|l|}{\multirow[b]{6}{*}{\begin{tabular}{l}
Open Type \\
\(\stackrel{2}{\infty}\) Magnetic \\
Starters
\end{tabular}}} & Non-Reversing 2-Element & MSO-N125 to N400 & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & - & - & - & - & - & - & - & - & - \\
\hline & & Non-Pevesing3-Ement (2E) & MSO-N125KP to N400KP & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & ( \()\) & (0) & (0) & \(\bigcirc\) & - & (0) & - & - & (0) & () & - & - \\
\hline & & Reversing 2-Element & MSO-2xN125 to N400 & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & - & - & - & - & - & - & ( & - & - \\
\hline & & Reversing 3-Element (2E) & MSO-2xN125KP to N400KP & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & H & H & H & \(\bigcirc\) & - & () & - & - & - & - & - & - \\
\hline & & OCO Opatated Type2-Emenert & MSOD-N125 to N400 & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & - & - & - & - & - & (0) & () & - & - \\
\hline & & CCOpatased Tpees:Emanti2E & MSOD-N125KP to N400KP & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & \(\bigcirc\) & - & ( \()\) & - & - & O & O & - & - \\
\hline \multicolumn{2}{|l|}{\multirow[t]{2}{*}{\[
\begin{array}{|l|}
\hline \text { Enclosed } \\
\text { Magnetic Starters } \\
\hline
\end{array}
\]}} & Non-Reversing 2-Element & MS-N125 to N400 & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & - & - & - & - & - & - & - & - & - \\
\hline & & Nor-Revesing3-Elenent 2 2] & MS-N125KP to N400KP & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & - & - & () & - & - & - & - & - & - \\
\hline \multicolumn{2}{|r|}{\multirow[t]{2}{*}{Themal Overload Relays}} & Standard 2-Element & TH-N120 to N400 & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & - & - & - & * & * & - & - & - & - \\
\hline & & 3-Element (2E) & TH-N120KP to N400KP & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & 0 & * & - & (0) & (0) & \(\bigcirc\) & ( 0 & (0) & * & * & (0) & (0) & \(\bigcirc\) & - \\
\hline \multicolumn{2}{|r|}{\multirow{3}{*}{Optional Units}} & Additiona Auxiliay Cortact & UN-AX2, 4, 11/80, 150 & \(\bigcirc\) & \(\bigcirc\) & 0 & \(\bigcirc\) & \(\bigcirc\) & * & (0) & - & - & \(\bigcirc\) & ( ) & \(\bigcirc\) & * & * & ( \()\) & (0) & \(\bigcirc\) & - \\
\hline & & Surge Absorber & UN-SA & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & ( \()\) & - & - & - & - & * & * & * & - & - & - & - \\
\hline & & Mechanical Interlock & UN-ML & \(\bigcirc\) & \(\bigcirc\) & 0 & \(\bigcirc\) & \(\bigcirc\) & * & ( 0 & - & - & * & - & * & * & * & - & - & - & - \\
\hline \multicolumn{2}{|l|}{\multirow[t]{6}{*}{}} & Non-Reversing & SD-Q & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & () & ( & ( & \(\bigcirc\) & ( & () & - & - & - & - & - & - \\
\hline & & Reversing & SD-QR & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & (0) & (0) & (0) & \(\bigcirc\) & (0) & () & - & - & - & - & - & - \\
\hline & & Non-Reversing & DU(D)-N & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & - & - & \(\bigcirc\) & - & - & - & - & - & - \\
\hline & & Reversing & DU(D)-2XN & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & - & - & \(\bigcirc\) & - & - & - & - & - & - \\
\hline & & AC Operated & B-N & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & - & - & \(\bigcirc\) & - & - & - & - & - & - \\
\hline & & DC Operated & BD-N & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & * & - & - & - & - & - & \(\bigcirc\) & - & - & - & - & - & - \\
\hline \multicolumn{4}{|c|}{Reference Page} & & & & & & 267 & & 69 & \[
\begin{aligned}
& 269 \\
& 270 \\
& 275 \\
& \hline
\end{aligned}
\] & 280 & 282 & 285 & 301 & 301 & 301 & 301 & & \\
\hline \multicolumn{3}{|r|}{\multirow[t]{3}{*}{Product Marking
\(\square\) is displayed on the product)}} & Standard Number & & & & & & & & & & & & & & & & & & \\
\hline & & & Certification Mark & & & & & & & Note 2 & Note 2 & & Note 3 & Note 2 & Note 2 & & & & & & \\
\hline & & & Certification Number & & & & & & & & & & & & & & & & & & \\
\hline
\end{tabular}

Note 1. O: Complies or conforms as standard product \(\bigcirc\) : Certified (add "CN" at the end of the model name when ordering)

\section*{©: Standard product and certified \(\diamond\) : Certification (pending) scheduled model}
\(\grave{\aleph}\) : Dedicated product and certified \(\quad *\) : Standard certification non-applicable model
Note 2. Refer to page 268 for details regarding the standard certification marks and product model names. Consult us with any questions. Note 3. Mark display by self-declaration rather than certification standard
Note 4. If JIS conformity declaration is required, make a request.
Note 5. For the MS-T series with its standard terminal cover removed, safety certification standards (UL certification, CSA certification), third-party certification standards, CCC certification, marine certification standards, and heat resistance certification standards are not valid.
Note 6. For information on MMP-T32 motor circuit breakers that meet domestic and international standards, refer to chapter 12.
Note 7. S(D)- \(2 \times\) T32, SR(D)-T9, and UT-AX2, 4 are not UL-certified. The other models are certified as standard.

\section*{10．2 Applicable Standard}

\section*{National Standards（Compliance，Regulatory Compliance and Model Names）}
\begin{tabular}{c|c|c|c}
\hline Type & Model Name & Standards & \multirow{3}{c}{ Application } \\
\hline Magnetic Starters & MS－T／N，MSO－T／N & & \\
\cline { 1 - 2 } Magnetic Contactors & S－T／N，SD－T／N & \multirow{2}{*}{ JIS C8201－4－1 } & \multirow{2}{*}{ Applicable with standard products } \\
\cline { 1 - 2 } Thermal Overload Relays & TH－T／N & & \\
\hline Contactor Relays & SR－T／K & JIS C8201－5－1 & \\
\hline
\end{tabular}

International Standards（Standards and Conformance Methods）
\begin{tabular}{|c|c|c|c|c|c|}
\hline Model & NEMA Standards & IEC Standards & EN Standards & BS Standards & VDE Standards \\
\hline Magnetic Contactor S－T／N & Applicable with standard products．（ 600 V or less） The selection is outlined below． （However，since the applicable capacity is slightly different from the size，select from the UL／CSA ceritified product page．） & \multicolumn{2}{|l|}{Applicable with standard product （690 V or less）} & \multicolumn{2}{|l|}{\[
\begin{aligned}
& \text { IEC 60947-4-1 } \\
& \text { EN 60947-4-1 } \\
& \text { BS EN 6094-4-1 } \\
& \text { DIN EN 60947-4-1(VDE 0660-102) }
\end{aligned}
\]} \\
\hline Thermal Overload Relay TH－T／N Note 1 & Applicable with the standard selection & \multicolumn{4}{|l|}{\[
\begin{aligned}
& \text { IEC 60947-4-1 } \\
& \text { EN 60947-4-1 } \\
& \text { BS EN 60947-4-1 } \\
& \text { DIN EN 60947-4-1(VDE 0660-102) } \\
& \hline
\end{aligned}
\]} \\
\hline Contactor Relay SR－T & Standard products are compliant with A600 and Q300 & \multicolumn{4}{|l|}{\begin{tabular}{|ll} 
Applicable with classes AC－15 and DC－13 & IEC 60947－5－1 \\
The rated current is the same as the standard \\
EN 60947－5－1 \\
（see page 160） & \\
\hline
\end{tabular}} \\
\hline
\end{tabular}

Note 1．Apply the 2－element thermal overload relay to single－phase（1 \(\varphi\) ），and 3－element（3 \(\varphi\) ）load to three－phase．

\section*{10．3 Electrical Appliances and Materials Safety Act}

In the law，enclosed magnetic starters and motor circuit breakers are items other than the specific electrical appliances．
The manufacturer is obliged to register the business，self－validate compliance，and display the PS－E mark on the products． The applicable enclosed magnetic starters are shown in Table 1，and the applicable motor circuit breakers in Table 2.
Table 1．Enclosed Magnetic Starter
Circuit Three－Phase 200 to 220 V
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline Circuit & & & & & Three－Phase & 200 to 220 V & & & & \\
\hline Model Name & MS－ & \(\square\)（Thermal O & verload Relay & with 2 Elem & nts） & MS－ & KP（Thermal & Overload Re & ay with 3 Ele & ments） \\
\hline \begin{tabular}{l}
Capacity［kW］ \\
Model Name
\end{tabular} & 0.75 or Less & Over 0.75 and 2.2 or Less & \begin{tabular}{l}
Over 2.2 and \\
3.7 or Less
\end{tabular} & Over 3.7 and 7.5 or Less & Over 7.5 and 12 or Less & 0.75 or Less & Over 0.75 and 2.2 or Less & Over 2.2 and 3.7 or Less & Over 3.7 and 7.5 or Less & Over 7.5 and 12 or Less \\
\hline MS－T10 & （5） & （Ts） & － & － & － & （T8） & （19） & － & － & － \\
\hline MS－T12 & （P） & （䧕） & （ses） 2.7 kW or Less） & － & － & （P） & （限） & （res）（2．7 kW or Less） & － & － \\
\hline MS－T21 & （09） & （Ts） & （ \({ }_{\text {Ps }}\) & － & － & （ \({ }_{\text {P }}\) & （ \({ }_{\text {P }}\) & （ \({ }_{\text {PS }}\) & － & － \\
\hline MS－T35 & （阿） & （ \({ }_{\text {P }}\) & （18） & （T8） & － & （ \({ }_{\text {¢ }}\) & （ \({ }_{\text {P }}\) & （19） & （\％） & － \\
\hline MS－T50 & － & － & （9） & （\％） & （Ts） & － & － & （Ts） & （9） & （19） \\
\hline MS－T65 & － & － & （Ts） & （Ts） & （5） & － & － & （Ts） & （ \({ }_{\text {cis }}\) & （15） \\
\hline MS－T80 & － & － & （19） & （Ts） & （TE） & － & － & （T） & （19） & （T） \\
\hline MS－T100 & － & － & （Ts） & （\％） & （T） & － & － & （T8） & （19） & （Ts） \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|c|}
\hline \multirow[t]{3}{*}{} & \multicolumn{4}{|c|}{Single－Phase 100 to 110 V} \\
\hline & \multicolumn{4}{|l|}{MS－\(\square\) DP（Thermal Overload Relay with 2 Elements）} \\
\hline & 0.2 or Less & Over 0.2 and 0.4 or Less & Over 0.4 and 0.75 or Less & Over 0.75 and 1.5 or Less \\
\hline MS－T10DP & （Ts） & （ \({ }_{\text {P }}\) & － & － \\
\hline MS－T12DP & （TE） & （TE） & － & － \\
\hline MS－T21DP & （Ts） & （T5） & （78） & － \\
\hline MS－T35DP & － & － & （T8） & （P） \\
\hline
\end{tabular}

Table 2．Motor Circuit Breakers
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{\multirow[t]{3}{*}{Circuit}} & \multicolumn{4}{|c|}{Single－Phase 200 to 220 V} \\
\hline & & 0.75 or Less & Over 0.75 and 3.7 or Less & \multicolumn{2}{|r|}{Over 3.7} \\
\hline & & \multicolumn{3}{|c|}{30 or Less} & 30 or More \\
\hline \multirow{4}{*}{MMP－T32} & 0.75 to 4A & （\％） & － & － & － \\
\hline & 6.3 to 18A & － & （8） & － & － \\
\hline & 25A & － & － & （8） & － \\
\hline & 32A & － & － & － & （8） \\
\hline
\end{tabular}

Note 1．The single－phase reversible type and 200 V class cannot be manufactured．
 displayed on the product＂，whereas＂－＂indicates that there is no product with the targeted capacity．

\section*{Application to Domestic and International Standards}

\subsection*{10.4 MS-T/N series Certification Standards/CE Mark List}



Note 1. ©: CE Mark (Self-Declaration) = Standard Product and Displayed on the Product, UL Standards/CSA Standards, TÜV Certification, CCC Certification = Standard Product with Certification Mark Displayed NK Standards = Standard Product with Certification Number Displayed
O: Certified with the certification mark. Always add "CN" at the end of the model name to specify when ordering. The certification mark is affixed to the product or displayed on the product.
O: Standard product with no certification or certification mark.
\(\hat{\aleph}\) : Dedicated product with certification and certification mark. Add "UL" (listing) or "UR" (recognition) at the end of the model name to specify when ordering
-: Standard certification non-applicable model or no schedule for acquisition.
Note 2. The SA specification (the model name is \(\square-\square S A\) for magnetic contactors and contactor relays) is equipped with a surge absorber and has been certified.
Note 3. For the applicable rating, see individual standard documents.
Note 4. Excluding the SQ specification.

\subsection*{10.5 UL/CSA Standards Certified Products}

The MS-T/MS-N series magnetic contactors and thermal overload relays have acquired the certification of the United States UL Standards and Canada CSA Standards, making them optimal for export to North America.
The UL/CSA certification status of this product can be verified by entering and searching for the UL file number in the "UL Product iQ \({ }^{\text {TM }}\) in the UL online site of Underwriters Laboratories, Inc.

\section*{UL Standards (Underwriter's Laboratories) United States Safety Standards}

UL is an institution of the United States that has established the UL standards as safety standards, conducts safety confirmation tests based on the UL standards, issues certificates for certified products and recognizes certification marks.
The UL certification mark is widely used throughout the United States. UL certification is mandated depending on the state and city, and therefore required when exporting devices, control panels and equipment to the United States.
The MS-T/N series complies with the Controller UL Standards and has acquired the UL Component Certification (recognition) or UL Product Certification (listing), and can be incorporated in control panels, equipment or the like for export to the United States.
\(\boldsymbol{\square}{ }^{\circledR}\) : UL Recognition
This product is referred to as component certified, and is intended to be incorporated into other products and equipment. In other words, for incorporation into control panels, machine tools, control devices or the like, a component certified product can be used.
UL Listing
This product is referred to as product certified, allowing direct sales to final consumers and use by final consumers. It can also be used for incorporation into control panels, machine tools, control devices or the like. As there are models whose outline drawings and terminal structure differ from standard products, refer to the UL/CSA safety standards certified product catalog for more information.

\section*{CSA Standards (Canadian Standard Association) Canadian Standards}

The CSA standards are product safety standards that have been established by the CSA (Canadian Standard Association). In Canada, the safety of electrical products has been prescribed by state laws, some of which require that the product be CSA standards certified. Therefore, the CSA standards certification is required when exporting devices, control panels, equipment and the like to Canada.
The MS-T/N series has acquired the CSA standards certification given by the UL testing organization and can be incorporated into control panels, equipment or the like for export to Canada. In addition, UL has been recognized by SCC (Standards Council of Canada) as a testing, certification and quality certification body, and CSA standards certified products as determined by UL are recognized by the safety regulations of all Canadian provinces.

네 : Recognition for Canada
CSA standards component certification by the UL testing organization.
-(1):Listing for Canada
Listed CSA standards product certification by the UL testing organization.

For the UL/CSA standards compliant certified products, the following certification marks have been recognized. (As usual, separate marks for the United States and Canada are also recognized.)
 UL/CSA standards component certification by the UL testing organization
-(U) us:Listing for both United States and Canada
Listed UL/CSA standards product certification by the UL testing organization

\section*{Application to Domestic and International Standards}

\subsection*{10.5.1 UL/CSA Certified Model List \\ Magnetic Contactors/Starters \\ T Series: UL60947-4-1, CSA C22.2 No.60947-4-1 \\ N Series: UL508, CSA C22.2 No. 14}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Frame Size} & \multicolumn{4}{|l|}{AC Operated Magnetic Contactors} & \multicolumn{2}{|l|}{DC Operated Magnetic Contactors} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{\begin{tabular}{l}
Mechanically Latched Contactors \\
Non-Reversing (SL, SLD-)
\end{tabular}}} & \multicolumn{2}{|l|}{AC Operated Magnetic Starters (Open Type)} \\
\hline & \multicolumn{2}{|l|}{Non-Reversing (S-)} & \multicolumn{2}{|r|}{Reversing
(S-2x)} & Non-Reversing (SD-) & Reversing (SD-2x) & & & Non-Reversing (MSO- \(\square K P\) ) & Reversing (MSO-2x \(\square K P\) ) \\
\hline & \(\mathrm{c} \mathrm{T}_{\mathrm{us}}^{®}\) & c! (UT)us & \[
c \div \|_{u s}^{®}
\] & c(iL) us & c!し) us & \[
\text { CUL Us }_{\text {ISTED }}
\] & \[
c=\|_{u s}^{®}
\] & \[
\text { c } \underbrace{\text { US }}_{\text {UISTED }}
\] & c (UL) US & (UL) us \\
\hline T10 & - & ( ) & - & ( \()\) & - & - & - & - & (4) & (4) (Note 1) \\
\hline T12 & - & ( & - & ( & ( & ( & - & - & (4) & (4) (Note 1) \\
\hline T20 & - & ( & - & ( \()\) & ( \()\) & ( \()\) & - & - & (4) & (4) (Note 1) \\
\hline T21 & - & ( & - & (0) & ( ) & ( & - & (3) & (4) & (4) (Note 1) \\
\hline T25 & - & O & - & O & - & - & - & - & (4) & (4) (Note 1) \\
\hline T32 & - & ( & - & - & ( & - & - & - & - & - \\
\hline T35 & - & ( & - & ( & ( & ( & - & (3) & (4) & (4) (Note 1) \\
\hline T50 & - & ( & - & (0) & ( \()\) & ( & - & (3) & (4) & (4) (Note 1) \\
\hline T65 & - & ( & - & (0) & (0) & (0) & - & (3) & (4) & (4) (Note 1) \\
\hline T80 & - & () & - & (0) & (0) & (0) & - & (3) & (4) & (4) (Note 1) \\
\hline T100 & - & ( \()\) & - & (0) & (0) & (0) & - & (3) & (4) & (4) (Note 1) \\
\hline N125 & \multicolumn{2}{|c|}{O(Note 2)} & \multicolumn{2}{|c|}{O(Note 2)} & ( & (0) & (1) & - & O(Note 2) & -(Note 1)(Note 2) \\
\hline N150 & \multicolumn{2}{|c|}{O(Note 2)} & \multicolumn{2}{|r|}{\(\bigcirc\) (Note 2)} & ( \()\) & ( \()\) & (1) & - & O(Note 2) & -(Note 1)(Note 2) \\
\hline N180 & \multicolumn{2}{|c|}{O(Note 2)} & \multicolumn{2}{|r|}{O(Note 2)} & - & - & - & - & O(Note 2) & -(Note 1)(Note 2) \\
\hline N220 & \multicolumn{2}{|c|}{O(Note 2)} & \multicolumn{2}{|c|}{\(\bigcirc\) (Note 2)} & ( & ( & (1) & - & O(Note 2) & -(Note 1)(Note 2) \\
\hline N300 & \multicolumn{2}{|c|}{\(\bigcirc\) (Note 2)} & \multicolumn{2}{|r|}{\(\bigcirc\) (Note 2)} & ( & ( & (1) & - & \(\bigcirc\) (Note 2) & -(Note 1)(Note 2) \\
\hline N400 & \multicolumn{2}{|c|}{\(\bigcirc\) (Note 2)} & \multicolumn{2}{|r|}{O(Note 2)} & ( & (0) & (1) & - & \(\bigcirc\) (Note 2) & -(Note 1)(Note 2) \\
\hline N600 & ( & - & ( & - & - & - & - & - & - & - \\
\hline N800 & (2) & - & - & - & - & - & - & - & - & - \\
\hline
\end{tabular}

, (W)w: UL/CSA Product Certification (Listing)
© : Standard Product and Certified
- : Dedicated Product (MSO-2xN■KPCS) and Certified (no model name on the product)
(1): Dedicated Product (SL(D)-NDUR) and Certified
(2): Dedicated Product (S-N800UR) and Certified
(3): Dedicated Product (SL(D)-T■UL) and Certified
(4): It is possible to meet the UL standards since the products are composed of UL/CSA listed S-T \(\square\) magnetic contactors and TH-T \(\square K P\) thermal overload relays.

Note 1. To meet the UL standards, replace control circuit wires of MSO- \(2 \times\) T \(\square K P / M S O-2 \times N \square K P\) types with UL listed wires and main circuit connection wires and conductors with UL listed products.
Note 2. As there are also certified products with solderless terminal structure, order with "UL" added at the end of the model name if the product requires solderless terminal structure.

\subsection*{10.5.2 UL Standards Certified Products}
(1) AC Operating Magnetic Contactor (Non-Reversing) T Series (Certification Standard UL60947-4-1) © (4) ust (File No. E58968)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline Model & \multicolumn{6}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{Rated Energizing Current [A]} & \multicolumn{2}{|c|}{\multirow[b]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline Magnetic & \multicolumn{2}{|l|}{Single-Phase (Non Reversible Type)} & \multicolumn{4}{|c|}{Three-Phase} & & & & \\
\hline Contactors & 110 to 120 V & 220 to 240 V & 200 V & 220 to 240 V & 440 to 480 V & 550 to 600 V & & \multicolumn{2}{|c|}{Rating} & \\
\hline S-T10(BC)(SA) & \(\frac{1}{2}\) & \(1 \frac{1}{2}\) & 3 & 3 & 5 & 5 & 13 & \multirow{11}{*}{\begin{tabular}{l}
A600 \\
AC600 V max \\
Making 7200 VA \\
Breaking 720 VA
\end{tabular}} & \multirow{11}{*}{\begin{tabular}{l}
Q300 \\
DC250 V max \\
Making 69 VA \\
Breaking 69 VA
\end{tabular}} & \multirow{11}{*}{The standard product is certified with © ULTEUS} \\
\hline S-T12(BC)(SA)(SQ) & \(\frac{1}{2}\) & \(1 \frac{1}{2}\) & 3 & 3 & \(7 \frac{1}{2}\) & \(7 \frac{1}{2}\) & 20 & & & \\
\hline S-T20(BC)(SA)(SQ & 1 & 2 & 3 & 5 & \(7 \frac{1}{2}\) & \(7 \frac{1}{2}\) & 20 & & & \\
\hline S-T21(BC)(SA) & 1 & 3 & 5 & 5 & 10 & 10 & 30 & & & \\
\hline S-T25(BC)(SA) & 2 & 3 & \(7 \frac{1}{2}\) & \(7 \frac{1}{2}\) & 15 & 15 & 30 & & & \\
\hline S-T32(BC)(SA) & 2 & 5 & 10 & 10 & 20 & 15 & 32.5 & & & \\
\hline S-T35(BC)(SA) & 2 & 5 & 10 & 10 & 20 & 20 & 40 & & & \\
\hline S-T50(BC)(SA) & 3 & \(7 \frac{1}{2}\) & 15 & 15 & 30 & 30 & 65 & & & \\
\hline S-T65(CW) & 3 & 10 & 15 & 20 & 40 & 40 & 95 & & & \\
\hline S-T80(CW) & 5 & 15 & 20 & 25 & 50 & 50 & 100 & & & \\
\hline S-T100 & \(7 \frac{1}{2}\) & 15 & 25 & 30 & 60 & 60 & 100 & & & \\
\hline
\end{tabular}
(2) AC Operating Magnetic Contactor (Non-Reversing) N Series (Certification Standard UL508)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline Model & \multicolumn{6}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{\[
\begin{array}{|c|}
\hline \text { Rated Energizing } \\
\text { Current } \\
{[A]} \\
\hline
\end{array}
\]} & \multicolumn{2}{|c|}{\multirow[t]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline Magnetic & \multicolumn{2}{|l|}{Single-Phase (Non Reversible Type)} & \multicolumn{4}{|c|}{Three-Phase} & & & & \\
\hline Contactors & 110 to 120 V & 220 to 240 V & 200 V & 220 to 240 V & 440 to 480 V & 550 to 600 V & & \multicolumn{2}{|c|}{Rating} & \\
\hline S-N125 & 10 & 20 & 40 & 40 & 75 & 75 & 125 & \multirow{8}{*}{\begin{tabular}{l}
A600 \\
AC600 V max \\
Making 7200 VA \\
Breaking 720 VA
\end{tabular}} & \multirow{8}{*}{\begin{tabular}{l}
R300 \\
DC250 V max \\
Making 28 VA \\
Breaking 28 VA
\end{tabular}} & \multirow{6}{*}{The standard product is certified with} \\
\hline S-N150 & 15 & 25 & 40 & 50 & 100 & 100 & 150 & & & \\
\hline S-N180 & 15 & 30 & 60 & 60 & 125 & 125 & 220 & & & \\
\hline S-N220 & 15 & 40 & 60 & 75 & 150 & 150 & 220 & & & \\
\hline S-N300 & 50 & 100 & 100 & 100 & 200 & 200 & 300 & & & \\
\hline S-N400 & 50 & 150 & 125 & 150 & 300 & 300 & 400 & & & \\
\hline S-N600 & - & - & 150 & 200 & 400 & 400 & 680 & & &  \\
\hline S-N800UR & - & - & 250 & 300 & 600 & 600 & 910 & & & Dedicated product and \({ }_{\mathbf{c}} \boldsymbol{\wedge}_{\mathrm{I}_{\mathrm{us}}^{\text {certified. }} \text {. }}\) \\
\hline
\end{tabular}

Note 1. 125 A to 400 A frames with "UL" at the end of the model name are \({ }^{\circ} \mathrm{UL}_{\text {us }}\) certified for solderless terminal structure.
(3) AC Operating Magnetic Contactor (Reversing) T Series (Certification Standard UL60947-4-1)
(2)w(File No. E58968)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline Model & \multicolumn{4}{|c|}{\multirow[t]{2}{*}{\[
\begin{gathered}
\hline \text { Rated Capacity [HP] } \\
\hline \text { Three-Phase } \\
\hline
\end{gathered}
\]}} & \multirow[t]{3}{*}{\begin{tabular}{l}
Rated
Energizing Current \\
[A]
\end{tabular}} & \multicolumn{2}{|c|}{\multirow[t]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline Magnetic Contactors & & & & & & & & \\
\hline S-2xT10(BC)(SA) & 200 V & \(\frac{220 \text { to } 240 \mathrm{~V}}{3}\) & \(\frac{440 \text { to } 480 \mathrm{~V}}{5}\) & \(\frac{550 ~ t o ~}{600 \mathrm{~V}}\) & & \multicolumn{2}{|c|}{Rating} & \\
\hline S-2×T12(BC)(SA) & 3 & 3 & \(7 \frac{1}{2}\) & \(7 \frac{1}{2}\) & 20 & \multirow{9}{*}{\begin{tabular}{l}
A600 \\
AC600 V max \\
Making 7200 VA \\
Breaking 720 VA
\end{tabular}} & \multirow{9}{*}{\begin{tabular}{l}
Q300 \\
DC250 V max \\
Making 69 VA \\
Breaking 69 VA
\end{tabular}} & \multirow{9}{*}{\begin{tabular}{l}
The standard product is \\

\end{tabular}} \\
\hline S-2xT20(BC)(SA) & 3 & 5 & \(7 \frac{1}{2}\) & \(7 \frac{1}{2}\) & 20 & & & \\
\hline S-2xT21(BC)(SA) & 5 & 5 & 10 & 10 & 30 & & & \\
\hline S-2xT25(BC)(SA) & \(7 \frac{1}{2}\) & \(7 \frac{1}{2}\) & 15 & 15 & 30 & & & \\
\hline S-2xT35(BC)(SA) & 10 & 10 & 20 & 20 & 40 & & & \\
\hline S-2xT50(BC)(SA) & 15 & 15 & 30 & 30 & 65 & & & \\
\hline S-2xT65(CW) & 15 & 20 & 40 & 40 & 95 & & & \\
\hline S-2xT80(CW) & 20 & 25 & 50 & 50 & 100 & & & \\
\hline S-2xT100 & 25 & 30 & 60 & 60 & 100 & & & \\
\hline
\end{tabular}
(4) AC Operating Magnetic Contactor (Reversing) N Series (Certification Standard UL508)
(1Lus(File No. E58968)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline Model & \multicolumn{4}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{Rated
Energizing Current
\([A]\)} & \multicolumn{2}{|r|}{\multirow[t]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline \multirow[t]{2}{*}{Magnetic Contactors} & & Thre & hase & & & & & \\
\hline & 200 V & 220 to 240 V & 440 to 480 V & 550 to 600 V & & \multicolumn{2}{|c|}{Rating} & \\
\hline S-2xN125 & 40 & 40 & 75 & 75 & 125 & \multirow{7}{*}{\begin{tabular}{l}
A600 \\
AC600 V max \\
Making 7200 VA \\
Breaking 720 VA
\end{tabular}} & \multirow{7}{*}{\begin{tabular}{l}
R300 \\
DC250 V max \\
Making 28 VA \\
Breaking 28 VA
\end{tabular}} & \multirow{6}{*}{The magnetic contactor is certified as a \({ }_{\text {c }}^{\text {LISTET }}\) Us standard product.} \\
\hline S-2xN150 & 40 & 50 & 100 & 100 & 150 & & & \\
\hline S-2xN180 & 60 & 60 & 125 & 125 & 220 & & & \\
\hline S-2xN220 & 60 & 75 & 150 & 150 & 220 & & & \\
\hline S-2xN300 & 100 & 100 & 200 & 200 & 300 & & & \\
\hline S-2xN400 & 125 & 150 & 300 & 300 & 400 & & & \\
\hline S-2xN600 & 150 & 200 & 400 & 400 & 680 & & & Standard products are applicable to \({ }_{c} \boldsymbol{\chi}^{\text {us }}\). \\
\hline
\end{tabular}

\footnotetext{
Note 1. 125 A to 400 A frames with "UL" at the end of the model name are \({ }_{\mathrm{c}} \mathrm{UL}_{\mathrm{L}}\) us certified for solderless terminal structure.
}

\section*{Application to Domestic and International Standards}
(5) DC Operated Magnetic Contactor (Non-Reversing/Reversing) T Series (Certification Standard UL60947-4-1)
(Ul) us(File No. E58968)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Model} & \multicolumn{6}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{Rated Energizing Current [A]} & \multicolumn{2}{|r|}{\multirow[b]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline \multirow[b]{2}{*}{Non-Reversing} & \multirow[t]{2}{*}{Reversing (2)} & \multicolumn{2}{|l|}{Single-Phase (Non Reversible Type)} & \multicolumn{4}{|c|}{Three-Phase} & & & & \\
\hline & & 110 to 120 V & 220 to 240 V & 200 V & 220 to 240 V & 440 to 480 V & 550 to 600 V & & & & \\
\hline SD-T12(BC)(SA)(SQ) & SD-2×T12(BC)(SA) & \(\frac{1}{2}\) & \(1 \frac{1}{2}\) & 3 & 3 & \(7 \frac{1}{2}\) & \(7 \frac{1}{2}\) & 20 & \multirow{9}{*}{\begin{tabular}{l}
A600 \\
AC600 V max \\
Making 7200 VA \\
Breaking 720 VA
\end{tabular}} & \multirow{9}{*}{\begin{tabular}{l}
Q300 \\
DC250 V max \\
Making 69 VA \\
Breaking 69 VA
\end{tabular}} & \multirow{9}{*}{The standard product is certified with \({ }_{\text {CULLUS }}^{\text {LISTE }}\).} \\
\hline SD-T20(BC)(SA)(SQ) & SD-2×T20(BC)(SA) & 1 & 2 & 3 & 5 & \(7 \frac{1}{2}\) & \(7 \frac{1}{2}\) & 20 & & & \\
\hline SD-T21(BC)(SA) & SD-2xT21(BC)(SA) & 1 & 3 & 5 & 5 & 10 & 10 & 30 & & & \\
\hline SD-T32(BC)(SA) & - & 2 & 5 & 10 & 10 & 20 & 15 & 32.5 & & & \\
\hline SD-T35(BC)(SA) & SD-2xT35(BC)(SA) & 2 & 5 & 10 & 10 & 20 & 20 & 40 & & & \\
\hline SD-T50(BC)(SA) & SD-2xT50(BC)(SA) & 3 & \(7 \frac{1}{2}\) & 15 & 15 & 30 & 30 & 65 & & & \\
\hline SD-T65(CW) & SD-2xT65(CW) & 3 & 10 & 15 & 20 & 40 & 40 & 95 & & & \\
\hline SD-T80(CW) & SD-2xT80(CW) & 5 & 15 & 20 & 25 & 50 & 50 & 100 & & & \\
\hline SD-T100 & SD-2xT100 & \(7 \frac{1}{2}\) & 15 & 25 & 30 & 60 & 60 & 100 & & & \\
\hline
\end{tabular}
(6) DC Operated Magnetic Contactor (Non-Reversing/Reversing) N Series (Certification Standard UL508) ©(U) © (File No. E58968)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Model} & \multicolumn{6}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{Rated Energizing Current [A]} & \multicolumn{2}{|r|}{\multirow[b]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline \multirow[t]{2}{*}{Non-Reversing} & \multirow[t]{2}{*}{Reversing (2)} & \multicolumn{2}{|l|}{Single-Phase (Non Reversible Type)} & \multicolumn{4}{|c|}{Three-Phase} & & & & \\
\hline & & 110 to 120 V & 220 to 240 V & 200 V & 220 to 240 V & 440 to 480 V & 550 to 600 V & & & & \\
\hline SD-N125 & SD-2xN125 & 10 & 20 & 40 & 40 & 75 & 75 & 125 & & & The standard \\
\hline SD-N150 & SD-2xN150 & 15 & 25 & 40 & 50 & 100 & 100 & 150 & &  & The \\
\hline SD-N220 & SD-2xN220 & 15 & 40 & 60 & 75 & 150 & 150 & 220 & AC600 V max & MC250 V max & product is certified \\
\hline SD-N300 & SD-2xN300 & 50 & 100 & 100 & 100 & 200 & 200 & 300 & & & (11) \\
\hline SD-N400 & SD-2xN400 & 50 & 150 & 125 & 150 & 300 & 300 & 400 & g 720 VA & Breaking 28 VA & LISted \\
\hline
\end{tabular}

Note 1. 125 A frames or higher with "UL" at the end of the model name are \({ }^{\circ} \mathrm{ULS}_{\text {LTEO }}\) Us certified for solderless terminal structure.
(7) Mechanically Latched Magnetic Contactor T Series (Certification Standard UL60947-4-1)
-(W) Us(File No. E58968)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Model} & \multicolumn{6}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{Rated Energizing Current [A]} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline \multirow[b]{2}{*}{Non-Reversing} & \multirow[b]{2}{*}{Reversing} & \multicolumn{2}{|l|}{Single-Phase (Non Reversible Type)} & \multicolumn{4}{|c|}{Three-Phase} & & & & \\
\hline & & 110 to 120 V & 220 to 240 V & 200 V & 220 to 240 V & 440 to 480 V & 550 to 600 V & & Rat & ing & \\
\hline SL(D)-T21UL(BC)(SA) & SL(D)-2xT21UL(BC)(SA) & 1 & 3 & 5 & 5 & 10 & 10 & 30 & & & \\
\hline SL(D)-T35UL(BC)(SA) & SL(D)-2xT35UL(BC)(SA) & 2 & 5 & 10 & 10 & 20 & 20 & 40 & A600 & Q300 & The dedicated \\
\hline SL(D)-T50UL(BC)(SA) & SL(D)-2xT50UL(BC)(SA) & 3 & \(7 \frac{1}{2}\) & 15 & 15 & 30 & 30 & 65 & AC600 V max & DC250 V max & product is certified \\
\hline SL(D)-T65UL & SL(D)-2xT65UL & 3 & 10 & 15 & 20 & 40 & 40 & 95 & Making 7200 VA & Making 69 VA & (Vi) us \\
\hline SL(D)-T80UL & SL(D)-2xT80UL & 5 & 15 & 20 & 25 & 50 & 50 & 100 & Breaking 720 VA & Breaking 69 VA & with \({ }_{\text {LISTED }}{ }^{\text {L }}\) Us \\
\hline SL(D)-T100UL & SL(D)-2xT100UL & \(7 \frac{1}{2}\) & 15 & 25 & 30 & 60 & 60 & 100 & & & \\
\hline
\end{tabular}
(8) Mechanically Latched Magnetic Contactor N Series (Certification Standard UL508)
\({ }_{c} \mathbf{N I}_{\text {us }}^{\infty}\) (File No. E58968)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Model} & \multicolumn{6}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{Rated Energizing Current [A]} & \multicolumn{2}{|r|}{\multirow[b]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline \multirow[b]{2}{*}{Non-Reversing} & \multirow[b]{2}{*}{Reversing} & \multicolumn{2}{|l|}{Single-Phase (Non Reversible Type)} & \multicolumn{4}{|c|}{Three-Phase} & & & & \\
\hline & & 110 to 120 V & 220 to 240 V & 200 V & 220 to 240 V & 440 to 480 V & 550 to 600 V & & & & \\
\hline SL(D)-N125UR & SL(D)-2xN125UR & 10 & 20 & 40 & 40 & 75 & 75 & 125 & & & \\
\hline SL(D)-N150UR & SL(D)-2xN150UR & 15 & 25 & 40 & 50 & 100 & 100 & 150 & A600 & R300 & The dedicated \\
\hline SL(D)-N220UR & SL(D)-2xN220UR & 15 & 40 & 60 & 75 & 150 & 150 & 220 & \begin{tabular}{l}
AC600 V max \\
Making 7200 VA
\end{tabular} & \begin{tabular}{l}
DC250 V max \\
Making 28 VA
\end{tabular} & product is certified \\
\hline SL(D)-N300UR & SL(D)-2xN300UR & - & - & 100 & 100 & 200 & 200 & 300 & & & \({ }^{\text {with }}\) c \({ }^{-1}\) \\
\hline SL(D)-N400UR & SL(D)-2xN400UR & - & - & 125 & 150 & 300 & 300 & 400 & & & \\
\hline
\end{tabular}
(9) Thermal Overload Relays T Series (Certification Standard UL60947-4-1)
\begin{tabular}{|c|c|c|c|}
\hline Model & Heater Designation [Adjustment Range (RC Value) (A) of Settling Current] & \multicolumn{2}{|r|}{Auxiliary Contact} \\
\hline TH-T18(BC)KP & \(0.12 \mathrm{~A}(0.1\) to 0.16\()\), 0.17 ( 0.14 to 0.22 ), \(0.24 \mathrm{~A}(0.2\) to 0.32\(), 0.35 \mathrm{~A}(0.28\) to 0.42\()\), \(0.5 \mathrm{~A}(0.4\) to 0.6\(), 0.7 \mathrm{~A}(0.55\) to 0.85 ), 0.9 A ( 0.7 to 1.1), 1.3A ( 1 to 1.6), 1.7A (1.4 to 2), 2.1A (1.7 to 2.5), 2.5A (2 to 3), 3.6A (2.8 to 4.4), 5A (4 to 6), 6.6A (5.2 to 8), 9A (7 to 11), 11A (9 to 13), 15A (12 to 18) Note 2 & \begin{tabular}{l}
Rating Code \\
Making Breaking
\end{tabular} & \[
\begin{aligned}
& \text { C600 } \\
& \text { AC600 Vmax } \\
& 1800 \text { VA (15 A max) } \\
& 180 \text { VA ( } 1.5 \mathrm{~A} \text { max) }
\end{aligned}
\] \\
\hline TH-T25(BC)KP & \(0.24 \mathrm{~A}(0.2\) to 0.32\(), 0.35 \mathrm{~A}(0.28\) to 0.42\(), 0.5 \mathrm{~A}(0.4\) to 0.6\(), 0.7 \mathrm{~A}(0.55\) to 0.85\(), 0.9 \mathrm{~A}(0.7\) to 1.1\()\), 1.3 A ( 1 to 1.6 ), 1.7A (1.4 to 2), 2.1A (1.7 to 2.5), 2.5A (2 to 3), 3.6A (2.8 to 4.4), \(5 \mathrm{~A}(4\) to 6\(), 6.6 \mathrm{~A}\) ( 5.2 to 8 ), 9 A ( 7 to 11), 11A (9 to 13), 15A (12 to 18), 22A (18 to 26) & \multirow[b]{2}{*}{Rating Code} & \multirow[b]{2}{*}{\[
\begin{aligned}
& \mathrm{B600} \\
& \text { AC600 Vmax }
\end{aligned}
\]} \\
\hline TH-T50(BC)KP & 29A (24 to 34), 35A (30 to 40), 42A (34 to 50) & & \\
\hline TH-T65(CW)KP & 15A (12 to 18), 22A (18 to 26), 29A (24 to 34), 35A (30 to 40), 42A (34 to 50), 54A (43 to 65) & \multirow[t]{2}{*}{Making Breaking} & \multirow[t]{2}{*}{3600 VA (30 A max) 360 VA (3 A max)} \\
\hline TH-T100KP & 67A (54 to 80), 82A (65 to 100) & & \\
\hline
\end{tabular}

Note 1. The maximum applicable current is 16 A .
The maximum applicable current other than the heater designation of 15 A is the largest current value within the adjustment range of settling current.
(10) Thermal Overload Relays N Series (Certification Standard UL508)
(WI) us(File No. E58969)
\begin{tabular}{|c|c|c|c|}
\hline Model & Heater Designation [Adjustment Range (RC Value) (A) of Settling Current] & \multicolumn{2}{|r|}{Auxiliary Contact} \\
\hline TH-N120KP & 42A (34 to 50), 54A (43 to 65), 67A (54 to 80), 82A (65 to 100) & \multirow[b]{3}{*}{Rating Code} & \multirow[b]{3}{*}{\[
\begin{aligned}
& \text { B600 } \\
& \text { AC600 Vmax }
\end{aligned}
\]} \\
\hline TH-N120TAKP is & 105A (85 to 125) & & \\
\hline TH-N120TAHZKP \(\star\) & 125A (100 to 150) & & \\
\hline \multirow[t]{2}{*}{TH-N220RHKP TH-N220HZKP} & 82A (65 to 100), 105A (85 to 125), 125A (100 to 150), 150A (120 to 180) & \multirow[t]{4}{*}{\begin{tabular}{l}
Making \\
Breaking
\end{tabular}} & \multirow[t]{2}{*}{\[
3600 \text { VA (30 A max) }
\]} \\
\hline & 180A (140 to 220) & & \\
\hline \multirow[t]{2}{*}{TH-N400RHKP \(\underset{~}{\Sigma}\) TH-N400HZKP} & 105A (85 to 125), 125A (100 to 150), 150A (120 to 180), 180A (140 to 220), 250A (200 to 300) & & \multirow[t]{2}{*}{360 VA (3 A max)} \\
\hline & 330A (260 to 400) & & \\
\hline
\end{tabular}

Note 1 . \(\begin{array}{r} \\ \text { is } \\ \text { for combination with the magnetic contactor and cannot be independently mounted. } \star \text { is exclusively for independent mounting. }\end{array}\)
Note 2. The symbol "KP" in the model name indicates 3 -element 2 E , and HZ indicates the independent mounting type.
Note 3. Frame N120 or higher with "UL" at the end of the model name is c LULTED \(_{\text {Lite }}^{\text {Us }}\) certified for solderless terminal structure.
(11) Contactor Relays T Series (Certification Standard UL60947-4-1)
(File No. E58969)
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multicolumn{4}{|c|}{Model} & \multicolumn{2}{|c|}{\multirow[b]{2}{*}{Rated}} & \multirow[b]{2}{*}{Remarks} \\
\hline \multicolumn{2}{|r|}{AC Operating} & \multicolumn{2}{|r|}{DC Operating} & & & \\
\hline \begin{tabular}{l}
c UL us \\
LISTED
\end{tabular} & SR-T5(BC)(SA)(SQ) & c ULUus & SRD-T5(BC)(SA)(SQ) & A600 AC600 V max Making 7200 VA Breaking 720 VA & \[
\begin{aligned}
& \hline \text { Q300 } \\
& \text { DC250 V max } \\
& \text { Making } 69 \text { VA } \\
& \text { Breaking } 69 \text { VA }
\end{aligned}
\] & The standard product is certified with - ULU) Us . \\
\hline
\end{tabular}
(12) Optional Unit T Series (Certification Standard UL60947-4-1) (File No. E58969)
\begin{tabular}{l|c}
\multicolumn{1}{c|}{ Model } & c \\
\hline UT-AX11(BC) Note 2 & ()\(^{®}\) \\
\hline UT-ML20(BC) & (1) \\
\hline UT-SA13, SA21, SA22, SA23, SA25 & \(\bigcirc\)
\end{tabular}
\(\overline{\text { Note 1. ©): Standard product and certified. (Mark displayed on the product) }}\)
(1): Certified as a contactor component. (mark not displayed on the product)

Note 2.
\begin{tabular}{|l|l|}
\hline \multicolumn{2}{|c|}{ Rated } \\
\hline A600 & Q300 \\
AC600 V max & DC250 V max \\
Making 7200 VA & Making 69 VA \\
Breaking 720 VA & Breaking 69 VA \\
\hline
\end{tabular}
(File No. E58969)
(File No. E58968 (AX80/AX150/AX600/UN-ML21 to ML220))
\begin{tabular}{|c|c|}
\hline Model Name & c \({ }^{\text {® }}\) \\
\hline UN-AX2 (CX), AX4 (CX), AX11 (CX) Note 3 & (0) \\
\hline UN-AX80, AX150, AX600 & (1) \\
\hline UQ-AX2(KR) Note 4 & (0) \\
\hline UN-ML21, ML80, ML150, ML220 & (1) \\
\hline UN-SA721, SA725 & (0) \\
\hline UN-SA33 & ( \({ }^{\text {a }}\) \\
\hline
\end{tabular}

Note 1. ©): Standard product and certified. (mark displayed on the product)
(1): Certified as a contactor component. (mark not displayed on the product)

Note 2. Products used in isolation from live parts (live part protection cover, reset release, etc.) are not subject to certification.
Note 3.
\begin{tabular}{|l|l|}
\hline \multicolumn{2}{|c|}{ Rating } \\
\hline A600 & R300 \\
AC600 V max & DC250 V max \\
Making 7200 VA & Making 28 VA \\
Breaking 720 VA & Breaking 28 VA \\
\hline
\end{tabular}

Note 4.
\begin{tabular}{|l|l|}
\hline \multicolumn{2}{|c|}{ Rating } \\
\hline A300 & Q300 \\
AC240 V max & DC250 V max \\
Making 7200 VA & Making 69 VA \\
Breaking 720 VA & Breaking 69 VA \\
\hline
\end{tabular}

\section*{Application to Domestic and International Standards}
(14) DC Interface Contactors (Certification Standard UL508)
(【乌) Us(File No. E58968)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{\multirow[b]{2}{*}{Model Name}} & \multicolumn{5}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{\begin{tabular}{c|} 
Rated \\
Continuity \\
Current \\
[A] \\
\hline
\end{tabular}} & \multicolumn{2}{|r|}{\multirow[b]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline & & \multicolumn{2}{|l|}{Single-Phase (Non-Reversible Type Only)} & \multicolumn{3}{|c|}{Three-Phase} & & & & \\
\hline Non-Reversible Type & Reversible Type & 110 to 120 V & 220 to 240 V & 200 to 208 V & 220 to 240 V & 440 to 480 V & & & ting & \\
\hline \[
\begin{aligned}
& \hline \text { SD-Q11 } \\
& \text { SD-Q12 }
\end{aligned}
\] & \[
\begin{aligned}
& \hline \text { SD-QR11 } \\
& \text { SD-QR12 }
\end{aligned}
\] & \multirow{3}{*}{\(\frac{1}{3}\)} & \multirow[t]{3}{*}{1} & \multirow[t]{3}{*}{3} & \multirow{3}{*}{3} & \multirow{3}{*}{5} & 20 & \[
\begin{array}{|l|}
\hline \text { A300 } \\
\text { AC240 V max }
\end{array}
\] & \[
\begin{aligned}
& \text { Q300 } \\
& \text { DC250 V max }
\end{aligned}
\] & \multirow[b]{3}{*}{The standard product is certified with o(UL) us} \\
\hline MSOD-Q11(KP) & MSOD-QR11(KP) & & & & & & \multirow[t]{2}{*}{13} & Making 7200 VA & Making 69 VA & \\
\hline MSOD-Q12(KP) & MSOD-QR12(KP) & & & & & & & Breaking 720 VA & Breaking 69 VA & \\
\hline
\end{tabular}
(15) Vacuum Magnetic Contactors (Certification Standard UL508)
\({ }_{c}\) In \(_{\text {Us }}^{\infty}\) (File No. E58968)
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Model Name} & \multicolumn{4}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{Rated Continuity Current [A]} & \multirow[t]{3}{*}{Auxiliary Contact Rating} & \multirow{3}{*}{Remarks} \\
\hline & \multicolumn{4}{|c|}{Three-Phase} & & & \\
\hline & 200 V & 220 to 240 V & 440 to 480 V & 550 to 600 V & & & \\
\hline SH-V160 & 60 & 60 & 150 & 150 & 200 & A600 & The standard \\
\hline SH-V320 & 100 & 125 & 250 & 300 & 350 & AC600 V max & product is \\
\hline SH-V400 & 125 & 150 & 350 & 400 & 450 & Making 7200 VA & \\
\hline SH-V600 & 200 & 250 & 500 & 600 & 610 & Breaking 720 VA & c \({ }^{\text {us }}\). \\
\hline
\end{tabular}
(16) Solid State Contactors for Motor/Heater Loads (Certification Standard UL508)
(14) Us(File No. E144063)
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{Model Name} & \multicolumn{4}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{Rated Continuity Current [A]} & \multirow{3}{*}{Remarks} \\
\hline \multirow[t]{2}{*}{3-Pole 2-Element Type} & \multirow[t]{2}{*}{3-Pole 3-Element Type} & \multicolumn{2}{|c|}{Single-Phase} & \multicolumn{2}{|c|}{Three-Phase} & & \\
\hline & & 110 to 120 V & 220 to 240 V & 220 to 240 V & 440 to 480 V & & \\
\hline US-N5SS & US-N5SSTE & \(\frac{1}{10}\) & \(\frac{1}{4}\) & \(\frac{3}{4}\) & - & 5 & \\
\hline US-N8SS & US-N8SSTE & \(\frac{1}{10}\) & \(\frac{1}{4}\) & \(\frac{3}{4}\) & - & 8 & \\
\hline US-N20(CX)(RM) & US-N20TE(CX)(RM) & \(\frac{1}{2}\) & 1 \(\frac{1}{2}\) & 3 & 5 & 20 & \\
\hline US-N30(CX) & US-N30TE(CX) & 1 & 3 & 5 & 10 & 30 & \\
\hline US-N40(CX) & US-N40TE(CX) & 2 & 3 & \(7 \frac{1}{2}\) & 20 & 40 & The standard product is \\
\hline US-N50(CX) & US-N50TE(CX) & 2 & 3 & \(7 \frac{1}{2}\) & 20 & 50 & certified with © (ULus . \\
\hline US-N70NS & US-N70NSTE & 3 & \(7 \frac{1}{2}\) & 15 & - & 70 & \\
\hline US-N80NS & US-N80NSTE & 3 & \(7 \frac{1}{2}\) & 15 & - & 80 & \\
\hline US-NH70NS & US-NH70NSTE & 3 & \(7 \frac{1}{2}\) & 15 & 30 & 70 & \\
\hline US-NH80NS & US-NH80NSTE & 3 & \(7 \frac{1}{2}\) & 15 & 30 & 80 & \\
\hline
\end{tabular}
(17) Solid State Contactors for Heater Loads (Certification Standard UL508)
\begin{tabular}{|c|c|c|c|}
\hline \multicolumn{2}{|c|}{Model Name} & \multirow[t]{2}{*}{Rated Continuity Current [A]} & \multirow[t]{2}{*}{Remarks} \\
\hline Batch Control Type & Individual Control Type & & \\
\hline US-H20(RM)(HZ)(UF) & US-H2ODD(RM)(HZ)(UF) & 20 & \multirow{4}{*}{The standard product is certified with \(\begin{gathered}\text { ULitive } \\ \text { us } \\ \text {. }\end{gathered}\)} \\
\hline US-H30(RM)(HZ)(UF) & US-H30DD(RM)(HZ)(UF) & 30(27) (Note 4) & \\
\hline US-H40(HZ) & US-H40DD(HZ) & 40 & \\
\hline US-H50 Note 3 & US-H50DD Note 3 & 50 & \\
\hline
\end{tabular}

Note 1. (HZ) has no cooling fin. (RM) can be rail-mounted.
Note 2. US-H \(\square\) (DD) HZ is certified at the rated continuity current when combined with the fin used for US-H \(\square\) (DD).
Note 3. US-H50 (DD) HZ has UR certification only.
Note 4. () is the rating for US-H3O (DD) UF.

\subsection*{10.5.3 CSA Standards Certified Product}

There are the following 2 types of certification marks.

(1) AC Operated Magnetic Contactor (Non-Reversible) T Series (Certification Standard CSA C22.2 No.60947-4-1) cellus(File No. E58968)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline Model Name & \multicolumn{6}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{Rated Continuity Current [A]} & \multicolumn{2}{|c|}{\multirow[b]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline Magnetic & \multicolumn{2}{|l|}{Singl--Phase (Non-Reversible Type Only)} & \multicolumn{4}{|c|}{Three-Phase} & & & & \\
\hline Contactors & 110 to 120 V & 220 to 240 V & 200 V & 220 to 240 V & 440 to 480 V & 550 to 600 V & & \multicolumn{2}{|c|}{Rating} & \\
\hline S-T10(BC)(SA) & \(\frac{1}{2}\) & \(1 \frac{1}{2}\) & 3 & 3 & 5 & 5 & 13 & \multirow{11}{*}{\begin{tabular}{l}
A600 \\
AC600 V max \\
Making 7200 VA \\
Breaking 720 VA
\end{tabular}} & \multirow{11}{*}{\begin{tabular}{l}
Q300 \\
DC250 V max \\
Making 69 VA \\
Breaking 69 VA
\end{tabular}} & \multirow{11}{*}{The standard product is certified with \({ }^{\circ}\)} \\
\hline S-T12(BC)(SA)(SQ) & \(\frac{1}{2}\) & \(1 \frac{1}{2}\) & 3 & 3 & \(7 \frac{1}{2}\) & \(7 \frac{1}{2}\) & 20 & & & \\
\hline S-T20(BC)(SA)(SQ) & 1 & 2 & 3 & 5 & \(7 \frac{1}{2}\) & \(7 \frac{1}{2}\) & 20 & & & \\
\hline S-T21(BC)(SA) & 1 & 3 & 5 & 5 & 10 & 10 & 30 & & & \\
\hline S-T25(BC)(SA) & 2 & 3 & \(7 \frac{1}{2}\) & \(7 \frac{1}{2}\) & 15 & 15 & 30 & & & \\
\hline S-T32(BC)(SA) & 2 & 5 & 10 & 10 & 20 & 15 & 32.5 & & & \\
\hline S-T35(BC)(SA) & 2 & 5 & 10 & 10 & 20 & 20 & 40 & & & \\
\hline S-T50(BC)(SA) & 3 & \(7 \frac{1}{2}\) & 15 & 15 & 30 & 30 & 65 & & & \\
\hline S-T65(CW) & 3 & 10 & 15 & 20 & 40 & 40 & 95 & & & \\
\hline S-T80(CW) & 5 & 15 & 20 & 25 & 50 & 50 & 100 & & & \\
\hline S-T100 & \(7 \frac{1}{2}\) & 15 & 25 & 30 & 60 & 60 & 100 & & & \\
\hline
\end{tabular}
(2) AC Operated Magnetic Contactor (Non-Reversible) N Series (Certification Standard CSA C22.2 No.14) c刿vs(File No. E58968)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline Model Name & \multicolumn{6}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{Rated Continuity Current [A]} & \multicolumn{2}{|c|}{\multirow[t]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline Magnetic & \multicolumn{2}{|l|}{Single-Phase (Non-Reversible Type Only)} & \multicolumn{4}{|c|}{Three-Phase} & & & & \\
\hline Contactors & 110 to 120 V & 220 to 240 V & 200 V & 220 to 240 V & 440 to 480 V & 550 to 600 V & & \multicolumn{2}{|c|}{Rating} & \\
\hline S-N125 & 10 & 20 & 40 & 40 & 75 & 75 & 125 & \multirow{8}{*}{\begin{tabular}{l}
A600 \\
AC600 V max \\
Making 7200 VA \\
Breaking 720 VA
\end{tabular}} & \multirow{8}{*}{\begin{tabular}{l}
R300 \\
DC250 V max \\
Making 28 VA \\
Breaking 28 VA
\end{tabular}} & \multirow{6}{*}{The standard product is certified with} \\
\hline S-N150 & 15 & 25 & 40 & 50 & 100 & 100 & 150 & & & \\
\hline S-N180 & 15 & 30 & 60 & 60 & 125 & 125 & 220 & & & \\
\hline S-N220 & 15 & 40 & 60 & 75 & 150 & 150 & 220 & & & \\
\hline S-N300 & - & - & 100 & 100 & 200 & 200 & 300 & & & \\
\hline S-N400 & - & - & 125 & 150 & 300 & 300 & 400 & & & \\
\hline S-N600 & - & - & 150 & 200 & 400 & 400 & 680 & & & Standard product and \({ }_{\mathbf{c}} \boldsymbol{\boldsymbol { \Lambda } _ { \text { us } } ^ { \text { ® } } \text { cerified. }}\) \\
\hline S-N800UR & - & - & 250 & 300 & 600 & 600 & 910 & & &  \\
\hline
\end{tabular}

Note 1. 125 A to 400 A frames with "UL" at the end of the model name are cULUs certified for solderless terminal structure.
(3) AC Operated Magnetic Contactor (Reversible) T Series (Certification Standard CSA C22.2 No.60947-4-1) © (4) usu(File No. E58968)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline Model Name & \multicolumn{4}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{Rated Continuity Current [A]} & \multicolumn{2}{|r|}{\multirow[b]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline & \multicolumn{4}{|c|}{Three-Phase} & & & & \\
\hline Magnetic Contactors & 200 V & 220 to 240 V & 440 to 480 V & 550 to 600 V & & \multicolumn{2}{|c|}{Rating} & \\
\hline S-2xT10(BC)(SA) & 3 & 3 & 5 & 5 & 13 & \multirow{10}{*}{\begin{tabular}{l}
A600 \\
AC600 V max \\
Making 7200 VA \\
Breaking 720 VA
\end{tabular}} & \multirow{10}{*}{\begin{tabular}{l}
Q300 \\
DC250 V max \\
Making 69 VA \\
Breaking 69 VA
\end{tabular}} & \multirow{10}{*}{The standard product is certified with \({ }_{\text {© }}^{\text {LISTED }}\)} \\
\hline S-2xT12(BC)(SA) & 3 & 3 & \(7 \frac{1}{2}\) & \(7 \frac{1}{2}\) & 20 & & & \\
\hline S-2xT20(BC)(SA) & 3 & 5 & \(7 \frac{1}{2}\) & \(7 \frac{1}{2}\) & 20 & & & \\
\hline S-2xT21(BC)(SA) & 5 & 5 & 10 & 10 & 30 & & & \\
\hline S-2xT25(BC)(SA) & \(7 \frac{1}{2}\) & \(7 \frac{1}{2}\) & 15 & 15 & 30 & & & \\
\hline S-2xT35(BC)(SA) & 10 & 10 & 20 & 20 & 40 & & & \\
\hline S-2xT50(BC)(SA) & 15 & 15 & 30 & 30 & 65 & & & \\
\hline S-2xT65(CW) & 15 & 20 & 40 & 40 & 95 & & & \\
\hline S-2xT80(CW) & 20 & 25 & 50 & 50 & 100 & & & \\
\hline S-2xT100 & 25 & 30 & 60 & 60 & 100 & & & \\
\hline
\end{tabular}
(4) AC Operated Magnetic Contactor (Reversible) N Series (Certification Standard CSA C22.2 No.14)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{3}{*}{Model Name} & \multicolumn{4}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{Rated Continuity Current [A]} & \multicolumn{2}{|r|}{\multirow[t]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline & \multicolumn{4}{|c|}{Three-Phase} & & & & \\
\hline & 200 V & 220 to 240 V & 440 to 480 V & 550 to 600 V & & \multicolumn{2}{|c|}{Rating} & \\
\hline S-2xN125 & 40 & 40 & 75 & 75 & 125 & \multirow{7}{*}{\begin{tabular}{l}
A600 \\
AC600 V max \\
Making 7200 VA \\
Breaking 720 VA
\end{tabular}} & \multirow{7}{*}{\begin{tabular}{l}
R300 \\
DC250 V max \\
Making 28 VA \\
Breaking 28 VA
\end{tabular}} & \multirow{6}{*}{The magnetic contactor is certified as a \({ }^{\mathrm{c}} \mathrm{ULTED}_{\text {USTED }}\) standard product.} \\
\hline S-2xN150 & 40 & 50 & 100 & 100 & 150 & & & \\
\hline S-2xN180 & 60 & 60 & 125 & 125 & 180 & & & \\
\hline S-2xN220 & 60 & 75 & 150 & 150 & 220 & & & \\
\hline S-2xN300 & 100 & 100 & 200 & 200 & 300 & & & \\
\hline S-2xN400 & 125 & 150 & 300 & 300 & 400 & & & \\
\hline S-2xN600 & 150 & 200 & 400 & 400 & 680 & & & Standard product and \({ }_{\mathrm{c}} \boldsymbol{\lambda}^{\text {w }}\) ws certified. \\
\hline
\end{tabular}

\footnotetext{
Note 1. 125 A to 400 A frames with "UL" at the end of the model name are c us certified for solderless terminal structure.
}

\section*{Application to Domestic and International Standards}

\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Model Name} & \multicolumn{6}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{Rated Continuity Current [A]} & \multicolumn{2}{|r|}{\multirow[b]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline Non-Reversible & \multirow[b]{2}{*}{Reversible Type (2)} & \multicolumn{2}{|l|}{Single-Phase (Non-Reversible Type Only)} & \multicolumn{4}{|c|}{Three-Phase} & & & & \\
\hline Type & & 110 to 120 V & 220 to 240 V & 200 V & 220 to 240 V & 440 to 480 V & 550 to 600 V & & & & \\
\hline SD-T12(BC)(SA)(SQ) & SD-2×T12(BC)(SA) & \(\frac{1}{2}\) & \(1 \frac{1}{2}\) & 3 & 3 & \(7 \frac{1}{2}\) & \(7 \frac{1}{2}\) & 20 & & & \\
\hline SD-T20(BC)(SA)(SQ) & SD-2×T20(BC)(SA) & 1 & 2 & 3 & 5 & \(7 \frac{1}{2}\) & \(7 \frac{1}{2}\) & 20 & & & \\
\hline SD-T21(BC)(SA) & SD-2xT21(BC)(SA) & 1 & 3 & 5 & 5 & 10 & 10 & 30 & A600 & & \\
\hline SD-T32(BC)(SA) & - & 2 & 5 & 10 & 10 & 20 & 15 & 32.5 & AC600 &  & The standard product is \\
\hline SD-T35(BC)(SA) & SD-2xT35(BC)(SA) & 2 & 5 & 10 & 10 & 20 & 20 & 40 & Making 7200 VA &  & \({ }^{(1 / L)}\) us \\
\hline SD-T50(BC)(SA) & SD-2xT50(BC)(SA) & 3 & \(7 \frac{1}{2}\) & 15 & 15 & 30 & 30 & 65 & Breaking 720 VA & Breaking 69 VA & Certified with LISTED \(^{\text {d }}\) \\
\hline SD-T65(CW) & SD-2xT65(CW) & 3 & 10 & 15 & 20 & 40 & 40 & 95 & & & \\
\hline SD-T80(CW) & SD-2xT80(CW) & 5 & 15 & 20 & 25 & 50 & 50 & 100 & & & \\
\hline SD-T100 & SD-2xT100 & \(7 \frac{1}{2}\) & 15 & 25 & 30 & 60 & 60 & 100 & & & \\
\hline
\end{tabular}
(6) DC Operated Magnetic Contactor (Non-Reversible/Reversible) N Series (Certification Standard CSA C22.2 No.14) © ©
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Model Name} & \multicolumn{6}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{\(\left\lvert\, \begin{gathered}\text { Rated } \\ \text { Continuity } \\ \text { Current }[A]\end{gathered}\right.\)} & \multicolumn{2}{|r|}{\multirow[b]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline Non-Reversible & \multirow[b]{2}{*}{Reversible Type (2)} & \multicolumn{2}{|l|}{Single-Phase (Non-Reversible Type Only} & \multicolumn{4}{|c|}{Three-Phase} & & & & \\
\hline Type & & 110 to 120 V & 220 to 240 V & 200 V & 220 to 240 V & 440 to 480 V & 550 to 600 V & & & & \\
\hline SD-N125 & SD-2xN125 & 10 & 20 & 40 & 40 & 75 & 75 & 125 & & & \\
\hline SD-N150 & SD-2xN150 & 15 & 25 & 40 & 50 & 100 & 100 & 150 & A600
AC600 V max &  & The standard product is \\
\hline SD-N220 & SD-2xN220 & 15 & 40 & 60 & 75 & 150 & 150 & 220 & Making 7200 VA & DC250 V max & \\
\hline SD-N300 & SD-2xN300 & - & - & 100 & 100 & 200 & 200 & 300 & Breaking 720 VA & Breaking 28 VA & certified with \({ }_{\text {LIStED }}\) \\
\hline SD-N400 & SD-2xN400 & - & - & 125 & 150 & 300 & 300 & 400 & & & \\
\hline
\end{tabular}

Note 1. 125 A frames or higher with "UL" at the end of the model name are ©UL Us certified for solderless terminal structure.
(7) Mechanically Latched Contactor T Series (Certification Standard CSA C22.2 No.60947-4-1)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Model Name} & \multicolumn{6}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{Rated
Continuity
Current \([A]\)} & \multicolumn{2}{|r|}{\multirow[b]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline Non-Reversible & \multirow[t]{2}{*}{Reversible Type} & \multicolumn{2}{|l|}{Single-Phase (Non-Reversible Type Only)} & \multicolumn{4}{|c|}{Three-Phase} & & & & \\
\hline Type & & 110 to 120 V & 220 to 240 V & 200 V & 220 to 240 V & 440 to 480 V & 550 to 600 V & & & & \\
\hline SL(D)-T21UL(BC)(SA) & SL(D)-2xT21UL(BC)(SA) & 1 & 3 & 5 & 5 & 10 & 10 & 30 & & & The dedicated \\
\hline SL(D)-T35UL(BC)(SA) & SL(D)-2xT35UL(BC)(SA) & 2 & 5 & 10 & 10 & 20 & 20 & 40 & A600 & Q300 & The dedicated \\
\hline SL(D)-T50UL(BC)(SA) & SL(D)-2xT50UL(BC)(SA) & 3 & \(7 \frac{1}{2}\) & 15 & 15 & 30 & 30 & 65 & AC600 V max & DC250 V max & product is \\
\hline SL(D)-T65UL & SL(D)-2xT65UL & 3 & 10 & 15 & 20 & 40 & 40 & 95 & Making 7200 VA & Making 69 VA & certified with \\
\hline SL(D)-T80UL & SL(D)-2xT80UL & 5 & 15 & 20 & 25 & 50 & 50 & 100 & Breaking 720 VA & Breaking 69 VA & c (1) us \\
\hline SL(D)-T100UL & SL(D)-2xT100UL & \(7 \frac{1}{2}\) & 15 & 25 & 30 & 60 & 60 & 100 & & & LISTED \\
\hline
\end{tabular}
(8) Mechanically Latched Contactor N Series (Certification Standard CSA C22.2 No.14)
\({ }_{c} \boldsymbol{1}_{\mathrm{us}}^{\ominus}\) (File No. E58968)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Model Name} & \multicolumn{6}{|c|}{Rated Capacity [ HP ]} & \multirow[t]{3}{*}{\[
\begin{array}{|c|}
\hline \text { Rated } \\
\text { Continuity } \\
\text { Current }[A] \\
\hline
\end{array}
\]} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline Non-Reversible & \multirow[t]{2}{*}{Reversible Type} & \multicolumn{2}{|l|}{Single-Phase (Non-Reversible Type Only)} & \multicolumn{4}{|c|}{Three-Phase} & & & & \\
\hline Type & & 110 to 120 V & 220 to 240 V & 200 V & 220 to 240 V & 440 to 480 V & 550 to 600 V & & & & \\
\hline SL(D)-N125UR & SL(D)-2xN125UR & 10 & 20 & 40 & 40 & 75 & 75 & 125 & & & \\
\hline SL(D)-N150UR & SL(D)-2xN150UR & 15 & 25 & 40 & 50 & 100 & 100 & 150 & A600 & R300 & The dedicated \\
\hline SL(D)-N220UR & SL(D)-2xN220UR & 15 & 40 & 60 & 75 & 150 & 150 & 220 & AC600 V max & \begin{tabular}{l}
DC250 V max \\
Making 28 VA
\end{tabular} & product is certified \\
\hline SL(D)-N300UR & SL(D)-2xN300UR & - & - & 100 & 100 & 200 & 200 & 300 & Breaking 720 VA & Breaking 28 VA & with c us . \\
\hline SL(D)-N400UR & SL(D)-2xN400UR & - & - & 125 & 150 & 300 & 300 & 400 & & & \\
\hline
\end{tabular}
(9) Thermal Overload Relay T Series (Certification Standard CSA C22.2 No.60947-4-1)
s(File No. E58969)
\begin{tabular}{|c|c|c|c|}
\hline Model Name & Heater Designation [Adjustment Range (RC Value) (A) of Settling Current] & \multicolumn{2}{|r|}{Auxiliary Contact} \\
\hline TH-T18(BC)KP & \(0.12 \mathrm{~A}(0.1\) to 0.16\(), 0.17\) (0.14 to 0.22\(), 0.24 \mathrm{~A}(0.2\) to 0.32\(), 0.35 \mathrm{~A}(0.28\) to 0.42\()\), \(0.5 \mathrm{~A}(0.4\) to 0.6\(), 0.7 \mathrm{~A}(0.55\) to 0.85 ), 0.9 A ( 0.7 to 1.1), 1.3A ( 1 to 1.6), 1.7A (1.4 to 2), 2.1A (1.7 to 2.5), 2.5A (2 to 3), 3.6A (2.8 to 4.4), 5A (4 to 6), 6.6A (5.2 to 8), 9 A (7 to 11), 11A (9 to 13), 15A (12 to 18) Note 2 & \begin{tabular}{l}
Rating Code \\
Making Breaking
\end{tabular} & \begin{tabular}{l}
C600 \\
AC600 Vmax \\
1800 VA (15 A max) \\
180 VA (1.5 A max)
\end{tabular} \\
\hline TH-T25(BC)KP & \(0.24 \mathrm{~A}(0.2\) to 0.32\(), 0.35 \mathrm{~A}(0.28\) to 0.42\(), 0.5 \mathrm{~A}(0.4\) to 0.6\(), 0.7 \mathrm{~A}(0.55\) to 0.85\(), 0.9 \mathrm{~A}(0.7\) to 1.1\()\), \(1.3 \mathrm{~A}(1\) to 1.6\(), 1.7 \mathrm{~A}(1.4\) to 2 ), 2.1A (1.7 to 2.5), 2.5A (2 to 3), 3.6 A ( 2.8 to 4.4 ), \(5 \mathrm{~A}(4\) to 6 ), \(6.6 \mathrm{~A}(5.2\) to 8 ), \(9 \mathrm{~A}(7\) to 11 ), 11A ( 9 to 13), 15A (12 to 18), 22A (18 to 26) & \multirow[b]{2}{*}{Rating Code} & \multirow[t]{2}{*}{B600 AC600 Vmax} \\
\hline TH-T50(BC)KP & 29A (24 to 34), 35A (30 to 40), 42A (34 to 50) & & \\
\hline TH-T65(CW)KP & 15A (12 to 18), 22A (18 to 26), 29A (24 to 34), 35A (30 to 40), 42A (34 to 50), 54A (43 to 65) & \multirow[t]{2}{*}{Making Breaking} & \multirow[t]{2}{*}{3600 VA (30 A max) 360 VA (3 A max)} \\
\hline TH-T100KP & 67A (54 to 80), 82A (65 to 100) & & \\
\hline
\end{tabular}

\footnotetext{
Note 1. The maximum applicable current is 16 A .
The maximum applicable current other than the heater designation of 15 A is the largest current value within the adjustment range of settling current.
}
(10) Thermal Overload Relay N Series (Certification Standard CSA C22.2 No.14)
\begin{tabular}{|c|c|c|c|}
\hline Model Name & Heater Designation [Adjustment Range (RC Value) (A) of Settling Current] & \multicolumn{2}{|r|}{Auxiliary Contact} \\
\hline TH-N120KP & 42A (34 to 50), 54A (43 to 65), 67A (54 to 80), 82A (65 to 100) & \multirow[b]{3}{*}{Rating Code} & \multirow[b]{3}{*}{\[
\begin{aligned}
& \text { B600 } \\
& \text { AC600 Vmax }
\end{aligned}
\]} \\
\hline TH-N120TAKP \(\downarrow\) & 105A (85 to 125) & & \\
\hline TH-N120TAHZKP \(\star\) & 125A (100 to 150) & & \\
\hline TH-N220RHKP \(\begin{gathered}\text { ¢ }\end{gathered}\) & 82A (65 to 100), 105A (85 to 125), 125A (100 to 150), 150A (120 to 180) & \multirow{4}{*}{\begin{tabular}{l}
Making \\
Breaking
\end{tabular}} & \multirow{4}{*}{3600 VA (30 A max) 360 VA (3 A max)} \\
\hline TH-N220HZKP \(\star\) & 180A (140 to 220) & & \\
\hline \multirow[t]{2}{*}{TH-N400RHKP TH-N400HZKP} & 105A (85 to 125), 125A (100 to 150), 150A (120 to 180), 180A (140 to 220), 250A (200 to 300) & & \\
\hline & 330A (260 to 400) & & \\
\hline
\end{tabular}

Note 1 . \(\vec{\sim}\) is for combination with the magnetic contactor and cannot be independently mounted. \(\star\) is exclusively for independent mounting.
Note 2. The symbol "KP" in the model name indicates 3-element 2 E , and HZ indicates the independent mounting type.
Note 3. Frame N120 or higher with "UL" at the end of the model name is \({ }_{\text {L }}^{\text {Litsen }}\) Us vertified for solderless terminal structure.
(11) Contactor Relay T Series (Certification Standard CSA C22.2 No.60947-4-1)
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multicolumn{4}{|c|}{Model Name} & \multicolumn{2}{|c|}{\multirow[b]{2}{*}{Rating}} & \multirow[b]{2}{*}{Remarks} \\
\hline \multicolumn{2}{|r|}{AC Operated} & \multicolumn{2}{|r|}{DC Operated} & & & \\
\hline c (UL) Us & SR-T5(BC)(SA)(SQ) & c (UL) US & SRD-T5(BC)(SA)(SQ) & A600 AC600 V max Making 7200 VA Breaking 720 VA & \begin{tabular}{l}
Q300 \\
DC250 V max \\
Making 69 VA \\
Breaking 69 VA
\end{tabular} & The standard product is certified with \(\underset{\text { c }}{\text { LILTED }}\) us . \\
\hline
\end{tabular}
(12) Optional Unit T Series (Certification Standard CSA C22.2 No.60947-4-1) (File No. E58969)
\begin{tabular}{l|c}
\multicolumn{1}{c|}{ Model Name } & c \({ }_{\text {U }}^{\text {U }}\) \\
\hline UT-AX11(BC) Note 2 & \(\bigcirc\) \\
\hline UT-ML20(BC) & \((1)\) \\
\hline UT-SA13, SA21, SA22, SA23, SA25 & \(\bigcirc\) \\
\hline
\end{tabular}

Note 1. ©: Standard product and certified. (mark displayed on the product)
Note 2.
(1): Certified as a contactor component. (mark not displayed on the product)
(13) Optional Unit N Series (Certification Standard CSA C22.2 No.14) (File No. E58969)
\begin{tabular}{|l|l|}
\hline \multicolumn{2}{|c|}{ Rating } \\
\hline A600 & Q300 \\
AC600 V max & DC250 V max \\
Making 7200 VA & Making 69 VA \\
Breaking 720 VA & Breaking 69 VA \\
\hline
\end{tabular}
(File No. E58968 (AX80/AX150/AX600/UN-ML11(CX), ML21 to ML220))
\begin{tabular}{|c|c|}
\hline Model Name & \[
C \mathrm{US}^{\circledR}
\] \\
\hline UN-AX2 (CX), AX4 (CX), AX11 (CX) Note 3 & ( 0 \\
\hline UN-AX80, AX150, AX600 & (1) \\
\hline UQ-AX2(KR) Note 4 & (0) \\
\hline UN-ML21 & (1) \\
\hline UN-ML21, ML80, ML150, ML220 & (1) \\
\hline UN-SA721, SA725 & (0) \\
\hline UN-SA33 & ( \({ }^{\text {a }}\) \\
\hline
\end{tabular}

Note 1. ©: Standard product and certified. (mark displayed on the product)
(1): Certified as a contactor component. (mark not displayed on the product)

Note 2. Products used in isolation from live parts (live part protection cover, reset release, etc.) are not subject to certification.

\section*{Note 3.}
\begin{tabular}{|l|l|}
\hline \multicolumn{2}{|c|}{ Rating } \\
\hline A600 & R300 \\
AC600 V max & DC250 V max \\
Making 7200 VA & Making 28 VA \\
Breaking 720 VA & Breaking 28 VA \\
\hline
\end{tabular}
\begin{tabular}{|l|l|}
\hline \multicolumn{2}{|c|}{ Rating } \\
\hline A300 & Q300 \\
AC240 V max & DC250 V max \\
Making 7200 VA & Making 69 VA \\
Breaking 720 VA & Breaking 69 VA \\
\hline
\end{tabular}

\section*{Application to Domestic and International Standards}
(14) DC Interface Contactors (Certification Standard CSA C22.2 No.14)
(WIUs(File No. E58968)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{\multirow[t]{2}{*}{Model Name}} & \multicolumn{5}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{Rated Continuity Current [A]} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Auxiliary Contact}} & \multirow{3}{*}{Remarks} \\
\hline & & \multicolumn{2}{|l|}{Single-Phase (Non-Reversible Type Only)} & \multicolumn{3}{|c|}{Three-Phase} & & & & \\
\hline Non-Reversible Type & Reversible Type & 110 to 120 V & 220 to 240 V & 200 to 208 V & 220 to 240 V & 440 to 480 V & & & & \\
\hline \[
\begin{aligned}
& \text { SD-Q11 } \\
& \text { SD-Q12 }
\end{aligned}
\] & \[
\begin{array}{|l|}
\hline \text { SD-QR11 } \\
\text { SD-QR12 }
\end{array}
\] & \(\frac{1}{3}\) & 1 & 3 & 3 & 5 & 20 & \[
\begin{aligned}
& \text { A300 } \\
& \text { AC240 V max }
\end{aligned}
\] & \[
\begin{aligned}
& \text { Q300 } \\
& \text { DC250 V max }
\end{aligned}
\] & \\
\hline \[
\begin{aligned}
& \text { MSOD-Q11(KP) } \\
& \text { MSOD-Q12(KP) }
\end{aligned}
\] & \[
\begin{aligned}
& \text { MSOD-QR11(KP) } \\
& \text { MSOD-QR12(KP) }
\end{aligned}
\] & & & & & & 13 & \begin{tabular}{l}
Making 7200 VA \\
Breaking 720 VA
\end{tabular} & Making 69 VA Breaking 69 VA & certified with \({ }_{\text {c }}^{\text {Usteo }}\) us. \\
\hline
\end{tabular}
(15) Vacuum Magnetic Contactors (Certification Standard CSA C22.2 No.14)
\({ }_{c} \mathbf{M I}_{\text {us }}^{®}\) (File No. E58968)
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Model Name} & \multicolumn{4}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{Rated Continuity Current [A]} & \multirow[b]{2}{*}{Auxiliary Contact} & \multirow{3}{*}{Remarks} \\
\hline & \multicolumn{4}{|c|}{Three-Phase} & & & \\
\hline & 200 V & 220 to 240 V & 440 to 480 V & 550 to 600 V & & Rating & \\
\hline SH-V160 & 60 & 60 & 150 & 150 & 200 & \multirow[t]{4}{*}{\begin{tabular}{l}
A600 \\
AC600 V max \\
Making 7200 VA \\
Breaking 720 VA
\end{tabular}} & \multirow[t]{4}{*}{The standard product is certified with
\[
\boldsymbol{q}^{\oplus}{ }_{\mathrm{us}}
\]} \\
\hline SH-V320 & 100 & 125 & 250 & 300 & 350 & & \\
\hline SH-V400 & 125 & 150 & 350 & 400 & 450 & & \\
\hline SH-V600 & 200 & 250 & 500 & 600 & 610 & & \\
\hline
\end{tabular}
(16) Solid State Contactors for Motor/Heater Loads (Certification Standard CSA C22.2 No.14)
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Model Name} & \multicolumn{4}{|c|}{Rated Capacity [HP]} & \multirow[t]{3}{*}{Rated
Continuity
Current
\([A]\)} & \multirow{3}{*}{Remarks} \\
\hline \multirow[t]{2}{*}{3-Pole 2-Element Type} & \multirow[t]{2}{*}{3-Pole 3-Element
Type} & \multicolumn{2}{|c|}{Single-Phase} & \multicolumn{2}{|c|}{Three-Phase} & & \\
\hline & & 110 to 120 V & 220 to 240 V & 220 to 240 V & 440 to 480 V & & \\
\hline US-N5SS & US-N5SSTE & \(\frac{1}{10}\) & \(\frac{1}{4}\) & \(\frac{3}{4}\) & - & 5 & \multirow{10}{*}{The standard product is certified with © (UL) us .} \\
\hline US-N8SS & US-N8SSTE & \(\frac{1}{10}\) & \(\frac{1}{4}\) & \(\frac{3}{4}\) & - & 8 & \\
\hline US-N20(CX)(RM) & US-N2OTE(CX)(RM) & \(\frac{1}{2}\) & \(1 \frac{1}{2}\) & 3 & 5 & 20 & \\
\hline US-N30(CX) & US-N30TE(CX) & 1 & 3 & 5 & 10 & 30 & \\
\hline US-N40(CX) & US-N40TE(CX) & 2 & 3 & \(7 \frac{1}{2}\) & 20 & 40 & \\
\hline US-N50(CX) & US-N50TE(CX) & 2 & 3 & \(7 \frac{1}{2}\) & 20 & 50 & \\
\hline US-N70NS & US-N70NSTE & 3 & \(7 \frac{1}{2}\) & 15 & - & 70 & \\
\hline US-N80NS & US-N80NSTE & 3 & \(7 \frac{1}{2}\) & 15 & - & 80 & \\
\hline US-NH70NS & US-NH70NSTE & 3 & \(7 \frac{1}{2}\) & 15 & 30 & 70 & \\
\hline US-NH80NS & US-NH80NSTE & 3 & \(7 \frac{1}{2}\) & 15 & 30 & 80 & \\
\hline
\end{tabular}
(17) Solid State Contactors for Heater Loads (Certification Standard CSA C22.2 No.14)
 Remarks
\begin{tabular}{|c|c|c|c|}
\hline \multicolumn{2}{|c|}{Model Name} & \multirow[t]{2}{*}{Rated Continuity Current [A]} & \multirow[t]{2}{*}{Remarks} \\
\hline Batch Control Type & Individual Control Type & & \\
\hline US-H20(RM)(HZ)(UF) & US-H20DD(RM)(HZ)(UF) & 20 & \multirow[b]{4}{*}{The standard product is certified with © (UL) us .} \\
\hline US-H30(RM)(HZ)(UF) & US-H30DD(RM)(HZ)(UF) & 30(27) (Note 4) & \\
\hline US-H40(HZ) & US-H40DD(HZ) & 40 & \\
\hline US-H50(HZ) & US-H50DD(HZ) & 50 & \\
\hline
\end{tabular}

Note 1. (HZ) has no cooling fin. (RM) can be rail-mounted.
Note 2. US-H \(\square\) (DD) HZ is certified at the rated continuity current when combined with the fin used for US-H \(\square\) (DD).
Note 3. US-H50 (DD) HZ has UR certification only.
Note 4. () is the rating for US-H30 (DD) UF.
10.5.4 Applicable Wire Size, Lug Size and Tightening Torques under UL Certification
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|}
\hline Model & \multicolumn{3}{|c|}{S-T10/S(D)-T12/T20} & \multicolumn{4}{|c|}{S(D)-T21/S-T25} & \multicolumn{2}{|c|}{S(D)-T32} \\
\hline Terminal & Main & Auxiliary & Control & \multicolumn{2}{|c|}{Main} & Auxiliary & Control & Main & Control \\
\hline Screw Size & M3.5 & M3.5 & M3.5 & \multicolumn{2}{|l|}{M4} & M3.5 & M3.5 & M4 & M3.5 \\
\hline Wire Strip Length & 10 mm & 10 mm & 9 mm & \multicolumn{2}{|c|}{11.5 mm} & 11.5 mm & 9 mm & 11.5 mm & 9 mm \\
\hline \[
\begin{aligned}
& \hline \text { Wire Size ( } 60 / 75^{\circ} \mathrm{C} \text { ) } \\
& \text { (copper only) (Sol./Str.) }
\end{aligned}
\] & 14-12 AWG & 14 AWG & 14 AWG & 14-10 AWG & 14-8 AWG & 14 AWG & 14 AWG & 14-10 AWG 8 AWG Note 1 & 14 AWG \\
\hline Recommended Crimp Lug Size (JST Cat No.) Note 2 & \[
\begin{aligned}
& 1.25-3.5 \text { to } 2-3.5 \\
& 5.5-\mathrm{S3}
\end{aligned}
\] & \[
\begin{aligned}
& 1.25-3.5 \text { to } \\
& 2-3.5
\end{aligned}
\] & \[
\begin{aligned}
& 1.25-3.5 \text { to } \\
& 2-3.5
\end{aligned}
\] & \[
1.25-4 \text { to } 5.5-
\] & \[
\begin{gathered}
\hline 1.25-4 \text { to } 5.5- \\
4 \\
8-\mathrm{NK} 4
\end{gathered}
\] & \[
\begin{aligned}
& 1.25-3.5 \text { to } \\
& 2-3.5
\end{aligned}
\] & \[
\begin{aligned}
& 1.25-3.5 \text { to } \\
& 2-3.5
\end{aligned}
\] & \[
\begin{aligned}
& 1.25-4 \text { to } \\
& 5-5.4 \\
& 8-N K 4
\end{aligned}
\] & \[
\begin{gathered}
1.25-3.5 \text { to } \\
2-3.5
\end{gathered}
\] \\
\hline Connection to Terminal Max. qty. & \multicolumn{9}{|c|}{Each Terminal - 2 Wires or 2 Crimp Lugs note 3} \\
\hline Tightening Torque & \[
\begin{gathered}
10.3 \mathrm{lb}-\mathrm{in} \\
(1.17 \mathrm{~N} \cdot \mathrm{~m}) \\
\hline
\end{gathered}
\] & \[
\begin{aligned}
& 10.3 \mathrm{lb}-\mathrm{in} \\
& (1.17 \mathrm{~N} \cdot \mathrm{~m}) \\
& \hline
\end{aligned}
\] & \[
\begin{aligned}
& 10.3 \mathrm{lb}-\mathrm{in} \\
& (1.17 \mathrm{~N} \cdot \mathrm{~m}) \\
& \hline
\end{aligned}
\] & \multicolumn{2}{|l|}{\[
\begin{gathered}
15 \mathrm{lb}-\mathrm{in} \\
(1.69 \mathrm{~N} \cdot \mathrm{~m}) \\
\hline
\end{gathered}
\]} & \[
\begin{aligned}
& 10.3 \mathrm{lb}-\mathrm{in} \\
& (1.17 \mathrm{~N} \cdot \mathrm{~m}) \\
& \hline
\end{aligned}
\] & \[
\begin{aligned}
& 10.3 \mathrm{lb}-\mathrm{in} \\
& (1.17 \mathrm{~N} \cdot \mathrm{~m}) \\
& \hline
\end{aligned}
\] & \[
\begin{gathered}
15 \mathrm{lb}-\mathrm{in} \\
(1.69 \mathrm{~N} \cdot \mathrm{~m}) \\
\hline
\end{gathered}
\] & \[
\begin{aligned}
& 10.3 \mathrm{lb}-\mathrm{in} \\
& (1.17 \mathrm{~N} \cdot \mathrm{~m}) \\
& \hline
\end{aligned}
\] \\
\hline
\end{tabular}

Note 1. When using 8 AWG with a three-phase AC200 to 208 V , use a copper wire with wire temperature rating of \(75^{\circ} \mathrm{C}\).
Note 2. Please use swaging tool which is recommended by JST.
Note 3. 2 conductors of the same size can be connected.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline Model & \multicolumn{3}{|c|}{S(D)-T35/T50} & \multicolumn{4}{|c|}{S(D)-T65/T80} & \multicolumn{3}{|c|}{S(D)-T100} \\
\hline Terminal & Main & Auxiliary & Control & \multicolumn{2}{|c|}{Main} & Auxiliary & Control & Main & Auxiliary & Control \\
\hline Screw Size & M5 & M3.5 & M3.5 & \multicolumn{2}{|c|}{M6} & M4 & M4 & M6 & M4 & M4 \\
\hline Wire Strip Length & 15 mm & 11.5 mm & 9 mm & \multicolumn{2}{|c|}{-} & 11 mm & 11 mm & - & 11 mm & 11 mm \\
\hline Wire Size (60/75 \(\left.{ }^{\circ} \mathrm{C}\right)\) (copper only) (Sol./Str.) & \[
\begin{gathered}
\text { 14-6 AWG } \\
\text { Note } 1
\end{gathered}
\] & 14 AWG & 14 AWG & 14-2 AWG & \[
\underset{\substack{14-1 \mathrm{AWGG} \\ \text { Note 2 }}}{ }
\] & 14 AWG & 14 AWG & \[
\underset{\substack{\text { Note } 3}}{14-1 / 0 \text { AWG }}
\] & 14 AWG & 14 AWG \\
\hline Recommended Crimp Lug Size (JST Cat No.) Note 4 & \[
\begin{aligned}
& 1.25-5 \text { to } \\
& 14-5
\end{aligned}
\] & 1.25-3.5 to 2-3.5 & \[
\begin{gathered}
1.25-3.5 \text { to } \\
2-3.5
\end{gathered}
\] & \[
\left.\right|_{22-6} ^{1.25-6} \text { to }
\] & \[
\begin{gathered}
1.25-6 \text { to } \\
22-6 \\
38-\mathrm{S} 6
\end{gathered}
\] & 1.25-4 to 2-4 & 1.25-4 to 2-4 & \[
\begin{array}{|c|}
\hline 1.25-6 \text { to } 22-6 \\
38-\mathrm{S6}, 60-6
\end{array}
\] & 1.25-4 to 2-4 & 1.25-4 to 2-4 \\
\hline Connection to Terminal Max. qty. & \multicolumn{10}{|c|}{Each Terminal - 2 Wires or 2 Crimp Lugs Note 5} \\
\hline Tightening Torque & \[
\begin{aligned}
& 22.5 \mathrm{lb}-\mathrm{in} \\
& (2.54 \mathrm{~N} \cdot \mathrm{~m})
\end{aligned}
\] & \[
\begin{aligned}
& 10.3 \mathrm{lb}-\mathrm{in} \\
& (1.17 \mathrm{~N} \cdot \mathrm{~m})
\end{aligned}
\] & \[
\begin{aligned}
& 10.3 \mathrm{lb}-\mathrm{in} \\
& (1.17 \mathrm{~N} \cdot \mathrm{~m})
\end{aligned}
\] & & & \[
\begin{gathered}
15 \mathrm{lb}-\mathrm{in} \\
(1.69 \mathrm{~N} \cdot \mathrm{~m})
\end{gathered}
\] & \[
\begin{gathered}
15 \mathrm{lb}-\mathrm{in} \\
(1.69 \mathrm{~N} \cdot \mathrm{~m})
\end{gathered}
\] & \[
\begin{aligned}
& 39.1 \mathrm{lb}-\mathrm{in} \\
& (4.41 \mathrm{~N} \cdot \mathrm{~m})
\end{aligned}
\] & \[
\begin{gathered}
15 \mathrm{lb}-\mathrm{in} \\
(1.69 \mathrm{~N} \cdot \mathrm{~m})
\end{gathered}
\] & \[
\begin{gathered}
15 \mathrm{lb}-\mathrm{in} \\
(1.69 \mathrm{~N} \cdot \mathrm{~m}) \\
\hline
\end{gathered}
\] \\
\hline
\end{tabular}

Note 1. When using 6 AWG, use a copper wire with wire temperature rating of \(75^{\circ} \mathrm{C}\).
Note 2. When using 1 AWG, use a copper wire with wire temperature rating of \(75^{\circ} \mathrm{C}\).
Note 3 . When using \(1 / 0\) AWG, use a copper wire with wire temperature rating of \(75^{\circ} \mathrm{C}\).
Note 4. Please use swaging tool which is recommended by JST.
Note 5. Two conductors of the same size can be connected.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline Model & \multicolumn{2}{|l|}{TH-T18KP} & \multicolumn{2}{|r|}{TH-T25KP} & \multicolumn{2}{|r|}{TH-T50KP} & \multicolumn{2}{|r|}{TH-T65KP} & \multicolumn{2}{|l|}{TH-T100KP} & \multicolumn{2}{|c|}{SR(D)-T5} \\
\hline Terminal & Main & Auxiliary & Main & Auxiliary & Main & Auxiliary & Main & Auxiliary & Main & Auxiliary & Auxiliary & Control \\
\hline Screw Size & M3.5 & M3.5 & M4 & M3.5 & M5 & M3.5 & M6 & M4 & M6 & M4 & M3.5 & M3.5 \\
\hline Wire Strip Length & 10.5 mm & 10.5 mm & 10 mm & 10.5 mm & 13.5 mm & 10.5 mm & - & 11 mm & - & 11 mm & 10 mm & 9 mm \\
\hline Wire Size \(\left(60 / 75^{\circ} \mathrm{C}\right)\) (copper only) (Sol./Str.) & \begin{tabular}{l}
14-12 \\
AWG Note 1
\end{tabular} & 14 AWG & \[
\begin{aligned}
& 14-8 \\
& \text { AWG }
\end{aligned}
\] & 14 AWG & \[
\underset{\text { Note 2 }}{14-6 \mathrm{AWG}}
\] & 14 AWG & 14-3 AWG & 14 AWG & \[
\underset{\text { Note } 3}{14-1} \mathrm{AWG}
\] & 14 AWG & 14 AWG & 14 AWG \\
\hline Recommended Crimp Lug Size (JST Cat No.) Note 4 & \[
\begin{gathered}
1.25-3.5 \text { to } 0-3.5 \\
5.5-S 3 \\
\hline
\end{gathered}
\] & \[
\begin{aligned}
& 1.25-3.5 \\
& \text { to } 2-3.5
\end{aligned}
\] & \[
\begin{gathered}
1.25-4 \text { to } 5.5-4 \\
8-\mathrm{NK} 4 \\
\hline
\end{gathered}
\] & \[
\begin{aligned}
& 1.25-3.5 \\
& \text { to } 2-3.5
\end{aligned}
\] & 1.25-5 to 14-5 & \[
\begin{aligned}
& 1.25-3.5 \\
& \text { to } 2-3.5
\end{aligned}
\] & \[
\begin{aligned}
& 2-6 \text { to } \\
& 22-6
\end{aligned}
\] & \[
\begin{gathered}
1.25-4 \text { to } \\
2-4
\end{gathered}
\] & \[
\begin{aligned}
& 2-6 \text { to } \\
& 22-6
\end{aligned}
\] & \[
\begin{gathered}
1.25-4 \text { to } \\
2-4
\end{gathered}
\] & \[
\begin{aligned}
& 1.25-3.5 \\
& \text { to } 2-3.5
\end{aligned}
\] & \[
\begin{aligned}
& 1.25-3.5 \\
& \text { to } 2-3.5
\end{aligned}
\] \\
\hline Connection to Terminal Max. qty. & \multicolumn{12}{|c|}{Each Terminal - 2 Wires or 2 Crimp Lugs Note 5} \\
\hline Tightening Torque & \[
\begin{array}{|c|}
\hline 10.3 \mathrm{lb}-\mathrm{in} \\
(1.17 \mathrm{~N} \cdot \mathrm{~m})
\end{array}
\] & \[
\begin{array}{l|}
\hline 10.3 \mathrm{lb}-\mathrm{in} \\
(1.17 \mathrm{~N} \cdot \mathrm{~m})
\end{array}
\] & \[
\begin{array}{|c|}
\hline 15 \mathrm{lb}-\mathrm{in} \\
(1.69 \mathrm{~N} \cdot \mathrm{~m})
\end{array}
\] & \[
\begin{array}{|c|}
\hline 10.3 \mathrm{Ib}-\mathrm{in} \\
(1.17 \mathrm{~N} \cdot \mathrm{~m})
\end{array}
\] & \[
\begin{array}{|l|}
\hline 22.5 \mathrm{Ib}-\mathrm{in} \\
(2.54 \mathrm{~N} \cdot \mathrm{~m})
\end{array}
\] & \[
\begin{aligned}
& 10.3 \mathrm{lb}-\mathrm{in} \\
& (1.17 \mathrm{~N} \cdot \mathrm{~m})
\end{aligned}
\] & \[
\begin{array}{|c|}
\hline 39.1 \mathrm{Ib}-\mathrm{in} \\
(4.41 \mathrm{~N} \cdot \mathrm{~m})
\end{array}
\] & \[
\begin{array}{|c|}
\hline 15 \mathrm{lb}-\mathrm{in} \\
(1.69 \mathrm{~N} \cdot \mathrm{~m})
\end{array}
\] & \[
\begin{array}{|c|}
\hline 39.1 \mathrm{Ib}-\mathrm{in} \\
(4.41 \mathrm{~N} \cdot \mathrm{~m})
\end{array}
\] & \[
\begin{gathered}
15 \mathrm{lb}-\mathrm{in} \\
(1.69 \mathrm{~N} \cdot \mathrm{~m})
\end{gathered}
\] & \[
\begin{aligned}
& 10.3 \mathrm{lb}-\mathrm{in} \\
& (1.17 \mathrm{~N} \cdot \mathrm{~m})
\end{aligned}
\] & \[
\begin{aligned}
& \hline 10.3 \mathrm{lb}-\mathrm{in} \\
& (1.17 \mathrm{~N} \cdot \mathrm{~m})
\end{aligned}
\] \\
\hline
\end{tabular}

Note 1. The applicable current for the heater designation 15A is 16 A or less.
Note 2. When using 6 AWG, use a copper wire with wire temperature rating of \(75^{\circ} \mathrm{C}\)
Note 3 . Use copper wire with wire temperature rating of \(75^{\circ} \mathrm{C}\).
Note 4. Please use swaging tool which is recommended by JST.
Note 5.2 conductors of the same size can be connected.

\section*{Application to Domestic and International Standards}

\subsection*{10.6 Compliance with EC Directives}

Compliance with EC Directives of Magnetic Starters Used as Components
Although the CE marking is required in order to distribute the magnetic starter within the EU for component use compliant with the EC Directives, when displaying the CE marking on machine tools, control devices or the like, it is not required for the magnetic starter as an embedded component.
When displaying the CE marking on machine tools, control devices or the like, the use of third party certification (TÜV certification) is recommended for the magnetic starter. As shown on page 282, the MS-T/N Series magnetic starters, SD-Q Series DC interface contactors and the like are TÜV certified.

\section*{- Compliance with Low Voltage Directive}

Compliance of Magnetic Starters in Single Exports
In single exports to the EU, magnetic starters are subject to the Low Voltage Directive. The Low Voltage Directive is module A and the compliance certificate is basically carried out by self-declaration; the applicable product specifications are as follows. EN-60947-4-1 Magnetic Starter Standards
EN-60947-5-1 Contactor Relay Standards
As shown on page 281, MS-T/N series magnetic starters, SD-Q Series DC interface contactors and the like are standard products and comply with the Low Voltage Directive.

\section*{- Compliance with EMC Directives}

As the MS-T/N series magnetic starter does not incorporate an internal electronic circuit, it is outside the scope of the EMC Directive.
(As the DC exciting circuits of S-T65 to T100 and S-N125 to N800 are simple rectifier circuits, they are EMC-excluded items.) The solid state contactor US-N/H is subject to the EMC Directive.

\section*{- Compliance with RoHS Directive}

In single exports to the EU, magnetic starters are subject to the RoHS Directive. (Category 9 "Monitoring and control equipment" of the RoHS Directive applies to the products). Six substances (lead, mercury, cadmium, hexavalent chromium, PBB, and PBDE) are restricted under the revised RoHS Directive (2011/65/EU commonly known as RoHS 2). As shown on page 281, MS-T/N series magnetic starters, SD-Q Series DC interface contactors, and the like are standard products and comply with the RoHS Directive.
Note that, US-N(H)70/N(H)80(TE) types containing restricted substances, cannot be exported as single products, but can be exported as spare parts to which the RoHS Directive does not apply.
In the official gazette Directive (EU) 2015/863 published in June 2015, four phthalates were newly added, totaling 10 substances under restriction. Magnetic starters are subject to RoHS 2 from July 22, 2021. However, to meet the needs of the customers who manufacture the products of category 1 to 7,10 , and 11 , such as household appliances, to which RoHS 2 starts to apply from July 22, 2019, we have been manufacturing products not containing the four additional substances since January, 2019. For the models compliant with RoHS 2, consult with your dealer or with us.

\section*{- Compliance with Machinery Directive}
(1) The MS-T/N series magnetic starter is a component used in equipment such as machine tools and control devices, and is outside the scope of the Machinery Directive.
(2) With respect to EN60204-2, the safety standards for mechanical equipment, compliances are as below.
\begin{tabular}{c|l|l|l}
\hline \multicolumn{1}{c|}{ Item } & Requirements & \multicolumn{1}{c|}{ Request Content } & \multicolumn{1}{c}{ Support } \\
\hline \begin{tabular}{c} 
Control Function in \\
Case of Failure
\end{tabular} & 9.4 & \begin{tabular}{l} 
If the failure of an electrical device would lead to hazardous \\
conditions, take appropriate measures to minimize the probability \\
of such risks.
\end{tabular} & \begin{tabular}{l} 
A magnetic contactor \\
with mirror contact (safety \\
separation function) is \\
available (*)
\end{tabular} \\
\cline { 2 - 4 } & 9.4 .2 .2 & \begin{tabular}{l} 
Provide redundancy. \\
The probability of a single failure of an electric circuit causing a \\
serious risk can be minimized by providing partial or total redundancy. \\
(The safety circuit will turn off if one of the relays fails. The relay \\
status (normal or otherwise) will be checked at each on/off cycle \\
of the machine. Cannot restart when one of the relays fails.
\end{tabular} & \\
\hline
\end{tabular}

\footnotetext{
* The mirror contact is a function in which even if the main contact is welded, the auxiliary break contact withstands the impulse voltage of 2500 V without contact.
}

\section*{Low Voltage Directive/RoHS Directive Compatible Models and CE Marking Display Locations}
\begin{tabular}{|c|c|c|}
\hline Model & Model Name & Display Location \\
\hline Magnetic Contactors (AC Operated) & \[
\begin{aligned}
& \text { S-(2x)T10(BC)(SA), S-(2x)T12(BC)(SA)(SQ) } \\
& \text { S-(2x)T20(BC)(SA)(SQ), S-(2x)T21(BC)(SA) } \\
& \text { S-(2x)T25(BC)(SA), S-(2x)T32(BC)(SA) } \\
& \text { S-(2x)T35(BC)(SA), S-(2x)T50(BC)(SA) } \\
& \text { S-(2x)T65, S-(2x)T80, S-(2x)T100 } \\
& \text { S-(2x)N38(CX)(SA), S-(2x)N48(CX)(SA) } \\
& \text { S-(2x)N125, S-(2x)N150 } \\
& \text { S-(2x)N180, S-(2x)N220, S-(2x)N300, S-(2x)N400, S-(2x)N600, S-(2x)N800 }
\end{aligned}
\] & \multirow{12}{*}{Displayed on the product name plate (Note 2)} \\
\hline Magnetic Starters (AC Operated) & ```
MSO-(2x)T10(BC)KP(SA), MSO-(2x)T12(BC)KP(SA)
MSO-(2x)T20(BC)KP(SA), MSO-(2x)T21(BC)KP(SA)
MSO-(2x)T25(BC)KP(SA)
MSO-(2x)T35(BC)KP(SA), MSO-(2x)T50(BC)KP(SA)
MSO-(2x)T65KP, MSO-(2x)T80KP, MSO-(2x)T100KP
MSO-(2x)N125KP, MSO-(2x)N150KP,
MSO-(2x)N180KP, MSO-(2x)N220KP, MSO-(2x)N300KP, MSO-(2x)N400KP
``` & \\
\hline Thermal Overload Relays & \begin{tabular}{l}
TH-T18(BC)KP, TH-T25(BC)KP, TH-T50(BC)KP, TH-T65KP, TH-T100KP TH-N120KP, TH-N120TAKP, \\
TH-N220RHKP, TH-N220HZKP, TH-N400RHKP, TH-N400HZKP
\end{tabular} & \\
\hline Contactor Relays (AC Operated) & SR-T5(BC)(SA)(SQ), SR-T9(BC)(SA) & \\
\hline Auxiliary Contact Unit & \begin{tabular}{l}
UT-AX2(BC), UT-AX4(BC), UT-AX11(BC) \\
UN-AX2(CX), UN-AX4(CX), UN-AX11(CX), UN-AX80, UN-AX150, UQ-AX2(KR)
\end{tabular} & \\
\hline Magnetic Contactors (DC Operated) & \[
\begin{aligned}
& \text { SD-(2x)T12(BC)(SA)(SQ), SD-(2x)T20(BC)(SA)(SQ), SD-(2x)T21(BC)(SA), } \\
& \text { SD-(2x)T32(BC)(SA), SD-(2x)T35(BC)(SA), SD-(2x)T50(BC)(SA), } \\
& \text { SD-(2x)T65, SD-(2x)T80, SD-(2x)T100 } \\
& \text { SD-(2x)N125, SD-(2x)N150, SD-(2x)N220, } \\
& \text { SD-(2x)N300, SD-(2x)N400, SD-(2x)N600, SD-(2x)N800 }
\end{aligned}
\] & \\
\hline Magnetic Starters (DC Operated) & \[
\begin{aligned}
& \text { MSOD-(2x)T12(BC)KP(SA), MSOD-(2x)T20(BC)KP(SA), MSOD-(2x)T21(BC)KP(SA), } \\
& \text { MSOD-(2x)T35(BC)KP(SA), MSOD-(2x)T50(BC)KP(SA) } \\
& \text { MSOD-(2x)T65KP, MSOD-(2x)T80KP, MSOD-(2x)T100KP } \\
& \text { MSOD-(2x)N125KP, MSOD-(2x)N150KP, MSOD-(2x)N220KP, } \\
& \text { MSOD-(2x)N300KP, MSOD-(2x)N400KP }
\end{aligned}
\] & \\
\hline Contactor Relays (DC Operated) & SRD-T5 (BC) (SA)(SQ), SRD-T9 (BC) (SA) & \\
\hline DC Interface & SD-Q11, SD-Q12, SD-QR11, SD-QR12 & \\
\hline Contactors & MSOD-Q(R)11KP, MSOD-Q(R)12KP & \\
\hline Solid State Contactors for Motor/Heater Loads & \begin{tabular}{l}
US-N5SS(TE), US-N8SS(TE), US-N20(TE), US-N30(TE), US-N40(TE), US-N50(TE), US-N70NS(TE), US-N80NS(TE), US-NH70NS(TE), US-NH80NS(TE), \\
US-N20(TE)CX, US-N30(TE)CX, US-N40(TE)CX, US-N50(TE)CX US-N20(TE)RM
\end{tabular} & \\
\hline Solid State Contactors for Heater Loads & US-H2O(DD), US-H30(DD), US-H40(DD), US-H50(DD), US-H2O(DD)RM, US-H30(DD)RM, US-H2O(DD)UF, US-H30(DD)UF & \\
\hline
\end{tabular}

Note 1. Standard products are compliant. The outline drawings, contact arrangement, rating, order model name and the like are the same as the standard product.
Note 2. As UN-AX80 and UN-AX150 have no product name plate, it is displayed on the individual product packaging.
Note 3. To keep the US-N5/N8SS (TE) and US-N (H) 70/N (H) 80NS (TE) compliant with the CE mark, use by connecting as shown in the figure below.
Note 4. US-N(H)70/N(H)80NS(TE) types contain substances restricted by the RoHS Directive and are dedicated as spare parts products within the EU region. They display CE markings as products for which the RoHS Directive does not apply.


Note: Connect the varistor (NVD05UCD039 [KOA]) in the location shown in the figure above.

Note: Connect the varistor (NVD05UCD039 [KOA]) and ferrite core
(ZCAT3035-1330 [TDK]) in the locations shown in the figure above.
Note: Connect the varistor (NVD05UCD039 [KOA]) and ferrite core
(ZCAT3035-1330 [TDK]) in the locations shown in the figure above. (Ferrite core mounting is not required for US-N70/N80 \(\square\) )


\section*{Application to Domestic and International Standards}

\subsection*{10.7 TÜV Certified Products}

\section*{TÜV Rheinland Inspection Association Certified Product}
(1) TÜV Certified Magnetic Contactor T Series (Certification Standard EN60947-4-1)
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Model Name} & \multicolumn{2}{|l|}{Certified Rating [A] (AC-3)} & \multirow[b]{2}{*}{Certification Number} & \multicolumn{2}{|l|}{Mirror Contact (Safety Separation Function) (Note 3)} & \multirow[b]{2}{*}{Remarks} \\
\hline & 220 to 240 V & 380 to 440 V & & Body Built-In Auxiliary Break Contact & Auxiliary Contact Unit Auxiliary Break Contact & \\
\hline S-T10(BC)(SA) & 11 & 9 & \multirow{3}{*}{R50255938} & O(Note 4) & \multirow{8}{*}{○ (UT-AX2(BC), UT-AX4(BC))} & \multirow{20}{*}{Standard product with the certification mark.} \\
\hline S-T12(BC)(SA)(SQ) & 13 & 12 & & \multirow{4}{*}{\(\bigcirc\)} & & \\
\hline S-T20(BC)(SA)(SQ) & 18 & 18 & & & & \\
\hline S-T21(BC)(SA) & 25 & 23 & \multirow{3}{*}{R50255941} & & & \\
\hline S-T25(BC)(SA) & 30 & 30 & & & & \\
\hline S-T32(BC)(SA) & 32 & 32 & & - & & \\
\hline S-T35(BC)(SA) & 40 & 40 & R50319775 & \multirow{4}{*}{\(\bigcirc\)} & & \\
\hline S-T50(BC)(SA) & 55 & 50 & R5031977 & & & \\
\hline S-T65(CW) & 65 & 65 & \multirow[t]{2}{*}{R50319817} & & \(\bigcirc\) & \\
\hline S-T80(CW) & 85 & 85 & & & (UN-AX2(BC), UN-AX4(BC)) & \\
\hline S-T100 & 105 & 105 & R9851138 & \(\bigcirc\) & - & \\
\hline SD-T12(BC)(SA)(SQ) & 13 & 12 & R50255938 & \multirow{3}{*}{\(\bigcirc\)} & \multirow{6}{*}{\begin{tabular}{l}
\(\bigcirc\) \\
(UT-AX2(BC), UT-AX4(BC))
\end{tabular}} & \\
\hline SD-T20(BC)(SA)(SQ) & 18 & 18 & & & & \\
\hline SD-T21(BC)(SA) & 25 & 23 & \multirow[t]{2}{*}{R50255941} & & & \\
\hline SD-T32(BC)(SA) & 32 & 32 & & - & & \\
\hline SD-T35(BC)(SA) & 40 & 40 & R50319775 & \multirow{4}{*}{\(\bigcirc\)} & & \\
\hline SD-T50(BC)(SA) & 55 & 50 & R50319775 & & & \\
\hline SD-T65(CW) & 65 & 65 & \multirow[t]{2}{*}{R50319817} & & \(\bigcirc\) & \\
\hline SD-T80(CW) & 85 & 85 & & & (UN-AX2(BC), UN-AX4(BC)) & \\
\hline SD-T100 & 105 & 105 & R9851138 & \(\bigcirc\) & - & \\
\hline
\end{tabular}

Note 1. Certification Rating: Certified in the following range.
Main Circuit Contact : 440 V or Less at AC-3 Rating and Rated Continuity Current
Auxiliary Contact : 550 V or Less at AC-15 Rating and Rated Continuity Current
Operation Coil
\begin{tabular}{lll}
\(:\) AC Operation & S-T10 to T80 & : AC24V Coil to AC500V Coil \\
& S-T100 & : AC24V Coil to AC500V Coil \\
DC Operation & & : DC12V Coil to DC220V Coil
\end{tabular}

Note 2. The specification of the surge absorber mounting type (with "SA" in the model name) is also TÜV certified.
Note 3. Mirror contact compliance acquired from TÜV, making it optimal for the interlock circuit of machine tools. The mirror contact indicates a function in which even if the main contact is welded, the auxiliary break contact withstands impulse voltage of \(2,500 \mathrm{~V}\) without contact.
Note 4. When ordering \(S-T 10(B C)(S A)\) with \(1 b\), indicate that it is with \(1 b\).
(2) TÜV Certified Magnetic Contactor N Series (Certification Standard EN60947-4-1)
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Model Name} & \multicolumn{2}{|l|}{Certified Rating [A] (AC-3)} & \multirow[b]{2}{*}{Certification Number} & \multicolumn{2}{|l|}{Mirror Contact (Safety Separation Function) (Note 3)} & \multirow[b]{2}{*}{Remarks} \\
\hline & 220 to 240 V & 380 to 440 V & & \begin{tabular}{|c|}
\hline Body Built-In \\
Auxiliary Break Contact \\
\hline
\end{tabular} & Auxiliary Contact Unit Auxiliary Break Contact & \\
\hline S-N38(CX)(SA) & 39 & 32 & \multirow[b]{2}{*}{R9651189} & \multirow[t]{2}{*}{-} & \multirow[t]{2}{*}{-} & \multirow{13}{*}{Standard product with the certification mark.} \\
\hline S-N48(CX)(SA) & 50 & 40 & & & & \\
\hline S-N125 & 125 & 120 & R9851169 & \(\bigcirc\) & - & \\
\hline S-N150 & 150 & 150 & R9851167 & \multirow{5}{*}{\(\bigcirc\)} & \multirow{5}{*}{(UN-AX150)} & \\
\hline S-N180 & 180 & 180 & R9851164 & & & \\
\hline S-N220 & 250 & 250 & R9851164 & & & \\
\hline S-N300 & 300 & 300 & \multirow[t]{2}{*}{R9851171} & & & \\
\hline S-N400 & 400 & 400 & & & & \\
\hline SD-N125 & 125 & 120 & R9851169 & \(\bigcirc\) & - & \\
\hline SD-N150 & 150 & 150 & R9851167 & \multirow{4}{*}{\(\bigcirc\)} & \multirow{4}{*}{(UN-AX150)} & \\
\hline SD-N220 & 250 & 250 & R9851164 & & & \\
\hline SD-N300 & 300 & 300 & \multirow[t]{2}{*}{R9851171} & & & \\
\hline SD-N400 & 400 & 400 & & & & \\
\hline
\end{tabular}

Note 1. Certification Rating: Certified in the following range.
Main Circuit Contact : 440 V or Less at AC-3 Rating and Rated Continuity Current
Auxiliary Contact : 550 V or Less at AC-15 Rating and Rated Continuity Current
Operation Coil
\begin{tabular}{lll} 
: AC Operation & S-N38, N48 & : AC24V Coil to AC440V Coil \\
& S-N125 to N150 & : AC24V Coil to AC500V Coil \\
& S-N180 to N400 & : AC48V Coil to AC500V Coil \\
DC Operation & & : DC12V Coil to DC220V Coil
\end{tabular}

Note 2. The specification of the surge absorber mounted type (with "SA" in the model name) is also TÜV certified.
Note 3. Mirror contact compliance acquired from TÜV, making it optimal for the interlock circuit of machine tools. The mirror contact indicates a function in which even if the main contact is welded, the auxiliary break contact withstands impulse voltage of \(2,500 \mathrm{~V}\) without contact.
(3) TÜV Certified DC Interface Contactor (Certification Standard: EN60947-4-1)
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Model Name} & \multicolumn{2}{|l|}{Certified Rating [A] (AC-3)} & \multirow[b]{2}{*}{Certification Number} & \multicolumn{2}{|l|}{Mirror Contact (Safety Separation Function) (Note 2)} & \multirow[b]{2}{*}{Remarks} \\
\hline & 220 to 240 V & 380 to 440 V & & Body Built-In Auxiliary Break Contact & Auxiliary Contact Unit Auxiliary Break Contact & \\
\hline SD-Q11 & 12 & 9 & R50004919 & O(Note 1) & O(UQ-AX2) & \multirow{4}{*}{Standard product and certified.} \\
\hline SD-Q12 & 12 & 9 & R50004919 & \(\bigcirc\) & - & \\
\hline SD-QR11 & 12 & 9 & R50004919 & - & - & \\
\hline SD-QR12 & 12 & 9 & R50004919 & - & - & \\
\hline
\end{tabular}

Note 1. When ordering SD-Q11 with 1b, indicate that it is with 1 b .
Note 2. The O marked products have acquired mirror contact compliance from TÜV, making them optimal for the interlock circuit of machine tools. The mirror contact indicates a function in which even if the main contact is welded, the auxiliary break contact withstands impulse voltage of \(2,500 \mathrm{~V}\) without contact.
(4) TÜV Certified Thermal Overload Relay T Series (Certification Standard EN60947-4-1)
\begin{tabular}{l|c|c}
\hline \multicolumn{1}{c|}{ Model Name } & Certification Number & Remarks \\
\cline { 1 - 2 } TH-T18(AR)(BC)KP(YS) & R50257058 & \multirow{3}{*}{} \\
\cline { 1 - 2 } TH-T25(AR)(BC)KP(YS) & R50257062 & \multirow{3}{*}{ Standard product } \\
and certified.
\end{tabular}
(6) TÜV Certified Auxiliary Contact Unit T Series (Certification Standard EN60947-5-1)
\begin{tabular}{l|c|c}
\hline Model Name & Certification Number & \multicolumn{1}{c}{ Remarks } \\
\hline UT-AX2(BC) & R50255937 & \multirow{2}{*}{\begin{tabular}{l} 
Standard product \\
and certified.
\end{tabular}} \\
\hline UT-AX4(BC) & R50255937 & \\
\hline UT-AX11(BC) & R50255937 & \\
\hline
\end{tabular}

Note 1. The AC-15 rating of 550 V or less and conventional free air thermal current are certified.
(5) TÜV Certified Thermal Overload Relay N Series (Certification Standard EN60947-4-1)
\begin{tabular}{|c|c|c|}
\hline Model Name & Certification Number & Remarks \\
\hline TH-N120KP & J9851168 & \multirow{6}{*}{Standard product and certified.} \\
\hline TH-N120TAKP & J9851168 & \\
\hline TH-N220RHKP & J9851166 & \\
\hline TH-N220HZKP & J9851166 & \\
\hline TH-N400RHKP & J9851172 & \\
\hline TH-N400HZKP & \(J 9851172\) & \\
\hline
\end{tabular}

Note 1. The thermal overload relay is TÜV certified for use in combination with magnetic contactors. (Excluding TH-N220/N400HZKP)
Note 2. TH-N120KP and N120TAKP are certified in combination with the UN-CZ live part protection cover.
(7) TÜV Certified Auxiliary Contact Unit N Series (Certification Standard EN60947-5-1)
\begin{tabular}{l|c|c}
\hline Model Name & Certification Number & Remarks \\
\cline { 1 - 2 } UN-AX2(CX) & J9551337 & \\
\cline { 1 - 2 } UN-AX4(CX) & J9551337 & \\
\cline { 1 - 2 } UN-AX11(CX) & \multirow{2}{*}{ Standard product } \\
\cline { 1 - 2 } UN-AX80 & R9551337 certified. \\
\cline { 1 - 2 } UN-AX150 & R9851225 & \\
\cline { 1 - 2 } UQ-AX2 & R50004919 & \\
\hline
\end{tabular}

Note 1. The AC-15 rating of 550 V or less ( 440 V or less for UQ-AX2) and conventional free air thermal current are certified.
Note 2. The auxiliary contact unit is TÜV certified for use in combination with magnetic contactors (or contactor relays).

\section*{Application to Domestic and International Standards}
(8) TÜV Certified Contactor Relay T Series (Certification Standard EN60947-5-1)
\begin{tabular}{|c|c|c|c|c|c|}
\hline Model Name & Certification Number & Remarks & Model Name & Certification Number & Remarks \\
\hline SR-T5(BC)(SA)(SQ) & R50255933 & \multirow[t]{2}{*}{Standard product and certified.} & SRD-T5(BC)(SA)(SQ) & R50255933 & \multirow[t]{2}{*}{Standard product and certified.} \\
\hline SR-T9(BC)(SA) & R50255933 & & SRD-T9(BC)(SA) & R50255933 & \\
\hline
\end{tabular}

Note 1. The AC-15 rating of 550 V or less and conventional free air thermal current are certified.
Note 2. The operation coil designations to be applied are AC24V to AC500V (alternating current) and DC12V to DC220V (direct current). Note 3. The specification of the surge absorber mounted type (with "SA" in the model name) is also TÜV certified.
(9) TÜV Certified Solid State Contactor for Motor/Heater Loads (Certification Standards EN60947-4-2/EN60947-4-3)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{5}{|c|}{Frame} & \multirow[t]{2}{*}{\[
\begin{gathered}
\text { N5SS } \\
(\mathrm{TE})
\end{gathered}
\]} & \multirow[t]{2}{*}{\begin{tabular}{l}
N8SS \\
(TE)
\end{tabular}} & \multirow[t]{2}{*}{\[
\begin{aligned}
& \text { N20 } \\
& \text { (TE) }
\end{aligned}
\]} & \multirow[t]{2}{*}{\[
\begin{aligned}
& \text { N30 } \\
& \text { (TE) }
\end{aligned}
\]} & \multirow[t]{2}{*}{\begin{tabular}{l}
N40 \\
(TE)
\end{tabular}} & \multirow[t]{2}{*}{\[
\begin{aligned}
& \text { N50 } \\
& \text { (TE) }
\end{aligned}
\]} & \multirow[t]{2}{*}{N70NS (TE)} & \multirow[t]{2}{*}{N80NS (TE)} & \multirow[t]{2}{*}{NH70NS (TE)} & \multirow[t]{2}{*}{NH80NS (TE)} \\
\hline & Load & Category & Voltage & Anderitenceative & & & & & & & & & & \\
\hline \multirow{6}{*}{Certified Rating (A)} & \multirow{4}{*}{Heater} & \multirow{4}{*}{AC-51} & \multirow[t]{2}{*}{AC100 to 240 V} & \(40^{\circ} \mathrm{C}\) & 5 & 8 & 20 & 30 & 40 & 50(45) & 70 & 80 & - & - \\
\hline & & & & \(60^{\circ} \mathrm{C}\) & 3 & 4.8 & 12 & 18 & 24 & 30(27) & 42 & 48 & - & - \\
\hline & & & \multirow[t]{2}{*}{AC200 to 400 V} & \(40^{\circ} \mathrm{C}\) & - & - & 20 & 30 & 40 & 50(45) & - & - & 65 & 75 \\
\hline & & & & \(60^{\circ} \mathrm{C}\) & - & - & 12 & 18 & 24 & 30(27) & - & - & 39 & 45 \\
\hline & \multirow{2}{*}{Motor} & \multirow{2}{*}{AC-53} & AC200 to 240V & \(40^{\circ} \mathrm{C}\) & 3.2 & 3.2 & 11.1 & 17.4 & 26 & 26 & 48 & 48 & 48 & 48 \\
\hline & & & AC400 to 440V & \(40^{\circ} \mathrm{C}\) & - & - & 11.1 & 17.4 & 26 & 26 & - & - & 48 & 48 \\
\hline \multirow{3}{*}{Type} & \multicolumn{2}{|l|}{Standard Product} & \multicolumn{2}{|c|}{US- \(\square\)} & \multicolumn{2}{|l|}{R50037627} & \multicolumn{4}{|c|}{R50037628} & \multicolumn{2}{|l|}{R50037629} & \multicolumn{2}{|l|}{R50037630} \\
\hline & \multicolumn{2}{|l|}{CAN Terminal Product} & \multicolumn{2}{|c|}{US-■CX} & \multicolumn{2}{|c|}{-} & \multicolumn{4}{|c|}{R50037628} & \multicolumn{4}{|c|}{-} \\
\hline & \multicolumn{2}{|l|}{Rail Mounting Product} & \multicolumn{2}{|c|}{US-■RM} & \multicolumn{2}{|c|}{-} & R50037628 & \multicolumn{3}{|c|}{-} & \multicolumn{4}{|c|}{-} \\
\hline
\end{tabular}

Note 1. The number in the Type column represents the certification number and "-" indicates no corresponding model.
Note 2. The value in the certified rating column () represents the rating for US-N50TE.
Note 3. The frame column (TE) represents the main circuit 3-pole 3-element type.
Note 4. TÜV mark is displayed on the product body (name plate).
(10) TÜV Certified Solid State Contactor for Heater Load (Certification Standards EN60947-4-3)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{5}{|c|}{Frame} & \multirow[b]{2}{*}{H20(DD)} & \multirow[b]{2}{*}{H30(DD)} & \multirow[b]{2}{*}{H40(DD)} & \multirow[b]{2}{*}{H50(DD)} \\
\hline & Load & Category & Voltage & Ambeititenpadue & & & & \\
\hline Certified & \multirow[t]{2}{*}{Heater} & \multirow{2}{*}{AC-51} & AC24 to & \(40^{\circ} \mathrm{C}\) & 20 & 30 & 40 & 50 \\
\hline Rating (A) & & & 480 V & \(60^{\circ} \mathrm{C}\) & 12 & 18 & 24 & 30 \\
\hline \multirow{4}{*}{Type} & \multicolumn{2}{|l|}{Standard Product} & \multicolumn{2}{|c|}{US- \(\square\)} & & & & \\
\hline & \multicolumn{2}{|l|}{No Cooling Fin} & \multicolumn{2}{|c|}{US-■HZ} & & & & \\
\hline & \multicolumn{2}{|l|}{Rail Mounting Product} & \multicolumn{2}{|r|}{US-DRM} & & & & \\
\hline & \multicolumn{2}{|l|}{Width Reduced Product} & \multicolumn{2}{|c|}{US-■UF} & & & & \\
\hline
\end{tabular}

Note 1. The number in the Type column represents the certification number and "-" indicates no corresponding model.
Note 2. The frame column (DD) represents the individual control.
Note 3. TÜV mark is displayed on the product body (name plate).

\section*{10．8 CCC Certified Products（China）}

Magnetic starters are specified as a China Compulsory Certification Practice product，which requires CCC certification for export from Japan to China and for marketing in China．
For the detailed specifications of combinable symbols（application range field of the model name \(* *\) ）shown on page 289， refer to page 34．When ordering standard products other than certified models（O marked products in the table below）， always add＂CN＂at the end of the model name to specify．The solid state contactor US－H \(\square\) for heater load and optional units（UN－CV，ML，RR，SA，etc．）that are used by attaching to a magnetic starter and are without load switching function are not subject to CCC certification．
In China，the＂Energy Efficiency Labeling Management Regulation＂has been implemented for the purpose of improving energy efficiency，which applies to the AC operated AC magnetic contactor（rated operational vpltage： \(380 \mathrm{~V}(400 \mathrm{~V}\) ），rated operating current： 6 to 630 A ）．
Export to China and／or sale of these products in China will require an energy efficiency label．
If these products are to be indirectly exported to China，consult with your dealer or with us．

\section*{10．8．1 CCC Certified Model Name List}
－Non－Reversible Magnetic Starter，Magnetic Contactor T Series
© ：Standard product and certified，\(\square\) ：Out of production range
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline & \multirow[b]{2}{*}{Product Specifications} & \multirow[b]{2}{*}{Model Name} & \multicolumn{11}{|c|}{Frame Size} \\
\hline & & & T10 & T12 & T20 & T21 & T25 & T32 & T35 & T50 & T65 & T80 & T100 \\
\hline \multirow[t]{9}{*}{} & With 2E Thermal & MSO－ロKP & O & \(\bigcirc\) & \(\bigcirc\) & & \(\bigcirc\) & & \(\bigcirc\) & O & \(\bigcirc\) & O & O \\
\hline & Wiring Streamlining Termina，With 2E Thermal & MSO－DBCKP & O & O & O & & O & & O & O & & & \\
\hline & Surge Absorber Built－in Type with 2E Thermal & MSO－DKPSA & O & O & O & & O & & O & O & & & \\
\hline & With Terminal Cover，With 2 E Thermal & MSO－पCWKP & & & & & & & & & \(\bigcirc\) & O & \\
\hline & Drop Time Shortened Type，With 2 E Thermal & MSO－ロKPQM & & & & & & & & & O & O & O \\
\hline & DC Operated Type，With 2E Thermal & MSOD－DKP & & \(\bigcirc\) & O & & & & \(\bigcirc\) & O & O & O & O \\
\hline & DC Opeated，Whing Streanlining Teminal，With 2E Themal & MSOD－पBCKP & & O & O & & & & O & O & & & \\
\hline & DC Opeated S Suge Absobere Builitin Tye，With 2E Themal & MSOD－DKPSA & & \(\bigcirc\) & \(\bigcirc\) & & & & \(\bigcirc\) & O & & & \\
\hline & DC Opeated Type With Teminal Coverand 2E Thermal & MSOD－पCWKP & & & & & & & & & O & O & \\
\hline \multirow{16}{*}{} & Standard Specifications & S－■ & O & \(\bigcirc\) & O & O & \(\bigcirc\) & O & O & O & O & O & \(\bigcirc\) \\
\hline & Wiring Streamlining Terminal & S－DBC & O & O & O & O & O & O & O & O & & & \\
\hline & Surge Absorber Built－in Type & S－DSA & O & O & （） & O & （） & O & O & O & & & \\
\hline & With Terminal Cover & S－DCW & & & & & & & & & \(\bigcirc\) & O & \(\bigcirc\) \\
\hline & Drop Time Shortened Type & S－DQM & & & & & & & & & O & O & O \\
\hline & DC Operated & SD－\(\square\) & & \(\bigcirc\) & O & O & & O & \(\bigcirc\) & O & \(\bigcirc\) & O & © \\
\hline & DC Operated，Wiring Streamlining Terminal & SD－DBC & & O & O & O & & O & O & O & & & \\
\hline & DC Operated Surge Absorber Built－in Type & SD－DSA & & O & © & O & & O & O & O & & & \\
\hline & DC Operated Type with Terminal Cover & SD－DCW & & & & & & & & & © & O & （） \\
\hline & Spring Clamp Terminals & S（D）－DSQ & & \(\bigcirc\) & \(\bigcirc\) & & & & & & & & \\
\hline & Mechanically Latched Type & SL（D）－■ & & & & O & & & \(\bigcirc\) & O & © & O & O \\
\hline & Mechanically Latched，Wring Streamlining Terminal & SL（D）－DBC & & & & O & & & O & O & & & \\
\hline & Mechanically Latched，Surge Absorber Built－in Type & SL（D）－पSA & & & & O & & & \(\bigcirc\) & O & & & \\
\hline & NC Main Contact Type & B（D）－口 & & & & O & & & & & & & \\
\hline & NC Main Contact，Wiring Streamlining Terminal & B（D）－DBC & & & & \(\bigcirc\) & & & & & & & \\
\hline & NC Main Contact，Surge Absorber Builtin Type & B（D）－DSA & & & & O & & & & & & & \\
\hline
\end{tabular}

Note 1．The delay open types MSO－TロDL and S－TロDL and mechanically latched type MSOL（D）－T \(\square\)（KP）are not certified．
－Non－Reversible Magnetic Starter，Magnetic Contactor N Series
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline & \multirow[b]{2}{*}{Product Specifications} & \multirow[b]{2}{*}{Model Name} & \multicolumn{12}{|c|}{Frame Size} \\
\hline & & & N38 & N48 & N65 & N100 & N125 & N150 & N180 & N220 & N300 & N400 & N600 & N800 \\
\hline \multirow[t]{7}{*}{} & With 2E Thermal & MS－■KP & & & & & 0 & \(\bigcirc\) & \(\bigcirc\) & 0 & O & \(\bigcirc\) & & \\
\hline & Surge Absorber Built－in Type & MS－■SA & & & & & & & & & & & & \\
\hline & With Push Button，with ON／OFF／Reset & MS－DPM & & & & & & & & & & & & \\
\hline & With Push Button，with ON／OFF／Reset & MS－पKPPM & & & & & & & & & & & & \\
\hline & With Push Button，with ON／OFF & MS－ロPS & & & & & & & & & & & & \\
\hline & With Push Button，with ON／OFF & MS－पKPPS & & & & & & & & & & & & \\
\hline & Drop Time Shortened Type & MS－पKPQM & & & & & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & & \\
\hline \multirow[t]{5}{*}{} & With 2E Thermal & MSO－ロKP & & & & & （0） & （） & （ \()\) & （0） & （） & （） & & \\
\hline & With Saturable Reactor with 2E & MSO－■KPSR & & & & & （0） & （ \()\) & （ & （0） & （ & （ \()\) & & \\
\hline & Drop Time Shortened Type with 2E Thermal & MSO－■KPQM & & & & & （0） & （） & （0） & （0） & （） & （） & & \\
\hline & DC Operated & MSOD－\(\square\) & & & & & & & & & & & & \\
\hline & DC Operated Type with 2E Thermal & MSOD－■KP & & & & & （0） & （0） & & （0） & （） & （0） & & \\
\hline \multirow[t]{5}{*}{} & Standard Specifications & S－■ & （） & （0） & & & （0） & （ \()\) & （0） & （0） & （0） & （ \()\) & （0） & （ ） \\
\hline & Drop Time Shortened Type & S－■QM & & & & & （ \({ }^{\text {a }}\) & （ \()\) & （ \()\) & （） & （ \()\) & （ \()\) & & \\
\hline & DC Operated & SD－\(\square\) & & & & & （0） & （） & & （0） & （0） & （ \()\) & （0） & （ \()\) \\
\hline & Mechanically Latched Type & SL（D）－\(\square\) & & & & & © & （） & & （0） & （0） & （） & O & \(\bigcirc\) \\
\hline & NC Main Contact Type & \(\mathrm{B}(\mathrm{D})\)－\(\square\) & & & \(\bigcirc\) & \(\bigcirc\) & & & & & & & & \\
\hline
\end{tabular}

Note 1．The delay open types MSO－N \(\square D L\) and S－N \(\square D L\) and mechanically latched type MSOL（D）－N \(\square(K P)\) are not certified．

\section*{Application to Domestic and International Standards}
－Reversible Magnetic Starter，Magnetic Contactor T Series
© ：Standard product and certified， \(\qquad\) Out of production range
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{} & \multirow[b]{2}{*}{Product Specifications} & \multirow[b]{2}{*}{Model Name} & \multicolumn{11}{|c|}{Frame Size} \\
\hline & & & T10 & T12 & T20 & T21 & T25 & T32 & T35 & T50 & T65 & T80 & T100 \\
\hline \multirow[t]{9}{*}{} & With 2E Thermal & MSO－2x■KP & （ 0 & （） & （0） & （0） & （） & & （） & （ & （0） & （0） & （） \\
\hline & Wiring Streamlining Terminal，With 2E Thermal & MSO－2x■BCKP & （0） & （） & （0） & （0） & （） & & （ 0 & （ 0 & & & \\
\hline & Surge Absorber Built－in Type with 2E Thermal & MSO－2x口KPSA & （ & （） & （0） & （0） & （） & & （） & （ 0 & & & \\
\hline & With Terminal Cover，With 2E Thermal & MSO－2x■CWKP & & & & & & & & & （0） & （0） & \\
\hline & Drop Time Shortened Type，With 2E Thermal & MSO－2x■KPQM & & & & & & & & & （0） & （0） & （0） \\
\hline & DC Operated Type，With 2E Thermal & MSOD－2x \(\square \mathrm{KP}\) & & （） & （0） & （） & & & （） & （） & （0） & （0） & （ 0 \\
\hline & DC Operated，Wiring Streamining Termina，With 2E Thermal & MSOD－2x■BCKP & & （0） & （0） & （0） & & & （0） & （0） & & & \\
\hline & DC Operated Surge Absorber Built－in Type，With 2E Thermal & MSOD－2x■KPSA & & （0） & （0） & （0） & & & （0） & （0） & & & \\
\hline & DC Operated Type With Terminal Cover and 2E Thermal & MSOD－2x■CWKP & & & & & & & & & （ 0 & （） & （ \()\) \\
\hline \multirow{13}{*}{} & Standard Specifications & S－2x■ & （ 0 & （） & （0） & （） & （） & （） & （） & （ \()\) & （0） & （0） & （） \\
\hline & Wiring Streamlining Terminal & S－2x■BC & （ 0 & （ 0 & （0） & （ 0 & （ 0 & （ 0 & （ \({ }^{\text {O }}\) & （ 0 & & & \\
\hline & Surge Absorber Built－in Type & S－2x■SA & （） & （） & （0） & （） & （） & （） & （0） & （0） & & & \\
\hline & With Terminal Cover & S－2x■CW & & & & & & & & & （0） & （0） & \\
\hline & Drop Time Shortened Type & S－2x■QM & & & & & & & & & （0） & （0） & （0） \\
\hline & DC Operated & SD－2x \(\square\) & & （） & （0） & （ 0 & & （ 0 & （ 0 & （0） & （0） & （0） & （ \()\) \\
\hline & DC Operated，Wiring Streamlining Terminal & SD－2x■BC & & （） & （0） & （0） & & （ 0 & （ & （ \()\) & & & \\
\hline & DC Operated Surge Absorber Built－in Type & SD－2x口SA & & （） & （0） & （） & & （） & （） & （0） & & & \\
\hline & DC Operated Type with Terminal Cover & SD－2x■CW & & & & & & & & & （0） & （0） & （0） \\
\hline & Spring Clamp Terminals & S（D）－2x■SQ & & （） & （0） & & & & & & & & \\
\hline & Mechanically Latched Type & SL（D）－2x \(\square\) & & & & （0） & & & （0） & （ \()\) & （0） & （0） & （ \()\) \\
\hline & Mechanically Latched，Wiring Streamlining Terminal & SL（D）－2x■BC & & & & （ \()\) & & & （ 0 & （ 0 & & & \\
\hline & Mechanically Latched，Surge Absorber Built－in Type & SL（D）－2x口SA & & & & （ \()\) & & & （ \()\) & （0） & & & \\
\hline
\end{tabular}

Note 1．The enclosed type MS－2 x T \(\square\) and mechanically latched type MSOL（D）－2 x T \(\square(\mathrm{KP})\) are not certified．
－Reversible Magnetic Starter，Magnetic Contactor N Series
© ：Certified as standard product，O：Certified（add＂CN＂at the end of the model name when ordering），\(\square\) ：Out of production range
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{} & \multirow[b]{2}{*}{Product Specifications} & \multirow[b]{2}{*}{Model Name} & \multicolumn{10}{|c|}{Frame Size} \\
\hline & & & N125 & N150 & N180 & N220 & N300 & N400 & N600 & N800 & N38 & N48 \\
\hline \multirow[t]{4}{*}{} & With 2E Thermal & MSO－2x■KP & （） & （ 0 & （） & （0） & （ 0 & （0） & & & & \\
\hline & With Saturable Reactor with 2E & MSO－2x■KPSR & （0） & （ \()\) & （ \()\) & （0） & （ \()\) & （0） & & & & \\
\hline & Drop Time Shortened Type with 2E Thermal & MSO－2x■KPQM & （ \({ }^{\text {O}}\) & （ \({ }^{\text {O}}\) & （ & （ \({ }^{\text {O}}\) & （ & （ \({ }^{\text {O}}\) & & & & \\
\hline & DC Operated Type with 2E Thermal & MSOD－2x口KP & （0） & （） & & （0） & O & （） & & & & \\
\hline \multirow[t]{4}{*}{} & Standard Specifications & S－2x■ & （） & （ 0 & （0） & （） & （） & （） & （0） & （） & （0） & （0） \\
\hline & Drop Time Shortened Type & S－2x■QM & （0） & （0） & （0） & （0） & （0） & （0） & & & & \\
\hline & DC Operated & SD－2x■ & （0） & （ \()\) & & （ 0 & （ 0 & （0） & （0） & （0） & & \\
\hline & Mechanically Latched Type & SL（D）－2x■ & （） & （） & & （0） & （） & （） & \(\bigcirc\) & O & & \\
\hline
\end{tabular}

Note 1．The enclosed type MS－2xN \(\square\) and mechanically latched type MSOL（D）－2xN \(\square\)（KP）are not certified．
－Thermal Overload Relay T Series
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multicolumn{4}{|r|}{O：Standard product and certified，} & \multicolumn{3}{|l|}{：Out of production range} \\
\hline \multirow[b]{2}{*}{Product Specifications} & \multirow[b]{2}{*}{Model Name} & \multicolumn{5}{|c|}{Frame Size} \\
\hline & & T18 & T25 & T50 & T65 & T100 \\
\hline Open－Phase Protection（2E） & TH－पKP & （0） & （0） & （0） & （0） & （0） \\
\hline 2E with Automatic Reset & TH－DARKP & （） & （0） & （） & （） & （） \\
\hline 2 E with Wiring Streamlining Terminal & TH－पBCKP & （ \()\) & （0） & （ 0 & & \\
\hline 2 LE with Antic corosion Treated Terminal & TH－DKPYS & （） & （） & （0） & （） & （0） \\
\hline
\end{tabular}
－Thermal Overload Relay N Series
©：Certified as standard product，O：Certified（add＂CN＂at the end of the model name when ordering）， \(\qquad\) Out of production range
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Product Specifications} & \multirow[b]{2}{*}{Model Name} & \multicolumn{7}{|c|}{Frame Size} \\
\hline & & N120 & N120TA & N220RH & N220HZ & N400RH & N400HZ & N600 \\
\hline Overtad ad Open－Phase Protection（2E） & TH－DKP & （0） & （） & （） & （） & （） & （） & \(\bigcirc\) \\
\hline  & TH－■HZKP & & （0） & & & & & \\
\hline 2E With Saturable Reactor & TH－पKPSR & （0） & （0） & （0） & （） & （0） & （0） & O \\
\hline 2E with Automatic Reset & TH－पARKP & （0） & （） & （） & （0） & （） & （） & （） \\
\hline
\end{tabular}

\section*{- Solid State Contactors}
©: Standard product and certified, \(\square\) : Out of production range
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Product Specifications}} & \multirow[b]{2}{*}{Model Name} & \multicolumn{10}{|c|}{Frame Size} \\
\hline & & & N5SS & N8SS & N20 & N30 & N40 & N50 & N70NS & N80NS & NH70NS & NH80NS \\
\hline \multirow[b]{3}{*}{2-Element Type} & Standard Specifications & US-■ & ( \()\) & ( \()\) & (0) & () & (0) & (0) & ( \()\) & ( & ( \()\) & ( \\
\hline & With Terminal Cover & US-■CX & & & () & () & () & (0) & & & & \\
\hline & IEC Rail Mounting & US- \(\square \mathrm{RM}\) & \multicolumn{2}{|l|}{Standard Equipment} & ( & & & & & & & \\
\hline \multirow[b]{3}{*}{3-Element Type} & Standard Specifications & US-पTE & () & (0) & () & () & (0) & (0) & (0) & ( \()\) & ( \()\) & ( \()\) \\
\hline & With Terminal Cover & US-पTECX & & & () & () & () & ( ) & & & & \\
\hline & IEC Rail Mounting & US-口TERM & \multicolumn{2}{|l|}{Standard Equipment} & ( & & & & & & & \\
\hline
\end{tabular}

Note 1. US-H \(\square\) for heater load is non-certified.
Note 2. The following optional units of the solid state contactor are not subject to certification. UA-DR1, UA-SH1, UA-SH8, UA-PC, UA-RE, UA-CVDR1, UA-CVSH-8, UA-CV501US

\section*{- Contactor Relay T Series}
©: Standard product and certified, \(\square\) : Out of production range
\begin{tabular}{|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{\multirow[b]{2}{*}{Product Specifications}} & \multirow[b]{2}{*}{Model Name} & \multicolumn{2}{|r|}{Frame Size} \\
\hline & & & T5 & T9 \\
\hline \multirow{4}{*}{AC Operated Type} & Standard Specifications & SR- \(\square\) & (0) & (0) \\
\hline & Wiring Streamlining Terminal & SR- \(\square\) BC & ( & () \\
\hline & Surge Absorber Mounted Type & SR-DSA & ( & ( \\
\hline & Spring Clamp Terminals & SR-DSQ & ( & \\
\hline \multirow{4}{*}{DC Operated Type} & DC Operated & SRD-■ & ( & (0) \\
\hline & Wiring Streamlining Terminal & SRD-■BC & ( 0 & ( \\
\hline & Surge Absorber Mounted Type & SRD- \(\square\) SA & (0) & () \\
\hline & Spring Clamp Terminals & SRD- \(\square\) SQ & ( & \\
\hline \multirow[b]{3}{*}{Mechanically Latched Type} & Mechanically Latched Type & SRL(D)- \(\square\) & ( 0 & \\
\hline & Wiring Streamlining Terminal & SRL(D)-■BC & ( & \\
\hline & Surge Absorber Mounted Type & SRL(D)- \(\square\) SA & ( & \\
\hline
\end{tabular}
- Contactor Relay K Series
©: Standard product and certified, \(\square\) : Out of production range
\begin{tabular}{l|l|c|c}
\hline \multicolumn{2}{c|}{ Product Specifications } & \multirow{2}{*}{ Model Name } & Frame Size \\
\cline { 3 - 4 } & & K100 \\
\hline \begin{tabular}{l} 
Mechanically \\
Latched Type
\end{tabular} & Mechanically Latched Type & SRL(D)- - & 0 \\
\cline { 2 - 4 } & With Terminal Cover & SRL(D)- \(\square \mathrm{CX}\) & \\
\hline
\end{tabular}

Note 1. The delay open type SR-N \(\square \mathrm{DL}, \mathrm{SR}(\mathrm{D})\)-N \(\square \mathrm{JH}\) with large rated auxiliary contact, and SR(D)-N \(\square\) LC with overlap contact are not certified.
- Auxiliary Contact Unit T Series ©: Standard product and certified
\begin{tabular}{l|l|c|c|c}
\hline \multirow{2}{*}{ Product Specifications } & \multirow{2}{*}{ Model Name } & \multicolumn{4}{|c}{ Frame Size } \\
\cline { 3 - 5 } & & 2 & 4 & 11 \\
\hline Standard Specifications & UT-AX \(\square\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) \\
\hline Wiring Streamlining Terminal & UT-AX \(\square\) BC & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) \\
\hline
\end{tabular}
- Auxiliary Contact Unit N Series

O: Standard product and certified, O: Certified (add "CN" at the end of the model name when ordering), \(\square\) : Out of production range
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Product Specifications} & \multirow[b]{2}{*}{Model Name} & \multicolumn{7}{|c|}{Frame Size} \\
\hline & & 2 & 22 & 4 & 11 & 80 & 150 & 600 \\
\hline Standard Specifications & UN-AX \(\square\) & ( & & ( \()\) & ( & \(\bigcirc\) & \(\bigcirc\) & O \\
\hline With Terminal Cover & UN-AX \(\square\) CX & ( & & ( \()\) & ( & & & \\
\hline With Low-Level Signal Contact & UN-LLD & & (0) & & & & & \\
\hline
\end{tabular}

\section*{- DC Interface Contactors}

O: Standard product and certified
\begin{tabular}{l|l|c|c|c|c|c}
\hline \multirow{2}{*}{\multicolumn{2}{c}{ Product Specifications }} & \multirow{3}{*}{ Model Name } & \multicolumn{4}{|c}{ Frame Size } \\
\cline { 3 - 6 } & & Non-Reversible Type & \multicolumn{2}{c}{ Reversible Type } \\
\cline { 3 - 6 } & & Q11 & Q12 & QR11 & QR12 \\
\hline Standard Specification - Magnetic Starter & MSOD- \(\square\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) \\
\hline With 2E Thermal & MSOD- \(\square K P\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) \\
\hline Wiring Streamlining Terminal & MSOD- \(\square \mathrm{BC}\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) \\
\hline Wiring Streamlining Terminal, With 2E Thermal & MSOD- \(\square\) BCKP & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) \\
\hline Standard Specifications - Magnetic Contactor & SD- \(\square\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) \\
\hline
\end{tabular}

Note 1. The DC12 V coil voltage designation is not certified.

\section*{Application to Domestic and International Standards}
- Auxiliary Contact Units for DC Interface Contactors

O: Standard product and certified
\begin{tabular}{l|c|c|c}
\hline \multirow{2}{*}{ Product Specifications } & \multirow{2}{*}{ Model Name } & \multicolumn{2}{|c}{ Frame Size } \\
\cline { 3 - 4 } & & 2 & 2 KR \\
\hline Standard Specifications & UQ-AX \(\square\) & 0 & \(\Theta\) \\
\hline
\end{tabular}
- Magnetic Contactors for DC

O: Certified (add "CN" at the end of the model name when ordering)
\begin{tabular}{l|l|c|c|c|c|c|c}
\hline \multirow{2}{*}{ Product Specifications } & \multirow{2}{*}{ Model Name } & \multicolumn{4}{|c}{ Frame Size } \\
\cline { 3 - 8 } & & N30 & N60 & N120 & N180 & N260 \\
\hline Standard Specifications & DU(D)- - & \(O\) & \(O\) & \(O\) & \(O\) & \(O\) \\
\hline
\end{tabular}
- Vacuum Magnetic Contactors

O: Certified (add "CN" at the end of the model name when ordering), \(\square\) : Out of production range
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{\multirow[b]{2}{*}{Product Specifications}} & \multirow[b]{2}{*}{Model Name} & \multicolumn{4}{|c|}{Frame Size} \\
\hline & & & V160 & V320 & V400 & V600 \\
\hline AC Operated Type & & SH-■ & O & O & O & O \\
\hline DC Operated Type & & SHD- \(\square\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \\
\hline Mechanically Latched & AC Operated Type & SHL-■ & O & O & O & \\
\hline Type & DC Operated Type & SHLD- \(\square\) & - & - & O & \\
\hline
\end{tabular}
- Voltage Detection Relays
\begin{tabular}{l|l|l|c} 
& \multicolumn{4}{c}{ O: Certified (add "CN" at the end of the model name when ordering) } \\
\hline & \multicolumn{2}{c}{ Product Specifications } & \multirow{2}{*}{ Model Name } \\
\multirow{2}{*}{ Application } \\
\hline For Standard & Operating Voltage AC100 to 110,200 to 220 V for \(50 / 60 \mathrm{~Hz}\) & SRE-AA & \(\bigcirc\) \\
\cline { 2 - 4 } \begin{tabular}{l} 
Detection
\end{tabular} & Operating Voltage AC115 to 120,230 to 240 V for \(50 / 60 \mathrm{~Hz}\) & SRE-AAU & \(\bigcirc\) \\
\hline For Power & Set Value (Scale) is OFF Voltage & SRE-K & \(\bigcirc\) \\
\cline { 2 - 4 } & Set Value (Scale) is ON Voltage & SRE-KT & \(\bigcirc\) \\
\hline
\end{tabular}
- Instantaneous Stop/Restart Relays

O: Certified (add "CN" at the end of the model name when ordering)
\begin{tabular}{l|c|c}
\hline Product Specifications & Model Name & Application \\
\hline Standard Specifications & UA-DL2 & 0 \\
\hline
\end{tabular}
- Fault Detection Units
\begin{tabular}{l|l|l|c}
\multicolumn{3}{c}{ O: Certified (add "CN" at the end of the model name when ordering) } \\
\hline \multirow{2}{c}{ Product Specifications } & \multicolumn{1}{c}{ Model Name } & Application \\
\hline \multirow{2}{*}{ For 200 V Main Circuit } & Standard Specifications & UN-FD & \(\bigcirc\) \\
\cline { 2 - 4 } & With Terminal Cover & UN-FDCX & \(\bigcirc\) \\
\hline \multirow{2}{*}{ For 400 V Main Circuit } & Standard Specifications & UN-FD4 & \(\bigcirc\) \\
\cline { 2 - 4 } & With Terminal Cover & UN-FD4CX & \(\bigcirc\) \\
\hline
\end{tabular}

Note 1. The DC24 V rated operational voltage specification is not certified.
- DC/AC Interface Units for Operation Coils
\begin{tabular}{l|l|c|c|c} 
O: Certified (add "CN" at the end of the model name when ordering), \(\square\) \\
\hline Product \\
Ppecifications
\end{tabular} Model Name of production range
Note 1. The following optional units for contactless output (triac output) are not subject to certification. UN-SY11, UN-SY21(CX), UN-SY31

\subsection*{10.8.2 Rating, Specification and Certification Number}
- Magnetic Starters (Certification Standard: GB/T14048.4)
<Enclosed Type>
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Model Name MS: AC Operated} & \multicolumn{2}{|l|}{Certified Rating Category AC-3 ( 220 to \(240 \mathrm{~V} / 380\) to 440 V )} & \multirow[t]{2}{*}{Heater Designation Range} & \multirow[t]{2}{*}{Coil Designation
Range} & \multirow[t]{2}{*}{Applicable Range of Model Name * * (Combinable)} & \multirow[t]{2}{*}{Auxiliary Contact Arrangement Standard} & \multirow[t]{2}{*}{Certification Number} \\
\hline & Rated Capacity (kW) & Rated Operating Current (A) & & & & & \\
\hline MS-N125CNKP & 37/60 & 125/120 & 42 to 105A & \multirow[t]{2}{*}{AC24V to AC500V} & \multirow{6}{*}{AR, QM} & 2a2b & 2003010304093067 \\
\hline MS-N150CNKP & 45/75 & 150/150 & 42 to 125A & & & 2a2b & 2003010304093079 \\
\hline MS-N180CNKP & 55/90 & 180/180 & 82 to 150A & \multirow{4}{*}{AC48V to AC500V} & & 2a2b & \multirow[b]{2}{*}{2003010304093070} \\
\hline MS-N220CNKP & 75/132 & 250/250 & 82 to 180A & & & 2a2b & \\
\hline MS-N300CNKP & 90/160 & 300/300 & 105 to 250A & & & 2a2b & \multirow[t]{2}{*}{2003010304093066} \\
\hline MS-N400CNKP & 125/220 & 400/400 & 105 to 330A & & & 2a2b & \\
\hline
\end{tabular}
<Open Type>
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Model Name MSO: AC Operated MSOD: DC Operated 2x: Reversible} & \multicolumn{2}{|l|}{Certified Rating Category AC-3 ( 220 to \(240 \mathrm{~V} / 380\) to 440 V )} & \multirow[t]{2}{*}{Heater Designation Range} & \multirow[t]{2}{*}{Coil Designation Range} & \multirow[t]{2}{*}{Applicable Range of Model Name ** (Combinable)} & \multirow[t]{2}{*}{Auxiliary Contact Arrangement Non-Reversing/ Reversing Standard} & \multirow[t]{2}{*}{Certification Number} \\
\hline & Rated Capacity (kW) & Rated Operating Current (A) & & & & & \\
\hline MSO-(2x)T10KP** & 2.5/4 & 11/9 & 0.12 to 9A & AC24V to AC500V & \multirow{7}{*}{AR, BC, SA, FS} & 1a/1a \(\times 2+2 \mathrm{~b}\) & \multirow{3}{*}{2015010304817542} \\
\hline MSO(D)-(2x)T12KP** & 3.5/5.5 & 13/12 & 0.12 to 11A & \multirow{3}{*}{AC24V to AC500V DC12V to DC220V} & & \multirow{2}{*}{1a1b/1a1b x \(2+2 \mathrm{~b}\)} & \\
\hline MSO(D)-(2x)T20KP** & 4.5/7.5 & 18/18 & 0.12 to 15A & & & & \\
\hline MSO(D)-(2x)T21KP** & 5.5/11 & 25/23 & 0.24 to 15A & & & \multirow{8}{*}{\(2 \mathrm{a} 2 \mathrm{~b} / 2 \mathrm{a} 2 \mathrm{~b} \times 2\)} & 2015010304817518 \\
\hline MSO-(2x)T25KP** & 7.5/15 & 30/30 & 0.24 to 22A & AC24V to AC500V & & & (15010304817518 \\
\hline MSO(D)-(2x)T35KP** & 11/18.5 & 40/40 & 0.24 to 29A & \multirow{5}{*}{AC24V to AC500V DC12V to DC220V} & & & 2016010304835055 \\
\hline MSO(D)-(2x)T50KP** & 15/22 & 55/50 & 0.24 to 42A & & & & 201601030483505 \\
\hline MSO(D)-(2x)T65KP** & 18.5/30 & 65/65 & 15 to 54A & & \multirow[t]{2}{*}{AR,CW,FS,QM (AC Operation Only)} & & \multirow[t]{2}{*}{2016010304835278} \\
\hline MSO(D)-(2x)T80KP** & 22/45 & 85/85 & 15 to 67A & & & & \\
\hline MSO(D)-(2x)T100KP** & 30/55 & 105/105 & 15 to 82A & & AR,FS,QM (AC Operation Only) & & 2016010304835279 \\
\hline MSO(D)-(2x)N125KP** & 37/60 & 125/120 & 42 to 105A & AC24V to AC500V DC12V to DC220V & \multirow{6}{*}{AR, QM (AC Operation Only), SR} & & 2003010304093067 \\
\hline MSO(D)-(2x)N150KP** & 45/75 & 150/150 & 42 to 125A & \multirow{5}{*}{AC48V to AC500V DC12V to DC220V} & & \multirow{5}{*}{\(2 \mathrm{a} 2 \mathrm{~b} / 3 \mathrm{a} 3 \mathrm{~b} \times 2\)} & 2003010304093079 \\
\hline MSO-(2x)N180KP** & 55/90 & 180/180 & 82 to 150A & & & & 2003010304093070 \\
\hline MSO(D)-(2x)N220KP** & 75/132 & 250/250 & 82 to 180A & & & & 203010304003070 \\
\hline MSO(D)-(2x)N300KP** & 90/160 & 300/300 & 105 to 250A & & & & 200301030409306 \\
\hline MSO(D)-(2x)N400KP** & 125/220 & 400/400 & 105 to 330A & & & & 2003010304093066 \\
\hline
\end{tabular}

\section*{Application to Domestic and International Standards}

\section*{- Magnetic Contactors (Certification Standard: GB/T14048.4)}

\section*{<Standard Type>}
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{\begin{tabular}{l}
Model Name \\
S: AC Operated \\
SD: DC Operated \\
2x: Reversible
\end{tabular}} & \multicolumn{2}{|l|}{Certified Rating Category AC-3 ( 220 to \(240 \mathrm{~V} / 380\) to 440 V )} & \multirow[t]{2}{*}{Conventional Free Air Thermal Current Ith (A)} & \multirow[t]{2}{*}{Coil Designation Range} & \multirow[t]{2}{*}{} & \multirow[t]{2}{*}{Auxiliary Contact Arrangement Non-Reversing/ Reversing Standard} & \multirow[t]{2}{*}{Certification Number} \\
\hline & Rated Capacity (kW) & Rated Operating Current (A) & & & & & \\
\hline S-(2x)T10** & 2.5/4 & 11/9 & 20 & \multirow{11}{*}{AC24V to AC500V DC12V to DC220V} & BC, SA & 1a/1ax \(2+2 \mathrm{~b}\) & \\
\hline S(D)-(2x)T12** & 3.5/5.5 & 13/12 & 20 & & & \(1 a 1 b / 1 a 1 b \times 2+2 b\) & 2013010304604263 \\
\hline S(D)-(2x)T20** & 4.5/7.5 & 18/18 & 20 & & BC, SA, SQ & Ta 1 /albx 2 & \\
\hline S(D)-(2x)T21** & 5.5/11 & 25/23 & 32 & & \multirow{5}{*}{BC, SA} & \multirow[t]{2}{*}{2a2b/2a2b x 2} & \multirow{3}{*}{2013010304604262} \\
\hline S-(2x)T25** & 7.5/15 & 30/30 & 32 & & & & \\
\hline S(D)-(2x)T32** & 7.5/15 & 32/32 & 32 & & & \(-/ 2 \mathrm{a} 2 \mathrm{~b} \times 2\) & \\
\hline S(D)-(2x)T35** & 11/18.5 & 40/40 & 60 & & & \multirow{6}{*}{\(2 \mathrm{a} 2 \mathrm{~b} / 2 \mathrm{a} 2 \mathrm{~b} \times 2\)} & \multirow[t]{2}{*}{2015010304790992} \\
\hline S(D)-(2x)T50** & 15/22 & 55/50 & 80 & & & & \\
\hline S(D)-(2x)T65** & 18.5/30 & 65/65 & 100 & & \multirow[t]{2}{*}{QM (AC Operation Only), CW} & & \multirow[t]{2}{*}{2015010304790996} \\
\hline S(D)-(2x)T80** & 22/45 & 85/85 & 135 & & & & \\
\hline S(D)-(2x)T100** & 30/55 & 105/105 & 150 & & QM (AC Operation Only) & & 2015010304790995 \\
\hline S(D)-(2x)N125** & 37/60 & 125/120 & 150 & \multirow[t]{2}{*}{AC24V to AC500V DC12V to DC220V} & \multirow{6}{*}{QM (AC Operation Only)} & & 2002010304024706 \\
\hline S(D)-(2x)N150** & 45/75 & 150/150 & 200 & & & \multirow{5}{*}{\(2 \mathrm{a} 2 \mathrm{~b} / 3 \mathrm{a} 3 \mathrm{~b} \times 2\)} & 2002010304024707 \\
\hline S-(2x)N180** & 55/90 & 180/180 & 260 & \multirow{4}{*}{AC48V to AC500V DC12V to DC220V} & & & \multirow[t]{2}{*}{2002010304024708} \\
\hline S(D)-(2x)N220** & 75/132 & 250/250 & 260 & & & & \\
\hline S(D)-(2x)N300** & 90/160 & 300/300 & 350 & & & & \multirow[t]{2}{*}{2002010304024709} \\
\hline S(D)-(2x)N400** & 125/220 & 400/400 & 450 & & & & \\
\hline S(D)-(2x)N600 & 190/330 & 630/630 & 660 & \multirow[t]{2}{*}{AC100V to AC500V DC24V to DC22OV} & \multirow[t]{2}{*}{-} & \multirow[t]{2}{*}{2a2b/4a4b \(\times 2\)} & \multirow[t]{2}{*}{2003010304095569} \\
\hline S(D)-(2x)N800 & 220/440 & 800/800 & 800 & & & & \\
\hline
\end{tabular}
<Mechanically Latched Type>
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Model Name SL: AC Operated SLD: DC Operated \(2 x\) : Reversible} & \multicolumn{2}{|l|}{Certified Rating Category AC-3 ( 220 to \(240 \mathrm{~V} / 380\) to 440 V )} & \multirow[t]{2}{*}{Conventional Free Air Thermal Current Ith (A)} & \multirow[t]{2}{*}{Coil Designation Range} & \multirow[t]{2}{*}{Applicable Range of Model Name \(* *\) (Combinable)} & \multirow[t]{2}{*}{Auxiliary Contact Arrangement Non-Reversing/ Reversing Standard
(Effective Contact) (Effective Contact)} & \multirow[t]{2}{*}{Certification Number} \\
\hline & Rated Capacity (kW) & Rated Operating Current (A) & & & & & \\
\hline SL(D)-(2x)T21** & 5.5/11 & 25/23 & 32 & \multirow{6}{*}{AC24V to AC500V DC12V to DC200V} & \multirow{3}{*}{\(B C, S A\)} & \multirow{6}{*}{2a2b/2a2b x 2} & 2013010304604262 \\
\hline SL(D)-(2x)T35** & 11/18.5 & 40/40 & 60 & & & & 201501030479099 \\
\hline SL(D)-(2x)T50** & 15/22 & 55/50 & 80 & & & & 2015010304790952 \\
\hline SL(D)-(2x)T65 & 18.5/30 & 65/65 & 100 & & & & 2015010304790996 \\
\hline SL(D)-(2x)T80 & 22/45 & 85/85 & 135 & & & & \\
\hline SL(D)-(2x)T100 & 30/55 & 105/105 & 150 & & \multirow{6}{*}{-} & & 2015010304790995 \\
\hline SL(D)-(2x)N125 & 37/60 & 125/120 & 150 & \multirow{5}{*}{AC100V to AC500V DC12V to DC200V} & & 1a2b/1a2b \(\times 2\) & 2002010304024706 \\
\hline SL(D)-(2x)N150 & 45/75 & 150/150 & 200 & & & \multirow{4}{*}{1a2b/2a3b x 2} & 2002010304024707 \\
\hline SL(D)-(2x)N220 & 75/132 & 250/250 & 260 & & & & 2002010304024708 \\
\hline SL(D)-(2x)N300 & 90/160 & 300/300 & 350 & & & & 2002010304024709 \\
\hline SL(D)-(2x)N400 & 125/220 & 400/400 & 450 & & & & 202010304024709 \\
\hline SL(D)-(2x)N600CN & 190/330 & 630/630 & 660 & \multirow[t]{2}{*}{AC100V to AC500V DC24V to DC200V} & \multirow[t]{2}{*}{-} & \multirow[t]{2}{*}{1a2b/3a4b x 2} & \multirow[t]{2}{*}{2002010304095569} \\
\hline SL(D)-(2x)N800CN & 220/440 & 800/800 & 800 & & & & \\
\hline
\end{tabular}
<Main Circuit 3-Pole>
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Model Name S: AC Operated 2x: Reversible} & \multicolumn{2}{|l|}{Certified Rating Category AC-3 ( 220 to \(240 \mathrm{~V} / 380\) to 440 V )} & \multirow[t]{2}{*}{Conventional Free Air Thermal Current Ith (A)} & \multirow[t]{2}{*}{Coil Designation Range} & \multirow[t]{2}{*}{Applicable Range of Model Name \(* *\) (Combinable)} & \multirow[t]{2}{*}{Auxiliary Contact Arrangement Non-Reversing/ Reversing Standard} & \multirow[t]{2}{*}{Certification Number} \\
\hline & Rated Capacity (kW) & Rated Operating Current (A) & & & & & \\
\hline S-(2x)N38** & 11/15 & 39/32 & 60 & \multirow[b]{2}{*}{AC24V to AC500V} & \multirow[b]{2}{*}{CX, SA} & -/2a2b x 2 & \multirow[b]{2}{*}{2002010304024684} \\
\hline S-(2x)N48** & 15/18.5 & 50/40 & 80 & & & -/2a2b x 2 & \\
\hline
\end{tabular}
- Special Purpose Magnetic Contactors (Certification Standard: GB/T14048.4)
<DC>
\begin{tabular}{|c|c|c|c|c|c|}
\hline Model Name DU: AC Operated DUD: DC Operated & Main Contact Arrangement & Coil Designation Range & Applicable Range of Model Name ** (Combinable) & Auxiliary Contact Arrangement & Certification Number \\
\hline DU(D)-N30CN** & \multirow{5}{*}{\begin{tabular}{l}
DU: 2a1b \\
DUD: 2a
\end{tabular}} & \multirow{3}{*}{AC24V to AC500V DC12V to DC220V} & \multirow{5}{*}{QM (AC Operation Only)} & 2a2b & 2002010304024704 \\
\hline DU(D)-N60CN** & & & & 2a2b & 2002010304024706 \\
\hline DU(D)-N120CN** & & & & 2a2b & 2002010304024707 \\
\hline DU(D)-N180CN** & & AC48V to AC500V & & 2a2b & 2002010304024708 \\
\hline DU(D)-N260CN** & & DC12V to DC220V & & 2a2b & 2002010304024709 \\
\hline
\end{tabular}

Note 1. Refer to page 253 for ratings.
<NC Main Contact Type>
\begin{tabular}{|c|c|c|c|c|c|}
\hline \begin{tabular}{l}
Model Name \\
B: AC Operated \\
BD: DC Operated
\end{tabular} & Main Contact Arrangement & Coil Designation Range & Applicable Range of Model Name ** (Combinable) & Auxiliary Contact Arrangement & Certification Number \\
\hline B(D)-T21** & \multirow[t]{2}{*}{\[
\begin{aligned}
& \text { B: 1a2b, 3b } \\
& \text { BD: 1a2b }
\end{aligned}
\]} & \multirow[b]{3}{*}{AC24V to AC500V DC12V to DC220V} & SA & 2a & 2013010304604262 \\
\hline B(D)-N65CN** & & & \multirow[b]{2}{*}{QM (AC Operation Only)} & 2a2b & 2002010304024705 \\
\hline B(D)-N100CN** & \[
\begin{aligned}
& \text { B: 1a2b } \\
& \text { BD: } 1 \mathrm{a} 2 \mathrm{~b}
\end{aligned}
\] & & & 2a2b & 2002010304024706 \\
\hline
\end{tabular}

Note 1. Refer to page 249 for ratings.
- Thermal Overload Relays (Certification Standard: GB/T14048.4)
<With 3-Element (2E)>
\begin{tabular}{|c|c|c|c|c|}
\hline Model Name & Heater Designation & Applicable Range of Model Name ** (Combinable) & Combination Magnetic Contactor & Certification Numbe \\
\hline TH-T18KP** & \(0.12 \mathrm{~A}, 0.17 \mathrm{~A}, 0.24 \mathrm{~A}, 0.35 \mathrm{~A}, 0.5 \mathrm{~A}, 0.7 \mathrm{~A}, 0.9 \mathrm{~A}, 1.3 \mathrm{~A}, 1.7 \mathrm{~A}\), 2.1A, 2.5A, 3.6A, 5A, 6.6A, 9A, 11A, 15A & \multirow[b]{2}{*}{AR, BC, FS, YS} & S-T10 to T20 & 2013010309620822 \\
\hline TH-T25KP** & \(0.24 \mathrm{~A}, 0.35 \mathrm{~A}, 0.5 \mathrm{~A}, 0.7 \mathrm{~A}, 0.9 \mathrm{~A}, 1.3 \mathrm{~A}, 1.7 \mathrm{~A}, 2.1 \mathrm{~A}, 2.5 \mathrm{~A}, 3.6 \mathrm{~A}\), 5A, 6.6A, 9A, 11A, 15A, 22A & & S-T21, T25 & 2013010309620821 \\
\hline TH-T50KP** & 29A, 35A, 42A & AR, BC, FS, YS & S-T21 to T50 & 2015010309794365 \\
\hline TH-T65KP** & 15A, 22A, 29A, 35A, 42A, 54A & AR, CW, FS, YS & S-T65 to T100 & 2015010309794371 \\
\hline TH-T100KP** & 67A, 82A & AR, FS, YS & S-T65 to T100 & 2015010309794379 \\
\hline TH-N120KP** & 42A, 54A, 67A, 82A & AR, HZ, SR & S-N125, N150 & \multirow{3}{*}{2002010309024724} \\
\hline TH-N120TAKP** & \multirow[b]{2}{*}{105A, 125A} & AR, SR & S-N125, N150 & \\
\hline TH-N120TAHZKP** & & AR & Independent Mounting Only & \\
\hline TH-N220RHKP** & \multirow[b]{2}{*}{82A, 105A, 125A, 150A, 180A} & \multirow{5}{*}{AR, SR} & S-N180, N220 & \multirow{4}{*}{2002010309024719} \\
\hline TH-N220HZKP** & & & Independent Mounting Only & \\
\hline TH-N400RHKP** & \multirow[t]{2}{*}{105A, 125A, 150A, 180A, 250A, 330A} & & S-N300, N400 & \\
\hline TH-N400HZKP** & & & Independent Mounting Only & \\
\hline TH-N600KPCN** & 250A, 330A, 500A, 660A & & For Independent Mounting & 2002010304095454 \\
\hline
\end{tabular}

\footnotetext{
Note 1. TH-N \(\square\) becomes the quick trip type when changed from KP to KF.
}

\section*{Application to Domestic and International Standards}
- Contactor Relays (Certification Standard: GB/T14048.5)
<Standard Type>
\begin{tabular}{l|c|c|c|c}
\hline \begin{tabular}{c} 
Model Name \\
SR: AC Operated \\
SRD: DC Operated
\end{tabular} & Coil Designation Range & \begin{tabular}{c} 
Applicable Range of \\
Model Name \(* *\) \\
(Combinable)
\end{tabular} & Contact Arrangement & Certification Number \\
\hline SR(D)-T5** & AC24V to AC500V & BC, SA, SQ & \(5 \mathrm{a}, 4 \mathrm{a} 1 \mathrm{~b}, 3 \mathrm{a} 2 \mathrm{~b}\) & 202013010303604260 \\
\hline SR(D)-T9** & DC12V to DC220V & BC, SA & \(9 \mathrm{am}, 7 \mathrm{a} 2 \mathrm{~b}, 5 \mathrm{a} 4 \mathrm{~b}\) & 2 \\
\hline
\end{tabular}
<Mechanically Latched Type>
\begin{tabular}{l|c|c|c|c}
\hline \begin{tabular}{c} 
Model Name \\
SRLL: AC Operated \\
SRLD: DC Operated
\end{tabular} & Coil Designation Range & \begin{tabular}{c} 
Applicable Range of \\
Model Name ** \\
(Combinable)
\end{tabular} & Contact Arrangement & Certification Number \\
\hline SRL(D)-T5** & \begin{tabular}{c} 
AC24V to AC500V \\
DC12V to DC200V
\end{tabular} & BC, SA & \(5 a, 4 a 1 b, 3 a 2 b\) & 2013010303604260 \\
\hline SRL (D)-K100 & \begin{tabular}{c} 
AC24V to AC440V \\
DC12V to DC200V
\end{tabular} & - & \(9 a, 8 a 1 b, 7 a 2 b, 6 a 3 b, 5 a 4 b, 4 a 5 b\) & 2002010303024696 \\
\hline
\end{tabular}
- Auxiliary Contact Units (Certification Standard: GB/T14048.5)
\begin{tabular}{|c|c|c|c|c|}
\hline Model Name & Contact Arrangement & Applicable Range of Model Name ** (Combinable) & Applicable Magnetic Contactors & Certification Number \\
\hline UT-AX2** & 2a, 1a1b, 2b & \multirow{3}{*}{BC} & \multirow{3}{*}{S-T10 to T32} & \multirow{3}{*}{2013010304608269} \\
\hline UT-AX4** & 4a, 3a1b, 2a2b & & & \\
\hline UT-AX11** & 1a1b & & & \\
\hline UN-AX2** & 2a, 1a1b, 2b & \multirow{3}{*}{CX} & S-T65, T80, S-N38, N48 & \multirow{3}{*}{2002010303024700} \\
\hline UN-AX4** & 4a, 3a1b, 2a2b & & S-T65, T80, S-N38, N48 & \\
\hline UN-AX11** & 1a1b & & S-T65,T80 & \\
\hline UN-AX80CN & 1a1b & \multirow{3}{*}{-} & S-T100, S-N125 & 2002010303024720 \\
\hline UN-AX150CN & 1a1b & & S-N150 to N400 & \multirow[b]{2}{*}{2002010303024722} \\
\hline UN-AX600CN & 2a2b & & S-N600CN, N800CN & \\
\hline UQ-AX2** & 1a1b & - & SD-Q11, SD-QR11 (Left Side) & \multirow[b]{2}{*}{2005010304149321} \\
\hline UQ-AX2KR** & 1a1b & - & SD-QR11 (Right Side) & \\
\hline UN-LL22** & Low-Level Contact: 1a1b Standard Contact: 1a1b & CX & S-T65, T80, S-N38, N48 & 2002010303024700 \\
\hline
\end{tabular}
- DC Interface Contactors (Certification Standard: GB/T14048.4)
<Magnetic Starters>
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Model Name Q: Non-Reversible QR: Reversible} & \multicolumn{2}{|l|}{Certified Rating Category AC-3 ( 220 to \(240 \mathrm{~V} / 380\) to 440 V )} & \multirow[t]{2}{*}{Heater Designation Range (Note 1)} & Coil Designation Range & \multirow[t]{2}{*}{Applicable Range of Model Name ** (Combinable)} & \multirow[t]{2}{*}{Auxiliary Contact Arrangement Standard} & \multirow[t]{2}{*}{Certification Number} \\
\hline & Rated Capacity (kW) & Rated Operating Current (A) & & DC Operated & & & \\
\hline MSOD-Q11** & \multirow[t]{2}{*}{3/4} & \multirow[t]{2}{*}{12/9} & \multirow[t]{2}{*}{0.12 to 11A} & \multirow[t]{2}{*}{DC24V} & \multirow[b]{2}{*}{AR,BC,KP} & 1a & \multirow[t]{2}{*}{2003010304093069} \\
\hline MSOD-Q12** & & & & & & 1a1b & \\
\hline MSOD-QR11** & \multirow[t]{2}{*}{3/4} & \multirow[t]{2}{*}{12/9} & \multirow[t]{2}{*}{0.12 to 11A} & \multirow[t]{2}{*}{DC24V} & \multirow[t]{2}{*}{AR,BC,KP} & \(1 \mathrm{~b} \times 2\) & \multirow[t]{2}{*}{2003010304093069} \\
\hline MSOD-QR12** & & & & & & 1a1b \(\times 2\) & \\
\hline
\end{tabular}
<Magnetic Contactors>
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{\begin{tabular}{l}
Model Name \\
Q: Non-Reversible QR: Reversible
\end{tabular}} & \multicolumn{2}{|l|}{Certified Rating Category AC-3 ( 220 to \(240 \mathrm{~V} / 380\) to 440 V )} & \multirow[t]{2}{*}{Conventional Free Air Thermal Current Ith (A)} & Coil Designation Range & \multirow[t]{2}{*}{Auxiliary Contact Arrangement Standard} & \multirow[t]{2}{*}{Certification Number} \\
\hline & Rated Capacity (kW) & Rated Operating Current (A) & & DC Operated & & \\
\hline SD-Q11 & \multirow[b]{2}{*}{3/4} & \multirow[b]{2}{*}{12/9} & \multirow[b]{2}{*}{20} & \multirow[b]{2}{*}{DC24V} & 1a & \multirow[b]{2}{*}{2003010304095567} \\
\hline SD-Q12 & & & & & 1a1b & \\
\hline SD-QR11 & \multirow[b]{2}{*}{3/4} & \multirow[t]{2}{*}{12/9} & \multirow[b]{2}{*}{20} & \multirow[b]{2}{*}{DC24V} & 2b & \multirow[b]{2}{*}{2003010304095567} \\
\hline SD-QR12 & & & & & 2a2b & \\
\hline
\end{tabular}
- Solid State Contactors (Certification Standard: GB/T14048.6)
<3-Pole 2-Element Type>
\begin{tabular}{|c|c|c|c|c|}
\hline Model Name & \[
\begin{gathered}
3 \varphi \text { Motor Capacity } \\
\text { 200/400 V } \\
\text { AC-53a (kW(A)) }
\end{gathered}
\] & Rated Operational Voltage & Applicable Range of Model Name ** (Combinable) & Certification Number \\
\hline US-N5SS & 0.4(3.2)/- & \multirow{10}{*}{DC12 V to 24V} & \multirow[t]{2}{*}{-} & \multirow[t]{2}{*}{2006010304174448} \\
\hline US-N8SS & 0.4(3.2)/- & & & \\
\hline US-N20** & 2.2(11.1)/3.7(8.7) & & CX, RM & \multirow{4}{*}{2005010304162980} \\
\hline US-N30** & 3.7(17.4)/7.5(17.4) & & \multirow{3}{*}{CX} & \\
\hline US-N40** & 5.5(26)/11(26) & & & \\
\hline US-N50** & 5.5(26)/11(26) & & & \\
\hline US-N70NS & 11(48)/- & & \multirow{4}{*}{-} & \multirow{4}{*}{2006010304174451} \\
\hline US-N80NS & 11(48)/- & & & \\
\hline US-NH70NS & 11(48)/22(48) & & & \\
\hline US-NH80NS & 11(48)/22(48) & & & \\
\hline
\end{tabular}
<3-Pole 3-Element Type>
\begin{tabular}{|c|c|c|c|c|}
\hline Model Name & \[
\begin{gathered}
3 \varphi \text { Motor Capacity } \\
200 / 400 \mathrm{~V} \\
\text { AC-53a (kW(A)) }
\end{gathered}
\] & Rated Operational Voltage & Applicable Range of Model Name ** (Combinable) & Certification Number \\
\hline US-N5SSTE & 0.4(3.2)/- & \multirow{10}{*}{DC12 V to 24V} & \multirow[b]{2}{*}{-} & \multirow[b]{2}{*}{2006010304174448} \\
\hline US-N8SSTE & 0.4(3.2)/- & & & \\
\hline US-N20TE** & 2.2(11.1)/3.7(8.7) & & CX, RM & \multirow{4}{*}{2005010304162980} \\
\hline US-N30TE** & 3.7(17.4)/7.5(17.4) & & \multirow{3}{*}{CX} & \\
\hline US-N4OTE** & 5.5(26)/11(26) & & & \\
\hline US-N50TE** & 5.5(26)/11(26) & & & \\
\hline US-N70NSTE & 11(48)/- & & \multirow{4}{*}{-} & \multirow{4}{*}{2006010304174451} \\
\hline US-N80NSTE & 11(48)/- & & & \\
\hline US-NH70NSTE & 11(48)/22(48) & & & \\
\hline US-NH80NSTE & 11(48)/22(48) & & & \\
\hline
\end{tabular}
- Vacuum Magnetic Contactors
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{\begin{tabular}{c|} 
Model Name \\
SH: AC Operated \\
SHD: DC Operated \\
SL: Mechanicilly Latched (AC Operated) \\
SLD: Mechanically Latched (DC Operated)
\end{tabular}} & \multicolumn{2}{|l|}{Certified Rating Category AC-3 (220 to \(240 \mathrm{~V} / 380\) to \(440 \mathrm{~V} / 1,000 \mathrm{~V}\) )} & \multirow[t]{2}{*}{Conventional Free Air Thermal Current Ith (A)} & \multirow[t]{2}{*}{Coil Designation Range} & \multirow[t]{2}{*}{Auxiliary Contact Arrangement Standard} & \multirow[t]{2}{*}{Certification Number} \\
\hline & Rated Capacity (kW) & Rated Operating Current (A) & & & & \\
\hline SH(D)-V160CN & \(45 / 90 / 220\) & \(180 / 180 / 160\) & 200 & \multirow{3}{*}{AC100V to AC500V DC100V, DC200V} & \multirow{3}{*}{2a2b} & \multirow{3}{*}{2006010304201618} \\
\hline SH(D)-V320CN & 75/150/400 & \(320 / 320 / 320\) & 350 & & & \\
\hline SH(D)-V400CN & \(95 / 200 / 500\) & \(400 / 400 / 400\) & 450 & & & \\
\hline SHL(D)-V160CN & \(45 / 90 / 220\) & 180/180/160 & 200 & \multirow{3}{*}{AC100V to AC500V DC100V, DC200V} & \multirow{3}{*}{\[
\begin{aligned}
& \text { SHL: } 2 a 2 b \\
& \text { SHLD: } 2 a 4 b
\end{aligned}
\]} & \multirow{3}{*}{2006010304201618} \\
\hline SHL(D)-V320CN & 75/150/400 & \(320 / 320 / 320\) & 350 & & & \\
\hline SHL(D)-V400CN & \(95 / 200 / 500\) & 400/400/400 & 450 & & & \\
\hline SH-V600CN & \(160 / 300 / 750\) & 630/630/600 & 750 & AC100V, AC200V & 2a2b & 2007010304229815 \\
\hline
\end{tabular}
- Voltage Detection Relays (Certification Standard: GB/T14048.5)
\begin{tabular}{|c|c|c|c|}
\hline Model Name & Detection Voltage Setting Range Minimum to Maximum & Output Contact & Certification Number \\
\hline SRE-AACN & AC3V to 250 V & \multirow{4}{*}{1c} & \multirow{4}{*}{2007010303224330} \\
\hline SRE-AAUCN & DC0.1V to 250 V & & \\
\hline SRE-KCN & AC75V to 250V, DC9V to 105V & & \\
\hline SRE-KTCN & AC80V to \(260 \mathrm{~V}, \mathrm{DC} 10 \mathrm{~V}\) to 115 V & & \\
\hline
\end{tabular}
- Instantaneous Stop/Restart Relays (Certification Standard: GB/T14048.5)
\begin{tabular}{c|c|c}
\hline Model Name & Designation & Certification Number \\
\hline UA-DL2CN & AC100V, AC200V & 2009010303329883 \\
\hline
\end{tabular}

\section*{Application to Domestic and International Standards}
- Fault Detection Units (Certification Standard: GB/T14048.5)
\begin{tabular}{l|c|c|c|c|c}
\hline \multicolumn{1}{c|}{ Model Name } & Rated Operational Voltage & Applicable Range of Model Name \(* *\) & Contact Arrangement & Certification Number \\
\hline UN-FDCN \(* *\) & AC100V, AC200V & \multirow{2}{*}{ CX } & 1c & \multirow{2}{*}{2009010303329892} \\
\cline { 1 - 2 } & & & 1a, 1b & \\
\hline
\end{tabular}
- DC/AC Interface Units for Operation Coils (Certification Standard: GB14048.5)
\begin{tabular}{l|c|c|c}
\hline \multicolumn{1}{c|}{ Model Name } & Applicable Range of Model Name \(* *\) & Applicable Magnetic Contactors & Certification Number \\
\hline UN-SY12CN & - & For Independent Mounting & \multirow{3}{*}{2009010303329884} \\
\hline UN-SY22CN \(* *\) & CX & S-N38, N48 & \\
\hline UN-SY32CN & - & S-T65, T80 & \\
\hline
\end{tabular}

\footnotetext{
Note 1. The following contactless output (triac output) optional units are not subject to certification.
} UN-SY11, UN-SY21(CX), UN-SY31

\subsection*{10.9 KC Certified Products (South Korea)}
- South Korea Electrical Appliance and Material Safety Management Act Target Certified Products
(Certification Standard: K60947-4-1)

\begin{tabular}{l|c|c}
\hline \multicolumn{1}{c}{ Model Name } & \begin{tabular}{c} 
Certified Rating (A) \\
440 V \\
AC-3
\end{tabular} & Certification Number \\
\hline S-T10(BC)(SA) & 9 & HU02021-13022A \\
\hline S-T12(BC)(SA) & 12 & HU02021-13023A \\
\hline SD-T12(BC)(SA) & 12 & HU02021-15035A \\
\hline S-T20(BC)(SA) & 18 & HU02021-13024A \\
\hline SD-T20(BC)(SA) & 18 & HU02021-15036A \\
\hline S-T21(BC)(SA), SL-T21 & 23 & HU02021-13025B \\
\hline SD-T21(BC)(SA), SLD-T21 & 23 & HU02021-15037B \\
\hline S-T25(BC)(SA) & 30 & HU02021-13025B \\
\hline S-T32(BC)(SA) & 32 & HU02021-13026A \\
\hline S-T35(BC)(SA), SL-T35 & 40 & HU02021-16044A \\
\hline SD-T35(BC)(SA), SLD-T35 & 40 & HU02021-16039A \\
\hline S-T50(BC)(SA), SL-T50 & 50 & HU02021-16045A \\
\hline SD-T50(BC)(SA), SLD-T50 & 50 & HU02021-16040A \\
\hline S-T65(CW), SL-T65 & 85 & HU02021-16046A \\
\hline SD-T65(CW), SLD-T65 & 85 & HU02021-16041A \\
\hline S-T80(CW), SL-T80 & 85 & HU02021-16046A \\
\hline SD-T80(CW), SLD-T80 & 85 & HU02021-16041A \\
\hline S-T100, SL-T100 & 105 & HU02021-16048A \\
\hline SD-T100, SLD-T100 & 105 & HU02021-16043A \\
\hline
\end{tabular}

Note 1. Always add "KK" at the end of the model name to specify when ordering.
Certification Standard: KC60947-5-1, KS C IEC60947-5-1
\begin{tabular}{l|c|c}
\hline \multicolumn{1}{c|}{ Model Name } & \begin{tabular}{c} 
Certified Rating (A) \\
220 V \\
AC-15
\end{tabular} & Certification Number \\
\hline SR-T5(BC)(SA), SRL-T5(BC)(SA) & 3 & HU02021-13030 \\
\hline SRD-T5(BC)(SA), SRL-D-T5(BC)(SA) & 3 & HU02021-15033 \\
\hline SR-T9(BC)(SA) & 3 & HU02021-18057 \\
\hline SRD-T9(BC)(SA) & 3 & HU02021-18034 \\
\hline SR-K100, SRL-K100 & 5 & HU02021-18055 \\
\hline SRD-K100, SRLD-K100 & 5 & HU02021-18056 \\
\hline UA-DL2 & 1 & HU02021-18054 \\
\hline UT-AX2(BC) & 3 & HU02021-18049 \\
\hline UT-AX4(BC) & 3 & HU02021-13032 \\
\hline UT-AX11(BC) & 3 & HU02021-18050 \\
\hline UN-AX2(CX) & 3 & HU02021-18049 \\
\hline UN-AX4(CX) & 3 & HU02021-13031 \\
\hline UN-AX11(CX) & 3 & HU02021-18050 \\
\hline UN-AX80 & 3 & HU02021-18051 \\
\hline UN-AX150 & 3 & HU02021-18052 \\
\hline UN-AX600 & & HU02021-18053 \\
\hline
\end{tabular}

Note 1. When ordering a KC certified product, make sure to add "KK" at the end of the model name.

\subsection*{10.10 Selection by Global Rating}

The table below is the global rating selection table of the S-T/N series magnetic contactor.
Although the ratings of the S-T/N series differ as different standards (JIS/JEM, EN (IEC), UL) are applicable in Japan, Europe and North America, selection from the table below allows worldwide application.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Model Name} & \multicolumn{7}{|l|}{Global Rating (3-Phase Motor) (Note 1, Note 2)} & \multirow[t]{2}{*}{Electrical Durability (Note 3)} & \multicolumn{2}{|l|}{Selection by Electrical Durability of 2 mil. times (Rating is the same as indicated at left)} \\
\hline & 200 & & 220 to & 240 V & 380 to & 440 & & & Model Name & Electrical Durability (Note 3) \\
\hline S-T10 & 11 & A & 9.6 & A & 7 & A & & \multirow{9}{*}{2 mil. times} & S-T10 & \multirow{11}{*}{2 mil. times} \\
\hline S-T12 & 11 & A & 9.6 & A & & A & & & S-T12 & \\
\hline S-T20 & 15.2 & A *1 & 15.2 & A & 14 & A & & & S-T20 & \\
\hline S-T21 & 17.5 & A & 15.2 & A & & A & & & S-T21 & \\
\hline S-T25 & 25 & A & & A & & A & & & S-T25 & \\
\hline S-T32 & 32 & A & 28 & A & 32 & A & & & S-T32 & \\
\hline S-T35 & 32 & A & & A & & A & & & S-T35 & \\
\hline S-T50 & 48 & A & 42 & A & 40 & A & & & S-T50 & \\
\hline S-T65 & 54 & A *1 & & A & & A & & & S-T65 & \\
\hline S-T80 & 68 & A *1 & & A & & A & & \multirow[b]{2}{*}{1 mil. times} & \multirow[b]{2}{*}{S-N125} & \\
\hline S-T100 & 80 & A *1 & 80 & A & & A & & & & \\
\hline S-N125 & 119 & A & 104 & A & 96 & A & & \multirow{5}{*}{1 mil. times} & \multirow[t]{2}{*}{S-N180} & \multirow{5}{*}{2 mil. times} \\
\hline S-N150 & 130 & A *1 & & A & 124 & A & & & & \\
\hline S-N180 & 177 & A & 156 & \(\mathrm{A}^{* 2}\) & 156 & & & & \multirow[t]{2}{*}{S-N300} & \\
\hline S-N220 & 192 & A *1 & & A & 180 & A & & & & \\
\hline S-N300 & 285 & A & 248 & A & 240 & A & & & S-N600 & \\
\hline
\end{tabular}

Note 1. Shown as an integer (figure after decimal point discarded) with the current value converted from the UL horsepower rating (normal start and stop of the three-phase motor) as reference.
However, T21 and below are represented by the lower 1 digit with the lower two digits rounded off. However, \(* 1\) to \(* 3\) are as follows.
* 1: Shows the current value converted from the UL horsepower rating of 220 V .
* 2: Shows the current value converted from the UL horsepower rating of 440 V .
* 3: UL Standards do not regulate switching durability. The durability shows the confirmation results based on the JIS Standards (JEM standard).

Note 2. Compatible with UL Certification (© (\%) Us ), TÜV Certification ( \(\Delta\) ), and CE Mark ( \(\epsilon\) ).
Note 3. UL Standards do not regulate switching durability. Shows the confirmation results according to the JIS Standards (JEM standard).

\section*{(Commentary)}

The rated current value of the S-T/N \(\square\) series magnetic contactor differs for each rating in Japan, Europe and North America. Therefore, the selection of JIS rating (JEM rating) standards (page 39) does not apply to North America.
In this way, the selection differs by location in accordance with the rating, requiring special attention when applying the same product to multiple regions such as Japan, Europe and North America.
The solution to this problem is the global rating selection table (above) for worldwide application. The above table shows the smallest values of rated current in Japan, Europe and North America as the global rating according to the model name of each magnetic contactor.
It should be noted that for switching durability, standards for both 1 million and 2 million times can be selected in the above table. (For S-T10 to S-T65, only 2 million times can be selected)

\title{
10.11 Short-Circuit Current Rating (SCCR) UL Standards Certified Products \\ - US Export Control Panel SCCR
}

\section*{1. \(\operatorname{SCCR}\)}

Initials for the Short Circuit Current Rating, it refers to the magnitude of the short-circuit current that the device or equipment can withstand.

\section*{2. Short-Circuit Performance of Control Panels and SCCR}
(1) Short-Circuit Performance of Control Panels

On the name plate of a control panel, the value that represents the short-circuit performance of the control panel is given along with the manufacturer's name, rated voltage, number of phases, frequency, full load current, etc. When using the control panel, the estimated short-circuit current at the panel entry must be smaller than the short-circuit performance displayed on the name plate.
(2) Control Panel SCCR

Conventionally, the breaking capacity of overcurrent protection devices such as circuit breakers and fuses to be installed on the inlet port has been used as the short circuit performance of control panels (Figure 1 a) reference). However, due to the revision of the NEC (National Electric Code: the US equivalent of electrical equipment standards) in 2005, SCCR is now displayed as the short circuit performance of control panels rather than the breaking capacity of overcurrent protection devices of the inlet port. Typically, some sort of "coordination" between devices ("protection coordination" when including a protection device) is required when constructing an electrical system by combining several electrical devices. When considering the coordination of the entire control panel and especially during a short circuit, exactly what indicators are appropriate? Can the breaking capacity of the overcurrent protection device on the inlet port explain the short circuit coordination of the control panel? One of the solutions to such questions is SCCR.

\section*{3. Method of Determining SCCR}

\section*{(1) Method of Determining SCCR}

The method of determining SCCR is defined in Section 409 of NEC, but SCCR is commonly determined using the UL508A Supplement SB.
(2) UL508A SB

UL508A SB regulates the next steps.
- Determine SCCR for individual power circuit components.
- Correct SCCR for each current-limiting element.
- Determine SCCR for the entire control panel.

Details for each are described below.
(1) Determine SCCR for power circuit components.

Power circuit refers to circuits of motors, heaters, lighting, etc. Power transformers, reactors, CTs and the like are not included. SCCR of individual components is determined by one of the following methods.
- Values displayed in rating plates, instruction manuals, etc.
- Default values in SB Table 4.1
* For example, Circuit Breaker: 5 kA , Magnetic Starter (for motors with 50 hp or less): 5 kA , etc.
- For load controllers, motor overload relays and combination motor controllers, the values verified in the performance requirements in accordance with the provisions of UL60947-4-1A or UL508, and mentioned in the procedure of the manufacturer
(2) Correction for Transformer Capacity and Secondary Side SCCR

For SCCR of target circuits of the following cases, this is SCCR of devices on the transformer primary side.
a) In cases where the short-circuit current ratings and breaking ratings of all components of the secondary side are larger than the calculated value of the short-circuit current directly below the power transformer secondary side. For impedance, use either what is known or calculate by assuming that the impedance is \(2.1 \%\).
b) In cases where the short-circuit current ratings and breaking ratings of all components of the secondary side are larger than the values on the table as specified in UL 508A SB
c) If it does not correspond to \(a / b\) above, the smallest SCCR of the transformer secondary side will be SCCR of the transformer primary side.
(3) Correction for Current Limiting Circuit Breaker and Current Limiting Fuse

When the feeder circuit has a current-limiting circuit breaker or current-limiting fuse, SCCR will be one of the following depending on the conditions of the branch circuit.
a) If SCCR of all components of the branch circuit is equal to or greater than the passing current peak value Ip of the currentlimiting circuit breaker or current-limiting fuse and SCCR of the branch circuit protection devices is equal to or greater than SCCR of the current-limiting circuit breaker or current-limiting fuse, SCCR of the current-limiting circuit breaker or currentlimiting fuse of the feeder circuit will be SCCR of the branch circuit.
b) If SCCR of all components of the branch circuit is equal to or greater than the passing current peak value ip of the currentlimiting circuit breaker or current-limiting fuse and SCCR of the branch circuit protection devices is less than SCCR of the current-limiting circuit breaker or current-limiting fuse, the smallest SCCR of the branch circuit protection device will be SCCR of the branch circuit.
c) In conditions other than a/b above, the smallest SCCR of all components of the branch circuit will be SCCR of the branch circuit.
(4) Determination of SCCR for the Entire Control Panel

After determining SCCR of each circuit and component by the steps mentioned above, the minimum value of SCCR will be SCCR of the entire control panel. Looking at Fig. 1 b ) as an example, 5 kA of the magnetic starter will be the minimum value, and the name plate of the control panel will display SCCR 5 kA .


Fig. 1 SCCR of Control Plate

\section*{4. SCCR Problem Points}

Although there is no general recommended value for SCCR of the control panel, in order to increase the degree of freedom in control panel application, relatively large SCCR is desirable. Given this perspective, SCCR 5 kA and the like of the magnetic starter applicable to motor load of 50 horsepower or less may become a problem.
However, it is generally difficult to improve SCCR by magnetic starter alone.

\section*{5. Our Countermeasures Against SCCR Problem Points}

We have acquired UL certification to enable large SCCR to be applied when combining breakers and magnetic starters (combination motor controllers) (Fig. 1 c) reference).
This shows the combination of a UL certified breaker (no fuse breaker) and magnetic starter. For example, although individual SCCR of the S-T10 magnetic contactor and TH-T18KP thermal overload relay is 5 kA , SCCR is improved to 25 kA at AC240 V when in combination with the NF100-SRU no-fuse breaker.

\section*{Application to Domestic and International Standards}

\section*{UL Certified Standard Products}

\section*{1. Short-Circuit Current Rating (SCCR) of Magnetic Contactors}

By using with a fuse or low voltage breaker that satisfies the rated current and rated breaking current shown in the table below, the short-circuit current rating (SCCR) in the table below can be applied to magnetic contactors.


Note 1. Examples of the recommended low-voltage breakers are given. UL489-listed low-voltage breakers that satisfy the ratings given above can be used.
Note that some 3-pole UL489-listed low-voltage breakers cannot be used in single-phase circuits.

\section*{2. Short-Circuit Current Rating (SCCR) of Thermal Overload Relays}

By using with a fuse or low voltage breaker that satisfies the rated current and rated breaking current shown in the table below, the short-circuit current rating (SCCR) in the table below can be applied to thermal overload relays.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{\multirow[b]{4}{*}{Thermal Overload Relay Model}} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{\[
\begin{array}{|l|}
\hline \text { Main Circuit Voltage: AC600 V Maximum } \\
\hline \text { Short } \\
\hline
\end{array}
\]}} & \multicolumn{4}{|r|}{Main Circuit Voltage: AC240 V Maximum} & \multicolumn{4}{|r|}{Main Circuit Voltage: AC480 V Maximum} \\
\hline & & & & \multirow[t]{3}{*}{Short Circuit Current Rating (SCCR)} & \multicolumn{3}{|c|}{\multirow[b]{2}{*}{Circuit Breakers}} & \multirow[t]{3}{*}{Short Circuit Current Rating (SCCR)} & & & \\
\hline & & Circuit & Maximum & & & & & & \multicolumn{3}{|c|}{Circuit Breakers} \\
\hline & & \[
\begin{aligned}
& \text { Current } \\
& \text { Rating } \\
& \text { (SCCR) } \\
& \hline
\end{aligned}
\] & Rated Current
of Fuse
(Class K5) & & Maximum Rated Current & Minimum Breaking Current & Recommended Model Name (Note 1) & & Maximum Rated Current & Minimum Breaking Current & Recommended Model Name (Note 1) \\
\hline \multirow{15}{*}{TH-T18KP} & 0.12A & \multirow{15}{*}{5 kA} & \multirow{11}{*}{15 A} & \multirow{15}{*}{\[
\begin{gathered}
10 \mathrm{kA} \\
/ \\
25 \mathrm{kA}
\end{gathered}
\]} & \multirow{12}{*}{15 A} & \multirow{12}{*}{\[
\begin{gathered}
10 \mathrm{kA} \\
/ \\
25 \mathrm{kA}
\end{gathered}
\]} & \multirow{15}{*}{\[
\begin{gathered}
\text { NF50-SMU } \\
\text { NF50-SVFU, NV50-SVFU } \\
/ \\
\text { NF100-SRU, NV100-SRU }
\end{gathered}
\]} & \multirow{15}{*}{10 kA} & \multirow{12}{*}{15 A} & \multirow{12}{*}{10 kA} & \multirow[b]{8}{*}{NF100-HRU NV100-HRU} \\
\hline & 0.17A & & & & & & & & & & \\
\hline & 0.24 A & & & & & & & & & & \\
\hline & 0.35A & & & & & & & & & & \\
\hline & 0.5A & & & & & & & & & & \\
\hline & 0.7A & & & & & & & & & & \\
\hline & 0.9A & & & & & & & & & & \\
\hline & 1.3A & & & & & & & & & & \\
\hline & 1.7A & & & & & & & & & & \multirow[t]{4}{*}{NF125-SVU NV125-SVU} \\
\hline & 2.5 A & & & & & & & & & & \\
\hline & 3.6A & & & & & & & & & & \\
\hline & 5A & & 20 A & & & & & & & & \\
\hline & 6.6A & & \multirow[b]{2}{*}{30 A} & & \multirow[b]{2}{*}{30 A} & \multirow[t]{3}{*}{\[
\begin{gathered}
10 \mathrm{kA} \\
/ \\
35 \mathrm{kA}
\end{gathered}
\]} & & & \multirow[b]{2}{*}{30 A} & \multirow{3}{*}{18 kA} & \\
\hline & 9A & & & & & & & & & & \\
\hline & 11A & & 40 A & & 50 A & & & & 50 A & & \\
\hline \multirow{15}{*}{TH-T25KP} & 0.24A & \multirow{15}{*}{5 kA} & \multirow{9}{*}{15 A} & \multirow{15}{*}{\[
\begin{gathered}
10 \mathrm{kA} \\
/ \\
35 \mathrm{kA}
\end{gathered}
\]} & \multirow{10}{*}{15 A} & \multirow{14}{*}{\[
\begin{gathered}
10 \mathrm{kA} \\
/ \\
50 \mathrm{kA}
\end{gathered}
\]} & \multirow{14}{*}{\begin{tabular}{l}
NF50-SMU \\
NF50-SVFU, NV50-SVFU / \\
NF100-HRU, NV100-HRU NF125-SVU, NV125-SVU
\end{tabular}} & \multirow{15}{*}{35 kA} & \multirow{10}{*}{15 A} & \multirow{15}{*}{50 kA} & \multirow{15}{*}{NF125-HVU NV125-HVU} \\
\hline & 0.35A & & & & & & & & & & \\
\hline & 0.5A & & & & & & & & & & \\
\hline & 0.7A & & & & & & & & & & \\
\hline & 0.9A & & & & & & & & & & \\
\hline & 1.3A & & & & & & & & & & \\
\hline & 1.7A & & & & & & & & & & \\
\hline & 2.1A & & & & & & & & & & \\
\hline & 2.5 A & & & & & & & & & & \\
\hline & 3.6A & & 20 A & & & & & & & & \\
\hline & 6.6A & & 30 A & & \multirow{3}{*}{30 A} & & & & \multirow{3}{*}{30 A} & & \\
\hline & 9A & & 40 A & & & & & & & & \\
\hline & 11A & & 50 A & & & & & & & & \\
\hline & 15A & & 70 A & & 50 A & & & & 50 A & & \\
\hline & 22A & & 100 A & & 75 A & \[
\begin{gathered}
14 \mathrm{kA} \\
/ \\
50 \mathrm{kA}
\end{gathered}
\] & NF100-CVFU, NV100-CVFU NF100-HRU, NV100-HRU NF125-SVU, NV125-SVU & & 75 A & & \\
\hline \multirow{15}{*}{TH-T50KP} & \multirow{5}{*}{29A} & \multirow{15}{*}{5 kA} & \multirow{5}{*}{125 A} & 10 kA & 50 A & 10 kA & NF50-SMU, NF50-SVFU,
NV50-SVFU & \multirow{3}{*}{18 kA} & \multirow{5}{*}{75 A} & \multirow{3}{*}{18 kA} & \multirow[t]{3}{*}{NF100-HRU, NV100-HRU, NF125-SVU, NV125-SVU} \\
\hline & & & & 14 kA & 40 A & 14 kA & NF50-SVFU, NV50-SVFU & & & & \\
\hline & & & & 18 kA & \multirow{3}{*}{75 A} & 18 kA & \multirow[t]{2}{*}{NF100-SRU, NV100-SRU,
NF100-HRU, NV100-HRU} & & & & \\
\hline & & & & 25 kA & & 35 kA & & \multirow[b]{2}{*}{35 kA} & & \multirow[b]{2}{*}{50 kA} & \multirow[t]{2}{*}{NF125-HVU, NV125-HVU} \\
\hline & & & & 35 kA & & 50 kA & NF100-HRU, NV100-HRU, NF125-SVU, NV125-SVU & & & & \\
\hline & \multirow{5}{*}{35A} & & \multirow{5}{*}{150 A} & 10 kA & 50 A & 10 kA & NF50-SMU, NF50-SVFU, NV50-SVFU & \multirow{3}{*}{18 kA} & \multirow{10}{*}{100 A} & \multirow{3}{*}{18 kA} & \multirow[t]{3}{*}{NF100-HRU, NV100-HRU, NF125-SVU, NV125-SVU} \\
\hline & & & & 14 kA & 75 A & 14 kA & NF50-SVFU, NV50-SVFU & & & & \\
\hline & & & & 18 kA & \multirow{3}{*}{100 A} & 18 kA & \multirow[t]{2}{*}{NF100-SRU, NV100-SRU, NF100-HRU, NV100-HRU} & & & & \\
\hline & & & & 25 kA & & 35 kA & & \multirow[b]{2}{*}{35 kA} & & \multirow[b]{2}{*}{50 kA} & \multirow[t]{2}{*}{NF125-HVU, NV125-HVU} \\
\hline & & & & 35 kA & & 50 kA & NF100-HRU, NV100-HRU, NF125-SVU, NV125-SVU & & & & \\
\hline & \multirow{5}{*}{42A} & & \multirow{5}{*}{200 A} & 10 kA & 50 A & 10 kA & NF50-SMU, NF50-SVFU,
NV50-SVFU & \multirow{3}{*}{18 kA} & & \multirow{3}{*}{18 kA} & \multirow[t]{3}{*}{NF100-HRU, NV100-HRU, NF125-SVU, NV125-SVU} \\
\hline & & & & 14 kA & 75 A & 14 kA & NF50-SVFU, NV50-SVFU & & & & \\
\hline & & & & 18 kA & \multirow{3}{*}{100 A} & 18 kA & \multirow[t]{2}{*}{NF100-SRU, NV100-SRU, NF100-HRU, NV100-HRU} & & & & \\
\hline & & & & 25 kA & & 35 kA & & \multirow[b]{2}{*}{35 kA} & & \multirow[b]{2}{*}{50 kA} & \multirow[t]{2}{*}{NF125-HVU, NV125-HVU} \\
\hline & & & & 35 kA & & 50 kA & NF100-HRU, NV100-HRU, NF125-SVU, NV125-SVU & & & & \\
\hline
\end{tabular}

Note 1. Examples of the recommended low-voltage breakers are given. UL489-listed low-voltage breakers that satisfy the ratings given above can be used.
Note that some 3-pole UL489-listed low-voltage breakers cannot be used in single-phase circuits.

\section*{Application to Domestic and International Standards}


Note 1. Examples of the recommended low-voltage breakers are given. UL489-listed low-voltage breakers that satisfy the ratings given above can be used.
Note that some 3-pole UL489-listed low-voltage breakers cannot be used in single-phase circuits.

\subsection*{10.12 Marine Certification Standard Products}
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{Magnetic Contactor Model} & \multirow[t]{2}{*}{\[
\begin{array}{|c|}
\hline \text { Certification Number } \\
\hline 14 \mathrm{~T} 401 \\
\hline
\end{array}
\]} & \multicolumn{2}{|l|}{Magnetic Contactor Model} & \multirow[t]{2}{*}{\[
\begin{array}{|c|}
\hline \text { Certification Number } \\
\hline 98 T 407 \\
\hline
\end{array}
\]} & \multirow[t]{2}{*}{\[
\begin{array}{|c|}
\hline \text { Magnetic Contactor Model } \\
\hline \text { SL(D)-N125NK }
\end{array}
\]} & \multirow[t]{2}{*}{\begin{tabular}{c} 
Certification Number \\
\hline 98 T 417
\end{tabular}} \\
\hline S-T10(BC)(SA) & - & & S-N125 & SD-N125 & & & \\
\hline S-T12(BC)(SA) & SD-T12(BC)(SA) & 14 T 402 & S-N150 & SD-N150 & \(98 T 408\) & SL(D)-N150NK & 987418 \\
\hline S-T20(BC)(SA) & SD-T20(BC)(SA) & 14 T 403 & S-N180 & - & 98 T 409 & SL(D)-N220NK & 987419 \\
\hline S-T21(BC)(SA) & SD-T21(BC)(SA) & 14 T 404 & S-N220 & SD-N220 & 987410 & SL(D)-N300NK & 98 T 420 \\
\hline S-T25(BC)(SA) & - & 14 T 405 & S-N300 & SD-N300 & 98 T 411 & SL(D)-N400NK & 98 T 421 \\
\hline S-T32(BC)(SA) & SD-T32(BC)(SA) & 14 T 406 & S-N400 & SD-N400 & 987412 & SL(D)-N600NK & 85 T 408 \\
\hline S-T35(BC)(SA) & SD-T35(BC)(SA) & 15 T 405 & S-N600 & SD-N600 & \(85 T 406\) & SL(D)-N800NK & 85T409 \\
\hline S-T50(BC)(SA) & SD-T50(BC)(SA) & 15 T 406 & S-N800 & SD-N800 & 85 T 407 & & \\
\hline S-T65(CW) & SD-T65(CW) & 15 T 407 & S-N38(CX)(SA) & - & \(96 T 402\) & & \\
\hline S-T80(CW) & SD-T80(CW) & 15 T 408 & S-N48(CX)(SA) & - & \(96 T 403\) & & \\
\hline S-T100 & SD-T100 & 15 T 410 & B-N65 & BD-N65 & 017401 & & \\
\hline B-T21 & BD-T21 & 17 T 402 & B-N100 & BD-N100 & 017402 & & \\
\hline
\end{tabular}

Note 1. S-T, S-N, SD-N, B-N and BD-N can be used as NK standards certified products
(Applicable with class AC-3 rating at 440 V or less. Model names with "BC" come with wiring streamlining terminals, "CX" and "CW" with terminal covers, and "SA" with built-in surge absorbers).
Note 2. The thermal overload relay is not covered by the standards.
Note 3. For SL(D)-N \(\square N K\), there is no product display of "NK" in the model name. (SL(D) uses NK certified wires for connection)

\section*{KR Standards (Korean Register of Shipping, South Korea Steel Ship Standards) Certified Magnetic Contactors}
\begin{tabular}{c|c||c|c||c|c}
\hline Magnetic Contactor Model & Certification Number & Magnetic Contactor Model & Certification Number & Magnetic Contactor Model & Certification Number \\
\hline S-T10(BC)(SA) & TKY02571-EL021 & S-T35(BC)(SA) & TKY02571-EL021 & S-N125 & KOB02571-EL020 \\
\hline S-T12(BC)(SA) & TKY02571-EL021 & S-T50(BC)(SA) & TKY02571-EL021 & S-N150 & KOB02571-ELO20 \\
\hline S-T20(BC)(SA) & TKY02571-EL021 & S-T65(CW) & TKY02571-EL021 & S-N180 & KOB02571-EL020 \\
\hline S-T21(BC)(SA) & TKY02571-EL021 & S-T80(CW) & TKY02571-EL021 & S-N220 & KOB02571-EL020 \\
\hline S-T25(BC)(SA) & TKY02571-EL021 & S-T100 & TKY02571-EL021 & S-N300 & KOB02571-ELO20 \\
\hline S-T32(BC)(SA) & TKY02571-EL021 & & & S-N400 & KOB02571-EL020 \\
\hline
\end{tabular}

Note 1. The standard types of the model names above can also be used as KR Standard products. (Applicable with class AC-3 rating at 440 V or less.)
Note 2. The thermal overload relay is not covered by the standards.

Lloyd Standards (Lloyd's Register of Shipping), BV Standards (Bureau Veritas, France Steel Ship Standards) Certified Magnetic Contactors, Thermal Overload Relays

\begin{tabular}{|c|c|c|c|c|}
\hline Model & Model Name & Loyd Certification Number & BV Cerrification Number & Remarks \\
\hline \multirow{3}{*}{Magnetic Contactors} & S-T10(BC)(SA), T12(BC)(SA), T20(BC)(SA), T21(BC)(SA), S-T25(BC)(SA), T32(BC)(SA), SD-T12(BC)(SA), T20(BC)(SA), T21(BC)(SA), T32(BC)(SA) & 14/10008 & \multirow[t]{2}{*}{38175} & \multirow[t]{2}{*}{Applicable with class AC-3 standard product at 440 V or less.} \\
\hline & S-T35(BC)(SA), T50(BC)(SA), T65(CW), T80(CW), T100 SD-T35(BC)(SA), T50(BC)(SA), T65(CW), T80(CW), T100 & 16/10003 & & \\
\hline & S-N125, N150, N180, N220, N300, N400, N600, N800 SD-N125, N150, N220, N300, N400, N600, N800 & 98/10016 & 07095 & Applicable with class AC-3 standard product at 690 V or less. (Note 2) \\
\hline \multirow[b]{3}{*}{Thermal Overload Relays} & TH-T18(AR)(BC)KP(YS), T25(AR)(BC)KP(YS) & 14/10010 & \multirow[b]{2}{*}{38176} & \multirow[t]{2}{*}{Applicable with standard product at 440 V or less.} \\
\hline & TH-T50(AR)(BC)KP(YS), T65KP, T100KP & 16/10004 & & \\
\hline & \begin{tabular}{l}
TH-N120(KP), N120TA(KP) \\
TH-N220RH(KP), N220HZ(KP), N400RH(KP), N400HZ(KP), N600(KP)
\end{tabular} & 98/10017 & 07905 & Applicable with standard product at 690 V or less. \\
\hline Contactor Relays & \[
\begin{aligned}
& \hline \text { SR-T5(BC)(SA), T9(BC)(SA) } \\
& \text { SRD-T5(BC)(SA), T9(BC)(SA) }
\end{aligned}
\] & 14/10009 & 38177 & \multirow{4}{*}{\begin{tabular}{l}
Applicable with class AC-15 \\
standard product at 550 V or less.
\end{tabular}} \\
\hline \multirow{3}{*}{Auxiliary Contact Unit} & UT-AX2(BC), AX4(BC), AX11(BC) & 14/10009 & 38174 & \\
\hline & UN-AX2 (CX), AX4 (CX), AX11 (CX) & 95/10010 & 06139 & \\
\hline & UN-AX80, AX150, AX600 & 98/10016 & 07905 & \\
\hline
\end{tabular}

Note 1. MSO is also applicable as standard.
Note 2. The control circuit contact is applicable at 550 V or less.

\section*{Application to Domestic and International Standards}

\section*{Magnetic Contactors and Thermal Overload Relays Certified by China Classification Society (CCS)}
\begin{tabular}{|c|c|c|}
\hline Model & Model Name & CCS Certification Number \\
\hline Magnetic Contactors & \[
\begin{aligned}
& \text { SD-T12, T20, T21, T32, T35, T50, T65, T80, T100 } \\
& \text { S-N125, N150, N180, N220, N300, N400, N600, N800 } \\
& \text { SD-N125, N150, N220, N300, N400, N600, N800 } \\
& \hline
\end{aligned}
\] & DB18T00165 \\
\hline Thermal Overload Relays & TH-T65KP, T100KP TH-N120KP, N120TAKP, N220RHKP, N220HZKP TH-N400RHKP, N400HZKP, N600KP & DB18T00166 \\
\hline Auxiliary Contact Unit & \begin{tabular}{l}
UT-AX2, AX4, AX11 \\
UN-AX2, AX4, AX11, AX80, AX150, AX600
\end{tabular} & DB18T00165 \\
\hline
\end{tabular}

\subsection*{10.13 How to Order}

\section*{1. Targeted Electrical Appliances}

Enclosed magnetic starters applicable to three-phase 200 V and single-phase 100 V. Same as standard products, except for single-phase circuit use. Refer to the section (page 267) of MS (enclosed type). When ordering the single-phase circuit use type, add "DP" at the end of the model name.

MS-T10DP \(\triangle 0.2 \mathrm{~kW} \triangle 110 \mathrm{~V} \triangle \mathrm{AC} 100 \mathrm{~V}\)

\section*{2. NK Standard Products}
- Standard products are applied as they are for S-T, S-N, SD-N, B-T, B-N and BD-T, BD-N.
- When ordering \(\operatorname{SL}(\mathrm{D})-\mathrm{N}\), add "NK" at the end of the model name as it uses NK certified wires.

The rest are the same as the standard product. Refer to page 301.
SL-N125NK \(\boldsymbol{A C}\) MC-AC400V \(\boldsymbol{A}\) MT-AC400V

\section*{3. UL/CSA Standard Products}

Other than the model name, the ordering method is the same as that of standard products. For model names (standard or dedicated products), refer to page 269.

\section*{4. CCC Certified Products}
- Referring to page 285, always add "CN" at the end of the model name when ordering products marked " ○ Certified (add "CN" at the end of the model name when ordering)."
S-N600CN \(\triangle\) AC200V
It should be noted that although "CN" is displayed in the model name on the packaging box, it is not displayed on the product.

\section*{5. KC Certified Products}

Referring to page 294, always add "KK" at the end of the model name when ordering.
S-T10KK \(\triangle\) AC200V

\section*{6. Other International Standards}
- Standard products are compliant with KR Standards (certified products), Lloyd Standards (certified products), BV Standards (certified product), NEMA Standards, IEC Standards, BS Standards, EN Standards and VDE Standards. Refer to pages 267 and 301 regarding application.
- If EAC certified products (for Russia) are needed, consult with your dealer or with us.

\section*{Related Equipment}
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11.2 Solid State Contactors for Motor/Heater Loads
US-N \(\square\), US-H \(\square . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . ~\) 306
11.3 Application to Each Load ......................... 314
11.4 Application Precautions........................... 318
11.5 Optional Units ......................................... 323
11.6 Outline Drawings ...................................... 337
11.7 Electric Motor Protection Relays
ET-N \(\square \ldots . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . ~\)
340
11.8 Voltage Detection Relays SRE ............... 344
11.9 Instantaneous Stop/Restart Relays
UA-DL2 ................................................ 346
11.10 How to Order ........................................ 348

\section*{Related Equipment}

\subsection*{11.1 Model List (US-N, US-H Series)}

\section*{US-N \(\square\) Solid State Contactors (Standard Models)}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{3}{|r|}{Category AC-1 Rated
Operating Current (A) (Note 6)} & 5 & 8 & 20 & 30 & 40 & 50 & 70 & 80 \\
\hline \multirow[b]{4}{*}{\[
\begin{aligned}
& 0 \\
& 0 . \\
& \lambda \\
& \lambda \\
& 0 \\
& 0 \\
& 0 \\
& 0
\end{aligned}
\]} & \multirow[t]{2}{*}{Heater Capacity (kW)} & \[
\begin{aligned}
& 1 \varphi 200 \mathrm{~V} \\
& \text { (Note 1) } \\
& \hline
\end{aligned}
\] & 1 & 1.6 & 4 & 6 & 8 & 10 & 14 & 16 \\
\hline & & \(3 \varphi 200 \mathrm{~V}\) & 1.7 & 2.7 & 6.9 & 10.3 & 13.8 & 17.3 & 24.2 & 27.7 \\
\hline & \multicolumn{2}{|l|}{Maximum Applicable Motor Capacity (kW) \(3 \varphi 200 \mathrm{~V}\) (Note 2)} & 0.4 & 0.4 & 2.2 & 3.7 & 5.5 & 5.5 & 11 & 11 \\
\hline & \multicolumn{2}{|l|}{For 3-Phase Loads US-N \(\square\)} & US-N5SS US-N5SSTE & US-N8SS US-N8SSTE & US-N20 US-N20TE & \begin{tabular}{l}
US-N30 US-N30TE \\
(Note 3)
\end{tabular} & US-N40 US-N4OTE &  & US-N70NS US-N70NSTE & US-N80NS US-N80NSTE \\
\hline \multirow[b]{5}{*}{\[
\begin{aligned}
& 0 \\
& \stackrel{2}{\lambda} \\
& \lambda \\
& 0 \\
& 0 \\
& 0 \\
& 0
\end{aligned}
\]} & \multicolumn{2}{|l|}{Category AC-1 Rated Operating Current (A) (Note 6)} & & & 20 & 30 & 40 & 50 & 70 & 80 \\
\hline & \multirow[t]{2}{*}{Heater Capacity (kW)} & \[
\begin{aligned}
& 1 \varphi 400 \mathrm{~V} \\
& \text { (Note 1) }
\end{aligned}
\] & & & 8 & 12 & 16 & 20 & 28 & 32 \\
\hline & & \(3 \varphi 400 \mathrm{~V}\) & & & 13.8 & 20.7 & 27.7 & 34.6 & 48.5 & 55.4 \\
\hline & \multicolumn{2}{|l|}{Maximum Applicable Motor Capacity (kW) \(3 \varphi 400 \mathrm{~V}\) (Note 2)} & & & 3.7 & 7.5 & 11 & 11 & 22 & 22 \\
\hline & \multicolumn{2}{|l|}{\begin{tabular}{l}
For 3-Phase Loads US-N \(\square\) \\
US-NH \(\square\)
\end{tabular}} & & &  & US-N30 US-N30TE (Note 3) & US-N40 US-N4OTE &  & US-NH70NS US-NH70NSTE & US-NH80NS US-NH80NSTE \\
\hline \multicolumn{3}{|l|}{IEC 35 mm Rail Mounting} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Possible With Standard Products}} & (Note 5) & & \multicolumn{3}{|l|}{\multirow[b]{2}{*}{Equipped With Standard Products}} & \\
\hline \multicolumn{3}{|l|}{Live Part Protection Cover Units} & & & & & & & & \\
\hline \multicolumn{3}{|c|}{Drive Units} & & & & & \multicolumn{3}{|l|}{JA-DR1} & \\
\hline \multicolumn{3}{|r|}{Drive Units with Outputs} & \multicolumn{2}{|r|}{UA-SH8 (Note 9)} & & & \multicolumn{3}{|l|}{JA-SH1} & \\
\hline \multicolumn{3}{|c|}{Reversing Units} & & & & & \multicolumn{3}{|l|}{JA-RE} & \\
\hline \multicolumn{3}{|r|}{Fault Detection Units} & & & & & \multicolumn{4}{|l|}{UN-FD (For 200 V Main Circuits)/UN-FD4 (For 400 V Main Circuits)} \\
\hline \multicolumn{3}{|r|}{Power Control Units} & \multicolumn{8}{|c|}{UA-PC} \\
\hline \multicolumn{3}{|c|}{Options (Note 4)} & \multicolumn{2}{|l|}{UA-SH8} & \[
\begin{aligned}
& 31 \\
& 2 \\
& 29 \\
& 24 \\
& \text { UA-DR1 }
\end{aligned}
\] &  & UA-RE & \multicolumn{2}{|c|}{} &  \\
\hline
\end{tabular}

\section*{US-H \(\square\) Solid State Contactors}
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{Category AC-1 Rated Operating Current (A) \(\left(-10\right.\) to \(\left.40^{\circ} \mathrm{C}\right)\) (Note 6)} & 20 & 30 & 40 & 50 \\
\hline \multirow[t]{3}{*}{\begin{tabular}{l}
Heater \\
Capacity (kW) (-10 to \(40^{\circ} \mathrm{C}\) ) (Note 6, Note 7)
\end{tabular}} & \(1 \varphi 200 \mathrm{~V}\) & 4 & 6 & 8 & 10 \\
\hline & \(3 ¢ 200 \mathrm{~V}\) & 6.9 & 10.3 & 13.8 & 17.3 \\
\hline & \(3 \varphi 400 \mathrm{~V}\) & 13.8 & 20.7 & 27.7 & 34.6 \\
\hline \multicolumn{2}{|l|}{US-H■} & \[
\begin{gathered}
\text { US-H2O } \\
\text { US-H2ODD }
\end{gathered}
\] &  &  &  \\
\hline \multicolumn{2}{|l|}{\begin{tabular}{l}
US-H \(\square\) UF \\
(Width Reduced Product)
\end{tabular}} & \[
\begin{aligned}
& \text { User } \\
& \text { US-H2OUF } \\
& \text { US-H2ODDUF }
\end{aligned}
\] &  & - & - \\
\hline \multirow[t]{2}{*}{IEC 35 mm Rail Mounting} & US-H口 & \multicolumn{2}{|r|}{(Note 5)} & \multicolumn{2}{|c|}{-} \\
\hline & US-HDUF & \multicolumn{2}{|l|}{Standard Equipment} & \multicolumn{2}{|c|}{-} \\
\hline \multirow{3}{*}{Optional} & Fault Detection Units & \multicolumn{4}{|l|}{UN-FD (For 200 V Main Circuits)/UN-FD4 (For 400 V Main Circuits)} \\
\hline & Power Control Units & \multicolumn{4}{|c|}{UA-PC} \\
\hline & Live Par Protection Cover Units & \multicolumn{4}{|c|}{UN-CV501US} \\
\hline
\end{tabular}

Note 1. Indicates the capacity per pole.
Note 2. The applicable motor load capacities differ depending on operating conditions. Refer to page 315 for details.
Note 3. The photo shows a US-N \(\square\) TE type model. The outline drawings are smaller for US-N \(\square\) types. Refer to page 337 for details regarding outline drawings.
Note 4. \(\square\) in the optional unit column indicates the applicable range.
Note 5. Possible with a dedicated product (US- \(\square\) RM).
Note 6. If the ambient temperature is \(40^{\circ} \mathrm{C}\) or more, use the rated operated current multiplied by the reduced rate shown in figure 1 on page 318.
Note 7. Indicates the value when using batch control as the main circuit control method.
Note 8. Refer to page 335 for optional live part protection covers.
Note 9. When mounting UA-SH8 drive units with outputs to US-N5SS/ N8SS(TE) types, first remove the US-N \(\square\) type body cover.

\section*{Related Equipment}

\subsection*{11.2 US-N \(\square\) (For Motor/Heater Loads), US-H \(\square\) (For Heater Loads) Solid State Contactors}

A combined series consisting of US-N series types for motor and heater loads together with US-H series types dedicated for heater loads.
US-N series are solid state contactors that are ideal for frequently switched motor loads such as on conveyor lines, and can be used for both motor and heater loads.
US-H series are dedicated heater load solid state contactors that are ideal for heater loads such as injection molding machinery or semiconductor manufacturing equipment.

\section*{Features}
- Realizes a Long Product Lifetime When Used for High-frequency Switching Applications Realizes a long product lifetime when used for frequently switching applications by using a power semiconductor element.
- Applicable for a Wide Range of Main Circuit Voltages (US-N, US-H)
Can be used over a wide range of main circuit voltages with US-N20 type supporting AC100 to 480 V and
US-H20 to H50 types supporting AC24 to 480 V .
- Compatible with a Large Number of International Standards (US-N, US-H) Our standard products comply with the domestic standards as well as various overseas standards and are certified as meeting all of the standards.
- JEM Standards
- IEC Standards
- UL, CSA Standards
-EC Directives
-TÜV Certified
- CCC Certification


US-N20TE

\section*{- No Noise and Clean Running}

Zero switching noise and clean running without generating dust due to wear.
- Live Part Protection Covers for Improved Safety (US-N, US-H)
Live part protection covers with finger protection functionality and compliance with DIN and VDE regulations have been made standard equipment for US-N series models and an optional add-on (UN-CV501US) for US-H series models.
- Indicator Lamps for Confirmation of Operation Standardized
With indicator lamps on the front surface, the operating voltage input status can be checked at a glance.
- A Wide Selection of Optional Units

The range of solid state contactor application is expanded greatly by using in combination with an abundant range of optional parts including drive units (UA-DR1) and reversing units (UA-RE).

\section*{Type Designations}
(1) US-N Solid State Contactors (3-Pole Type)

(2) US-H Solid State Contactors

(3) Optional Units


\section*{Related Equipment}

\subsection*{11.2.1 US-N \(\square\) Solid State Contactors}
- Ratings/Specifications
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline & & & \multicolumn{4}{|c|}{3-Pole Type} \\
\hline \multicolumn{3}{|c|}{Appearance} &  &  &  & त्वत्तम: \\
\hline \multirow{7}{*}{} & \multirow{3}{*}{Standard} & Single-Pole Type & - & - & - & - \\
\hline & & 3-Pole 2-Element Type & US-N5SS & US-N8SS & US-N20 & US-N30 \\
\hline & & 3-Pole 3-Element Type & US-N5SSTE & US-N8SSTE & US-N20TE & US-N30TE \\
\hline & \multirow[t]{2}{*}{With CAN Terminal} & 3-Pole 2-Element Type & - & - & US-N20CX & US-N30CX \\
\hline & & 3-Pole 3-Element Type & - & - & US-N20TECX & US-N30TECX \\
\hline & \multirow[t]{2}{*}{IEC 35 mm Rail Mounting} & 3-Pole 2-Element Type & (Note 1) & (Note 1) & US-N20RM & - \\
\hline & & 3-Pole 3-Element Type & (Note 1) & (Note 1) & US-N20TERM & - \\
\hline \multirow{9}{*}{\[
\begin{aligned}
& \text { 읻 } \\
& \text { 둗 }
\end{aligned}
\]} & \multirow[t]{2}{*}{Rated Operating Current (-10 to \(40^{\circ} \mathrm{C}\) ) (Note 2)} & JEM (Category AC-1) & 5 A & 8 A & 20 A & 30 A \\
\hline & & IEC (Category AC-51) & 5 A & 8 A & 20 A & 30 A \\
\hline & \multirow{4}{*}{Applicable Heater Capacity
\[
\left(-10 \text { to } 40^{\circ} \mathrm{C}\right)
\]} & \(1 \varphi 200 \mathrm{~V}\) (Note 4) & 1 kW & 1.6 kW & 4 kW & 6 kW \\
\hline & & \(3 \varphi 200 \mathrm{~V}\) & 1.7 kW & 2.7 kW & 6.9 kW & 10.3 kW \\
\hline & & \(1 \varphi 400 \mathrm{~V}\) (Note 4) & - & - & 8 kW & 12 kW \\
\hline & & \(3 \varphi 400 \mathrm{~V}\) & - & - & 13.8 kW & 20.7 kW \\
\hline & \multirow[t]{2}{*}{Maximum Applicable Motor Capacity (Maximum Operating Current (Note 5))} & \(3 \varphi 200 \mathrm{~V}\) & 0.4 kW (3.2 A) & 0.4 kW (3.2 A) & 2.2 kW (11.1 A) & 3.7 kW (17.4 A) \\
\hline & & \(3 \varphi 400 \mathrm{~V}\) & - & - & 3.7 kW (8.7 A) & 7.5 kW (17.4 A) \\
\hline & \multicolumn{2}{|l|}{Minimum Load Current} & \multicolumn{2}{|c|}{150 mA} & \multicolumn{2}{|c|}{300 mA} \\
\hline & \multicolumn{2}{|l|}{Main Circuit Control Method} & \multicolumn{4}{|c|}{Batch Control} \\
\hline \(\stackrel{\square}{0}\) & \multicolumn{2}{|l|}{Rated Operational Voltage} & \multicolumn{2}{|l|}{AC100 to \(240 \mathrm{~V} 50 / 60 \mathrm{~Hz}\)} & \multicolumn{2}{|l|}{AC100 to \(480 \mathrm{~V} 50 / 60 \mathrm{~Hz}\)} \\
\hline \[
\frac{\stackrel{\circ}{6}}{\stackrel{\circ}{\sigma}}
\] & \multicolumn{2}{|l|}{Operating Voltage} & \multicolumn{4}{|c|}{85 to 110\% of Rated Operational Voltage} \\
\hline \(\stackrel{\text { ¢ }}{4}\) & \multicolumn{2}{|l|}{Rated Insulation Voltage} & \multicolumn{2}{|c|}{AC250 V} & \multicolumn{2}{|c|}{AC500 V} \\
\hline - & \multicolumn{2}{|l|}{Making Voltage Drop} & \multicolumn{4}{|c|}{1.5 V/Phase} \\
\hline O & \multicolumn{2}{|l|}{Open Circuit Leakage Current} & \multicolumn{2}{|l|}{15 mA or Less (AC240 V 60 Hz )} & \multicolumn{2}{|l|}{30 mA or Less (AC480 V 60 Hz )} \\
\hline \[
\begin{aligned}
& \text { 亏ָ } \\
& \text { ָ̄ }
\end{aligned}
\] & \multicolumn{2}{|l|}{Surge ON Current ( \(60 \mathrm{~Hz}, 1\) Half-Wave Cycle Peak Value)} & \multicolumn{2}{|c|}{160 A} & 800 A & 1300 A \\
\hline \[
\frac{. \bar{c}}{\bar{\sigma}}
\] & \multicolumn{2}{|l|}{Tolerance \(\mathrm{I}^{2} \mathrm{t}\left(\mathrm{A}^{2} \mathrm{~s}\right)\)} & \multicolumn{2}{|c|}{106} & 2600 & 7000 \\
\hline \(\Sigma\) & \multicolumn{2}{|l|}{Trigger System} & \multicolumn{4}{|c|}{Zero Voltage Trigger System} \\
\hline & \multicolumn{2}{|l|}{Making and Breaking Capacities} & 32 A & 50 A & 111 A & 174 A \\
\hline & \multicolumn{2}{|l|}{Rated Operational Voltage} & \multicolumn{4}{|c|}{DC12 to 24 V (10\% or Less Voltage Ripple)} \\
\hline & \multicolumn{2}{|l|}{Operating Voltage Fluctuation Range} & \multicolumn{4}{|c|}{85 to 110\% of Rated Operational Voltage} \\
\hline \(\stackrel{\square}{\text { ¢ }}\) & \multicolumn{2}{|l|}{Control Circuit Maximum Applied Voltage} & \multicolumn{4}{|c|}{DC26.4 V} \\
\hline \% & \multicolumn{2}{|l|}{Control Circuit Input Current} & \multicolumn{2}{|c|}{20 mA (DC12 to 24 V )} & \multicolumn{2}{|c|}{5 mA (DC12 to 24 V )} \\
\hline : & \multicolumn{2}{|l|}{Input Impedance} & \multicolumn{2}{|c|}{0.6 to \(1.2 \mathrm{k} \Omega\)} & \multicolumn{2}{|c|}{2.4 to \(4.8 \mathrm{k} \Omega\)} \\
\hline ¢ & \multicolumn{2}{|l|}{Closing Voltage} & \multicolumn{4}{|c|}{DC9 V or Less} \\
\hline 苟 & \multicolumn{2}{|l|}{Openning Voltage} & \multicolumn{4}{|c|}{DC3 V or More} \\
\hline - & \multicolumn{2}{|l|}{Response Time} & \multicolumn{4}{|c|}{Max. 1 ms + 1/2 Cycle} \\
\hline \(\bigcirc\) & \multicolumn{2}{|l|}{Operation Indicator} & \multicolumn{4}{|c|}{LED Indicator (Lights When Operating Voltage Applied)} \\
\hline \[
\begin{aligned}
& E \\
& 0 \\
& \hline
\end{aligned}
\] & \multicolumn{2}{|l|}{Cooling Fan Rated operational Voltage (Note 6)} & \multicolumn{4}{|c|}{-} \\
\hline & \multirow[b]{2}{*}{Fan Fault Detection Output} & Contact Arrangement & \multicolumn{4}{|c|}{-} \\
\hline & & Contact Capacity & \multicolumn{4}{|c|}{-} \\
\hline & \multicolumn{2}{|l|}{Withstand Voltage} & \multicolumn{2}{|c|}{2 kV} & \multicolumn{2}{|c|}{2.5 kV} \\
\hline \(\stackrel{\text { c }}{ }\) & \multicolumn{2}{|l|}{Insulation Resistance} & \multicolumn{4}{|c|}{\(100 \mathrm{M} \Omega\)} \\
\hline \% & \multicolumn{2}{|l|}{Rated Impulse Withstand Voltage (Note 7)} & \multicolumn{2}{|c|}{4 kV} & \multicolumn{2}{|c|}{6 kV} \\
\hline - & \multicolumn{2}{|l|}{Operating Ambient Temperature} & \multicolumn{4}{|c|}{-10 to \(60^{\circ} \mathrm{C}\) (Use at Reduced Current When \(40^{\circ} \mathrm{C}\) or More)} \\
\hline ¢ & Relative Temperature & & \multicolumn{4}{|c|}{45\% to 85\% RH} \\
\hline ¢ & \multicolumn{2}{|l|}{Altitude} & \multicolumn{4}{|c|}{2,000 m or below} \\
\hline Ê & Vibration-Resistant & & & 10 to & \(6 \mathrm{~m} / \mathrm{s}^{2}\) & \\
\hline \(\bigcirc\) & \multicolumn{2}{|l|}{Shock-Resistant} & \multicolumn{4}{|c|}{\(98 \mathrm{~m} / \mathrm{s}^{2}\)} \\
\hline
\end{tabular}

Note 1. Applicable with standard products.
Note 2. If the ambient temperature is \(40^{\circ} \mathrm{C}\) or more, use the rated operated current multiplied by the reduced rate shown in the figure at right.
Note 3. The value in [] indicates the IEC (class AC-51) rating for US-N50TE(CX) types.
Note 4. Indicates the capacity per element.
Note 5. Indicates the applicable capacities when selecting solid state contactors by their element capacities.
The applicable motor capacities differ depending on motor operating conditions. Refer to page 315 for information regarding selection.


Ambient Temperature ( \({ }^{\circ} \mathrm{C}\) )

Note 6. Special fan products with rated voltages of AC100 to 110 V can also be manufactured.
Note 7. In accordance with IEC60947-1.
Note 8. Consult with us separately if information on the amount of heat generated by the main circuit is required.
\begin{tabular}{|c|c|c|c|}
\hline \multicolumn{4}{|c|}{3-Pole Type} \\
\hline  &  &  &  \\
\hline - & - & - & - \\
\hline US-N40 & US-N50 & US-N70NS & US-N80NS \\
\hline US-N40TE & US-N50TE & US-N70NSTE & US-N80NSTE \\
\hline US-N40CX & US-N50CX & - & - \\
\hline US-N40TECX & US-N50TECX & - & - \\
\hline - & - & - & - \\
\hline - & - & - & - \\
\hline 40 A & 50 A & 70 A & 80 A \\
\hline 40 A & \(50 \mathrm{~A}[45 \mathrm{~A}]^{\text {Note } 3}\) & 70 A & 80 A \\
\hline 8 kW & \(10 \mathrm{~kW}[9 \mathrm{~kW}]^{\text {Note } 3}\) & 14 kW & 16 kW \\
\hline 13.8 kW & 17.3 kW [15.5 kW] \({ }^{\text {Note } 3}\) & 24.2 kW & 27.7 kW \\
\hline 16 kW & 20 kW [18 kW] \({ }^{\text {Note } 3}\) & - & - \\
\hline 27.7 kW & 34.6 kW [31.1 kW] \({ }^{\text {Note } 3}\) & - & - \\
\hline 5.5 kW (26 A) & 5.5 kW (26 A) & 11 kW (48 A) & 11 kW (48 A) \\
\hline 11 kW (26 A) & 11 kW (26 A) & & \\
\hline \multicolumn{4}{|c|}{300 mA} \\
\hline \multicolumn{4}{|c|}{Batch Control} \\
\hline \multicolumn{2}{|c|}{AC100 to \(480 \mathrm{~V} 50 / 60 \mathrm{~Hz}\)} & \multicolumn{2}{|c|}{AC100 to \(240 \mathrm{~V} 50 / 60 \mathrm{~Hz}\)} \\
\hline \multicolumn{4}{|c|}{85 to 110\% of Rated Operational Voltage} \\
\hline \multicolumn{2}{|c|}{AC500 V} & \multicolumn{2}{|c|}{AC250 V} \\
\hline \multicolumn{4}{|c|}{1.5 V/Phase} \\
\hline \multicolumn{2}{|c|}{30 mA or Less (AC480 V 60 Hz )} & \multicolumn{2}{|c|}{30 mA or Less (AC240 V 60 Hz )} \\
\hline \multicolumn{4}{|c|}{1800 A} \\
\hline \multicolumn{4}{|c|}{13500} \\
\hline \multicolumn{4}{|c|}{Zero Voltage Trigger System} \\
\hline \multicolumn{2}{|c|}{260 A} & \multicolumn{2}{|c|}{480 A} \\
\hline \multicolumn{4}{|c|}{DC12 to 24 V (10\% or Less Voltage Ripple)} \\
\hline \multicolumn{4}{|c|}{85 to 110\% of Rated Operational Voltage} \\
\hline \multicolumn{4}{|c|}{DC26.4 V} \\
\hline \multicolumn{2}{|c|}{5 mA (DC12 to 24 V )} & \multicolumn{2}{|c|}{20 mA (DC12 to 24 V )} \\
\hline \multicolumn{2}{|c|}{2.4 to \(4.8 \mathrm{k} \Omega\)} & \multicolumn{2}{|c|}{0.6 to \(1.2 \mathrm{k} \Omega\)} \\
\hline \multicolumn{4}{|c|}{DC9 V or Less} \\
\hline \multicolumn{4}{|c|}{DC3 V or More} \\
\hline \multicolumn{4}{|c|}{Max. 1 ms + 1/2 Cycle} \\
\hline \multicolumn{4}{|c|}{LED Indicator (Lights When Operating Voltage Applied)} \\
\hline \multicolumn{2}{|c|}{-} & \multicolumn{2}{|c|}{AC200 to \(240 \mathrm{~V} 50 / 60 \mathrm{~Hz}\)} \\
\hline \multicolumn{2}{|c|}{-} & \multicolumn{2}{|c|}{Break Contact} \\
\hline \multicolumn{2}{|c|}{-} & \multicolumn{2}{|c|}{DC5 to \(24 \mathrm{~V} / \mathrm{AC} 100\) to 240 V 0.1 A} \\
\hline \multicolumn{2}{|c|}{2.5 kV} & \multicolumn{2}{|c|}{2 kV} \\
\hline \multicolumn{4}{|c|}{\(100 \mathrm{M} \Omega\)} \\
\hline \multicolumn{2}{|c|}{6 kV} & \multicolumn{2}{|c|}{4 kV} \\
\hline \multicolumn{4}{|c|}{-10 to \(60^{\circ} \mathrm{C}\) (Use at Reduced Current When \(40^{\circ} \mathrm{C}\) or More)} \\
\hline \multicolumn{4}{|c|}{45\% to 85\% RH} \\
\hline \multicolumn{4}{|c|}{2,000 m or below} \\
\hline \multicolumn{4}{|c|}{10 to \(55 \mathrm{~Hz} 19.6 \mathrm{~m} / \mathrm{s}^{2}\)} \\
\hline \multicolumn{4}{|c|}{\(98 \mathrm{~m} / \mathrm{s}^{2}\)} \\
\hline
\end{tabular}

\section*{Related Equipment}

\section*{Circuits}

Figures 1 to 4 show the block circuit diagrams for US-N(H) \(\square\) types.


Note 1. The main circuit and control circuit are isolated via a photocoupler.
Note 2. US-N \((H) \square\) types adopt a zero voltage trigger system.
Note 3. US-N20/N30/N40/N50(TE) types do not have A3 and A4 terminals.
Note 4. A cooling fan and fan fault detector are integrated into US-N(H)70/N(H)80NS(TE) types.
Note 5. Control circuit wiring (FA1, FA2, OT1 and OT2 terminals) must be used for models with an integrated cooling fan and fan fault detector. (Refer to the Connections section)
Refer to "Application Precautions" for information regarding handling of cooling fans.

\section*{Connecting}

Figures 5 to 7 show sample circuit connections for US-N(H) \(\square\) types.
Use a low signal contact if using a contact in place of a transistor as the drive signal for US-N(H) \(\square / \mathrm{K}(\mathrm{H}) \square\) types.


Note. Refer to page 281 for information regarding CE Mark compliance.


Note. Refer to page 281 for information regarding CE Mark compliance.

\subsection*{11.2.2 US-H \(\square\) Solid State Contactors}

\section*{- Ratings/Specifications}


Note 1. If the ambient temperature is \(40^{\circ} \mathrm{C}\) or more, use the rated operated current multiplied by the reduced rate shown in figure 1 on page 318 .
Note 2. US-H \(\square \mathrm{HZ}\) types without cooling fins can also be manufactured. Refer to the Applications column on page 313 for information regarding US-H \(\square \mathrm{HZ}\) type application.
Note 3. US-H \(\square\) types are solid state contactors for heater loads. Do not use with motor loads, as they are not applicable.

\section*{Circuit}

Fig. 1 US-H20/H30/H40/H50 (Batch Control)


Fig. 2 US-H20/H30/H40/H50DD (Individual Control)


\section*{Related Equipment}

\section*{Connecting}


Note 1. Connect the load directly to the power supply for single-phase operation.
Note 2. The rated current of US-H \(\square\) types should be selected to match the heater current


Note 1. Connect the load directly to the power supply for single-phase operation.
Note 2. Heater current is \(\sqrt{ } 3\) times for US-H \(\square\) types, so the rated current of US-H \(\square\) types should be selected accordingly.


Note 1. The solid line __ indicates \(\sqrt{ } 3\) times the heater current, so the current capacity of the power wiring should be selected accordingly to withstand the current. Note 2. 2 heaters can be independently controlled when using US-H \(\square\) DD (individual control) types.



Note 1. The solid line ___ indicates double the heater current, so the current capacity of the power wiring should be selected accordingly to withstand the current.
Note 2. 2 heaters can be independently controlled when using US-H \(\square\) DD (individual control) types.

\section*{US-H \(\square\) HZ (Without Cooling Fins) Application}

US-H \(\square\) (DD)HZ solid state contactors are US-H \(\square\) (DD) types without the cooling fins, allowing for combination with cooling fins that give your desired performance and cooling fins to suit the load conditions.
(1) Rating

The operating current when combining with fins with the same thermal resistance value as US-H \(\square\) (DD) types or when directly mounted to control panels (iron plate) is indicated in the table below.

Operating Current Based on Mounting Conditions
\begin{tabular}{c|c|c}
\hline Model Name & For Fins With Thermal Resistance Equivalent to US-H (DD) (Cooling Fin Thermal Resistance Value: \(0.42^{\circ} \mathrm{CM}\) ) & For Direct Mounting to Control Board Mounting Panels (Iron Plate) (Thermal Resistance Value: \(\left.3^{\circ} \mathrm{C} / \mathrm{M}\right)\) \\
\hline US-H2O(DD)HZ & 20 A & 5 A \\
\hline US-H3O(DD)HZ & 30 A & 8 A \\
\hline US-H4O(DD)HZ & 40 A & 9 A \\
\hline US-H50(DD)HZ & 50 A & 10 A \\
\hline
\end{tabular}

Note. Calculate the operating current for thermal resistances differing from the table above using the operating currents for cooling fin thermal resistance values in Figure 8.


\section*{(2) Mounting}
1. The surface to which US-H \(\square(D D) H Z\) types are mounted (cooling fins or control panel) should have flatness within \(50 \mu \mathrm{~m}\).
2. When mounting to cooling fins or control panel, apply a 0.1 mm thick coating of thermal compound with good heat-transfer properties to the rear surface of US-H \(\square(\mathrm{DD}) \mathrm{HZ}\) types.
Thermal Compound (E.g.) G-747 (Shin-Etsu Silicone)
3. Use 2 M 4 screws with a tightening torque of 1.2 to \(2.05 \mathrm{~N} \cdot \mathrm{~m}\) when mounting to cooling fins or control panels.
4. The US-H \(\square(D D) H Z\) type connects to the control circuit terminal from the side, so some space to the sides is required for wiring. Secure the amount of wiring space indicated by dimension A in Figure 9.

\section*{Fig. 9 US-H■(DD)HZ Wiring Space}

\begin{tabular}{l|c}
\hline \multicolumn{1}{c|}{ Model Name } & A Dimension \\
\hline US-H \(\square H Z\) & 20 mm or More \\
\hline US-H■DDHZ & 30 mm or More \\
\hline
\end{tabular}

\section*{Related Equipment}

\subsection*{11.3 Application to Each Load}

\subsection*{11.3.1 US-N \(\square\) Solid State Contactors}

\section*{- Heater Load}

The table below shows the AC rated operating current applicable with heater loads (JEM1441 (class AC-1), IEC60947-4-3 (Class AC-51)).
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Model Name} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{Rated Operating Current (A)}} & \multicolumn{5}{|c|}{Applicable Heater Capacity (kW)} \\
\hline & & & \multicolumn{3}{|c|}{Single-Phase} & \multicolumn{2}{|c|}{Three-Phase} \\
\hline & JEM (Category AC-1) & IEC (Category AC-51) & 100 V & 200 V & 400 V & 200 V & 400 V \\
\hline US-N5SS(TE) & 5 & 5 & 0.5 & 1 & - & 1.7 & - \\
\hline US-N8SS(TE) & 8 & 8 & 0.8 & 1.6 & - & 2.7 & - \\
\hline US-N20(TE)(CX)(RM) & 20 & 20 & 2 & 4 & 8 & 6.9 & 13.8 \\
\hline US-N30(TE)(CX) & 30 & 30 & 3 & 6 & 12 & 10.3 & 20.7 \\
\hline US-N40(TE)(CX) & 40 & 40 & 4 & 8 & 16 & 13.8 & 27.7 \\
\hline US-N50(CX) & 50 & 50 & 5 & 10 & 20 & 17.3 & 34.6 \\
\hline US-N50TE(CX) & 50 & 45 & 4.5 & 9 & 18 & 15.5 & 31.1 \\
\hline US-N70NS(TE) & 70 & 70 & 7 & 14 & - & 24.2 & - \\
\hline US-N80NS(TE) & 80 & 80 & 8 & 16 & - & 27.7 & - \\
\hline US-NH70NS(TE) & 70 & 65 & - & 14 & 28 & 24.2 & 48.5 \\
\hline US-NH80NS(TE) & 80 & 75 & - & 16 & 32 & 27.7 & 55.4 \\
\hline
\end{tabular}

Note 1. Rating applicable for -10 to \(40^{\circ} \mathrm{C}\) ambient temperature. If the temperature is \(40^{\circ} \mathrm{C}\) or more, use the rated operated current multiplied by the reduced rate shown in Figure 1 on page 318.
Note 2. Calculate the applicable heater capacity using the equations below. For single-phase: power supply voltage \(x\) load current For three-phase: \(\sqrt{3} \times\) power supply voltage \(\times\) load current ( \(3 \times\) power supply voltage \(x\) load current for delta connections)
Note 3. An energizing inrush current flows for heater loads when US-N is connected on the primary side of the transformer. Take this inrush current into account when making a selection. (Refer to technical documents)

\section*{Motor Load}

For applications with direct start motor loads, an applicable solid state contactor frame size should be determined based on motor starting current, starting time, switching frequency and utilization. Accordingly, it is necessary to clarify the application conditions for practical use and select a frame size that will support them.
Figure 1 and page 315 show examples for selecting a US-N solid state contactor based on the operating conditions.
Refer to page 320 for selection of solid state contactors with no-fuse breakers, thermal overload relays and quick-trip fuse protection functions.

\section*{Fig. 1 Current Pattern for Motor Direct Start}


\author{
Im : Rated Current \\ ts: Starting Time \\ T1: Current Flow Time \\ T2 : Downtime \\ Utilization: \(\left(\frac{\mathrm{T} 1}{\mathrm{~T} 1+\mathrm{T} 2}\right) \times 100\)
}

\section*{(1) 200 V Main Circuit Motor}
- Selection Criteria A (Switching Frequency: 1200 Times/Hour, Utilization: 25\%, Starting Current: 6 Times Full-Load Current, Ambient Temperature \(40^{\circ} \mathrm{C}\) )

- Selection Criteria B (Switching Frequency: 600 Times/Hour, Utilization: 40\%, Starting Current: 6 Times Full-Load Current, Ambient Temperature \(40^{\circ} \mathrm{C}\) )

- Selection Criteria C (Switching Frequency: 150 Times/Hour, Utilization: 60\%, Starting Current: 6 Times Full-Load Current, Ambient Temperature \(40^{\circ} \mathrm{C}\) )

(2) 400 V Main Circuit Motor
- Selection Criteria A (Switching Frequency: 1200 Times/Hour, Utilization: 25\%, Starting Current: 6 Times Full-Load Current, Ambient Temperature \(40^{\circ} \mathrm{C}\)
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline & \multicolumn{7}{|c|}{Starting Time} \\
\hline Motor Capacity ( \(3 \varphi 400 \mathrm{~V}\) ) & 0.1 s & 0.2 s & 0.3 s & 0.4 s & 0.5 s & 0.6 s & 0.7 s \\
\hline 3.7 kW ( 8.7 A ) & \multicolumn{5}{|c|}{US-N20} & US- & \\
\hline 5.5 kW ( 13.0 A ) & \multicolumn{7}{|c|}{US-N30} \\
\hline 7.5 kW ( 17.4 A ) & \multicolumn{2}{|l|}{US-N30} & & & \multicolumn{2}{|l|}{US-NH70■/NH80■} & \\
\hline 11 kW (26.0 A) & US-N40/N50■ & & & US-N & 80] & & \\
\hline 15 kW (34.0 A) & \multicolumn{7}{|c|}{US-NH70■/NH80]} \\
\hline 22 kW (48.0 A) & US-NH70ロ/NH80ロ & & & & & & \\
\hline
\end{tabular}

\section*{11 Related Equipment}
- Selection Criteria B (Switching Frequency: 600 Times/Hour, Utilization: 40\%, Starting Current: 6 Times Full-Load Current, Ambient Temperature \(40^{\circ} \mathrm{C}\) )

- Selection Criteria C (Switching Frequency: 150 Times/Hour, Utilization: 60\%, Starting Current: 6 Times Full-Load Current, Ambient Temperature \(40^{\circ} \mathrm{C}\) )
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline & \multicolumn{7}{|c|}{Starting Time} \\
\hline Motor Capacity ( \(3 \varphi 400 \mathrm{~V}\) ) & 0.1 s & 0.2 s & 0.3 s & 0.4 s & 0.5 s & 0.6 s & 0.7 s \\
\hline 3.7 kW (8.7 A) & \multicolumn{7}{|c|}{US-N20■} \\
\hline 7.5 kW (17.4 A) & \multicolumn{4}{|c|}{US-N30 \(\square\)} & & US- & \\
\hline 11 kW (26.0 A) & US-N & & \multicolumn{5}{|c|}{US-NH70 \(\square\) /NH80 \(\square\)} \\
\hline 15 kW (34.0 A) & \multicolumn{7}{|c|}{US-NH70 \(\square / \mathrm{NH} 80 \square\)} \\
\hline 22 kW (48.0 A) & \multicolumn{3}{|l|}{US-NH70 \(\square\) /NH80■} & & & & \\
\hline
\end{tabular}

\section*{Capacitive Load}

US-N solid state contactors close using a zero voltage trigger system. As such, these can suppress an inrush current when closing capacitive loads of approximately 2 to 10 times the rated current, making them suitable for frequently switched phase advanced capacitors. When using a phase advanced capacitor the voltage and current waveforms may become distorted. As these distortions increase the noise of transformers and motors, a series reactor with \(6 \%\) the capacitive reactance is generally inserted to help suppress distortions to the voltage and current due to the 5th harmonic. This series reactor not only helps to restore the waveform but also helps to suppress the inrush current. We recommend their use in all capacitive circuits. The maximum inrush current with a \(6 \%\) series reactor in place is approximately 5 times the rated current. When the capacitor is open-circuited, the effect of residual charge in the capacitor means a voltage 2 times greater than the power supply is applied to the main circuit element. The rated voltage of the US-N unit to be used hence must be 2 times the intended circuit voltage.

\section*{Use a AC400 V main circuit voltage US-N \(\square\) unit for AC200 V capacitive load applications.}

Fig. 2 Capacitor Load Application Circuit

- Capacitor Load Application Capacity (AC200 V)
\begin{tabular}{c|c|c}
\hline Model Name & Single-Phase Capacitor & Three-Phase Capacitor \\
\hline US-N20 \(\square\) & 3 kVA & 5 kVA \\
\hline US-N30 \(\square\) & 4.6 kVA & 8 kVA \\
\hline US-N40 \(\square\) & 6 kVA & 10 kVA \\
\hline US-N50 \(\square\) & 7.6 kVA & 13 kVA \\
\hline US-NH7ONS(TE)/US-NH80NS(TE) (1 to 3 Units) & 10 kVA & 18 kVA \\
\hline
\end{tabular}

\subsection*{11.3.2 US-H \(\square\) Solid State Contactors}

\section*{- Heater Load}

The table below shows the AC rated operating current applicable with heater loads (JEM1441 (class AC-1), IEC60947-4-3 (Class AC-51)).
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Model Name} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Rated Operating Current (A)}} & \multicolumn{5}{|c|}{Applicable Heater Capacity (kW)} \\
\hline & & & \multicolumn{3}{|c|}{Single-Phase} & \multicolumn{2}{|c|}{Three-Phase} \\
\hline & JEM (Category AC-1) & IEC (Category AC-51) & 100 V & 200 V & 400 V & 200V & 400 V \\
\hline US-H20 (RM)(UF) & 20 & 20 & 2 & 4 & 8 & 6.9 & 13.8 \\
\hline US-H30 (RM)(UF) & 30 & 30 & 3 & 6 & 12 & 10.3 & 20.7 \\
\hline US-H40 & 40 & 40 & 4 & 8 & 16 & 13.8 & 27.7 \\
\hline US-H50 & 50 & 50 & 5 & 10 & 20 & 17.3 & 34.6 \\
\hline US-H20DD (RM)(UF) & 20 & 20 & 2 & 4 & 8 & - & - \\
\hline US-H30DD (RM)(UF) & 30 & 30 & 3 & 6 & 12 & - & - \\
\hline US-H40DD & 40 & 40 & 4 & 8 & 16 & - & - \\
\hline US-H50DD & 50 & 50 & 5 & 10 & 20 & - & - \\
\hline
\end{tabular}

Note 1. Rating applicable for -10 to \(40^{\circ} \mathrm{C}\) ambient temperature. If the temperature is \(40^{\circ} \mathrm{C}\) or more, use the rated operated current multiplied by the reduced rate shown in Figure 1 on page 318.
Note 2. Calculate the applicable heater capacity using the equations below.
For single-phase: Power supply voltage x load current
For three-phase: \(\sqrt{3} \times\) power supply voltage \(x\) load current ( \(3 \times\) power supply voltage \(x\) load current for delta connections)

Related Equipment

\subsection*{11.4 Application Precautions}

\section*{- Working Environment}
(1) Operating Ambient Temperature: \(-10^{\circ} \mathrm{C}\) to \(60^{\circ} \mathrm{C}\) However, if the temperature is \(40^{\circ} \mathrm{C}\) to \(60^{\circ} \mathrm{C}\) then use the rated operating current multiplied by the reduced rate shown in Figure 1. (No freezing, no condensation)
(2) Storage Temperature : \(-30^{\circ} \mathrm{C}\) to \(65^{\circ} \mathrm{C}\)
(3) Relative Humidity
: 45\% to 85\% RH
(4) Vibration
: 10 to \(55 \mathrm{~Hz} 19.6 \mathrm{~m} / \mathrm{s}^{2}\) or Less
(5) Shock
(6) Environment
: \(98 \mathrm{~m} / \mathrm{s}^{2}\) or Less
: Use only in well-ventilated areas free of dust, gas and organic solvents.

\section*{- Mounting}
(1) US-N and US-H type main circuit and cooling fins are electrically isolated so there is no need to insulate when mounting. Mount in the mounting orientation shown in Figure 2. Remember to take ventilation within the panel into consideration.
Do not place in contact with cables etc. as the temperature of the cooling fins is approximately \(100^{\circ} \mathrm{C}\) when the rated operating current is being continuously applied.
(2) If using US-N or US-H units on column panels or arranging with other equipment, take care to secure at least the amount of space indicated in Figure 3. If mounting US-N or US-H units vertically, then space all US-N or US-H units at least 300 mm apart.

\section*{- Main Circuit Voltage Application Range}

The main circuit voltage can be operated within the range indicated in the above-right table.
DC power supplies are not supported.

\section*{Operating Voltage and Wiring Used}

The DC operating voltage for US-N or US-H drive units is required to be DC12 to 24 V with \(10 \%\) or less voltage ripple. (Fig. 4)
Avoid combining the control input and power lines of US-N or US-H units.
Use a twisted-pair cable for the control circuit and limit the length to 10 m or less.

\section*{Open Circuit Leakage Current}
(1) 15 to 50 mA of leakage current will flow when US-N or US-H units are open-circuited (OFF), depending on the model. These leakage currents may cause electric shocks on the load side, so a no-fuse breaker or magnetic contactor should be connected on the power-side, as per Figure 5, to ensure the load is open-circuited.
(2) The leakage current may prevent light load motors from stopping when US-N is switched off. In such cases, connect a resistor in parallel with the load such that the load current is 10 or more times greater than the leakage current. (Fig. 6)
(3) If there is no load present with US-N or US-H units, the main circuit will not switch on and operation cannot be verified. However, the operation indicator lamp will illuminate when voltage is applied and a voltage close to the power supply voltage is applied to the load side of US-N or US-H units. (Due to US-N or US-H leakage currents) Connect a sample load such as a resistor (so that 1 A or so flows) to check the operation of US-N or US-H units.
- Main Circuit Voltage Application Range
\begin{tabular}{l|c|c}
\hline \multicolumn{1}{|c|}{ Series } & US-N & US-H \\
\hline Main Circuit Voltage & - & H20 to H50 \\
\hline AC24 to 480 V & N20 to N50 & - \\
\hline AC100 to 480 V & N5, N8, N70, N80 & - \\
\hline AC100 to 240 V & NH70, NH80 & - \\
\hline AC200 to 480 V & \\
\hline
\end{tabular}

Note. This table indicates the applicable model names. - is not applicable



\section*{Cooling Fan Circuit Connections}

US-N(H)70NS(TE) and US-N(H)80NS(TE) units have an integrated cooling fan and fan fault detector. Take care to ensure these are wired to the control circuit.
(1) Cooling Fan Operating Power Terminal (FA1, FA2)

Connect the cooling fan operating power supply to the primary-side main circuit of the US-N unit as per Figure 7. If the main circuit is AC400 V , then reduce the voltage to AC200 V using a control transformer. Avoid connecting to the secondary side of the US-N unit, as the lifespan of the cooling fan will be reduced if frequently started or stopped.
(2) Cooling Fan

The lifespan of the cooling fan bearing is approximately 10,000 to 35,000 hours and should be replaced as required according to the running conditions. Replacement is also required if abnormal noise or vibrations are generated. (Replacement cooling fan units are available.)
(3) Fan Fault Detector Terminals (OT1, OT2)

Fan fault detectors operate when the is a fault with the cooling fins (faulty cooling fan etc.) by open-circuiting the normally closed fan fault detector contact. Connect to the control circuit in series to switch OFF the US-N unit when a fault is detected. The fan fault detector automatically resets (closes the contact) when the temperature has dropped. If retention of the detection signal is required, then attach an external retention circuit.

\section*{Applicable Wire Size and Terminal Screw Tightening Torque}
©There is a risk of overheating or fire. Be sure to maintain the tightening torque and periodically re-tighten the screw. Electric wires should be properly connected according to the electric wiring diagram. Tightening the terminal screw should be properly conducted within the tightening torque shown in the tables (1) and (2). Insufficient tightening of the terminal screw may cause overheating or cause the electric wire to fall off.
Excessive tightening torque may damage the terminal screw.

\section*{AC Operated Optional Unit Control Via Solid State Relays}

When controlling the switching of AC operated optional units (UA-DR \(\square\), UA-SH \(\square\), UA-RE, UN-FD \(\square\) ) with a solid state relay or triac output, use a solid state relay or triac output with an integrated varistor. US-N type optional UA-SH \(\square\) unit auxiliary outputs have an integrated varistor and can be controlled by the optional units listed above.

\section*{Non-Applicable Connections}

US-N or US-H types are 1-pole to 3-pole compatible and can switch single-phase and three-phase loads. The special configurations shown below cannot be used.
(1) Parallel Connections (Refer to Figure 8)

Poles of the US-N or US-H unit main circuit cannot be connected in parallel in order to increase current capacity. (Explanation) The ON power supply to the thyristor of each pole has some variance which causes continuity current to concentrate at the pole with lower voltage, damaging the thyristor.
(2) Series Connections (Refer to Figure 9)

Poles of the US-N or US-H unit main circuit cannot be connected in series in order to increase the rated voltage. (Explanation) The closing voltage and operating time of each pole has some variance which causes timing mismatches, applying excessive voltage to certain poles, resulting in damage.
(3) Inverter Secondary Connections

(1) Applicable Wire Size and Terminal Screw Tightening Torque (Main Circuit)
\begin{tabular}{|c|c|c|c|c|}
\hline Model Name & Teminisfericie & Applicable Wire Size & Applicale Crimp Lug Size & Temina Scceen Tigtrexing Toque \\
\hline US-N5SS (TE) US-N8SS (TE) & M3.5 & \[
\begin{gathered}
\varphi 1.6 \mathrm{~mm} \\
1.25 \text { to } 2 \mathrm{~mm}^{2}
\end{gathered}
\] & 1.25-3.5 to 2-3.5 & 0.94 to \(1.51 \mathrm{~N} \cdot \mathrm{~m}\)
(Standard \(1.17 \mathrm{~N} \cdot \mathrm{~m}\) ) \\
\hline \[
\begin{aligned}
& \hline \text { US-N20 (TE) } \\
& \text { to N50 (TE) }
\end{aligned}
\] & M5 & \[
\begin{aligned}
& \hline \text { (Note } 1) \\
& \left(2 \text { to } 14 \mathrm{~mm}^{2}\right) \\
& \hline
\end{aligned}
\] & 1.25-5 to 14-5 & \begin{tabular}{|c}
2.06 to \(3.33 \mathrm{~N} \cdot \mathrm{~m}\) \\
(Standard \(2.54 \mathrm{~N} \cdot \mathrm{~m}\) )
\end{tabular} \\
\hline US-N (H) 7ONS (TE) US-N (H) 80NS (TE) & M6 & - & \[
\begin{gathered}
\hline 1.25-6 \text { to } 22-6 \\
38-\mathrm{S} 6
\end{gathered}
\] & \[
\begin{array}{|c}
\hline 3.53 \text { to } 5.78 \mathrm{~N} \cdot \mathrm{~m} \\
\text { (Standard } 4.41 \mathrm{~N} \cdot \mathrm{~m}) \\
\hline
\end{array}
\] \\
\hline \[
\begin{gathered}
\hline \text { US-H2O (DD) } \\
\text { to H5O (DD) } \\
\text { US-H20/H30 (DD)UF } \\
\hline
\end{gathered}
\] & M5 & - & 1.25-5 to 14-5 & 2.06 to \(3.33 \mathrm{~N} \cdot \mathrm{~m}\) (Standard \(2.54 \mathrm{~N} \cdot \mathrm{~m}\) ) \\
\hline
\end{tabular}

Note 1. The value in parentheses is applicable for US-N \(\square\) (TE)CX only.
(2) Applicable Wire Size and Terminal Screw Tightening Torque (Control Circuit)
\begin{tabular}{|c|c|c|c|c|}
\hline Model Name & Temina Serensie & Applicable Wire Size & Applicable Crimp Lug Size & Terrina Sceen Tigtiening Torque \\
\hline US-N/H Series All Models & M3.5 & \[
\begin{gathered}
\varphi 1.6 \mathrm{~mm} \\
1.25 \text { to } 2 \mathrm{~mm}^{2}
\end{gathered}
\] & \[
\begin{gathered}
1.25-3.5 \text { to } \\
2-3.5
\end{gathered}
\] & \[
\begin{array}{|c|}
\hline 0.94 \text { to } 1.51 \mathrm{~N} \cdot \mathrm{~m} \\
\text { (Standard } 1.17 \mathrm{~N} \cdot \mathrm{~m})
\end{array}
\] \\
\hline \begin{tabular}{l}
UA, UN- \(\square\) \\
All Option Models
\end{tabular} & M3.5 & \[
\begin{gathered}
\varphi 1.6 \mathrm{~mm} \\
1.25 \text { to } 2 \mathrm{~mm}^{2}
\end{gathered}
\] & \[
\begin{gathered}
1.25-3.5 \text { to } \\
2-3.5
\end{gathered}
\] & 0.94 to \(1.51 \mathrm{~N} \cdot \mathrm{~m}\) (Standard \(1.17 \mathrm{~N} \cdot \mathrm{~m}\) ) \\
\hline
\end{tabular}


Use on the secondary-side of the inverter is not possible as a large leakage current flows when switched off due to harmonics, potentially causing the surge absorber to burn out.

\section*{Related Equipment}

\section*{Failure Mode}

US-N or US-H units may fail if subjected to incorrect handling or operating conditions. Current usually flows continuously while in the main circuit element failure mode of US-N or US-H units. Fault detection units (UN-FD) are available as optional units to detect when US-N or US-H units fail while the main circuit element is in continuity mode. This unit should be combined for use with a no-fuse breaker with voltage tripping device or magnetic contactor.

\section*{Short-circuit Protection}

US-N or US-H units have little over-current withstanding capacity (surge ON current) and regions that cannot be protected by no-fuse breakers so must be protected with quick-trip fuses or thyristor protectors.
(1) Quick-Trip Fuses

Quick-trip fuses are economical when divided among heater loads and motor loads with starting currents. The table below shows quick-trip fuse selection criteria.
- Quick-Trip Fuse Selection Criteria
\begin{tabular}{l|l|l}
\hline \multicolumn{1}{c|}{ Selection Criteria } & \multicolumn{1}{|c}{ Content } & \multicolumn{1}{c}{ Equation } \\
\hline (1) Fuse Rated Current & \begin{tabular}{l} 
Limiting of Load \\
Current to Prevent Fuse \\
Temperature Rise and \\
Erroneous Fusing
\end{tabular} & \begin{tabular}{c} 
(Fuse Rated Current) \(\times 0.8\) \\
\(\geq\) (Load Current)
\end{tabular} \\
\hline \begin{tabular}{c} 
(2) Fusing Properties of \\
Fuse
\end{tabular} & \begin{tabular}{l} 
Limiting of Overcurrent to \\
Prevent Fuse Deterioration \\
and Fusion by Repeated \\
Overcurrent (Ex: Motor \\
Start-Up Current)
\end{tabular} & \begin{tabular}{l} 
(Fusing Current of Fuse) \(\times 0.6\) \\
\(>\) (Load Start-Up Current)
\end{tabular} \\
\hline \begin{tabular}{l} 
(3) Relationship of the \\
Total Breaking I It of the \\
Fuse and Allowable I't \\
of the Element
\end{tabular} & \begin{tabular}{l} 
Protection of the Element \\
with Respect to Short \\
Circuit of a Half Cycle or \\
Less
\end{tabular} & \begin{tabular}{l} 
(Total Breaking I It of Fuse) \\
\(<\) (Allowable I't of Element)
\end{tabular} \\
\hline (4) Relationship of the \\
Fusing Characteristics \\
of the Fuse and & \begin{tabular}{l} 
Protection of the Element \\
during Large Current \\
State Current of the
\end{tabular} & \begin{tabular}{l} 
The intersection of the \\
Fusing characteristics \\
of the fuse and state \\
current characteristics \\
of the element is to be \\
50 ms or more
\end{tabular} \\
Element
\end{tabular}

For Heater Loads: Select (1), (3), (4)
For Motor Loads: Select (2), (3), (4)
(2) Thyristor Protector

Applicable during the limited area of short-circuit current during an accident when protecting US-N and US-H types with a thyristor protector.
US-N or US-H have rated surge ON current properties and allowable \(I^{2}\) t values to withstand over-current situations. Protection against the rated surge ON consists of a balance of thyristor protector operating characteristics and allowable \(I^{2} t\) and is limited to the protectable region applicable when short-circuited (shorted time region) with restricted thyristor protector current (continuous \(I^{2} t\) ).



Relationship of Protective Properties

Fig. 11 Protection Via Thyristor Protector

(1) US-N \(\square\)

3-Pole 2-Element Type)

(2) US-N \(\square T E\) (3-Pole 3-Element Type)

(3) US-H■Type

\section*{- Heater Load}

For nichrome, iron, chrome and aluminum type general heaters or far-infrared heaters without inrush current, \(3 x\) the thyristor protector types listed in the table below are ideal.
If the operating circuit short-circuit current exceeds the value listed in the table below, use a no-fuse breaker and quick-trip fuse with the US-N or US-H unit.
- US-N, US-H Series Combination Chart
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{3}{*}{} & \multirow{3}{*}{Model Name} & \multirow{3}{*}{\[
\begin{aligned}
& \text { Tolerance } I^{2} t \\
& \left(A^{2} s\right)
\end{aligned}
\]} & \multirow{3}{*}{Main Circuit Voltage} & \multicolumn{7}{|c|}{Thyristor Protector Rated Current} \\
\hline & & & & 10 A & 15 A & 20 A & 25 A & 30 A & 40 A & 50 A \\
\hline & & & & \multicolumn{7}{|l|}{Thyristor Protector (SP50-K 1P/2P/3P \(\square\) 3x) Short-Circuit Protection Current (kA)} \\
\hline \multirow{12}{*}{\[
\begin{gathered}
\text { Solid State } \\
\text { Contactors } \\
\text { for General Loads }
\end{gathered}
\]} & \multirow{3}{*}{US-N20 \(\square\)} & \multirow{3}{*}{2600} & Single-Phase ACi10V & 8 & 5 & 3 & 2 & - & - & - \\
\hline & & & 3 -Phase AC220 V & 4 & 3 & 2.2 & 1.6 & - & - & - \\
\hline & & & 3-Phase AC440 V & 1.7 & 1.5 & 1.2 & 1 & - & - & - \\
\hline & \multirow{3}{*}{US-N30 \(\square\)} & \multirow{3}{*}{7000} & Singe-Phase AC110V & 10 & 10 & 8.5 & 6 & 4.3 & 3.2 & - \\
\hline & & & 3-Phase AC220 V & 5 & 5 & 5 & 3.9 & 2.8 & 2.1 & - \\
\hline & & & 3-Phase AC440 V & 2.5 & 2.5 & 2.5 & 2.1 & 1.3 & - & - \\
\hline & \multirow{3}{*}{US-N40 \(\square\) US-N50} & \multirow{3}{*}{13500} & Single-Phase AC110V & 10 & 10 & 10 & 10 & 8.6 & 6 & 4.4 \\
\hline & & & 3-Phase AC220 V & 5 & 5 & 5 & 5 & 5 & 3.5 & 2.9 \\
\hline & & & 3-Phase AC440 V & 2.5 & 2.5 & 2.5 & 2.5 & 2.5 & 2 & 1.9 \\
\hline & \multirow[t]{2}{*}{US-N70NS(TE) US-N80NS(TE)} & \multirow[b]{2}{*}{13500} & Single.Phase AC110V & 10 & 10 & 10 & 10 & 8.6 & 6 & 4.4 \\
\hline & & & 3-Phase AC220 V & 5 & 5 & 5 & 5 & 5 & 3.5 & 2.9 \\
\hline & US-NH70NS(TE) US-NH80NS(TE) & 13500 & 3 -Phase AC440 V & 2.5 & 2.5 & 2.5 & 2.5 & 2.5 & 2.1 & 1.9 \\
\hline \multirow{12}{*}{Solid State Contactors for Heater Loads} & \multirow{3}{*}{US-H20 \(\square\)} & \multirow{3}{*}{450} & Singe-Phase AC110V & 0.6 & 0.5 & 0.4 & - & - & - & - \\
\hline & & & 3-Phase AC220 V & 0.55 & 0.42 & 0.39 & 0.3 & - & - & - \\
\hline & & & 3-Phase AC440 V & 0.38 & 0.34 & 0.3 & - & - & - & - \\
\hline & \multirow{3}{*}{US-H30 \(\square\)} & \multirow{3}{*}{2600} & Singe-Phase AC110V & 8 & 5 & 3 & 2 & 1.7 & 1.2 & 1 \\
\hline & & & 3 -Phase AC220 V & 4 & 3 & 2.2 & 1.6 & 1.3 & 0.9 & 0.8 \\
\hline & & & 3-Phase AC440 V & 1.7 & 1.5 & 1.2 & 1 & 0.85 & 0.75 & 0.67 \\
\hline & \multirow{3}{*}{US-H40 \(\square\)} & \multirow{3}{*}{4100} & Single.Phase AC110V & 10 & 8.2 & 5 & 3.5 & 2.7 & 2 & 1.6 \\
\hline & & & 3-Phase AC220 V & 5 & 5 & 3.3 & 2.4 & 1.7 & 1.4 & 1.2 \\
\hline & & & 3-Phase AC440 V & 2.5 & 2.1 & 1.8 & 1.5 & 1.3 & 1 & 0.9 \\
\hline & \multirow{3}{*}{US-H50 \(\square\)} & \multirow{3}{*}{7000} & Singe:Phase AC110V & 10 & 10 & 8.5 & 6 & 4.3 & 3.2 & 2.5 \\
\hline & & & 3-Phase AC220 V & 5 & 5 & 5 & 3.9 & 2.8 & 2.1 & 1.7 \\
\hline & & & 3-Phase AC440 V & 2.5 & 2.5 & 2.5 & 2.1 & 1.8 & 1.5 & 1.3 \\
\hline
\end{tabular}
- Motor Load

Thyristor protectors are not applicable. Use a no-fuse breaker and quick-trip fuse with the US-N unit.

\section*{Related Equipment}

\section*{Device Selection}

Selection of the solid state contactor, thermal overload relay and no-fuse breaker for each motor capacity and also the selection of element protection for US-N \(\square\) units is explained below.
However, US-N \(\square\) units with no-fuse breakers may not be able to offer short-circuit protection over all regions and may need to be combined with a short-circuit protecting quick-trip fuse, as described on page 320.

\section*{(1) Thermal Overload Relay and No-Fuse Breaker Selection}

The applicable solid state contactor frames for motor loads can be selected from page 315, while the thermal overload relay and no-fuse breaker selection should be made from the contents below.
The solid state contactors listed below are selected based on the following ratings as per pages 315 and 316: switching frequency: 600 times/hour, utilization: \(40 \%\), starting current: 6 times full-load current, starting time: 0.2 s or less, ambient temperature \(40^{\circ} \mathrm{C}\).
- At AC200 V Rating
\begin{tabular}{c|l|l|l}
\hline Motor Capacity & Solid State Contactors & Thermal Overload Relays & No-Fuse Breakers \\
\hline 0.4 kW & US-N5SS(TE) & TH-T25 2.1 A & NF32-SV 5 A \\
\hline 0.75 kW & US-N5SS(TE) & TH-T25 3.6 A & NF32-SV 10 A \\
\hline 1.5 kW & US-N20(TE) & TH-T25 6.6 A & NF32-SV 15 A \\
\hline 2.2 kW & US-N20(TE) & TH-T25 9 A & NF32-SV 20 A \\
\hline 3.7 kW & US-N30(TE) & TH-T25 15 A & NF32-SV 30 A \\
\hline 5.5 kW & \begin{tabular}{l} 
US-N40(TE) \\
US-N50(TE)
\end{tabular} & TH-T25 22 A & NF63-SV 50 A \\
\hline 7.5 kW & \begin{tabular}{l} 
US-N70NS(TE) \\
US-N80NS(TE)
\end{tabular} & TH-T65 29 A & NF63-SV 60 A \\
\hline 11 kW & \begin{tabular}{l} 
US-N70NS(TE) \\
US-N80NS(TE)
\end{tabular} & TH-T65 42 A & NF125-SV 75 A \\
\hline
\end{tabular}
- At AC400 V Rating
\begin{tabular}{c|l|l|l}
\hline Motor Capacity & Solid State Contactors & Thermal Overload Relays & No-Fuse Breakers \\
\hline 3.7 kW & US-N20(TE) & TH-T25 6.6 A & NF32-SV 20 A \\
\hline 5.5 kW & US-N30(TE) & TH-T25 11 A & NF32-SV 30 A \\
\hline 7.5 kW & US-N30(TE) & TH-T25 15 A & NF32-SV 30 A \\
\hline 11 kW & \begin{tabular}{l} 
US-N40(TE) \\
US-N50(TE)
\end{tabular} & TH-T25 22 A & NF63-SV 50 A \\
\hline 15 kW & \begin{tabular}{l} 
US-NH7ONS(TE) \\
US-NH8ONS(TE)
\end{tabular} & TH-T65 29 A & NF63-SV 60 A \\
\hline 22 kW & \begin{tabular}{l} 
US-NH7ONS(TE) \\
US-NH80NS(TE)
\end{tabular} & TH-T65 42 A & NF125-SV 75 A \\
\hline
\end{tabular}
(2) Selection When US-N \(\square\) Element Protection is Required

There are some cases in which US-N \(\square\) elements will not be protected if overloaded (current exceeding 6 times the motor full-load current) when using the combinations in the table above.
Use one of the solid state contactor frames below if US-N \(\square\) element protection is required.

\section*{- At AC200 V Rating}
\begin{tabular}{c|l|l|l}
\hline Motor Capacity & Solid State Contactors & Thermal Overload Relays & No-Fuse Breakers \\
\hline 0.4 kW & US-N8SS(TE) & TH-T25 2.1 A & NF32-SV 5 A \\
\hline 0.75 kW & US-N20(TE) & TH-T25 3.6 A & NF32-SV 10 A \\
\hline 1.5 kW & US-N30(TE) & TH-T25 6.6 A & NF32-SV 15 A \\
\hline 2.2 kW & \begin{tabular}{l} 
US-N40(TE) \\
US-N50(TE)
\end{tabular} & TH-T25 9 A & NF32-SV 20 A \\
\hline 3.7 kW & \begin{tabular}{l} 
US-N40(TE) \\
US-N50(TE)
\end{tabular} & TH-T25 15 A & NF32-SV 30 A \\
\hline 5.5 kW & \begin{tabular}{l} 
US-N70NS(TE) \\
US-N80NS(TE)
\end{tabular} & TH-T25 22 A & NF63-SV 50 A \\
\hline
\end{tabular}
- At AC400 V Rating
\begin{tabular}{c|l|l|l}
\hline Motor Capacity & Solid State Contactors & Thermal Overload Relays & No-Fuse Breakers \\
\hline 1.5 kW & US-N20(TE) & TH-T25 3.6 A & NF32-SV 10 A \\
\hline 2.2 kW & US-N30(TE) & TH-T25 5 A & NF32-SV 10 A \\
\hline 3.7 kW & US-N30(TE) & TH-T25 6.6 A & NF32-SV 20 A \\
\hline 5.5 kW & \begin{tabular}{l} 
US-N40(TE) \\
US-N50(TE)
\end{tabular} & TH-T25 11 A & NF32-SV 30 A \\
\hline 7.5 kW & \begin{tabular}{l} 
US-N40(TE) \\
US-N50(TE)
\end{tabular} & TH-T25 15 A & NF32-SV 30 A \\
\hline 11 kW & \begin{tabular}{l} 
US-NH7ONS(TE) \\
US-NH80NS(TE)
\end{tabular} & TH-T25 22 A & NF63-SV 50 A \\
\hline
\end{tabular}

\section*{Differences Between 3-Pole 2-Element and 3-Pole 3-Element Types}

US-N \((H) \square\) units are available as 3 -pole 2 -element and 3 -pole 3 -element types. The functionality between the two is essentially the same, but as the central pole of 3-pole 2-element (between 3/L2 and 4/T2 terminals) types is internally connected, delta connections cannot be used to increase applicable capacity.
Of the 3-pole 2-element products, US-N30 and N50 types are more compact than their US-N30TE and N50TE 3-pole
3-element counterparts, allowing for greater minimization of occupied space to be achieved.

\subsection*{11.5 Optional Units}
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Optional Unit Names} & \multirow[b]{2}{*}{Model Name} & \multicolumn{4}{|c|}{Applicable Models} \\
\hline & & US-N5SS/N8SS(TE) & US-N20(TE) to N50(TE) & US-N(H)70/N(H)80NS(TE) & \[
\begin{aligned}
& \text { US-H2O to H50(DD) } \\
& \text { US-H20/H3O(DD)UF }
\end{aligned}
\] \\
\hline Drive Units & UA-DR1 & X & (Note 2) & (Note 2) & X \\
\hline \multirow[b]{2}{*}{Drive Units with Outputs} & UA-SH8 & (Note 1) & X & X & X \\
\hline & UA-SH1 & X & (Note 2) & (Note 2) & X \\
\hline Reversing Unit & UA-RE & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & X \\
\hline \multirow{2}{*}{Fault Detection Units} & UN-FD & \(\bigcirc\) & \(\bigcirc\) & (N70/N80(TE)) & \(\bigcirc\) \\
\hline & UN-FD4 & X & \(\bigcirc\) & (NH70/NH8O(TE)) & \(\bigcirc\) \\
\hline Power Control Units & UA-PC & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) \\
\hline Live Part Protection Cover Units & UN-CV501US & X & X & X & \(\bigcirc\) \\
\hline \multirow[b]{2}{*}{Optional Unit Names} & \multirow[b]{2}{*}{Model Name} & \multicolumn{3}{|c|}{Applicable Models} & \\
\hline & & UA-DR1 & UA-SH1 & UA-SH8 & \\
\hline \multirow{2}{*}{Live Part Protection Cover Units} & UA-CVDR1 & \(\bigcirc\) & \(\bigcirc\) & X & \\
\hline & UA-CVSH8 & X & X & \(\bigcirc\) & \\
\hline
\end{tabular}

Note 1. When mounting UA-SH8 units to US-N5SS/N8SS(TE) types, first remove the US-N \(\square\) type body cover.
If live part protection is required for UA-SH8 units then a UA-CVSH8 live part protection cover should be mounted.
Refer to page 335 for details regarding the outline drawings when UA-CVSH8 is mounted to a UA-SH8 unit.
Note 2. When mounted to US-N20(TE) to N50(TE), US-N(H)70/N(H)80NS(TE), the outline drawings are increased.
Refer to pages 337 for information about outline drawings.
If live part protection is required for UA-DR1 or SH1 units, a UA-CVDR1 live part protection cover should be mounted.

\subsection*{11.5.1 Drive Units (UA-DR1)}

US-N units can be driven at AC100 V or AC200 V by using UA-DR1 drive units.
\begin{tabular}{|c|c|c|c|}
\hline \multicolumn{4}{|l|}{- Rating} \\
\hline \multicolumn{2}{|l|}{Appearance} & & \\
\hline \multicolumn{2}{|l|}{Model Name} & UA-DR1 AC100V & UA-DR1 AC200V \\
\hline \multicolumn{2}{|l|}{Rated Operational Voltage} & AC100 to \(120 \mathrm{~V} 50 / 60 \mathrm{~Hz}\) & AC200 to \(240 \mathrm{~V} 50 / 60 \mathrm{~Hz}\) \\
\hline \multicolumn{2}{|l|}{Input Current} & \multicolumn{2}{|c|}{20 mA} \\
\hline \multicolumn{2}{|l|}{Rated Output Voltage/Current} & \multicolumn{2}{|c|}{DC12 to \(24 \mathrm{~V} / 20 \mathrm{~mA}\)} \\
\hline \multirow[t]{2}{*}{Response Time} & \(\mathrm{OFF} \rightarrow \mathrm{ON}\) & \multicolumn{2}{|l|}{Max. \(30 \mathrm{~ms}+1 / 2 \mathrm{Cycle}+1 \mathrm{~ms}\) (When Combined With US-N)} \\
\hline & \(\mathrm{ON} \rightarrow\) OFF & \multicolumn{2}{|l|}{Max. \(30 \mathrm{~ms}+1 / 2\) Cycle + 1 ms (When Combined With US-N)} \\
\hline \multicolumn{2}{|l|}{Allowable Voltage Fluctuation Range} & \multicolumn{2}{|l|}{85 to \(110 \%\) of Rated Operational Voltage} \\
\hline \multicolumn{2}{|l|}{Operating Temperature/Humidity} & \multicolumn{2}{|l|}{-10 to \(60^{\circ} \mathrm{C} / 45\) to \(85 \%\) RH} \\
\hline
\end{tabular}
- Circuit

Fig. 1 UA-DR1 Type Circuit


US-N

\section*{Related Equipment}

\section*{Mounting}

UA-DR1 units should be mounted on the right side of US-N units using the conductor attached to the UA-DR1 unit. Refer to page 337 for information regarding outline drawings as the width and depth may increase for some models.

Fig. 2 UA-DR1 Type Mounting Method


Conductor
(Included With UA-DR1)

\section*{Thermal Overload Relay Connection}

Connect as shown in Figure 3 if using a thermal overload relay with circuits combined with UA-DR1 types.

Fig. 3 Thermal Overload Relay Connection


\section*{US-N Connections}

Connect as per Figure 4 if using a combination of UA-DR1 unit.


\subsection*{11.5.2 Drive Units with Outputs (UA-SH1, UA-SH8)}

US-N units can be driven at AC100 V or AC200 V by using UA-SH1 or UA-SH8 drive units with outputs while simultaneously allowing use of the auxiliary outputs (triac outputs (1 circuit)).

Rating
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multicolumn{3}{|l|}{Appearance} & \multicolumn{2}{|c|}{} & &  \\
\hline \multicolumn{3}{|l|}{Model Name} & UA-SH1 AC100V & UA-SH1 AC200V & UA-SH8 AC100V & UA-SH8 AC200V \\
\hline \multirow{5}{*}{\[
\stackrel{\stackrel{\rightharpoonup}{亠 凶}}{\stackrel{\rightharpoonup}{0}}
\]} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{\[
\begin{array}{|l}
\hline \text { Rated Operational Voltage } \\
\hline \text { Input Current } \\
\hline
\end{array}
\]}} & AC100 to \(120 \mathrm{~V} 50 / 60 \mathrm{~Hz}\) & AC200 to \(240 \mathrm{~V} 50 / 60 \mathrm{~Hz}\) & AC100 to \(120 \mathrm{~V} 50 / 60 \mathrm{~Hz}\) & AC200 to \(240 \mathrm{~V} 50 / 60 \mathrm{~Hz}\) \\
\hline & & & \multicolumn{2}{|c|}{20 mA} & & \\
\hline & \multicolumn{2}{|l|}{Rated Output Voltage/Current} & \multicolumn{2}{|c|}{DC12 to \(24 \mathrm{~V} / 20 \mathrm{~mA}\)} & \multicolumn{2}{|c|}{DC24 V/30 mA} \\
\hline & \multirow[t]{2}{*}{Response Time} & OFF \(\rightarrow\) ON & \multicolumn{2}{|l|}{Max. 50 ms (When Combined With US-N)} & \multicolumn{2}{|l|}{Max. 50 ms (When Combined With US-N5/N8SS(TE))} \\
\hline & & ON \(\rightarrow\) OFF & \multicolumn{2}{|l|}{Max. 50 ms (When Combined With US-N)} & \multicolumn{2}{|l|}{Max. 50 ms (When Combined With US-N5/N8SS(TE))} \\
\hline \multirow[t]{5}{*}{} & \multicolumn{2}{|l|}{Rated Load Voltage} & \multicolumn{4}{|c|}{AC100 to \(240 \mathrm{~V} 50 / 60 \mathrm{~Hz}\)} \\
\hline & \multicolumn{2}{|l|}{Rated Load Current} & \multicolumn{4}{|c|}{0.5 A (Class AC-15)} \\
\hline & \multicolumn{2}{|l|}{Output Method} & \multicolumn{4}{|c|}{Triac Output (1 Circuit/Built-in Surge Absorber)} \\
\hline & \multicolumn{2}{|l|}{Leakage Current} & \multicolumn{4}{|c|}{3 mA or Less} \\
\hline & \multicolumn{2}{|l|}{Making Voltage Drop} & \multicolumn{4}{|c|}{1.5 V or Less} \\
\hline \multirow[t]{3}{*}{} & \multicolumn{2}{|l|}{Alowable Voltage Fluctuation Range} & \multicolumn{4}{|c|}{85 to 110\% of Rated Voltage} \\
\hline & \multicolumn{2}{|l|}{Operating Temperature/Humidity} & \multicolumn{4}{|c|}{-10 to \(60^{\circ} \mathrm{C} / 45\) to \(85 \% \mathrm{RH}\)} \\
\hline & Operation In & dicator & \multicolumn{2}{|c|}{-} & \multicolumn{2}{|l|}{Lights When Operating Voltage Applied} \\
\hline
\end{tabular}

\section*{Circuits/Connections}



\section*{- Handling}
(1) Types/Mounting

Front Clip-on mounted UA-SH8 units can be mounted to US-N5/N8SS(TE) units. Side-mounted UA-SH1 units can be mounted to US-N20/N30/N40/N50(TE) and US-N(H)70/ N(H)80NS(TE) units. UA-SH1 units should be mounted to the conductor attached to the right side of US-N units.
(2) Self-Retaining Circuit

Connect as per Figure 3 if mounting a self-retaining circuit.
(3) When mounting UA-SH8 units to US-N5SS/N8SS(TE) Fig. 3 Self-Retaining Circuit types, first remove the US-N type body cover. If live part protection is required, mount a UA-CVSH8 live part protection cover to the UA-SH8 unit.

\section*{Related Equipment}

\subsection*{11.5.3 Reversing Units (UA-RE)}

An interlock can be achieved between forward US-N units and reverse US-N units through the use of a UA-RE reversing unit, allowing for reversible motor running.

Rating
\begin{tabular}{|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{Appearance} & \multicolumn{3}{|c|}{} \\
\hline \multicolumn{2}{|l|}{Model Name} & UA-RE AC100V & UA-RE AC200V & UA-RE DC24V \\
\hline \multicolumn{2}{|l|}{Rated Operational Voltage} & AC100 to \(120 \mathrm{~V} 50 / 60 \mathrm{~Hz}\) & AC200 to \(240 \mathrm{~V} 50 / 60 \mathrm{~Hz}\) & DC24 V \\
\hline \multicolumn{2}{|l|}{Input Current} & \multicolumn{3}{|l|}{Control (A1-A2): 35 mA , Signal (A2-15 or 21): 10 mA} \\
\hline \multicolumn{2}{|l|}{Rated Output Voltage/Current} & \multicolumn{3}{|c|}{DC12 V/20 mA} \\
\hline \multicolumn{2}{|l|}{Interlock Time} & \multicolumn{3}{|c|}{Max. 100 ms} \\
\hline \multirow[t]{2}{*}{Response Time} & \(\mathrm{OFF} \rightarrow \mathrm{ON}\) & \multicolumn{3}{|l|}{Max. \(20 \mathrm{~ms}+1 / 2\) Cycle +1 ms (When Combined With US-N)} \\
\hline & \(\mathrm{ON} \rightarrow\) OFF & \multicolumn{3}{|l|}{Max. \(20 \mathrm{~ms}+1 / 2\) Cycle + 1 ms (When Combined With US-N)} \\
\hline \multicolumn{2}{|l|}{Allowable Voltage Fluctuation Range} & \multicolumn{3}{|l|}{85 to \(110 \%\) of Rated Operational Voltage} \\
\hline \multicolumn{2}{|l|}{Operating Temperature/Humidity} & \multicolumn{3}{|c|}{-10 to \(60^{\circ} \mathrm{C} / 45\) to \(85 \%\) RH} \\
\hline \multicolumn{2}{|l|}{Operation Indicator} & \multicolumn{3}{|l|}{Lights During Forward Output (Green LED)/Lights During Reverse Output (Red LED)} \\
\hline
\end{tabular}

\section*{Circuit}


Note 1. The A1 and A2 input terminals of products with DC24 V operating voltage have no polarity.

\section*{Connecting}

\section*{Fig. 2 Connecting US-N \(\square\) (TE) and UA-RE Types}


\section*{Operating Conditions}
(1) Max. 100 ms switching time between forward and reverse modes.
(2) The input signal that is input first is given priority and the second signal is invalid until the first input signal switches OFF.


\subsection*{11.5.4 Fault Detection Units (UN-FD, UN-FD4)}

Detects failures that occur to the main circuit element of US-N or US-H units when in conduction mode, and can be used to prevent abnormal operation of loads by interrupting the power supply by combining a no-fuse breaker with voltage tripping device or magnetic contactor. Fault detection units are available as UN-FD type for 200 V main circuits or as UN-FD4 type for 400 V main circuits. The table below shows the differences. Refer to the Specifications column of each item for details.
\begin{tabular}{|c|c|c|}
\hline Model Name & UN-FD & UN-FD4 \\
\hline Type & UN-FD AC100V, AC200V, DC24V 3 Types & UN-FD4 AC100V, AC200V, DC24V 3 Types \\
\hline Rated Main Circuit Voltage & AC200 to \(240 \mathrm{~V} 50 / 60 \mathrm{~Hz}\) & AC380 to \(440 \mathrm{~V} 50 / 60 \mathrm{~Hz}\) \\
\hline Output Contact Arrangement & 1c & 1a and 1b Types \\
\hline Allowable Detection Retention Time & 1 Second (Minimum Rating) & Continuous Rating \\
\hline Fault Detection Criteria & \begin{tabular}{l}
- Detects When 1 or More of 2 Elements Have Continuity Failure For 2-Element Types \\
- Detects When 2 or More of 3 Elements Have Continuity Failure For 3-Element Types or Opening Faults
\end{tabular} & \begin{tabular}{l}
- Detects When 1 or More of 2 Elements Have Continuity Failure For 2-Element Types or When Both Elements Have Opening Faults \\
- Detects When 2 or More of 3 Elements Have Continuity Failure For 3-Element Types or Opening Faults \\
- Fault Detection For When the Control Input Signal is ON and Main Circuit Power Supply is OFF
\end{tabular} \\
\hline Fault Detection Retention & No Protection Function & Electric Retention via Operating Power Supply \\
\hline Reset & When Main Circuit Power Supply Is Open & When Operating Power Supply is Turned Off \\
\hline Indicator & None & \begin{tabular}{l}
- With Fault Detection Indicator Lamp \\
- With Operation Indicator Lamp
\end{tabular} \\
\hline
\end{tabular}

\section*{(1) UN-FD Type}

Rating
\begin{tabular}{|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{Appearance} & &  & \\
\hline \multicolumn{2}{|l|}{Model Name} & UN-FD AC100V & UN-FD AC200V & UN-FD DC24V \\
\hline \multicolumn{2}{|l|}{Rated Operational Voltage} & AC100 to 120 V 50/60 Hz & AC200 to 240 V \(50 / 60 \mathrm{~Hz}\) & DC24 V \\
\hline \multicolumn{2}{|l|}{Rated Main Circuit Voltage} & AC20 & 00 to \(240 \mathrm{~V} 50 / 60\) & 0 Hz \\
\hline \multicolumn{2}{|l|}{Input Current} & & 17 mA & \\
\hline \multirow{2}{*}{Output} & Cortact Arangement & & 1 c & \\
\hline & Contact Rating & AC240 V 1 A, AC120 V & 1.5 A (Class AC-15), DC & 24 V 1 A (Class DC12) \\
\hline \multicolumn{2}{|l|}{Minimum Control Input Time} & & 20 ms & \\
\hline \multicolumn{2}{|l|}{Detection Time} & & 0.2 to 0.5 s & \\
\hline \multicolumn{2}{|l|}{Allowable Detection Retention Time} & 1 Sec & cond (Minimum Rating & \\
\hline \multicolumn{2}{|l|}{Allowable Voltage Fluctuation Range} & 85 to 110\% of Rated V & Voltage (Both Control Ci & rcuit and Main Circuit) \\
\hline \multicolumn{2}{|l|}{Operating Temperature/Humidity} & -10 to & \(60^{\circ} \mathrm{C} / 45\) to 85\% & \% RH \\
\hline \multicolumn{2}{|l|}{Combined Protection Function} & \begin{tabular}{l}
(1) No-Fuse Brea \\
(2) Magnetic Co \\
- Operate the ab shut off power
\end{tabular} & kers with Voltage ntactors ove (1) or (2) with to the main circu & \begin{tabular}{l}
Tripping Device \\
hin 1 second to uit.
\end{tabular} \\
\hline
\end{tabular}
- Connecting


Note 1. UN-FD types cannot be used in the following circuits.
Capacitive Load Circuits • Star-Delta Starting Circuits • Inverter Circuits
Note 2. UN-FD types cannot be used in combination with UA-PC type power control units.
Note 3. CAN terminal types (UN-FDCX) are also manufactured.

\section*{- Operating Circuit}
(1) Figures 2 to 5 indicate the main and control circuits when both use the same power supply. Use separate power supplies if the main circuit voltage and control circuit voltage are different.
(2) When using thermal overload relays with motor loads, connect the break contact of the thermal overload relay in series with the contact signal.
(3) For single-phase loads, use any 2 of the UN-FD terminals numbered 15, 16 or 18 to connect to the terminals of the load.

Fig. 2 Connecting UN-FD Types and No-Fuse Breakers (With Drive Unit)


Fig. 3 Connecting UN-FD Types and Magnetic Contactors (With Drive Unit)


\section*{Related Equipment}

Fig. 4 Connecting UN-FD Types and No-Fuse Breakers (Without Drive Unit)


\section*{Operating Conditions}
(1) Normal operation is judged to be when load current flows while the control input signal is being input.
(2) Fault detection operation is judged to be when load current flows while the control input signal is in the OFF state.
(3) US-N or US-H units trigger fault detection operation of the UN-FD unit if a main circuit power supply is applied without a load connected. Connect an actual load or a sample load such as a resistor (so that 1 A or so flows) to check the operation of US-N or US-H units. This is in order for the fault detection unit to be able to determine that a fault has occurred in the US-N or US-H unit when a voltage approximately equal to the power supply voltage is applied (due to US-N or US-H leakage current) to the load side while the US-N or US-H unit is in the OFF state. This is not considered abnormal behavior of the fault detection unit.

Fig. 5 Connecting UN-FD Types and Magnetic Contactors (Without Drive Unit)


\section*{- Fault Detection Criteria}
- Detects when 1 or more of the 2 elements fail continuity tests for US-N \(\square\) (SS)(NS) and US-H solid state contactors. - Detects when 2 or more of the 3 elements fail continuity tests for US-N \(\square\) TE(SS)(NS) solid state contactors.

\section*{- Handling}
(1) A no-fuse breaker or magnetic contactor should be configured to open-circuit the main circuit after fault detection. When using a fault detection unit in combination with a no-fuse breaker with voltage tripping device, use the output make contact of the fault detection unit to trip the no-fuse breaker during a fault.
When using a fault detection unit (UN-FD) in combination with a magnetic contactor, use a self-retaining circuit to retain the magnetic contactor coil and configure it such that the output break contact of the fault detection unit releases the selfretaining circuit of the magnetic contactor coil, causing the magnetic contactor to form an open-circuit.
(2) UN-FD units are rated for only short periods of time, so the detection state should not be maintained for more than 1 second. UN-FD units are reset when the main circuit becomes open-circuited.
(3) UN-FD has a fault detection time of 0.2 to 0.5 seconds. UN-FD may malfunction when applied to a motor with a long residual voltage decay time or a solid state contactor switching capacitive loads. Therefore, consider using a system that allows operation input signals to be delayed or another device to detect faults.
(4) Input as the forward/reverse signal for UN-FD unit input circuits when using a circuit supporting reversing running.

\section*{(2) UN-FD4 Type}

Rating
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{Appearance} & \multicolumn{6}{|c|}{} \\
\hline \multicolumn{2}{|l|}{Model Name} & \[
\begin{gathered}
\text { UN-FD4 } \\
\text { AC100V1A }
\end{gathered}
\] & \[
\begin{gathered}
\text { UN-FD4 } \\
\text { AC100V1B }
\end{gathered}
\] & \[
\begin{gathered}
\text { UN-FD4 } \\
\text { AC200V1A }
\end{gathered}
\] & \[
\begin{gathered}
\hline \text { UN-FD4 } \\
\text { AC200V1B }
\end{gathered}
\] & \[
\begin{gathered}
\hline \text { UN-FD4 } \\
\text { DC24V1A }
\end{gathered}
\] & \[
\begin{gathered}
\hline \text { UN-FD4 } \\
\text { DC24V1B }
\end{gathered}
\] \\
\hline \multicolumn{2}{|l|}{Rated Operational Voltage} & \multicolumn{2}{|l|}{AC100 to \(120 \mathrm{~V} 50 / 60 \mathrm{~Hz}\)} & \multicolumn{2}{|l|}{AC200 to \(240 \mathrm{~V} 50 / 60 \mathrm{~Hz}\)} & \multicolumn{2}{|c|}{DC24 V} \\
\hline \multicolumn{2}{|l|}{Rated Main Circuit Voltage} & \multicolumn{6}{|c|}{AC380 to \(440 \mathrm{~V} 50 / 60 \mathrm{~Hz}\)} \\
\hline \multicolumn{2}{|l|}{Input Current} & \multicolumn{6}{|c|}{Control (A1 to A2): 17 mA , Signal (24): 10 mA} \\
\hline \multirow[b]{2}{*}{Output} & Contact Arangement & 1a & 1b & 1a & 1b & 1 a & 1b \\
\hline & Contact Rating & \multicolumn{6}{|c|}{AC240 V 1 A, AC120 V 1.5 A (Class AC-15), DC24 V 1 A (Class DC-12)} \\
\hline \multicolumn{2}{|l|}{Minimum Control Input Time} & \multicolumn{6}{|c|}{20 ms} \\
\hline \multicolumn{2}{|l|}{Detection Time} & \multicolumn{6}{|c|}{0.2 to 0.5 s} \\
\hline \multicolumn{2}{|l|}{Allowable Detection Retention Time} & \multicolumn{6}{|c|}{Continuous Rating} \\
\hline \multicolumn{2}{|l|}{Allowable Voltage Fluctuation Range} & \multicolumn{6}{|c|}{85 to 110\% of Rated Voltage (Both Control Circuit and Main Circuit)} \\
\hline \multicolumn{2}{|l|}{Operating Temperature/Humidity} & \multicolumn{6}{|c|}{-10 to \(60^{\circ} \mathrm{C} / 45\) to \(85 \% \mathrm{RH}\)} \\
\hline \multicolumn{2}{|l|}{Operation Indicator} & \multicolumn{6}{|c|}{Lights With Signal Input (Green LED)/Lights When in Fault State (Red LED)} \\
\hline \multicolumn{2}{|l|}{Combined Protection Function} & \[
\begin{array}{|c|}
\hline \text { No-Fuse Breakers } \\
\text { with Voltage Tripping Device } \\
\hline
\end{array}
\] & Magnetic Contactors & No-Fuse Breakers
with Voltage Tripping Device & Magnetic Contactors & \[
\begin{array}{|c|}
\hline \text { No-Fuse Breakers } \\
\text { with Voltage Tripping Device } \\
\hline
\end{array}
\] & Magnetic Contactors \\
\hline \multicolumn{2}{|l|}{Fault Detection Retention} & \multicolumn{6}{|c|}{Electric Retention via Operating Power Supply} \\
\hline \multicolumn{2}{|l|}{Fault Detection Reset} & \multicolumn{6}{|c|}{Resetting By Turning OFF Operating Power} \\
\hline
\end{tabular}

Note 1. UN-FD4 types cannot be used in the following circuits.
- Capacitive Load Circuits • Star-Delta Starting Circuits • Inverter Circuits

Note 2. UN-FD4 types cannot be used in combination with UA-PC type power control units.
Note 3. CAN terminal types (UN-FD4CX) are also manufactured.

\section*{Connecting}


\section*{Operating Circuit}
(1) Figures 8 to 11 indicate the main and control circuits when both use the same power supply. Use separate power supplies if the main circuit voltage and control circuit voltage are different.
(2) When using thermal overload relays with motor loads, connect the break contact of the thermal overload relay in series with the control input signal.
(3) For single-phase loads, use any 2 of the UN-FD4 terminals numbered 15, 16 or 18 to connect to the terminals of the load.

Fig. 8 Connecting UN-FDADIA Types and No-Fuse Breakers (With Drive Unit)


Fig. 9 Connecting UN-FD4D1B Types and Magnetic Contactors (With Drive Unit)



\section*{Operating Conditions}
(1) Normal operation is judged to be when load current flows while the control input signal is being input.
(2) Fault detection operation is judged to be when load current flows while the control input signal is in the OFF state. Detects a fault when the control input signal is ON while the main circuit power supply is OFF.
(3) US-N or US-H units trigger fault detection operation of the UN-FD4 unit if a main circuit power supply is applied without a load connected. Connect an actual load or a sample load such as a resistor (so that 1 A or so flows) to check the operation of US-N or US-H units. This is in order for the fault detection unit to be able to determine that a fault has occurred in the US-N or US-H unit when a voltage approximately equal to the power supply voltage is applied (due to US-N or US-H leakage current) to the load side while the US-N or US-H unit is in the OFF state. This is not considered abnormal behavior of the fault detection unit.


Note. It is also possible to use DC24V circuits alone if using DC operated magnetic contactors ( DC 24 V coils).


\section*{- Fault Detection Criteria}
- Detects when 1 or more of the 2 elements fail continuity tests or when both elements undergo open-circuit faults for US-N \(\square\) and US-H \(\square\) solid state contactors.
- Detects when 2 or more of the 3 elements fail continuity tests or open-circuit faults for US-N \(\square T E\) solid state contactors.

\section*{- Handling}
(1) A no-fuse breaker or magnetic contactor should be configured to open-circuit the main circuit after a fault has been detected
(2) UN-FD4 units do not reset until the operating power supply is switched OFF. Switch OFF the operating power supply in order to reset.
(3) UN-FD4 has a fault detection time of 0.2 to 0.5 seconds. UN-FD4 may malfunction when applied to a motor with a long residual voltage decay time or a solid state contactor switching capacitive loads. Therefore, consider using a system that allows operation input signals to be delayed or another device to detect faults.
(4) Input as the forward/reverse signal for UN-FD4 unit input circuits when using a circuit supporting reversing running.

\subsection*{11.5.5 Power Control Unit (UA-PC)}

UA-PC power control units can be combined with US-N or US-H solid state contactors to control power using a low-noise minimal-cycle control system that is ideal for controlling the temperature of electric heaters, etc.

Rating
\begin{tabular}{|c|c|c|c|}
\hline \multicolumn{2}{|l|}{Appearance} & \multicolumn{2}{|l|}{} \\
\hline \multicolumn{2}{|l|}{Model Name} & UA-PC AC100V & UA-PC AC200V \\
\hline \multicolumn{2}{|l|}{Rated Operational Voltage} & AC100 to \(110 \mathrm{~V} 50 / 60 \mathrm{~Hz}\) & AC200 to 220V 50/60Hz \\
\hline \multicolumn{2}{|l|}{Input Current} & \multicolumn{2}{|c|}{20 mA} \\
\hline \multicolumn{2}{|l|}{Control Method} & \multicolumn{2}{|l|}{Cycle Control (Zero Voltage Trigger)} \\
\hline \multicolumn{2}{|l|}{Input Signal} & \multicolumn{2}{|l|}{\begin{tabular}{l}
Current Signal : 4 to 20mA(250 ) \\
Voltage Signal : 1 to \(5 \mathrm{~V}(100 \mathrm{k} \Omega)\) \\
Contact Signal : ON, OFF Symbols \\
Variable Resistance : Manual Setting/Gradient Setting
\end{tabular}} \\
\hline \multicolumn{2}{|l|}{Rated Output Voltage/Current} & \multicolumn{2}{|c|}{DC12V/20mA} \\
\hline \multicolumn{2}{|l|}{Gradient Setting} & \multicolumn{2}{|l|}{0 to 100\%(Adjustable Via Setter)} \\
\hline \multicolumn{2}{|l|}{Control Period} & \multicolumn{2}{|l|}{0.2 to 1s (Adjustable Via Setter)} \\
\hline \multirow[t]{2}{*}{Combining US-N/US-H} &  & \multicolumn{2}{|c|}{0 to 100\%} \\
\hline & Applicable Loads & \multicolumn{2}{|r|}{Resistor/Heating Element} \\
\hline \multirow[t]{2}{*}{Operation Indicator} & Power Indicator & \multicolumn{2}{|l|}{Lights With Control Circuit Voltage Input (Red LED)} \\
\hline & Output Indicator & \multicolumn{2}{|l|}{Lights With US-N Drive Signal Output (Red LED)} \\
\hline \multicolumn{2}{|l|}{Allowable Voltage Fluctuation Range} & \multicolumn{2}{|l|}{85 to 110\% of Rated Operational Voltage} \\
\hline \multicolumn{2}{|l|}{Operating Temperature/Humidity} & \multicolumn{2}{|l|}{-10 to \(60^{\circ} \mathrm{C} / 45\) to \(85 \% \mathrm{RH}\)} \\
\hline
\end{tabular}

Connecting


\section*{Properties}

\section*{Fig. 2 Output Properties}


\section*{Fig. 3 Gradient Properties}



\section*{Operating Circuit}

Fig. 4 Operating Circuit Example


\section*{Related Equipment}

\section*{Application}
(1) No. of US-N Drive Units

The below indicates the number of US-N or US-H drive units for UA-PC units.
\begin{tabular}{|c|c|c|}
\hline Man Civiicantol Method & \multicolumn{2}{|c|}{3-Pole Batch Control} \\
\hline Model Name & US-N5SS(TE)/N8SS(TE) US-N70NS(TE)/N80NS(TE) US-NH70NS(TE)/NH80NS(TE) & US-N20(TE)to N50(TE) \\
\hline Connection Circuit & Capable Of Driving Up To 1 Units
\begin{tabular}{|l|l|l|l|}
\hline \multirow{2}{*}{ UA-PC } & (C1) & Al & US-N \\
& (C2) & A2 & \\
\hline
\end{tabular} & Capable Of Driving Up To 4 Units \\
\hline Maic Cinit Cantol Method & \multicolumn{2}{|c|}{3-Pole Individual Control} \\
\hline Model Name & US-H2O to H50 & US-H20DD to H50DD \\
\hline Connection Circuit &  & Capable Of Driving Up To 1 Unit (2 Circuits) \\
\hline
\end{tabular}
(2) Signal Input Circuit Example
(1) to (18) show the possible signal input circuits.



\section*{Related Equipment}
(3) Application Example - Rapid Start-Up Load Temperature Circuit via a UA-PC Power Control Unit

This method of temperature control rapidly starts up electric heaters to reach the set temperature in the shortest amount of time. To achieve this, the heat is initially turned on at \(100 \%\) power for rapid heating, then as the temperature approaches the set temperature the power level is reduced.
The way in which UA-PC units support this kind of temperature control is indicated below.
(1) Usage Method

Short-circuiting terminals 1 and C2 of the UA-PC power control unit being used results in a 100\% output signal regardless of control input signal.
Accordingly, the required functionality can be achieved by using a contact to control the current path between terminals 1 and C2.
a) Time Control Using Timers

A timer is used to short-circuit terminals 1 and C2 for a fixed period of time only after power has been applied to the electric heater, open-circuiting the contact after the timed period has elapsed.
b) Control Using Thermal Switches or Temperature Controllers with Lower-Limit Alarm Outputs

Thermal switches which activate when the electric heater temperature is a little below the set temperature, or a temperature controller with lower-limit alarm output (open-circuited at low temperatures) are used to control the current path between terminals 1 and C2.
(2) Operating Circuit Example

\section*{Fig. 5 Rapid Start-Up Load Temperature Circuit}


\section*{Handling}
(1) Applicable Loads

UA-PC power control units are intended only for use with resistive loads and cannot be used with inductive loads or for control of transformer primary coils. Select a solid state contactor rated to suit the heater capacity.
(2) Wiring
-Wiring between the UA-PC unit and temperature controller/setter should be as short as possible ( 3 m or less) and should be connected such that each of the respective signals match.
- For lengths exceeding 3 m , use a single-core wire or a 2-core shielded wire ( 10 m or less) and connect the shield to ground.
- Use 10 m or less of twisted-pair cable for wiring the UA-PC output terminals and solid state contactor input terminals together.
- Avoid parallel wiring between the control circuit and main circuit.
(3) Setters

The below types of variable resistors are available for external setting.
\begin{tabular}{|c|c|}
\hline UA-PC \\
\hline
\end{tabular}
\begin{tabular}{|c|c|}
\hline Symbol & Resistor/Application \\
\hline VR10 & \(10 \mathrm{k} \Omega /\) Gradient Setter \\
\hline VR1 & \(1 \mathrm{k} \Omega /\) Main Setter \\
\hline
\end{tabular}



Pre-Drilled Holes

s



\subsection*{11.5.6 Live Part Protection Cover Units}

Covers for preventing inadvertent contact with live parts after wiring in panel mounting.
The below live part protection cover units are available as optional units or as US-H \(\square\) type live part protection covers.

\section*{Production Range/Applicable Models}
\begin{tabular}{l|l}
\hline \multicolumn{1}{c|}{ Model Name } & \multicolumn{1}{c}{ Applicable Models } \\
\hline UA-CVDR1 & UA-DR1, UA-SH1 \\
\hline UA-CVSH8 & UA-SH8 \\
\hline UN-CV501US & US-H20/H30/H40/H50(DD), US-H20/H30(DD)UF \\
\hline
\end{tabular}

\section*{Outline Drawings}
Model Name \(\quad\) UA-CVDR1

\section*{Mounting Method}
Model Name

\section*{Related Equipment}

\section*{Removal Method}
Model Name

\section*{- Minimum Order Unit}

The minimum order quantity for all types is 10 pieces. 10 pieces per bag are shipped. Place orders in multiples of 10 when ordering.

\subsection*{11.6 Outline Drawings}
- US-N Solid State Contactors
\begin{tabular}{|c|c|c|c|c|}
\hline Model Name & Appearance & Outline Drawings & Hole Drilling Dimensions & Weight (kg) \\
\hline US-N5SS US-N5SSTE US-N8SS US-N8SSTE &  & \begin{tabular}{l}
 \\
*2 Dimension: Dimensions when UA-SH8 mounted with US-ND unit covers removed. The values in parentheses show dimensions including UA-CVSH8.
\end{tabular} & Mounting Dimension: Also Allow For \(30 \times 52\), \(34 \times 52\) and \(30 \times 48\). & \begin{tabular}{l}
\[
\begin{array}{|c}
\text { US-N5SS } \\
\text { US-N5SSTE } \\
0.27
\end{array}
\] \\
US-N8SS
US-N8SSTE
\[
0.4
\]
\end{tabular} \\
\hline US-N20(CX) US-N20TE(CX) US-N30(CX) &  &  &  & 0.78 \\
\hline US-N20(CX)RM US-N20TE(CX)RM &  &  & - & 0.8 \\
\hline US-N30TE(CX) US-N40(CX) US-N40TE(CX) US-N50(CX) &  &  &  & 1.2 \\
\hline US-N50TE(CX) &  &  &  & 1.58 \\
\hline US-N70NS US-N70NSTE US-N80NS US-N80NSTE &  &  &  & \begin{tabular}{l}
US-N70NS US-N70NSTE \\
1.8 \\
US-N8ONS US-N80NSTE 1.9
\end{tabular} \\
\hline US-NH70NS US-NH70NSTE US-NH80NS US-NH80NSTE &  &  &  & \begin{tabular}{l}
US-NH70NS US-NH70NSTE \\
1.9 \\
US-NH80NS US-NH8ONSTE 2.0
\end{tabular} \\
\hline
\end{tabular}

\section*{11 \\ Related Equipment}

US-H Solid State Contactors
\begin{tabular}{|c|c|c|c|c|}
\hline Model Name & Appearance & Outline Drawings & Hole Drilling Dimensions & Weight (kg) \\
\hline \[
\begin{aligned}
& \text { US-H2O } \\
& \text { US-H20DD } \\
& \text { US-H30 } \\
& \text { US-H3ODD }
\end{aligned}
\] &  & *1 Dimension: Dimensions including live part protection cover UN-CV501US. &  & 0.42 \\
\hline \[
\begin{aligned}
& \text { US-H40 } \\
& \text { US-H40DD } \\
& \text { US-H50 } \\
& \text { US-H50DD }
\end{aligned}
\] &  & *1 Dimension: Dimensions including live part protection cover UN-CV501US. &  & 0.85 \\
\hline \begin{tabular}{l}
US-H2OHZ \\
US-H20DDHZ \\
US-H3OHZ \\
US-H30DDHZ \\
US-H4OHZ \\
US-H4ODDHZ \\
US-H5OHZ \\
US-H50DDHZ
\end{tabular} &  & *1 Dimension: Dimensions including live part protection cover UN-CV501US. &  & 0.13 \\
\hline US-H20RM US-H20DDRM US-H30RM US-H30DDRM &  & *1 Dimension: Dimensions including live part protection cover UN-CV501US. &  & 0.44 \\
\hline \[
\begin{aligned}
& \text { US-H20UF } \\
& \text { US-H2ODDUF }
\end{aligned}
\] &  & *1 Dimension: Dimensions including live part protection cover UN-CV501US. &  & 0.52 \\
\hline \[
\begin{aligned}
& \text { US-H3OUF } \\
& \text { US-H30DDUF }
\end{aligned}
\] &  & *1 Dimension: Dimensions including live part protection cover UN-CV501US. &  & 0.68 \\
\hline
\end{tabular}

Optional
\begin{tabular}{|c|c|c|c|c|}
\hline Model Name & Appearance & Outline Drawings & Hole Drilling Dimensions & Weight (kg) \\
\hline UA-SH8 &  & *1 Dimension: Dimensions including live part protection cover UA-CVSH8. & Can be mounted on US-N5SS(TE) types. (Front Clip-on Type) Connecting conductor is included with the unit. & 0.5 \\
\hline \begin{tabular}{l}
UA-DR1 \\
UA-SH1
\end{tabular} &  & *1 Dimension: Dimensions including live part protection cover UA-CVDR1. & UA-DR1 and UA-SH1 include connecting conductors for US-N. & 0.1 \\
\hline \begin{tabular}{l}
UA-RE \\
UN-FD \\
UN-FD4
\end{tabular} &  & *1 Dimension: Dimension from Center of IEC 35 mm Rail. &  & 0.1 \\
\hline UA-PC &  & *1 Dimension: Dimension from Center of IEC 35 mm Rail. &  & 0.5 \\
\hline
\end{tabular}

\section*{Related Equipment}

\subsection*{11.7 ET-N \(\square\) Electric Motor Protection Relays}

Electric motor protection relays that can protect against overloads (including restriction) and open-phases (including unbalanced currents) during AC motor start-up or running, as well as detect reverse-phase states.

\section*{Features}
- Optimal Protection to Suit Load Properties

Protection function and overload operating time can be selected to suit the load via the mode setting switch.
Protection Function: Overload, Open-Phase and Reverse-Phase Combination
Operating Time: Select Among 3/5/7/15/30 Seconds
(At Current 600\% of Setpoint)
- Wide Current Settling Range

Applicable with a current settling range 3 to 4 times the minimum scale.
- Easy Fault-Finding Via Operation Indicator Lamp

Indicators: Power/Overload/Open-Phase/Reverse-Phase
- Indicates Load Equipment Running State

Indicates the normal running or stopped states of load equipment.
- Output Contacts 1a1b

Make contacts and break contacts are completely independent and
can be used with circuits at different voltages.
- Simple Operation

Has settings/operation displays located on the front surface to make initial settings and maintenance easy.
Settings/operation displays have protective covers to prevent misoperation.
- Operation Checking

Checking of overload operation properties is possible.
Can also be operated momentarily with external testing circuits.
- Self-Diagnosing Functionality

Equipped with self-diagnosing functionality that triggers a trip when abnormalities are detected.


ET-N60
- Compact

ET-N60 have a reduced width of 78 mm which is effective for reducing the size of control panels.
- Simple Wiring

The main circuit wiring is connected via terminals so there is no need to wind up main circuit power lines.
- Rail Mounting Standardized

ET-N60 can be mounted on IEC, DIN and JIS standards compliant 35 mm width rail.

\section*{Type Designations}
- Electric Motor Protection Relays
\begin{tabular}{|c|c|c|c|c|c|}
\hline ET & - - & \(\triangle\) & \(\triangle\) & AC100V & \\
\hline Symbol & Frame Size & Symbol & Current Settling Range & Symbol & Rated Operational Voltage \\
\hline & & 1A & 0.25 to 1 A & AC100V & AC100 to \(120 \mathrm{~V} 50 / 60 \mathrm{~Hz}\) \\
\hline & & 4A & 1 to 4 A & AC200V & AC200 to \(240 \mathrm{~V} 50 / 60 \mathrm{~Hz}\) \\
\hline N60 & 60 A Frame & 8A & 2 to 8 A & & \\
\hline & & 20A & 5 to 20 A & & \\
\hline & & 60A & 15 to 60 A & & \\
\hline N150 & 150 A Frame & 150A & 40 to 150 A & & \\
\hline N360 & 360 A Frame & 360A & 110 to 360 A & & \\
\hline
\end{tabular}
- Terminal Cover Units


\section*{Rating}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{\multirow{2}{*}{Model Name}} & \multirow[t]{2}{*}{Range of Settling Current [A]} & \multicolumn{2}{|l|}{Applicable Motor Capacity [kW]} & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Model Name}} & \multirow[t]{2}{*}{Range of Settling Current [A]} & \multicolumn{2}{|l|}{Applicable Motor Capacity [kW]} \\
\hline & & & 200 to 220 V & 400 to 440 V & & & & 200 to 220 V & 400 to 440 V \\
\hline ET-N60 & 1A & 0.25 to 1 & 0.03 to 0.2 & 0.05 to 0.4 & ET-N60 & 60A & 15 to 60 & 3.7 to 11 & 7.5 to 22 \\
\hline ET-N60 & 4 A & 1 to 4 & 0.2 to 0.75 & 0.4 to 1.5 & ET-N150 & 150A & 40 to 150 & 11 to 37 & 22 to 75 \\
\hline ET-N60 & 8A & 2 to 8 & 0.4 to 1.5 & 0.75 to 2.2 & ET-N360 & 360A & 110 to 360 & 30 to 90 & 55 to 150 \\
\hline ET-N60 & 20A & 5 to 20 & 1.5 to 4 & 2.2 to 7.5 & & & & & \\
\hline
\end{tabular}

\section*{Properties}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline Main Circuit Rat & d Insulation Voltage & \multicolumn{7}{|c|}{\(660 \mathrm{~V} 50 / 60 \mathrm{~Hz}\)} \\
\hline \multicolumn{2}{|l|}{Rated Current} & 1A & 4A & 8A & 20A & 60A & 150A & 360A \\
\hline \multicolumn{2}{|l|}{Current Settling Range} & 0.25 to 1A & 1 to 4A & 2 to 8A & 5 to 20A & 15 to 60A & 40 to 150A & 110 to 360A \\
\hline \multicolumn{2}{|l|}{Control Circuit Rated Operational Voltage} & \multicolumn{7}{|c|}{100 to 120 V or 200 to \(240 \mathrm{~V} 50 / 60 \mathrm{~Hz}\)} \\
\hline \multicolumn{2}{|l|}{Allowable Operating Voltage Fluctuation Range} & \multicolumn{7}{|c|}{85 to 110\% of Rated Operational Voltage} \\
\hline \multicolumn{2}{|l|}{Control Circuit Input} & \multicolumn{7}{|c|}{For AC100 V: 7 VA (With AC100 V Applied)/For AC200 V: 14 VA (With AC200 V Applied)} \\
\hline \multirow{3}{*}{Output Contact} & Contact Arrangement & \multicolumn{7}{|c|}{1a1b} \\
\hline & Rating & \multicolumn{7}{|c|}{AC240 V 1 A, AC120 V 2 A (Class AC-15)} \\
\hline & Reset & \multicolumn{7}{|c|}{Manual Reset} \\
\hline \multicolumn{2}{|l|}{Protection Mode} & \multicolumn{7}{|c|}{Overload/Overload + Open-Phase/Overload + Open-Phase + Reverse-Phase} \\
\hline \multirow{3}{*}{Overload} & Operating Current & \multicolumn{7}{|c|}{115 \(\pm 5 \%\)} \\
\hline & Operating Time & \multicolumn{7}{|c|}{3/5/7/15/30 Seconds (at 600\% Current)} \\
\hline & Operating Method & \multicolumn{7}{|c|}{Heat-Accumulating Operation (Inching/Hot Start Protection)} \\
\hline \multirow{3}{*}{Open Phase} & Operating Current & \multicolumn{7}{|c|}{70\% or More} \\
\hline & Imbalance Sensitivity & \multicolumn{7}{|c|}{30 to 50\%} \\
\hline & Operating Time & \multicolumn{7}{|c|}{\(3 \pm 1 \mathrm{~s}\)} \\
\hline \multirow{3}{*}{Reverse-Phase} & Detection Method & \multicolumn{7}{|c|}{Current Detection} \\
\hline & Operating Current & \multicolumn{7}{|c|}{70\% or More} \\
\hline & Operating Time & \multicolumn{7}{|c|}{0.5 s or Less} \\
\hline \multicolumn{2}{|l|}{Property Fluctuations As Voltage Fluctuates} & \multicolumn{7}{|c|}{Operating Current \(\pm 5 \%\), Operating Time \(\pm 10 \%\)} \\
\hline \multicolumn{2}{|l|}{Property Fluctuations As Temperature Fluctuates} & \multicolumn{7}{|c|}{Operating Current \(\pm 5 \%\), Operating Time \(\pm 10 \%\)} \\
\hline \multicolumn{2}{|l|}{Operation Indicator Lamp} & \multicolumn{7}{|c|}{Power/Overload/Open-Phase/Reverse-Phase Individual Tripping Indicators} \\
\hline \multicolumn{2}{|l|}{Withstand Voltage} & \multicolumn{7}{|c|}{Main Circuit: AC2500 V for 1 Minute, Operation Control Circuit: AC2000 V for 1 Minute} \\
\hline
\end{tabular}

\section*{Working Environment Criteria}
(1) Ambient Temperature: -10 to \(55^{\circ} \mathrm{C}\) (no condensation, no freezing)
(2) Relative Humidity: 45 to \(85 \%\) RH
(3) Vibration: 10 to \(55 \mathrm{~Hz} 19.6 \mathrm{~m} / \mathrm{s}^{2}\) or Less
(4) Shock: \(49 \mathrm{~m} / \mathrm{s}^{2}\) or Less
(5) Altitude: 2000 m or Below

\section*{- Handling}
- Control Panel

The protection mode setting switch and current adjusting dial have a control groove to support control operations via compact minus (flathead) screwdrivers.


Fig. 1. Control Panel

Note 1. When operating the buttons with the protective
cover on, do so with the button front surface part open.
If the buttons are pressed from above the cover without opening it, unnecessary operations may occur.

\section*{- Protection Mode Settings}

Configure the protection function and operating time via the protection mode settings switch to suit the load characteristics and application before use. The switch is set to position 0 at shipping.
However, if the settings switch is stopped between two values unstable operation may result, so take care ensure a clear selection is made.
Do not set the switch to the "F" position.


Fig. 2. Overload Protection Properties
- Protection Mode Setting Switch Settings and Protection Functionality
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline Set Position & Protection Function & Operating Time (At 600\% l) & Set Position & Protection Function & \[
\begin{gathered}
\text { Operating Time } \\
\text { (At } 600 \% 1 \text { ) }
\end{gathered}
\] & Set Position & Protection Function & Operating Time (At 600\% I) \\
\hline 0 & Overioad, Open-Phase and Reverse-Phase Protection (3E) & 3 s & 5 & Overload and Open-Phase Protection (2E) & 3 s & A & Overload Protection (1E) & 3 s \\
\hline 1 & Overload, Open-Phase and Reverse-Phase Protection (3E) & 5 s & 6 & Overload and Open-Phase Protection (2E) & 5 s & B & Overload Protection (1E) & 5 s \\
\hline 2 & Overload, Open-Phase and Reverse-Phase Protection (3E) & 7 s & 7 & Overload and Open-Phase Protection (2E) & 7 s & C & Overload Protection (1E) & 7 s \\
\hline 3 & Overioad, Open-Phase and Reverse-Phase Protection (3E) & 15 s & 8 & Overload and Open-Phase Protection (2E) & 15 s & D & Overload Protection (1E) & 15 s \\
\hline 4 & Overioad, Open-Phase and Reverse-Phase Protection (3E) & 30 s & 9 & Overload and Open-Phase Protection (2E) & 30 s & E & Overload Protection (1E) & 30 s \\
\hline
\end{tabular}

\section*{- Configuring Settling Current}

Configure the current adjusting dial to suit the rated current of the load before use.
For greater precision configuration, illuminate the "OC" lamp of the ET-N when setting the current.
- Detailed Setting Procedure (Set the current using the following procedure.)
(1) Turn the current setting dial to the maximum position.
(2) Apply the operating power supply.
(3) Allow \(115 \%\) of the rated motor current to flow through the ET-N main circuit terminal using an actual load or a resistor.
(4) Set the protection mode setting switch to " A " to " E " if testing single-phase current, connect the main circuit in series with 1/L1 phase, 3/L2 phase and 5/L3 phase, then allow the main circuit current to flow.
(5) The "OC" indicator lamp should now blink with a 1 second period.
(6) In this state, slowly reduce the current value using the current setting dial. (Rotate to the left)
(7) Stop turning the current setting dial when the "OC" indicator lamp blinking changes from a 1 second period to a 0.2 second period to complete configuration.
The overload protection properties are those shown in Figure 2. Configure special load devices by first verifying the overload withstanding capacity of the device.
Do not turn the current adjusting dial past the maximum or minimum values of the rated current range.

\section*{Related Equipment}

\section*{- Mounting}

The control circuit terminal should be facing downwards to be in the correct orientation when screw mounting or IEC 35 mm rail mounting on vertical surfaces.
If mounting horizontally with screws, then rotate the unit 90 degrees in a counterclockwise direction.
Close mounting is not possible, as a minimum gap of
10 mm should be established when mounting.

\section*{- Indicator Lamp Display Contents}

4 indicator lamps are used to indicate the running and tripping status of the load device.
\begin{tabular}{c|c|c|c}
\hline Indicator LampN Nanes & Always Lit & 1 s Blinking & 0.2 s Blinking \\
\hline PW & Power Indicator & Self-Diagnosing Abnormal Tripping & - \\
\hline OC & Overload & \begin{tabular}{c} 
Load Running \\
Tripping
\end{tabular} & \begin{tabular}{l} 
Testing Overcurrent \\
and Overload \\
Protection (Test 1)
\end{tabular} \\
\hline PF & Open Phase Tripping & - & - \\
\hline REV & Reverse-Phase Tripping & Test Tripping (Test 2) & - \\
\hline
\end{tabular}
- Tests
(1) Overload Protection Testing (Test 1)

Pressing the test button applies a signal with 600\% normal current in order to test the overload protection function. The OC indicator lamp will blink with a 0.2 second period. Continue to press the test button and time how long it takes until the OC indicator lamp is continuously lit or the output contact operates in order to test the overload protection function.
The operating time should be \(\pm 10 \%\) of the operating time range (at 600\% current) configured with the protection mode settings switch.
(2) Test Tripping (Test 2)

Simultaneously press the test button and reset button to momentarily trip the output relay.

\section*{- Reset}

Press the reset button to reset the tripped state relay. If tripped via an overload then the relay cannot be immediately reset. (If tripped via an overload then the relay cannot be reset for 5 minutes) Open-phase or reversephase trips can be reset. The relay is reset electrically so cannot be reset if the operating power supply is OFF.
- Reverse-Phase Protection

The operating time for reverse-phase protection is 0.5 seconds, so the motor will rotate in the reverse direction for a short period of time even if the phases are reversed. If reversing for even a short period of time cannot be tolerated, then use in combination with a separate reverse-phase protection relay. The current flowing in ET-N main circuit terminals is used to detect phase reversal, so detection is not possible if the order of the phases between ET-N and the load device are changed.
- Non-Applicable Loads

ET-N units have an integrated current transformer that detects main circuit current and provides overcurrent protection, protecting the load device. (Refer to Figure 3). The integrated current transformer is designed to detect 50/60 Hz power, so a reduction in power supply frequency (low inverter operating frequency) may fail to saturate the iron core of the transformer, causing only low signals from the main circuit current to be detected, changing the operating properties of the ET-N unit. ET-N units cannot be used to protect motors for the above reasons when driving with an inverter and so should not be used.
They are similarly unusable for DC circuits or for circuits other than \(50 / 60 \mathrm{~Hz}\) for the same reasons.
- Applicable Wires
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Model Name} & \multicolumn{4}{|c|}{Main Circuit} & \multicolumn{4}{|c|}{Control Circuit} \\
\hline & \begin{tabular}{|l|}
\hline Terminal \\
Screw \\
Size \\
\hline
\end{tabular} & Applicable Wires & \begin{tabular}{|c} 
Applicable \\
Crimp \\
Lugs
\end{tabular} & \[
\begin{array}{|c|}
\hline \text { Tghtitang Toruve } \\
\text { N.m Parenthesess } \\
\text { show standad value }
\end{array}
\] & \[
\begin{gathered}
\hline \text { Terminal } \\
\text { Screw } \\
\text { Size } \\
\hline
\end{gathered}
\] & Applicable Wires & Applicable Crimp Lugs & \begin{tabular}{|c} 
Tightering Torque \\
N.m Parentheses \\
show standard value
\end{tabular} \\
\hline \[
\begin{aligned}
& \text { ET-N60 } \\
& 1 \mathrm{~A} \text { to } 60 \mathrm{~A}
\end{aligned}
\] & M5 & \multirow{3}{*}{-} & \[
\begin{aligned}
& 1.25-5 \\
& \text { to } 14-5
\end{aligned}
\] & \[
\begin{gathered}
2.06 \text { to } 3.33 \\
(2.54)
\end{gathered}
\] & \multirow{3}{*}{M3.5} & \multirow{3}{*}{\[
\begin{aligned}
& 1.25 \text { to } 2 \mathrm{~mm}^{2} \\
& \varphi 1.6 \mathrm{~mm}
\end{aligned}
\]} & \multirow{3}{*}{\[
\begin{aligned}
& 1.25-3.5 \\
& \text { to } 2-3.5 \varphi
\end{aligned}
\]} & \multirow{3}{*}{\[
\begin{gathered}
0.94 \text { to } 1.51 \\
(1.17)
\end{gathered}
\]} \\
\hline \[
\begin{array}{r}
\hline \text { ET-N150 } \\
150 \mathrm{~A}
\end{array}
\] & M8 & & \[
\begin{aligned}
& 5.5-8 \\
& \text { to } 60-8
\end{aligned}
\] & \[
\begin{gathered}
6.28 \text { to } 10.29 \\
(7.84)
\end{gathered}
\] & & & & \\
\hline \[
\begin{array}{r}
\hline \text { ET-N360 } \\
360 \mathrm{~A}
\end{array}
\] & M12 & & \[
\begin{aligned}
& \text { 5.5-12 } \\
& \text { to } 200-12
\end{aligned}
\] & \[
\begin{array}{|c}
19.6 \text { to } 31.3 \\
(24.5)
\end{array}
\] & & & & \\
\hline
\end{tabular}

The external current transformer should be used with objects that have large overcurrent time constants in order not to saturate up to 600\% rated motor current.
(3) Single-Phase Motor Application

Single-phase loads should be connected with the protection mode setting switch set to any of overcurrent protection positions \(A\) to \(E\) as per Figure 5.
(4) Phase Advanced Capacitor Connections

Phase advanced capacitors should be connected to the main circuit power supply side of ET-N units as per Figure 6.

Outline Drawings

- UN-CV602 Live Part Protection Cover Units

\section*{- Outline Drawings}

- Mounting Method

1. Insert protrusion \(A\) of the live part protection cover into groove A of the ET-N upper surface. (Figs. (1) and (2))
2. Press the live part protection cover B claw in the direction of the arrow and insert it into the \(B\) groove of the ET-N lower surface. (Figs. (1) and (2))
\begin{tabular}{|c|c|}
\hline Model Name & Minimum Order Unit \\
\hline UN-CV602 & 5 (5-Pack) \\
\hline
\end{tabular}

\section*{Related Equipment}

\subsection*{11.8 SRE Voltage Detection Relays}

SRE-AA units can detect both DC and AC overvoltage or undervoltage conditions with high precision, and have a wide configurable range from 0.1 V to 250 V . SRE-K units not only allow detection by simply connecting to a power terminal but can be used to detect drops in power supply voltage, such as a warning when switching to home generated power during a power outage or when battery voltage drops.

\section*{Features}
- High External Surge Withstand Capability
The integrated surge absorber circuit delivers excellent external surge withstanding capacity.
- Simple Wiring Adopts self-lifting terminal screws for simple wiring.
- High Precision

The detector uses an IC for high accuracy and high reliability.
- High Input Impedance

Has a high input impedance so as to not affect other equipment.
- Wide Detection Range

Has a wide 0.1 to 250 V range for DC and 3 to 250 V range for AC .
(For Standard Detection)

\section*{Type Designations}

\section*{1. For Standard Detection}

2. For Power Detection


Note. AC detection is applicable for those items marked with \(*\) above.
Ratings/Specifications
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline By Model & \multicolumn{2}{|r|}{Model Name} & Detection Voltage Setting Range & Detector Input Max. Voltage (Continuous) & Input Impedance & Output Contact & Rated Operational Voltage \\
\hline \multirow{11}{*}{For Standard Detection} & \multirow{11}{*}{SRE-AA SRE-AAU} & OP5D & DC 0.1 to 0.5 V & \(\pm 100 \mathrm{~V}\) & \(20 \mathrm{~K} \Omega\) & \multirow[b]{9}{*}{Contact Arrangement 1c} & \multirow{11}{*}{\[
\begin{gathered}
\text { AC100 to } 110,200 \text { to } 220 \mathrm{~V} \\
50 / 60 \mathrm{~Hz} \text { Shared Use } \\
\text { or } \\
\text { AC115 to } 120,230 \text { to } 240 \mathrm{~V} \\
50 / 60 \mathrm{~Hz}
\end{gathered}
\]} \\
\hline & & 1P5D & DC 0.3 to 1.5 V & \(\pm 100 \mathrm{~V}\) & \(50 \mathrm{~K} \Omega\) & & \\
\hline & & 005D & DC 1 to 5 V & \(\pm 150 \mathrm{~V}\) & \(100 \mathrm{~K} \Omega\) & & \\
\hline & & 015D & DC 3 to 15 V & \(\pm 150 \mathrm{~V}\) & \(100 \mathrm{~K} \Omega\) & & \\
\hline & & 050D & DC 10 to 50 V & \(\pm 200 \mathrm{~V}\) & \(500 \mathrm{~K} \Omega\) & & \\
\hline & & 150D & DC 30 to 150 V & \(\pm 300 \mathrm{~V}\) & \(800 \mathrm{~K} \Omega\) & & \\
\hline & & 250D & DC 50 to 250 V & \(\pm 300 \mathrm{~V}\) & \(800 \mathrm{~K} \Omega\) & & \\
\hline & & 015A & AC 3 to 15 V & AC150 V & \(100 \mathrm{~K} \Omega\) & & \\
\hline & & 050A & AC 10 to 50 V & AC200 V & \(500 \mathrm{~K} \Omega\) & & \\
\hline & & 150A & AC 30 to 150 V & AC300 V & \(800 \mathrm{~K} \Omega\) & \multirow[t]{2}{*}{Rated Operating Current Class AC-15 Electrical Durability} & \\
\hline & & 250A & AC 50 to 250 V & AC300 V & \(800 \mathrm{~K} \Omega\) & & \\
\hline \multirow{14}{*}{For Power Detection} & \multirow{7}{*}{SRE-K} & AC100V & AC 75 to 105 V & AC120 V & \multirow{4}{*}{\[
\begin{aligned}
& \text { Input } \\
& 1.8 \mathrm{VA}
\end{aligned}
\]} & \multirow[t]{5}{*}{\begin{tabular}{ll} 
& of 0.5 mil. times \\
AC110 V & 1.5 A \\
AC220 V & 1 A \\
Class DC-13 & Electrical Durability \\
& of 0.25 mil. times \\
DC110 V & 0.2 A
\end{tabular}} & AC100 V 50/60 Hz Shared Use \\
\hline & & AC120V & AC 90 to 125 V & AC132 V & & & AC120 V 50/60 Hz Shared Use \\
\hline & & AC200V & AC 150 to 210 V & AC240 V & & & AC200 V 50/60 Hz Shared Use \\
\hline & & AC240V & AC 180 to 250 V & AC264 V & & & AC240 V 50/60 Hz Shared Use \\
\hline & & DC12V & DC 9 to 12.5 V & DC 14 V & \multirow{3}{*}{\[
\begin{aligned}
& \text { Input } \\
& 1.7 \mathrm{~W}
\end{aligned}
\]} & & DC 12 V \\
\hline & & DC24V & DC 18 to 25 V & DC 28 V & & \multirow[b]{2}{*}{Rated Continuity Current Ith 3 A} & DC 24 V \\
\hline & & DC100V & DC 75 to 105 V & DC120 V & & & DC100 V \\
\hline & \multirow{7}{*}{SRE-KT} & AC100V & AC 80 to 115 V & AC120 V & \multirow{4}{*}{\[
\begin{aligned}
& \text { Input } \\
& 1.8 \mathrm{VA}
\end{aligned}
\]} & & AC100 V 50/60 Hz Shared Use \\
\hline & & AC120V & AC 95 to 130 V & AC132 V & & & AC120 V 50/60 Hz Shared Use \\
\hline & & AC200V & AC 160 to 230 V & AC240 V & & & AC200 V \(50 / 60 \mathrm{~Hz}\) Shared Use \\
\hline & & AC240V & AC 190 to 260 V & AC264 V & & & AC240 V \(50 / 60 \mathrm{~Hz}\) Shared Use \\
\hline & & DC12V & DC 10 to 14 V & DC 14 V & \multirow{3}{*}{\[
\begin{aligned}
& \text { Input } \\
& 1.7 \mathrm{~W}
\end{aligned}
\]} & & DC 12 V \\
\hline & & DC24V & DC 20 to 28 V & DC 28 V & & & DC 24 V \\
\hline & & DC100V & DC 80 to 115 V & DC120 V & & & DC100 V \\
\hline
\end{tabular}

Note. SRE-AA(U) DC detectors can be used with single-phase full-wave power supplies.

Properties
\begin{tabular}{l|c|c|c}
\hline \multicolumn{1}{c|}{ Item } & Use Conditions & Properties & Remarks \\
\hline Voltage Fluctuation Properties & 85 to \(110 \%\) of Rated Operational Voltage & \(\pm 1.5 \%\) & Excluding SRE-K, KT Types \\
\hline Ambient Temperature Properties & \(-10^{\circ} \mathrm{C}\) to \(55^{\circ} \mathrm{C}\) & \(\pm 2.5 \%\) & \\
\hline Repeat Properties & Repeating under Identical Conditions & \(\pm 1 \%\) & \\
\hline Response Time & \(150 \%\) of Set Voltage Applied & 100 ms & \\
\hline Withstand Voltage & Between Batch Terminal - Ground Terminal, Input - Output & AC1500 V for 1 Minute & \\
\hline Insulation Resistance & Between Batch Terminal - Ground Terminal, Input - Output & \(100 \mathrm{M} \Omega\) or More & DC500 V Insulation Tester \\
\hline Power Consumption & Rated Operational Voltage Applied & 2 VA & Same as SRE-K, KT Types \\
\hline Surge Withstand Voltage & Detection Input, Power Input & \(3500 \mathrm{~V} 1 \times 40 \mu \mathrm{~s}\) & Excluding DC Operated SRE-K, KT Types \\
\hline
\end{tabular}

\section*{Working Environment Criteria}
(1) Ambient Temperature : -10 to \(55^{\circ} \mathrm{C}\) (no condensation, no freezing)
(2) Relative Humidity : 45 to \(85 \%\) RH
(3) Vibration
: 10 to \(55 \mathrm{~Hz} 19.6 \mathrm{~m} / \mathrm{s}^{2}\) or Less
(4) Shock
(5) Altitude

\section*{- Application}
- SRE-AA Type
- DC Motor Speed Detection
- DC Motor Field Detection
- Motor PG Output Detection
- For Power Supply Voltage Output Protection

\section*{Operation}

- For Detection Feedback of Each Signal Output
- SRE-K, SRE-KT Types
- For Emergency Power Supply Switching Detection
- For Household Generated Power Switching Detection
- General Power Supply Voltage Drop Detection
- Battery Voltage Drop Detection

Connection Method


\section*{Outline Drawings}
\begin{tabular}{|c|c|c|c|c|}
\hline Model Name & Appearance & Outline Drawings & Hole Drilling Dimensions & Weight [kg] \\
\hline SRE-AA SRE-K SRE-KT &  &  &  & 0.3 \\
\hline
\end{tabular}

\section*{Related Equipment}

\subsection*{11.9 UA-DL2 Instantaneous Stop/Restart Relays}

Power supply continuity is very important for industrial plants. Short-term voltage drop or power failures can affect plant machinery and even cause the production line to grind to a halt.
UA-DL2 instantaneous stop/restart relays automatically restart load equipment that has stopped momentarily due to voltage drop or temporary outages, when power returns.
- Features
- Simple Mounting/Wiring

Can be connected without the need to modify existing control circuitry. The plug-in structure also simplifies wiring, attachment and removal.
- Compact

The reduced mounting area required allows for more compact panels.

- 100 V and 200 V Shared Operating Voltage
- With Operation Indicator
- Lights up when the power is on, turns off when the power is off
- Switchable Allowable Momentary Failure Time
The allowable momentary failure time can be switched between 1 and 2 seconds for optimal configuration to suit the properties of the load equipment.

\section*{Ratings/Specifications}
\begin{tabular}{|c|c|}
\hline Item & Specifications \\
\hline Control Circuit Allowable Voltage Fluctuation Range & 85 to 110\% of Rated Voltage \\
\hline Operating Temperature/Humidity & -10 to \(55^{\circ} \mathrm{C} / 45\) to \(85 \% \mathrm{RH}\) \\
\hline Withstand Voltage & AC2000 V for 1 Minute \\
\hline Insulation Resistance & \(100 \mathrm{M} \Omega\) or More \\
\hline Vibration-Resistant/Shock-Resistant & Vibration: 10 to \(55 \mathrm{~Hz} 19.6 \mathrm{~m} / \mathrm{s}^{2} /\) Shock: \(98 \mathrm{~m} / \mathrm{s}^{2}\) \\
\hline Operating Time & 1 Second/2 Seconds Switchable \\
\hline Time \({ }^{\text {a }}\) ( \({ }^{\text {S }}\) Setting Error & -20\% to +90\% (With AC100 V/AC200 V Applied) \\
\hline Accuracy \({ }^{\text {a }}\) Voltage Error & \(\pm 35 \%\) \\
\hline Accuracy & \(\pm 25 \%\) \\
\hline Minimum Retention Time & 5 s or More \\
\hline Minimum Off Time & 50 ms \\
\hline Input & 3 VA \\
\hline Electrical Durability & 0.5 mil. times \\
\hline ( \({ }^{\text {Contact Arrangement }}\) & 1a \\
\hline Contact Capacity & AC220 V 1 A, AC110 V 1.5 A (Class AC-15) \\
\hline Applicable Magnetic Contactor Model Names & S-T10 to T100, S-N125 to N400* \\
\hline
\end{tabular}

Note 1. There is a limit to the size of the coil impedance of the magnetic contactor to be combined with. \(*\) Consult with us regarding use in combination with other magnetic contactors.

Connection Diagram (The functionality of the UA-DL2 units is the same for examples 1 and 2; however, the ON and OFF operating switch connections differ.)


\section*{Circuit Operation}
\begin{tabular}{l} 
Operating Switch \\
Operating Switch
\end{tabular}
Power Supply

\section*{Precautions for Use}
(1) The allowable momentary failure time is set to 2 seconds at shipping. To set to 1 second, firmly rotate the switch in the direction of the arrow until it won't rotate any further.
(2) Terminal (2) and (7) connections differ depending on the operating circuit voltage. Connect for use in accordance with the circuit voltage used. (Refer to connection diagram note 1.)
(3) The length of OFF commands sent by external switches (the OFF push button switch in the connection diagram) must be at least 50 ms .
(4) When using a relay contact in place of a push button switch (OFF), use a contact that won't open if power failures occur. If the push button switch (OFF) opens, the UA-DL2 unit will turn OFF and the magnetic contactor will not restart.

(5) Uses an electrolytic capacitor so the operation time should be checked periodically.
- Type Designations
(1) Instantaneous Stop/Restart Relays
\begin{tabular}{|c|c|c|c|}
\hline UA-DL2 & AC100/200V & \multicolumn{2}{|l|}{} \\
\hline & Designation & Rated & Itage \\
\hline & AC100/200V & 100 to 110
200 to 220 & \(50 / 60 \mathrm{~Hz}\) \(50 / 60 \mathrm{~Hz}\) \\
\hline & AC120V & 100 to 110
110 to 120 & \(50 / 60 \mathrm{~Hz}\) \(50 / 60 \mathrm{~Hz}\) \\
\hline & AC240V & \begin{tabular}{l}
200 to 220 \\
220 to 240
\end{tabular} & \(50 / 60 \mathrm{~Hz}\) \(50 / 60 \mathrm{~Hz}\) \\
\hline
\end{tabular}
(2) Socket

PF-08RM Surface Connection Socket (For Panel Mounted Rail Mounting)
PF-08TM Surface Connection Socket (For Panel Mounting)

\section*{Outline Drawings}
\begin{tabular}{|c|c|c|c|}
\hline Model Name & Outline Drawings & Hole Drilling Dimensions & Weight [kg] \\
\hline \begin{tabular}{l}
Instantaneous \\
Stop/Restart \\
Relays \\
UA-DL2
\end{tabular} &  & - & 0.1 \\
\hline Socket PF-08RM &  & Up to 2 2-3.5 Sized Crimp Lugs Compliant with Terminal Up to 21.25 to \(2 \mathrm{~mm}^{2}\) Sized Wires Conforming to Terminal & 0.05 \\
\hline Socket PF-08TM &  & Up to 2-3.5 Sized Crimp Lugs Conforming to Terminal Up to 21.25 to \(2 \mathrm{~mm}^{2}\) Sized Wires Conforming to Terminal & 0.05 \\
\hline
\end{tabular}

\section*{Related Equipment}

\subsection*{11.10 How to Order}

Follow the steps below when ordering. (Enter a space in \(\mathbf{\triangle}\).)
1. US-N Solid State Contactors
\begin{tabular}{|c|}
\hline Model Name \\
US-N20TE \\
\hline Specify from page 304. \\
\hline
\end{tabular}

\section*{2. US-H Solid State Contactors}
\begin{tabular}{|c|}
\hline Model Name \\
US-H20 \\
\hline Specify from page 305, 307 and 311 . \\
\hline
\end{tabular}

\section*{3. Optional Units}

Model Name
UA-CVDR1
Specify from page 335.

\section*{4. Electric Motor Protection Relays}
\begin{tabular}{l} 
ET Type \\
\hline Model Name \\
\hline ET-N60 \\
\hline Specify from page 340. \\
\hline ET Live Part Protectio \\
\hline Model Name \\
\hline UN-CV602 \\
\hline Specify from page 343. \\
\hline
\end{tabular}
5. Voltage Relays
\(\square\) SRE-AA \(\square\) Type
\begin{tabular}{|c|c|c|}
\hline Model Name & & Detection Voltage Designation \\
\hline SRE-AA & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{\[
\begin{array}{r}
\mathbf{\triangle} 015 \mathrm{D} \\
\triangle 150 \mathrm{~A} \\
\hline
\end{array}
\]}} \\
\hline SRE-AAU & & \\
\hline Specify from page 344. & & Select the detection voltage configuration range from page 344. \\
\hline \(\square\) SRE-K \(\square\) Type & & \\
\hline Model Name & & Operation and Detection Voltage Designation \\
\hline SRE-K SRE-KT & \multicolumn{2}{|l|}{\[
\begin{aligned}
& \triangle \mathrm{AC} 100 \mathrm{~V} \\
& \triangle \mathrm{DC} 100 \mathrm{~V}
\end{aligned}
\]} \\
\hline Specify from page 344. & & Select the detection voltage configuration range from page 344. \\
\hline
\end{tabular}

\section*{6. Instantaneous Stop/Restart Relays}


\section*{7. Socket}
\begin{tabular}{|c|}
\hline Model Name \\
\hline PF-08RM \\
\hline Specify from page 347. \\
\hline
\end{tabular}

MEMO
Motor Circuit
Breakers MMP-T32
12.1 Features ..... 352
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* MMP-T32(BC) motor circuit breakers manufactured after April 2021 do not bear the UL mark. Note that information on the UL standard is for products that bear the UL mark only. For details, refer to the "MITSUBISHI ELECTRIC Control Equipment Sales and Service 168".

\author{
Sales and Service 168
}
https://www.mitsubishielectric.com/fa/document/sales/lvsw/168_e/168_e.pdf

\subsection*{12.1 Features}

\section*{A device integrating a circuit breaker and thermal overload relay functions}

One motor circuit breaker can protect motor branch circuits from overloads, open phase, and short circuits. The connecting conductor unit can be used to connect between a motor circuit breaker and a magnetic contactor without wires, and modularize them. This method saves space in the panel and reduces wiring time. Moreover, the motor circuit breaker meets the international standards of major countries and is UL-listed for its high SCCR.

Features

- Compact Design and Superior Interrupting Performance Compact design ( 45 mm wide) with a rated breaking capacity of \(100 \mathrm{kA}(200 / 240 \mathrm{~V}\) ).
An auxiliary contact unit, alarm contact unit, and short-circuit display unit can be integrated without changing the width.
- Contribution to the Downsizing of the Control Board and Panel, and Reduction in Wiring Time The connecting conductor unit (UT-MT \(\square\) ) can be used to connect between a motor circuit breaker and a magnetic contactor without wires, and modularize them. This reduces the space required in the panel and wiring time. Bus bars to connect products in parallel and fast wiring terminals are also available.
<Wiring Example of Connecting Conductor Units>
No wires are required, and products can be modularized.
- High Level of Safety (Reliable Wire Protection) Using motor circuit breakers allows individual protection circuits. Thereby, the number of devices in the circuits can be reduced compared to that in general group protection circuits. Concerns over selecting wires for group protection can be solved, and wires can be protected easily and reliably. For further details, refer to page 363.
- High SCCR to Meet the UL Standards Type E/F combination motor controllers and group installation are UL-listed. Motor circuit breakers help increase the SCCR and reduce the number of devices. Refer to page 364 for details on the SCCR and combination motor controllers, and page 365 for details on group installation.

<Example of Installation to Control Circuitry>
The space required in the panel can be reduced. \(* 40 \%\) reduction compared to our former product


\subsection*{12.2 Specifications}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{3}{|l|}{Frame Size} & \multicolumn{9}{|c|}{32 A} \\
\hline \multicolumn{3}{|l|}{Model Name} & \multicolumn{4}{|c|}{MMP-T32} & \multicolumn{5}{|c|}{MMP-T32BC *1} \\
\hline Standard & & & \multicolumn{9}{|l|}{JIS C8201-2-1 Ann. 1, JIS C8201-4-1, EN60947-2, EN60947-4-1, IEC60947-2, IEC60947-4-1, GB/T14048.2} \\
\hline \multicolumn{3}{|l|}{No. of Poles} & \multicolumn{9}{|c|}{3} \\
\hline \multicolumn{3}{|l|}{Handle Shape} & \multicolumn{9}{|c|}{Tumbler Handle} \\
\hline \multicolumn{3}{|l|}{Rated Current In [A]} & \multicolumn{9}{|c|}{0.1 to 32} \\
\hline \multicolumn{3}{|l|}{Rated Operational Voltage Ue [V]} & \multicolumn{9}{|c|}{100 to 690} \\
\hline \multicolumn{3}{|l|}{Rated Operating Frequency [Hz]} & \multicolumn{9}{|c|}{50/60} \\
\hline \multicolumn{3}{|l|}{Rated Insulation Voltage Ui [V]} & \multicolumn{9}{|c|}{690} \\
\hline \multicolumn{3}{|l|}{Rated Impulse Withstand Voltage Uimp [kV]} & \multicolumn{9}{|c|}{6} \\
\hline \multirow[t]{17}{*}{Rated Short Circuit Breaking Capacity [kA]} & \multicolumn{2}{|l|}{Rated Operating Current le \([\mathrm{A}]^{* 2}\)} & 200/240 V & \multicolumn{2}{|l|}{400/415 V} & \multicolumn{2}{|l|}{440/460 V} & \multicolumn{2}{|c|}{500 V} & \multicolumn{2}{|c|}{600/690 V} \\
\hline & Heater Designation & Current Setting Range & Icu Ics & Icu & Ics & Icu & Ics & Icu & Ics & Icu & Ics \\
\hline & 0.16 & 0.1 to 0.16 & 100 & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} \\
\hline & 0.25 & 0.16 to 0.25 & 100 & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} \\
\hline & 0.4 & 0.25 to 0.4 & 100 & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} \\
\hline & 0.63 & 0.4 to 0.63 & 100 & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} \\
\hline & 1 & 0.63 to 1 & 100 & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} \\
\hline & 1.6 & 1 to 1.6 & 100 & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} \\
\hline & 2.5 & 1.6 to 2.5 & 100 & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & 8 & 6 \\
\hline & 4 & 2.5 to 4 & 100 & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & 8 & 6 \\
\hline & 6.3 & 4 to 6.3 & 100 & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & \multicolumn{2}{|c|}{100} & 6 & 5 \\
\hline & 8 & 5.5 to 8 & 100 & \multicolumn{2}{|c|}{100} & 50 & 38 & 42 & 32 & 6 & 5 \\
\hline & 10 & 7 to 10 & 100 & \multicolumn{2}{|c|}{100} & 50 & 38 & 42 & 32 & 6 & 5 \\
\hline & 13 & 9 to 13 & 100 & \multicolumn{2}{|c|}{100} & 50 & 38 & 42 & 32 & 6 & 5 \\
\hline & 18 & 12 to 18 & 100 & 50 & 38 & 35 & 27 & 10 & 8 & 4 & 3 \\
\hline & 25 & 18 to 25 & 100 & 50 & 38 & 35 & 27 & 10 & 8 & 4 & 3 \\
\hline & 32 & 24 to 32 & 100 & 50 & 38 & 35 & 27 & 10 & 8 & 4 & 3 \\
\hline \multirow[t]{2}{*}{Category of Use} & \multicolumn{2}{|l|}{Selectivity Category} & \multicolumn{9}{|c|}{Cat.A} \\
\hline & \multicolumn{2}{|l|}{Utilization Category} & \multicolumn{9}{|c|}{AC-3} \\
\hline \multicolumn{3}{|l|}{Tripping Class (JIS C8201-4-1, IEC 60947-4-1)} & \multicolumn{9}{|c|}{10} \\
\hline \multicolumn{3}{|l|}{Instant Tripping Characteristics} & \multicolumn{9}{|c|}{13x Max. le} \\
\hline \multirow[t]{2}{*}{Switching Life} & \multicolumn{2}{|l|}{Mechanical [Times]} & \multicolumn{9}{|c|}{0.1 mil.} \\
\hline & \multicolumn{2}{|l|}{Electrical [Times] (AC-3)} & \multicolumn{9}{|c|}{0.1 mil.} \\
\hline \multicolumn{3}{|l|}{Tripping Durability [Times]} & \multicolumn{9}{|c|}{1,000} \\
\hline \multicolumn{3}{|l|}{Open-Phase Protection} & \multicolumn{9}{|c|}{Yes} \\
\hline \multicolumn{3}{|l|}{Tripping Display} & \multicolumn{9}{|c|}{Yes} \\
\hline \multicolumn{3}{|l|}{Test Trip Function} & \multicolumn{9}{|c|}{Yes} \\
\hline \multicolumn{3}{|l|}{Auxiliary Contact Unit} & \multicolumn{9}{|c|}{UT-MAX (1a or 1b)} \\
\hline \multicolumn{3}{|l|}{Alarm Contact Unit} & \multicolumn{9}{|c|}{UT-MAL (1a or 1b)} \\
\hline \multicolumn{3}{|l|}{Short-circuit Display Unit} & \multicolumn{9}{|c|}{UT-TU} \\
\hline \multicolumn{3}{|l|}{Mass [g]} & \multicolumn{9}{|c|}{330} \\
\hline
\end{tabular}
*1: MMP-T32BC is equipped with wiring streamlining terminal \(* 2\) : Rated operating current for UL application is listed on a separate page

\section*{Type Designations \\ MMP-T Series}


\section*{Motor Circuit Breakers MMP-T32}

\subsection*{12.3 Working Environment}
(1) Ambient Temperature : \(-10^{\circ} \mathrm{C}\) to \(40^{\circ} \mathrm{C}\)
(Applied outside control panel) Daily Average Temperature Maximum \(35^{\circ} \mathrm{C}\), Yearly Average Temperature Maximum \(25^{\circ} \mathrm{C}\)
(2) Maximum Temperature Inside Control Panel : \(55^{\circ} \mathrm{C}\) (yearly average temperature inside panel of \(40^{\circ} \mathrm{C}\) or below)

Please note that operation characteristics are affected by the ambient temperature.
(3) Relative Humidity : \(45 \%\) to \(85 \%\) RH (no condensation, no freezing)
(4) Altitude : 2000 m or Below
(5) Vibration : 10 to \(55 \mathrm{~Hz} 19.6 \mathrm{~m} / \mathrm{s}^{2}\) or Less
(6) Shock : \(49 \mathrm{~m} / \mathrm{s}^{2}\) or Less
(7) Atmosphere : Low levels of dust, smoke, corrosive gas, moisture or sodium. When used in a sealed state for a long time, contact failure, etc., can occur.
Do not use the products in an atmosphere containing flammable gas.
(8) Storage Temperature/Relative Humidity: \(-30^{\circ} \mathrm{C}\) to \(65^{\circ} \mathrm{C} / 45 \%\) to \(85 \% \mathrm{RH}\) (no condensation, no freezing) Storage temperature refers to ambient temperature during transportation or storage of product. When starting use of the product, the temperature must be within the working temperature.
(9) Precautions for Use
: Set the position of the adjusting dial in consideration of the panel interior temperature and the mounting conditions.


ISET \(=1 /\) XSET \(\times 100\)
\(\left[\begin{array}{ll}1 & \text { : Motor Rated Current } \\ \text { XSET } & : \text { Determined based on the following Figures } 1 \text { and } 2\end{array}\right]\)
(E.g.) If I = 2.8 A, Panel Interior Temperature \(=40^{\circ} \mathrm{C}\), and close mounted I SET \(=2.8 /(90-5) \times 100 \approx 3.3 \mathrm{~A}\)
\(\rightarrow\) Set the adjusting dial to position 3.3 A .
<Test Tripping>

<Fig. 1. Temperature compensation properties>

<Fig. 2. Mounting condition compensation>

<Handle locking>

(10) Connecting
\begin{tabular}{|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Model Name} & MMP-T32 & UT-MAX(LL), UT-MAL(LL) \\
\hline \multicolumn{2}{|l|}{Terminal Screw Size} & M4 & M3.5 \\
\hline \multicolumn{2}{|l|}{Recommended Length L of Insulation Layer to be Peeled off When Wired with Bare Wire} & 10 mm & 8.5 mm \\
\hline \multirow{3}{*}{Applicable Wire Size} & Single Wire [mm] & \(\varphi\) 1.6, \(\varphi 2.6\) & \(\varphi 1.6\) \\
\hline & Stranded Wire [ \(\mathrm{mm}^{2}\) ] & 1 to 6 & 0.5 to 2 \\
\hline & UL Electrical Wire (60/70 \({ }^{\circ} \mathrm{C}\), Copper Only) (Note 4) & \#14 to \#8 & \#16 to \#14 \\
\hline \multicolumn{2}{|l|}{Crimp Lug Size} & \[
\begin{gathered}
\text { R1.25-4 to R5.5-4 } \\
\text { 8-4NS (Note 3) }
\end{gathered}
\] & 0.5-3.7A to 2-S3A (Note 3) \\
\hline \multicolumn{2}{|l|}{Terminal Screw Tightening Torque [ \(\mathrm{N} \cdot \mathrm{m}\) ]} & 1.4 to 2.0 & 0.9 to 1.1 \\
\hline
\end{tabular}

Note 1. In each terminal, two wires or two crimp lugs may be connected.
Note 2. For details about handling, temperature compensation, close mounting, etc., refer to the Operating Manual. Note 3. J.S.T. Mfg. Co., Ltd. model numbers are shown as typical products.
(11) Installation: Install the motor circuit breaker using an IEC rail. (Applicable IEC rail: 35 mm wide and 15 mm high) Screw mounting not possible.
(Screws can be used for UT-BT20, BT32, and BT32D only.) The installation angle must be within the ranges shown in the figure.
Arc Spacing:
\begin{tabular}{|c|c|c|c|} 
& \multicolumn{1}{c}{\([\mathrm{mm}]\)} \\
\hline\(\leq 690 \mathrm{~V}\) & 27.5 & 75 & 87.5 \\
\hline
\end{tabular}


Permissible Installation Angles


\subsection*{12.4 Operating Characteristic Curve}
(h)


\subsection*{12.5 Selection and application}
* Information on the UL standard is for products that bear the UL mark only.
(Refer to page 362.)

\section*{- How to Select a Motor Circuit Breaker}

The following outlines the steps of selecting a motor circuit breaker.
(1) Check the load current of the motor.
(2) Select the rated current of the motor circuit breaker. Refer to "Specifications" on page 353. *To use it with an inverter, refer to the following section.
(3) Check the specifications of the control panel (wires and their applicable size for the branch circuit).
(4) Check the breaking capacity of the circuit. Refer to "Specifications" on page 353.

To meet standards such as Type 1 and Type E/F, check the rating table.
(5) Check the operation characteristics. Refer to "Operating Characteristic Curve" on page 355.

\section*{- Use with a Single-phase Motor}

To use it with a single-phase motor, use all the poles and wire them in series.
(Figure to the right)
The motor circuit breaker has an open-phase protection function.
Connecting only two poles may unnecessarily activate the function.

\section*{Use with an Inverter}

Inverters can detect overcurrent and undervoltage. Therefore, use motor circuit breakers for short-circuit protection as the overcurrent detection function of the thermal overload relay is


Single-phase Motor Wiring not required. Select a motor circuit breaker according to the following conditions.
(1) To prevent the motor circuit breaker from being activated by the load current including high frequency components, select a slightly larger heater value than the rated current of the inverter. (Reference value: Load current \(\times\) 1.4)
(2) For wire protection, the operating characteristic of the motor circuit breaker must be equal to or lower than the thermal properties of the wire.
*The above formula is for reference purposes only. The motor circuit breaker may be activated by the capacitor charging current at power-on of the inverter or other factors. Therefore, check the actual operation as well.
*The combination motor controller Type E is UL-listed for the SCCR when used with an inverter (manufactured by Mitsubishi Electric). (For the ratings, refer to page 369.)

\section*{- Use with an IE3 Motor}

The motor circuit breaker (MMP-T32) can be used with an IE3 motor (superline premium series compatible with IE3 premium efficiency). The starting current of the IE3 motor is higher than that of the former motor.
*Refer to the following table for combinations of MMP-T32 and SF-PR high-efficiency motors (our motors that conform to the Top Runner Standard).
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multicolumn{3}{|l|}{SF-PR High-efficiency Motor} & \multicolumn{3}{|r|}{Motor Circuit Breakers} \\
\hline Main Circuit Voltage & No. of Poles [P] & Output [kW] & \begin{tabular}{l}
Model \\
Name
\end{tabular} & Heater Designation & Current Setting Range \\
\hline \multirow{18}{*}{\[
\begin{gathered}
\text { Three-Phase } \\
200 \mathrm{~V} 50 \mathrm{~Hz} \\
200-230 \mathrm{~V} 60 \mathrm{~Hz}
\end{gathered}
\]} & \multirow{6}{*}{2-pole} & 0.75 & \multirow{18}{*}{MMP-T32} & 4A & 2.5 to 4A \\
\hline & & 1.5 & & 6.3A & 4 to 6.3A \\
\hline & & 2.2 & & 10A & 7 to 10A \\
\hline & & 3.7 & & 18A & 12 to 18A \\
\hline & & 5.5 & & 25A & 18 to 25A \\
\hline & & 7.5 & & 32A & 24 to 32A \\
\hline & \multirow{6}{*}{4-pole} & 0.75 & & 4A & 2.5 to 4A \\
\hline & & 1.5 & & 8A & 5.5 to 8A \\
\hline & & 2.2 & & 10A & 7 to 10A \\
\hline & & 3.7 & & 18A & 12 to 18A \\
\hline & & 5.5 & & 25A & 18 to 25A \\
\hline & & 7.5 & & 32A & 24 to 32A \\
\hline & \multirow{6}{*}{6-pole} & 0.75 & & 4A & 2.5 to 4A \\
\hline & & 1.5 & & 8A & 5.5 to 8A \\
\hline & & 2.2 & & 10A & 7 to 10A \\
\hline & & 3.7 & & 18A & 12 to 18A \\
\hline & & 5.5 & & 25A & 18 to 25A \\
\hline & & 7.5 & & 32A & 24 to 32A \\
\hline
\end{tabular}

Note 1. The table shows reference heater designations for when MMP-T32 is used with SF-PR high-efficiency motors manufactured by Mitsubishi Electric. Depending on the condition of voltage, frequency, ambient temperature, and installation, the actual value may go beyond the current settling range of the heater designation. Check the rated motor current or other values before selecting a heater designation.
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multicolumn{3}{|l|}{SF-PR High-efficiency Motor} & \multicolumn{3}{|r|}{Motor Circuit Breakers} \\
\hline Main Circuit Voltage & \begin{tabular}{l}
No. of Poles \\
[P]
\end{tabular} & Output [kW] & \begin{tabular}{l}
Model \\
Name
\end{tabular} & Heater Designation & Current Setting Range \\
\hline \multirow{24}{*}{Three-Phase \(380-415 \mathrm{~V} 50 \mathrm{~Hz}\)} & \multirow{8}{*}{2-pole} & 0.75 & \multirow{24}{*}{MMP-T32} & 2.5A & 1.6 to 2.5A \\
\hline & & 1.5 & & 4A & 2.5 to 4A \\
\hline & & 2.2 & & 6.3A & 4 to 6.3A \\
\hline & & 3.7 & & 8A & 5.5 to 8A \\
\hline & & 5.5 & & 13A & 9 to 13A \\
\hline & & 7.5 & & 18A & 12 to 18A \\
\hline & & 11 & & 25A & 18 to 25A \\
\hline & & 15 & & 32A & 24 to 32A \\
\hline & \multirow{8}{*}{4-pole} & 0.75 & & 2.5A & 1.6 to 2.5A \\
\hline & & 1.5 & & 4A & 2.5 to 4A \\
\hline & & 2.2 & & 6.3A & 4 to 6.3A \\
\hline & & 3.7 & & 10A & 7 to 10A \\
\hline & & 5.5 & & 13A & 9 to 13A \\
\hline & & 7.5 & & 18A & 12 to 18A \\
\hline & & 11 & & 25A & 18 to 25A \\
\hline & & 15 & & 32A & 24 to 32A \\
\hline & \multirow{8}{*}{6-pole} & 0.75 & & 2.5A & 1.6 to 2.5A \\
\hline & & 1.5 & & 4A & 2.5 to 4A \\
\hline & & 2.2 & & 6.3A & 4 to 6.3A \\
\hline & & 3.7 & & 10A & 7 to 10A \\
\hline & & 5.5 & & 13A & 9 to 13A \\
\hline & & 7.5 & & 18A & 12 to 18A \\
\hline & & 11 & & 25A & 18 to 25A \\
\hline & & 15 & & 32A & 24 to 32A \\
\hline
\end{tabular}

\subsection*{12.6 Optional Units}

\section*{- Optional Units (for the Motor Circuit Breaker)}
\begin{tabular}{|c|c|c|c|c|c|}
\hline Number & Product Name & Model Name & Specifications & Description & Applicable Models \\
\hline \multirow{3}{*}{(1)} & \multirow{3}{*}{Auxiliary Contact (Interior)} & UT-MAX & 1 a & \multirow{3}{*}{The contacts of this unit operate in unison with the turning ON/OFF of the main unit.} & \multirow{14}{*}{MMP-T32} \\
\hline & & \multirow[t]{2}{*}{UT-MAXLL (For Very Small Loads)} & 1a & & \\
\hline & & & 1 b & & \\
\hline \multirow{3}{*}{(2)} & \multirow{3}{*}{Alarm Contact (Interior)} & \multirow[t]{2}{*}{UT-MAL} & 1 a & \multirow{3}{*}{The contacts of this unit operate (either short-circuits, overloads, openphase) in unison with the trip operation of the main unit.} & \\
\hline & & & 1b & & \\
\hline & & (For Very Small Loads) & 1 b & & \\
\hline (3) & Power Supply Block & UT-EP3 & & This is a terminal block unit that can enable the wiring of bare wires (single core wire/ stranded wire) on the power supply side if the unit is connected in parallel with a bus bar. & \\
\hline \multirow{5}{*}{(4)} & \multirow{5}{*}{Bus Bar} & UT-2B4 & 45mm Clearance & \multirow{5}{*}{A unit that can supply power (parallel connection) to 2 or 3 units individually without use of electric wire.} & \\
\hline & & UT-3B4 & \[
45 \mathrm{~mm} \text { Clearance }
\] & & \\
\hline & & UT-2B5 & 57 mm Clearance & & \\
\hline & & UT-2B5 & Row of 2 & & \\
\hline & & UT-3B5 & \[
\begin{array}{|c|}
\hline 57 \mathrm{~mm} \text { Clearance } \\
\hline \text { Row of } 3 \\
\hline
\end{array}
\] & & \\
\hline (5) & Power Side Terminal Cover & UT-CV3 & & Power side terminal cover for UL60947-4-1A, Type E/F. When attaching the cover to MMP-T32BC, remove the screw holder of the power supply terminals. Fast wiring terminals cannot be used. & \\
\hline (6) & Short-circuit Display Unit & UT-TU & & A unit that operates and displays in red only when the unit trips due to a short circuit. Necessary for application to UL60947-4-1A, Type E/F. & \\
\hline
\end{tabular}

Note 1. For the models that can be used with the optional units, refer to "Outline Drawings" on pages 371 to 373.
Note 2. The power supply block and the bus bar (4) cannot be used with the power side terminal cover (5).
Note 3. For options for combination starters, refer to page 359.

\section*{Configuration Diagram of Options}




\section*{Optional Unit Specifications}

\section*{- Operating Optional Units}
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Unit Types} & \multirow[b]{2}{*}{Model Name} & \multirow[b]{2}{*}{Contact Arrangement} & \multicolumn{4}{|c|}{Operation of MMP-T32} \\
\hline & & & ON & Short Circuit Tripping & OverladiOpen.PRase Triping (Test Tripoing) & OFF \\
\hline \multirow[t]{2}{*}{Auxiliary Contact Unit} & \multirow[t]{2}{*}{UT-MAX(LL)} & 1 a & ON & OFF & OFF & OFF \\
\hline & & 1 b & OFF & ON & ON & ON \\
\hline \multirow[t]{2}{*}{Alarm Contact Unit} & \multirow[t]{2}{*}{UT-MAL(LL)} & 1 a & OFF & ON & ON & OFF \\
\hline & & 1 b & ON & OFF & OFF & ON \\
\hline Short-circuit Display Unit & UT-TU & - & No Display & Red Display & No Display & No Display \\
\hline
\end{tabular}
- Specifications of Auxiliary Contact Unit and Alarm Contact Unit
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Model Name} & \multirow{3}{*}{Contact Arrangement} & \multicolumn{2}{|c|}{\multirow[b]{2}{*}{Durability}} & \multirow{3}{*}{Minimum Applicable Load} & \multicolumn{6}{|c|}{Rated Operating Current [A]} \\
\hline & & & & & \multicolumn{2}{|l|}{\begin{tabular}{l}
AC-12 \\
(Resistive Load)
\end{tabular}} & \multicolumn{4}{|c|}{DC-12
(Resistive Load)} \\
\hline & & Mechanical & Electrical & & 125V & 250 V & 30 V & 48 V & 125 V & 250 V \\
\hline UT-MAX & 1a, 1b & \multirow{4}{*}{0.1 mil. times} & \multirow{4}{*}{10,000 times} & \(5 \mathrm{~V} / 160 \mathrm{~mA}\) & 5 & 3 & - & - & 0.4 & 0.2 \\
\hline UT-MAL & 1a, 1b & & & \(24 \mathrm{~V} / 40 \mathrm{~mA}\) & 5 & 3 & - & - & 0.4 & 0.2 \\
\hline UT-MAXLL & 1a, 1b & & & \(5 \mathrm{~V} / 1 \mathrm{~mA}\) & 0.1 & - & 0.1 & 0.03 & - & - \\
\hline UT-MALLL & 1a, 1b & & & \(24 \mathrm{~V} / 0.25 \mathrm{~mA}\) & & - & & & - & - \\
\hline
\end{tabular}
- Specifications of Power Supply Block and Bus Bar
\begin{tabular}{l|c|c|l}
\multicolumn{1}{c|}{ Model Name } & \begin{tabular}{c} 
Conventional Free Air \\
Thermal Current Ith \([A]\)
\end{tabular} & \begin{tabular}{c} 
Rated Conditional Short-Circuit \\
Current Iq \([\mathrm{KA}]\)
\end{tabular} & \multicolumn{1}{|c}{ Applicable Electrical Wire }
\end{tabular}

\section*{Option Unit Specifications}
- How to Install UT-MAX or MAL
(1) Set the handle to the OFF position.

Installing the product in the trip state will cause damage.
(2) Remove the covers from the housing.

Remove three covers on one side.
(3) The removed covers are not required.

Dispose of them.
(4) Insert the product into place.

Insert it as far as it will go.

- How to Install UT-TU
(1) Set the handle to the OFF position.
(2) Open the cover in the direction of the arrow.
(3) Insert the product into place.
(4) Close the cover.

Close it until it clicks.

- Parallel Connection Using Bus Bar Unit
- When connecting four or more MMP-T32 Motor Circuit Breakers in parallel, connect them alternately reversing multiple UT- \(\square \mathrm{B} \square\) Bus Bar Units.
- Meet the following requirement in limiting the number of units when connecting in parallel.
[Rated Current of Bus Bar Unit (63 A)] > [Sum Value of Settling Current (Parallel Connection)]
- Application Example: For Connecting 4 Units in Parallel (Close Mounting)

Bus Bar Units to be Used

- Connection Example \(*\) Determine the arrangement of the bus bar unit according to the feed position.


\subsection*{12.7 Combination Starter}
* Information on the UL standard is for products that bear the UL mark only.
(Refer to page 362.)
To make a combination starter, use a motor circuit breaker and a contactor in combination.
The combination starter satisfies the requirements for Type 1 coordination (protection of magnetic starters and short- circuit protection devices defined in IEC 60947 and JIS C8201).
Using an optional unit can modularize the combination starter. If an electrical accident occurs, the combination starter decreases the possibility of spreading the effect to neighboring areas. Moreover, the combination starter contributes to space saving and less wiring.
\begin{tabular}{|c|c|c|c|c|c|}
\hline Number & Product Name & Model Name & Specifications & Description & Applicable Models \\
\hline \multirow{5}{*}{(1)} & \multirow{5}{*}{Connecting Conductor Unit} & UT-MT20 & & \multirow{5}{*}{Unit for electrically and mechanically connecting MMP-T32 and a magnetic contactor.} & \multirow{13}{*}{MMP-T32} \\
\hline & & UT-MT32 & & & \\
\hline & & UT-MQ12 & & & \\
\hline & & UT-MT20D & & & \\
\hline & & UT-MT32D & & & \\
\hline \multirow{3}{*}{(2)} & \multirow{3}{*}{Mounting Base Unit} & UT-BT20 & & \multirow{3}{*}{Plate for mounting a combination starter by combining MMP-T32 and a magnetic contactor. Can be rail mounted or screw mounted.} & \\
\hline & & UT-BT32 & & & \\
\hline & & UT-BT32D & & & \\
\hline (3) & Mounting Base Unit & UT-BT32DMP & & This is a plate to combine MMP-T32 and a DC operated magnetic contactor and install them. Single rail mounting is possible. & \\
\hline \multirow{3}{*}{(4)} & \multirow{3}{*}{Jointing Block Unit} & UT-RT10 & & \multirow{3}{*}{A block that connects the 2 mounting base units mechanically.} & \\
\hline & & UT-RT20 & & & \\
\hline & & UT-RT32 & & & \\
\hline (5) & Jointing Block Unit & UT-RT32DMP & & This is a unit to combine UT-BT32DMP and a reversible magnetic contactor. It is required to use UT-BT32DMP in combination with MMP-T32 and a reversible DC operated magnetic contactor. & \\
\hline
\end{tabular}

Note 1. Motor circuit breaker options can also be installed. (Page 357)

\section*{Configuration Diagram of Options}


\section*{Motor Circuit Breakers MMP-T32}

Combinations of Devices to Make Combination Starters
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline Motor Circuit Breaker (Type E Optional Unit) & \multicolumn{2}{|l|}{Magnetic Contactors} & Connecting Conductor Unit & Mounting Base Unit & Mounting Method & Jointing Block Unit \\
\hline \multirow{19}{*}{\[
\begin{aligned}
& \text { MMP-T32 } \\
& \text { (UT-CV3, UT-TU) }
\end{aligned}
\]} & S-T10 & \multirow{6}{*}{NonReversing} & UT-MT20 & \multirow[t]{3}{*}{Configurable without the base unit if screw mounting is not required} & IEC Rail (1 pc) & - \\
\hline & S-T12/T20 & & UT-MT20 & & IEC Rail (1 pc) & - \\
\hline & S-T32 & & UT-MT32 & & IEC Rail (1 pc) & - \\
\hline & S-T10 & & UT-MT20 & UT-BT20 & Screw Mounting or IEC Rail (2 pcs) & - \\
\hline & S-T12/T20 & & UT-MT20 & UT-BT20 & Screw Mounting or IEC Rail (2 pcs) & - \\
\hline & S-T32 & & UT-MT32 & UT-BT32 & Screw Mounting or IEC Rail (2 pcs) & - \\
\hline & S-2xT10 & \multirow{3}{*}{Reversing} & UT-MT20 & UT-BT20 (2 Units) & Screw Mounting or IEC Rail (2 pcs) & UT-RT10 \\
\hline & S-2xT12/T20 & & UT-MT20 & UT-BT20 (2 Units) & Screw Mounting or IEC Rail (2 pcs) & UT-RT20 \\
\hline & S-2xT32 & & UT-MT32 & UT-BT20 (2 Units) & Screw Mounting or IEC Rail (2 pcs) & UT-RT32 \\
\hline & SD-Q11/Q12 & Non-Reversing & UT-MQ12 & \multirow[t]{2}{*}{Not Required (Screw Mounting Not Possible)} & IEC Rail (1 pc) & - \\
\hline & SD-QR11/QR12 & Reversing & UT-MQ12 & & IEC Rail (1 pc) & Not Required \\
\hline & \multirow[b]{2}{*}{SD-T12/T20} & \multirow{4}{*}{NonReversing} & \multirow{2}{*}{UT-MT20D} & UT-BT32D & Screw Mounting or IEC Rail (2 pcs) & - \\
\hline & & & & UT-BT32DMP & IEC Rail (1 pc) & - \\
\hline & \multirow{2}{*}{SD-T32} & & \multirow[t]{2}{*}{UT-MT32D} & UT-BT32D & Screw Mounting or IEC Rail (2 pcs) & - \\
\hline & & & & UT-BT32DMP & IEC Rail (1 pc) & - \\
\hline & \multirow[t]{2}{*}{SD-2xT12/T20} & \multirow{4}{*}{Reversing} & UT-MT2 & UT-BT32D (2 Units) & Screw Mounting or IEC Rail (2 pcs) & UT-RT20 \\
\hline & & & UT M 20 D & UT-BT32DMP (2 Units) & IEC Rail (1 pc) & UT-RT32DMP \\
\hline & \multirow[t]{2}{*}{SD-2xT32} & & \multirow[t]{2}{*}{UT-MT32D} & UT-BT32D (2 Units) & Screw Mounting or IEC Rail (2 pcs) & UT-RT32 \\
\hline & & & & UT-BT32DMP (2 Units) & IEC Rail (1 pc) & UT-RT32DMP \\
\hline
\end{tabular}

Note 1. For Type E/F certification, use UT-CV3 and UT-TU in combination. (Page 367 for the ratings)
Note 2. If only one IEC rail is used for the installation (no mounting base unit is used), the operating conditions of the contactor are as follows: Opening and closing: 600 times/hour, mechanical durability: \(5,000,000\) times ( \(10,000,000\) times when a mounting base unit is used)

\section*{- Where and How to Install Optional Units}
- Connecting Conductor Units (UT-MT20 and MT32)
- Loosen the terminals for installing the connecting conductor unit.

- Mounting Base Units (UT-BT20, BT32, and BT32D)
- Install the connecting conductor unit using the following steps.


Note 1. For how to install UT-MT20D or 32D, refer to the instructions for the product.

- Mounting Base Units (UT-BT32DMP)


Note 1. The connecting conductor unit is required to install the mounting base unit.
Note 2. For combination with a reversible magnetic contactor, use two mounting base units (UT-BT**) and connect them using a jointing block unit (UT-RT**).

\section*{Type 1 Coordination (Non-Reversing/Reversing, Direct Start)}

Satisfies the requirements for protection coordination Type 1 (Type 1 Coordination) of combination starters specified in IEC 60947-4-1 and JIS C 8201-4-1.
- Combining Motor Circuit Breakers and Magnetic Contactors (Type 1 Coordination)
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multicolumn{3}{|c|}{Motor Circuit Breakers} & \multirow[b]{2}{*}{Magnetic Contactors} & \multicolumn{4}{|c|}{Rated Conditional Short-Circuit Current Iq [kA]} \\
\hline Model Name & Heater Designation & Rated Current Setting Range [A] & & 200/240 V & 400/415 V & 440/460 V & 500 V \\
\hline \multirow{15}{*}{MMP-T32} & 0.16 & 0.1 to 0.16 & \multirow{15}{*}{Refer to the Combination List (Table Below)} & 50 & 50 & 50 & 50 \\
\hline & 0.25 & 0.16 to 0.25 & & 50 & 50 & 50 & 50 \\
\hline & 0.4 & 0.25 to 0.4 & & 50 & 50 & 50 & 50 \\
\hline & 0.63 & 0.4 to 0.63 & & 50 & 50 & 50 & 50 \\
\hline & 1 & 0.63 to 1 & & 50 & 50 & 50 & 50 \\
\hline & 1.6 & 0.1 to 1.6 & & 50 & 50 & 50 & 50 \\
\hline & 2.5 & 1.6 to 2.5 & & 50 & 50 & 50 & 50 \\
\hline & 4 & 2.5 to 4 & & 50 & 50 & 50 & 50 \\
\hline & 6.3 & 4 to 6.3 & & 50 & 50 & 50 & 50 \\
\hline & 8 & 5.5 to 8 & & 50 & 50 & 50 & 42 \\
\hline & 10 & 7 to 10 & & 50 & 50 & 50 & 42 \\
\hline & 13 & 9 to 13 & & 50 & 50 & 50 & 42 \\
\hline & 18 & 12 to 18 & & 50 & 50 & 35 & 10 \\
\hline & 25 & 18 to 25 & & 50 & 50 & 35 & 10 \\
\hline & 32 & 24 to 32 & & 50 & 50 & 35 & 10 \\
\hline
\end{tabular}

The following table shows the magnetic contactors that can be combined with each rating of the motor circuit breaker.


Note 1. When combining \(S(D)-T 21\) and \(S-T 25\), only wiring with electric wires is possible. (Connecting conductor units cannot be used)
Note 2. The above table is based on the class AC-3 maximum rated operating current of each magnetic contactor. Select with attention to the actual operating conditions.
Note 3. When selecting a unit to use it with a motor circuit breaker and a magnetic contactor, use the following combinations or refer to page 360 .
S-T10(BC) to T20(BC): UT-MT20
S-T32(BC): UT-MT32
SD-T12(BC)/T20(BC): UT-MT20D+UT-BT32D or UT-MT20D+UT-BT32DMP
SD-T32(BC): UT-MT32D+UT-BT32D or UT-MT32D+UT-BT32DMP
S-2xT10(BC): UT-MT20+UT-RT10+UT-BT20 (2 Units)
S-2xT12(BC)/T20(BC): UT-MT20+UT-RT20+UT-BT20 (2 Units)
S-2xT32(BC): UT-MT32+UT-RT32+UT-BT32 (2 Units)
SD-2×T12(BC)/T20(BC): UT-MT20D+UT-RT20+UT-BT32D (2 Units) or UT-MT20D+UT-RT32DMP+UT-BT32DMP (2 Units) SD-2×T32(BC): UT-MT32D+UT-RT32+UT-BT32D (2 Units) or UT-MT32D+UT-RT32DMP+UT-BT32DMP (2 Units)
S-T21(BC)/T25(BC)/SD-T21(BC)/S-2xT21(BC)/SD-2xT21(BC)/T25(BC): Electric Wire Connection
SD-Q11/Q12/QR11/QR12: UT-MQ12

\subsection*{12.8 Applicable Standard}

Regulatory/Legal Conformity and Compliance
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline & ndards/R & gulat & \begin{tabular}{l}
Model Name \\
ns
\end{tabular} & MMP-T32 & UT-MAX UT-MAL & UT-TU & UT-CV3 & \begin{tabular}{l}
UT-MT20 \\
UT-MT32 \\
UT-MT20D \\
UT-MT32D \\
UT-MQ12
\end{tabular} & UT-BT20 UT-BT32 & \[
\begin{gathered}
\text { UT-BT32D } \\
\text { UT-BT32DMP }
\end{gathered}
\] & UT-2B4/3B4 UT-2B5/3B5 & UT-EP3 \\
\hline \multirow{10}{*}{} & \multicolumn{2}{|l|}{\multirow{3}{*}{International}} & IEC60947-2 & \(\bigcirc\) & * & * & * & * & * & * & \(\bigcirc\) & \(\bigcirc\) \\
\hline & & & IEC60947-4-1 & \(\bigcirc\) & * & * & * & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) \\
\hline & & & IEC60947-5-1 & * & \(\bigcirc\) & * & * & * & * & * & * & * \\
\hline & \multirow{5}{*}{Europe} & & EN60947-2 & \(\bigcirc\) & * & * & * & * & * & * & * & * \\
\hline & &  & EN60947-4-1 & \(\bigcirc\) & * & * & * & * & * & * & * & * \\
\hline & & & EN60947-5-1 & * & \(\bigcirc\) & * & * & * & * & * & * & * \\
\hline & & \begin{tabular}{l}
TÜV \\
Cexificion Number
\end{tabular} & EN60947-2 & \[
\left|\begin{array}{l}
\text { R50269663 } \\
\text { R50269678 } \\
\text { R50269688 } \\
\text { R50269690 }
\end{array}\right|
\] & * & * & * & * & * & * & * & * \\
\hline & & \multicolumn{2}{|l|}{RoHS Directive} & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) \\
\hline & China &  & \begin{tabular}{|l|}
\hline\(G B / T 14048.2\) \\
\hline\(G B / T 14048.2\) \\
\hline
\end{tabular} & \[
\begin{array}{|c|}
\hline(2012010307533513) \\
\hline *
\end{array}
\] & \(*\)
\(\underset{(2012010304563726)}{\bigcirc}\) & \multicolumn{7}{|c|}{*} \\
\hline & \begin{tabular}{l}
North \\
America \\
Canada
\end{tabular} & \begin{tabular}{l}
UL/CSA \\
c (UL) us \\
(File Number)
\end{tabular} & \begin{tabular}{|l|}
\hline UL60947-4-1 \\
\hline CSA C22.2 \\
No.60947-4-1 \\
\hline
\end{tabular} & Refer to Note 1. Single Unit: E3661855 Combination: E319448| & \[
\begin{gathered}
\text { O } \\
\text { (E361855) }
\end{gathered}
\] & (E319418) & \[
\begin{gathered}
O \\
\text { (E319418) }
\end{gathered}
\] & (E319418) & \[
\begin{gathered}
O \\
\text { (E319418) }
\end{gathered}
\] & \[
\begin{gathered}
O \\
(E 319418)
\end{gathered}
\] & - & - \\
\hline \multirow{4}{*}{\[
\begin{aligned}
& \text { O} \\
& \text { W } \\
& 0 \\
& E \\
& 0
\end{aligned}
\]} & \multicolumn{2}{|r|}{\multirow{3}{*}{Japan}} & \[
\begin{aligned}
& \text { JIS C8201-2-1 } \\
& \text { Ann. } 1
\end{aligned}
\] & \(\bigcirc\) & * & * & * & * & * & * & \(\bigcirc\) & \(\bigcirc\) \\
\hline & & & JIS C8201-4-1 & \(\bigcirc\) & * & * & * & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) \\
\hline & & & JIS C8201-5-1 & * & * & * & * & * & * & * & * & * \\
\hline & Electrical A Materials & pliances and Safety Act & Non-Specified Electric Appliances & \(\bigcirc\) & \multicolumn{8}{|c|}{*} \\
\hline
\end{tabular}

O: Compliant (or Certified in the Case of Third-Party Authentication), -: Models not yet certified (non-pending); *: Standard certification non-applicable model

Note 1. MMP-T32(BC) motor circuit breakers manufactured after April 2021 do not bear the UL mark. Note that information on the UL standard is for products that bear the UL certification mark only.
Using a motor circuit breaker that does not bear the UL certification mark will void the UL certification of the Type E/F combination motor controller and group installation.
For details, refer to the "MITSUBISHI ELECTRIC Control Equipment Sales and Service 168".
Sales and Service 168
https://www.mitsubishielectric.com/fa/document/sales/lvsw/168_e/168_e.pdf


\section*{Reliable Wire Protection (EN/JIS Standards)}

Motor circuit breakers allow you to solve concerns over selecting wires for group protection.

\section*{- General Group Protection (Only with a Master Breaker)}

Standards of major countries such as IEC/EN 60204 and JIS B9960-1 require that the control panel properly protect wires and load equipment from short circuits.
In some cases, it is difficult to select the size of wires for general group protection to protect them properly. Individual protection using motor circuit breakers will solve such concerns.


Select a master breaker rated to protect wires and load equipment on the secondary side.
All the wires must be thick ( \(*\) ) enough to be protected by the master breaker.
* Branch breaker rating \(\times 1.25\) < permissible current of wires

The wire used in the branch circuit must meet the following conditions.
1. The size matches the load current (the cost and current-carrying capacity both taken into account).
2. The wire matches the terminal size of the load equipment.
3. The wire can be protected from burn damage due to short circuits and overloads.

\section*{Concerns}

If thin wires are used, condition 3 may not be met. If thick wires are used, conditions 1 and 2 may not be met, increasing the cost and decreasing workability.

As a result, it may be difficult to select wires with safety and cost both taken into account.
*In many cases in Japan, the wire of branch circuits in the control panel is too thin to be protected by the master breaker. The manufacturer must produce "safe" control panels to meet standards.

Individual protection using motor circuit breakers will solve such concerns.

\section*{- Individual Protection Using Motor Circuit Breakers}


The motor circuit breaker has a short-circuit protection function, which protects branch circuits independently.
* Since the motor circuit breaker has both functions of a breaker and a thermal overload relay, branch circuits can be protected independently without additional devices.
- Reasons that Individual Protection Makes Wire Selection Easier
(1) Wiring on the secondary side of motor circuit breakers

Since branch circuits can be protected independently, the wire size can be selected according to the load current of motors.
(2) Wiring of branch circuits

A special exemption is available for individual protection (EN 60204 Clause 7.2.8). If the following conditions are met, the wire size used on the secondary side of the motor circuit breaker in range (1) can be used for the branch circuit in range (2).
1. The conductor current capacity exceeds the load capacity.
2. The length of each connection conductor for the overcurrent protection device is within 3 m .
3. The conductor is protected by an enclosure or duct.

For individual protection, if an electrical accident occurs on the load side, the possibility of spreading the effect to neighboring areas can be decreased.

\section*{Motor Circuit Breakers MMP-T32}

\subsection*{12.9 UL Standards and SCCR}
* Information on the UL standard is for products that bear the UL mark only.
(Refer to page 362.)
The motor circuit breaker is UL-listed. Moreover, with the motor circuit breaker, Type E/F combination motor controllers, high SCCR (short circuit current rating), and group installation are available.

\section*{What is SCCR (Short-Circuit Current Rating)?}

Article 409 of NFPA 70 (National Electric Code: NEC), which is the electrical equipment standard of the United States, requires the SCCR value to be displayed on industrial control panels. SCCR is defined as the value of the short-circuit current that various devices connected to the main circuit can withstand; it is stipulated that the SCCR value of the control panel must be greater than the estimated short circuit current at the location where the control panel is installed. The SCCR value for industrial control panels is determined based on supplement SB of UL 508A.

- Determination of SCCR for Control Panel Basically, the smallest SCCR value among the power circuit components is regarded as SCCR for the control panel.
In the case of the circuit in the figure at left, the SCCR value for the control panel is 5 kA .
- Determination of SCCR Value for Power Circuit Components The determination method of SCCR for the power circuit components is in accordance with one of the following.
(1) The SCCR value displayed on device rating plates, in instruction manuals, etc.
(2) The estimated SCCR value described in table UL508A, SB4.1.
(3) The value described in the manufacturer's UL procedure and evaluated using a specific combination.
- To increase the SCCR value of the control panel When adopting the values from (1) or (2) above, the SCCR value of the magnetic contactors/thermal overload relays is 5 kA and the SCCR of the control panel is limited. However, by applying the SCCR value of (3), it is possible to further increase the SCCR value of the control panel.
- Examples for Combinations of Specific Devices

The following types of specific combinations can achieve a high SCCR.
(1) Combination Motor Controller Type C

Combination of UL489 Breaker and UL60947-4-1 Contactor or Thermal Overload Relay
(2) Combination Motor Controller Type E

Combination of UL 60947-4-1 Motor Circuit Breaker and Specific Optional Items
* Specific Optional Items: Power Side Terminal Cover (UT-CV3) and ShortCircuit Display Unit (UT-TU)
(3) Combination Motor Controller Type F

Combination with Combination Motor Controller Type E and UL60947-4-1 Contactor
\(\Rightarrow\) MMP-T32 has a high SCCR UL certification with Type E/F
Refer to page 367 for Type E/F combination table and SCCR values.

- Advantages Seen in Type E/F Circuit Example

By using Type E/F it is possible to display a high SCCR value.
The circuit diagram at left shows an example using Type F, with SCCR value of 50 kA .
Also, by adopting Type E/F combination motor controllers, it is possible to reduce the number of components (breakers). In addition, connecting with connecting conductor units can save space and wiring.
- Increasing the SCCR value by other methods (reference) The SCCR values can also be increased by using the following methods.
* Check UL508A SB for details.
1. Correction for Transformer Capacity and Secondary Side SCCR
2. Correction with Current Limiting Circuit Breaker and Current Limiting Fuse

\section*{Group Installation}

A group installation is a short-circuit protection method that protects multiple motor branch circuits with one short-circuit protection device, such as a circuit breaker or fuse, for group protection (UL standards). To design group protection that meets the UL standards, consider adopting this short-circuit protection method. MMP-T32 is UL-listed for high SCCR in group installation when used with circuit breakers
- Group Protection (UL Standards)

For general protection circuits, a BCP is installed to each branch circuit.
Since many BCPs are used for such circuits, group protection is adopted in some cases. To meet the UL standards, consider the following conditions.

Selecting A (BCP):
Consider the following conditions.
- Capacity enough to protect wire B
- Conditions in which devices D and E meet the UL standards
(Availability of group protection and required SCCR)

Select wires that connect the BCP according to the following conditions.
Selecting B (branch circuit conductor):
- Select one considering the load current \((*)\) of the branch circuit.
*Maximum rated motor current value \(\times 1.25+\) total current value of the other motors
Selecting C (tap conductor):
Select one that meets any of the following conditions.
- Same capacity as B
- Capacity of more than \(1 / 3\) of B (up to 7.5 m , protection against damage to the wire required)

If the conditions mentioned above are met, the wire may be thick depending on condition C , and thereby the equipment size may become large.
- Group Protection Using Motor Circuit Breakers (UL Standards)

Group protection using motor circuit breakers has the following advantages.
<Advantage 1: The number of BCPs can be reduced.>
MMP-T32 is UL-listed when used with high rated breakers (BCPs). Therefore, many branch circuits can be placed in the downstream of one BCP.
<Advantage 2: High SCCR>
The motor circuit breaker is UL-listed for its high SCCR in group installation. The SCCR of the control panel can be increased.
* For details on the UL-listed ratings for group installation, refer to page 370.
- Differences from Individual Protection Using Type E/F

When a Type E/F combination motor controller (MMP-T32 with optional unit) is used, branch circuits are protected independently.
Individual protection using Type E/F has the following advantages.
<Advantage 1: The number of devices can be reduced.>
Since the rated current of the upstream protection device is not restricted to meet the UL standards, the number of protection devices can be further reduced.
<Advantage 2: Thin wires can be used for tap conductors.>
For circuits including Type E/F, tap conductors with any of the following conditions can be used. Therefore, thinner wires can be selected.
Selecting C' (tap conductor):
Select one that meets any of the following conditions.
- Same capacity as B
- Capacity of more than \(1 / 3\) of \(B\) (up to 7.5 m, protection against damage to the wire required)
- Capacity of more than \(1 / 10\) of \(B\) (up to 3 m , protection against damage to the wire required)
\begin{tabular}{|l|}
\hline [Definition of Abbreviations] \\
MCP: Main Circuit Protection device \\
BCP: Branch Circuit Protection device \\
MMS: Manual Motor Starter
\end{tabular}


General Protection Circuit Example


Group Protection Circuit Example


Group Protection Circuit Example Using Motor Circuit Breakers


Individual Protection Circuit Example Using Type E/F

\section*{Motor Circuit Breakers MMP-T32}

\section*{UL Standard Certified Rating (Motor Circuit Breakers)}

When UL standards are applied and used, select from the rating table below.

\section*{Motor Circuit Breakers UL Standard Certified Ratings}
[Certified Rating]
- Main Circuit Single-Phase
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{\multirow{4}{*}{Motor Circuit Breaker (Current Setting Range)}} & \multicolumn{12}{|c|}{Certified Rating} \\
\hline & & \multicolumn{2}{|l|}{110 to 120V} & \multicolumn{2}{|r|}{200 V} & \multicolumn{2}{|c|}{208 V} & \multicolumn{2}{|l|}{220 to 240V} & \multicolumn{2}{|l|}{440 to 480V} & \multicolumn{2}{|l|}{550 to 600V} \\
\hline & & \multicolumn{2}{|l|}{Maximum Rated ! Maximum Rated} & \multicolumn{2}{|l|}{Maximum Rated: Maximum Rated} & \multicolumn{2}{|l|}{Maximum Rated:Maximum Rated} & \multicolumn{2}{|l|}{Maximum Rated: Maximum Rated} & \multicolumn{2}{|l|}{Maximum Rated: Maximum Rated} & \multicolumn{2}{|l|}{Maximum Rated: Maximum Rated} \\
\hline & & Capacity [HP] & Operating Curent \([A\) & Capacity [HP] & Operating Current \([A]\) & Capacity [HP] & Operating Current \([A]\) & Capacity [HP] & Operating Current \([A]\) & Capanacity
\[
[H P]
\] & \begin{tabular}{l}
Operating \\
Current \([A]\)
\end{tabular} & Capacity [HP] & Operating Curent \([A]\) \\
\hline \multirow{15}{*}{MMP-T32} & 0.1 to 0.16 & - & 0.16 & - & 0.16 & - & 0.16 & - & 0.16 & - & 0.16 & - & 0.16 \\
\hline & 0.16 to 0.25 & - & 0.25 & - & 0.25 & - & 0.25 & - & 0.25 & - & 0.25 & - & 0.25 \\
\hline & 0.25 to 0.4 & - & 0.4 & - & 0.4 & - & 0.4 & - & 0.4 & - & 0.4 & - & 0.4 \\
\hline & 0.4 to 0.63 & - & 0.63 & - & 0.63 & - & 0.63 & - & 0.63 & - & 0.63 & - & 0.63 \\
\hline & 0.63 to 1 & - & 1 & - & 1 & - & 1 & - & 1 & - & 1 & - & 1 \\
\hline & 1 to 1.6 & - & 1.6 & - & 1.6 & - & 1.6 & 1/10 & 1.5 & - & 1.6 & - & 1.6 \\
\hline & 1.6 to 2.5 & - & 2.5 & 1/6 & 2.5 & 1/6 & 2.4 & 1/6 & 2.2 & 1/2 & 2.5 & 1/2 & 2 \\
\hline & 2.5 to 4 & 1/8 & 3 & 1/3 & 4 & 1/3 & 4 & 1/3 & 3.6 & 1 & 4 & 1-1/2 & 4 \\
\hline & 4 to 6.3 & 1/4 & 5.8 & 1/2 & 5.6 & 1/2 & 5.4 & 1/2 & 4.9 & 2 & 6 & 2 & 4.8 \\
\hline & 5.5 to 8 & 1/3 & 7.2 & 3/4 & 7.9 & 3/4 & 7.6 & 1 & 8 & 2 & 6 & 3 & 6.8 \\
\hline & 7 to 10 & 1/2 & 9.8 & 1 & 9.2 & 1 & 8.8 & 1-1/2 & 10 & 3 & 8.5 & - & 10 \\
\hline & 9 to 13 & 3/4 & 13 & 1-1/2 & 11.5 & 1-1/2 & 11 & 2 & 12 & 5 & 13 & 5 & 11.2 \\
\hline & 12 to 18 & 1 & 16 & 2 & 13.8 & 2 & 13.2 & 3 & 17 & 5 & 14 & 7-1/2 & 16 \\
\hline & 18 to 25 & 2 & 24 & 3 & 19.6 & 3 & 18.7 & - & 25 & 7-1/2 & 21 & 10 & 20 \\
\hline & 24 to 32 & 2 & 24 & 5 & 32 & 5 & 30.8 & 5 & 28 & 10 & 26 & 15 & 27 \\
\hline
\end{tabular}

Note 1. Since "-" has no horsepower setting by standard, select the maximum rated operating current [A].

\section*{- Main Circuit Three-Phase}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{\multirow{4}{*}{Motor Circuit Breaker (Current Setting Range)}} & \multicolumn{12}{|c|}{Certified Rating} \\
\hline & & \multicolumn{2}{|l|}{110 to 120V} & \multicolumn{2}{|c|}{200 V} & \multicolumn{2}{|c|}{208 V} & \multicolumn{2}{|l|}{220 to 240V} & \multicolumn{2}{|l|}{440 to 480V} & \multicolumn{2}{|l|}{550 to 600V} \\
\hline & & \multicolumn{2}{|l|}{Maximum Rated !Maximum Rated} & \multicolumn{2}{|l|}{Maximum Rated: Maximum Rated} & \multicolumn{2}{|l|}{Maximum Rated: Maximum Rated} & \multicolumn{2}{|l|}{Maximum Rated: Maximum Rated} & \multicolumn{2}{|l|}{Maximum Rated: Maximum Rated} & \multicolumn{2}{|l|}{Maximum Rated: Maximum Rated} \\
\hline & & \begin{tabular}{l}
Capacity \\
[HP]
\end{tabular} & \begin{tabular}{l}
Operating \\
Current \([A]\)
\end{tabular} & Capacity [HP] & \begin{tabular}{l}
Operating \\
Current \([A]\)
\end{tabular} & Capacity [HP] & \begin{tabular}{l}
Operating \\
Current \([A]\)
\end{tabular} & Capacity [HP] & Operating Curent \([A]\) & Capacity [HP] & Operating Curent \([A]\) & Capacity [HP] & \begin{tabular}{l}
Operating \\
Current \([A]\)
\end{tabular} \\
\hline \multirow{15}{*}{MMP-T32} & 0.1 to 0.16 & - & 0.16 & - & 0.16 & - & 0.16 & - & 0.16 & - & 0.16 & - & 0.16 \\
\hline & 0.16 to 0.25 & - & 0.25 & - & 0.25 & - & 0.25 & - & 0.25 & - & 0.25 & - & 0.25 \\
\hline & 0.25 to 0.4 & - & 0.4 & - & 0.4 & - & 0.4 & - & 0.4 & - & 0.4 & - & 0.4 \\
\hline & 0.4 to 0.63 & - & 0.63 & - & 0.63 & - & 0.63 & - & 0.63 & - & 0.63 & - & 0.63 \\
\hline & 0.63 to 1 & - & 1 & - & 1 & - & 1 & - & 1 & 1/2 & 1 & 1/2 & 0.9 \\
\hline & 1 to 1.6 & - & 1.6 & - & 1.6 & - & 1.6 & - & 1.6 & 3/4 & 1.6 & 3/4 & 1.3 \\
\hline & 1.6 to 2.5 & - & 2.5 & 1/2 & 2.5 & 1/2 & 2.4 & 1/2 & 2.2 & 1 & 2.1 & 1-1/2 & 2.4 \\
\hline & 2.5 to 4 & - & 4 & 3/4 & 3.7 & 3/4 & 3.5 & 1 & 4 & 2 & 3.4 & 3 & 3.9 \\
\hline & 4 to 6.3 & 3/4 & 6.3 & 1-1/2 & 6.3 & 1-1/2 & 6.3 & 1-1/2 & 6 & 3 & 4.8 & 5 & 6.1 \\
\hline & 5.5 to 8 & 1 & 8 & 2 & 7.8 & 2 & 7.5 & 2 & 6.8 & 5 & 7.6 & 5 & 6.1 \\
\hline & 7 to 10 & 1 & 8.4 & - & 10 & - & 10 & 3 & 9.6 & 5 & 7.6 & 7-1/2 & 9 \\
\hline & 9 to 13 & 1-1/2 & 12 & 3 & 11 & 3 & 10.6 & 3 & 9.6 & 7-1/2 & 11 & 10 & 11 \\
\hline & 12 to 18 & 2 & 13.6 & 5 & 17.5 & 5 & 16.7 & 5 & 15.2 & 10 & 14 & 15 & 17 \\
\hline & 18 to 25 & 3 & 19.2 & 7-1/2 & 25.3 & 7-1/2 & 24.2 & 7-1/2 & 22 & 15 & 21 & 20 & 22 \\
\hline & 24 to 32 & 5 & 30.4 & 10 & 32 & 10 & 30.8 & 10 & 28 & 20 & 27 & 30 & 32 \\
\hline
\end{tabular}

Note 1. Since " - " has no horsepower setting by standard, select the maximum rated operating current \([A]\).

\section*{UL Standard Certification (SCCR) [Type E/F Combination Motor Controllers]}

Type E/F combination motor controllers can be configured by applying power side terminal covers and short circuit display units to motor circuit breakers. Increasing the SCCR value contributes to panel miniaturization and reduced wiring.

\section*{Type E/F Selection Table}
(1) Type E Combination
[Certified Rating]
\begin{tabular}{|c}
\begin{tabular}{c} 
Combination \\
Arrangements
\end{tabular}
\end{tabular}\(=\)\begin{tabular}{c} 
Motor Circuit Breaker \\
MMP-T32
\end{tabular}\(+\)\begin{tabular}{c} 
Power Side Terminal \\
Cover Kit UT-CV3
\end{tabular}\(+\)\begin{tabular}{c} 
Short-circuit Display \\
Unit UT-TU
\end{tabular}
- Main Circuit Three Phase 220 to 240 V
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multicolumn{4}{|c|}{Type E Combination} & \multicolumn{4}{|c|}{Certified Rating} \\
\hline Motor Circuit Breaker & (Current Setting Range) & Power Side Terminal Cover & Short-circuit Display Unit & Maximum Rated Capacity [HP] & Maximum Rated Operating Current [ \(\mid\) ] \(]\) & \multicolumn{2}{|c|}{SCCR} \\
\hline \multirow{15}{*}{MMP-T32} & 0.1 to 0.16 & \multirow{15}{*}{UT-CV3} & \multirow{15}{*}{UT-TU} & - & 0.16 & \multirow{15}{*}{240 V} & \multirow{13}{*}{50kA} \\
\hline & 0.16 to 0.25 & & & - & 0.25 & & \\
\hline & 0.25 to 0.4 & & & - & 0.4 & & \\
\hline & 0.4 to 0.63 & & & - & 0.63 & & \\
\hline & 0.63 to 1 & & & - & 1 & & \\
\hline & 1 to 1.6 & & & - & 1.6 & & \\
\hline & 1.6 to 2.5 & & & 1/2 & 2.2 & & \\
\hline & 2.5 to 4 & & & 1 & 4 & & \\
\hline & 4 to 6.3 & & & 1-1/2 & 6 & & \\
\hline & 5.5 to 8 & & & 2 & 6.8 & & \\
\hline & 7 to 10 & & & 3 & 9.6 & & \\
\hline & 9 to 13 & & & 3 & 9.6 & & \\
\hline & 12 to 18 & & & 5 & 15.2 & & \\
\hline & 18 to 25 & & & 7-1/2 & 22 & & 25kA \\
\hline & 24 to 32 & & & 10 & 28 & & 25kA \\
\hline
\end{tabular}

Note 1. Since " - " has no horsepower setting by standard, select the maximum rated operating current [A].
- Main Circuit Three Phase 440 to 480 V
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multicolumn{4}{|c|}{Type E Combination} & \multicolumn{4}{|c|}{Certified Rating} \\
\hline \multicolumn{2}{|l|}{Motor Circuit Breaker (Current Setting Range)} & Power Side Terminal Cover & Short-circuit Display Unit & Maximum Rated Capacity [HP] & Maximum Rated Operating Curenent [A] & \multicolumn{2}{|c|}{SCCR} \\
\hline \multirow{15}{*}{MMP-T32} & 0.1 to 0.16 & \multirow{15}{*}{UT-CV3} & \multirow{15}{*}{UT-TU} & - & 0.16 & \multirow{15}{*}{\[
\begin{gathered}
480 \mathrm{Y} \\
/ \\
277 \mathrm{~V}
\end{gathered}
\]} & \\
\hline & 0.16 to 0.25 & & & - & 0.25 & & \\
\hline & 0.25 to 0.4 & & & - & 0.4 & & \\
\hline & 0.4 to 0.63 & & & - & 0.63 & & \\
\hline & 0.63 to 1 & & & 1/2 & 1 & & \\
\hline & 1 to 1.6 & & & 3/4 & 1.6 & & \\
\hline & 1.6 to 2.5 & & & 1 & 2.1 & & 50kA \\
\hline & 2.5 to 4 & & & 2 & 3.4 & & \\
\hline & 4 to 6.3 & & & 3 & 4.8 & & \\
\hline & 5.5 to 8 & & & 5 & 7.6 & & \\
\hline & 7 to 10 & & & 5 & 7.6 & & \\
\hline & 9 to 13 & & & 7-1/2 & 11 & & \\
\hline & 12 to 18 & & & 10 & 14 & & \\
\hline & 18 to 25 & & & 15 & 21 & & 25kA \\
\hline & 24 to 32 & & & 20 & 27 & & 25kA \\
\hline
\end{tabular}

Note 1. Since "-" has no horsepower setting by standard, select the maximum rated operating current [A].


Certified Rating]
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{7}{|c|}{Type F Combination} & \multicolumn{4}{|c|}{Certified Rating} \\
\hline \multicolumn{2}{|l|}{Type E Combination (Current Setting Range)} & \multicolumn{4}{|c|}{Magnetic Contactors} & Connecting Conductor Unit & Maximum Rated Capacity [HP] & Maximum Rated Operating Curent \([\) ] & \multicolumn{2}{|r|}{SCCR} \\
\hline \multirow[b]{6}{*}{MMP-T32} & \multicolumn{8}{|l|}{\multirow[t]{14}{*}{}} & & \multirow{14}{*}{50kA} \\
\hline & & & & & & & & & & \\
\hline & & & & & & & & & & \\
\hline & & & & & & & & & & \\
\hline & & & & & & & & & & \\
\hline & & & & & & & & & & \\
\hline UT-CV3 & & & & & & & & &  & \\
\hline & & & & & & & & & 240V & \\
\hline UT-TU & & & & & & & & & & \\
\hline & & & & & & & & & & \\
\hline & & & & & & & & & & \\
\hline & & & & & & & & & & \\
\hline & & & & & & & & & & \\
\hline & & & & & & & & & & \\
\hline
\end{tabular}

Note 1. Since "-" has no horsepower setting by standard, select the maximum rated operating current \([A]\).
- Main Circuit Three Phase 440 to 480 V


Note 1. Since " - " has no horsepower setting by standard, select the maximum rated operating current [A].

\section*{Motor Circuit Breakers MMP-T32}

\section*{UL Standard Certification (SCCR) [Combination with Servo Amplifier]}

The SCCR is acquired by combining a Combination Motor Controller Type E and a Mitsubishi Electric AC servo amplifier.
The applicable combinations and SCCR values are shown in the table below.
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{Type E Combination Motor Controller (SCPD)} & \multicolumn{3}{|c|}{Servo Amplifiers} & \multirow[t]{2}{*}{Main Circuit Voltage (Vac)} & \multirow[t]{2}{*}{\[
\begin{aligned}
& \text { SCCR } \\
& (k A)
\end{aligned}
\]} \\
\hline Model Name & Maximum Heater Designation & Model Name & Input Rating (Vac) & Input Phase & & \\
\hline \multirow{21}{*}{MMP-T32} & 1.6A & MR-J4-10\# & \multirow{9}{*}{200 to 240} & \multirow{9}{*}{Three-Phase} & \multirow{9}{*}{240} & \multirow{7}{*}{50} \\
\hline & 2.5 A & MR-J4-20\# & & & & \\
\hline & 4A & MR-J4-40\# & & & & \\
\hline & 6.3A & MR-J4-60\# & & & & \\
\hline & 6.3A & MR-J4-70\# & & & & \\
\hline & 8A & MR-J4-100\# & & & & \\
\hline & 18A & MR-J4-200\# & & & & \\
\hline & 25A & MR-J4-350\# & & & & \multirow[b]{2}{*}{25 (Note 1)} \\
\hline & 32A & MR-J4-500\# & & & & \\
\hline & 2.5A & MR-J4-60\#4 & \multirow{6}{*}{380 to 480} & \multirow{6}{*}{Three-Phase} & \multirow{6}{*}{480 Y 277} & \multirow{5}{*}{50} \\
\hline & 4A & MR-J4-100\#4 & & & & \\
\hline & 8A & MR-J4-200\#4 & & & & \\
\hline & 13A & MR-J4-350\#4 & & & & \\
\hline & 18A & MR-J4-500\#4 & & & & \\
\hline & 25A & MR-J4-700\#4 & & & & 25 (Note 1) \\
\hline & 6.3 A & MR-J4W2-22B & \multirow{6}{*}{200 to 240} & \multirow{6}{*}{Three-Phase} & \multirow{6}{*}{240} & \multirow{6}{*}{50} \\
\hline & 8A & MR-J4W2-44B & & & & \\
\hline & 13A & MR-J4W2-77B & & & & \\
\hline & 18A & MR-J4W2-1010B & & & & \\
\hline & 8A & MR-J4W3-222B & & & & \\
\hline & 13A & MR-J4W3-444B & & & & \\
\hline
\end{tabular}
\#: Either A, B, or GF.
- UL Standard Certification (SCCR) [Combination with Inverter]

The SCCR is acquired by combining a Combination Motor Controller Type E and a Mitsubishi Electric inverter.
The applicable combinations and SCCR values are shown in the table below.
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{Type E Combination Motor Controller (SCPD)} & \multicolumn{2}{|c|}{Inverters} & \multirow{2}{*}{Main Circuit Voltage (Vac)} & \multirow[t]{2}{*}{\begin{tabular}{l}
SCCR \\
(kA)
\end{tabular}} \\
\hline Model Name & Maximum Heater Designation & Model Name & Capacity [kW] & & \\
\hline \multirow{28}{*}{MMP-T32} & 1.6A & \multirow{7}{*}{FR-E720} & 0.1 & \multirow{28}{*}{\(480 Y 277\)} & \multirow{6}{*}{50} \\
\hline & 4A & & 0.2 & & \\
\hline & 6.3A & & 0.4 & & \\
\hline & 10A & & 0.75 & & \\
\hline & 13A & & 1.5 & & \\
\hline & 18A & & 2.2 & & \\
\hline & 25A & & 3.7 & & 25 (Note 1) \\
\hline & 4A & \multirow{7}{*}{FR-E740} & 0.4 & & \multirow{5}{*}{50} \\
\hline & 6.3A & & 0.75 & & \\
\hline & 8A & & 1.5 & & \\
\hline & 10A & & 2.2 & & \\
\hline & 18A & & 3.7 & & \\
\hline & 25A & & 5.5 & & \multirow[b]{2}{*}{25 (Note 1)} \\
\hline & 32A & & 7.5 & & \\
\hline & 1.6A & \multirow[b]{2}{*}{FR-D720} & 0.1 & & \multirow{6}{*}{50} \\
\hline & 4A & & 0.2 & & \\
\hline & 6.3A & \multirow{5}{*}{\[
\begin{aligned}
& \text { FR-D720 } \\
& \text { (FR-F720PJ) }
\end{aligned}
\]} & 0.4 & & \\
\hline & 8A & & 0.75 & & \\
\hline & 13A & & 1.5 & & \\
\hline & 18A & & 2.2 & & \\
\hline & 25A & & 3.7 & & 25 (Note 1) \\
\hline & 2.5A & \multirow{7}{*}{\[
\begin{gathered}
\text { FR-D740 } \\
\text { (FR-F740PJ) }
\end{gathered}
\]} & 0.4 & & \multirow{5}{*}{50} \\
\hline & 4A & & 0.75 & & \\
\hline & 6.3A & & 1.5 & & \\
\hline & 10A & & 2.2 & & \\
\hline & 18A & & 3.7 & & \\
\hline & 25A & & 5.5 & & \multirow[b]{2}{*}{25 (Note 1)} \\
\hline & 32A & & 7.5 & & \\
\hline \multirow{24}{*}{MMP-T32} & 8A & \multirow{5}{*}{FR-A820} & 0.4 & \multirow{24}{*}{\(480 Y 277\)} & \multirow{3}{*}{50} \\
\hline & 13A & & 0.75 & & \\
\hline & 18A & & 1.5 & & \\
\hline & 25A & & 2.2 & & \multirow[b]{2}{*}{25 (Note 1)} \\
\hline & 32A & & 3.7 & & \\
\hline & 4A & \multirow{7}{*}{FR-A840} & 0.4 & & \multirow{5}{*}{50} \\
\hline & 6.3A & & 0.75 & & \\
\hline & 8A & & 1.5 & & \\
\hline & 13A & & 2.2 & & \\
\hline & 18A & & 3.7 & & \\
\hline & 25A & & 5.5 & & \multirow[b]{2}{*}{25 (Note 1)} \\
\hline & 32A & & 7.5 & & \\
\hline & 8A & \multirow{5}{*}{FR-F820} & 0.75 & & \multirow{3}{*}{50} \\
\hline & 13A & & 1.5 & & \\
\hline & 18A & & 2.2 & & \\
\hline & 25A & & 3.7 & & \multirow[t]{2}{*}{25 (Note 1)} \\
\hline & 32A & & 5.5 & & \\
\hline & 4A & \multirow{7}{*}{FR-F840} & 0.75 & & \multirow{5}{*}{50} \\
\hline & 6.3A & & 1.5 & & \\
\hline & 8A & & 2.2 & & \\
\hline & 13A & & 3.7 & & \\
\hline & 18A & & 5.5 & & \\
\hline & 25A & & 7.5 & & \multirow[b]{2}{*}{25 (Note 1)} \\
\hline & 32A & & 11 & & \\
\hline
\end{tabular}

Note 1. If a heater designation of 18A or less is selected based on the load current, the SCCR is 50kA.
Note 2. To prevent the Type E combination motor controller from being activated by the load current including high frequency components of the inverter, select a slightly larger heater designation value than the rated current of the inverter. Then, check the actual operation Reference value: Load current \(\times 1.4\) ). If the Type E combination motor controller is activated by the maximum heater designation value in the above table, use a UL489-listed low voltage breaker.

\section*{Motor Circuit Breakers MMP-T32}

\section*{UL Certification Rating (SCCR) [Group Installation]}

The table below shows the UL certification ratings applicable to group installation circuits.

Table 1. Motor Circuit Breaker MMP-T32 Single Unit


Table 2. Motor Circuit Breaker MMP-T32+S(D)-(2x)T \(\square\)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow{4}{*}{Motor Circuit Breaker Model Name} & & & & & & \multicolumn{8}{|c|}{Short-Circuit Current Rating (SCCR)} \\
\hline & \multirow[b]{3}{*}{Heater Designation} & & & & & \multicolumn{4}{|l|}{\multirow[t]{2}{*}{Main Circuit Voltage: 240 V Maximum Low Voltage Circuit Breaker (BCP) Rating}} & \multicolumn{4}{|l|}{\multirow[t]{2}{*}{Main Circuit Voltage: 480 V Maximum Low Voltage Circuit Breaker (BCP) Rating}} \\
\hline & & \multicolumn{4}{|l|}{\multirow[b]{2}{*}{Combination Connecting Unit/Magnetic Contactor}} & & & & & & & & \\
\hline & & & & & & & Maximum Rated Current & Minimum Breaking Current & Recommended Model Name & & Maximum Rated Current & Minimum Breaking Current & Recommended Model Name \\
\hline \multirow{15}{*}{MMP-T32} & 0.16A & \multirow{12}{*}{\begin{tabular}{l}
UT-MT20 \\
S-(2x)T10
\end{tabular}} & \multirow{12}{*}{\[
\begin{aligned}
& \text { UT-MT20(D) } \\
& \frac{1}{\text { S(D)-(2x)T12 }}
\end{aligned}
\]} & \multirow{13}{*}{\[
\begin{aligned}
& \text { UT-MT20(D) } \\
& \quad / \\
& \text { S(D)-(2x)T20 }
\end{aligned}
\]} & \multirow{15}{*}{\[
\begin{gathered}
\text { UT-MT32(D) } \\
/ \\
\text { S(D)-(2x)T32 }
\end{gathered}
\]} & \multirow{15}{*}{50 kA} & \multirow{15}{*}{250 A} & \multirow{15}{*}{50 kA} & \multirow{15}{*}{\[
\begin{aligned}
& \text { NF250-HVU } \\
& \text { NV250-HVU }
\end{aligned}
\]} & \multirow{15}{*}{50 kA} & \multirow{15}{*}{250 A} & \multirow{15}{*}{50 kA} & \multirow{15}{*}{\[
\begin{aligned}
& \text { NF250-HVU } \\
& \text { NV250-HVU }
\end{aligned}
\]} \\
\hline & 0.25A & & & & & & & & & & & & \\
\hline & 0.4 A & & & & & & & & & & & & \\
\hline & 0.63 A & & & & & & & & & & & & \\
\hline & 1A & & & & & & & & & & & & \\
\hline & 1.6A & & & & & & & & & & & & \\
\hline & 2.5A & & & & & & & & & & & & \\
\hline & 4A & & & & & & & & & & & & \\
\hline & 6.3A & & & & & & & & & & & & \\
\hline & 8A & & & & & & & & & & & & \\
\hline & 10A & & & & & & & & & & & & \\
\hline & 13A & & & & & & & & & & & & \\
\hline & 18A & \multirow{3}{*}{-} & \multirow{3}{*}{-} & & & & & & & & & & \\
\hline & 25A & & & \multirow[t]{2}{*}{-} & & & & & & & & & \\
\hline & 32A & & & & & & & & & & & & \\
\hline
\end{tabular}

\footnotetext{
Note. Some combinations require the mounting base unit (UT-BT \(\square\) ) and jointing block unit (UT-RT \(\square\) ) for installation.
}

\subsection*{12.10 Outline Drawings}


MMP-T32 + UT-MAX(LL)/UT-MAL(LL)
\begin{tabular}{|l|}
\hline Model Name \\
\hline UT-MAX \\
\hline UT-MAXLL \\
\hline UT-MAL \\
\hline UT-MALLL \\
\hline
\end{tabular}

The above figure shows the state where 2 units [UT-MAX(LL) and/or are installed.
Outline drawings of UT-MAX(LL) and UT-MAL(LL) are equivalent.
\begin{tabular}{|c|c|c|}
\hline \multicolumn{3}{|c|}{ Contact Arrangement } \\
\hline \multirow{2}{*}{ Model Name } & Terminal No. (marked) \\
\cline { 3 - 3 } & 1 a & 1 b \\
\hline UT-MAX & \(13(23)\)-14(24) & \(11(21)-12(22)\) \\
\hline UT-MAXLL & & \\
\hline UT-MAL & \(17(27)-18(28)\) & \(15(25)-16(26)\) \\
\hline UT-MALLL & \\
\hline
\end{tabular}

MMP-T32 + UT-CV3 + UT-TU
(Type E Combination)
\begin{tabular}{|l|}
\hline Model Name \\
\hline UT-CV3 \\
\hline UT-TU \\
\hline
\end{tabular}



MMP-T32
(Unit: mm)

\section*{MMP-T32 + UT-MT20 + S-T10}


MMP-T32 + UT-MT20 + S-T12/S-T20
(Unit: mm)

MMP-T32 + UT-MT32 + S-T32

 UT-MT32

\section*{Motor Circuit Breakers MMP-T32}


MMP-T32x2 + UT-2B4/UT-2B5


MMP-T32x3 + UT-3B4/UT-3B5

\begin{tabular}{|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Variable Dimensions} & \multicolumn{3}{|l|}{Variable Dimension [mm]} & Model Name \\
\hline & A & B & C & UT-3B4 \\
\hline UT-3B4 & 135 & 125 & 45 & UT-3B5 \\
\hline UT-3B5 & 159 & 149 & 57 & \\
\hline
\end{tabular}

MMP-T32+ UT-MT32D + SD-T32 + UT-BT32D


MMP-T32 + UT-MT \(\square+\) UT-BT \(\square+\) S-T \(\square\)

\begin{tabular}{|c|c|c|c|c|}
\hline \multirow{2}{*}{ Variable Dimensions } & \multirow{2}{*}{ Combination Contactor } & \multicolumn{3}{|c|}{ Variable Dimension \([\mathrm{mm}]\)} \\
\cline { 3 - 5 } & A & B & C \\
\hline UT-BT20 & S-T10/T12/T20 & 163 & 106 & 116 \\
\hline UT-BT32 & S-T32 & 167 & 104 & 120 \\
\hline
\end{tabular}

MMP-T32 + UT-MT \(\square\) + UT-BT \(\square\) x 2 +
S(D)-2 \(\times\) T \(\square+\) UT-RT \(\square\)
(Unit: mm)

\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Combination Contactor} & \multirow[t]{2}{*}{Combination Connecting Conductor Unit} & \multirow[t]{2}{*}{\begin{tabular}{l}
Combination \\
Mounting Base Unit
\end{tabular}} & \multirow[t]{2}{*}{Variable Dimensions} & \multicolumn{3}{|l|}{Variale Dimension [mm]} \\
\hline & & & & A & B & C \\
\hline S-2×T10 & UT-MT20 & UT-BT20 (2 Units) & UT-RT10 & 91 & 46 & 116 \\
\hline S-2xT12/T20 & UT-MT20 & UT-BT20 (2 Units) & UT-RT20 & 99 & 54 & 116 \\
\hline SD-2xT12/T20 & UT-MT20D & UT-BT32D (2 Units) & UT-RT20 & 99 & 54 & 16 \\
\hline S-2×T32 & UT-MT32 & UT-BT32 (2 Units) & & 98 & 53 & 150 \\
\hline SD-2×T32 & UT-MT32D & UT-BT32D (2 Units) & UT & 98 & 53 & 154 \\
\hline
\end{tabular}

Note. The main circuit conductor kit UT/UN-SD \(\square\) is also available as a reversible electric wire. When using UN-SD18CX, switch the reversible wire power side and load side for this kit.

MMP-T32 + UT-MT \(\square D+\)
SD-T \(\square+\) UT-BT32DMP

\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Combination Contactor} & \multirow[t]{2}{*}{Combination Connecting Conductor Unit} & \multirow[t]{2}{*}{Variable Dimensions} & \multicolumn{6}{|l|}{Variable Dimension [mm]} \\
\hline & & & A & B & C & D & I & F \\
\hline SD-T12/T20 & UT-MT20D & \multirow[b]{2}{*}{UT-BT32DMP} & 99 & 164 & 188 & 84 & 90 & 103 \\
\hline SD- & UT-M & & 97 & 167 & 19 & 89 & 96 & \\
\hline
\end{tabular}
\begin{tabular}{|c|}
\hline Model Name \\
\hline UT-BT32DMP \\
\hline
\end{tabular}

MMP-T32×2 + UT-EP3 + UT- \(\square\) B \(\square\)


MMP-T32 + UT-MT \(\square \mathrm{D}+\mathrm{SD}-2 \times\) T \(\square\) +
UT-BT32DMP x \(2+\) UT-RT32DMP

\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Combination
Contactor} & \multirow[t]{2}{*}{Combination Connecting Conductor Unit} & \multirow[t]{2}{*}{Combination Mounting Base Unit} & \multirow[t]{2}{*}{Variable Dimensions} & \multicolumn{3}{|l|}{Variale Dimension [mm]} \\
\hline & & & & A & B & C \\
\hline SD-2xT12/T20 & UT-MT20D & \multirow[t]{2}{*}{UT-RT32DMP (2 Units)} & \multirow[b]{2}{*}{-RT32DMP} & 190 & 98 & 103 \\
\hline SD-T32 & UT-MT32D & & & 191 & 96 & 141 \\
\hline
\end{tabular}

Note. The main circuit conductor kit UT/UN-SD \(\square\) is also available as a reversible electric wire. When using UN-SD18CX, switch the reversible wire power side and load side for this kit.


MMP-T32 + UT-MQ12 + SD-Q \(\square\)

\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multicolumn{8}{|c|}{\begin{tabular}{c} 
Connecting \\
Conductor Unit
\end{tabular}} & \multicolumn{6}{|c|}{ Combination } & \multicolumn{5}{|c|}{ Variable Dimension [mm] } \\
\cline { 2 - 7 } & Contactor & A & B & C & +D & +E \\
\hline \multirow{5}{*}{ UT-MQ12 } & SD-Q11 & 163 & 14 & 50 & 0 & 0 \\
\cline { 2 - 7 } & SD-Q12 & 163 & 14 & 50 & 9.5 & 0 \\
\cline { 2 - 7 } & SD-QR11 & 166 & 14 & 50 & 0 & 45 \\
\cline { 2 - 7 } & SD-QR12 & 166 & 14 & 50 & 54.5 \\
\hline
\end{tabular}
\begin{tabular}{|c|}
\hline Model Name \\
\hline UT-MQ12 \\
\hline
\end{tabular}

\subsection*{12.11 How to Order}

\section*{- How to Order}

Follow the steps below when ordering.
(Enter a space in \(\mathbf{4}\).)
\begin{tabular}{lll|}
\hline \multicolumn{1}{|c|}{ Model Name } & & Heater Designation \\
\hline MMP-T32 & MMP-T32BC & \\
MMA \\
\hline
\end{tabular}

\section*{How to Order Options}

Follow the steps below when ordering.
\begin{tabular}{|c|c|c|}
\hline \multicolumn{3}{|l|}{(Enter a space in \(\mathbf{\triangle}\).)} \\
\hline \multirow{3}{*}{Auxiliary Contact Unit} & Model Name & Contact Arrangement \\
\hline & UT-MAX & 1 a \\
\hline & UT-MAX & 1b \\
\hline Alarm Contact Unit & UT-MAL & 1a \\
\hline & UT-MAL & 1b \\
\hline
\end{tabular}

Note. When ordering an optional unit without contact arrangement options, state the model name only.

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\section*{Supplementary Information}

\subsection*{13.1 Model Name Changes and Compatibility Between New and Old Products}

Our magnetic starters, magnetic contactors and contactor relays undergo model name transition as follows.


The mounting compatibility between the old and current models with equal capacity is shown below. Note that the symbols in the compatibility column are as follows, showing the compatibility for the standard mounting dimensions of each series. Not coil/contactor compatibility.
O: Compatible
- Can be made compatible by adding an MSO-T/N Series-dedicated adapter (available as a separate part) *

■: Standard products are not compatible, \(\mathrm{S} / \mathrm{MSO}(\mathrm{D})-2 \times T \square \mathrm{XN}\) is compatible
- : Can be made compatible by directly incorporating MSO-NロXA into MSO-A Series
\(\triangle\) : Can be made compatible by adding an S-T/N Series-dedicated adapter (available as a separate part) *
© : Standard products are not compatible, S, SD and SL(D)-N \(\square X A\) are compatible
\(x\) : Not compatible
* The adapters for S-T12 and SR-T5 can be used only for products where the manufacturing numbers on the front is " \(14 \mathrm{Y} * *\) " or " \(14 \mathrm{Z} * *\) ", or products where the first 2 -digit number is equal to or greater than " 15 " (those that have been manufactured in part of October 2014, and from November on).

\section*{1. Magnetic Starters}
(1) Mounting Compatibility of MS-A and MS-T/N
\begin{tabular}{l|c|l}
\hline \multicolumn{3}{|c}{ Non-Reversible Type } \\
\hline Old Model & Compatibility & Current Model \\
\hline MS-A10(RM) & \(O\) & MS-T10 \\
\hline MS-A11(RM) & \(O\) & MS-T12 \\
\hline MS-A12(RM) & \(x\) & MS-T12 \\
\hline MS-A20 & \(O\) & MS-T21 \\
\hline MS-A21 & \(O\) & MS-T21 \\
\hline MS-A25 & \(O\) & MS-T35 \\
\hline MS-A35 & \(O\) & MS-T35 \\
\hline MS-A50 & x & MS-T50 \\
\hline MS-A60 & x & MS-T65 \\
\hline MS-A65 & \(x\) & MS-T65 \\
\hline MS-A80 & \(O\) & MS-T80 \\
\hline MS-A100 & O & MS-N125 \\
\hline MS-A120 & \(O\) & MS-N125 \\
\hline MS-A125 & \(O\) & MS-N125 (MS-N150) \\
\hline MS-A150 & \(O\) & MS-N220 \\
\hline MS-A220 & \(O\) & MS-N300 \\
\hline MS-A300 & \(x\) & MS-N400 \\
\hline MS-A401 & - & - \\
\hline MS-A400 & &
\end{tabular}
\begin{tabular}{c|c|c}
\hline \multicolumn{3}{|c}{ Reversible Type } \\
\hline Old Model & Compatibility & Current Model \\
\hline MS-AR11 & x & MS-2xT21 \\
\hline MS-2xA20 & \(O\) & MS-2xT21 \\
\hline MS-2xA21 & \(O\) & MS-2xT21 \\
\hline MS-2xA25 & x & MS-2xT35 \\
\hline MS-2xA35 & \(O\) & MS-2xT35 \\
\hline MS-2xA50 & x & MS-2xT50 \\
\hline MS-2xA60 & x & MS-2xT65 \\
\hline MS-2xA65 & \(x\) & MS-2xT65 \\
\hline MS-2xA80 & \(O\) & MS-2xT80 \\
\hline MS-2xA100 & \(O\) & MS-2xN125 \\
\hline MS-2xA120 & x (O) & MS-2xN125 (MS-2xN150) \\
\hline MS-2xA125 & \(O\) & MS-2xN150 \\
\hline MS-2xA150 & \(O\) & MS-2xN220 \\
\hline MS-2xA220 & \(O\) & MS-2xN300 \\
\hline MS-2xA300 & \(O\) & MS-2xN400 \\
\hline MS-2xA401 & \(x\) & MS-2xN400 \\
\hline MS-2xA400 &
\end{tabular}
(2) Mounting Compatibility of MS-K and MS-T/N
\begin{tabular}{l|c|c}
\hline \multicolumn{3}{|c}{ Non-Reversible Type } \\
\hline Old Model & Compatibility & Current Model \\
\hline MS-K10 & \(O\) & MS-T10 \\
\hline MS-K11 & \(O\) & MS-T12 \\
\hline MS-K12 & \(O\) & MS-T12 \\
\hline MS-K20 & \(O\) & MS-T21 \\
\hline MS-K21 & \(O\) & MS-T21 \\
\hline MS-K25 & \(O\) & MS-T35 \\
\hline MS-K35 & \(O\) & MS-T35 \\
\hline MS-K50 & x & MS-T50 \\
\hline MS-K65 & x & MS-T65 \\
\hline MS-K80 & \(O\) & MS-T80 \\
\hline MS-K95 & \(O\) & MS-T100 \\
\hline MS-K100 & \(O\) & MS-N125 \\
\hline MS-K125 & \(O\) & MS-N125 \\
\hline MS-K150 & \(O\) & MS-N150 \\
\hline MS-K180 & \(O\) & MS-N220 \\
\hline MS-K220 & \(O\) & MS-N300 \\
\hline MS-K300 & \(O\) & MS-N400 \\
\hline MS-K400 & \\
\hline
\end{tabular}
\begin{tabular}{c|c|c}
\hline \multicolumn{3}{|c}{ Reversible Type } \\
\hline Old Model & Compatibility & Current Model \\
\hline MS-KR11 & x & MS-2xT21 \\
\hline MS-2xK20 & \(O\) & MS-2xT21 \\
\hline MS-2xK21 & \(O\) & MS-2xT21 \\
\hline MS-2xK25 & \(O\) & MS-2xT35 \\
\hline MS-2xK35 & \(O\) & MS-2xT35 \\
\hline MS-2xK50 & x & MS-2xT50 \\
\hline MS-2xK65 & O & MS-2xT65 \\
\hline MS-2xK80 & \(O\) & MS-2xT80 \\
\hline MS-2xK95 & \(O\) & MS-2xT100 \\
\hline MS-2xK100 & \(O\) & MS-2xN125 \\
\hline MS-2xK125 & \(O\) & MS-2xN125 \\
\hline MS-2xK150 & \(O\) & MS-2xN150 \\
\hline MS-2xK180 & \(O\) & MS-2xN180 \\
\hline MS-2xK220 & \(O\) & MS-2xN300 \\
\hline MS-2xK300 & \(O\) & MS-2xN400 \\
\hline MS-2xK400 & & \\
\hline
\end{tabular}
(3) Mounting Compatibility of MS-N and MS-T Types
\begin{tabular}{c|c|c}
\hline \multicolumn{3}{|c}{ Non-Reversible Type } \\
\hline Old Model & Compatibility & Current Model \\
\hline MS-N10 & \(O\) & MS-T10 \\
\hline MS-N11 & \(O\) & MS-T12 \\
\hline MS-N12 & \(O\) & MS-T12 \\
\hline MS-N20 & \(O\) & MS-T21 \\
\hline MS-N21 & \(O\) & MS-T21 \\
\hline MS-N25 & \(O\) & MS-T35 \\
\hline MS-N35 & \(O\) & MS-T35 \\
\hline MS-N50 & \(x\) & MS-T50 \\
\hline MS-N65 & \(O\) & MS-T65 \\
\hline MS-N80 & \(x\) & MS-T80 \\
\hline MS-N95 & \(O\) & MS-T100 \\
\hline
\end{tabular}
\begin{tabular}{c|c|c}
\hline \multicolumn{3}{|c}{ Reversible Type } \\
\hline Old Model & Compatibility & Current Model \\
\hline MS-2xN20 & \(O\) & MS-2xT21 \\
\hline MS-2xN21 & \(O\) & MS-2xT21 \\
\hline MS-2xN25 & \(O\) & MS-2xT35 \\
\hline MS-2xN35 & \(O\) & MS-2xT35 \\
\hline MS-2xN50 & \(x\) & MS-2xT50 \\
\hline MS-2xN65 & \(O\) & MS-2xT65 \\
\hline MS-2xN80 & \(x\) & MS-2xT80 \\
\hline MS-2xN95 & \(O\) & MS-2xT100 \\
\hline
\end{tabular}
(4) Mounting Compatibility of MSO-A and MSO-T/N Types
\begin{tabular}{l|c|c}
\hline \multicolumn{3}{c}{ Non-Reversible Type } \\
\hline Old Model & Compatibility & Current Model \\
\hline MSO-A10(RM) & \(\bullet\) & MSO-T10 \\
\hline MSO-A11(RM) & 0 & MSO-T12 \\
\hline MSO-A12(RM) & \(\bullet\) & MSO-T12 \\
\hline MSO-A20 & \(\bullet\) & MSO-T20 \\
\hline MSO-A21 & 0 & MSO-T21 \\
\hline MSO-A25 & \(x\) & MSO-T25 \\
\hline MSO-A35 & \(x\) & MSO-T35 \\
\hline MSO-A50 & \(x\) & MSO-T50 \\
\hline MSO-A60 & \(x\) & MSO-T65 \\
\hline MSO-A65 & \(x\) & MSO-T65 \\
\hline MSO-A80 & \(\bullet\) & MSO-T80 \\
\hline MSO-A100 & \(\bullet\) & MSO-N125 \\
\hline MSO-A120 & \(\bullet\) & MSO-N125 (MSO-N150) \\
\hline MSO-A125 & \(\bullet\) & MSO-N150 \\
\hline MSO-A150 & \(\bullet\) & MSO-N220 \\
\hline MSO-A220 & \(\bullet\) & MSO-N300 \\
\hline MSO-A300 & \(x\) & MSO-N400 \\
\hline MSO-A401 & \(x\) & S-N600 + TH-N600 \\
\hline MSO-A400 & & \\
\hline MSO-A600 & \\
\hline
\end{tabular}
\begin{tabular}{l|c|c}
\hline \multicolumn{3}{|c}{ Reversible Type } \\
\hline \multirow{2}{*}{ MSO-AR11 } & Compatibility & Current Model \\
\hline & \(x\) & MSO-2xT10 \\
\hline MSO-2xA20 & \(x\) & MSO-2xT12 \\
\hline MSO-2xA21 & \(x\) & MSO-2xT20 \\
\hline MSO-2xA25 & \(x\) & MSO-2xT21 \\
\hline MSO-2xA35 & \(x\) & MSO-2xT25 \\
\hline MSO-2xA50 & \(x\) & MSO-2xT35 \\
\hline MSO-2xA60 & \(x\) & MSO-2xT50 \\
\hline MSO-2xA65 & \(x\) & MSO-2xT65 \\
\hline MSO-2xA80 & \(x\) & MSO-2xT65 \\
\hline MSO-2xA100 & \(x\) & MSO-2xT80 \\
\hline MSO-2xA120 & \(x\) & MSO-2xN125 \\
\hline MSO-2xA125 & \(x\) & MSO-2xN125 \\
\hline MSO-2xA150 & \(x\) & MSO-2xN150 \\
\hline MSO-2xA220 & \(x\) & MSO-2xN220 \\
\hline MSO-2xA300 & \(x\) & MSO-2xN300 \\
\hline MSO-2xA401 & \(x\) & MSO-2xN400 \\
\hline MSO-2xA400 & \(x\) & MSO-2xN400 \\
\hline MSO-2xA600 & \(x\) & S-2xN600 + TH-N600 \\
\hline
\end{tabular}
(5) Mounting Compatibility of MSO-K and MSO-T/N Types
\begin{tabular}{c|c|c}
\hline \multicolumn{2}{|c}{ Non-Reversible Type } \\
\hline Old Model & Compatibility & Current Model \\
\hline MSO-K10 & \(\bullet\) & MSO-T10 \\
\hline MSO-K11 & \(O\) & MSO-T12 \\
\hline MSO-K12 & \(\bullet\) & MSO-T12 \\
\hline MSO-K18 & \(O\) & MSO-T20 \\
\hline MSO-K19 & \(\bullet\) & MSO-T20 \\
\hline MSO-K20 & \(\bullet\) & MSO-T20 \\
\hline MSO-K21 & x & MSO-T21 \\
\hline MSO-K25 & x & MSO-T25 \\
\hline MSO-K35 & \(\bullet\) & MSO-T35 \\
\hline MSO-K50 & \(O\) & MSO-T50 \\
\hline MSO-K65 & \(\bullet\) & MSO-T80 \\
\hline MSO-K80 & \(O\) & MSO-T100 \\
\hline MSO-K95 & \(O\) & MSO-N125 \\
\hline MSO-K100 & \(O\) & MSO-N125 \\
\hline MSO-K125 & \(O\) & MSO-N150 \\
\hline MSO-K150 & \(O\) & MSO-N180 \\
\hline MSO-K180 & \(O\) & MSO-N220 \\
\hline MSO-K220 & \(O\) & MSO-N300 \\
\hline MSO-K300 & \(O\) & MSO-N400 \\
\hline MSO-K400 & &
\end{tabular}
\begin{tabular}{c|c|c}
\hline \multicolumn{3}{|c}{ Reversible Type } \\
\hline Old Model & Compatibility & Current Model \\
\hline \multirow{2}{*}{ MSO-KR11 } & x & MSO-2xT10 \\
\cline { 2 - 3 } & x & MSO-2xT12 \\
\hline MSO-2xK18 & x & MSO-2xT20 \\
\hline MSO-2xK19 & x & MSO-2xT20 \\
\hline MSO-2xK20 & x & MSO-2xT20 \\
\hline MSO-2xK21 & x & MSO-2xT21 \\
\hline MSO-2xK25 & & MSO-2xT25 \\
\hline MSO-2xK35 & \(\square\) & MSO-2xT35 \\
\hline MSO-2xK50 & \(O\) & MSO-2xT50 \\
\hline MSO-2xK65 & \(\square\) & MSO-2xT65 \\
\hline MSO-2xK80 & \(O\) & MSO-2xT80 \\
\hline MSO-2xK95 & \(O\) & MSO-2xT100 \\
\hline MSO-2xK100 & \(O\) & MSO-2xN125 \\
\hline MSO-2xK125 & \(O\) & MSO-2xN150 \\
\hline MSO-2xK150 & \(O\) & MSO-2xN180 \\
\hline MSO-2xK180 & \(O\) & MSO-2xN220 \\
\hline MSO-2xK220 & \(O\) & MSO-2xN300 \\
\hline MSO-2xK300 & \(O\) & MSO-2xN400 \\
\hline MSO-2xK400 & \\
\hline
\end{tabular}

\section*{13 \\ Supplementary Information}
(6) Mounting Compatibility of MSO-N and MSO-T Types
\begin{tabular}{l|c|c}
\hline \multicolumn{3}{c}{ Non-Reversible Type } \\
\hline Old Model & Compatibility & Current Model \\
\hline MSO-N10 & \(\bullet\) & MSO-T10 \\
\hline MSO-N11 & \(O\) & MSO-T12 \\
\hline MSO-N12 & \(\bullet\) & MSO-T12 \\
\hline MSO-N18 & \(O\) & MSO-T20 \\
\hline MSO-N20 & \(\bullet\) & MSO-T20 \\
\hline & 0 & MSO-T21 \\
\hline MSO-N21 & 0 & MSO-T21 \\
\hline MSO-N25 & \(\bullet\) & MSO-T25 \\
\hline MSO-N35 & \(O\) & MSO-T35 \\
\hline MSO-N50 & \(\bullet\) & MSO-T50 \\
\hline MSO-N65 & \(O\) & MSO-T65 \\
\hline MSO-N80 & \(\bullet\) & MSO-T80 \\
\hline MSO-N95 & \(O\) & MSO-T100 \\
\hline
\end{tabular}
\begin{tabular}{c|c|c}
\hline \multicolumn{3}{|c}{ Reversible Type } \\
\hline Old Model & Compatibility & Current Model \\
\hline MSO- \(2 \times\) N10 & x & MSO- \(2 \times\) T10 \\
\hline MSO- \(2 \times\) N11 & x & MSO- \(2 \times\) T12 \\
\hline MSO- \(2 \times\) N18 & x & MSO- \(2 \times\) T20 \\
\hline \multirow{2}{*}{ MSO- \(2 \times\) N20 } & x & MSO- \(2 \times\) T20 \\
\hline & 0 & MSO- \(2 \times\) T21 \\
\hline MSO- \(2 \times\) N21 & \(O\) & MSO- \(2 \times\) T21 \\
\hline MSO- \(2 \times\) N25 & x & MSO- \(2 \times\) T25 \\
\hline MSO- \(2 \times\) N35 & O & MSO- \(2 \times\) T35 \\
\hline MSO- \(2 \times\) N50 & \(\square\) & MSO- \(2 \times\) T50 \\
\hline MSO- \(2 \times\) N65 & \(O\) & MSO- \(2 \times\) T65 \\
\hline MSO- \(2 \times\) N80 & \(\square\) & MSO- \(2 \times\) T80 \\
\hline MSO- \(2 \times\) N95 & \(O\) & MSO- \(2 \times\) T100 \\
\hline
\end{tabular}

\section*{2. Magnetic Contactors}
(1) Mounting Compatibility of S-A and S-T/N Types
\begin{tabular}{|c|c|c|}
\hline \multicolumn{3}{|c|}{Non-Reversible Type} \\
\hline Old Model & Compatibility & Current Model \\
\hline S-A10(RM)* & \(\triangle\) & S-T10 \\
\hline S-A11(RM)* & \(\bigcirc\) & S-T12 \\
\hline S-A12(RM)* & \(\triangle\) & S-T12 \\
\hline S-A20 & \(\triangle\) & S-T20 \\
\hline S-A21 & \(\bigcirc\) & S-T21 \\
\hline S-A25 & x & S-T25 \\
\hline S-A35 & x & S-T35 \\
\hline S-A50 & x & S-T50 \\
\hline S-A60 & \(\triangle\) & S-T65 \\
\hline S-A65 & x & S-T65 \\
\hline S-A80 & x & S-T80 \\
\hline S-A100 & A & S-N125 \\
\hline S-A120 & A & S-N125 \\
\hline S-A125 & \(\mathrm{x}(\mathbf{( 1 )}\) & S-N125(S-N150) \\
\hline S-A150 & A & S-N150 \\
\hline S-A220 & A & S-N220 \\
\hline S-A300 & A & S-N300 \\
\hline S-A401 & A & S-N400 \\
\hline S-A400 & X & S-N400 \\
\hline S-A600 & \(\bigcirc\) & S-N600 \\
\hline S-A800 & \(\bigcirc\) & S-N800 \\
\hline
\end{tabular}
*(RM) indicates that it can be rail-mounted. S-T10 to T80 are standard products that can be rail-mounted.
(2) Mounting Compatibility of S-K and S-T/N Types
\begin{tabular}{|c|c|c|}
\hline \multicolumn{3}{|c|}{Non-Reversible Type} \\
\hline Old Model & Compatibility & Current Model \\
\hline S-K10 & \(\triangle\) & S-T10 \\
\hline S-K11 & \(\bigcirc\) & S-T12 \\
\hline S-K12 & \(\triangle\) & S-T12 \\
\hline S-K18 & \(\bigcirc\) & S-T20 \\
\hline S-K19 & \(\triangle\) & S-T20 \\
\hline S-K20 & \(\triangle\) & S-T20 \\
\hline S-K21 & \(\bigcirc\) & S-T21 \\
\hline S-K25 & X & S-T25 \\
\hline S-K28 & x & S-T32 \\
\hline S-K35 & X & S-T35 \\
\hline S-K38 & x & S-T35 \\
\hline S-K48 & x & S-T50 \\
\hline S-K50 & \(\triangle\) & S-T50 \\
\hline S-K65 & \(\bigcirc\) & S-T65 \\
\hline S-K80 & \(\triangle\) & S-T80 \\
\hline S-K95 & \(\bigcirc\) & S-T100 \\
\hline S-K100 & \(\bigcirc\) & S-N125 \\
\hline S-K125 & \(\bigcirc\) & S-N125 \\
\hline S-K150 & \(\bigcirc\) & S-N150 \\
\hline S-K180 & \(\bigcirc\) & S-N180 \\
\hline S-K220 & \(\bigcirc\) & S-N220 \\
\hline S-K300 & \(\bigcirc\) & S-N300 \\
\hline S-K400 & \(\bigcirc\) & S-N400 \\
\hline S-K600 & \(\bigcirc\) & S-N600 \\
\hline S-K800 & \(\bigcirc\) & S-N800 \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|}
\hline \multicolumn{3}{|c|}{Reversible Type} \\
\hline Old Model & Compatibility & Current Model \\
\hline \multirow[b]{2}{*}{S-AR11} & x & S-2xT10 \\
\hline & x & S-2xT12 \\
\hline S-2×A20 & x & S-2xT20 \\
\hline S-2×A21 & X & S-2xT21 \\
\hline S-2×A25 & x & S-2xT25 \\
\hline S-2×A35 & x & S-2×T35 \\
\hline S-2×A50 & x & S-2xT50 \\
\hline S-2×A60 & x & S-2xT65 \\
\hline S-2xA65 & x & S-2xT65 \\
\hline S-2×A80 & x & S-2xT80 \\
\hline S-2×A100 & x & S-2×N125 \\
\hline S-2×A120 & x & S-2×N125 \\
\hline S-2×A125 & x & S-2×N125 \\
\hline S-2×A150 & x & S-2×N150 \\
\hline S-2×A220 & x & S-2×N220 \\
\hline S-2×A300 & x & S-2×N300 \\
\hline S-2×A401 & X & S-2×N400 \\
\hline S-2×A400 & x & S-2×N400 \\
\hline S-2×A600 & x & S-2×N600 \\
\hline S-2×A800 & x & S-2×N800 \\
\hline
\end{tabular}
\begin{tabular}{l|c|c}
\hline \multicolumn{2}{|c}{ Old Model } & Reversible Type \\
\hline \multirow{2}{*}{\(\mathrm{S}-\mathrm{KR} 11\)} & x & \(\mathrm{S}-2 \times \mathrm{T} 10\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 18\) & x & \(\mathrm{S}-2 \times \mathrm{T} 12\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 19\) & x & \(\mathrm{S}-2 \times \mathrm{T} 32\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 20\) & x & \(\mathrm{S}-2 \times \mathrm{T} 20\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 21\) & x & \(\mathrm{S}-2 \times \mathrm{T} 20\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 25\) & x & \(\mathrm{S}-2 \times \mathrm{T} 21\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 28\) & x & \(\mathrm{S}-2 \times \mathrm{T} 25\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 35\) & x & \(\mathrm{S}-2 \times \mathrm{T} 32\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 38\) & O & \(\mathrm{S}-2 \times \mathrm{T} 35\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 48\) & x & \(\mathrm{S}-2 \times \mathrm{T} 35\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 50\) & x & \(\mathrm{S}-2 \times \mathrm{T} 50\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 65\) & \(\mathbf{Q}\) & \(\mathrm{~S}-2 \times \mathrm{T} 50\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 80\) & O & \(\mathrm{S}-2 \times \mathrm{T} 65\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 95\) & \(\square\) & \(\mathrm{~S}-2 \times \mathrm{T} 80\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 100\) & O & \(\mathrm{S}-2 \times \mathrm{T} 100\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 125\) & O & \(\mathrm{S}-2 \times \mathrm{N} 125\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 150\) & O & \(\mathrm{S}-2 \times \mathrm{N} 125\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 180\) & O & \(\mathrm{S}-2 \times \mathrm{N} 150\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 220\) & O & \(\mathrm{S}-2 \times \mathrm{N} 180\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 300\) & O & \(\mathrm{S}-2 \times \mathrm{N} 220\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 400\) & O & \(\mathrm{S}-2 \times \mathrm{N} 300\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 600\) & O & \(\mathrm{S}-2 \times \mathrm{N} 400\) \\
\hline \(\mathrm{~S}-2 \times \mathrm{K} 800\) & O & \(\mathrm{S}-2 \times \mathrm{N} 600\) \\
\hline
\end{tabular}
(3) Mounting Compatibility of S-N and S-T Types
\begin{tabular}{l|c|c}
\hline \multicolumn{2}{|c}{ Non-Reversible Type } \\
\hline S-N10 & Compatibility & Current Model \\
\hline S-N11 & \(\triangle\) & S-T10 \\
\hline S-N12 & \(O\) & S-T12 \\
\hline S-N18 & \(\Delta\) & S-T12 \\
\hline \multirow{2}{*}{ S-N20 } & \(O\) & S-T20 \\
\hline S-N21 & \(\triangle\) & S-T20 \\
\hline S-N25 & \(O\) & S-T21 \\
\hline S-N28 & \(O\) & S-T21 \\
\hline S-N35 & \(\triangle\) & S-T25 \\
\hline S-N50 & \(O\) & S-T32 \\
\hline S-N65 & \(O\) & S-T35 \\
\hline S-N80 & \(\triangle\) & S-T50 \\
\hline S-N95 & \(O\) & S-T65 \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|}
\hline \multicolumn{3}{|c|}{Reversible Type} \\
\hline Old Model & Compatibility & Current Model \\
\hline S-2xN10 & x & S-2xT10 \\
\hline S-2xN11 & \(\times\) & S-2xT12 \\
\hline S-2xN18 & \(\times\) & S-2xT20 \\
\hline S-2xN20 & \(\times\) & S-2xT20 \\
\hline & \(\bigcirc\) & S-2xT21 \\
\hline S-2xN21 & \(\bigcirc\) & S-2xT21 \\
\hline S-2xN25 & \(\times\) & S-2xT25 \\
\hline S-2xN28 & \(\bigcirc\) & S-2xT32 \\
\hline S-2xN35 & \(\bigcirc\) & S-2xT35 \\
\hline S-2xN50 & \(\square\) & S-2xT50 \\
\hline S-2xN65 & \(\bigcirc\) & S-2xT65 \\
\hline S-2xN80 & - & S-2xT80 \\
\hline S-2xN95 & \(\bigcirc\) & S-2xT100 \\
\hline
\end{tabular}
(4) Mounting Compatibility of SD-A and SD-T/N Types
\begin{tabular}{l|c|c}
\hline \multicolumn{3}{|c}{ Non-Reversible Type } \\
\hline Old Model & Compatibility & Current Model \\
\hline SD-A11 & \(O\) & SD-T12 \\
\hline SD-A12 & \(\triangle\) & SD-T12 \\
\hline SD-A21 & \(O\) & SD-T21 \\
\hline SD-A35 & \(x\) & SD-T35 \\
\hline SD-A50 & x & SD-T50 \\
\hline SD-A60 & \(\Delta\) & SD-T65 \\
\hline SD-A65 & x & SD-T65 \\
\hline SD-A80 & x & SD-T80 \\
\hline SD-A100 & \(\mathbf{\Delta}\) & SD-N125 \\
\hline SD-A150 & \(\mathbf{\Delta}\) & SD-N150 \\
\hline SD-A220 & \(\mathbf{\Delta}\) & SD-N220 \\
\hline SD-A300 & \(\mathbf{\Delta}\) & SD-N300 \\
\hline SD-A401 & \(\mathbf{\Delta}\) & SD-N400 \\
\hline SD-A400 & \(x\) & SD-N400 \\
\hline SD-A600 & \(O\) & SD-N600 \\
\hline
\end{tabular}
\begin{tabular}{l|c|c}
\hline \multicolumn{3}{|c}{ Reversible Type } \\
\hline Old Model & Compatibility & Current Model \\
\hline SD-2xA21 & \(x\) & SD-2xT21 \\
\hline SD-2xA35 & \(x\) & SD-2xT35 \\
\hline SD-2xA50 & \(x\) & SD-2xT50 \\
\hline SD-2xA60 & \(x\) & SD-2xT65 \\
\hline SD-2xA65 & \(x\) & SD-2xT65 \\
\hline SD-2xA80 & \(x\) & SD-2xT80 \\
\hline SD-2xA100 & \(x\) & SD-2xN125 \\
\hline SD-2xA150 & \(x\) & SD-2xN150 \\
\hline SD-2xA220 & \(x\) & SD-2xN220 \\
\hline SD-2xA300 & \(x\) & SD-2xN300 \\
\hline SD-2xA401 & \(x\) & SD-2xN400 \\
\hline SD-2xA400 & \(x\) & SD-2xN400 \\
\hline SD-2xA600 & & \\
\hline
\end{tabular}
(5) Mounting Compatibility of SD-K and SD-T/N Types
\begin{tabular}{l|c|c}
\hline \multicolumn{3}{|c}{ Non-Reversible Type } \\
\hline Old Model & Compatibility & Current Model \\
\hline SD-K11 & \(O\) & SD-T12 \\
\hline SD-K12 & \(\triangle\) & SD-T12 \\
\hline SD-K21 & 0 & SD-T21 \\
\hline SD-K35 & x & SD-T35 \\
\hline SD-K50 & \(\triangle\) & SD-T50 \\
\hline SD-K65 & \(O\) & SD-T65 \\
\hline SD-K80 & \(\triangle\) & SD-T80 \\
\hline SD-K95 & \(O\) & SD-T100 \\
\hline SD-K100 & \(O\) & SD-N125 \\
\hline SD-K125 & \(O\) & SD-N125 \\
\hline SD-K150 & \(O\) & SD-N150 \\
\hline SD-K220 & \(O\) & SD-N220 \\
\hline SD-K300 & \(O\) & SD-N300 \\
\hline SD-K400 & \(O\) & SD-N400 \\
\hline SD-K600 & \(O\) & SD-N600 \\
\hline SD-K800 & \(O\) & SD-N800 \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|}
\hline \multicolumn{3}{|c|}{Reversible Type} \\
\hline Old Model & Compatibility & Current Model \\
\hline SD-2xK21 & x & SD-2xT21 \\
\hline SD-2xK35 & \(\bigcirc\) & SD-2xT35 \\
\hline SD-2xK50 & \(\square\) & SD-2xT50 \\
\hline SD-2xK65 & 0 & SD-2xT65 \\
\hline SD-2xK80 & \(\square\) & SD-2xT80 \\
\hline SD-2xK95 & \(\bigcirc\) & SD-2xT100 \\
\hline SD-2xK100 & \(\bigcirc\) & SD-2xN125 \\
\hline SD-2xK125 & \(\bigcirc\) & SD-2xN125 \\
\hline SD-2xK150 & \(\bigcirc\) & SD-2xN150 \\
\hline SD-2xK220 & \(\bigcirc\) & SD-2xN220 \\
\hline SD-2xK300 & \(\bigcirc\) & SD-2xN300 \\
\hline SD-2xK400 & \(\bigcirc\) & SD-2xN400 \\
\hline SD-2xK600 & \(\bigcirc\) & SD-2xN600 \\
\hline SD-2xK800 & \(\bigcirc\) & SD-2xN800 \\
\hline
\end{tabular}
(6) Mounting Compatibility of SD-N and SD-T Types
\begin{tabular}{l|c|c}
\hline \multicolumn{3}{|c}{ Non-Reversible Type } \\
\hline Old Model & Compatibility & Current Model \\
\hline SD-N11 & \(O\) & SD-T12 \\
\hline SD-N12 & \(\triangle\) & SD-T12 \\
\hline SD-N21 & \(O\) & SD-T21 \\
\hline SD-N35 & \(O\) & SD-T35 \\
\hline SD-N50 & \(\triangle\) & SD-T50 \\
\hline SD-N65 & \(O\) & SD-T65 \\
\hline SD-N80 & \(\triangle\) & SD-T80 \\
\hline SD-N95 & \(O\) & SD-T100 \\
\hline
\end{tabular}
\begin{tabular}{l|c|c}
\hline \multicolumn{3}{|c}{ Reversible Type } \\
\hline \multicolumn{1}{|c}{ Old Model } & Compatibility & Current Model \\
\hline SD-2xN11 & x & SD-2xT12 \\
\hline SD-2xN21 & 0 & SD-2xT21 \\
\hline SD-2xN35 & 0 & SD-2xT35 \\
\hline SD-2xN50 & \(\square\) & SD-2xT50 \\
\hline SD-2xN65 & \(O\) & SD-2xT65 \\
\hline SD-2xN80 & \(\square\) & SD-2xT80 \\
\hline SD-2xN95 & \(O\) & SD-2xT100 \\
\hline
\end{tabular}

\section*{13 \\ Supplementary Information}
(7) Mounting Compatibility of SL(D)-A and SL(D)-T/N Types
\begin{tabular}{l|c|l}
\hline \multicolumn{3}{c}{ Non-Reversible Type } \\
\hline Old Model & Compatibility & \multicolumn{1}{c}{ Current Model } \\
\hline SL(D)-A21 & 0 & SL(D)-T21 \\
\hline SL(D)-A50 & \(\Delta\) & SL(D)-T50 \\
\hline SL(D)-A60 & \(\Delta\) & SL(D)-T65 \\
\hline SL(D)-A80 & \(\triangle\) & SL(D)-T80 \\
\hline SL(D)-A100 & \(\mathbf{\Delta}\) & SL(D)-N125 \\
\hline SL(D)-A120 & \(\mathbf{\Delta}\) & SL(D)-N125 \\
\hline SL(D)-A150 & \(\mathbf{\Delta}\) & SL(D)-N150 \\
\hline SL(D)-A220 & \(\mathbf{\Delta}\) & SL(D)-N220 \\
\hline SL(D)-A300 & \(\mathbf{\Delta}\) & SL(D)-N300 \\
\hline SL(D)-A401 & \(x\) & SL(D)-N400 \\
\hline SL(D)-A400 & 0 & SL(D)-N600 \\
\hline SL(D)-A600 & & \\
\hline
\end{tabular}
(8) Mounting Compatibility of SL(D)-K and SL(D)-T/N Types
\begin{tabular}{l|c|c}
\hline \multicolumn{3}{c}{ Non-Reversible Type } \\
\hline Old Model & Compatibility & Current Model \\
\hline SL(D)-K21 & \(O\) & SL(D)-T21 \\
\hline SL(D)-K35 & \(x\) & SL(D)-T35 \\
\hline SL(D)-K50 & \(\triangle\) & SL(D)-T50 \\
\hline SL(D)-K65 & 0 & SL(D)-T65 \\
\hline SL(D)-K80 & \(\triangle\) & SL(D)-T80 \\
\hline SL(D)-K95 & \(O\) & SL(D)-T100 \\
\hline SL(D)-K100 & \(O\) & SL(D)-N125 \\
\hline SL(D)-K125 & \(O\) & SL(D)-N125 \\
\hline SL(D)-K150 & 0 & SL(D)-N150 \\
\hline SL(D)-K220 & \(O\) & SL(D)-N220 \\
\hline SL(D)-K300 & \(O\) & SL(D)-N300 \\
\hline SL(D)-K400 & \(O\) & SL(D)-N400 \\
\hline SL(D)-K600 & \(O\) & SL(D)-N600 \\
\hline SL(D)-K800 & \(O\) & SL(D)-N800 \\
\hline
\end{tabular}
(9) Mounting Compatibility of \(\operatorname{SL}(\mathrm{D})-\mathrm{N}\) and \(\operatorname{SL}(\mathrm{D})-\mathrm{T}\) Types
\begin{tabular}{l|c|l}
\hline \multicolumn{3}{c}{ Non-Reversible Type } \\
\hline Old Model & Compatibility & \multicolumn{1}{c}{ Current Model } \\
\hline SL(D)-N21 & \(\bigcirc\) & SL(D)-T21 \\
\hline SL(D)-N35 & \(O\) & SL(D)-T35 \\
\hline SL(D)-N50 & \(\triangle\) & SL(D)-T50 \\
\hline SL(D)-N65 & \(O\) & SL(D)-T65 \\
\hline SL(D)-N80 & \(\triangle\) & SL(D)-T80 \\
\hline SL(D)-N95 & \(O\) & SL(D)-T100 \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|}
\hline \multicolumn{3}{|c|}{Reversible Type} \\
\hline Old Model & Compatibility & Current Model \\
\hline SL(D)-2xA21 & x & SL(D)-2xT21 \\
\hline SL(D)-2xA50 & x & SL(D)-2xT50 \\
\hline SL(D)-2xA60 & x & SL(D)-2xT65 \\
\hline SL(D)-2xA80 & \(\bigcirc\) & SL(D)-2xT80 \\
\hline SL(D)-2xA100 & x & SL(D)-2xN125 \\
\hline SL(D)-2xA120 & x & SL(D)-2xN125 \\
\hline SL(D)-2xA150 & x & SL(D)-2xN150 \\
\hline SL(D)-2xA220 & x & SL(D)-2xN220 \\
\hline SL(D)-2xA300 & x & SL(D)-2xN300 \\
\hline SL(D)-2xA401 & X & SL(D)-2xN400 \\
\hline SL(D)-2xA400 & x & SL(D)-2xN400 \\
\hline SL(D)-2xA600 & x & SL(D)-2xN600 \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|}
\hline \multicolumn{3}{|c|}{Reversible Type} \\
\hline Old Model & Compatibility & Current Model \\
\hline SL(D)-2xK21 & x & SL(D)-2xT21 \\
\hline SL(D)-2xK35 & \(\bigcirc\) & SL(D)-2xT35 \\
\hline SL(D)-2xK50 & x & SL(D)-2xT50 \\
\hline SL(D)-2xK65 & \(\bigcirc\) & SL(D)-2xT65 \\
\hline SL(D)-2xK80 & x & SL(D)-2xT80 \\
\hline SL(D)-2xK95 & \(\bigcirc\) & SL(D)-2xT100 \\
\hline SL(D)-2xK100 & \(\bigcirc\) & SL(D)-2xN125 \\
\hline SL(D)-2xK125 & \(\bigcirc\) & SL(D)-2xN125 \\
\hline SL(D)-2xK150 & \(\bigcirc\) & SL(D)-2xN150 \\
\hline SL(D)-2xK220 & \(\bigcirc\) & SL(D)-2xN220 \\
\hline SL(D)-2xK300 & \(\bigcirc\) & SL(D)-2xN300 \\
\hline SL(D)-2xK400 & \(\bigcirc\) & SL(D)-2xN400 \\
\hline SL(D)-2xK600 & \(\bigcirc\) & SL(D)-2xN600 \\
\hline SL(D)-2xK800 & \(\bigcirc\) & SL(D)-2xN800 \\
\hline
\end{tabular}
\begin{tabular}{l|c|c|}
\hline \multicolumn{3}{|c|}{ Reversible Type } \\
\hline Old Model & Compatibility & Current Model \\
\hline SL(D)-2xN21 & \(O\) & SL(D)-2xT21 \\
\hline SL(D)-2xN35 & \(O\) & SL(D)-2xT35 \\
\hline SL(D)-2xN50 & \(x\) & SL(D)-2xT50 \\
\hline SL(D)-2xN65 & \(O\) & SL(D)-2xT65 \\
\hline SL(D)-2xN80 & \(x\) & SL(D)-2xT80 \\
\hline SL(D)-2xN95 & \(O\) & SL(D)-2xT100 \\
\hline
\end{tabular}

\section*{3. Contactor Relays}
(1) Mounting Compatibility of \(\operatorname{SR}(\mathrm{RM})\) Type and current models (SR-K/SR-T)
\begin{tabular}{l|c|c}
\hline \multicolumn{1}{|c|}{ Old Model } & Compatibility & \multicolumn{1}{c}{ Current Model } \\
\hline SR-40(RM) & \(\bigcirc\) & SR-T5 \\
\hline SR-50(RM) & \(\triangle\) & SR-T5 \\
\hline SR-80(RM) & \(\bigcirc\) & SR-T9 \\
\hline SR-63,60(RM) & x & SR-T9 \\
\hline SR-100 & \(\bigcirc\) & SR-K100 \\
\hline
\end{tabular}
(3) Mounting Compatibility of SR-N Type and current models (SR-T)
\begin{tabular}{c|c|c}
\hline Old Model & Compatibility & Current Model \\
\hline SR-N4 & \(\bigcirc\) & SR-T5 \\
\hline SR-N5 & \(\triangle\) & SR-T5 \\
\hline SR-N8 & \(\bigcirc\) & SR-T9 \\
\hline
\end{tabular}
(5) Mounting Compatibility of SRD-K Type and current models (SRD-T)
\begin{tabular}{c|c|c}
\hline Old Model & Compatibility & Current Model \\
\hline SRD-K4 & \(\bigcirc\) & SRD-T5 \\
\hline SRD-K5 & \(\triangle\) & SRD-T5 \\
\hline SRD-K8 & \(\bigcirc\) & SRD-T9 \\
\hline
\end{tabular}
(7) Mounting Compatibility of SRL(D) Type and current models (SRL(D)-K/SRL(D)-N/SRL-T)
\begin{tabular}{l|c|l}
\multicolumn{1}{c}{ Old Model } & Compatibility & \multicolumn{1}{c}{ Current Model } \\
\hline SRL(D)-40(SE) & \(\bigcirc\) & SRL(D)-T5 \\
\hline SRL(D)-50(SE) & \(\triangle(\bigcirc)\) & SRL(D)-T5(SRL(D)-K100) \\
\hline \begin{tabular}{l} 
SRL(D)-100(SE)/ \\
SRL(D)-101
\end{tabular} & \(\bigcirc\) & SRL(D)-K100 \\
\hline
\end{tabular}
(9) Mounting Compatibility of SRL(D)-N and SRL(D)-T Types
\begin{tabular}{c|c|c}
\hline Old Model & Compatibility & Current Model \\
\hline SRL(D)-N4 & O & SRL(D)-T5 \\
\hline
\end{tabular}
(2) Mounting Compatibility of SR-K Type and current models (SR-K/SR-T)
\begin{tabular}{l|c|l}
\hline \multicolumn{1}{|c|}{ Old Model } & Compatibility & \multicolumn{1}{c}{ Current Model } \\
\hline SR-K4 & \(\bigcirc\) & SR-T5 \\
\hline SR-K5 & \(\triangle\) & SR-T5 \\
\hline SR-K8 & \(\bigcirc\) & SR-T9 \\
\hline SR-K63,K6 & x & SR-T9 \\
\hline SR-K10 & \(\bigcirc\) & SR-K100 \\
\hline
\end{tabular}
(4) Mounting Compatibility of SRD Type and current models (SRD-K/SRD-T)
\begin{tabular}{l|c|l}
\hline \multicolumn{1}{|c|}{ Old Model } & Compatibility & \multicolumn{1}{|c}{ Current Model } \\
\hline SRD-40 & \(\bigcirc\) & SRD-T5 \\
\hline SRD-50 & \(\triangle\) & SRD-T5 \\
\hline SRD-80 & \(\bigcirc\) & SRD-T9 \\
\hline SRD-100 & \(\bigcirc\) & SRD-K100 \\
\hline
\end{tabular}
(6) Mounting Compatibility of SRD-N Type and current models (SRD-T)
\begin{tabular}{c|c|c}
\hline Old Model & Compatibility & Current Model \\
\hline SRD-N4 & \(\bigcirc\) & SRD-T5 \\
\hline SRD-N5 & \(\triangle\) & SRD-T5 \\
\hline SRD-N8 & \(\bigcirc\) & SRD-T9 \\
\hline
\end{tabular}
(8) Mounting Compatibility of SRL(D)-K Type and current models (SRL(D)-K/SRL(D)-N/SRL-T)
\begin{tabular}{l|c|c}
\hline \multicolumn{1}{c|}{ Old Model } & Compatibility & \multicolumn{1}{c}{ Current Model } \\
\hline SRL(D)-K4 & \(\bigcirc\) & SRL(D)-T5 \\
\hline SRL(D)-K10 & \(\bigcirc\) & SRL(D)-K100 \\
\hline
\end{tabular}

\section*{13 \\ Supplementary Information}

\subsection*{13.2 Magnetic Starters and Magnetic Contactors New and Old Model Comparison List}

MS-K, MS-N and MS-T Enclosed Magnetic Starters Comparison List (Category AC-3)
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline & \multicolumn{2}{|r|}{Model Name} & MS-K10 & MS-K11 & MS-K12 & MS-K20 & MS-K21 & MS-K25 & MS-K35 & MS-K50 & \\
\hline \multirow{7}{*}{} & \multirow[t]{3}{*}{\begin{tabular}{|c|}
\hline Rated \\
Capacity \\
(kW) \\
AC-3 \\
\hline
\end{tabular}} & 220 to 240 V & 2.5 (2.2) & 3.5 (2.7) & 3.5 (2.7) & 5.5 (4) & 5.5 (4) & 7.5 (5.5) & 11 (7.5) & 15 (11) & \\
\hline & & 380 to 440 V & 4 (2.7) & 5.5 (4) & 5.5 (4) & 11 (7.5) & 11 (7.5) & 15 (11) & 18.5 (15) & 22 (22) & \\
\hline & & 500 V & 4 (2.7) & 5.5 (5.5) & 5.5 (5.5) & 11 (7.5) & 11 (7.5) & 15 (11) & 18.5 (15) & 22 (22) & \\
\hline & \multicolumn{2}{|l|}{Auxiliary Contact Arrangement} & 1 a & 1 a & 1a1b & 1a1b & 2a2b & 2a2b & 2a2b & 2a2b & \\
\hline & Outline & Drawings (mm) & \multicolumn{3}{|c|}{3-M4 Screw Mounting Hole} & \multicolumn{2}{|l|}{3-M5 Screw Mounting Hole} & \multicolumn{2}{|l|}{4-M5 Screw Mounting Hole} & 4-M5 Screw Mounting Hole & \\
\hline & \multicolumn{2}{|r|}{Weight (kg)} & 0.8 & 0.8 & 0.9 & 1.2 & 1.2 & 2.0 & 2.0 & 3.2 & \\
\hline & \multicolumn{2}{|l|}{Mounting Compatibility With MS-T Series} & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & x & \\
\hline \multirow{8}{*}{\[
\begin{aligned}
& \infty \\
& \stackrel{0}{\square} \\
& \infty \\
& \underset{\infty}{\infty} \\
& \sum
\end{aligned}
\]} & \multicolumn{2}{|r|}{Model Name} & MS-N10 & MS-N11 & MS-N12 & MS-N20 & MS-N21 & MS-N25 & MS-N35 & MS-N50 & \\
\hline & \multirow[t]{3}{*}{\begin{tabular}{|c|}
\hline Rated \\
Capacity \\
(kW) \\
AC-3 \\
\hline
\end{tabular}} & 220 to 240 V & 2.5 (2.2) & 3.5 (2.7) & 3.5 (2.7) & 4.5 (4) & 5.5 (4) & 7.5 (5.5) & 11 (7.5) & 15 (11) & \\
\hline & & 380 to 440 V & 4 (2.7) & 5.5 (4) & 5.5 (4) & 7.5 (7.5) & 11 (7.5) & 15 (11) & 18.5 (15) & 22 (22) & \\
\hline & & 500 V & 4 (2.7) & 5.5 (5.5) & 5.5 (5.5) & 7.5 (7.5) & 11 (7.5) & 15 (11) & 18.5 (15) & 25 (22) & \\
\hline & \multicolumn{2}{|l|}{Auxiliary Contact Arrangement} & 1 a & 1a & 1a1b & 1a1b & 2a2b & 2a2b & 2a2b & 2a2b & \\
\hline & \multicolumn{2}{|l|}{Outline Drawings (mm)} & \multicolumn{3}{|c|}{3-M4 Screw Mounting Hole} & \multicolumn{2}{|l|}{3-M5 Screw Mounting Hole} & \multicolumn{2}{|l|}{4-M5 Screw Mounting Hole} & 4-M5 Screw Mounting Hole & \\
\hline & \multicolumn{2}{|r|}{Weight (kg)} & 0.8 & 0.8 & 0.8 & 1.1 & 1.1 & 1.8 & 1.8 & 2.9 & \\
\hline & \multicolumn{2}{|l|}{Mounting Compatibility With MS-T Series} & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & x & \\
\hline \multirow{7}{*}{} & \multicolumn{2}{|r|}{Model Name} & MS-T10 & \multicolumn{2}{|c|}{3 5 (2.7)} & \multicolumn{2}{|c|}{MS-T21} & \multicolumn{2}{|c|}{MS-T35} & MS-T50 & \\
\hline & \multirow[t]{3}{*}{\begin{tabular}{|c|}
\hline Rated \\
Capacity \\
(kW) \\
AC-3
\end{tabular}} & 220 to 240 V & 2.5 (2.2) & & & \multicolumn{2}{|c|}{5.5 (4)} & \multicolumn{2}{|c|}{11 (7.5)} & 15 (11) & \\
\hline & & 380 to 440 V & 4 (2.7) & \multicolumn{2}{|c|}{5.5 (4)} & \multicolumn{2}{|c|}{11 (7.5)} & \multicolumn{2}{|c|}{18.5 (15)} & 22 (22) & \\
\hline & & 500 V & 4 (2.7) & \multicolumn{2}{|c|}{5.5 (5.5)} & \multicolumn{2}{|c|}{11 (7.5)} & \multicolumn{2}{|c|}{18.5 (15)} & 25 (22) & \\
\hline & Auxiliary Con & tact Arrangement & 1 a & \multicolumn{2}{|c|}{1a1b} & \multicolumn{2}{|c|}{2a2b} & \multicolumn{2}{|c|}{2a2b} & 2a2b & \\
\hline & Outline & Drawings (mm) & \multicolumn{3}{|c|}{3-M4 Screw Mounting Hole} & \multicolumn{2}{|l|}{3-M5 Screw Mounting Hole} & \multicolumn{3}{|c|}{4-M5 Screw Mounting Hole} & \\
\hline & Weig & ght (kg) & 0.74 & \multicolumn{2}{|c|}{0.76} & \multicolumn{2}{|c|}{1.12} & \multicolumn{2}{|c|}{1.9} & 1.9 & \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline & MS-K65 & MS-K80 & MS-K95 & MS-K100 & MS-K125 & MS-K150 & MS-K180 & MS-K220 & MS-K300 & MS-K400 \\
\hline & 18.5 (15) & 22 (19) & 30 (22) & 30 (25) & 37 (30) & 45 (37) & 55 (45) & 75 (55) & 90 (75) & 125 (110) \\
\hline & 30 (30) & 45 (37) & 55 (45) & 55 (50) & 60 (60) & 75 (75) & 90 (90) & 132 (110) & 100 (150) & 220 (200) \\
\hline & 30 (30) & 45 (45) & 55 (45) & 55 (55) & 60 (60) & 90 (90) & 110 (110) & 132 (132) & 100 (160) & 220 (200) \\
\hline & 2a2b & 2a2b(4a4b) & 2a2b(4a4b) & \multicolumn{2}{|c|}{2a2b(4a4b)} & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) \\
\hline  & 4.5Sceerl Mowing tob & \multicolumn{2}{|r|}{} & \multicolumn{2}{|l|}{4-M6 Screw Mounting Hole} & \multicolumn{3}{|c|}{AM S Sceen Mounting tole} & \multicolumn{2}{|l|}{4-M10 Screw Mounting Hole} \\
\hline & 3.2 & 4.0 & 4.0 & \multicolumn{2}{|c|}{8} & 12.8 & 16.2 & 16.2 & 28 & 28 \\
\hline & \(\bigcirc\) & x & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) \\
\hline & MS-N65 & MS-N80 & MS-N95 & \multicolumn{2}{|c|}{MS-N125} & MS-N150 & MS-N180 & MS-N220 & MS-N300 & MS-N400 \\
\hline & 16.5 (15) & 22 (19) & 30 (22) & \multicolumn{2}{|c|}{37 (30)} & 45 (37) & 55 (45) & 75 (55) & 90 (75) & 125 (110) \\
\hline & 30 (30) & 45 (37) & 55 (45) & \multicolumn{2}{|c|}{60 (60)} & 75 (75) & 90 (90) & 132 (110) & 160 (150) & 220 (200) \\
\hline & 37 (30) & 45 (45) & 55 (45) & \multicolumn{2}{|c|}{60 (60)} & 90 (90) & 110 (110) & 132 (132) & 160 (160) & 225 (200) \\
\hline & 2a2b & 2a2b(4a4b) & 2a2b(4a4b) & \multicolumn{2}{|c|}{2a2b(4a4b)} & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) \\
\hline  & 4-M5 Screw Mounting Hole & \multicolumn{2}{|r|}{4-M6 Screw Mounting Hole} & \multicolumn{2}{|l|}{4.ME Sceew Mounting Hole} & \multicolumn{3}{|c|}{4-M8 Screw Mounting Hole} & \multicolumn{2}{|l|}{4-M10 Screw Mounting Hole} \\
\hline & 2.9 & 4.0 & 4.0 & 8 & 8 & 12.8 & 16.2 & 16.2 & 27.5 & 28 \\
\hline & \(\bigcirc\) & x & \(\bigcirc\) & \multicolumn{7}{|l|}{} \\
\hline & MS-T65 & MS-T80 & MS-T100 & \multicolumn{7}{|l|}{\multirow[t]{2}{*}{}} \\
\hline & 18.5 (15) & 22 (19) & 30 (22) & & & & & & & \\
\hline & 30 (30) & 45 (37) & 55 (45) & & & & & & & \\
\hline & 37 (30) & 45 (45) & 55 (45) & & & & & & & \\
\hline & 2a2b & 2a2b & & & & & & & & \\
\hline & \multicolumn{2}{|c|}{4-M5 Screw Mounting Hole} & 4-M6 Screw Mounting Hole & & & & & & & \\
\hline & 2.9 & 2.9 & 4.0 & & & & & & & \\
\hline
\end{tabular}

Note 1. The mounting compatibility symbols have the following indications.
\(O\) : Can be directly replaced as an enclosed type
x: Not compatible
Note 2. If replacing the starter or contactor only, consult with your dealer or with us.

MSO-K, MSO-N and MSO-T Non-Enclosed Type Magnetic Starter Comparison List (Category AC-3)



Note 1. The mounting compatibility symbols have the following indications.
O: Compatible
- Can be made compatible by adding an MSO-T/N Series-dedicated adapter (available as a separate part)
\(\diamond\) : Can be made compatible by incorporating an MSO-N Series-dedicated adapter (available as a separate part) into the mounting plate of MSO-A Series *
- : Can be made compatible by directly incorporating MSO-N \(\square\) XA into MSO-A Series
x: Not compatible
* The adapters for S-T12 and SR-T5 can be used only for products where the manufacturing numbers on the front is " 14 Y \(* *\) " or " \(14 Z * *\) ", or products where the first 2 -digit number is equal to or greater than " 15 " (some of those manufactured in October 2014, and those manufactured from November on).
Note 2. Although MSO-N600 is not manufactured, a non-enclosed type magnetic starter can be configured by combining a S-N600 magnetic contactor, TH-N600 thermal overload relay, and current transformer.

\section*{13 \\ Supplementary Information}

S-K, S-N and S-T Magnetic Contactors Comparison List (Category AC-3)

\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline & S-K65 & S-K80 & S-K95 & S-K100 & S-K125 & S-K150 & S-K180 & S-K220 & S-K300 & S-K400 & S-K600 & S-K800 \\
\hline & 65 (65) & 85 (80) & 105 (93) & 105 (100) & 125 (125) & 150 (150) & 180 (180) & 250 (220) & 300 (300) & 400 (400) & 630 (630) & 800 (800) \\
\hline & 62 (62) & 85 (75) & 105 (93) & 105 (100) & 120 (120) & 150 (150) & 180 (180) & 250 (220) & 300 (300) & 400 (400) & 630 (630) & 800 (800) \\
\hline & 45 (45) & 75 (75) & 85 (75) & 85 (80) & 90 (90) & 140 (140) & 180 (180) & 200 (200) & 250 (250) & 350 (350) & 500 (500) & 720 (720) \\
\hline & 100 & 135 & 150 & 150 & 150 & 200 & 260 & 260 & 350 & 450 & 660 & 800 \\
\hline & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b & a4b) & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) \\
\hline &  &  & Mounting Hole &  & \begin{tabular}{l}
unting Hole \\
\(\uparrow\)
\end{tabular} &  &  & \begin{tabular}{l}
Mounting Hole \\
\(\stackrel{+}{+}\)
\end{tabular} &  & \begin{tabular}{l}
Mounting Hole \\
\(\stackrel{?}{\sim}\)
\end{tabular} &  & \begin{tabular}{l}
nting Hole \\
Allows Mounting of 263, Lower 80)
\end{tabular} \\
\hline & M6 & M6 & M6 & & & M8 & M10 & M10 & M12 & M12 & M16 & M16 \\
\hline & 1.25-6 to 22-6 & 1.25-6 to 60-6 & 1.25-6 to 60-6 & 5.5-8 & 60-8 & 8-8 to 100-8 & 14-10 to 150-10 & 14-10 to 150-10 & 22-12 to 200-12 & 22-12 to 200-12 & 80-16 to 325-16 & 80-16 to 325-16 \\
\hline & 1.1 & 1.8 & 1.8 & & & 3.2 & 5.5 & 5.5 & 9.5 & 9.5 & 24 & 24 \\
\hline & \(\bigcirc\) & \(\diamond\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) & \(\bigcirc\) \\
\hline & S-N65 & S-N80 & S-N95 & & & S-N150 & S-N180 & S-N220 & S-N300 & S-N400 & S-N600 & S-N800 \\
\hline & 65 (65) & 85 (80) & 105 (100) & 125 & (25) & 150 (150) & 180 (180) & 250 (220) & 300 (300) & 400 (400) & 630 (630) & 800 (800) \\
\hline & 65 (65) & 85 (80) & 105 (93) & 120 & 20) & 150 (150) & 180 (180) & 250 (220) & 300 (300) & 400 (400) & 630 (630) & 800 (800) \\
\hline & 60 (45) & 75 (75) & 85 (75) & & & 140 (140) & 180 (180) & 200 (200) & 250 (250) & 350 (350) & 500 (500) & 720 (720) \\
\hline & 100 & 135 & 150 & & & 200 & 260 & 260 & 350 & 450 & 660 & 800 \\
\hline & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b & a4b) & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) \\
\hline &  & \(\xrightarrow{2 \text { 2.MS Scere Ma }}\) &  &  & ounting Hole &  &  & Mounting Hole &  & \begin{tabular}{l}
Mounting Hole \\
g
\end{tabular} &  & \begin{tabular}{l}
Mounting Hole \\
unting of wer 80) \(\times 275\)
\end{tabular} \\
\hline & M6 & M6 & M6 & & & M8 & M10 & M10 & M12 & M12 & M16 & M16 \\
\hline & 1.25-6 to 22-6 & 1.25-6 to 60-6 & 1.25-6 to 60-6 & 5.5-8 & 60-8 & 8-8 to 100-8 & 14-10 to 150-10 & 14-10 to 150-10 & 22-12 to 200-12 & 22-12 to 200-12 & 80-16 to 325-16 & 80-16 to 325-16 \\
\hline & 0.75 & 1.7 & 1.7 & & & 3.3 & 5.5 & 5.5 & 9.0 & 9.5 & 24 & 24 \\
\hline & \(\bigcirc\) & \(\diamond\) & \(\bigcirc\) & & & & & & & & & \\
\hline & S-T65 & S-T80 & S-T100 & & & & & & & & & \\
\hline & 65 (65) & 85 (80) & 105 (100) & & & & & & & & & \\
\hline & 65 (65) & 85 (80) & 105 (93) & & & & & & & & & \\
\hline & 60 (45) & 75 (75) & 85 (75) & & & & & & & & & \\
\hline & 100 & 120 & 150 & & & & & & & & & \\
\hline & 2a2b(4a4b) & 2a2b(4a4b) & 2a2b(4a4b) & & & & & & & & & \\
\hline & \multicolumn{2}{|l|}{2-M4 Screw Mounting Hole} &  & & & & & & & & & \\
\hline & \multicolumn{2}{|l|}{M6} & M6 & & & & & & & & & \\
\hline & \multicolumn{2}{|l|}{1.25-6 to 22-6, 38-S6, 60-S6} & 1.25-6 to 60-6 & & & & & & & & & \\
\hline & 0.75 & 0.75 & 1.7 & & & & & & & & & \\
\hline
\end{tabular}

Note 1 . The mounting compatibility symbols have the following indications.
O: Compatible
- \(\mathrm{S}-\mathrm{N} \square \mathrm{XA}\) can be replaced as is
\(\diamond\) : Can be made compatible by adding an S-T/N Series-dedicated adapter (available as a separate part) *
x : Not compatible
* The adapters for S-T12 and SR-T5 can be used only for products where the manufacturing numbers on the front is "14Y \(* *\) " or " \(14 Z * *\) ", or products where the first 2 -digit number is equal to or greater than " 15 " (some of those manufactured in October 2014, and those manufactured from November on).

\subsection*{13.3 Compatibility of New and Old Thermal Overload Relays and Magnetic Contactors When Used In Combination}

\subsection*{13.3.1 Compatibility of New (MS-T Series) and Old (MS-N Series) When Used In Combination}

Whether or not each thermal overload relay and magnetic contactor from the MS-T/MS-N Series can be combined is shown in the table below.
(1) Mounting Compatibility of MS-N Series Magnetic Contactors and MS-T Series Thermal Overload Relays
\begin{tabular}{l|l|c|l}
\hline \multicolumn{1}{c|}{ Magnetic Contactors } & Thermal Overload Relays & Compatibility & \\
\hline S-N10 & TH-T18(KP) & None & (The mounting portion of the thermal overload relay does not match) \\
\hline S-N11/SD-N11 & TH-T18(KP) & None & (The mounting portion of the thermal overload relay does not match) \\
\hline S-N12/SD-N12 & TH-T18(KP) & None & (The mounting portion of the thermal overload relay does not match) \\
\hline S-N20 & TH-T25(KP) & None & (The mounting portion of the thermal overload relay does not match) \\
\hline S-N21/SD-N21 & TH-T25(KP) & None & (The mounting portion of the thermal overload relay does not match) \\
\hline S-N25 & TH-T25(KP) & None & (The mounting portion of the thermal overload relay does not match) \\
\hline S-N35/SD-N35 & TH-T25(KP)/T50(KP) & None & (The mounting portion of the thermal overload relay does not match) \\
\hline S-N50/SD-N50 & TH-T65(KP) & Yes Note1 & Can be combined using the MSO(D)-N50/N65 connecting conductors and mounting brackets. \\
\hline S-N65/SD-N65 & TH-T65(KP) & Yes & Can be combined using the MSO(D)-N50/N65 connecting conductors and mounting brackets. \\
\hline S-N80 & TH-T65(KP)/T100(KP) & Yes & Can be combined using the MSO-N80/N95 connecting conductors and mounting brackets. \\
\hline SD-N80 & TH-T65(KP)/T100(KP) & Yes & Can be combined using the MSOD-N80/N95 connecting conductors and mounting brackets. \\
\hline S-N95 & TH-T65(KP)/T100(KP) & Yes & Can be combined using the MSO-N80/N95 connecting conductors and mounting brackets. \\
\hline SD-N95 & TH-T65(KP)/T100(KP) & Yes & Can be combined using the MSOD-N80/N95 connecting conductors and mounting brackets. \\
\hline
\end{tabular}

Note 1.Cannot be combined with TH-T25(KP)/T50(KP).
(2) Mounting Compatibility of MS-T Series Magnetic Contactors and MS-N Series Thermal Overload Relays
\begin{tabular}{l|l|c|l}
\hline \multicolumn{1}{c|}{ Magnetic Contactors } & Thermal Overload Relays & Compatibility & \multicolumn{1}{c}{ Combination Method } \\
\hline S-T10 & TH-N12(KP) & None & (The mounting portion of the thermal overload relay does not match) \\
\hline S-T12/SD-T12 & TH-N12(KP) & None & (The mounting portion of the thermal overload relay does not match) \\
\hline S-T20/SD-T20 & TH-N20(KP) & None & (Different outline drawings) \\
\hline S-T21/SD-T21 & TH-N20(KP) & None & (The mounting portion of the thermal overload relay does not match) \\
\hline S-T25 & TH-N20(TA)(KP) & None & (The mounting portion of the thermal overload relay does not match) \\
\hline S-T35/SD-T35 & TH-N20(TA)(KP) & None & (The mounting portion of the thermal overload relay does not match) \\
\hline S-T50/SD-T50 & TH-N60(KP) & None & (Different outline drawings) \\
\hline S-T65/SD-T65 & TH-N60(KP) & Yes & Can be combined using the MSO(D)-N50/N65 connecting conductors and mounting brackets. \\
\hline S-T80/SD-T80 & TH-N60(TA)(KP) & Yes \({ }^{\text {Note2 }}\) & Can be combined using the MSO(D)-N50/N65 connecting conductors and mounting brackets. \\
\hline S-T100 & TH-N60(TA)(KP) & Yes & Can be combined using the MSO-N80/N95 connecting conductors and mounting brackets. \\
\hline SD-T100 & TH-N60(TA)(KP) & Yes & Can be combined using the MSOD-N80/N95 connecting conductors and mounting brackets. \\
\hline
\end{tabular}

Note 2. Cannot be combined using the MSO-N80/N95 or MSOD-N80/N95 connecting conductors and mounting brackets.
Note 3. If connecting conductors and mounting brackets are required, optional connecting conductor kits are also available.
- For S(D)-T65/T80 Frame (AC/DC Operation) : BH559N350
- For S-T100 Frame (AC Operation) : BH569N350
- For SD-T100 Frame (DC Operation) : BH569N352

\subsection*{13.3.2 Compatibility of New (MS-N series) and Old (MS-K series) When Used In Combination}

Whether or not each thermal overload relay and magnetic contactor from the MS-N/MS-K Series can be combined is shown in the table below.
(1) Mounting Compatibility of MS-K Series Magnetic Contactors and MS-N Series Thermal Overload Relays
\begin{tabular}{l|l|c|l}
\hline \multicolumn{1}{c|}{ Magnetic Contactors } & Thermal Overload Relays & Compatibility & \multicolumn{1}{c}{ Combination Method } \\
\hline \begin{tabular}{l} 
S-K125,K150 \\
SD-K125,K150
\end{tabular} & TH-N120(TA)(KP) & Yes & \begin{tabular}{l} 
Can be combined using the K Series connecting conductors and mounting brackets. \\
(Note 1)
\end{tabular} \\
\hline \begin{tabular}{l} 
S-K180/K220 \\
SD-K220
\end{tabular} & TH-N220RH(KP) & Yes & Use the screws that come with the thermal overload relay. \\
\hline \begin{tabular}{l} 
S-K300/K400 \\
SD-K300/K400
\end{tabular} & TH-N400RH(KP) & Yes & Use the screws that come with the thermal overload relay. \\
\hline
\end{tabular}
(2) Mounting Compatibility of MS-N Series Magnetic Contactors and MS-K Series Thermal Overload Relays
\begin{tabular}{l|l|c|l}
\hline \multicolumn{1}{c|}{ Magnetic Contactors } & Thermal Overload Relays & Compatibility & \multicolumn{1}{c}{ Combination Method } \\
\hline \begin{tabular}{l} 
S-N125,N150 \\
SD-N125,N150
\end{tabular} & TH-K120(TA)(KP) & Yes & \begin{tabular}{l} 
Can be combined using the K Series connecting conductors and mounting brackets. \\
(Note 1)
\end{tabular} \\
\hline \begin{tabular}{l} 
S-N180/N220 \\
SD-N220
\end{tabular} & TH-K220RH(KP) & Yes & Use the screws fixing the currently attached thermal overload relay. \\
\hline \begin{tabular}{l} 
S-N300/N400 \\
SD-N300/N400
\end{tabular} & TH-K400RH(KP) & Yes & Use the screws fixing the currently attached thermal overload relay. \\
\hline
\end{tabular}

Note 1. If connecting conductors and mounting brackets are required, optional connecting conductor kits are also available.

\subsection*{13.4 Compatibility of New and Old Optional Units When Used In Combination}

\subsection*{13.4.1 Compatibility of New (MS-T Series) and Old (MS-N Series) When Used In Combination}

The combinability of MS-T/MS-N Series optional units, magnetic contactors, contactor relays, and thermal overload relays is shown in the following table. For more information on the optional units, refer to page 191.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Product Name} & \multicolumn{4}{|c|}{MS-T Series} & \multicolumn{4}{|c|}{MS-N Series} \\
\hline & \multirow[t]{2}{*}{Unit Model Name} & \multicolumn{3}{|c|}{Application to MS-N Series} & \multirow[t]{2}{*}{Unit Model Name} & \multicolumn{3}{|c|}{Application to MS-T Series} \\
\hline & & AC Operated & DC Operated & Mechanicall Latched Type & & AC Operated & DC Operated & Mechanically Latched Type \\
\hline \multirow{3}{*}{Auxiliary Contacts} & UT-AX2,AX4 & x & x & x & UN-AX2,AX4 & S-T65, 880 & SD-T65, T80 & x \\
\hline & UT-AX11 & x & x & x & UN-AX11 & S-T65, T80 & SD-T65, T80 & SL(D)-T65, 880 \\
\hline & & & & & UN-AX80 & S-T100 & SD-T100 & SL(D)-T100 \\
\hline \multirow{3}{*}{Mechanical Interlocks} & & & & & UN-ML11 & x & x & x \\
\hline & UT-ML20 & x & x & x & UN-ML21 & S-T21 to T80 & SD-T21 to T80 & SL(D)-T21 to T80 \\
\hline & & & & & UN-ML80 & S-T100 & SD-T100 & SL(D)-T100 \\
\hline \multirow{11}{*}{Surge Absorbers for Operation Coils} & UT-SA13 & x & \multirow{3}{*}{SRD-N4,N5,N8 SD-N11 to N35} & \multirow{5}{*}{SRL(D)-N4 Closing Coil SL(D)-N21 Closing Coil} & UN-SA13 & x & x & x \\
\hline & UT-SA21 & \multirow{4}{*}{SR-N4,N5,N8 S-N10 to N35 S-N38,N48} & & & UN-SA21 & x & \(x\) & x \\
\hline & UT-SA22 & & & & UN-SA22 & x & x & x \\
\hline & UT-SA23 & & x & & UN-SA23 & x & x & x \\
\hline & UT-SA25 & & SRD-N4,N5,N8 SD-N11 to N35 & & UN-SA25 & x & x & x \\
\hline & & & & & UN-SA721 & \(x\) & SD-T65, T80 & SL(D)-T21 to T80*1 \\
\hline & & & & & UN-SA712 & x & x & SL(D)-T21 to T50*1 \\
\hline & & & & & UN-SA722 & x & SD-T65, T80 & SL(D)-T65, T80*1 \\
\hline & & & & & UN-SA713 & x & SD-T65, T80 & SLD-T21 to T80*1 \\
\hline & & & & & UN-SA723 & x & x & SL-T21 to T80*1 \\
\hline & & & & & UN-SA725 & x & SD-T65, T80 & SL(D)-T21 to T80*1 \\
\hline \multirow{3}{*}{Surge Absorbers for Main Circuits} & UT-SA3320 & x & x & x & UN-SA3310 & x & x & x \\
\hline & UT-SA3332 & x & x & x & UN-SA3320 & x & \(\times\) & x \\
\hline & & & & & UN-SA33 & S-T10 to T100 & SD-T12 to T100 & SL(D)-T21 to T100 \\
\hline \multirow{6}{*}{DC/AC Interfaces for Operation Coil} & & & & & UN-SY11 & S-T10 to T100 & x & - \\
\hline & & & & & UN-SY12 & S-T10 to T100 & x & x \\
\hline & UT-SY21 & \(x\) & \(x\) & x & UN-SY21(CX) & x & x & x \\
\hline & UT-SY22 & x & \(\times\) & x & UN-SY22(CX) & x & x & x \\
\hline & & & & & UN-SY31 & S-T65, T80 & x & x \\
\hline & & & & & UN-SY32 & S-T65, T80 & x & x \\
\hline \multirow[t]{2}{*}{Live Part Protection Covers} & UT-CW800 & S-N50,N65 & SD-N50,N65 & x & & & & \\
\hline & UT-CW655 & \multicolumn{3}{|c|}{TH-N60} & UN-CZロ & S-T65 to T100 & SD-T65 to T100 & SL(D)-T65 to T100 \\
\hline Manal Opeation Perenerion Covers & UT-CV107 & x & x & x & UN-CV117 & x & x & x \\
\hline \multirow{6}{*}{Main Circuit Conductor Kits (For Reversing)} & UT-SD10 & x & x & x & UN-SD10CX & x & x & x \\
\hline & UT-SD20 & x & x & x & UN-SD21CX & x & \(\times\) & x \\
\hline & & & & & UN-SD18CX & S-2xT32 & SD-2xT32 & x \\
\hline & UT-SD25 & x & x & x & UN-SD25CX & S-2xT35, T50 & SD-2xT35, T50 & SL(D)-2xT35, T50 \\
\hline & & & & & UN-SD50 & S-2xT65, T80 & SD-2xT65, T80 & SL(D)-2xT65, T80 \\
\hline & & & & & UN-SD80 & S-2xT100 & SD-2xT100 & SL(D)-2xT100 \\
\hline \multirow{6}{*}{Main Circuit Conductor Kits (For Crossover)} & UT-SG10 & x & x & x & UN-SG10CX & x & x & x \\
\hline & UT-SG20 & x & x & x & UN-SG21CX & x & x & x \\
\hline & & & & & UN-SG18CX & S-2xT32 & SD-2xT32 & x \\
\hline & UT-SG25 & x & x & \(x\) & UN-SG25CX & S-2xT35, T50 & SD-2xT35, T50 & SL(D)-2xT35, T50 \\
\hline & & & & & UN-SG50 & S-2xT65, T80 & SD-2xT65,T80 & SL(D)-2xT65, T80 \\
\hline & & & & & UN-SG80 & S-2xT100 & SD-2xT100 & SL(D)-2xT100 \\
\hline Main Circuit Conductor Kits (For 3-Pole Short-Circuit) & & & & & UN-YG21 to YG80 & S-T21 to T100 & SD-T21 to T100 & SL(D)-T21 to T100 \\
\hline Main Circuit Conductor Kits (For 2-Pole Short-Circuit) & UT-YD20 & SR-N4,N5,N8 S-N10 to N12 & \[
\begin{aligned}
& \text { SRD-N4,N5,N8 } \\
& \text { SD-N11,N12 }
\end{aligned}
\] & SRL(D)-N4 & UN-YD21 to YD80 & S-T21 to T100 & SD-T21 to T100 & SL(D)-T21 to T100 \\
\hline \multirow{4}{*}{3-Pole Array Connection Units} & UT-YY20 & x & x & x & UN-YY21 & S-T21 & SD-T21 & SL(D)-T21 \\
\hline & & & & & UN-YY35 & S-T35, T50 & SD-T35, T50 & SL(D)-T35, T50 \\
\hline & & & & & UN-YY50 & S-T65, T80 & SD-T65, T80 & SL(D)-T65, 880 \\
\hline & & & & & UN-YY80 & S-T100 & SD-T100 & SL(D)-T100 \\
\hline \multirow[t]{2}{*}{Thermal Overload Relay Misoperation Prevention Covers} & & & & & UN-CV203 & \multicolumn{3}{|c|}{TH-T25, T50} \\
\hline & & & & & UN-CV603 & & TH-T65, T100 & \\
\hline \multirow{3}{*}{Thermal Overload Relays Reset Releases} & \[
\begin{aligned}
& \hline \text { UT-RR204 } \\
& \text { to RR704 }
\end{aligned}
\] & \multicolumn{3}{|c|}{\(\times\)} & \[
\begin{array}{|l|}
\hline \text { UN-RR205 } \\
\text { to RR705 }
\end{array}
\] & \multicolumn{3}{|c|}{x} \\
\hline & & & & & \[
\begin{array}{|l|}
\hline \text { UN-RR200 } \\
\text { to RR700 } \\
\hline
\end{array}
\] & \multicolumn{3}{|c|}{TH-T25, T50} \\
\hline & & & & & UN-RR206 to RR706 & \multicolumn{3}{|c|}{TH-T65, T100} \\
\hline \multirow[t]{3}{*}{Thermal Overload Relays Fluorescent Display Lamps} & & & & & UN-TL12 & \multicolumn{3}{|c|}{TH-T18} \\
\hline & & & & & UN-TL20 & \multicolumn{3}{|c|}{TH-T25, T50} \\
\hline & & & & & UN-TL60 & \multicolumn{3}{|c|}{TH-T65, T100} \\
\hline \multirow[t]{2}{*}{Thermal Overload Relays With Independent Mounting} & UT-HZ18 & \multicolumn{3}{|c|}{\multirow[t]{2}{*}{x}} & UN-HZ12 & \multicolumn{3}{|c|}{\(\times\)} \\
\hline & & & & & UN-RM20 & \multicolumn{3}{|c|}{TH-T25} \\
\hline
\end{tabular}

Note 1. x indicates inapplicability.
Note 2. \(* 1\) can be applied to the tripping coil.

\section*{13 Supplementary Information}

\subsection*{13.4.2 Compatibility of New (MS-N series) and Old (MS-K series) When Used In Combination}

The combinability of MS-N/MS-K Series optional units, magnetic contactors, contactor relays, and thermal overload relays is shown in the following table. For more information on the optional units, refer to page 191.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline \multirow{3}{*}{Product Name} & \multicolumn{4}{|c|}{MS-N Series} & \multicolumn{4}{|c|}{MS-K Series} \\
\hline & \multirow{2}{*}{Unit Model Name} & \multicolumn{3}{|c|}{Application to MS-K Series} & \multirow[b]{2}{*}{Unit Model Name} & \multicolumn{3}{|c|}{Application to MS-N Series} \\
\hline & & AC Operated & DC Operated & Mechanically Lathed Type & & AC Operated & DC Operated & Mechanically Lathed Type \\
\hline \multirow{3}{*}{Auxiliary Contacts} & UN-AX80 & S-K125 & SD-K125 & SL(D)-K125 & UA-AX80 & S-N125 & SD-N125 & SL(D)-N125 \\
\hline & UN-AX150 & S-K150 to K400 & SD-K150 to K400 & SL(D)-K150 to K400 & UA-AX150 & S-N150 to N400 & SD-N150 to N400 & SL(D)-N150 to N400 \\
\hline & UN-AX600 & S-K600,K800 & SD-K600,K800 & SL(D)-K600,K800 & UA-AX600 & S-N600,N800 & SD-N600,N800 & SL(D)-N600,N800 \\
\hline \multirow{3}{*}{Mechanical Interlocks} & UN-ML80 & S-K125 & SD-K125 & SL(D)-K125 & UA-ML80 & S-N125 & SD-N125 & SL(D)-N125 \\
\hline & UN-ML150 & S-K150 & SD-K150 & SL(D)-K150 & UA-ML150 & S-N150 & SD-N150 & SL(D)-N150 \\
\hline & UN-ML220 & S-K180 to K400 & SD-K220 to K400 & SL(D)-K220 to K400 & UA-ML220 & S-N180 to N400 & SD-N220 to N400 & SL(D)-N220 to N400 \\
\hline Surge Absorbers for Man Circuits & UN-SA33 & S-K125 to K800 & SD-K125 to K800 & SL(D)-K125 to K800 & UA-SA33 & S-N125 to N800 & SD-N125 to N800 & SL(D)-N125 to N800 \\
\hline \multirow[t]{2}{*}{DC/AC Interfaces for Operation Coil} & UN-SY11 & S-K125 to K400 & - & - & UA-SY11 & S-N125 to N400 & - & - \\
\hline & UN-SY12 & S-K125 to K400 & - & - & UA-SY12 & S-N125 to N400 & - & - \\
\hline Main Circuit Conductor Kits (For Reversing) & \[
\begin{array}{|l|l|}
\hline \text { UN-SD80 } \\
\text { to SD600 }
\end{array}
\] & \[
\begin{array}{|l}
\hline \text { S-2xK125 } \\
\text { to K800 }
\end{array}
\] & \[
\begin{array}{|l}
\hline \text { SD-2xK125 } \\
\text { to K800 }
\end{array}
\] & \[
\begin{array}{|l}
\hline \text { SL(D)-2xK125 } \\
\text { to K800 }
\end{array}
\] & \[
\begin{aligned}
& \text { UA-SD80 } \\
& \text { to SD600 }
\end{aligned}
\] & \[
\begin{array}{|l}
\hline \text { S-2xN125 } \\
\text { to N800 }
\end{array}
\] & \[
\begin{array}{|l}
\hline \text { SD-2xN125 } \\
\text { to N800 }
\end{array}
\] & \[
\begin{aligned}
& \text { SL(D)-2xN125 } \\
& \text { to N800 }
\end{aligned}
\] \\
\hline Main Circuit Conductor Kits (For Crossover) & UN-SG80 to SG600 & \begin{tabular}{l}
S-2xK125 \\
to K800
\end{tabular} & \[
\begin{aligned}
& \hline \text { SD-2xK125 } \\
& \text { to K800 }
\end{aligned}
\] & SL(D)-2xK125
to K800 & UA-SG80 & \begin{tabular}{l}
S-2xN125 \\
to N800
\end{tabular} & \[
\begin{array}{|l}
\hline \text { SD-2xN125 } \\
\text { to N800 }
\end{array}
\] & SL(D)-2xN125
to N800 \\
\hline Main Circuit Conductor Kits (For 3-Pole Short-Circuit) & UN-YG21 to YG300 & S-K125 to K400 & SD-K125 to K400 & SL(D)-K125 to K400 & UA-YG21
to YG300 & S-N125 to N400 & SD-N125 to N400 & SL(D)-N125 to N400 \\
\hline Main Circuit Conductor Kits (For 2-Pole Short-Circuit) & UN-YD11 to YD300 & S-K125 to K400 & SD-K125 to K400 & SL(D)-K125 to K400 & UA-YD11 to YD300 & S-N125 to N400 & SD-N125 to N400 & SL(D)-N125 to N400 \\
\hline \multirow[t]{2}{*}{Thermal Overload Relays Misoperation Prevention Covers} & UN-CV203 & \multicolumn{3}{|c|}{x} & UA-CV203 & \multicolumn{3}{|c|}{TH-N120 to N600} \\
\hline & UN-CV603 & \multicolumn{3}{|c|}{TH-K120 to K600} & & & & \\
\hline \multirow[t]{2}{*}{Thermal Overload Relays Reset Releases} & UN-RR200 to RR700 & \multicolumn{3}{|c|}{\(x\)} & UA-RR200 to RR700 & \multicolumn{3}{|c|}{TH-N120 to N600} \\
\hline & \[
\begin{array}{|l}
\text { UN-RR206 } \\
\text { to RR706 }
\end{array}
\] & \multicolumn{3}{|c|}{TH-K120 to K600} & & & & \\
\hline \multirow[t]{2}{*}{Thermal Overload Relays Fluorescent Display Lamps} & UN-TL20 & \multicolumn{3}{|c|}{x} & UA-TL20 & \multicolumn{3}{|c|}{TH-N120 to N600} \\
\hline & UN-TL60 & \multicolumn{3}{|c|}{TH-K120 to K600} & & & & \\
\hline
\end{tabular}

Note 1. x indicates inapplicability.
Note 2. \(* 1\) can be applied to the tripping coil.

\subsection*{13.5 MS-T Series Changes}

The main contents of what has been changed from MS-T Series to MS-N Series are summarized.
For more information regarding mounting compatibility, refer to the following. It is to be noted that components such as contacts and operation coils are for respective series only, and have no compatibility.
- Magnetic Starters and Magnetic Contactors Page 376 (for contactor relays, T5/T9 is similarly compatible with magnetic contactor T12.)

\section*{Product Marking}
(1) Terminal Number
\begin{tabular}{|c|c|c|c|c|c|}
\hline & Item & MS-T Target Model Names (Typical Model) & MS-T Series & MS-N Series & Remarks \\
\hline \multirow{4}{*}{} & \begin{tabular}{l}
Auxiliary \\
Terminal \\
Number \\
(Magnetic \\
Contactor)
\end{tabular} &  & \begin{tabular}{l}
Make Contacts: 13NO-14NO \\
Break Contacts: 21NC-22NC \\
Make Contacts: \(13 \mathrm{NO}-14 \mathrm{NO}\) \\
43NO-44NO \\
Break Contacts: 21NC-22NC 31NC- \\
32NC \\
Make Contacts: \(13 \mathrm{NO}-14 \mathrm{NO}\) \\
43NO-44NO \\
Break Contacts: 21NC-22NC 31NC- \\
32NC
\end{tabular} & \begin{tabular}{l}
Make Contacts: 13NO-14NO \\
Break Contacts: 21NC-22NC \\
Make Contacts: 13 (13) NO-14 (14) NO \\
43 (23) NO-44 (24) NO \\
Break Contacts: 21 (31) NC-22 (32) NC \\
31 (41) NC-32 (42) NC
\end{tabular} & \begin{tabular}{l}
NO (Normally \\
Open): Make Contact \\
NC (Normally \\
Closed): Break Contact
\end{tabular} \\
\hline & Auxiliary Terminal Number (Contactor Relay) & \[
\begin{aligned}
& \text { SR-T5 } \\
& \text { SRD-T5 }
\end{aligned}
\] & \begin{tabular}{l}
- Ones Place of the Number for \\
Make Contacts: 3-4 \\
Break Contacts: 1-2 \\
- Tens Place of the Number Changes to 1 to 5 \\
E.g.: SR-T5 3a2b \\
A2 Al 11 NC 23NO 33 NO 43NO 51NC
\end{tabular} & \begin{tabular}{l}
- Ones Place of the Number for Make Contacts: 3-4 \\
Break Contacts: 1-2 \\
-Tens Place of the Number Changes to 0 to 4 \\
E.g.: SR-N5 3a2b \\
A2 Al 01NC 13NO 23NO 33No 4inc
\end{tabular} & Complies With the International Standards IEC \\
\hline & & \[
\begin{gathered}
\text { SR-T9 } \\
\text { SRD-T9 }
\end{gathered}
\] & \begin{tabular}{l}
- Ones Place of the Number for \\
Make Contacts: 3-4, \\
Break Contacts: 1-2 \\
- Tens Place of the Number \\
Changes to 1 to 9 \\
Example: SR-T9 5a4b \\
64NO 72NC 82NC 94NO
\end{tabular} & \begin{tabular}{l}
- Ones Place of the Number for \\
Make Contacts: 3-4 \\
Break Contacts: 1-2 \\
- Tens Place of the Number Changes to \\
1 to 8 \\
E.g.: SR-N8 5a3b \\
53NO 6INC 73NO 83NO \\
A. Al 13no 21nc 31No 43no
\end{tabular} & \\
\hline & Coil Terminal Number & \begin{tabular}{c} 
S-T10 to T35 \\
SD-T12 to T35 \\
\hdashline S-T50 to T100 \\
SD-T50 to T100
\end{tabular} & \begin{tabular}{l}
A1, A2 \\
(Embossed Characters) \\
A1, A2 \\
(Embossed Characters)
\end{tabular} & \begin{tabular}{l}
A1, A2 \\
(Simultaneous Printing With Rated Coil Display) \\
A1, A2 \\
(Embossed Characters)
\end{tabular} & \\
\hline
\end{tabular}

\section*{13 Supplementary Information}
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Item} & MS-T Target Model Names (Typical Model) & MS-T Series & MS-N Series & Remarks \\
\hline \multirow{3}{*}{} & \multirow[t]{3}{*}{\begin{tabular}{l}
Auxiliary \\
Terminal Number (Auxiliary Contact Unit)
\end{tabular}} & UT-AX11 & \begin{tabular}{l}
- Ones Place of the Number for \\
Make Contacts: 3-4 \\
Break Contacts: 1-2 \\
- Tens Place of the Number Changes to 6 to 7 \\
E.g.: UT-AX11 1a1b \\
(When mounted on the left side of the body)
\end{tabular} & \begin{tabular}{l}
- Ones Place of the Number for \\
Make Contacts: 3-4 \\
Break Contacts: 1-2 \\
- Tens Place of the Number Changes to 5 to 6 \\
E.g.: UN-AX11 1a1b \\
(When mounted on the left side of the body)
\end{tabular} & \\
\hline & & UT-AX2 & \begin{tabular}{l}
- Ones Place of the Number for \\
Make Contacts: 3-4 \\
Break Contacts: 1-2 \\
- Tens Place of the Number Changes to 6 to 7 \\
E.g.: UT-AX2 1a1b
\end{tabular} & \begin{tabular}{l}
- Ones Place of the Number for \\
Make Contacts: 3-4 \\
Break Contacts: 1-2 \\
- Tens Place of the Number Changes to 5 to 6 \\
E.g.: UN-AX2 1a1b
\end{tabular} & \\
\hline & & UT-AX4 & \begin{tabular}{l}
- Ones Place of the Number for \\
Make Contacts: 3-4 \\
Break Contacts: 1-2 \\
- Tens Place of the Number Changes to 6 to 9 \\
E.g.: UT-AX4 2a2b \\
63NO 71NC 81NC 93NO \\
64 NO 72 NC 82NC 94NO
\end{tabular} & \begin{tabular}{l}
- Ones Place of the Number for \\
Make Contacts: 3-4 \\
Break Contacts: 1-2 \\
- Tens Place of the Number Changes to 5 to 8 \\
E.g.: UN-AX4 2a2b \\
53NO 61NC 71NC 83NO \\
54NO 62NC 72NC 84NO
\end{tabular} & \\
\hline \multirow{5}{*}{} & \multirow[t]{5}{*}{Terminal Number} & S-T10 to T20
SD-T12 to T20
SR-T5/T9
SRD-T5/T9
UT-AX2, AX4 & - Laser printed on the product front for both the body and auxiliary contact unit & For the body (lower part of SR-N8), printed on the product front in blue For the upper part of SR-N8 (auxiliary contact unit), the terminal number is printed on the paper name plate in blue & \\
\hline & & UT-AX11 & - The terminal number is printed on a paper name plate on the product front & The terminal number is printed on the paper name plate in blue & \\
\hline & & \[
\begin{aligned}
& \text { S-T21 to T35 } \\
& \text { SD-T21 to T35 }
\end{aligned}
\] & Laser printed on the front of the product & Printed on the front of the product in blue & \\
\hline & & \[
\begin{aligned}
& \text { S-T50 } \\
& \text { SD-T50 }
\end{aligned}
\] & Laser printed on the front of the product & Printed on the name plate on the product front in blue & \\
\hline & & \[
\begin{aligned}
& \text { S-T65 to T100 } \\
& \text { SD-T65 to T100 }
\end{aligned}
\] & Printed on the name plate on the product front in gray & Printed on the name plate on the product front in blue & \\
\hline
\end{tabular}
(2) Rating
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Item} & \begin{tabular}{|c|}
\hline MS-T Target Model \\
Names (Typical Model)
\end{tabular} & MS-T Series & MS-N Series & Remarks \\
\hline \multirow{7}{*}{} & \multirow[t]{3}{*}{Main Circuit Rating} & S-T10 to T35
SD-T12 to T35
SR-T5, T9
SRD-T5, T9 & All laser printed on the side & \begin{tabular}{l}
- The Ith rating \((A)\) is printed on the front bottom left \\
- Other ratings are displayed on a name plate on the side
\end{tabular} & \\
\hline & & \[
\begin{aligned}
& \text { S-T50 } \\
& \text { SD-T50 }
\end{aligned}
\] & Laser printed on the side & Printed on the name plate on the front in gray & \\
\hline & & \[
\begin{aligned}
& \text { S-T-65 to T100 } \\
& \text { SD-T65 to T100 }
\end{aligned}
\] & Printed on the name plate on the front in gray & Printed on the name plate on the front in gray & \\
\hline & Coil Rating & S-T10 to T35
SD-T12 to T35
SR-T5, T9
SRD-T5, T9 & All laser printed (No color-coding) & \begin{tabular}{l}
- The designation AC100V/200V has all rated ranges color-coded (between the power supply side coil terminals)
\[
\begin{array}{ll}
100 \mathrm{~V} & 50 \mathrm{~Hz} \\
100 \text { to } 110 \mathrm{~V} & 60 \mathrm{~Hz} \\
200 \mathrm{~V} & 50 \mathrm{~Hz}
\end{array}
\] \\
- Other ratings have all rated ranges printed on a name plate in white - SD and SRD are printed in black on blue
\end{tabular} & \\
\hline & & S-T50
SD-T50 & All laser printed (No color-coding) & - The designation AC100V/200V is printed in black on color-coded nameplates & \\
\hline & & \[
\begin{aligned}
& \text { S-T65 to T100 } \\
& \text { SD-T-65 to T100 }
\end{aligned}
\] & All printed in black on white nameplates & \begin{tabular}{l}
Other ratings are printed in black on white nameplates \\
- SD is printed in black on blue
\end{tabular} & \\
\hline & Coil Polarity (+ -) & \[
\begin{gathered}
\text { SD-T12 to T32 } \\
\text { SRD-T5, T9 }
\end{gathered}
\] & Laser printed between the coil terminals & (no marking as it has no polarity) & \\
\hline
\end{tabular}
(3) Model Names
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Item} & MS-T Target Model Names (Typical Model) & MS-T Series & MS-N Series & Remarks \\
\hline \multirow{4}{*}{} & \multirow[t]{4}{*}{Model Name} & S-T10 to T35 SD-T12 to T35 SR-T5, T9 SRD-T5, T9 UT-AX2, AX4 & Laser printed on the product front left & Printed on the front left center of the product in blue & \\
\hline & & \[
\begin{aligned}
& \text { S-T50 } \\
& \text { SD-T50 }
\end{aligned}
\] & Laser printed on the product front left & Printed on the name plate on the product front in blue & \\
\hline & & \[
\begin{aligned}
& \text { S-T65 to T100 } \\
& \text { SD-T-65 to T100 }
\end{aligned}
\] & Printed on the name plate on the product front in gray & Printed on the name plate on the product front in blue & \\
\hline & & UT-AX11 & Printed on the paper name plate on the side of the product & Printed on the front center of the product in blue & \\
\hline
\end{tabular}

\section*{13 \\ Supplementary Information}

\section*{Wiring Related}
(1) Terminals/Location
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline Item & MS-T Target Model Names (Typical Model) & \multicolumn{2}{|r|}{MS-T Series} & \multicolumn{2}{|r|}{MS-N Series} & Remarks \\
\hline & \[
\begin{aligned}
& \text { S-T10 to T35 } \\
& \text { SD-T12 to T35 } \\
& \text { SR-T5, SRD-T5 }
\end{aligned}
\] & Make Contact & Break Contact & Make Contact
\[
\stackrel{\perp}{\top}
\] & Break Contact卉 & \\
\hline Contact Mark Display of Auxiliary & SR-T9, SRD-T9 & Upper Part (Body Side) & \begin{tabular}{l}
Lower Part \\
(Additional Auxiliar Contact Unit Side)
\end{tabular} & Upper Part (Body Side) & \begin{tabular}{l}
Lower Part \\
(Additional Auxiliary Contact Unit Side)
\end{tabular} & \\
\hline Terminal
\[
\left[\begin{array}{c}
\text { Displayed with engraved } \\
\text { marks on contact and } \\
\text { terminal, etc. }
\end{array}\right]
\] & & Make Contact & Make Contact & Make Contact
\[
\stackrel{\perp}{\top}
\] & Make Contact & \\
\hline & & Break Contact & Break Contact & Break Contact卉 & Break Contact & \\
\hline
\end{tabular}
(2) Rail Mounting
\begin{tabular}{|c|c|c|c|c|}
\hline Item & MS-T Target Model Names (Typical Model) & MS-T Series & MS-N Series & Remarks \\
\hline \multirow{5}{*}{DIN Rail Mounting} & \[
\begin{aligned}
& \text { S-T10 to T50 } \\
& \text { SD-T12 to T50 }
\end{aligned}
\] & -Mounting & Mounting & \\
\hline & & -Removing & -Removing & \\
\hline & & Screwdriver Not Required & \multirow[t]{2}{*}{Operated by Screwdriver} & \\
\hline & S-T65 & \multirow[b]{2}{*}{Same Operation as N Series} & & \\
\hline & S-T80 & & Not Available & \\
\hline
\end{tabular}
(3) Other
\begin{tabular}{|c|c|l|l|l|}
\hline \multicolumn{1}{|c|}{ Item } & \begin{tabular}{c} 
MS-T Target Model \\
Names (Typical Model)
\end{tabular} & \multicolumn{1}{c|}{ MS-T Series } & \multicolumn{1}{c|}{ MS-N Series } & Remarks \\
\hline \multirow{4}{*}{\begin{tabular}{c} 
Coil Surge \\
Absorber Function
\end{tabular}} & \begin{tabular}{c} 
S-T10SA to T50SA \\
SD-T12SA to T50SA
\end{tabular} & \begin{tabular}{l} 
- Surge Absorber Mounted Type Operation \\
Coil Surge Absorber Unit UT-SA21 \\
(Varistor Element) Mounted on Main Body
\end{tabular} & \begin{tabular}{l} 
- Surge Absorber Integrated Type \\
Operation Coil Surge Absorber (Varistor \\
Element) Integrated in Main Body
\end{tabular} & \\
\cline { 2 - 6 } & & \begin{tabular}{l} 
Integrated Surge Absorber Function \\
Through AC Operated DC Excitation \\
Type Electromagnet \\
S-T65 T100
\end{tabular} & \begin{tabular}{l} 
Integrated Surge Absorber Function \\
Through AC Operated DC Excitation \\
Type Electromagnet
\end{tabular} & \\
\hline
\end{tabular}

\subsection*{13.6 MS-N Series Changes}

The main contents of what has been changed from MS-K Series to MS-N Series are summarized.
For more information regarding mounting compatibility, refer to the following. It is to be noted that components such as contacts and operation coils are for respective series only, and have no compatibility. Refer to page 389 regarding optional units.
- Magnetic Starters/Magnetic Contactors
- Thermal Overload Relays

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\section*{- Product Marking}
(1) Terminal Number
\begin{tabular}{|c|c|c|c|c|c|}
\hline & Item & MS-N Model Names (Typical Model) & MS-N Series & MS-K Series & Remarks \\
\hline \multirow{5}{*}{} & \multirow[t]{2}{*}{Main Terminal Number} & \multirow[t]{2}{*}{S-N, TH-N All Models} & Power Supply Side: 1/L1, 3/L2, 5/L3 & Power Supply Side: R/1/L1, S/3/L2, T/5/L3 & \multirow[t]{3}{*}{Change in accordance with JEM1038 and JIS C4531} \\
\hline & & & Load Side: 2/T1, 4/T2, 6/T3 & Load Side: U/2/T1, V/4/T2, W/6/T3 & \\
\hline & \multicolumn{2}{|l|}{Auxiliary Terminal Number} & Ones Place of the Number for Make Contacts: 3-4, Break Contacts: 1-2 & Ones Place of the Number for Make Contacts: 3-4, Break Contacts: 1-2 & \\
\hline & (Magnetic Contactors) & S-N125 to N800 &  &  & \multirow[t]{2}{*}{NO (Normally Open): Make Contact NC (Normally Closed): Break Contact} \\
\hline & Coil Terminal Number & S-N125 to N800 & A1/a, A2/b (Mold Embossed Characters) & A1/a, A2/b (Mold Embossed Characters) & \\
\hline \multirow[t]{3}{*}{} & \multirow[t]{3}{*}{Auxiliary Terminal Number} & S-N125 & \multirow[b]{3}{*}{Printed on the name plate on top of the arc box (arc cover) in black} & Embossed on the base barrier & \\
\hline & & S-N150 to N400 & & Embossed on the base side & \\
\hline & & S-N600/N800 & & Embossed on the auxiliary contact unit & \\
\hline
\end{tabular}
(2) Rating
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Item} & MS-N Model Names (Representative Model) & MS-N Series & MS-K Series & \multirow[t]{3}{*}{Remarks} \\
\hline \multirow[t]{2}{*}{\[
\begin{aligned}
& \stackrel{ᄃ}{0} \\
& \stackrel{0}{n} \\
& 0 \\
& 0 \\
& \frac{\pi}{0} \\
& \frac{0}{0} \\
& 0.0
\end{aligned}
\]} & \multirow[t]{2}{*}{Main Circuit Rating} & \[
\begin{aligned}
& \text { S-N125 to } \\
& \text { N400 }
\end{aligned}
\] & \multirow[t]{2}{*}{- The Ith rating (A) is printed on the name plate on the front bottom left - The JIS and JEM ratings are printed on a name plate in the upper right hand corner, IEC rating is on the front right center, UL rating is on the front lower right and EN rating is on the front lower center (EN rating shows the rated operating current (A) and others show the rated capacity (UL is (HP), others are (kW)))} & The JEM rating is printed on the name plate on the front left in green, and the IEC rating on the front right in red [both the rated capacity (kW) and rated operating current (A)] & \\
\hline & & S-N600/N800 & & - The JEM rating is printed on the name plate on the front center in green, and the IEC rating in red [both the rated capacity (kW) and rated operating current (A)] & \\
\hline
\end{tabular}
(3) Model Names and Standards
\begin{tabular}{|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Item} & MS-N Model Names (Typical Model) & MS-N Series & MS-K & Series & Remarks \\
\hline \multirow{4}{*}{} & Model Name & \[
\begin{aligned}
& \text { S-N125 to } \\
& \text { N800 }
\end{aligned}
\] & Printed on the left center of the arc cover (arc box) in black & \multicolumn{2}{|l|}{Printed on the name plate on the front upper right of the arc cover (arc box)} & \\
\hline & \multirow{3}{*}{Compliance and Certification Standards} & \[
\begin{aligned}
& \text { S-N125 to } \\
& \text { N400 }
\end{aligned}
\] & \(\left.\begin{array}{l|l|}\begin{array}{ll}\text { JIS C8201-4-1 } \\ \text { JEM 1038 }\end{array} \\ \text { NK Certification Number } & \text { Printed on } \\ \text { the name } \\ \text { IEC 60947-4-1 } & \text { plate on } \\ \text { DIN VDE 0660 } & \text { the front } \\ \text { BS EN 60947 } \\ \text { cULus, CE and TÜV Marks }\end{array}\right)\) & JEM 1038 NK Certification Number IEC 947-4-1 DIN VDE 0660 BS EN 60947 UR and CE Marks & Printed on the name plate on the front & \multirow{3}{*}{The cUL mark is equivalent to the CSA mark} \\
\hline & & S-N600 & \begin{tabular}{ll}
\begin{tabular}{l} 
JIS C8201-4-1 \\
JEM 1038 \\
NK Certification Number \\
IEC 60947-4-1
\end{tabular} & \begin{tabular}{l} 
Printed on the \\
DIN VDE 0660 \\
nS EN \\
BS \\
CURus and CE Marks
\end{tabular}
\end{tabular} the front & \begin{tabular}{l}
JEM 1038 \\
NK Certification Number IEC 947-4-1 DIN VDE 0660 BS EN 60947-4-1 UR and CE Marks
\end{tabular} & Printed on the name plate on the front & \\
\hline & & S-N800 &  & JEM 1038
NK Certification Number
IEC 947-4-1
VDE 0660
BS EN 60947-4-1
CE Mark & Printed on the name plate on the front & \\
\hline
\end{tabular}

\section*{13 Supplementary Information}

\section*{Changes in Outline Drawings and Structure}
(1) Mounting
\begin{tabular}{|c|c|l|l|l|}
\hline Item & \begin{tabular}{c} 
MS-N Model Names \\
Representative Model)
\end{tabular} & \multicolumn{1}{|c|}{ MS-N Series } & \multicolumn{1}{c|}{ MS-K Series } & Remarks \\
\hline \multirow{2}{*}{ Arc Space } & N125 to N220 & 10 mm & 30 mm & \\
\cline { 2 - 6 } & N300/N400 & 10 mm & 50 mm & \\
\cline { 2 - 6 } & N600/N800 & 10 mm & 10 mm & \\
\hline \multirow{2}{*}{\begin{tabular}{c} 
Mounting \\
Compatibility With \\
MS-A Series
\end{tabular}} & \begin{tabular}{c} 
MSO/S- \\
N125 to N400
\end{tabular} & \begin{tabular}{l} 
Can be made compatible with MSO/ \\
S-N \(\square\) XA
\end{tabular} & \begin{tabular}{l} 
Can be made compatible by changing \\
the direction of the mounting plate
\end{tabular} & \\
\cline { 2 - 6 } & S-N600/N800 & Compatible & Compatible & \\
\hline
\end{tabular}
(2) Other
\begin{tabular}{|c|c|c|c|c|}
\hline Item & MS-N Model Names (Representative Model) & MS-N Series & MS-K Series & Remarks \\
\hline \multirow[t]{3}{*}{Built-in Operation Coil Surge Absorbing Function} & \[
\begin{aligned}
& \text { MSOL(D)/SL(D) } \\
& \text {-N125 to N220 }
\end{aligned}
\] & \multirow[t]{2}{*}{Built-in Surge Absorbing Function (Closing/Tripping) (Excluding AC/DC24 V and 48 V )} & No Surge Absorbing Function (Closing/Tripping) & \\
\hline & \[
\begin{aligned}
& \text { MSOL(D)/SL(D) } \\
& \text {-N300, N400 }
\end{aligned}
\] & & Surge Absorbing Function Built-in Only for Closing & \\
\hline & \[
\begin{gathered}
\text { SL(D)-N600, } \\
\text { N800 }
\end{gathered}
\] & Built-in Surge Absorbing Function (Closing/Tripping) (Excluding AC/DC24 V and 48 V ) & Built-in Surge Absorbing Function (Closing/Tripping) & \\
\hline
\end{tabular}

\subsection*{13.7 Mounting Dimensions When Using Mounting-Compatible Adapter for MS-T Series Magnetic Contactors and Contactor Relays}

Although the MS-T Series is not compatible with the MS-N Series and some other models, it can be made compatible with the use of our MS-T Series additional mounting-compatible adapter.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline \multirow{4}{*}{\[
\begin{aligned}
& \text { D} \\
& \text { d } \\
& \text { To } \\
& 0 . \\
& 0 \\
& 0 \\
& \hline
\end{aligned}
\]} & Model & Name & S-T10 & \[
\begin{aligned}
& \text { S-T12, SR-T5 } \\
& (* 3)
\end{aligned}
\] & S-T20 & S-T25 & S-T50 & S-T80 \\
\hline & \multicolumn{2}{|l|}{Outline Drawing (*1)} &  &  &  &  &  &  \\
\hline & \multirow[t]{2}{*}{Mounting Pitch Width x Height} & Body & \(28 \times 60\) & \[
\begin{gathered}
35 \times 60 \\
30 \times 60 \\
34 \times 52 \\
35 \times 50 \text { to } 52
\end{gathered}
\] & \[
\begin{gathered}
35 \times 60 \\
30 \times 60 \\
34 \times 52 \\
35 \times 50 \text { to } 52
\end{gathered}
\] & \[
\begin{aligned}
& 54 \times 56 \\
& 54 \times 60
\end{aligned}
\] & \[
\begin{aligned}
& 65 \times 70 \\
& 60 \times 70
\end{aligned}
\] & \(70 \times 75\) \\
\hline & & Adapter
(*2) & \[
\begin{aligned}
& 35 \times 50 \\
& 34 \times 52
\end{aligned}
\] & \(40 \times 50\) & \[
\begin{aligned}
& 54 \times 60 \\
& 54 \times 56
\end{aligned}
\] & \[
\begin{aligned}
& 65 \times 70 \\
& 60 \times 70
\end{aligned}
\] & \(70 \times 75\) & \[
\begin{gathered}
80 \times 110 \\
86 \times 90
\end{gathered}
\] \\
\hline \multirow{4}{*}{\[
\begin{aligned}
& \text { O} \\
& \text { CN } \\
& \text { © } \\
& 0 \\
& 0 \\
& 0 \\
& 0
\end{aligned}
\]} & \multicolumn{2}{|l|}{Model Name} & - & SD-T12, SRD-T5 & SD-T20 & - & SD-T50 & SD-T80 \\
\hline & \multicolumn{2}{|l|}{Outline Drawing (*1)} & - &  &  & - &  &  \\
\hline & \multirow[t]{2}{*}{Mounting Pitch Width x Height} & Body & - & \[
\begin{gathered}
35 \times 60 \\
34 \times 52 \\
35 \times 50 \text { to } 52
\end{gathered}
\] & \[
\begin{gathered}
35 \times 60 \\
34 \times 52 \\
35 \times 50 \text { to } 52
\end{gathered}
\] & - & \[
\begin{aligned}
& 65 \times 70 \\
& 60 \times 70
\end{aligned}
\] & \(70 \times 75\) \\
\hline & & \begin{tabular}{l}
Adapter \\
(*2)
\end{tabular} & - & \(40 \times 50\) & \[
\begin{aligned}
& 54 \times 60 \\
& 54 \times 56
\end{aligned}
\] & - & \(70 \times 75\) & \[
\begin{gathered}
80 \times 110 \\
86 \times 90
\end{gathered}
\] \\
\hline
\end{tabular}
*1. The dimensions shown in the figure are the mounting pitch when using the mounting-compatible adapter.
*2. There are no changes in the depth dimensions when using the mounting-compatible adapter.
\(* 3\). Mounting-compatible adapters can be used only with S-T12 and SR-T5 types where the manufacturing numbers on the front of the product is " \(14 Y * *\) " or " \(14 Z * *\) ", or where the first 2 digits are equal to or greater than " 15 " (some of those manufactured in October 2014, and those manufactured from November on).
*4. Please use mounting screws with metal washers.
13.8 Model Names of Discontinued Former Models and Replacements
\begin{tabular}{c|l|l|l|l|l}
\hline Old Model Name & \multicolumn{1}{|c|}{ Model Name } & \begin{tabular}{l} 
Alternative Model \\
Name
\end{tabular} & \multicolumn{1}{c}{ Compatibility } & Rounting & Rating
\end{tabular}

\subsection*{13.9 Tool for Selecting Power Distribution Control Devices Compatible with Mitsubishi Electric Motors}

\subsection*{13.9.1 3-phase Motor with Direct-on-Line Starting}

For D.O.L starting at 3phase 1500rpm or 1800rpm squirrel cage motors under AC-3 operating conditions according to IEC609 47-4-1.
Fuse is valid for this motor full load current and for max. \(6 \times f\). I.c. starting current and max. 5 secs starting time.
The setting current of the heater should be adjusted to the motor full-load current.

\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Motor rating}} & 0.06 & 0.09 & 0.12 & 0.18 & 0.25 & 0.37 & 0.55 & 0.75 & 1.1 & 1.5 & 2.2 & 3 & 3.7 & 4 & 5.5 & 7.5 & 11 & 15 & kW \\
\hline & & & 1/12 & 1/8 & 1/6 & 1/4 & 1/3 & 1/2 & 3/4 & 1 & \(11 / 2\) & 2 & 3 & 4 & 5 & \(51 / 2\) & \(71 / 2\) & 10 & 15 & 20 & HP \\
\hline \multirow{8}{*}{\begin{tabular}{l}
220 V \\
3-phase \\
\(50 / 60 \mathrm{~Hz}\)
\end{tabular}} & \multicolumn{2}{|l|}{motor full load current} & 0.5 & 0.7 & 0.8 & 1.2 & 1.5 & 2.1 & 2.7 & 3.5 & 4.5 & 6.1 & 8.7 & 11.5 & 14.2 & 15.2 & 20 & 26.5 & 39 & 50 & A \\
\hline & type designation of Magnetic Starter & MSO- & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T12 & T20 & T20 & T21 & T35 & T35 & T50 & KP \\
\hline & associated thermal overload relay & TH- & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T25 & T50 & T50 & T65 & KP \\
\hline & heater designation & & 0.5 & 0.7 & 0.9 & 1.3 & 1.7 & 2.1 & 2.5 & 3.6 & 5 & 6.6 & 9 & 11 & 15 & 15 & 22 & 29 & 35 & 54 & A \\
\hline & Fuse (VDE0660 gT time-delay) & & 2 & 2 & 4 & 4 & 6 & 6 & 10 & 16 & 16 & 20 & 25 & 35 & 50 & 50 & 50 & 80 & 80 & 160 & A \\
\hline & MCCB & NF & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 63-SV & 63-SV & 125-SV & 125-SV & \\
\hline & rated current(In) & & (3) & (3) & (3) & 3 & 4 & 6 & 6 & 10 & 16 & 16 & 20 & 25 & 32 & 32 & 50 & 63 & 50 & 63 & A \\
\hline & wire size recommended & & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 2.5 & 4 & 4 & 6 & 10 & 16 & 25 & \(\mathrm{mm}^{2}\) \\
\hline & motor full load current & & 0.25 & 0.35 & 0.45 & 0.65 & 0.85 & 1.2 & 1.6 & 2.0 & 2.7 & 3.6 & 5.1 & 6.8 & 8.5 & 8.7 & 11.8 & 16 & 22 & 30 & A \\
\hline & type designation of Magnetic Starter & MSO- & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T12 & T12 & T20 & T20 & T21 & T35 & KP \\
\hline & associated thermal overload relay & TH- & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T25 & T50 & KP \\
\hline & heater designation & & 0.24 & 0.35 & 0.5 & 0.7 & 0.9 & 1.3 & 1.7 & 2.1 & 2.5 & 3.6 & 5 & 6.6 & 9 & 9 & 11 & 15 & 22 & 29 & A \\
\hline & Fuse (VDE0660 gT time-delay) & & *2 & *2 & 2 & 2 & 4 & 4 & 6 & 6 & 10 & 16 & 16 & 20 & 25 & 25 & 35 & 50 & 50 & 80 & A \\
\hline & MCCB & NF & - & - & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 63-SV & 63-SV & \\
\hline & rated current(In) & & - & - & (3) & (3) & (3) & 3 & 4 & 6 & 6 & 10 & 16 & 16 & 20 & 20 & 25 & 32 & 50 & 63 & A \\
\hline & wire size recommended & & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 2.5 & 4 & 6 & 10 & \(\mathrm{mm}^{2}\) \\
\hline & motor full load current & & 0.2 & 0.3 & 0.4 & 0.6 & 0.8 & 1.1 & 1.5 & 1.9 & 2.6 & 3.5 & 5.0 & 6.3 & 7.5 & 8.0 & 11 & 15 & 21 & 28 & A \\
\hline & type designation of Magnetic Starter & MSO- & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T10,T12 & T12 & T12 & T20 & T20 & T21 & T35 & KP \\
\hline & associated thermal overload relay & TH- & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T25 & T50 & KP \\
\hline \[
415 \mathrm{~V}
\] & heater designation & & 0.24 & 0.35 & 0.5 & 0.7 & 0.9 & 1.3 & 1.3 & 1.7 & 2.5 & 3.6 & 5 & 6.6 & 6.6 & 9 & 11 & 15 & 22 & 29 & A \\
\hline \[
50 \mathrm{~Hz}
\] & Fuse (VDE0660 gT time-delay) & & *2 & *2 & *2 & 2 & 4 & 4 & 6 & 6 & 10 & 16 & 16 & 20 & 20 & 25 & 35 & 50 & 50 & 80 & A \\
\hline & MCCB & NF & - & - & - & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 63-SV & 63-SV & \\
\hline & rated current(In) & & - & - & - & (3) & (3) & 3 & 3 & 4 & 6 & 10 & 10 & 16 & 16 & 20 & 25 & 32 & 50 & 63 & A \\
\hline & wire size recommended & & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 2.5 & 4 & 6 & 10 & \(\mathrm{mm}^{2}\) \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Motor rating}} & 18.5 & 22 & 30 & 37 & 45 & 55 & 75 & 90 & 110 & 132 & 160 & 200 & 250 & 315 & 355 & 400 & 450 & kW \\
\hline & & & 25 & 30 & 40 & 50 & 60 & 75 & 100 & 125 & 150 & 180 & 220 & 270 & 340 & 420 & 480 & 540 & 600 & HP \\
\hline \multirow{8}{*}{\begin{tabular}{l}
220 V \\
3-phase \\
\(50 / 60 \mathrm{~Hz}\)
\end{tabular}} & \multicolumn{2}{|l|}{motor full load current} & 62 & 75 & 100 & 124 & 148 & 182 & 245 & 295 & 350 & 420 & 510 & 630 & & - & - & & - & A \\
\hline & type designation of Magnetic Starter & MSO- & T65 & T80 & T100 & N125 & N150 & N180 & N220 & N300 & N400 & S-N600 & S-N600 & S-N800 & - & - & - & - & - & KP \\
\hline & associated thermal overload relay & TH- & T65 & T80 & T100 & N120TA & N120TA & N220RH & N220RH & N400RH & N400RH & N600+CT & N600+CT & N600+CT & - & - & - & - & - & KP \\
\hline & heater designation & & 54 & 82 & 95 & 125 & 125 & 180 & 210 & 250 & 330 & 500 & 500 & 660 & - & - & - & & - & A \\
\hline & Fuse (VDE0660 gT time-delay) & & 160 & 200 & 200 & 315 & 315 & 400 & 500 & 800 & 800 & 800 & 1000 & 1250 & - & - & - & - & - & A \\
\hline & MCCB & NF & 125-SV & 125-SV & 250-SV & 250-SV & 250-SV & 400-SW & 400-SW & 630-SW & 630-SW & 630-SW & 800-SEW & 1000-SW & - & - & - & - & - & \\
\hline & rated current(In) & & 80 & 100 & 150 & 200 & 225 & 300 & 350 & 500 & 500 & 630 & 600 & 1000 & - & - & - & - & - & A \\
\hline & wire size recommended & & 25 & 35 & 50 & 50 & 70 & 95 & 150 & 150 & 150 & 185 & 240 & 150(2vires) & - & - & - & - & - & \(\mathrm{mm}^{2}\) \\
\hline & motor full load current & & 37 & 43 & 57 & 72 & 86 & 105 & 140 & 168 & 205 & 245 & 290 & 360 & 475 & 580 & 636 & 710 & 800 & A \\
\hline & type designation of Magnetic Starter & MSO- & T35 & T50 & T65 & T80 & T80 & T100 & N150 & N180 & N220 & N220 & N300 & N400 & S-N600 & S-N600 & S-N800 & S-N800 & S-N800 & KP \\
\hline & associated thermal overload relay & TH- & T50 & T65 & T65 & T100 & T100 & T100 & N120TA & N220RH & N220RH & N220RH & N400RH & N400RH & N600+CT & N600+CT & N600+CT & N600+CT & N600+CT & KP \\
\hline & heater designation & & 35 & 42 & 54 & 67 & 82 & 95 & 125 & 150 & 180 & 210 & 250 & 330 & 500 & 500 & 660 & 660 & 660 & A \\
\hline \[
50 / 60 \mathrm{~Hz}
\] & Fuse (VDE0660 gT time-delay) & & 80 & 125 & 160 & 160 & 200 & 200 & 315 & 315 & 500 & 500 & 800 & 800 & 1000 & 1250 & 1250 & 1500 & 1500 & A \\
\hline & MCCB & NF & \(125-\mathrm{SV}\) & 125-SV & 125-SV & 125-SV & 125-SV & 250-SV & 250-SV & 250-SV & 400-SW & 400-SW & 630-SW & 630-SW & 800-SEW & 800-SEW & 1000-SW & 1250-SW & 1250-SW & \\
\hline & rated current(In) & & 50 & 63 & 80 & 100 & 125 & 150 & 225 & 250 & 300 & 350 & 500 & 600 & 600 & 700 & 1000 & 1200 & 1200 & A \\
\hline & wire size recommended & & 10 & 16 & 25 & 25 & 35 & 50 & 50 & 70 & 95 & 150 & 150 & 185 & 240 & 300 & 300 & 185(2wies) & 185(2wies) & \(\mathrm{mm}^{2}\) \\
\hline & motor full load current & & 35 & 40 & 54 & 67 & 79 & 98 & 130 & 160 & 190 & 230 & 270 & 328 & 435 & 530 & 580 & 650 & 730 & A \\
\hline & type designation of Magnetic Starter & MSO- & T35 & T50 & T65 & T80 & T80 & T100 & N150 & N180 & N220 & N220 & N300 & N400 & S-N600 & S-N600 & S-N600 & S-N800 & S-N800 & KP \\
\hline & associated thermal overload relay & TH- & T50 & T65 & T65 & T100 & T100 & T100 & N120TA & N220RH & N220RH & N220RH & N400RH & N400RH & N600+CT & N600+CT & N600+CT & N600+CT & N600+CT & KP \\
\hline & heater designation & & 35 & 42 & 54 & 67 & 82 & 95 & 125 & 150 & 180 & 210 & 250 & 330 & 500 & 500 & 660 & 660 & 660 & A \\
\hline \[
50 \mathrm{~Hz}
\] & Fuse (VDE0660 gT time-delay) & & 80 & 125 & 160 & 160 & 200 & 200 & 315 & 315 & 500 & 500 & 800 & 800 & 800 & 1000 & 1250 & 1250 & - & A \\
\hline & MCCB & NF & 125-SV & 125-SV & 125-SV & 125-SV & 125-SV & 125-SV & 250-SV & 250-SV & 400-SW & 400-SW & 400-SW & 630-SW & 630-SW & 800-SEW & 800-SEW & 1000-SW & 1250-SW & \\
\hline & rated current(In) & & 50 & 50 & 80 & 100 & 100 & 125 & 200 & 250 & 300 & 350 & 400 & 500 & 630 & 600 & 700 & 1000 & 1200 & A \\
\hline & wire size recommended & & 10 & 16 & 25 & 25 & 35 & 50 & 50 & 70 & 95 & 150 & 150 & 185 & 240 & 300 & 300 & 185[(2wres) & 185[2wires) & \(\mathrm{mm}^{2}\) \\
\hline
\end{tabular}

Note1. This selection scale made up depending upon the average rating current of motor.
Note2. Actual rating current could be high or low for a specific motor. Therefore heater selection on this basis always involves risk. For fully reliable motor protection, select heaters on the basis of full load current rating as show on the motor nameplate.
Note3. Type MSO-N600KP and N800KP are not available.
Use contactor S-N600 or S-N800 and OLR TH-N600KP with suitable CTs.

\subsection*{13.9.2 3-phase Motor with Star-delta Starting}

For star-delta starting at 1500 rpm or 1800 rpm 3phase squirrel cage motors.
The selection of contactor MCS can be applied only to this diagram.
Fuse is valid for this motor full load current and for max. \(2 \times\) f.I.c. starting current and max. 15 secs starting time.
The setting current of the heater should be adjusted to \(1 / \sqrt{ } 3 \times f\).l.c


\begin{tabular}{l}
\hline \\
\hline \\
220 V \\
3 -phase
\end{tabular}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Motor rating}} & 2.2 & 3 & 3.7 & 4 & 5.5 & 7.5 & 11 & 15 & 18.5 & 22 \\
\hline & & 3 & 4 & 5 & \(51 / 2\) & \(71 / 2\) & 10 & 15 & 20 & 25 & 30 \\
\hline \multicolumn{2}{|l|}{motor full load current} & 8.7 & 11.5 & 14.2 & 15.2 & 20 & 26.5 & 39 & 50 & 62 & 75 \\
\hline type designation of Magnetic Starter MCM+OLR & MSO- & T12 & T12 & T12 & T12 & T12 & T20 & T25 & T35 & T35 & T50 \\
\hline type designation of OLR & TH- & T18 & T18 & T18 & T18 & T18 & T18 & T25 & T50 & T50 & T65 \\
\hline heater designation & & 5 & 6.6 & 9 & 9 & 11 & 15 & 22 & 29 & 35 & 42 \\
\hline type designation of Contactor MCD & S- & T12 & T12 & T12 & T12 & T12 & T20 & T25 & T35 & T35 & T50 \\
\hline type designation of Contactor MCS & S- & T10 & T10 & T10 & T10 & T10 & T10 & T10 & T10 & T12 & T20 \\
\hline \multicolumn{2}{|l|}{Fuse (VDE0660 gT time-delay)} & 16 & 20 & 32 & 32 & 32 & 40 & 63 & 80 & 100 & 100 \\
\hline MCCB & NF & 32-SV & 32-SV & 32-SV & 63-SV & 63-SV & 63-SV & 125-SV & 125-SV & 125-SV & 160-SV \\
\hline \multicolumn{2}{|l|}{rated current(In)} & 20 & 32 & 32 & 40 & 50 & 63 & 63 & 80 & 100 & 125 \\
\hline \multicolumn{2}{|l|}{wire size recommended(*)} & 1.5 & 1.5 & 1.5 & 4 & 6 & 10 & 16 & 25 & 25 & 35 \\
\hline \multicolumn{2}{|l|}{wire size recommended(*)} & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 2.5 & 4 & 6 & 6 & 10 \\
\hline \multicolumn{2}{|l|}{motor full load current} & 5.1 & 6.8 & 8.5 & 8.7 & 11.8 & 16 & 22 & 30 & 37 & 43 \\
\hline \multicolumn{2}{|l|}{type designation of Magnetic Starter MCM + OLR MSO-} & T12 & T12 & T12 & T12 & T12 & T20 & T20 & T20 & T21 & T25 \\
\hline \multicolumn{2}{|l|}{type designation of OLR TH-} & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T25 & T25 \\
\hline \multicolumn{2}{|l|}{heater designation} & 3.6 & 3.6 & 5 & 5 & 6.6 & 9 & 15 & 15 & 22 & 22 \\
\hline \multicolumn{2}{|l|}{type designation of Contactor MCD S-} & T12 & T12 & T12 & T12 & T12 & T20 & T20 & T20 & T21 & T25 \\
\hline \multicolumn{2}{|l|}{type designation of Contactor MCS S-} & T10 & T10 & T10 & T10 & T10 & T10 & T10 & T10 & T12 & T12 \\
\hline \multicolumn{2}{|l|}{Fuse (VDE0660 gT time-delay)} & 12 & 16 & 16 & 16 & 20 & 32 & 32 & 40 & 40 & 63 \\
\hline \multicolumn{2}{|l|}{MCCB NF} & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 63-SV & 63-SV & 125-SV & 125-SV & 125-SV \\
\hline \multicolumn{2}{|l|}{rated current(In)} & 16 & 16 & 20 & 20 & 32 & 40 & 50 & 50 & 63 & 63 \\
\hline \multicolumn{2}{|l|}{wire size recommended} & 1.5 & 1.5 & 1.5 & 1.5 & 2.5 & 4 & 6 & 10 & 10 & 16 \\
\hline \multicolumn{2}{|l|}{wire size recommended} & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 2.5 & 2.5 & 4 \\
\hline \multicolumn{2}{|l|}{motor full load current} & 5.0 & 6.3 & 7.5 & 8 & 11 & 15 & 21 & 28 & 35 & 40 \\
\hline \multicolumn{2}{|l|}{type designation of Magnetic Starter MCM+OLR MSO-} & T12 & T12 & T12 & T12 & T12 & T12 & T20 & T20 & T21 & T25 \\
\hline \multicolumn{2}{|l|}{type designation of OLR \({ }^{\text {a }}\) TH-} & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T18 & T25 & T25 \\
\hline \multicolumn{2}{|l|}{heater designation} & 3.6 & 3.6 & 5 & 5 & 6.6 & 9 & 11 & 15 & 22 & 22 \\
\hline \multicolumn{2}{|l|}{type designation of Contactor MCD S-} & T12 & T12 & T12 & T12 & T12 & T12 & T20 & T20 & T21 & T25 \\
\hline \multicolumn{2}{|l|}{type designation of Contactor MCS S-} & T10 & T10 & T10 & T10 & T10 & T10 & T10 & T10 & T10 & T12 \\
\hline \multicolumn{2}{|l|}{Fuse (VDE0660 gT time-delay)} & 12 & 16 & 16 & 16 & 20 & 32 & 32 & 40 & 40 & 63 \\
\hline \multicolumn{2}{|l|}{MCCB NF} & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 32-SV & 63-SV & 125-SV & 125-SV & 125-SV \\
\hline \multicolumn{2}{|l|}{rated current(In)} & 16 & 16 & 16 & 20 & 25 & 32 & 50 & 40 & 50 & 63 \\
\hline \multicolumn{2}{|l|}{wire size recommended} & 1.5 & 1.5 & 1.5 & 1.5 & 2.5 & 4 & 6 & 10 & 10 & 16 \\
\hline \multicolumn{2}{|l|}{wire size recommended} & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 1.5 & 2.5 & 2.5 & 4 \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline & 30 & 37 & 45 & 55 & 75 & 90 & 110 & kW \\
\hline & 40 & 50 & 60 & 75 & 100 & 125 & 150 & HP \\
\hline & 100 & 124 & 148 & 182 & 245 & 295 & 350 & A \\
\hline & T65 & T80 & T80 & N125 & N150 & N180 & N220 & KP \\
\hline & T65 & T100 & T100 & N120TA & N120TA & N220RH & N220RH & KP \\
\hline & 54 & 67 & 82 & 105 & 150 & 180 & 210 & A \\
\hline & T65 & T80 & T80 & N125 & N150 & N180 & N220 & \\
\hline & T21 & T25 & T35 & T35 & T50 & T65 & T80 & \\
\hline & 125 & 160 & 200 & 220 & 315 & 400 & 400 & A \\
\hline & 160-SV & 250-SV & 250-SV & 400-SW & 400-SW & 630-SW & 630-SW & \\
\hline & 160 & 200 & 225 & 300 & 400 & 500 & 600 & A \\
\hline & 50 & 50 & 70 & 95 & 150 & 150 & 150 & \(\mathrm{mm}^{2}\) \\
\hline & 16 & 25 & 25 & 35 & 50 & 70 & 95 & \(\mathrm{mm}^{2}\) \\
\hline & 57 & 72 & 86 & 105 & 140 & 168 & 205 & A \\
\hline & T35 & T50 & T50 & T65 & T80 & T100 & N125 & KP \\
\hline & T50 & T65 & T65 & T65 & T100 & T100 & N120TA & KP \\
\hline & 29 & 42 & 54 & 54 & 82 & 95 & 105 & A \\
\hline & T35 & T50 & T50 & T65 & T80 & T100 & N125 & \\
\hline & T20 & T20 & T20 & T21 & T25 & T35 & T50 & \\
\hline & 63 & 100 & 100 & 125 & 160 & 200 & 250 & A \\
\hline V & 125-SV & 160-SV & 160-SV & 160-SV & 250-SV & 400-SW & 400-SW & \\
\hline & 100 & 125 & 150 & 160 & 225 & 300 & 350 & A \\
\hline & 25 & 25 & 35 & 50 & 50 & 70 & 95 & \(\mathrm{mm}^{2}\) \\
\hline & 6 & 6 & 10 & 16 & 25 & 35 & 35 & \(\mathrm{mm}^{2}\) \\
\hline & 54 & 67 & 79 & 98 & 130 & 160 & 190 & A \\
\hline & T35 & T50 & T50 & T65 & T80 & T100 & N125 & KP \\
\hline & T50 & T65 & T65 & T65 & T100 & T100 & N120TA & KP \\
\hline & 29 & 42 & 42 & 54 & 67 & 95 & 105 & A \\
\hline & T35 & T50 & T50 & T65 & T80 & T100 & N125 & \\
\hline & T20 & T20 & T20 & T21 & T25 & T35 & T50 & \\
\hline & 63 & 100 & 100 & 125 & 160 & 160 & 250 & A \\
\hline V & 125-SV & 125-SV & 160-SV & 160-SV & 250-SV & 400-SW & 400-SW & \\
\hline & 80 & 100 & 125 & 150 & 225 & 300 & 350 & A \\
\hline & 25 & 25 & 35 & 50 & 50 & 70 & 95 & \(\mathrm{mm}^{2}\) \\
\hline & 6 & 6 & 10 & 16 & 25 & 35 & 35 & \(\mathrm{mm}^{2}\) \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline & \multicolumn{2}{|l|}{\multirow[b]{2}{*}{Motor rating}} & 132 & 160 & 200 & 250 & 315 & 355 & 400 & 450 & kW \\
\hline & & & 180 & 220 & 270 & 340 & 420 & 480 & 540 & 600 & HP \\
\hline \multirow{11}{*}{\begin{tabular}{l}
220 V \\
3-phase \\
\(50 / 60 \mathrm{~Hz}\)
\end{tabular}} & \multicolumn{2}{|l|}{motor full load current} & 420 & 510 & 630 & 790 & 990 & 1100 & 1230 & 1380 & A \\
\hline & type designation of Magnetic Starter MCM+OLR & MSO- & N300 & N300 & N400 & S-N600 & S-N600 & S-N600 & S-N800 & S-N800 & KP \\
\hline & type designation of OLR & TH- & N400RH & N400RH & N400RH & N600+CT & N600+CT & N600+CT & N600+CT & N600+CT & KP \\
\hline & heater designation & & 250 & 250 & 330 & 500 & 500 & 660 & 660 & 660 & A \\
\hline & type designation of Contactor MCD & S- & N300 & N300 & N400 & N600 & N600 & N600 & N800 & N800 & \\
\hline & type designation of Contactor MCS & S- & T100 & T100 & N125 & N150 & N220 & N220 & N220 & N300 & \\
\hline & Fuse (VDE0660 gT time-delay) & & 500 & 630 & 800 & 1000 & 1250 & 1500 & 1500 & 2000 & A \\
\hline & MCCB & NF & 800-SEW & 1000-SW & 1000-SW & 1250-SW & 1600-SW & AE1600-SW & AE2000-SW & AE2000-SW & \\
\hline & rated current(In) & & 600 & 800 & 1000 & 1200 & 1500 & 1600 & 2000 & 2000 & A \\
\hline & wire size recommended(*) & & 185 & 240 & 185(2wires) & 240(2wires) & 60x5[2aas) & 80x5(2ars) & 80x[2bass) & 100x533ass) & \(\mathrm{mm}^{2}\) \\
\hline & wire size recommended(*) & & 120 & 185 & 240 & 150(2wires) & 185(2vires) & 240(2vires) & 240(2wires) & 240(2vires) & \(\mathrm{mm}^{2}\) \\
\hline & motor full load current & & 245 & 290 & 360 & 475 & 580 & 636 & 710 & 800 & A \\
\hline & type designation of Magnetic Starter MCM+OLR & MSO- & N150 & N180 & N220 & N300 & N400 & N400 & S-N600 & S-N600 & KP \\
\hline & type designation of OLR & TH- & N120TA & N220RH & N220RH & N400RH & N400RH & N400RH & N600+CT & N600+CT & KP \\
\hline & heater designation & & 125 & 150 & 180 & 250 & 330 & 330 & 500 & 500 & A \\
\hline & type designation of Contactor MCD & S- & N150 & N180 & N220 & N300 & N400 & N400 & N600 & N600 & \\
\hline 3-phase & type designation of Contactor MCS & S- & T50 & T65 & T80 & T100 & N125 & N150 & N150 & N180 & \\
\hline 50/60Hz & Fuse (VDE0660 gT time-delay) & & 250 & 310 & 400 & 630 & 630 & 800 & 800 & 1000 & A \\
\hline & MCCB & NF & 400-SW & 630-SW & 630-SW & 1000-SW & 1000-SW & 1000-SW & 1250-SW & 1250-SW & \\
\hline & rated current(In) & & 400 & 500 & 600 & 700 & 900 & 1000 & 1200 & 1200 & A \\
\hline & wire size recommended & & 150 & 150 & 185 & 240 & 185(2vires) & 240(2vires) & 240(2vires) & 240(2vires) & \(\mathrm{mm}^{2}\) \\
\hline & wire size recommended & & 50 & 70 & 95 & 150 & 185 & 240 & 150 (2wires) & 150(2vires) & \(\mathrm{mm}^{2}\) \\
\hline & motor full load current & & 230 & 270 & 328 & 435 & 530 & 580 & 650 & 730 & A \\
\hline & type designation of Magnetic Starter MCM + OLR & MSO- & N150 & N180 & N220 & N300 & N400 & N400 & N400 & S-N600 & KP \\
\hline & type designation of OLR & TH- & N120TA & N220RH & N220RH & N400RH & N400RH & N400RH & N400RH & N600+CT & KP \\
\hline & heater designation & & 125 & 150 & 180 & 250 & 330 & 330 & 330 & 500 & A \\
\hline 415 V & type designation of Contactor MCD & S- & N150 & N180 & N220 & N300 & N400 & N400 & N400 & N600 & \\
\hline 3-phase & type designation of Contactor MCS & S- & T50 & T65 & T65 & T80 & T100 & N125 & N150 & N150 & \\
\hline & Fuse (VDE0660 gT time-delay) & & 250 & 315 & 400 & 630 & 630 & 800 & 800 & 1000 & A \\
\hline & MCCB & NF & 400-SW & 630-SW & 630-SW & 800-SEW & 1000-SW & 1000-SW & 1000-SW & 1250-SW & \\
\hline & rated current(In) & & 400 & 500 & 600 & 500 & 800 & 900 & 1000 & 1200 & A \\
\hline & wire size recommended & & 150 & 150 & 185 & 150(2wires) & 185(2wires) & 185/(2wires) & 240(2wires) & 240(2vires) & \(\mathrm{mm}^{2}\) \\
\hline & wire size recommended & & 50 & 70 & 95 & 150 & 185 & 185 & 240 & 150(2vires) & \(\mathrm{mm}^{2}\) \\
\hline
\end{tabular}

Note1. This selection scale made up depending upon the average rating current of motor.
Note2. Actual rating current could be high or low for a specific motor.Therefore heater selection on this basis always involves risk.For fully reliable motor protection, select heaters on the basis of full load current rating as show on the motor nameplate.
Note3. Type MSO-N600KP and N800KP are not available.Use contactor S-N600 or S-N800 and OLR TH-N600KP with suitable CTs.

\subsection*{13.10 Index by Content}



\section*{Supplementary Information}


\subsection*{13.11 Index by Model Name}
\begin{tabular}{|c|c|c|c|}
\hline \multicolumn{2}{|r|}{Format} & Product Name & Page \\
\hline \multirow[t]{2}{*}{B} & B-T/ND & NC Main Contact Contactors (AC Operated Type) & 249 \\
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\hline & UL/CSA Standards Certified Product List & MS-T/N & All & 270 \\
\hline & Usage Environment & MS-T/N/K & All & 64 \\
\hline \multirow[t]{2}{*}{V} & Vacuum Magnetic Contactors (Medium and Low Voltage) & SH-V & SH(D)-/SHL(D)-V \(\square\) & 259 \\
\hline & Voltage Detection Relays & SRE & SRE- \(\square\) & 344 \\
\hline
\end{tabular}

\section*{\(\triangle\) Precautions Regarding Safety \\ - For correct and safe use, read the "Instruction Manual" beforehand.}

For safety, make sure that only technicians qualified for electric work or wiring perform connection of the product.
- When a product described in this catalog is to be used in a facility where a failure can lead to injury to the human body or serious damage to earnings, make sure to install safety mechanisms.
- Upon adoption for use, read the "Notes for Adopting the Product" on page 10, beforehand.


Mitsubishi Electric Corporation Nagoya Works is a factory certified for ISO 14001 (standards for environmental management systems).


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[^0]:    - MS-N Series models feature a white front surface design that brightens the board interior.

