

**Automating the World** 

FACTORY AUTOMATION

# Programmable Controllers MELSEC-Q series [QnU]











The Mitsubishi Electric Group is actively solving social issues, such as decarbonization and labor shortages, by providing production sites with energy-saving equipment and solutions that utilize automation systems, thereby helping towards a sustainable society. Mitsubishi Electric is involved in many areas including the following:

#### **Energy and Electric Systems**

A wide range of power and electrical products from generators to large-scale displays.

#### **Electronic Devices**

A wide portfolio of cutting-edge semiconductor devices for systems and products.

#### **Home Appliance**

Dependable consumer products like air conditioners and home entertainment systems.

#### Information and Communication Systems

Commercial and consumer-centric equipment, products and systems.

#### **Industrial Automation Systems**

Maximizing productivity and efficiency with cutting-edge automation technology.



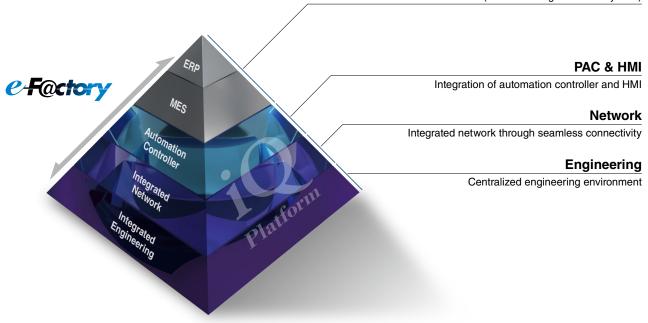


FA Integrated Platform "iQ Platform" Movie

# iQ Platform for maximum return on investment

Minimize TCO, Seamless integration, Maximize productivity, Transparent communications: these are common items that highlight the benefits of the iQ Platform and e-F@ctory. The iQ Platform minimizes TCO at all phases of the automation life cycle by improving development times, enhancing productivity, reducing maintenance costs, and making information more easily accessible across the plant. Together with e-F@ctory, offering various best-in-class solutions through its e-F@ctory alliance program, the capabilities of the manufacturing enterprise is enhanced even further realizing the next level for future intelligent manufacturing plants.

ERP (Enterprise resource planning) MES (Manufacturing execution system)



# Further reduce TCO while securing your manufacturing assets

#### Automation Controller

Improve productivity and product quality

- 1. High-speed system bus realizing improved system performance
- On-screen multi-touch control enabling smooth GOT (HMI) operations

#### **Integrated Network**

Best-in-class integrated network optimizing production capabilities

- 1. CC-Link IE supporting 1 Gbps high-speed communication
- 2. Seamless connectivity within all levels of manufacturing with SLMP

#### **Centralized Engineering**

Integrated engineering environment with system level features

- 1. Automatic generation of system configuration
- 2. Share parameters across multiple engineering software via MELSOFT Navigator
- 3. Changes to system labels are reflected between PAC and HMI

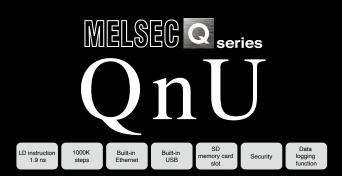


# Universal Model

PUL

PULL

ATTEL



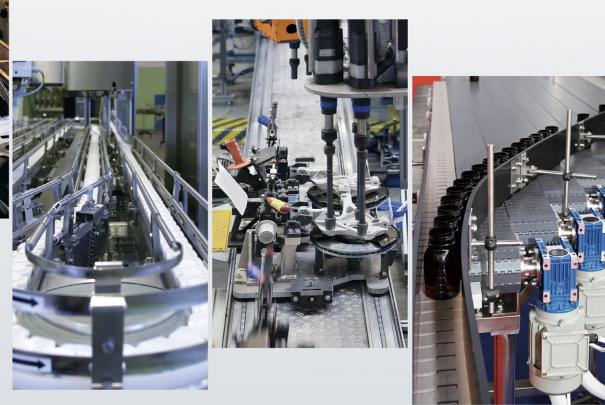


The MELSEC-Q Series has gained continuous supports since its release in 1999, helping to promote factory automation and support economic growth. High-speed and highly functional MELSEC-QnU Series was released in 2012. High quality and stable modules for versatile applications are widely used in many industries.

#### Contents

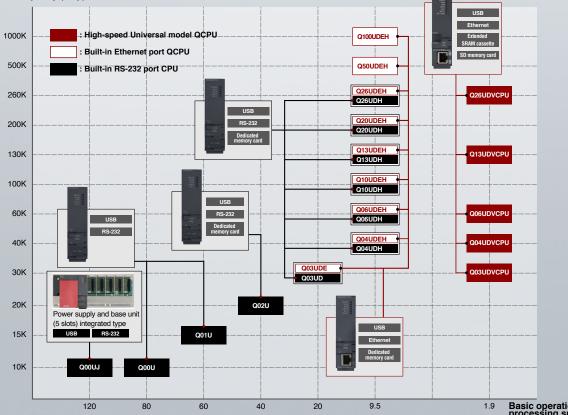
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MELSEC-Q Series Universal model lineup

Program capacity (step)



Basic operation processing speed (ns)

# Melsec estives



#### High-speed Universal model QCPU

Q03UDV, Q04UDV, Q06UDV, Q13UDV, Q26UDV



 $^{\star}$  This CPU type is only supported by GX Works2 (not supported by GX Developer).

#### High-speed Universal model QCPU



### CPU

- Basic operation processing speed (LD instruction): 1.9 ns
   Program capacity: maximum 260K steps
- ► Fixed Scan interrupt program (minimum interval): 100 µs





USB port

#### **Cassette port**

Expand standard RAM (up to 8 MB)
 Use simultaneously with SD memory card
 Continuously access file registers

1



Maximum of 32 character password is supported. A mix of alphanumeric and special characters

(\*, @, and & etc.) can be used further strengthening the security of the password. In addition, protection of intellectual property can be enhanced by blocking any unauthorized devices and only allowing registered devices to access the CPU.





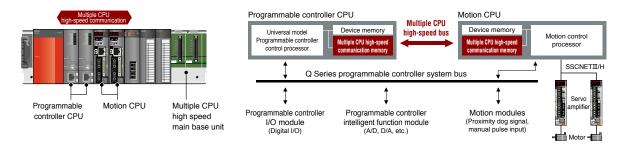
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## Productivity



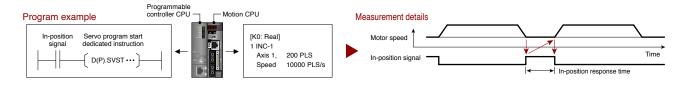
#### Multiple CPUs

To achieve high-speed synchronized control between multiple CPUs, a dedicated bus is used, independent of sequence program operation (0.88 ms operation cycle)<sup>\*1</sup>. This multiple CPU high-speed communication is synchronized with motion control to maximize efficiency.



In-position response time

Fast in-position response time is realized between the motion CPU and programmable controller. The in-position signal is triggered by the servo amplifier of the first axis, with the time taken between the second axis at start-up and the speed command output of the programmable controller CPU.



\*1. Q00UJ, Q00U, Q01U and Q02U are not supported.



#### Improved production time

As applications are getting larger and more complex it is essential to shorten the system operation cycle time. To achieve this, the ultra high-speed of 1.9 ns (LD instruction) processing enables to realize shorter operating cycles.

System performance can be improved by reducing the overall scan time, preventing any variances in performance. In addition to realization of high-speed control which is normally associated with microcomputer control.

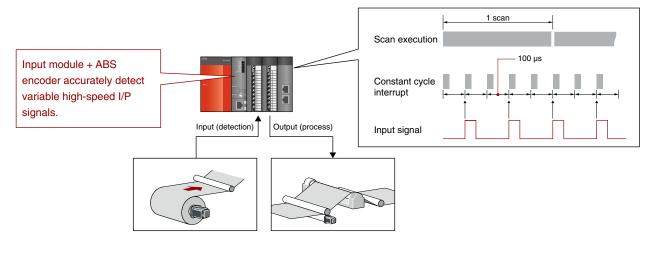
#### Data processing

High-speed floating point addition processing supports high-speed and high-precision operation processing. Also, double-precision floating-point operation instruction is included to simplify programming and reduce calculation errors when implementing complex equations.

#### Higher system accuracy

Minimal fixed scan interrupt program time is 100 µs\*1. High-speed I/O signals resulting in high-accuracy control system.

Example: High-speed position detection of film paper feed system

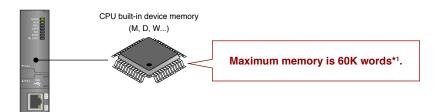


\*1. Only supported by High-speed Universal model QCPU and Universal model process CPU.

## Productivity

#### Basic functions

The maximum CPU's built-in device memory capacity is 60K words\*1. Support increasing control and quality data.

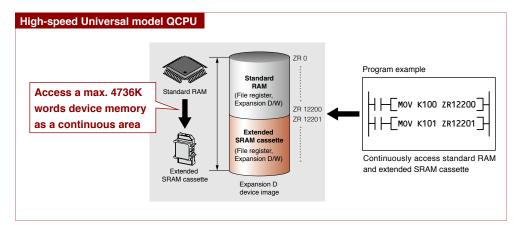


\*1. Only for Q13UDVCPU and Q26UDVCPU.

#### Large data volume at high-speed

When an 8 MB extended SRAM cassette is installed in the High-speed Universal model QCPU, the standard RAM can be as one continuous file register with up to 4736K words capacity, simplifying the user program.

Even if the device memory is insufficient, the file register area can be expanded easily by installing the extended SRAM cassette.



#### ■ File register capacity\*2

Model	Q03UDV	Q04UDV	Q06UDV	Q13UDV	Q26UDV
Extended SRAM cassette not installed (Standard RAM capacity)	96K words (192 KB)	128K words (256 KB)	384K words (768 KB)	512K words (1024 KB)	640K words (1280 KB)
with Q4MCA-1MBS (1 MB)*3	608K words	640K words	896K words	1024K words	1152K words
with Q4MCA-2MBS (2 MB)*3	1120K words	1152K words	1408K words	1536K words	1664K words
with Q4MCA-4MBS (4 MB)*3	2144K words	2176K words	2432K words	2560K words	2688K words
with Q4MCA-8MBS (8 MB)*3	4192K words	4224K words	4480K words	4608K words	4736K words

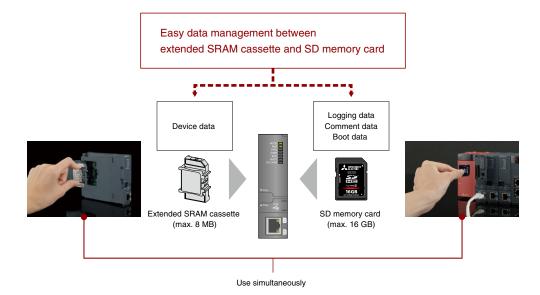
\*2. Maximum capacity when using extended SRAM cassette file as a file register. Total when CPU's standard RAM and extended SRAM cassette are installed.

\*3. Only High-speed Universal model QCPU



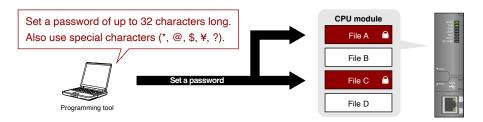
#### SD memory card

SD memory card is supported allowing easy data exchange with a personal computer. The SD memory card and extended SRAM cassette can be used at the same time allowing extension of file registers (with extended SRAM cassette), data file logging, boot data, and storing of large comment data (SD memory card).

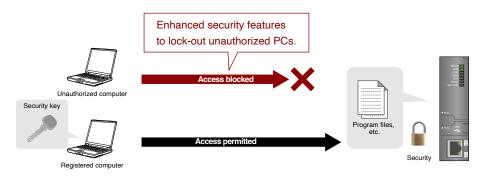


#### Protect important data

A max. 32-character file password can be set<sup>\*1</sup>. Special characters (\*, @, &, etc.) can be used in addition to alphanumeric characters making it difficult to compromise the password.



Also protection of valuable intellectual property can be enhanced by only allowing preregistered devices to access the CPU, blocking out unauthorized users\*<sup>2</sup>.



\*1. Only supported by High-speed Universal model QCPU and Universal model process CPU. Other models use 4 character password system.

\*2. Only supported by High-speed Universal model QCPU and Universal model process CPU.



## **User-friendly**

**Data logging function** 

Q03UDV, Q04UDV, Q06UDV, Q13UDV, Q26UDV

#### Display collected data on a computer or GOT (HMI)



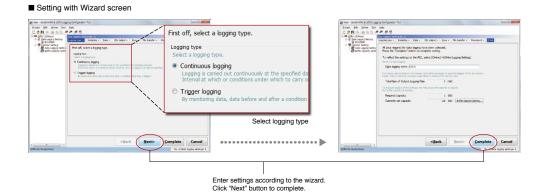
Logging data display and analysis tool GX LogViewer



GOT log viewer function

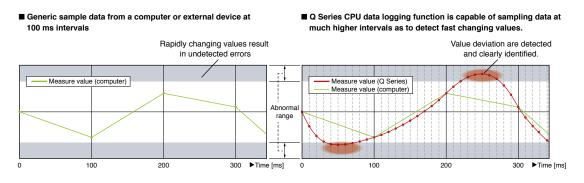
#### Easy logging without a program

Save collected data in CSV format on an SD memory card just by completing easy settings with the dedicated setting tool wizard. Various reference materials including daily reports, form creation and general reports can be created easily within the saved CSV file. This data can be used for a wide variety of applications requiring traceability, production data, etc.



#### Logging of control data variances

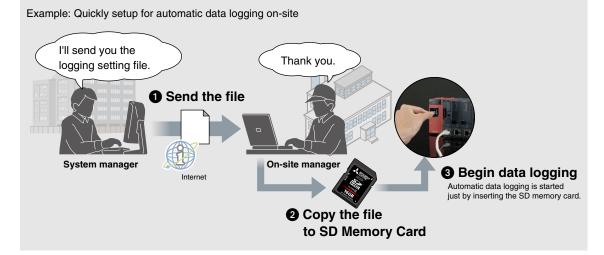
Data is collected during each scan or within millisecond intervals allowing detection of control deviation even at very high speeds. Therefore, identification of errors can be conducted faster and in more detail.





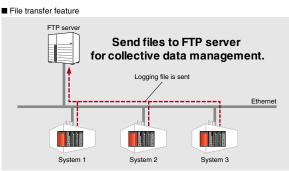
#### Automatic logging just by using an SD memory card

Automatic data logging realized just by inserting the SD memory card into the CPU, which is achieved as the memory card includes the logging configuration file. Instructing data logging remotely is also realized just by sending the configuration file by e-mail and copying onto the SD memory card.



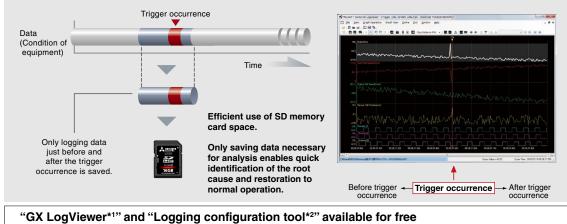
#### Automatically send logging files to FTP server

Data logging files stored on the SD memory card can be sent to FTP server just by making a simple setting with the Logging configuration tool. As the logging server can handle multiple files, management and maintenance tasks can be reduced.



#### Quick troubleshooting response

Error causes and solutions can be quickly done as only the required data related to the problem is extracted, without having to spend time on filtering large volumes of diagnostic data.



To obtain a copy of GX LogViewer and Logging configuration tool, please contact your local Mitsubishi Electric representative.

\*1. Refer to page 58 for details on GX LogViewer

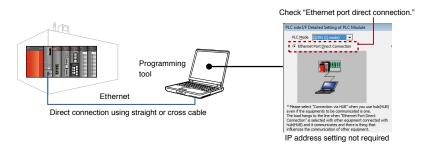
\*2. The logging configuration tool is enclosed with GX Works2.

#### CPU modules with Built-in Ethernet Port

Q03UDV, Q04UDV, Q06UDV, Q13UDV, Q26UDV Q03UDE, Q04UDEH, Q06UDEH, Q10UDEH, Q13UDEH, Q20UDEH, Q26UDEH, Q50UDEH, Q100UDEH

#### Easily connect to CPUs via Ethernet

IP address settings are not required to connect to CPU modules directly (one-to-one connection) using GX Works2 or GX Developer. Both straight and cross cables can be used, and are automatically identified by the CPU module. Therefore this connection method is as easy as using USB. Even operators who are not familiar with network settings can easily establish a connection.



#### CC-Link IE Field Network Basic does not require network module

Programmable controller CPUs with an embedded Ethernet port can be used as a master station<sup>\*1</sup>, eliminating the need for an additional network module. The network can be configured with a minimum number of modules reducing space and hardware cost.

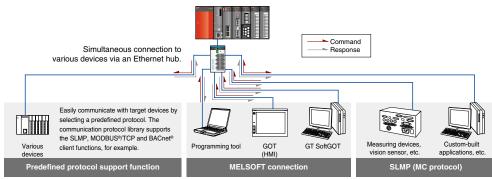


\*1. Only supported by High-speed Universal model QCPU and Universal model process CPU

\*2. SLMP:Seamless Message Protocol

#### Easily connect to BACnet<sup>®</sup> and MODBUS<sup>®</sup>/TCP

Ethernet realizes a high-speed connection, such as communication with external devices. By using predefined protocol support function<sup>\*3</sup>, various devices that require open network protocol support, such as BACnet<sup>®</sup> and MODBUS<sup>®</sup>/TCP are supported.

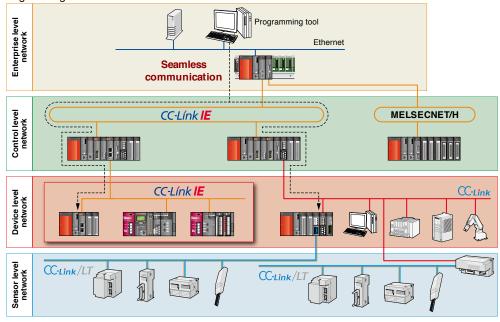


\*3. Only supported by High-speed Universal model QCPU and Universal model process CPU.

# SEC 🖸 series

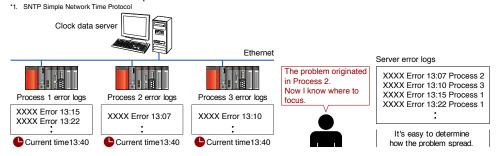
#### Seamless communication across all layers

The Universal model QCPUs support a multitude of networking technologies including the high-speed, high-capacity CC-Link IE Controller Network and CC-Link IE Field Network. Along with MELSECNET/H, Ethernet, and CC-Link, these networks may be accessed seamlessly beyond network type or hierarchy. Each programmable controller on the network can be accessed for programming and maintenance duties by using a personal computer with the appropriate engineering tools connected via Ethernet.



#### Accurate clock data

The CPU module's clock is automatically corrected with the SNTP\*1 clock synchronization function. When CPU clock data is reliably synchronized between systems, any time-stamped events or errors that involve more than one CPU can be easily understood in terms of their order of occurrence and relationship.



#### Program-less device data transfer

#### Simple PLC communication function\*2

Using the programming tool, a simple parameter setting is all that is needed to transfer device data such as production information with no programming required. This function makes it possible to easily establish

communications not only with Q Series, but also

MELSEC iQ-R Series, iQ-F Series, L Series and QnA/A

#### Series controllers.

\*2. QnUDVCPU or QnUDPVCPU module whose first five serial number digits is "20042" or later is required.



Data communication is also possible between the CPU modules in which the parameters are not set. (In that case, the data communication is done through the CPU module in which the parameters are set.)



MELSEC-Q Series\*3\*4 MELSEC iQ-R Series\*3

- MELSEC iQ-F Series\*3 MELSEC-L Series\*3\*4 MELSEC-OnA/A Series\*
- \*3. Built-in Ethernet port CPU is supported.
- \*4. CPU module and Ethernet interface module are supported

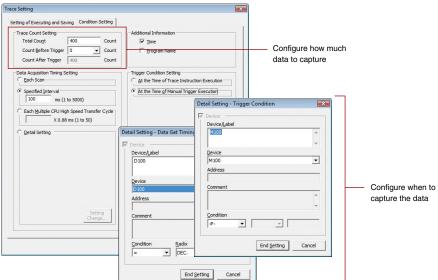
■ Simple PLC Communication Setting

Ethernet

#### Sampling trace function\*1

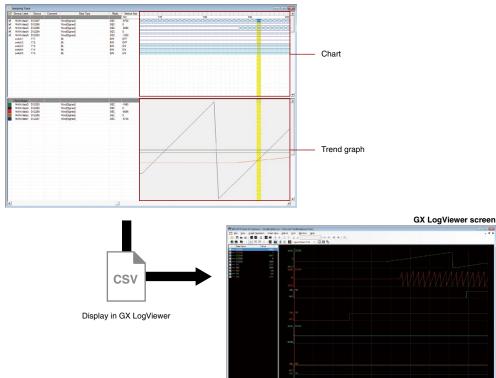
The sampling trace function is a useful diagnostic tool for analyzing error data, and sequence of events for program debug, etc. It can help reduce the overall time required for startup and commissioning of equipment.

In the multiple CPU configuration it can help to determine the timing and transfer of data between CPU modules. Collected data can be easily analyzed within the programming software tool with differences in word device and bit device values conveniently shown in chart and graph form. In addition, the results from sampling trace can be exported to GX LogViewer CSV file format for analysis within the software.



Sampling trace execution condition settings

#### Sampling Trace window: example results

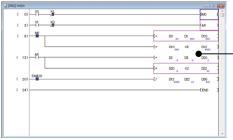


\*1. Not supported by Q00UJ.

# Melsec o series

#### Debugging process

Universal model CPUs have the ability to use the "Executional conditioned device test" function, which automatically sets device values to user specified values at any step during program simulation. Traditionally, to simulate real I/O or other device value change, a separate program would need to be written to perform debugging. By using the "Executional conditioned device test" function, it is possible to debug even small portions of simple ladder programs without the need to modify the program or add rungs of ladder. Therefore, debugging can be completed faster and easier.





Configure the device setting by choosing the step No. and execution timing (before/after instruction execution).

Devices that have been added to the executional conditioned device test are highlighted by a pink box for easy identification.

2		Program Name	Step No.	Device	ON/OFF/Setting Value	Execution Timing	Device Comment	
2		MAIN	5		ON	Before Executing Instruction		
		MAIN	7	00	80	Before Executing Instruction		
3		MAIN	7	01	500	Sefore Executing Instruction		
4		MAIN	17	022	20	Before Executing Instruction		_
5								
6	Π.							
2	C		1					
8								
2								
10	Π							
11								
12	Π.							_
13								_
14	Г							_
15								_
16	С.							

A list of all devices being controlled by the function is automatically generated and can be saved and recalled for further debugging at a later time.

#### Device point assignment

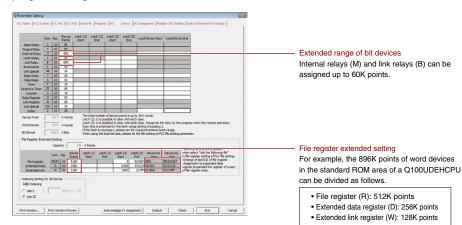
#### Extended range of bit devices

Bit devices, internal relay (M) and link relay (B), can now be assigned up to 60K points each. Previous models are limited to 32K points.

The total number of device points remains the same, however greater flexibility of device utilization and programming is achieved.

#### File register extended setting: data registers and link registers\*1

The number of Data Register (D) and Link Register (W) device points can be extended using standard ROM or a memory card. Previous models only allow the extension of File Register (R/ZR) device points. Using this setting, it is easy to create more data or link registers to accommodate program changes, etc.



\*1. Not supported by Q00UJ.

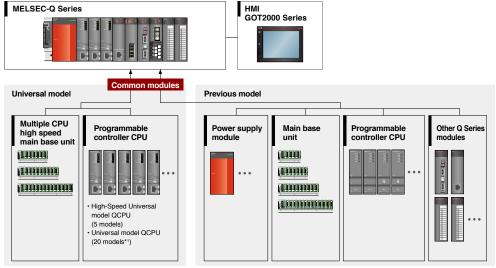
#### Maintenance cost



#### Compatibility

#### Use existing Q Series modules

Conventional Q Series modules are compatible with the Universal model QCPU Series. Therefore, when requiring an upgrade, system maintenance costs of existing systems can be kept to a minimum with little disruption when changing over.



\*1. The Q00UJCPU is all-in-one type, with integrated power supply, 5-slot base unit, and CPU.

#### Use existing Q Series programs

Conventional QCPU programs can be used just by changing the PLC type<sup>\*2</sup> within the programming tool, which enables easy upgrade to the Universal model Series with little reengineering required.

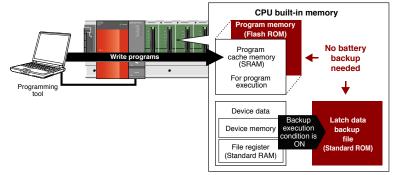


\*2. Depending on the program, the number of steps may vary when the PLC type is changed.



#### Automatically backup critical data

Programs and parameter files are automatically backed up to the program memory (Flash ROM) which does not require battery backup. This prevents loss of program and parameter data owing to failure in battery replacement. Also, back-up of important data such as device data can be registered to the standard ROM in order to prevent data loss due to a flat battery in case of planned outage during consecutive holidays. The backup data is restored automatically when the power is restored.

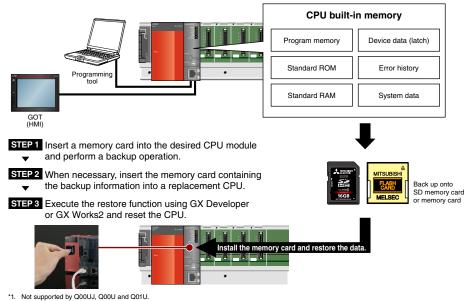


#### Shorten system down recovery time

#### CPU module change function\*1

The CPU module change function allows the user to create a comprehensive backup of all CPU information to a memory card. In the unlikely event of a CPU failure or other catastrophic event, the backup data can be used to quickly program a new CPU module.

Using this function, the system can rapidly be made operational and downtime can be minimized.



#### Serial numbers

Serial numbers can be checked quickly without having to remove them from the base unit (No interruption of operation is necessary). Also, serial numbers may be checked using the "product information list"

feature included in GX Developer and GX Works2.



 Serial numbers are located on the bottom front of modules

Sort (* c	rder by	Ingtallation	Cord	fer by Type <u>N</u> ame						
Base	Slot	Туре	Series	Model Name	Point	I/O Address	Master PLC	Serial No.	Ver	Production Number
0	CPU	CPU	Q	Q03UDECPU				120320000000000	8	120325120865002-B
0	0			Empty						
0	1			Empty						
0	2			Empty						
0	3			Empty						
0	4			Empty						

The serial numbers of connected modules appear – in the Product Information List and can be exported in CSV format.



## Multiple CPUs ideal for distributed control and distributed function

CPU Lineup

The MELSEC-Q Series offers programmable controller, process, C language, motion, robot and CNC CPUs to cover various different control requirements. With the multiple CPU configuration, a best-fit control system can be realized. In addition, high availability systems can be easily realized with the high-reliability redundant system range.

# **MELSEC** PROCESS

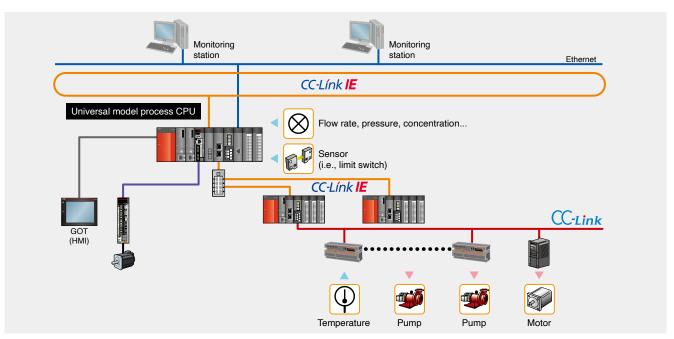
MELSEC process control is a flexible, highly reliable platform with advanced functionality designed to cost-effectively meet the needs of a wide range of industries.

#### Detailed instrument control to match the process state

#### Q13UDPVCPU, Q26UDPVCPU

MELSEC process controllers offer features that rival those of costly DCS systems at a fraction of the cost. A single CPU can control a large number of PID loops while simultaneously performing standard sequence control.

In addition, PX Developer and GX Works2 support process programming (FBD). The Universal model process CPU includes four models, from a small-scale suitable for discrete process control to a large-scale for continuous process control (PID loops: up to about 100 loops).





#### Pre-installed systems with the C Controller

#### Q24DHCCPU-LS, Q26DHCCPU-LS, Q12DCCPU-V

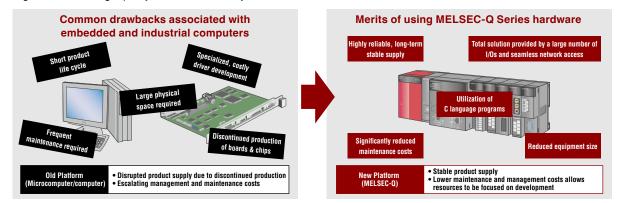
The C Controller is a generic open platform controller that can execute C language type programs, based on the MELSEC system architecture. It utilizes industrial performance such as long term parts supply, high availability, and advanced functionality. The high-end model Q24DHCCPU-V/-VG comes pre-installed with VxWorks®, and supports advanced information processing and control system I/O. The standard model Q12DCCPU-V is a space saving controller that realizes high-speed I/O control. The Q24DHCCPU-LS and Q26DHCCPU-LS are OS independent controllers. Linux® based control can be easily realized by installing third-party partner OS, supporting advanced information processing with a user interface environment close to conventional personal computers. Wide scope of applications are realized with the availability of these controllers, used together with MELSEC-Q Series I/O modules, third-party products, open source, and customized applications/programs. Providing freedom with a robust, easier and high-performance system.

\*1. Set product (Q24DHCCPU-VG-B000/B002) with GENWARE® 3-VG by International Laboratory Corporation.

#### Ideal for a diverse range of systems, based on a generic platform architecture Leveraging the C Controller to realizing customized systems, by utilization of third-party applications, installation of third-party partner OS, utilization of programs, and open source applications. Partner Zone Customize System Integrator Plug-in Application Development Application Device **Open Source C** Controller **CW Workbench** CW-Sim **MELSEC-Q Series** C Controller Setting & Monitoring Tool **Open Platform**

The C Controller overcomes the overheads associated with maintaining embedded computers (micro boards, etc.) and industrial computers realizing a cost effective solution.

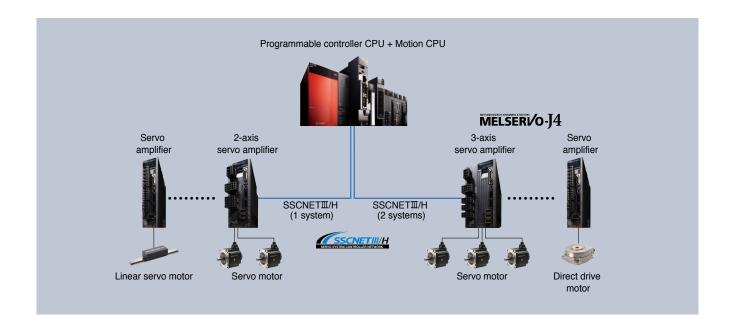
The C Controller platform is a solution that realizes personal computer level functionality without the burden of high maintenance costs usually associated with personal computers. In addition, it includes a robust design that is ideal for industrial environments by being based on the high quality MELSEC control system.



#### Connecting with servo amplifiers and servo motors

Motion CPU
 Q173DSCPU, Q172DSCPU

Each MELSEC-Q Series Motion controller is capable of high-speed control of up to 32 axes (96 axes when using three CPUs together). Each Motion CPU is the same size as a standard Q Series programmable controller. The new generation Motion controller is packed with advanced functions while saving space with its smaller size.



#### Automating production sites with robots

Robot controller
 CR800-Q

The iQ Platform compatible robot controller increases the speed of data communications between CPUs and dramatically reduces I/O processing times using a high-speed standard base between multiple CPUs.



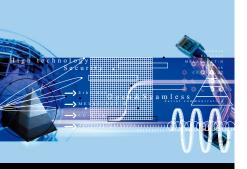
#### 

This CNC controller is part of the Mitsubishi FA integration solution "iQ Platform".

The integration of the high-performance CNC and high-speed programmable controller helps reduce the total operation cycle time. Supporting a wide range of interface and I/O modules flexible to many different applications.



Q Platform makes it possible to structure optimum controllers for various lines.

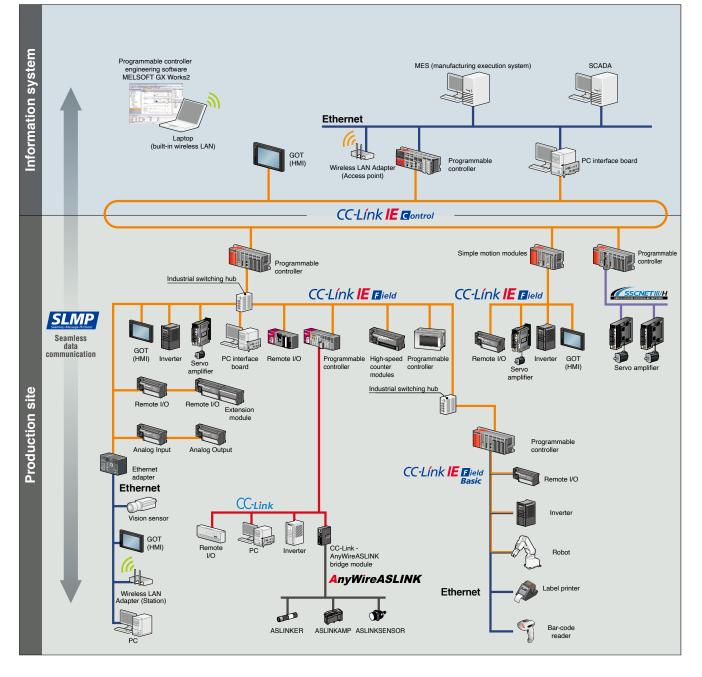


# Optimum network scalable to fit any application size

Network

Enhanced information communication by networking is the essential requirement in the automation industry. The MELSEC-Q Series provides an open and seamless network environment integrating the following different level of automation networks: CC-Link IE; high-speed and large capacity Ethernet-based integrated open network that connects shop floor and IT system as the core of e-F@ctory, CC-Link; SEMI certified global standard network originating from Japan and Asia, and AnyWire; sensor level distributed control network.

#### Network Configurations

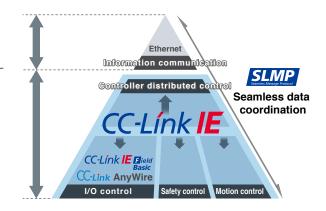


#### **Seamless communication**

Seamless data communication through Ethernet, CC-Link IE, and CC-Link allow easy access to information, no matter where it resides on the network. Through this technology, it is possible to "drill down" from the Enterprise or IT layer through multiple networks accessing programming controllers using GX Works2 programming or other related software.

In addition, many devices supporting SLMP\*1 such as vision sensors and RFID controllers may be connected to the CC-Link IE.

\*1. SLMP (SeamLess Message Protocol) is a protocol advocated by the CC-Link Partner Association.



### CC-LÍNK IE Gontrol

CC-Link IE Control is a high-reliability distributed control network designed to handle very large data communications (128K word) over a high-speed (1 Gbps) dual loop optical cable topology. \* Compatible modules: QJ71GP21-SX, QJ71GP21-SX

### CC-Línk IE Flield

CC-Link IE Field is an all-round versatile gigabit Ethernet based network integrating controller, I/O control, safety control, and motion control in a flexible wiring topology supporting star, ring, and line configurations. \* Compatible modules: QJ71GF11-T2, QS0J71GF11-T2 (safety control), QD77GF4, QD77GF8, QD77GF6 (motion control)

# CC-Línk **IE F**ield Basic

CC-Link IE Field Network Basic realizes easier network integration, as its cyclic communications stack is software-based, without requiring a dedicated ASIC helping to reduce implementation costs for device partners. CC-Link IE Field Network Basic, which is a part of CC-Link IE, realizes easier connection of Ethernet devices. \* Compatible modules: OnUDVCPU, OnUDPVCPU

# CC-Link

CC-Link is a high-speed and high-reliable deterministic I/O control network which realizes reduced wiring whilst offering multi-vendor compatible products. This open field network is a global standard originating from Japan and Asia. \* Compatible module: QJ61BT11N

#### AnyWireASLINK

AnyWireASLINK makes it possible to centrally monitor (visibility) the state of all sensors from the programmable controller, by that improving productivity and reducing operation steps. \* AnyWireASLINK-compatible modules: QJ51AW12AL, NZ2AW1C2AL

#### SSCNETIII/H

SSCNETTI/H is a dedicated high-speed, high-performance, and highly reliable servo system control network which offers flexible long distance wiring capabilities based on optical fiber cable topology. \*Compatible modules: QD77MS2, QD77MS4, QD77MS16

#### BACnet®

This network supports the communication protocol standard BACnet<sup>®</sup> client function. This network is mainly used to monitor and control air-conditioning, lighting and fire detection, etc. in building automation system applications.

Compatible modules: QnUDVCPU, QJ71E71-100 (client only)

#### **MODBUS®**

Q-Series is now supporting the MODBUS® protocol network, realizing easy communication, with various MODBUS® slave devices compatible with Ethernet MODBUS®/TCP or RS-232/422/485 serial communication. \* Module supporting MODBUS®/TCP : QJ71MT91 (master/slave functions), QNUDVCPU, QJ71E71-100 (master only)

(master only) \* Modules supporting MODBUS<sup>®</sup>: QJ71MB91 (master/slave functions), QJ71C24N (-R2/R4) (master only)

Application	Enterprise level network	Control level network	Device level network			Sensor level network
Network	Information communication	Controller distributed control	I/O control	Safety control	Motion control	Control
Ethernet	•					
CC-Link IE Control		•				
CC-Link IE Field		•	•	•	•	
CC-Link IE Field Network Basic			•			
CC-Link			•			
AnyWireASLINK						•
SSCNETII/H					•	
BACnet <sup>®</sup>	•					
MODBUS®/TCP		•				
MODBUS®			•			

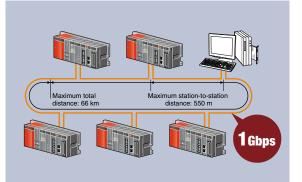
#### Distributed control network designed for large bandwidth and high-speed

#### CC-Link IE Controller Network module

Standard model------QJ71GP21-SX With external power supply function ...... QJ71GP21S-SX

- » Commercially available Ethernet components can be used for significant cost savings over alternative networks.
- » Deterministic, reliable performance helps to reduce operation cycle time. This cyclic data exchange is fixed and will not suffer from degraded performance even when large volumes of data are transferred.
- » Share massive amounts of data between controllers. (Up to 256K bytes of network shared memory per station)
- » The CC-Link IE Controller Network modules, QJ71GP21-SX and QJ71GP21S-SX, may be configured as normal stations, or the control station.





#### Performance Specifications\*1

Item		Specification				
	LB	32K points (32768 points, 4 KB) (Safety CPU: 16K points (16384 points, 2 KB))				
Max. link points per network	LW	128K points (131072 points, 256 KB) (Safety CPU: 16K points (16384 points, 32 KB))				
	LX	8K points (819	2 points, 1 KB)			
	LY	8K points (819	2 points, 1 KB)			
		Regular mode	Extended mode*2			
	LB	16K points (16384 points, 2 KB)	32K points (32768 points, 4 KB)			
Max. link points per station	LW	16K points (16384 points, 32 KB)	128K points (131072 points, 256 KB)			
	LX	8K points (8192 points, 1 KB)	8K points (8192 points, 1 KB)			
	LY	8K points (8192 points, 1 KB)	8K points (8192 points, 1 KB)			
Communication speed		1 Gbps				
Number of stations per network		120 (1 control station plus 119 normal stations)				
Connection cable		Optical fiber cable (Multi-mode fiber)				
Overall cable distance		66000 m (When 120 stations are connected)				
Station-to-station distance (Max.)		550 m (Core/Clad = 50/125 (m))				
Max. number of networks		23	39			
Max. number of groups		32				
Network topology		Ri	ng			

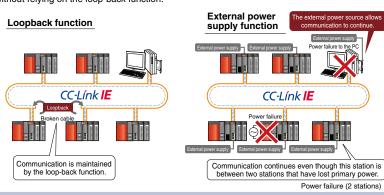
\*1. When the control station is a Universal model QCPU.

\*2. To use extended mode, (QJ71GP21(S)-SX) network modules and Universal model CPUs whose first five serial number digits are 12052 or later are required. All stations in the network must support the extended mode Also, GX Works2 version 1.34 L or later is required.

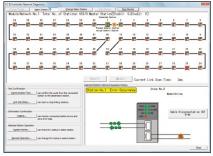
#### Designed to continue functioning even in the worst possible scenarios

• The use of fiber optic cables which are completely immune to EMI and RFI noise allows the network to function in environments where other networks cannot. The dual loop design allows the network to continue functioning even if cables become damaged or the power is lost to a station.

• Additionally, CC-Link IE stations can be powered using an external supply. That allows communication to continue normally in the event of a loss of the primary power supply, without relying on the loop-back function.



#### Visual display of network connection status



View the network connection status of entire system to identify problems at a glance. The cause of problems can be quickly identified and suggested remedies implemented to minimize down

#### **CC-Link IE Field Network**

• CC-Link IE Field Network module ...... QJ71GF11-T2

- » Tremendous speed and bandwidth using commercially available cables and connectors. The network design (topology) is highly flexible to fit any layout.
- » Operates as either a master or local station. Perfect for managing remote I/O control and distributed control.
- » Devices from other stations can be accessed easily via transient communication using dedicated instructions.
- » Function blocks for transient communication are available to further simplify messaging.
- » The network can ensure 32-bit data integrity using the station-based block data assurance function. This forces pairs of word data to get updated together during link refresh.
- » The QJ71GF11-T2 CC-Link IE Field Network module can function as a local or master



#### Performance Specifications

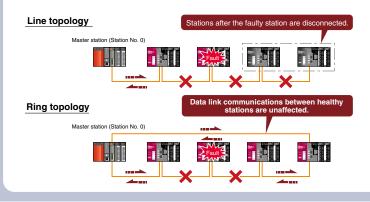
Item		Specification				
	RX	16K points (16384 points, 2 KB)				
Max. link points per	RY	16K points (16384 points, 2 KB)				
network	RWr	8K points (8192 points, 16 KB)				
	RWw	8K points (8192 points, 16 KB)				
	RX	2K points (2048 points, 256 B)				
Max. link points per	RY	2K points (2048 points, 256 B)				
station	RWr	1K points (1024 points, 2 KB)				
	RWw	1K points (1024 points, 2 KB)				
Communication speed	I	1 Gbps				
Number of stations pe	r network	121 (1 master station plus 120 device stations)				
Connection cable		Ethernet cable (Category 5e or higher, double shielded/STP)				
	Line topology	12 km (with 1 master station and 120 device stations connected)				
Maximum overall cable distance	Star topology	Depends on the system configuration.*1				
Cable distance	Ring topology	12.1 km (with 1 master station and 120 device stations connected)				
Max. station-to-station	distance	100 m				
Max. number of netwo	rks	239				
Network topology		Line, star, line and star mixed, or ring*2				

\*1. Up to 20 hubs can be connected per network

\*2. Ring networks may not be mixed with line or star networks. QJ71GF11-T2 network modules whose first five serial number digits are 12072 or later are required for ring networks. Additionally, GX Works2 version 1.34 L or later is required.

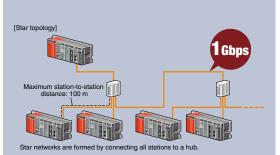
#### Easy diagnosis functions

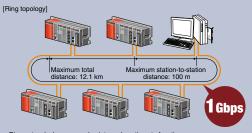
• In certain situations such as power loss, a station could be prevented from communicating. In a line network this can cause perfectly healthy stations can become separated from the network. In a ring network, only the faulty station is separated, thus increasing the system reliability.





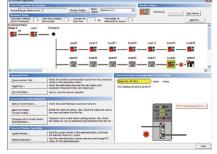
This method of connecting stations has two endpoints where stations are directly connected to each other and no hubs are necessary.





Ring networks have no end points and continue to function even if a connection becomes broken.

#### Visual display of network connection status



The network diagnostic tools in GX Works2\*3 allow problems to be identified rapidly. In addition to a visual overview of the network and several other tools, detailed monitoring of CPUs and modules from any station, to any station is possible. \*3. Not supported by GX Developer.

#### Linking the sensor with the programmable controller

#### 

The AnyWireASLINK master module links the sensor inputs and outputs to the programmable controller. The module enables flexible layout of sensors with 512 I/O points. The sensor power can be supplied to the AnyWireASLINK transmission line (2-wire) for communication, allowing sensors to be added easily. With the MELSEC-Q/L/F Series, faulty sensors can be detected and the remote unit settings can be managed at once by GX Works2 engineering environment, further reducing the engineering time.

#### AnyWireASLINK

#### System configuration example

#### Basic configuration

Either the 2-wire type or 4-wire remote units can be selected according to the load current for AnyWireASLINK. In addition to the 2-wire type, a 4-wire type can also be used by supplying the local power.

#### 2-wire type

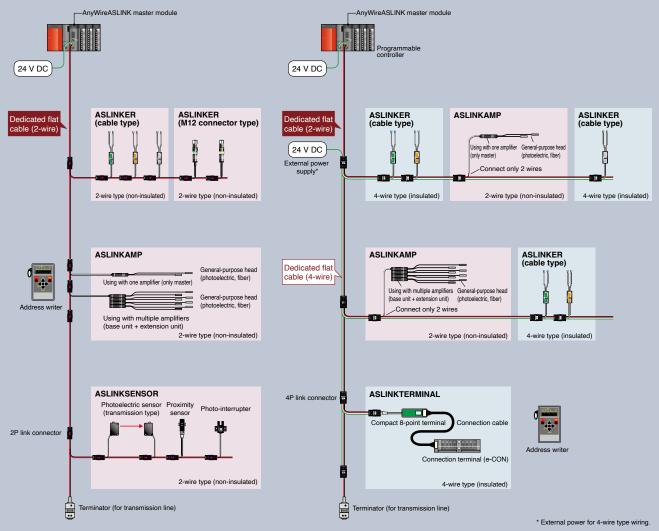
If the load current is low, 2-wire type (non-insulated) remote units can be used without an external power supply.

#### 4-wire type

The 4-wire type (insulated) remote units require an external 24 V DC power supply to satisfy large load current applications, for example.

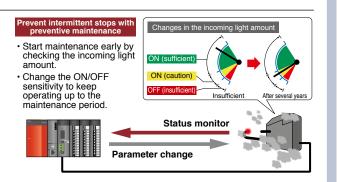
#### Configuration with 2-wire type (with no local power feed)

#### Configuration with 2-wire/4-wire type (with local power feed)



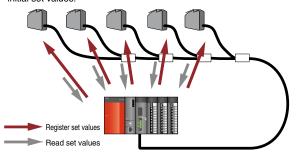
#### Preventing intermittent operation stops

AnyWireASLINK can be used to monitor and save the sensor information within the programmable controller. Parameter settings of the AnyWireASLINK can also be changed via the programmable controller. Perform "preventive maintenance" with this function to prevent intermittent stops before they happen.



#### Reducing the setup time, and providing the traceability

AnyWireASLINK enables the set value to be registered at once to multiple sensors via a GOT (HMI) or personal computer. Also, the initial set values can be re-confirmed easily without having to read each sensor individually. Register set values to multiple sensors, and automatically read the initial set values.



Model	QJ51AW12AL
Number of connected I/O points	Max. 512 points (256 input points/256 output points)
Number of connected modules	Max. 128 modules (varies according to each remote unit's current consumption)
Maximum transmission distance (overall length)*1	200 m*2
Transmission method	DC power superimposed total frame cyclic method
Connection style	Bus type (multi-drop method, T-branch method, tree branch method)
Transmission protocol	Dedicated protocol (AnyWireASLINK)
Error control	Checksum, double verification method
Transmission clock	270 kHz
RAS function	Transmission cable break position detection function, transmission cable short-circuit detection function, transmission power drop detection function
Transmission cable (DP, DN)	<ul> <li>UL compatible universal 2-wire cable (VCTF, VCT 1.25 mm<sup>2</sup>, 0.75 mm<sup>2</sup>, rated temperature 70°C or more)</li> <li>UL compatible universal cable (1.25 mm<sup>2</sup>, 0.75 mm<sup>2</sup>, rated temperature 70°C or more)</li> <li>Dedicated flat cable (1.25 mm<sup>2</sup>, 0.75 mm<sup>2</sup>, rated temperature 90°C)</li> </ul>
Power cable (24 V, 0 V)*1	<ul> <li>UL compatible universal 2-wire cable (VCTF, VCT 0.75 mm<sup>2</sup>2.0 mm<sup>2</sup>, rated temperature 70°C or more)</li> <li>UL compatible universal cable (0.75 mm<sup>2</sup>2.0 mm<sup>2</sup>, rated temperature 70°C or more)</li> <li>Dedicated flat cable (1.25 mm<sup>2</sup>, 0.75 mm<sup>2</sup>, rated temperature 90°C)</li> </ul>
Transmission cable supply current*1	Using 1.25 mm² cable: Max. 2 A Using 0.75 mm² cable: Max. 1 A
External power supply	Voltage: 21.627.6 V DC (24 V DC -10+15%), ripple voltage 0.5 Vp-p or less Recommended voltage: 26.4 V DC (24 V DC +10%) Module current consumption: 0.1 A Transmission cable current supply: Max. 2 A*1

\*1. Refer to the manual for the relation of the overall length, transmission cable (DP, DN) wire diameter and transmission cable current supply. In some remote units with cables, the wire diameter of the transmission cable (DP, DN) integrated with the module may be 0.75 mm<sup>2</sup> or less.

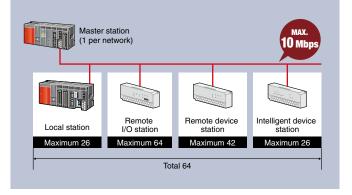
\*2. With the remote units having an integrated transmission cable (DP, DN) and module, the length of the transmission cable (DP, DN) is included in the overall length.

#### Open field network with many compatible devices

#### • CC-Link network module ...... QJ61BT11N

- » By building on reliable field bus technology, CC-Link is capable of moving large volumes of bit data, like ON/OFF relay status, and word data at highspeed.
- » CC-Link keeps cyclic transmission consistent and guarantees punctuality by separating it from message (transient) communication. Even if message communication becomes saturated, it will not affect the link scan time.
- $\scriptstyle *$  The QJ61BT11N module supports CC-Link version 1 and 2, and may be used as a local or master module.





#### ■Performance Specifications

Item			Specification		
Communication speed			Can select from 156 kbps/625 kbps/2.5 Mbps/5 Mbps/10 Mbps		
Transmission path	Transmission path		Bus (RS-485)		
			Remote inputs/outputs (RX, RY): 8192 points		
Maximum number o	f link points per syste	m*1	Remote registers (RWw): 2048 points		
			Remote registers (RWr): 2048 points		
			Remote inputs/outputs (RX, RY): 32 points (30 points for local station)		
		Single	Remote registers (RWw): 4 points		
			Remote registers (RWr): 4 points		
	Expanded cyclic setting	Double	Remote inputs/outputs (RX, RY): 32 points (30 points for local station)		
Maximum number			Remote registers (RWw): 8 points		
of link points per			Remote registers (RWr): 8 points		
system			Remote inputs/outputs (RX, RY): 64 points (62 points for local station)		
System		Quadruple	Remote registers (RWw): 16 points		
			Remote registers (RWr): 16 points		
			Remote inputs/outputs (RX, RY): 128 points (126 points for local station)		
		Octuple	Remote registers (RWw): 32 points		
			Remote registers (RWr): 32 points		
Maximum number o	f connected stations	(master station)	64*2		
Total distance/speed	d (When using Ver. 1.	10)	1200 m/156 kbps, 900 m/625 kbps, 400 m/2.5 Mbps, 160 m/5 Mbps, 100 m/10 Mbps (Using repeaters, it is possible to extend the network distance up to 13.2 km)		
	rotal alotanoo, opood (Thion doing for into)		(Using repeaters, it is possible to extend the network distance up to 13.2 km)		

\*1. For CC-Link version 2.

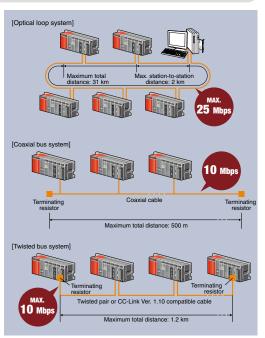
\*2. Using only remote I/O stations.



#### MELSECNET/H network

<ul> <li>MELSECNET/H network module Optical loop typeQJ71LP21-25, Q</li> </ul>	QJ71LP21S-25, QJ71LP21G,
	5, QJ72LP25G (Remote I/O station)
Coaxial bus type QJ71BF	R11, QJ72BR15 (Remote I/O station)
Twisted bus type	QJ71NT11B

- » MELSECNET/H network systems support controller-to-controller, controller-to-personal computer, and controller-to-remote I/O station communications. Multiple wiring types are available and many functions designed to increase reliability are included, such as support for redundant systems.
- » Coaxial bus type: Using low cost coaxial cable allows networks to be constructed at less cost than optical loop networks.
- » Twisted bus type: The combination of an affordable network module and twisted-pair cables allows a network system to be built at very low cost.



#### ■Performance Specifications

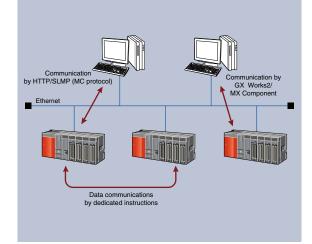
	Item				Specif	ication		
Network conf	figurations		Optical loo	op system	Coaxial b	us system	Twisted b	us system
Model			QJ71LP21(S)-25 QJ72LP25-25	QJ71LP21G QJ72LP25G	QJ71 QJ72	BR11 BR15	QJ71	NT11B
Cable			Fiber optic (SI)	Fiber optic (GI)	Coaxial (3C-2V)	Coaxial (5C-2V)	Twisted pair	CC-Link Ver. 1.10- compatible cable
	Maximum number of		16384	points (8192 points ir	the MELSECNET/10	mode)	16384 points	
	link points per network	LW	16384 points (8192 points in the MELSECNET/10 mode)			16384 points		
		LX/LY				points		
PLC to PLC network	Maximum number of link po	pints per station		• MELSECNET/H mode {(LY + LB) /8 + (2 x LW)} ≤ 2000 bytes • MELSECNET/H extended mode {(LY + LB) /8 + (2 x LW)} ≤ 35840 bytes				
	Number of stations per net	work	Up to 64 (1 control station, 6		Up to	32 stations (1 control	station, 31 normal sta	ations)
	Maximum number of	LB		ster to Remote Sub-r	points naster or Remote I/O: O to Remote Master:			
	link points per network	LW	16384 points (Remote Master to Remote Sub-master or Remote I/O: 8192 points, Remote Sub-master or Remote I/O to Remote Master: 8192 points)					
		LX/LY			points		]	
Remote I/O network	Maximum number of link points per station		<ul> <li>Remote Master to Remote I/O ((LY + LB) /8 + (2 × LW)) ≤ 1600 bytes</li> <li>Remote I/O to Remote Master ((LX + LB) /8 + (2 × LW)) ≤ 1600 bytes</li> <li>Multiplexed Remote Master from/to Multiplexed Remote Sub-master ((LY + LB) /8 + (2 × LW)) ≤ 2000 bytes</li> </ul>					-
	Maximum I/O points per remote I/O station		$X + Y \le 4096$ points If X/Y numbers are duplicated, only one side is taken into consideration.					
		М	8192 points			]		
	Device points per remote	SM			points			
	I/O station	D			points		-	
		SD	2048 points			-		
	Number of stations per net	work	Up to 65 stations station, 64 remo		station, 32 remo	(1 remote master ote I/O stations)		
Communication speed		25 Mbps/10 Mbps		10 Mbps			ps/625 kbps/1.25 /5 Mbps/10 Mbps	
Overall distance			30	km	300 m	500 m	1200 m/156 kbps, 600 m/312 kbps, 400 m/625 kbps, 200 m/1.25 Mbps	1200 m/156 kbps, 900 m/312 kbps, 600 m/625 kbps, 400 m/1.25 Mbps, 200 m/2.5 Mbps, 150 m/5 Mbps, 100 m/10 Mbps
Distance betw	ween stations		Up to 1 km	2 km				-

#### Interface module connectable with multiple Ethernet devices

#### • Ethernet interface module

10BASE-T/100BASE-TX ...... QJ71E71-100

- » Use dedicated instructions for communication between programmable controller CPUs.
- » A communication library and sample code is available to allow a web server to access any of the Ethernet modules and exchange information with the programmable controller CPU module. In this way, the web server may host a web page that allows remote operation of a programmable controller over the Internet via web browser.
- » To improve programming, maintenance, and debugging efficiency, multiple CPU connections may be established simultaneously using GX Developer and GX Works2.
- » The E-mail Function allows Ethernet modules to send e-mail with attachments in binary, ASCII, and CSV formats via a mail server.
- » Perform existence checks and keep connections open using the KeepAlive or PING functions. This can be used to ensure connectivity and quickly discover errors.

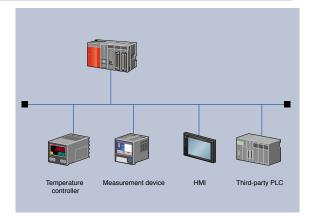


#### Connect with a large variety of devices using the MODBUS® interface module

MODBUS<sup>®</sup> interface module

RS-232 1ch, RS-422/485 1ch	QJ71MB91
10BASE-T/100BASE-TX	QJ71MT91

- » Using the master function, communicate with third-party MODBUS® compatible slave devices.
- » Slave mode is also supported, which allows communication with other MODBUS® masters such as third-party programmable controllers.
- » Using the QJ71MB91 synchronization function, a master station may be connected to CH1 (RS-232) and communicate with multiple slaves connected to the CH2 (RS-422/485) interface.
- » The QJ71MT91 module is able to operate using the master and slave functions simultaneously.

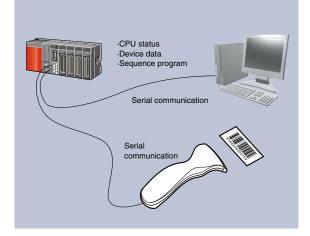


#### These highly flexible communications modules allow connection to practically any serial device

#### Serial communication module

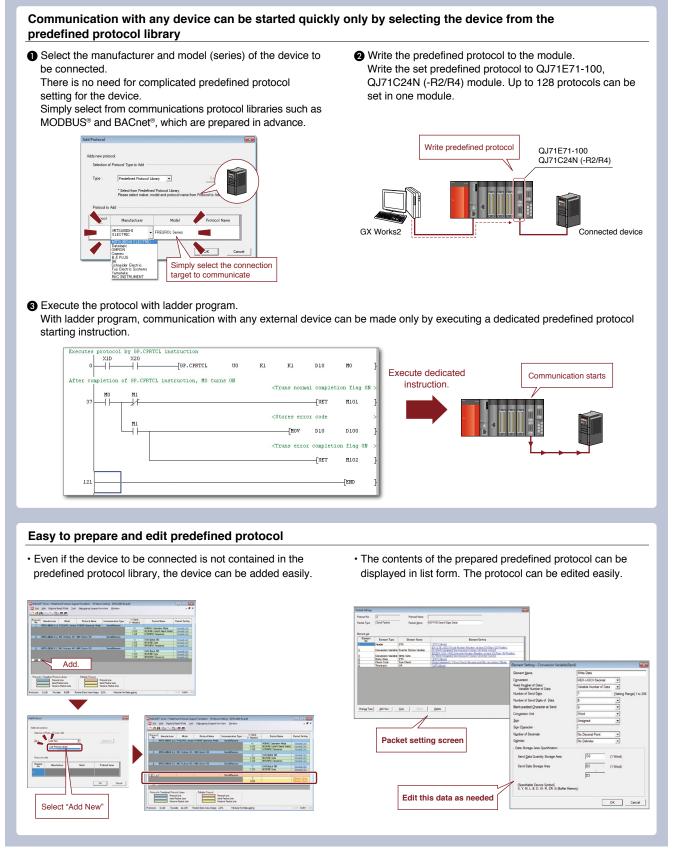
RS-232 1ch, RS-422/485 1ch	QJ71C24N
RS-232 2ch	QJ71C24N-R2
RS422/485 2ch	QJ71C24N-R4

- » Push the limits of serial technology: baud rates up to 230.4 kbps, distance up to 1200 m, and multiple block batch read/write up to 960 words from QCPU device memory.
- » External devices (personal computer, HMI, etc.) may read and write data in the programmable controller CPU using MC protocol.
- » Connect with intelligent devices using their native protocol (barcode reader, measurement device, etc.) by selecting non-procedure protocol and using a sequence program for communication control.
- » MELSOFT engineering software can establish a connection to the programmable controller CPU through the serial connection to perform programing and maintenance duties.
- » Dedicated functions are available to facilitate RS-232 communication over public telephone lines using a serial modem. One of them, the remote password function, prevents unauthorized access to programmable controllers via the modem line.





#### Combination of Ethernet/serial communication module and GX Works2 (predefined protocol support function)



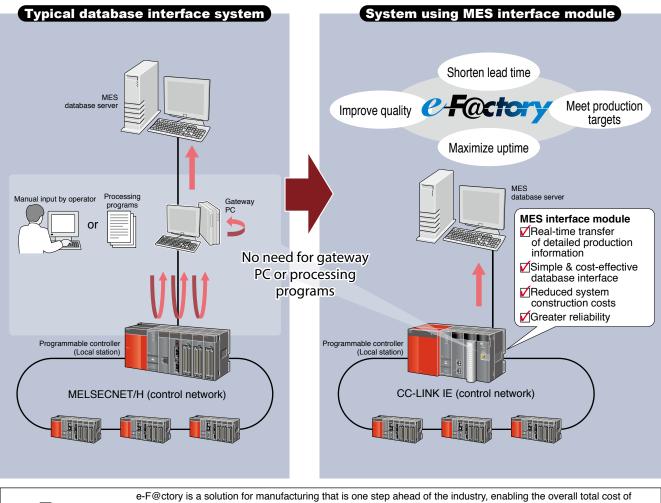
\* Supported by QJ71C24N (-R2/R4) with the function version B and a serial number whose first 5 digits are 11062 or higher.

\* Supported by products with the first five digits of the QJ71E71-100 product number of 15042 or later.

#### Make the jump from shop floor data to valuable information in real time

#### 

- » Simplify the process of connecting to enterprise system databases such as an MES\*1 by connecting directly. Configuration of the module is easy and does not require any programming.
- » When user-defined trigger conditions occur, the specified data is read and transferred via SQL text. This event-driven communication method reduces network loading when compared to conventional solutions, which are based on polling architecture.
- » Executes pre-registered SQL jobs. Also receives production instructions from MES and downloads production information from the database.
- MES (Manufacturing Execution System): A system that manages and controls production activities to \*1. optimize quality, production volume, delivery, costs, etc.



e-Factory

development, production and maintenance to be reduced through the utilization of FA and information-processing technologies that continuously support customer improvement activities. The result, increased corporate value for the customer.

#### Fulfill the need for traceability and discover a powerful troubleshooting tool

#### 

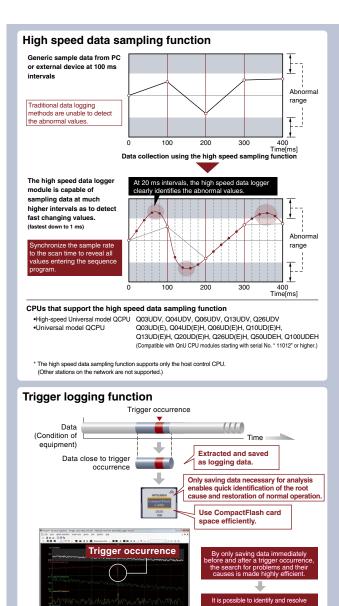
» High speed data sampling function

The high speed data sampling function has the power to synchronize with the sequence program scan, ensuring that every value available to the program is logged for analysis. Using this method, it is possible to perform detailed operational analysis and identify existing or potential problems.

» Trigger logging function

efore trigger occurrence

Trigger logging allows the user to specify, in great detail, when data should be saved. This greatly simplifies the process of investigating why a problem has occurred and assists in the quick identification of solutions. Additionally, it allows CompactFlash memory card space to be used efficiently.

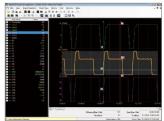


After trigge

- » The logging data display and analysis tool, GX LogViewer, has a simple and effective interface that is user customizable and includes features to maximize the efficiency of analyzing collected data. The High speed Data Logger Module Configuration Tool enables the user to create sophisticated data collection rules using an intuitive step-by-step process. The wizard like interface is beginner-friendly and includes features like importing global labels and device comments.
- » Automatic generation of reports including graphs
- By creating an Excel<sup>®</sup> layout file and transferring it to the module, the report function can automatically fill in the numbers using sampled data to create reports on a reoccurring basis. All kinds of reports may be created that include charts, graphs, and other visual aids. It is even possible to e-mail the reports automatically.

#### High speed data logger module tools

#### Data display and analysis tool: GX LogViewer



View a list of events or a trend graph [pictured left] either in real-time (online) or historical (saved file) modes. Helpful features ensure key information is immediately visible.

#### High speed data logger module configuration tool



Even making sophisticated data collection rules is easy to do using the intuitive step-by-step configuration process.

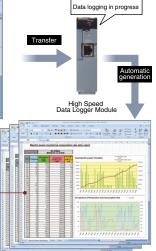
The High speed Data Logger Module Tools are available at no additional cost. Please contact your nearest Mitsubishi Electric representative for details.

#### Automatic generation of reports including graphs



Layout files (forms that are empty) are created in Excel<sup>®</sup> and transferred to the module using the configuration tool.

The layout file is automatically filled in with the specified sample data, time, etc. and saved as a new file. thus creating a report.



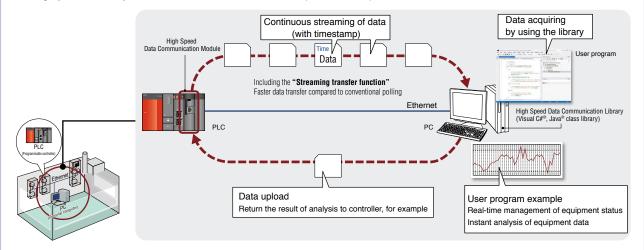
#### Supporting productivity and enhanced device value through real-time transfer of control data

#### ● High speed data communication module·······QJ71DC96

» High data accuracy communication from the programmable controller to the personal computer can be easily realized with the high-speed data communication module (QJ71DC96). Data can be streamed at high speed to the personal computer by synchronizing with the controller scan cycle without having to continuously poll data as was previously achieved. This feature realizes improved productivity by resulting in real-time control data analysis on the personal computer.

#### Fast and reliable large data transfer in real-time

• Transfer of large data volumes across a very short sampling period can be realized with "Streaming transfer" feature. High data integrity can be easily achieved across TCIP/IP Ethernet to personal computer based servers.

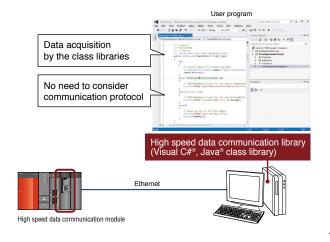


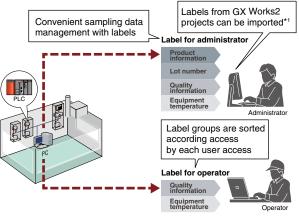
#### Data acquisition without considering protocol

 Communication between the module and a personal computer is provided in the form of Visual C#<sup>®</sup> and Java<sup>®</sup> class libraries. These class libraries enable a simple personal computer program to acquire data from the programmable controller without considering the communication protocol.

#### Labels for effective data sampling

 Labeling (naming) each personal computer data makes classifications of transferring data simple. Multiple labels are grouped and sorted as label groups by equipment or user.
 Label group access control corresponding to user levels is also possible.





\*1. The engineering software GX Works2 Version 1.44 W or later is required when the global labels of GX Works2 project are imported to the Configuration Tool of this module.

#### Ethernet related products

#### Industrial switching hub NZ2EHG-T8N\*1

#### Powered by CONTEC

- » Supports the transmission speed of 10 Mbps/100 Mbps/1 Gbps.
- » Equipped with Auto MDI/MDI-X and auto-negotiation functions.
- » Saves up to 60% power consumption\*<sup>2</sup> by using the automatic power adjustment function.
- » Operates in ambient temperatures of 0 to  $50C^{\circ}$ , with the fan-less configuration.
- » Compatible with DIN rail installation, enabling the hub to be installed in various orientations.

#### \*1. The rated input voltage is 12 to 24 V DC.

\*2. For comparison, power consumption was measured when all 8 ports were used and not used.

This product was developed and manufactured by Contec Co. Ltd. Please note that the specifications and conditions of guarantee differ from MELSEC Series products.

#### Managed CC-Link IE switch NZ2MHG-T8F2\*3

- » Supports the transmission speed of 10 Mbps/100 Mbps/1 Gbps
- » Connectable to CC-Link IE and Ethernet devices simultaneously
- » ERP- and LA- style redundant topologies between switches continue communication at network failure including cable disconnection, by switching network paths
- » With an SFP transceiver\*4, long-distance optical cable, which is ideal for systems requiring facility-to-facility landline communication is available
- » Supports VLAN and can manage multiple networks by one switch
- » Supports SNMP, which enables monitoring of the entire network and easy identification of faulty areas (system maintainability is improved with this feature)

\*3. The rated input voltage is 24 V DC.

\*4. Either the optical port (OPT1/OPT2) or RJ45 port (P1/P2) can be used at a time.



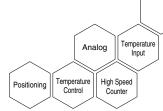




### Module Lineup

# Comprehensive range of I/O and intelligent function modules

The Q Series I/O and intelligent function module lineup is extensive and capable of meeting the needs of a wide range of applications. Some of the available modules include motion control, serial communication, temperature control, temperature input, standard digital and analog I/O modules, and channel isolated analog modules. Attain the ideal solution for the application, whether it be high speed positioning or high accuracy temperature control.



#### Input modules, Interrupt module

	DC input						AC i	nput
Point	5 V	DC	5/12 V DC	24 V	DC	48 V DC/AC	100120 V AC	100240 V AC
	Positive	Negative	Positive/Negative	Positive	Negative	Positive/Negative	100120 V AC	100240 V AC
8 points	-	-	-	-	-	-	-	QX28
16 points	QX70H	QX90H	QX70	QX40 QX40-TS QX40-S1 QX40H QI60	QX80 QX80H QX80-TS	QX50	QX10 QX10-TS	-
32 points	-	-	QX71	QX41 QX41-S1 QX41-S2	QX81 QX81-S2	-	-	-
64 points	-	-	QX72	QX42 QX42-S1	QX82 QX82-S1	-	-	-

#### **Output modules**

	Contact output	TRIAC output		Transistor output			
Point	24 V DC, 240 V AC	100240 V AC	512 V DC	524 V DC		1224 V DC	
	24 V DC, 240 V AC	100240 V AC	Sink type	Sink type	Sink/Source type	Sink type	Source type
8 points	QY18A	-	-	-	QY68A	-	-
16 points	QY10 QY10-TS	QY22	QY70	-	-	QY40P QY40P-TS QY50	QY80 QY80-TS
32 points	-	-	QY71	QY41H	-	QY41P	QY81P
64 points	-	-	-	-	-	QY42P	QY82P

#### I/O combined module

I/O points	DC input/transistor output 24 V DC positive/1224 V DC sink type		
8 points/7 points	QX48Y57		
32 points/32 points	QH42P (occupy 32 points) QX41Y41P (occupy 64 points)		

	_			
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Ana	iuu	mou	u	ies.
	- J			

					Analog input				Analog	output
Number of	Channel			Signal			Temperature input		Voltage	Current
channels isolated	isolated	Voltage input	Current input	Current input conditioning	Load cell	CT input	Temperature input	RTD	output	output
1	٠	-	-	-	Q61LD	-	-	-	-	-
	٠	-	-	Q62AD-DGH	-	-	-	-	Q62D	A-FG
2	-	-	-	-	-	-	-	-	Q62D Q64A	AN D2DA*1
	•	Q64A	D-GH	-	-	-	Q64TD Q64TDV-GH	Q64RD-G	-	-
4	-	Q64A Q64A Q64A		-	-	-	-	Q64RD	Q64D Q64D	
6	٠	-	-	Q66AD-DG	-	-	-	-	Q66D	A-G
8	•	Q68A	D-G	-	-	-	Q68TD-G-H01 Q68TD-G-H02	Q68RD3-G	-	-
	-	Q68ADV	Q68ADI	-	-	Q68CT	-	-	Q68DAVN	Q68DAIN

\*1. I/O combined module

#### Temperature control modules

Number of	Wire break	Ing	put	
channels	detection	Thermocouple	RTD	
4	•	Q64TCTTBWN	Q64TCRTBWN	
4	-	Q64TCTTN	Q64TCRTN	

#### Simple motion modules

Number of axes	CC-Link IE Field	SSCNETI/H
2	-	QD77MS2
4	QD77GF4	QD77MS4
8	QD77GF8	-
16	QD77GF16	QD77MS16

#### Positioning modules

Number of over	Specialized fur	nctionality type	Simple control and fast-response type		
Number of axes	Open collector output	Differential drive output	Open collector output	Differential drive output	
1	QD75P1N	QD75D1N	-	-	
2	QD75P2N	QD75D2N	-	-	
3	-	-	-	-	
4	QD75P4N	QD75D4N	QD70P4	QD70D4	
8	-	-	QD70P8	QD70D8	

#### High-speed counter modules, Pulse input module

Number of channels		Maximum counting	Channel isolated	Input specifications				
		speed		5 V DC	12 V DC	24 V DC	Differential drive output	
		200 kpps			QD62 QD62E QD65PD2		-	
2	2-phase input	500 kpps	-	-	-	-	QD62D	
		4 Mpps		-	-	-	QD64D2	
		8 Mpps		-	-	-	QD65PD2	
6	2-phase input	200 kpps	-	QD63P6	-	-	-	
8	1-phase input	30 kpps	•		QD60P8-G		-	

#### Energy measuring modules, Insulation monitoring module

Number of channels	Energy measuring	Insulation monitoring
1	QE81WH QE81WH4W	-
2	-	QE82LG
3	QE83WH4W	-
4	QE84WH	-

#### Loop control module

Number of	Input					
channels	Voltage	Current	Thermocouple	RTD		
2	Q62HLC					

## **Application specific intelligent modules**

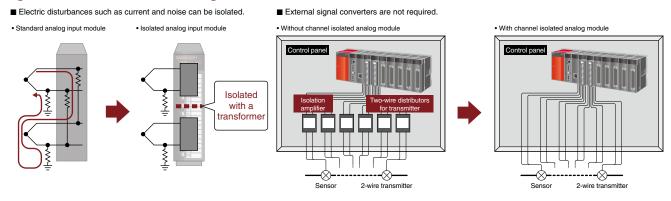
#### A range of analog modules ideal for process control applications

#### Isolated analog modules suitable for process control

<ul> <li>Channel isolated high resolution analog-digital converter module</li> <li>Q64AD-GH</li> </ul>	System configuration example
Channel isolated high resolution analog-digital converter module     (with signal conditioning function)	
<ul> <li>Channel isolated high resolution digital-analog converter module</li> <li>Q62DA-FG</li> </ul>	
Channel isolated analog-digital converter moduleQ68AD-G	Analog input sig
<ul> <li>Channel isolated analog-digital converter module (with signal conditioning function)</li> </ul>	
Channel isolated digital-analog converter module	

The channel isolated analog modules are specifically designed for process control applications by offering high accuracy conversion combined with high isolation voltage. Flow meters, pressure gauges, etc. can be directly connected to the analog input, and control valves to the analog output. Hardware and installation costs can be substantially reduced because external isolation amplifiers are not required. When used with a general purpose controller, a low cost process control solution can be created.

#### High dielectric withstand voltage



#### High conversion speed analog modules

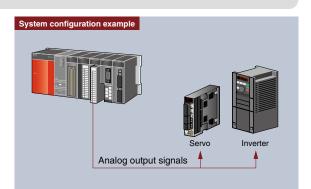
- High speed analog-digital converter module
   Q64ADH

- Digital-analog converter module

#### Q62DAN, Q64DAN, Q68DAVN, Q68DAIN

Analog-digital/Digital-analog converter module ........ Q64AD2DA

Many high-speed A/D and D/A conversion (analog) modules are available. These modules are feature packed to allow maximum flexibility when connecting to devices. Both speed and accuracy are great enough to control sensitive motion applications using servos or inverters.



Flow rate Temperate Pressure

Voltag Power

gnals



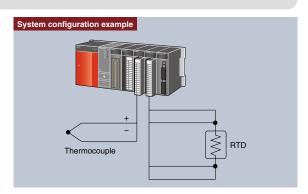
#### High accuracy temperature input modules

• Temperature input module

Thermocouple input module ......Q64TD, Q64TDV-GH, Q68TD-G-H01, Q68TD-G-H02

RTD input module ...... Q64RD, Q64RD-G, Q68RD3-G

Temperature data can be captured by connecting a thermocouple or a resistance temperature detector. Multi-channel (8-channel) input types and channel-isolated types are available. An optimum model for the intended application can be selected.



Control

panel

СТ

System configuration example

Temperature

Heater

#### PID loop control integrated temperature control modules

Q64TCTTBWN Platinum RTD input module Q64TCRTN, Q64TCRTBWN

The devices which require high stability of temperature control such as extrusion forming machines, these modules prevent overheating and overcooling. The standard control (heating or cooling) or heating-cooling control (heating and cooling) mode can be selected depending on the machine to be controlled.

In addition, the mixed control mode (combination of standard control and heating-cooling control) can be selected.

#### Peak current suppression function

This function avoids simultaneously turning on outputs to control the peak current. It can save energy and reduce the running cost.

- Simultaneous temperature rise function
- This function allows several loops to reach the set value at the same time to conduct uniform temperature control.

It prevents idling and is effective in saving energy and reducing running cost.

Self-tuning function

The PID constant is automatically adjusted during control.

The automatic tuning cost (time, materials and power) can be reduced.

#### Loop control module ideal for temperature and flow rate control environments which require fast response

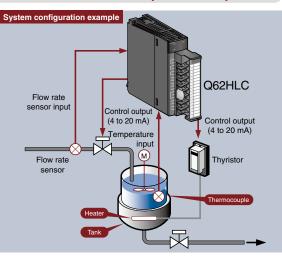
Loop control module
 Q62HLC

With its speed-proportional control format and 25 ms sampling cycle, the loop control module is well suited for high-precision, high-resolution thermocouple inputs, micro voltage inputs, voltage inputs, current inputs, and current outputs. It is also ideal for sudden temperature change control,

• Connectable to JIS, IEC, NBS, ASTM standards compliant thermocouples.

pressure control, and flow control applications which require fast response.

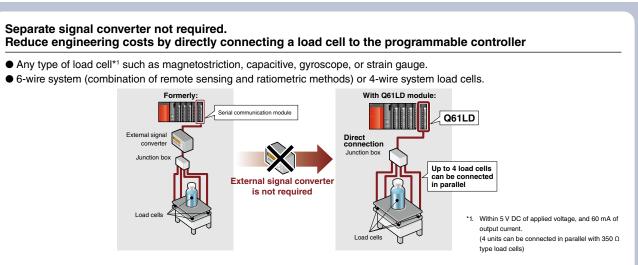
- Permits analog value measurements of various input ranges by using micro voltage, voltage, and current input sensors.
- Offers program control while automatically changing the target values (SV) and PID constants [proportional band (P), integral time (I), derivative time (D)] in a time-specific manner, as well as a cascade control function that permits control with CH 1 as the primary loop, and CH 2 as the secondary loop.



#### Interface with all types of load cell with the load cell I/P module

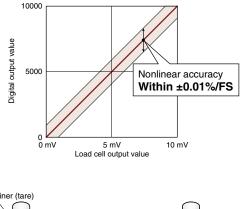
#### Load cell input module Q61LD

Load cells can now be directly connected to the programmable controller system without requiring an external signal converter. The module achieves highly accurate measurement with steady data conversion speed that guarantees the accuracy of load cells.



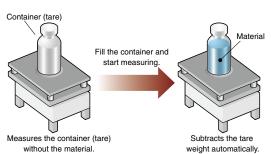
Applications requiring high accuracy can be achieved by connecting the load cell directly to the programmable controller.

- Nonlinear accuracy: Within ±0.01%/FS
- Zero drift: Within ±0.25 μV/°C RTI
- Gain drift: Within ±15 ppm/°C
- (Load cell rated output is 2 mV/V, ambient temperature is 25°C, and the tare weight subtraction function is not used.)



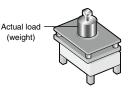
#### Zero offset function

This function subtracts the tare weight automatically relative to the load cell usage range when calibrating measuring instruments. Using this function can improve the accuracy of the measuring instrument.



#### Static load calibration function

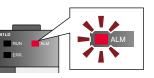
The gross weight value can be accurately calibrated by applying the actual load (weight) onto the load cell.



#### Input signal error detection function

Load cell input signal errors can be detected.

- Input signal error
- Weight capacity over error
- · Zero point out of range Exceed conversion error



#### Direct CT sensor connection reduces wiring and saves space

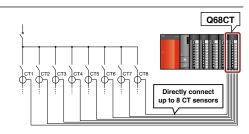
#### • CT input module Q68CT

The direct connection of the CT sensor\*1 and the programmable controller has eliminated the need to connect a separate signal converter. Very accurate measurements can be achieved with stable data conversion speed for load control of systems and devices, monitoring of operations, and control and monitoring of power systems.

\*1. The CT (Current Transformer) sensor refers to an instrument transformer, a current sensor is essential for measuring alternating currents.

#### Direct CT sensor connection reduces wiring and saves space

- Directly connect to the CT sensor without an external signal converter. The AC current for up to eight channels can be measured with one unit, by that reducing the wiring steps and costs.
- Set the CT sensor type (input range) for each channel. CT sensors with 0 to 5 A AC or 0 to 600 A AC can be used by one unit.



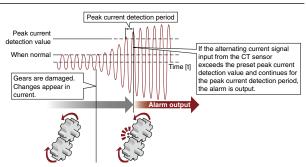
#### Predictive maintenance of devices by detecting the peak current.

#### Peak current detection function

• The device can be serviced and troubleshooting performed by detecting the peak current.

With a motor for example, the load applied on the motor is changed by the gear wear and damage, and the load current suddenly changes. The device trouble can be diagnosed by detecting the transient peak current at this time.

Detection level



#### Input signal error detection function

Input range setting

• Over-range (peak value over) of the CT input value can be detected. Since the flow of a large current exceeding the range of the measurement target can be detected, errors in the measurement target can be monitored.

1						
05 A (AC)	Approxi	imately 6.25 A (AC)	Alternati	ing current waveform		Returns to
050 A (AC)	Approxi	imately 62.5 A (AC)			occurrence Athe r	neasurement range
0100 A (AC)	Approx	timately 125 A (AC)		Peak value		-
0200 A (AC)	Approx	imately 250 A (AC)		Ţ	$ \land \land \land$	Current value from the CT
0400 A (AC)	Approx	imately 500 A (AC)	1	Input range (	h / / / /	$(1) \land \land$
0600 A (AC)	Approx	imately 750 A (AC)	measure	ement range		Time
Connectable CT	sensors			Destructure		
Model	Manufacturer	Analog input range		Peak value		Sampling cycle
EMU-CT50		050 A (AC)		Input signal	ON	
EMU-CT100	Mitsubishi Electric Corporation	0100 A (AC)		error detection flag	OFF	OFF
EMU-CT400		0400 A (AC)		g		UFF
EMU-CT600		0600 A (AC)		Conversion	ON	ON
CTF-5A		05 A (AC)		completed flag	OFF	
CTF-50A	Multi Measuring	050 A (AC)			Value before the	Value returned to
CTF-100A	Instruments	0100 A (AC)		Digital output value	over-range occurrence	the measurement range
CTF-200A	Co., Ltd. (introduced	0200 A (AC)				ON
CTF-400A	products)	0400 A (AC)		Error clear request		
CTF-600A		0600 A (AC)			OFF	OFF
CTL-10-3FC		05 A (AC), 050 A (AC)	)			
CTL-16-3FC	U.R.D. Co., Ltd.	0100 A (AC)				
CTL-24-3FC	(introduced	0200 A (AC)				
CTL-36-6SC	products)	0400 A (AC)				
CTT-36-9SC		0600 A (AC)				

#### Simple motion module for positioning control and synchronous control

#### Advanced control but simple use

Speed/torgue control and synchronous control are supported in addition to the traditional positioning control. Using the "simple motion module setting tool," operations such as positioning setting, monitoring and debugging can be performed easily. In addition, data synchronized with the motion controller can be collected and displayed in waveform.

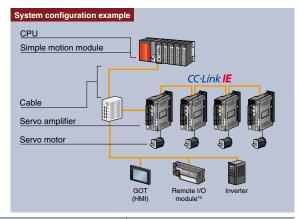
#### • Simple motion module

#### CC-Link IE Field Network connection type ...... QD77GF

The 
in the above model indicates the number of axes (4, 8, 16). The simple motion module supports the general purpose CC-Link IE Field Network, with its flexible wiring. This module can be used as the CC-Link IE Field's master station\*1 while retaining the simple motion module's functions. This realizes flexible networking

supporting connection to various devices such as GOT(HMI), remote I/O, inverter, etc. \*1. QD77GF4, QD77GF8, QD77GF16 master station transmission style can use the line type or star type. Up to 104 remote devices can be connected to one network.

\*2. The setting and diagnosis function using GX Works2 is disabled.



		QD77GF4	QD7	7GF8	QD77GF16		
Maximum number of control axes		4-axes	8-axes		16-axes		
Servo amplifier connection method		CC-Link IE Field Network					
Maximum distance between stations			10	0 m			
Control system		PTP (Point to Point) control, path control (both linear and arc can be set), speed control, speed/position switching control, position/speed switching control, speed-torque control, synchronous control, electronic cam control					
	1-axis linear control						
	1-axis speed control						
	2-axis linear interpolation control						
	2-axis circular interpolation control		Operation cycle	Starting time			
Starting	2-axis speed control		0.88 ms	1.77 ms			
time	· ·		1.77 ms	3.55 ms			
	3-axis linear interpolation control		3.55 ms	7.11 ms			
	3-axis speed control						
	4-axis linear interpolation control						
	4-axis speed control						

#### SSCNETI/H connection type----- QD77MS

The  $\Box$  in the above model indicates the number of axes (2, 4, 16). The SSCNET  $\mathbbm/H$  connection reduces wiring, enables connections of up to 100 m between stations, and easily supports absolute position settings. The upper limit LS, lower limit LS, and near-point dog signals can be input from the servo amplifier, thus greatly reducing wiring. In addition to positioning control and speed control, processes such as synchronous control and electronic cam control can be performed.

System configuration example	
CPU Simple motion module Cable Servo amplifier Servo motor	

		QD77MS2	QD77MS4	QD77MS16		
Maximum number of control axes		2-axes	4-axes	16-axes		
Servo amp	lifier connection method		SSCNETI/H			
Maximum o	distance between stations		100 m			
Control system		PTP (Point to Point) control, path control (both linear and arc can be set), speed control, speed/position switching control, position/speed switching control, speed-torque control (press-fit control), synchronous control, electronic cam control, torque control, tightening & press-fit control				
	1-axis linear control					
	1-axis speed control					
	2-axis linear interpolation control	0.88 ms				
	2-axis circular interpolation control					
Starting time	2-axis speed control		0.88 ms	1.77 ms		
	3-axis linear interpolation control					
	3-axis speed control					
	4-axis linear interpolation control	-				
	4-axis speed control					

#### A large selection of motion control solutions are available to fit any motion application.

#### High-speed, accurate positioning control

Various types of motion control are supported including 2 to 4-axis linear interpolation, 2-axis circular interpolation, speed control, speed/ position changeover, path control and constant speed control. Making settings (including positioning data), monitoring, and debugging is made much easier using GX Works2's built-in intelligent function module tools or the stand-alone tool, GX Configurator-QP. For servo control, Q Series leverages the benefits of SSCNET, a Mitsubishi high performance motion control network. This allows Mitsubishi intelligent digital servos to be connected by a simple daisy chain cable that reduces cost and increases performance.

#### Positioning module

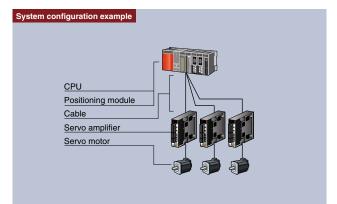
Open collector pulse train output type ......QD75P

Differential driver pulse train output type ...... QD75D N

The  $\Box$  in the above model indicates the number of axes (1, 2, 4). For compatibility with the widest range of motion hardware, both open collector and differential driver type positioning modules are available. Transmission of high-speed pulses, up to 4 Mpps, to a servo amplifier can be made reliably up to 10 meters away. These pulse train output positioning modules can provide a high level of speed and accuracy for practically any application.

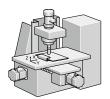
		QD75P⊟N	QD75D⊡N	
Pulse train outp	out format	Open collector output Differential drive		
Max. output pul	se	200 kpps	4 Mpps	
Max. connectio	n distance to drive unit	2 m	10 m	
Control system		PTP (Point To Point) control and helical can be set), spe switching control, position-s	ed control, speed-position	
	1-axis linear control	1.5	ms	
	1-axis speed control	1.5	ms	
	2-axis linear interpolation control	1.5 ms		
	2-axis circular interpolation control	2.0 ms		
	2-axis speed control	1.5 ms		
Starting time*1	3-axis linear interpolation control	1.7 ms		
	3-axis helical interpolation control	2.6 ms		
	3-axis speed control	1.7 ms		
	4-axis linear interpolation control	1.8 ms		
	4-axis speed control	1.8 ms		

\*1. Using the pre-reading start function, the actual starting time can be shortened.



Application example > X-Y table control
Function
2-axis linear interpolation

- 3-axis linear interpolation
- 2-axis circular interpolation
- Constant speed pass control
- 3-axis helical interpolation



#### The ideal solution for simple multi-axis positioning

These modules are ideal for high-speed linear positioning control in a multi-axis system. Easily satisfying the requirements for simple positioning control applications, these modules include functions, such as positioning control, speed control and variable positioning control.

#### Positioning module

Open collector pulse train output type ......QD70P

These modules are a great match for stepper motor control. Acceleration and deceleration can be performed smoothly with very fine changes in speed. "Fast start processing" is a basic feature that allows for a single axis positioning start time of just 0.1 ms.

		QD70P□	QD70D	
Pulse train	n output format	Open collector output	Differential drive output	
Max. output pulse		200 kpps	4 Mpps	
Max. connection distance to drive unit		2 m 10 m		
Control system		PTP (Point To Point) control, path control (linear only), speed-position switching control		
	1-axis start	0.1 ms		
Starting time	4-axis simultaneous start*1	0.2 ms		
8-axis simultaneous start*1		0.4 ms		

\*1. When START signal switches ON within 1 scan. There are no start delays between axes.

# System configuration example

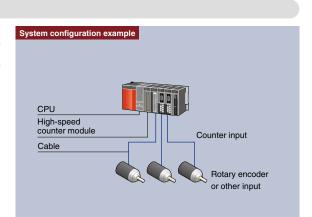
# A selection of high-speed counter modules and pulse counter module for accuracy intensive, high resolution control applications is available

#### Pulse input modules capable of high-speed counting

• High-speed counter module Standard typeQD62, QD62E, QD62D
Multi-channel high-speed counter module
4 Mpps compatible high-speed counter moduleQD64D2
Multi-function counter/timer module
Inputs may be connected to a variaty of devices for positioning control

Inputs may be connected to a variety of devices for positioning control, precision measurement, etc. The maximum counting speed may be adjusted via parameter (excluding QD64D2) for more reliable counting at lower frequencies.

- » External coincidence output (QD64D2 includes 2 per channel): Select coincidence output, continuous comparison (QD64D2 only), or the coincidence detection interrupt function for flexible high-speed external device control.
- » Many functions are available to satisfy application requirements including the coincidence output test function (QD64D2 only), latch counter function (excluding QD63P6), and preset function.
- » Calculate pulses at speeds up to 8 Mpps (4 multiples of 2 phases). Perform precise position tracking using a high-resolution encoder for demanding applications such as semiconductor and LCD manufacturing. (QD65PD2)



		QD62 (DC input sinking output type)	QD62E (DC input sourcing output type)	QD62D (differential input sinking output type)	QD63P6 (DC input)	QD64D2 (DC input, sink output type)	QD65PD2 (DC/Differential input, external output terminals)
Number of ch	er of channels 2 channels 2 channels 2 channels 2 channels 2 channels				2 channels		
	Phase				phase input, 2-phase in	put, CW/CCW	
Count input signal	Signal level	5/12/24 V DC 25 mA		mA level (AM26LS31 [maximizatured by Texas Instruments] maximizatured by Texas Instruments]		[Differential input] EIA Standards RS-422-A, differential line driver level (AM26LS31 [manufactured by Texas Instruments] or equivalent) [DC input] 5/12/24 V DC, 710 mA	
	Pulse input			1-phase pulse input (x1, x2), CW/CCW, 2-phase (x1, x2, x4)			
Counting spe	ed (max.)	200	kpps	500 kpps	200 kpps	4 Mpps	[Differential input]······8 Mpps [DC input]······200 kpps
Counting speed (max.)		Ring counter function	Linear counter function     Ring counter function     Coincidence output function		Linear counter function     Ring counter function     Coincidence     detection function     Preset function     Periodic pulse     counter function	Linear counter function     Ring counter function     Coincidence detection     function     Continuous comparison     function     Preset function     Latch counter function	Coincidence output function     Cam switch function     Preset/replace function     Latch counter function     Count disable function

# Multi-function counter/timer module (QD65PD2) • Perform extremely accurate position tracking

- Counting speed up to 8 Mpps (4 multiples of 2 phases)
  - Maximum counting speed 8 Mpps
- Multiple functions designed for ease of use
   Pulse measurement function
   With a resolution of 100 ns, it is possible to perform highly accurate pulse measurement.
- PWM output function
  - Precisely control PWM output up to 200 kHz. With a resolution of 0.1  $\mu s,$  superfine control of the duty cycle is possible.
  - Cam switch function
  - Configure up to 16 cam settings and use up to 8 dedicated outputs. The cam switch function enables highly accurate timing control.
  - Perform sophisticated control using coincidence detection The coincidence output function allows complex applications to be supported. Depending on the situation, either the cam switch function or the coincidence output function can be used.

#### Channel isolated pulse input module QD60P8-G

This module is appropriate for the measurement of input pulse counts (related to speed, revolution, instantaneous flow rate, etc.) and the measurement of quantities (length, cumulative flow, and so forth). The QD60P8-G operates on a 10 ms control cycle, thus the minimum value refresh time is 10 ms. The count cycle setting can be changed to the desired time for cumulative count values and moving average pulse counts (sampling pulse counts).

		QD60P8-G	
Number of channels		8 channels	
	Phase	1-phase input	
Count input signal	Signal level	5 V DC/1224 V DC, ≥ 4 mA	
orginar	Pulse input	1-phase pulse input	
Counting speed (max.)		30 k/10 k/1 k/100/50/10/1/0.1 pps	

# Power measuring and insulation monitoring modules for easily measuring various energy information

#### Rack installation type energy measuring module

- Energy measuring module QE81WH
- Energy measuring module (multi-circuit) ...... QE84WH
- Energy measuring module (three-phase 4-wire product) ....... QE81WH4W
- Energy measuring module (multi-circuit, three-phase 4-wire product) -- QE83WH4W

Using only one module, highly detailed information about electric energy (consumption and regeneration), reactive energy, current, voltage, electric power, power factor, and frequency can be measured. Minimum and maximum values are constantly monitored and 2 types of upper/lower limit warnings can be implemented without any programming. The amount of electric power used by output devices only while ON can be measured.

The power rate during device operation and the power rate in takt units can be retrieved. The multi-circuit product allows power to be measured in a smaller space as up to four circuits can be measured with a three-phase 3-wire product in one slot, and up to three circuits with a three-phase 4-wire product. For example, one unit can be used to measure other loads from the control panel trunk.

In addition, the parameters can be set easily with GX Works2 (Version 1.91 V and higher).

N	Model	QE81WH QE84WH*1		QE81WH4W	QE83WH4W*1	
Phase v	wire system	Single-phase 2-wire/single-phase 3-wire/three-phase 3-wire		Three-phase 4-wire*2		
		110 V AC, 220 (single-phase 2-wire,		63.5/110 V AC277/480 V AC		
D	Voltage circuit	110 V AC (1 - 2 220 V AC (1 - 3 line)	line, 2 - 3 line) (single-phase 3-wire)			
Instrument rating		Using two-stage configuration in combination with commercially-avai voltage transformer (VT). Primary voltage value can be set up to 6,6				
strume	Current	50, 100, 250, 400, 600 A AC (Using dedicated split type current sensor. Each value indicates current sensor's primary current value.)				
드	circuit			AC nt sensor is used with th rimary current value car		
	Frequency	50/60 Hz (frequency automatically judged)				
Number of measurement circuits		1 circuit	4 circuits	1 circuit	3 circuits	
Measurement items		Power rate (c regenerative), rate, period pow voltage, power, power factor	reactive power ver rate, current, reactive power,	Power rate (consumption, regenerative), reactive power rate, period power rate, current, voltage, power, reactive power, apparent power rate, power factory, frequency		

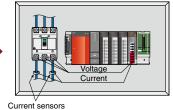
 Current measurement mode is provided. Up to eight circuits can be measured when measuring only the current value.

 The separate voltage transformer (QE8WH4VT) is required for the three-phase 4-wire compatible products.

#### Minimal impact on control panel layout

 By installing the energy measuring module onto the open slot of the base unit, measuring instrument can be added without changing the layout in the control panel.





#### Allows for detailed power measurement at high speed (250 ms)

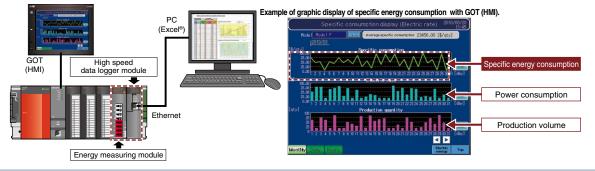
- Allows for easy specific energy consumption<sup>\*3</sup> management by matching the "production information" of the CPU module with the "energy information" of the energy measuring module.
- Since measured data is automatically collected in a buffer memory at 250 ms, detailed specific energy consumption management is also available.



\*3. The specific energy consumption is a numerical value displayed by "dividing energy consumption by production volume," which is one type of index that measures energy productivity. Improving this number leads to improved productivity and energy conservation

#### Allows for easy construction of a "visualization" system

- Allows for easy graphic display of specific energy consumption with a GOT (HMI) installed on the control panel at the manufacturing site.
- Combination with the "high-speed data logger module (QD81DL96)" allows specific energy consumption analysis to be easily performed with a personal computer.





#### Insulation monitoring module measuring leakage current

Insulation monitoring module ......
 QE82LG

Leakage current can be measured for safety measures. Risks of electric shock are detected by monitoring leakage current (Io).

The isolated state of equipment can be constantly monitored.

The resistive leakage current (lor) is measured to constantly monitor the deterioration of equipment insulation.

Two-stage warning is provided for each measurement item. Two-stage warning for each of leakage current (Io) and resistive leakage current (Ior) can be issued via program-less communication. The two-stage warning function can be used to give a warning for calling for attention and a hazard warning. One module can monitor two circuits. One module can monitor two circuits of power supplies of the same phase/wire type on the same system.

In addition, the parameters can be set easily with GX Works2 (Version 1.91V and higher).

#### Measurement items

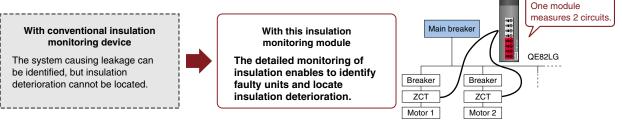
Leakage current (Io) and resistive leakage current (Ior)

	Mo	del	Details	
Phase/wire type			Common to single-phase 2-wire and single-phase 3-wire/three-phase 3-wire types	
		Single-phase 2-wire Three-phase 3-wire	Common to 110 V AC and 220 V AC	
Instrument ratings		Single-phase 3-wire	110 V AC (between wires 1 and 2, between wires 2 and 3), 220 V AC (between wires 1 and 3)	
	Leakage current circuit		1 A AC (ZCT is used. Primary current of ZCT	
	Frequency		50/60 Hz (automatic discrimination of frequency)	
Number of circuits which can be monitored			2 circuits*3	

- \*1. The module can be connected directly to 110-V and 220-V power supplies. To connect to a 440-V power supply, an external voltage transformer (VT) is necessary. Leakage current cannot be measured if voltage input is not provided.
- \*2. Resistive leakage current (lor) can be measured on single-phase 3-wire and three-phase 3-wire delta circuits. On special circuits, such as three-phase 3-wire star circuits, highresistance grounding circuits and capacitor grounding circuits, only lo can be measured.
- \*3. Leakage current (Io, Ior) measurement on CH1 and CH2 can be performed only on circuits on the same system as the voltage input.

#### Early detection of insulation deterioration of production equipment

- The structure directly connected to programmable controller in the control panel saves space and facilitates measurement of leakage current in places close to loads.
- Failures caused by leakage (earth fault) and insulation of motor loads in production equipment can be monitored. Progression of insulation deterioration is not overlooked.
- The upper limit warning monitor can be set in two stages. Insulation deterioration and condition can be observed at an early stage, so that preventive measures can be taken before production equipment suddenly stops or goes down.



#### lor method realizes constant monitoring of insulation deterioration of equipment

• With the conventional systems, such as inverter circuits with large capacitive leakage current (loc), it has difficulty for insulation monitoring.

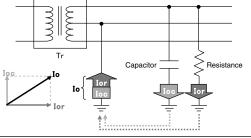
The module is capable of measuring resistive leakage current (lor) and removes the capacitive leakage current then monitors the accurate leakage current caused by insulation deterioration.

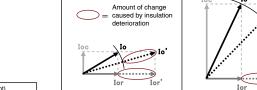
 Resistive leakage current (lor) is constantly measured even during operation of equipment. Signs of insulation deterioration can be detected without power interruption.

Leakage current (lo) is affected by capacitive leakage current (loc) of entire equipment.

Therefore, resistive leakage current (lor) measurement is effective in diagnosis of insulation deterioration.

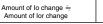
■Method of measuring leakage current (lo measurement and lor measurement)





When loc is low

Ior: Leakage current caused by insulation deterioration (resistive component in the leakage current) Ioc: Leakage current (capacitive component of leakage current) flowing even if insulation is in good conditio Io: Leakage current obtained by synthesizing Ior and Ioc (vector synthesis)



 Capacitive leakage current (loc) fluctuates in equipment with long wiring or equipment with inverter devices and filters

When loc is high

Amount of Io change <

Amount of lor change



**MELSOFT** integrated FA software

Software

Automation has brought tremendous productivity benefits to industrial and commercial applications. By creating the MELSOFT integrated FA software family of products, Mitsubishi Electric is aiming to bring similar productivity benefits to system designers, automation engineers, operators, and maintenance personnel. MELSOFT engineering tools are undergoing continuous evolution in order to meet the demands of new technologies and applications.

#### Programmable Controller Engineering Software

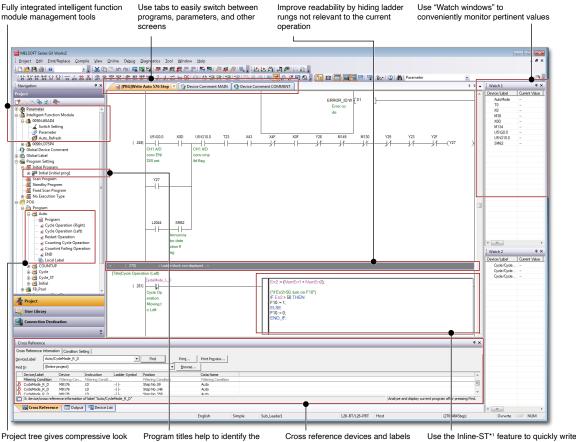
#### **GX Works2**

# GX WorksZ

GX Works2 focuses on driving down total cost by including features that speed up commissioning, reduce downtime, improve programming productivity, and provide strong security.

#### • User interface that is "easy to use" by design

The programming tool GX Works2 has been developed from the ground up to be intuitive for all users and allow anyone to begin programming easily. The user interface and other functions provide a comfortable programming environment that enables improvements in design efficiency.

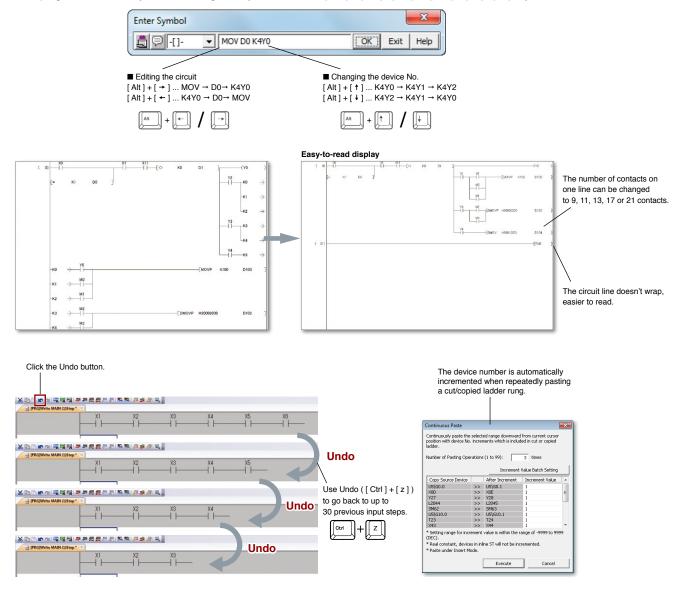


at flow of information in program content of each program with ease complex expressions in ladder programs and structure

\*1. In-line ST can be only be created in projects that use labels.

#### • Easily create circuits with few key inputs

The program can be easily modified using the keyboard shortcut [Alt] + [  $\leftarrow$  ] / [  $\rightarrow$  ] or [Alt] + [  $\uparrow$  ] / [  $\downarrow$  ] keys.



#### • Efficiently edit lines with keyboard

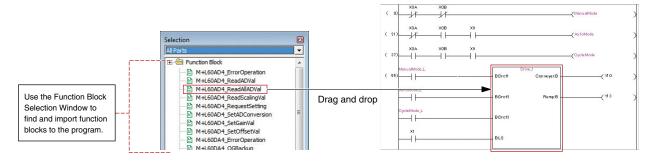
Ladder rungs can be easily modified just by using the various keyboard shortcut keys, eliminating the need to switch to editing mode.

	(Y10	>
	KM1	>
Input line with $\boxed{\texttt{Ourl}} + \boxed{\rightarrow}$ or $\boxed{\texttt{Ourl}} + \boxed{\Downarrow}$ Input lines up to coil in batch with $\boxed{\texttt{Ourl}} + \boxed{\texttt{frsuit}} + \boxed{\rightarrow}$ (Batch input lines in a vertical direction with $\boxed{\texttt{Ourl}} + \boxed{\texttt{frsuit}} + \boxed{\clubsuit}$	)	
 /	(110	, ,

■ How to input a line Press [Ctrl] + [ → ] or [Ctrl] + [ ↓ ] at an empty spot. Press [Ctrl] + [ → ] or [Ctrl] + [ ↓ ] on top of a line to delete it.

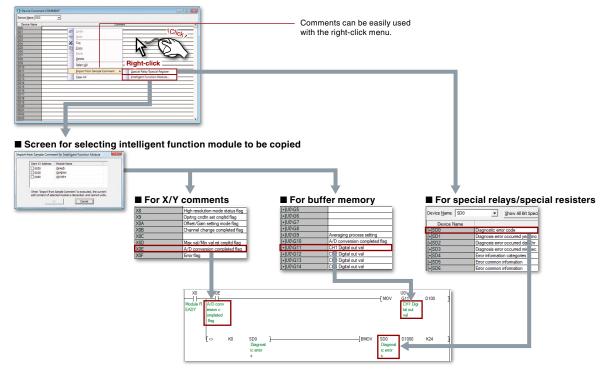
#### • Use function blocks for common operations

Function blocks allow selections of commonly used code to be easily reused and shared among projects. Shared or created function blocks can be added to a program using simple drag and drop operation. Using function blocks effectively results in faster development times with fewer programming mistakes.



#### • Use sample comments to eliminate the need to input comments

Sample comments are provided for the CPU's special relays/registers and the intelligent function module's buffer memory/XY signals. These can be copied into the project's comments thus greatly reducing the time required for entering device comments.



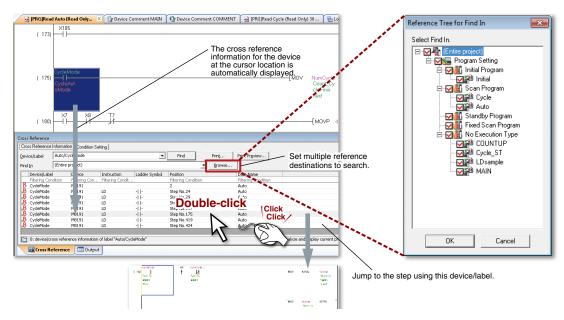
#### • Quickly identify similar devices

Word device comments can be registered per bit with the contents displayed directly on the ladder rung.



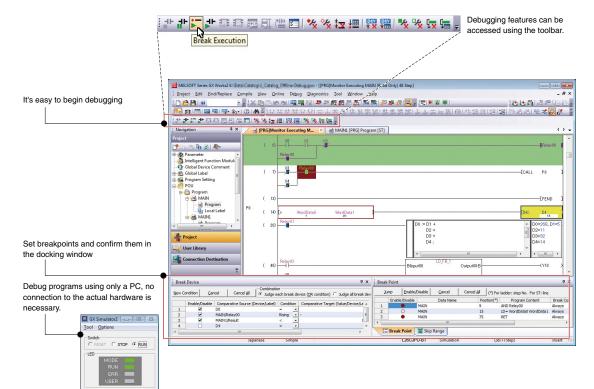
#### • Cross referencing interlinked with circuit displays

Relevant devices and labels can be searched within the contents of the program by using the cross reference tool. The results are immediately displayed in the cross reference dialog box conveniently besides the actual program view screen. It is then very easy to check where the relevant device is actually used within the program, just by double clicking on the target device.



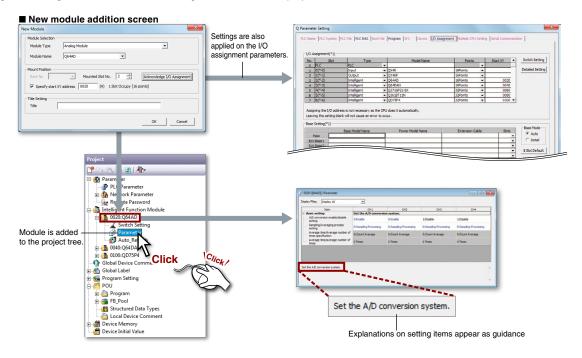
#### • Offline debug without physical hardware

The simulation function is now integrated. The program can be executed in a step-by-step method, finding program errors more easily.



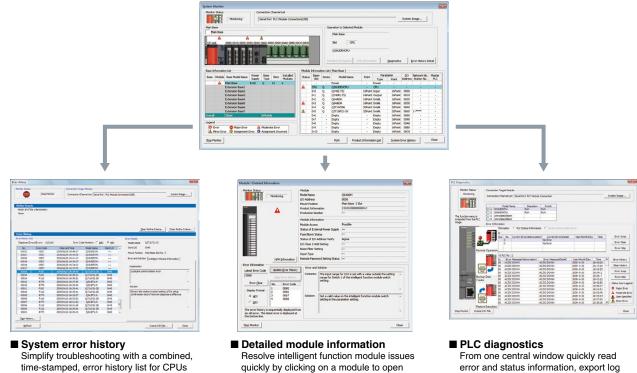
#### Intelligent function module setting

Manage the intelligent function module's setting with a GX Works2 project.



#### Visible System monitor function and PLC diagnostics

Operation status of the entire programmable controller system is clearly displayed. Each module's diagnosis and detailed information is displayed on the monitor for the entire system allowing the problem point to be confirmed quickly.



Resolve intelligent function module issues quickly by clicking on a module to open this function. All of the information relevant to the module is displayed here including error codes, their description, and possible solutions. From one central window quickly read error and status information, export log files to CSV, perform remote CPU operations like reset, stop, CPU memory format. and more.

and intelligent function modules.

The details section provides explanations

of error codes and suggested solutions.



#### Time-stamped error history list

Simplify troubleshooting with a combined, time-stamped, error history list for the CPU and all expansion modules. The details section provides explanations of error codes and suggested solutions.

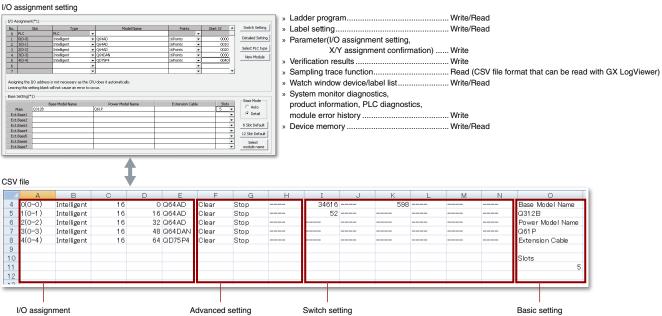
STEP	Stop Monito	Serial Port P	LC Module Connectio	n(U58)	System Image	Displayed Lin	ors/Errors: 123/12		ode Notation: C DE	
Search						No. 🗸	Error Code	Date and Time	Model Name	Start I/C
all of the cr	teria below					00060		2009/10/08 18:14:17		
						00059	7D13	2009/10/08 17:53:06	QJ71C24N-R2	00F0
						00058	7D16	2009/10/08 17:52:32	QJ71C24N-R2	00F0
					Gear Refine Criteria Enter Refine Criteria	00057	05DC	2009/10/08 16:14:09	Q26UDEHCPU	
listory						00056	7D12	2009/10/08 16:00:53	QJ71C24N-R2	00F0
tory List	irrore: 123/123	Error Cr	de Notation: (* DB	GUEV	Error Details Model Name L3610711					
	Error Code	Date and Time	Model Name	Start L/D	Start I/O 0110	00055	7D16	2009/10/08 15:56:40	QJ71C24N-R2	00F0
60	0782	2009/10/08 18:14:17	QJE18T11N	0110	Nount Position Main block 1th slot	00054	7D16	2009/10/08 15:50:24	QJ71C24N-R2	00F0
59 58	7D13 7D15	2009/30/08 17:53:06 2009/30/08 17:52:32	QJ71C24N-R2 QJ71C24N-R2	00F0 00F0	Error and Solution Intelligent Module Information	00053	7D16	2009/10/08 14:59:03	QJ71C24N-R2	00F0
\$7	OSDC	2009/30/08 36:14:09	O26UDEHCPU		and a statem [ sneegen woode promation ]	00052	7D12	2009/10/08 14:43:27	QJ71C24N-R2	00F0
156	7012 7015	2009/10/08 16:00:53 2009/10/08 15:56:40	QJ71C24N-R2 QJ71C24N-R2	0070	Explanation	00051	7D12	2009/10/08 14:35:53	QJ71C24N-R2	00F0
154 153	7D 16	2009/30/08 15:50:24	OJ71C24N-R2	0050	Station number specification error. The transmission destination and source stations were the same when	00050	7EF2			00F0
52	7016 7012	2009/10/08 14:59:03 2009/10/08 14:43:27	QJ71C24N-R2 QJ71C24N-R2	00F0	other station connection was specified.			2009/10/08 14:35:02	QJ71C24N-R2	UUFU
151	7012 7FF2	2009/20/08 14:35:53	GJ71C24N-R2	00F0		00049	1005	2009/10/08 14:03:44	Q26UDEHCPU	
190	1005	2009/10/08 14:35:02 2009/10/08 14:03:44	QJ71C24N-R2 Q26UDEHOPU	00F0	Solution	00048	7F42	2009/10/08 13:37:00	QJ71C24N-R2	00F0
48	77-42	2009/20/08 13:37:00	QJ71C24N-R2	00F0	Check the transmission destination station number, or change to host connection.	00047	0C21	2009/10/08 13:13:56	Q26UDEHCPU	
147 146	0021	2009/10/08 13:13:56 2009/10/08 13:12:40	Q26UDEHCPU Q26UDEHCPU	-	Change to host connections.	00046	0834			
145	OSDC	2009/10/08 13:11:51	Q26UDEHOPU					2009/10/08 13:12:40	Q26UDEHCPU	
44	7542	2009/20/08 12:04:52 2009/20/08 11:43:17	QJ71C24N-R2 Q24UDEHOPU	00F0	*	00045	05DC	2009/10/08 13:11:51	Q26UDEHCPU	
42	0840	2009/10/08 11:41:01	Q26UDEHCPU	-	•	00044	7F42	2009/10/08 12:04:52	QJ71C24N-R2	00F0
r History						00043	0840	2000/10/08 11-43-17	OPELIDENCEL	
Jefresh	1				Create CSV Ele Cines	00042	0840	Explanation		
						····· /		Station number specifica destination and source other station connection	stations were the sar	
								Solution		
								Check the transmission of change to host connection		umber, or
					Quickly identify	the error, its cause,	and colution			

#### • Save, edit labels and parameters with Microsoft® Excel®

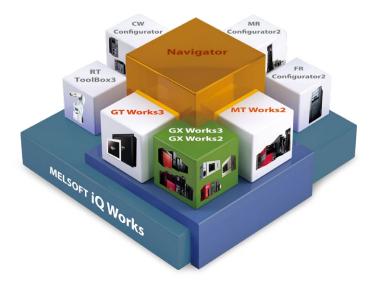
Various program data can be exported in CSV file format.

- Exporting to CSV format has various advantages, as shown below:
  - Data can be utilized on a personal computer even if GX Works2 is not installed
  - Data can be saved directly on the personal computer
  - Data can be sent and utilized off-site
  - Utilization of data for creating documents and graphs are possible using Excel®
  - Can use in other software that support CSV format

#### ■ Example of I/O assignment setting CSV file



#### iQ Works



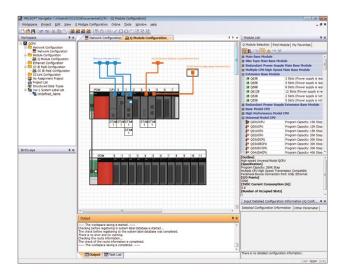
# MELSOFT iQ Works

#### Next Generation Integrated Engineering Environment

MELSOFT iQ Works is an integrated software suite consisting of GX Works3, GX Works2, MT Works2, GT Works3, RT ToolBox3, FR Configurator2, CW Configurator and MR Configurator2. The advantages of this powerful integrated software suite are that system design is made much easier with a substantial reduction in repetitious tasks, cutting down on errors while helping to reduce the overall TCO.

#### Graphical project management

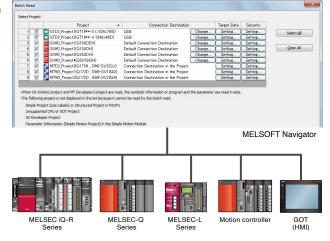
The entire control system is represented using the "Network Configuration," "Module Configuration" and field network configuration windows. System components are easily added using a drag & drop interface, and the validity of the system can be confirmed using the check function to ensure parameters are configured correctly, the power supply is sufficient, etc. Different programmable controller and GOT (HMI) projects can be grouped together (for example by factory, line, and cell) for central management.



#### • Read project data for multiple devices in a batch

Multiple projects can be read as a block just by having one connection to the programmable controller. If there are multiple devices such as other CPU or GOT (HMI) on the same network as the target master programmable controller, it is possible to upload all projects to each target device without having to individually connect to each device.

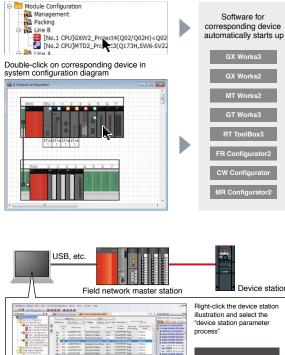




#### • Automatically start up the relevant maintenance software with a single click

Just double-click on the corresponding project in the system configuration diagram or workspace tree to automatically startup the software relevant for that device. Maintenance can be efficiently performed without having to know and startup each relevant software manually.

#### Double-click on corresponding project in workspace tree



#### Set up field network device stations

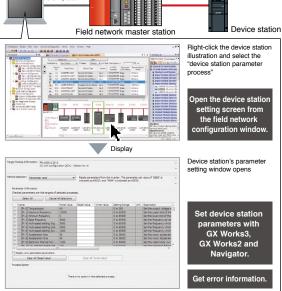
There's no need to prepare a dedicated tool to check or change the parameter settings of a device station on-site. The latest version of iQ Works includes device station setting utility. Inverter parameters, for example, can be confirmed or changed for speed adjustment directly from the field network configuration window. In addition, error information can be read easily.

#### CC-Línk

CC-Link

Ethernet

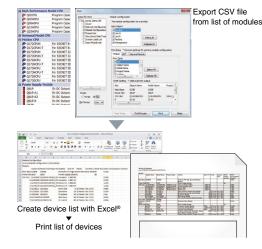
**AnyWireASLINK** 



#### • Prepare a device from the system configuration diagram with no manual inputs

A list of modules used can be exported as a CSV file from the system configuration diagram.

This is particularly useful when utilizing data for creating a bill of materials (BOM) in Excel<sup>®</sup>, etc.



#### **GX LogViewer**



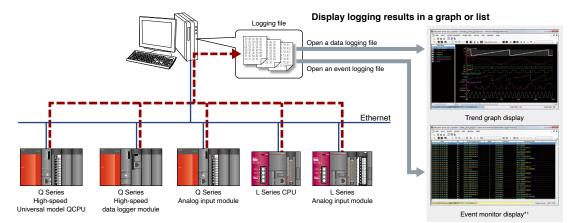
## **GX LogViewer**

#### Visualizing the production process

Within modern manufacturing needs, data collection has become more important for fully optimizing the production process. GX LogViewer is a software tool that realizes visualization of large amounts of production data in a simple to use format. Utilizing this functionality to identify root error causes and improving the production rate.

#### Easily display and analyze large amounts of collected logging data

This tool is used when large amounts of data need to be visualized and collected from the MELSEC-Q Series or MELSEC-L Series. The connection settings and checking of log files are the same as GX Works2 enabling individual connections to each module.

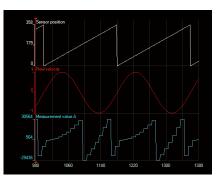


\*1. The event monitor display is supported only with the Q Series high-speed logger module.

#### • Easily adjust graphs without referring to the setup manual

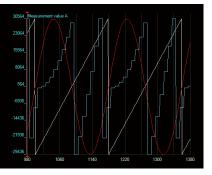
#### Arranging graphs

Able to arrange each graph so as not to overlap each other. It is easier to display the graphs as each graph is evenly spaced out.

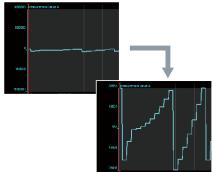


#### Overlapping graphs

With this it is possible to overlap each graph over one another. Multiple graphs can be compared enabling easier data analysis and comparison.



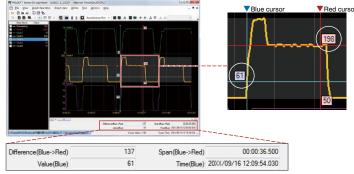
Automatically adjusting graphs Various attributes of the graph are automatically adjusted (max/min values) as to display the upper and lower limit values better.





#### • Easily confirm changes in data with dual cursors

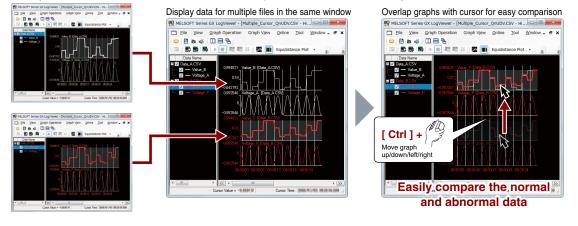
Data changes within a designated time frame can be quickly checked with user-friendly dual cursors (multi-cursors). When the cursors are moved to the point at which changes are to be confirmed, the difference in time and value between those points will appear.



The difference in time and value between the cursors is automatically calculated and displayed.

#### • Display data for multiple files within one graph area for easy comparison

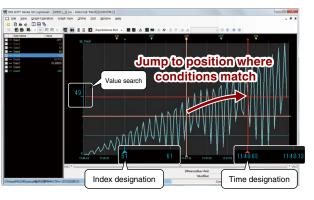
Data for multiple files are displayed with the same time units in the same graph area. The display position within a file can be moved easily. This allows the differences of data within multiple files to be confirmed easily.



#### Quickly jump cursor to designated position

Cursor jump

Confirm data values by quickly moving the cursor to a designated value, time or index position in the trend graph.



alue Time	s for jump cursor.
File Name	HSDL1_Q.cev
Data Name	Data5
Dassfication	Conditional -
	< - Data5 < -
Value Range	

Jump Cursor
Select conditions for jump cursor.
Value inte index
File Name HSDL1_Q.csv
Time Range
2011/03/31 11:46:43 to 2011/03/31 11:48:22
Date and time to which the cursor jumps V Date
2011/03/31
Hour     Minute     Second
11 • 47 • 33 •
Select a cursor that jumps
Red Cursor     O Blue Cursor
Carcasa O Brecasa
Jump Previous Jump Next Close

Select continues for yange curror.

 Value
 Time
 Index

 File Name
 HSDL1\_Q corv

 File Name
 HSDL1\_Q corv

 Index Range
 110 100

 Index to which the curror jumps
 51

 Select a curror that jumps
 61 Bet Curror

 Bet Curror
 Bare Devices

 Jump Envices
 Jump Elect

ump Cursor

Time designation

The cursor jumps to the designated time.

Index designation The cursor jumps to the designated index.

Values are searched, and the cursor jumps to the position where the conditions match.

Value search





**MELSEC** Safety

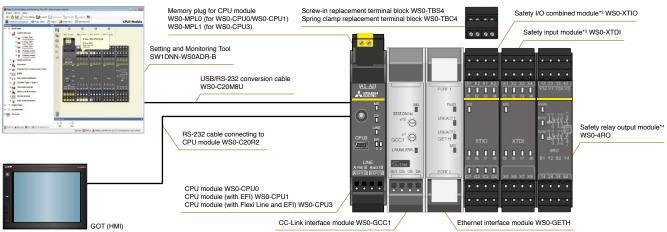
# Ensuring safety between the operator and machine

Based on a principle of separating machines from operators, safety protection measures were implemented on the basis of risk assessment and safety control such as implementation of an emergency stop. The advancement of technology realizes operations such as slowing down the operation speed when an operator approaches a machine and continuous operation without stopping when an operator is away from a machine. The concept of safety has shifted to a level where operators and machines can work in collaboration ensuring increased safety. Mitsubishi Electric offers a total safety solution which realizes "collaboration" of operators and machines with a large variety of products.

#### **MELSEC-WS Series Safety Controller**

#### • Safety controller CPU\*1 ...... WS0-CPU0, WS0-CPU1, WS0-CPU3

The safety controller is a controller dedicated to safety control, conforming to international standards such as ISO 13849-1 Category 4 PL e and IEC 61508 SIL 3. The MELSEC-WS is ideal for small to medium-size safety machines and systems. I/O points of up to 144 (no redundancy) and up to 2 network interfaces and the dedicated Setting and Monitoring Tool, which contains safety sensor/switch connections and function blocks, all support the configuration of a safety system. The CPU cannot be installed on the Q Series base unit.



\*2. No. of input points: 8 points (single wiring), No. of output points: 4 points (single wiring)

No. of input points: 8 points (single wiring)

\*4. Safety relay output: 4 points

SICK

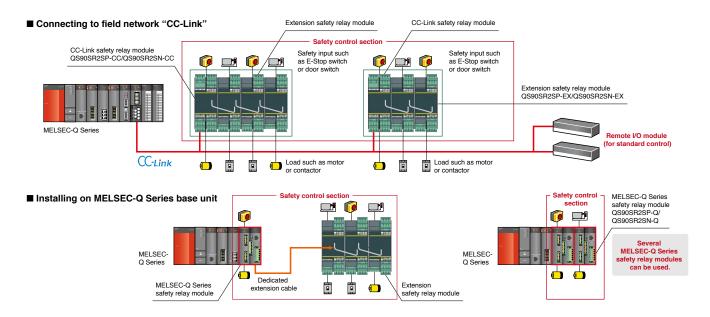
The MELSEC-WS Series was developed and manufactured by SICK AG. SICK is a German supplier of safety solutions. SICK designs and manufactures a broad range of safety products including industrial-use sensors and automatic identification systems. General specifications and product guarantee conditions for co-branded products may vary from those of general MELSEC products For more information, please refer to the relevant product manuals or contact your local Mitsubishi Electric sales office/representative

#### SICK AG http://www.sick.com/

#### **MELSEC-QS Series Safety Relay Modules**

● Q Series safety relay module	QS90SR2SP-Q, QS90SR2SN-Q
CC-Link safety relay module	QS90SR2SP-CC, QS90SR2SN-CC
Extension safety relay module	QS90SR2SP-EX, QS90SR2SN-EX

The safety relay module integrates the emergency stop circuit and the restart circuit with a double safety relay. A basic safety function can be realized with just wiring, eliminating the need for programming and parameter settings. Furthermore, the number of I/O points can be increased by adding extension modules.





iQ Sensor Solution

# A tool for connecting! Visualizing! For a more seamless sensor control

Sensors used on the manufacturing floor are becoming more intelligent and complex, requiring even more maintenance of equipment and the overall management of various configuration setup software. With iQSS, the intelligent sensor solution provided by Mitsubishi Electric, configuration and maintenance of sensors are further simplified with the enhanced connectivity to other components such as industrial computers, automation controllers, HMIs, and engineering software even further reducing the overall TCO\*.

time taken to adjust sections involving

multiple devices.

\* Total Cost of Ownership

# iQSS covers all the sensors from general sensors to advanced sensors





General specifications indicate the environmental specifications in which this product can be installed and operated. Unless otherwise specified, the general specifications apply to all products of the Q Series.

Install and operate the Q Series products in the environment indicated in the general specifications.

Item	Specification								
Operating ambient temperature		055°C							
Storage ambient temperature		−2575°C*1							
Operating ambient humidity			5…95% RH*², ı	non-condensing					
Storage ambient humidity			5…95% RH*², ı	non-condensing					
			Frequency	Constant acceleration	Half amplitude	Sweep count			
	on resistance JIS B 3502 and IEC 61131-2	Under	58.4 Hz	-	3.5 mm (0.14 inches)	10 times each in			
Vibration resistance		vibration	8.4150 Hz	9.8 m/s²	-	X, Y, Z directions			
		Under continuous	58.4 Hz	-	1.75 mm (0.069 inches)				
		vibration	8.4150 Hz	4.9 m/s²	-	-			
Shock resistance	Co	mpliant with JIS B 35	02 and IEC 61131-2	(147 m/s², 3 times e	ach in directions X, Y	(, Z)			
Operating atmosphere			No corros	sive gases					
Operating altitude*3			≤ 2000 m	(6562 feet)					
Installation location			Inside a co	ontrol panel					
Overvoltage category*4			5	Π					
Pollution level*5			5	2					

\*1. The storage ambient temperature is -20 to 75°C if the system includes the AnS/A Series modules.

\*2. The operating ambient humidity and storage ambient humidity are 10 to 90% RH if the system includes the AnS/A Series modules

\*3. Do not use or store the programmable controller under pressure higher than the atmospheric pressure of altitude 0 m. Doing so can cause a malfunction.

When using the programmable controller under pressure, please contact your sales representative.

\*4. This indicates the section of the power supply to which the equipment is assumed to be connected between the public electrical power distribution network and the machinery within premises. Category II applies to equipment for which electrical power is supplied from fixed facilities. The surge voltage withstand level for up to the rated voltage of 300 V is 2500 V.

\*5. This index indicates the degree to which conductive material is generated in terms of the environment in which the equipment is used. Pollution level 2 is when only non-conductive pollution occurs. A temporary conductivity caused by condensing must be expected occasionally.

# **CPU Module Performance Specifications**

#### **Universal model QCPU**

	Item	Q03UDVCPU	Q04UDVCPU	Q06UDVCPU	Q13UDVCPU	Q26UDVCPU	Q00UJCPU	Q00UCPU	Q01UCPU
Control method					Stored program	cyclic operation			
I/O control mo	de				Refr				
Program language (sequence control language)					<ul> <li>Logic symboli</li> </ul>				
	USB*1								
Peripheral connection port	Ethernet (100BASE-TX/10BASE-T)			•				-	
5011	RS-232			-				•	
Memory card	interface		(SD Memory	• / Card, SDHC Me	mory Card)*2			-	
Extended SRA	AM cassette port			•				-	
	LD instruction			1.9 ns			120 ns	80 ns	60 ns
Dessertion	MOV instruction			3.9 ns		240 ns	160 ns	120 ns	
Processing speed*3	PC MIX value*4	007					4.00	700	0.70
speeu .	(instruction/µs)			227	4.92	7.36	9.79		
	Floating point addition			0.014 µs			0.42 µs	0.30 µs	0.24 µs
Fotal number of	of instructions*5			859			821	8	55
Floating point									
01									
	ng processing instruction								
PID instruction									
Special function (Trigonometrico exponential op	function, square root,					•			
Constant scan Function for ke	n eeping regular scan time)	0.5…2000 ms (setting available in units of 0.1 ms)				0.5…2000 ms (setting available in units of 0.5 ms)			
Program capa	city*6	30K steps	40K steps	60K steps	130K steps	260K steps	10K :	steps	15K steps
	device points [X/Y]		8192 points			points			
Number of I/O	points [X/Y]	4096 points				256 points	1024	points	
nternal relay [	[M]*7	9216 points	15360	points		8192 points			
atch relay [L]	*7								
_ink relay [B]*	7				8192	points			
Timer [T]*7		2048 points							
Retentive time	er [ST]*7	0 point							
Counter [C]*7									
Data register [	<sup>7</sup> دוח	1024 points           13312 points         22528 points           41984 points					12288 points		
Data register [D]*7		13312 points	22528	points				12288 points	
• •	a register [D]*7	13312 points	22528	points 0 point			-		oint
Extended data	a register [D]*7	13312 points	22528		41984		-		oint
Extended data	a register [D]* <sup>7</sup> W]	13312 points	22528		41984	points	- -	0 p	voint
Extended data Link register [\ Extended link	a register [D]* <sup>7</sup> M] register [W]* <sup>7</sup>	13312 points	22528	0 point	41984	points	-	0 p	
Extended data Link register [\ Extended link Annunciator [F	a register [D]*7 <i>N</i> ] register [W]*7 _]*7	13312 points	22528	0 point	8192 2048	points	-	0 p	
Extended data Link register [\ Extended link Annunciator [F Edge relay [V]	register [D]* <sup>7</sup> <i>N</i> ] register [W]* <sup>7</sup> =]* <sup>7</sup> * <sup>7</sup>	13312 points	22528	0 point	41984 8192 2048 2048	points points points points points	-	0 p	
Extended data Link register [\ Extended link Annunciator [F Edge relay [V] Link special re	register [D]* <sup>7</sup> N] register [W]* <sup>7</sup> -] <sup>+7</sup> * <sup>7</sup> elay [SB]* <sup>7</sup>	13312 points	22528	0 point	41984 8192 2048 2048	points points points points points points	•	0 p	
Extended data Link register [\ Extended link Annunciator [F Edge relay [V] Link special re Link special re	register [D]*7 N] register [W]*7 -]*7 *7 elay [SB]*7 egister [SW]*7			0 point 0 point	41984 8192 2048 2048 2048 2048 2048	points points points points points points points	•	q 0 q 0	point
Extended data Link register [\ Extended link Annunciator [F Edge relay [V] Link special re Link special re File register [F	register [D]*7 N] register [W]*7 -]*7 *7 elay [SB]*7 egister [SW]*7 R, ZR]	13312 points 98304 points*8		0 point 0 point	41984 8192 2048 2048 2048 2048 2048 524288 points* <sup>8</sup>	points points points points points points points 655360 points* <sup>8</sup>	•	q 0 q 0	
Extended data Link register [\ Extended link Annunciator [F Edge relay [V] Link special re Link special re File register [F Step relay [S]*	a register [D]*7 M] register [W]*7 -]*7 *7 elay [SB]*7 egister [SW]*7 R, ZR] 7	98304 points*8		0 point 0 point	41984 8192 2048 2048 2048 2048 2048 524288 points* <sup>8</sup> 8192	points points points points points points 655360 points* <sup>®</sup> points	· · · · · · · · · · · · · · · · · · ·	q 0 q 0	point
Extended data Link register [\ Extended link Annunciator [F Edge relay [V] Link special re Link special re File register [F Step relay [S] <sup>*</sup> ndex register/s	register [D]*7 <i>N</i> ] register [W]*7 -]*7 *7 elay [SB]*7 egister [SW]*7 R, ZR] -7 tandard device register [Z]	98304 points*8		0 point 0 point	41984 8192 2048 2048 2048 2048 2048 524288 points* <sup>8</sup> 8192	points points points points points points points 655360 points* <sup>8</sup>	- - -	0 p	point
Extended data Link register [\ Extended link Annunciator [F Edge relay [V] Link special re Link special re File register [F Step relay [S] <sup>*</sup> ndex register/s	register [D]*7 M] register [W]*7 []*7 *7 egister [SW]*7 egister [SW]*7 R, ZR] 7 tandard device register [Z] [Z]	98304 points*8	131072 points*8	0 point 0 point 393216 points*8	41984 8192 2048 2048 2048 2048 524288 points*6 8192 Max. 20	points points points points points points 655360 points* <sup>®</sup> points		0 p 0 p 65536 Max. 1	point
Extended data Link register [\ Extended link Annunciator [F Edge relay [V] Link special re File register [F Step relay [S]* Index register/s Index register/s 2-bit ZR inde	register [D]*7 M] register [W]*7 []*7 *7 egister [SW]*7 egister [SW]*7 R, ZR] 7 tandard device register [Z] [Z]	98304 points*8	131072 points*8	0 point 0 point 393216 points*8 Max. 10 points	41984 8192 2048 2048 2048 2048 524288 points*6 8192 Max. 20	points points points points points points 655360 points* <sup>®</sup> points	- - - -	0 p 0 p 65536 Max. 1	o points
Extended data Link register [\ Extended link Annunciator [F Edge relay [V] Link special re Link special re File register [F Step relay [S] ndex register/s ndex register/s ndex register/s 22-bit ZR inde Pointer [P]	register [D]*7 N] register [W]*7 -]*7 *7 egister [SW]*7 egister [SW]*7 R, ZR] -7 tandard device register [Z] [Z] exing)	98304 points*8	131072 points*8	0 point 0 point 393216 points** Max. 10 points er [Z] is used in do	41984 8192 2048 2048 2048 2048 524288 points*6 8192 Max. 20	points points points points points points 655360 points* <sup>®</sup> points	- - - -	0 p 0 p 65536 Max. 1 (Index register [Z] is i	o points
Extended data Link register [\ Extended link Annunciator [F Edge relay [V] Link special re Link special re File register [F Step relay [S] ndex register/s ndex register/s ndex register/s 22-bit ZR inde Pointer [P] nterrupt point	register [D]*7 N] register [W]*7 -]*7 *7 elay [SB]*7 egister [SW]*7 R, ZR] -7 tandard device register [Z] [Z] exing) er [I]	98304 points*8	131072 points*8	0 point 0 point 393216 points** Max. 10 points er [Z] is used in du 4096 points	41984 8192 2048 2048 2048 2048 524288 points*6 8192 Max. 20 0uble words.)	points points points points points points 655360 points* <sup>®</sup> points	- - -	0 p 0 p 65536 Max. 1 (Index register [Z] is I 512 points	o points
Extended data Link register [\ Extended link Annunciator [F Edge relay [V] Link special re Link special re File register [F Step relay [S]* ndex register [32-bit ZR ind Pointer [P] Interrupt point Special relay [	register [D]*7 N] register [W]*7 =]*7 *7 syster [SW]*7 syster [SW]*7 syster [SW]*7 tandard device register [Z] [Z] exing) er [I] SM]	98304 points*8	131072 points*8	0 point 0 point 393216 points** Max. 10 points er [Z] is used in du 4096 points	41984 8192 2048 2048 2048 2048 2048 524288 points*6 8192 Max. 20 0uble words.)	points points points points points points 655360 points* <sup>®</sup> points 0 points	- - -	0 p 0 p 65536 Max. 1 (Index register [Z] is I 512 points	o points
Extended data ink register [\ Extended link Annunciator [F Edge relay [V] ink special re ink special re File register [F Step relay [S] <sup>*</sup> ndex registers 32-bit ZR indc Pointer [P] nterrupt point Special relay [ Special register	register [D]*7 N] register [W]*7 =]*7 *7 syster [SW]*7 syster [SW]*7 syster [SW]*7 tandard device register [Z] [Z] exing) er [I] SM] er [SD]	98304 points*8	131072 points*8	0 point 0 point 393216 points** Max. 10 points er [Z] is used in du 4096 points	41984 8192 2048 2048 2048 2048 524288 points*8 8192 Max. 20 0uble words.)	points points points points points points 655360 points*8 points 0 points	-	0 p 0 p 65536 Max. 1 (Index register [Z] is I 512 points	o points
Extended data Link register [\ Extended link Annunciator [F Edge relay [V] Link special re Link special re File register [F Step relay [S]*	register [D]*7 N] register [W]*7 =]*7 *7 egister [SW]*7 a, ZR] 7 tandard device register [Z] [Z] exing) er [I] SM] er [SD] [FX]	98304 points*8	131072 points*8	0 point 0 point 393216 points** Max. 10 points er [Z] is used in du 4096 points	41984 8192 2048 2048 2048 2048 524288 points*® 8192 Max. 20 0uble words.) 2048 2048 2048 2048	points points points points points points 655360 points*8 points 0 points	-	0 p 0 p 65536 Max. 1 (Index register [Z] is I 512 points	o points
Extended data Link register [\ Extended link Annunciator [F Edge relay [V] Link special re Link special re File register [F Step relay [S]" Index register/s Index register/s Index register Saber [P] Interrupt point Special relay [ Special relay [ Special register Function input Function output	register [D]*7 N] register [W]*7 =]*7 *7 sigister [SW]*7 sigister [SW]*7 s, ZR] 7 tandard device register [Z] [Z] exing) er [I] SM] er [SD]  [FX] ut [FY]	98304 points*8	131072 points*8	0 point 0 point 393216 points** Max. 10 points er [Z] is used in du 4096 points	41984 8192 2048 2048 2048 2048 2048 524288 points*® 8192 Max. 20 0uble words.) 2048 2048 2048 2048 16 p 16 p	points po	- - - -	0 p 0 p 65536 Max. 1 (Index register [Z] is I 512 points	o points
Extended data Link register [\ Extended link Annunciator [F Edge relay [V] Link special re Link special re File register [F Step relay [S]" Index register/s Index register (32-bit ZR indu Pointer [P] Interrupt point Special relay [ Special registe Function input	register [D]*7 N] register [W]*7 =]*7 *7 sigister [SW]*7 sigister [SW]*7 s, ZR] 7 tandard device register [Z] [Z] exing) er [I] SM] er [SD]  [FX] ut [FY]	98304 points*8	131072 points*8	0 point 0 point 393216 points** Max. 10 points er [Z] is used in du 4096 points	41984 8192 2048 2048 2048 2048 524288 points*® 8192 Max. 20 0uble words.) 2048 2048 2048 2048	points po	- - - - - - - -	0 p 0 p 65536 Max. 1 (Index register [Z] is t 512 points 128 points	o points

\*2. The operation of devices that are not manufactured or recommended as compatible products by Mitsubishi Electric cannot be guaranteed.

3. The processing speed is the same even when the device is indexed.
4. The PC MIX value is the average number of instructions such as the basic and data processing instructions executed in 1µs. A larger value indicates a higher processing speed.

\*5. Intelligent function module dedicated instructions are not included.

When the QnUD(H)CPU or QnUDE(H)CPU is replaced with the QnUDVCPU, the number of steps in the program may change (increase or decrease). For more information, refer to the relevant manual.
 Indicates the number of points in the default state. This can be changed with the parameter.

\*8. Indicates the number of points when using the built-in memory (standard RAM). This can be increased with the extended SRAM cassette. When using together with the extended SRAM cassette, the value obtained by totaling the number of points in the following table is the nu er of points in the following table is the number of file registers that can be used.

when using together with the extended SHAW casselite, the value obtained by totaling the number of points in the following table is								
With Q4MCA-1MBS (1 MB)	With Q4MCA-2MBS (2 MB)	With Q4MCA-4MBS (4 MB)	With Q4MCA-8MBS (8 MB)					
524288 points	1048576 points	2097152 points	4194304 points					



Specifications

	Q03UDECPU	Q04UDEHCPU	Q06UDEHCPU	Q10UDEHCPU	Q13UDEHCPU	Q20UDEHCPU	Q26UDEHCPU						
Q02UCPU	Q03UDCPU	Q040DEHCP0	Q06UDHCPU	Q10UDHCPU	Q13UDHCPU	Q200DEHCP0	Q260DEHCP0	Q50UDEHCPU	Q100UDEHCPU				
	4				cyclic operation								
					resh								
	Relay symbol language (ladder)												
	<ul> <li>Logic symbolic language (list)</li> <li>MELSAP3 (SFC), MELSAP-L</li> </ul>												
	• Function block												
	Structured text (ST)												
_	Q03UDECPU	Q04UDEHCPU	Q06UDEHCPU	Q10UDEHCPU	Q13UDEHCPU	Q20UDEHCPU	Q26UDEHCPU						
•	Q03UDCPU	Q04UDHCPU	Q06UDHCPU	Q10UDHCPU	Q13UDHCPU	Q20UDHCPU	Q26UDHCPU		-				
	(SRAM card, Flash card, ATA card)												
40 ns	20 ns												
80 ns	40 ns			19	ns								
14	28			6	0								
0.18 µs	0.12 µs			0.05	57 μs								
857				Q03Q26UD				8	65				
					(H)CPU: 855								
				-									
					000 ms								
001/ ataza	00K stars	1016 atoms		(setting available					10001/				
20K steps	30K steps	40K steps	60K steps	100K steps	130K steps points	200K steps	260K steps	500K steps	1000K steps				
2048 points					points								
Lotopolito	1				points	-			-				
					points								
				8192	points								
					points								
					oint								
					points								
					points			10107	) mainta				
					oint points			131072	2 points				
					oint								
					points				·				
					points								
				2048	points								
				1	points								
65536 points*9	98304 points*9	131072 points*9	393216 points*9		points*9	655360	points*9	786432 points*9	917504 points*9				
					points								
					0 points 0 points								
			(Ind	ex register [Z] is u		rds.)							
					points			8192	points				
					ooints								
					points								
					points								
					oints								
					oints								
					pints								
*0 Indicator the pur	mbor of points when u	ing the built in memory	(standard RAM) This	can be expanded with		b cord (Mriting from t		ible with the Flech com					

\*9. Indicates the number of points when using the built-in memory (standard RAM). This can be expanded with the SRAM card or Flash card. (Writing from the program is not possible with the Flash card.) Up to 4184064 points can be used with the SRAM card.

# **CPU Module Performance Specifications**

#### Universal model process CPU

Control method	ltem d	Q04UDPVCPU	Q06UDPVCPU Stored program	Q13UDPVCPU	Q26UDPVCPU				
/O control mod				fresh					
Sequence control Program language		Relay symbol language (ladder)     Logic symbolic language (list)     MELSAP3 (SFC), MELSAP-L     Function block     Structured text (ST)							
	Process control language	Process control FBD*1							
Peripheral connection port	USB* <sup>2</sup> Ethernet (100BASE-TX/10BASE-T) RS-232	•							
Memory card i	nterface		(SD memory card, §	● SDHC memory card)* <sup>3</sup>					
Connector for e	extended SRAM		(00	•					
	LD instruction		1!	9 ns					
	MOV instruction								
Processing speed*4	PC MIX value (instruction/µs)*5		3.9 ns 227						
	Floating point addition		0.0	14 µs					
Fotal number o	of instructions*6			59					
Floating point i				•					
• •	ng processing instruction			•					
PID instruction				•					
Special functio	on instruction function, square root,	•							
Constant scan Function for ke	eeping regular scan time)	0.52000 ms (setting available in units of 0.1 ms)							
Program capad		40K steps	60K steps	130K steps	260K steps				
	device points [X/Y]			points					
Number of I/O		4096 points							
nternal relay [l	M]*8	15360 points 28672 points							
atch relay [L]	*8	8192 points							
ink relay [B]*8	3		8192	points					
Fimer [T]*8			2048	points					
Retentive time	r [ST]*8		0 1	point					
Counter [C]*8			1024	points					
Data register [[	D]*8	22528	8 points	4198	34 points				
Extended data				point					
ink register [V	V]*8			points					
Extended link I			0 1	point					
Annunciator [F	•			points					
Edge relay [V]'				points					
ink special re				points					
ink special re	• • •			points					
File register [R		131072 points*9	393216 points*9	524288 points*9	655360 points*9				
Step relay [S]*				points					
•	tandard device register [Z]			0 points					
ndex register [				0 points					
	on specification of ZR device)			used in double words.)					
Pointer [P]				points					
nterrupt pointe				points					
				points					
Special registe		2048 points 16 points							
Special registe	[FX]		16 points						
Special registe Function input	[FX]			points					
Special registe Function input Function outpu Function regist	[FX] ut [FY]		16 r						
Special relay [ Special registe Function input Function outpu Function regist Local device	[FX] ut [FY]		16 r	points					

\*2. USB port terminal is mini B.

\*3. Mitsubishi Electric shall not guarantee the operation of any third-party products.

\*4. The processing speed is the same even when the device is indexed.

\*5. The PC MIX value is the average number of instructions such as the basic and data processing instructions executed in 1 µs. A larger value indicates a higher processing speed.

\*6. Intelligent function module dedicated instructions are not included.
 \*7. When the QnUD(H)CPU or QnUDE(H)CPU is replaced with the QnUDVCPU, the number of steps in the program may change (increase or decrease). For details, please refer to the relevant manual.

\*8. Indicates the number of points in the default state. This can be changed with the parameter

'9. Points when using an internal memory (standard RAM). File register area can be extended with an extended SRAM cassette. When used with an extended SRAM cassette, the total points in the table below can be used as file register.

Q4MCA-1MBS (1M bytes)	Q4MCA-2MBS (2M bytes)	Q4MCA-4MBS (4M bytes)	Q4MCA-8MBS (8M bytes)	
524288 points	1048576 points	2097152 points	4194304 points	



Module Combinations for Multiple CPU System

Restrictions apply depending on CPU type, the number that can be installed, and supported serial No. For more information, please refer to the relevant users manual for each CPU.

Possible

Multiple CPU	high spee	d main base u	<ul> <li>Possible (multiple CPU high-speed communication not available)</li> <li>Impossible</li> </ul>				
$\searrow$		High-speed Universal model QCPU	Universal n	nodel QCPU	Universal model process CPU	Motion CPU/ Robot CPU*1/CNC CPU	C Controller CPU
CPU 1	CPU 2 to 4	Q03UDV Q04UDV Q06UDV Q13UDV Q26UDV	Q00U Q01U Q02U	Q03UD(E) Q04UD(E)H Q06UD(E)H Q10UD(E)H Q13UD(E)H Q20UD(E)H Q26UD(E)H Q50UDEH Q100UDEH	Q04UDPV Q06UDPV Q13UDPV Q26UDPV Q26UDPV	Q172D Q173D Q172DS Q172DS CR800-Q Q173NC	Q24DHCCPU-V Q24DHCCPU-VG Q24DHCCPU-LS Q26DHCCPU-LS Q12DCCPU-V
High-speed Universal model QCPU	Q03UDV Q04UDV Q06UDV Q13UDV Q26UDV	•	-	•	•	•	•
	Q00U Q01U Q02U	-	-	-	-	-	0
Universal model QCPU	Q03UD(E) Q04UD(E)H Q06UD(E)H Q10UD(E)H Q13UD(E)H Q23UD(E)H Q26UD(E)H Q26UD(E)H Q50UDEH Q100UDEH	•	-	•	•	•	•

\*1. The robot CPU includes CR800-Q.

#### Main base unit other than Q3 DB

O Possible (multiple CPU high-speed communication not available) - Impossible

				- Impossible			
CPU 2 to 4 CPU 1		High-speed Universal model QCPU	Universal model QCPU		Universal model Motion CPU/ process CPU Robot CPU*2/CNC CF		U C Controller CPU
		Q03UDV Q04UDV Q06UDV Q13UDV Q13UDV Q26UDV	000U Q01U Q02U	003UD(E) 004UD(E)H 006UD(E)H 010UD(E)H 013UD(E)H 020UD(E)H 026UD(E)H 026UD(E)H 0100DEH 0100UDEH	Q06UDPV Q13UDPV Q26UDPV	Q173D Q172DS Q173DS	Q24DHCCPU-V Q24DHCCPU-VG Q24DHCCPU-LS Q26DHCCPU-LS Q12DCCPU-V
High-speed Universal model QCPU	Q03UDV Q04UDV Q06UDV Q13UDV Q26UDV	0	-	0	0	-	○*3
Universal model QCPU	Q00U Q01U Q02U	-	-	-	-	-	○*3
	Q03UD(E) Q04UD(E)H Q06UD(E)H Q10UD(E)H Q13UD(E)H Q20UD(E)H Q26UD(E)H Q50UDEH Q100UDEH	0	-	0	0	-	○*3

\*2. The robot CPU includes CR800-Q.
\*3. In case of using Q12DCCPU-V, the redundant power main base unit (Q3□RB) cannot be used.

# Extensive global support coverage providing expert help whenever needed

#### **Global FA centers**

#### EMEA

Europe FA Center MITSUBISHI ELECTRIC EUROPE B.V. Polish Branch Tel: +48-12-347-65-00

Germany FA Center MITSUBISHI ELECTRIC EUROPE B.V. German Branch Tel: +49-2102-486-0 / Fax: +49-2102-486-7780

UK FA Center MITSUBISHI ELECTRIC EUROPE B.V. UK Branch Tel: +44-1707-27-8780 / Fax: +44-1707-27-8695

Czech Republic FA Center MITSUBISHI ELECTRIC EUROPE B.V. Czech Branch Tel: +420-734-402-587

Italy FA Center MITSUBISHI ELECTRIC EUROPE B.V. Italian Branch Tel: +39-039-60531 / Fax: +39-039-6053-312

Turkey FA Center MITSUBISHI ELECTRIC TURKEY ELEKTRIK URUNLERI A.S. Tel: +90-216-969-2500 / Fax: +90-216-661-4447

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Thailand FA Center MITSUBISHI ELECTRIC FACTORY AUTOMATION (THAILAND) CO., LTD. Tel: +66-2682-6522-31 / Fax: +66-2682-6020

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#### Malaysia

Malaysia FA Center Malaysia FA Center Tel: +60-3-7626-5080 / Fax: +60-3-7658-3544

#### Indonesia

Indonesia FA Center

PT. MITSUBISHI ELECTRIC INDONESIA Cikarang Office Tel: +62-21-2961-7797 / Fax: +62-21-2961-7794

#### Vietnam

Hanoi FA Center MITSUBISHI ELECTRIC VIETNAM COMPANY LIMITED Hanoi Branch Office Tel: +84-24-3937-8075 / Fax: +84-24-3937-8076

Ho Chi Minh FA Center MITSUBISHI ELECTRIC VIETNAM COMPANY LIMITED Tel: +84-28-3910-5945 / Fax: +84-28-3910-5947

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#### **Philippines FA Center**

MELCO Factory Automation Philippines Inc. Tel: +63-(0)2-8256-8042

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India Ahmedabad FA Center MITSUBISHI ELECTRIC INDIA PVT. LTD. Ahmedabad Branch Tel: +91-7965120063

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India Gurgaon FA Center MITSUBISHI ELECTRIC INDIA PVT. LTD. Gurgaon Head Office Tel: +91-124-463-0300 / Fax: +91-124-463-0399

India Pune FA Center MITSUBISHI ELECTRIC INDIA PVT. LTD. Pune Branch Tel: +91-20-2710-2000 / Fax: +91-20-2710-2100

#### Americas

#### USA

North America FA Center MITSUBISHI ELECTRIC AUTOMATION, INC. Tel: +1-847-478-2469 / Fax: +1-847-478-2253

#### Mexico

Mexico City FA Center MITSUBISHI ELECTRIC AUTOMATION, INC. Mexico Branch Tel: +52-55-3067-7500

#### Mexico FA Center

MITSUBISHI ELECTRIC AUTOMATION, INC. Queretaro Office Tel: +52-442-153-6014

Mexico Monterrey FA Center MITSUBISHI ELECTRIC AUTOMATION, INC. Monterrey Office Tel: +52-55-3067-7599

#### Brazil

**Brazil FA Center** 

MITSUBISHI ELECTRIC DO BRASIL COMERCIO E SERVICOS LTDA. Tel: +55-11-4689-3000 / Fax: +55-11-4689-3016

#### Support

## **Discover the latest information in Factory Automation**

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- · Overview of available factory automation products
- · Library of downloadable literature
- Support tools such as online e-learning courses, terminology dictionary, etc.
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Mitsubishi Electric Factory Automation Global website: www.MitsubishiElectric.com/fa



#### **Online e-learning**

An extensive library of e-learning courses covering the factory automation product range has been prepared. Courses from beginner to advanced levels of difficulty are available in various languages.



#### Beginner level

Designed for newcomers to Mitsubishi Electric Factory Automation products gaining a background of the fundamentals and an overview of various products related to the course.

#### Basic to Advanced levels

These courses are designed to provide education at all levels. Various different features are explained with application examples providing an easy and informative resource for in-house company training.

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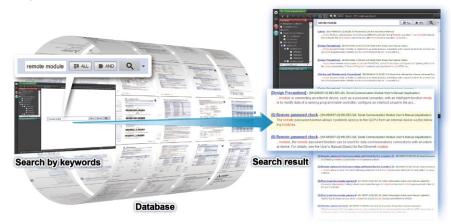


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## Innovative next-generation, e-Manual

#### e-Manual Viewer

The e-Manual viewer is a next-generation digital manual offered by Mitsubishi Electric that consolidates factory automation products manuals into an easy-to-use package with various useful features integrated into the viewer. The e-Manual allows multiple manuals to be cross-searched at once, further reducing time for setting up products and troubleshooting.



#### Key features included

- One-stop database containing all required manuals, with local file cache
- Included with GX Works3 engineering software
- Also available in tablet version
- Easily download manuals all at once

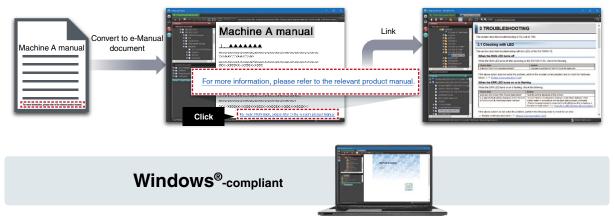
- Multiple users can share the latest manuals and knowhow with document sharing function
- Directly port sample programs within manuals to GX Works3
- Downloaded manuals are usable offline



Windows<sup>®</sup>-compliant

#### e-Manual Create

e-Manual Create is software for converting word files and chm files to e-Manual documents. e-Manual Create allows users to directly refer to Mitsubishi Electric e-Manuals from user's customized device maintenance manuals and such, supporting quick troubleshooting and reduction in document creation process.



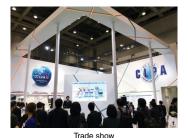
\* To obtain the Windows® version of e-Manual Viewer and e-Manual Create, please contact your local Mitsubishi Electric sales office or representative.

# CC-Link Partner Association (CLPA) - Actively promoting worldwide adoption of CC-Link networks

# Proactively supporting CC-Link, from promotion to specification development

The CC-Link Partner Association (CLPA) was established to promote the worldwide adoption of the CC-Link open-field network. By conducting promotional activities such as organizing trade shows and seminars, conducting conformance tests, and providing catalogs, brochures and website information, CLPA activities are successfully increasing the number of CC-Link partner manufacturers and CC-Link-compatible products. As such, CLPA is playing a major role in the globalization of CC-Link.







Conformance testing lab

Visit the CLPA website for the latest CC-Link information.

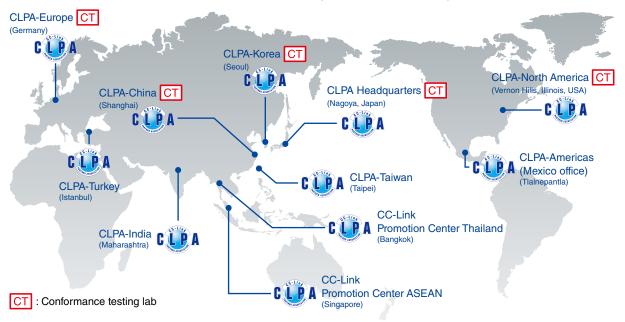


CLPA website www.cc-link.org/en

CLPA Headquarters 6F Ozone Front Bldg. 3-15-58 Ozone Kita-ku, Nagoya 462-0825, JAPAN TEL: +81-52-919-1588 FAX: +81-52-916-8655 e-mail: info@cc-link.org

#### Global influence of CC-Link continues to spread

CC-Link is supported globally by CLPA. With offices throughout the world, support for partner companies can be found locally. Each regional CLPA office undertakes various support and promotional activities to further the influence of CC-Link/CC-Link IE in that part of the world. For companies looking to increase their presence in their local area, CLPA is well placed to assist these efforts through offices in all major regions.



# **Product List**

\*Please check the compatibility and restrictions of the product in the related manual before purchasing.

[Legend] DB : Double brand product (Note) NEW : Recently released product SOON : Product available soon

#### **CPU** module

Туре		Model	Outline				
High-speed Universal model QCPU		Q03UDVCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 30K steps, basic operation processing speed (LD instruction): 1.9 ns, program memory capacity: 120 KB, peripheral connection ports: USB, Ethernet (predefined protocol support function), memory card I/F: SD memory card and extended SRAM cassette CC-Link IE Field Network Basic compatible				
		Q04UDVCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 40K steps, basic operation processing speed (LD instruction): 1.9 ns, program memory capacity: 160 KB, peripheral connection ports: USB, Ethernet (predefined protocol support function), memory card I/F: SD memory card and extended SRAM cassette CC-Link IE Field Network Basic compatible				
		Q06UDVCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 60K steps, basic operation processing speed (LD instruction): 1.9 ns, program memory capacity: 240 KB, peripheral connection ports: USB, Ethernet (predefined protocol support function), memory card I/F: SD memory card and extended SRAM cassette CC-Link IE Field Network Basic compatible				
		Q13UDVCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 130K steps, basic operation processing speed (LD instruction): 1.9 ns, program memory capacity: 520 KB, peripheral connection ports: USB, Ethernet (predefined protocol support function), memory card I/F: SD memory card and extended SRAM cassette CC-Link IE Field Network Basic compatible				
		Q26UDVCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 260K steps, basic operation processing speed (LD instruction): 1.9 ns, program memory capacity: 1040 KB, peripheral connection ports: USB, Ethernet (predefined protocol support function), memory card I/F: SD memory card and extended SRAM cassette CC-Link IE Field Network Basic compatible				
Universal model QCPU		Q00UJCPU	No. of I/O points: 256 points, no. of I/O device points: 8192 points, program capacity: 10K steps, basic operation processi speed (LD instruction): 120 ns, program memory capacity: 40 KB, peripheral connection ports: USB and RS-232, no mer card I/F, 5-slot base, with 100240 V AC input/5 V DC/3 A output power supply				
		Q00UCPU	No. of I/O points: 1024 points, no. of I/O device points: 8192 points, program capacity: 10K steps, basic operation processing speed (LD instruction): 80 ns, program memory capacity: 40 KB, peripheral connection ports: USB and RS-232, no memory card I/F				
		Q01UCPU	No. of I/O points: 1024 points, no. of I/O device points: 8192 points, program capacity: 15K steps, basic operation processing speed (LD instruction): 60 ns, program memory capacity: 60 KB, peripheral connection ports: USB and RS-232, no memory card I/F				
		Q02UCPU	No. of I/O points: 2048 points, no. of I/O device points: 8192 points, program capacity: 20K steps, basic operation processing speed (LD instruction): 40 ns, program memory capacity: 80 KB, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card				
		Q03UDCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 30K steps, basic operation processing speed (LD instruction): 20 ns, program memory capacity: 120 KB, multiple CPU high-speed communication, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card				
		Q04UDHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 40K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 160 KB, multiple CPU high-speed communication, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card				
		Q06UDHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 60K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 240 KB, multiple CPU high-speed communication, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card				
		Q10UDHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 100K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 400 KB, multiple CPU high-speed communication, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card				
		Q13UDHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 130K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 520 KB, multiple CPU high-speed communication, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card				
		Q20UDHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 200K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 800 KB, multiple CPU high-speed communication, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card				
		Q26UDHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 260K steps, basic operation proces speed (LD instruction): 9.5 ns, program memory capacity: 1040 KB, multiple CPU high-speed communication, peripheral connection ports: USB and RS-232, memory card IF: SRAM card, FLASH card, and ATA card				
	Built-in Ethernet type	Q03UDECPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 30K steps, basic operation processing speed (LD instruction): 20 ns, program memory capacity: 120 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card				
		Q04UDEHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 40K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 160 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card				
		Q06UDEHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 60K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 240 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card				
		Q10UDEHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 100K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 400 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card				
		Q13UDEHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 130K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 520 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card				
		Q20UDEHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 200K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 800 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card				
		Q26UDEHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 260K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 1040 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card				
		Q50UDEHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 500K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 2000 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card				
		Q100UDEHCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 1000K steps, basic operation processing speed (LD instruction): 9.5 ns, program memory capacity: 4000 KB, multiple CPU high-speed communication, peripheral connection ports: USB and Ethernet, memory card IF: SRAM card, FLASH card, and ATA card				

Note: General specifications and product guarantee conditions of jointly developed products are different from those of MELSEC products. For more information, please refer to the product manuals or contact your local Mitsubishi representative for details.



Тур	e 	Model	Outline
		Q04UDPVCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 40K steps, basic operation processing speed (LD instruction): 1.9 ns, program memory capacity: 160 KB, peripheral connection ports: USB, Ethernet (predefined protocol support function), memory card I/F: SD memory card and extended SRAM cassette CC-Link IE Field Network Basic compatible
Universal model	process CPU	Q06UDPVCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 60K steps, basic operation processing speed (LD instruction): 1.9 ns, program memory capacity: 240 KB, peripheral connection ports: USB, Ethernet (predefined protocol support function), memory card I/F: SD memory card and extended SRAM cassette CC-Link IE Field Network Basic compatible
Oniversal model	process CPU	Q13UDPVCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 130K steps, basic operation processing speed (LD instruction): 1.9 ns, program memory capacity: 520 KB, peripheral connection ports: USB, Ethernet (predefined protocol support function), memory card I/F: SD memory card and extended SRAM cassette CC-Link IE Field Network Basic compatible
		Q26UDPVCPU	No. of I/O points: 4096 points, no. of I/O device points: 8192 points, program capacity: 260K steps, basic operation processing speed (LD instruction): 1.9 ns, program memory capacity: 1040 KB, peripheral connection ports: USB, Ethernet (predefined protocol support function), memory card I/F: SD memory card and extended SRAM cassette CC-Link IE Field Network Basic compatible
		Q24DHCCPU-V	No. of I/O points: 4096 points, endian format: little endian, removable storage: SD memory card, OS: VxWorks® Version 6.8.1
C Controller CPI		Q26DHCCPU-LS	No. of I/O points: 4096 points, endian format: little endian, removable storage: SD memory card, OS: No pre-installed operating system (Operating system installed by user)
C Controller CPC	0	Q24DHCCPU-LS	No. of I/O points: 4096 points, endian format: little endian, removable storage: SD memory card, OS: No pre-installed operating system (Operating system installed by user)
		Q12DCCPU-V	No. of I/O points: 4096 points, endian format: little endian, removable storage: CompactFlash card, OS: VxWorks® Version 6.4
		Q12DCCPU-V-BZ11	C Controller (Q12DCCPU-V) pre-installed with SECS/GEM COMMUNICATION SOFTWARE for NONGEM, supports SECS-I (SEMI E4), HSMS (SEMI E37)
		Q12DCCPU-V-BZ13	C Controller (Q12DCCPU-V) pre-installed with SECS/GEM COMMUNICATION SOFTWARE for GEM, middle kit version that supports GEM (SEMI E30). (does not support Trace data collection, Limit monitoring, Document file output)
		Q12DCCPU-V-BZ15	C Controller (Q12DCCPU-V) pre-installed with SECS/GEM COMMUNICATION SOFTWARE for GEM ADVANCED, full kit version that supports GEM (SEMI E30). (supports Trace data collection, Limit monitoring, Document file output)
		Q12DCCPU-V-BZ19	C Controller (Q12DCCPU-V) pre-installed with DATA COLLECTION SOFTWARE, equipped with Simple MES functionality.
	Applications pre-installed model	Q12DCCPU-V-BZ1B	C Controller (Q12DCCPU-V) pre-installed with DATA COLLECTION SOFTWARE Light, not equipped with Simple MES functionality.
	model	Q24DHCCPU-VG-B000	C Controller (Q24DHCCPU-VG) pre-installed with GENWARE®3-VG Runtime License Version, runtime library and font data are pre-installed.
		Q24DHCCPU-VG-B002	C Controller (Q24DHCCPU-VG) pre-installed with GENWARE®3-VG Tool License Version, GUI development environment (CI SKETCH-E) is pre-installed into the Runtime License version
		Q26DHCCPU-LS-B031	C Controller (Q26DHCCPU-LS) pre-installed with Lineo uLinux Station +, Web pages application that can be configured in basic Linux® system.
		Q24DHCCPU-LS-B030	C Controller (Q24DHCCPU-LS) pre-installed with Lineo uLinux and uLinux Station, Web pages application that can be configured in basic Linux <sup>®</sup> system.
	Cable	Q12DCCPU-CBL*1*2*3	RS-232 connection converter cable (custom mini-DIN to 9-pin D-sub connector)

For use with 024DHCCPU-V, 024DHCCPU-VG.
 \*2. For use with 024DHCCPU-LS, 026DHCCPU-LS.
 \*3. For use with 012DCCPU-V.

### CPU module

Туре	Model	Outline
	Q6BAT	Replacement battery
	Q7BATN	Replacement large-capacity battery
Battery	Q7BATN-SET	Large-capacity battery with holder for installing CPU
	Q8BAT	Replacement large-capacity battery module
	Q8BAT-SET	Large-capacity battery module with CPU connection cable
	Q4MCA-1MBS*1	Extended SRAM cassette, capacity: 1 MB
Extended SRAM cassette	Q4MCA-2MBS*1	Extended SRAM cassette, capacity: 2 MB
Extended Shaw casselle	Q4MCA-4MBS*1	Extended SRAM cassette, capacity: 4 MB
	Q4MCA-8MBS*1	Extended SRAM cassette, capacity: 8 MB
	NZ1MEM-2GBSD*1*2*3*4	SD memory card, capacity: 2 GB
	NZ1MEM-4GBSD*1*2*3*4	SDHC memory card, capacity: 4 GB
SD memory card	NZ1MEM-8GBSD*1*2*3*4	SDHC memory card, capacity: 8 GB
	NZ1MEM-16GBSD*1*2*3*4	SDHC memory card, capacity: 16 GB
	Q2MEM-1MBSN*5	SRAM memory card, capacity: 1 MB
	Q2MEM-2MBSN*5	SRAM memory card, capacity: 2 MB
	Q3MEM-4MBS*5	SRAM memory card, capacity: 4 MB
	Q3MEM-4MBS-SET*5	SRAM memory card with cover, capacity: 4 MB
Memory card	Q3MEM-8MBS*6	SRAM memory card, capacity: 8 MB
	Q3MEM-8MBS-SET*6	SRAM memory card with cover, capacity: 8 MB
	Q3MEM-CV	Memory card protective cover for the Universal model QCPU (comes with Q3MEM-4MBS-SET/Q3MEM-8MBS-SET)
	Q3MEM-CV-H	Memory card protective cover for the Process CPU (comes with Q3MEM-4MBS-SET)
	GT05-MEM-128MC*4	CompactFlash card, capacity: 128 MB
	GT05-MEM-256MC*4	CompactFlash card, capacity: 256 MB
	QD81MEM-512MBC*4*7	CompactFlash card, capacity: 512 MB
CompactFlash card	QD81MEM-1GBC*4*7	CompactFlash card, capacity: 1 GB
	QD81MEM-2GBC*4*7	CompactFlash card, capacity: 2 GB
	QD81MEM-4GBC*4*7	CompactFlash card, capacity: 4 GB
	QD81MEM-8GBC*4*7	CompactFlash card, capacity: 8 GB
SRAM card battery	Q2MEM-BAT	Replacement battery for Q2MEM-1MBSN and Q2MEM-2MBSN
Shaw card ballery	Q3MEM-BAT	Replacement battery for Q3MEM-4MBS and Q3MEM-8MBS
Connection cable	QC30R2	RS-232 cable for connecting PC and CPU, 3 m (between mini-DIN6P and Dsub9P)
Cable disconnection prevention holder	Q6HLD-R2	Holder for preventing RS-232 cable (Programmable Controller CPU connection) disconnection

For use with QnUDVCPU.
 For use with QADHCCPU-V, Q24DHCCPU-VG.
 For use with Q24DHCCPU-V, Q24DHCCPU-VG.
 For use with Q24DHCCPU-LS, Q26DHCCPU-LS.
 Mitsubishi Electric shall not guarantee the operation of any non-Mitsubishi Electric products.
 For use with the Universal model QCPUs (except QnUDV) and redundant CPUs that are equipped with the memory card interface.
 For use with Q12DCCPU-V.



Base unit		
Туре	Model	Outline
	Q33B	3 slots, 1 power supply module required, for Q Series modules
Main base	Q35B	5 slots, 1 power supply module required, for Q Series modules
Main Dase	Q38B	8 slots, 1 power supply module required, for Q Series modules
	Q312B	12 slots, 1 power supply module required, for Q Series modules
	Q35DB	5 slots, power supply module required, for Q Series modules
Multiple CPU high speed main base	Q38DB	8 slots, 1 power supply module required, for Q Series modules
main babb	Q312DB	12 slots, 1 power supply module required, for Q Series modules
	Q32SB	2 slots, 1 slim type power supply module required, for Q Series modules
Slim type main base	Q33SB	3 slots, 1 slim type power supply module required, for Q Series modules
	Q35SB	5 slots, 1 slim type power supply module required, for Q Series modules
Redundant power main base	Q38RB	8 slots, 2 redundant power supply modules required, for Q Series modules
	Q63B	3 slots, 1 power supply module required, for Q Series modules
	Q65B	5 slots, 1 power supply module required, for Q Series modules
Extension base	Q68B	8 slots, 1 power supply module required, for Q Series modules
Extension base	Q612B	12 slots, 1 power supply module required, for Q Series modules
	Q52B	2 slots, power supply module not required, for Q Series modules
	Q55B	5 slots, power supply module not required, for Q Series modules
Redundant power extension base	Q68RB	8 slots, 2 redundant power supply modules required, for Q Series modules
	QC05B	0.45 m cable for connecting extension base unit
	QC06B	0.6 m cable for connecting extension base unit
Extension cable	QC12B	1.2 m cable for connecting extension base unit
Extension cable	QC30B	3 m cable for connecting extension base unit
	QC50B	5 m cable for connecting extension base unit
	QC100B	10 m cable for connecting extension base unit
	Q6DIN1	DIN rail mounting adapter for Q38B, Q312B, Q68B, Q612B, Q38RB, Q68RB, Q38DB, and Q312DB
DIN roll mounting adapter	Q6DIN2	DIN rail mounting adapter for Q35B, Q65B, and Q00UJCPU
DIN rail mounting adapter	Q6DIN3	DIN rail mounting adapter for Q32SB, Q33SB, Q35SB, Q33B, Q52B, Q55B, and Q63B
	Q6DIN1A	DIN rail mounting adapter (with vibration-proofing bracket set) for Q3_B, Q5_B, Q6_B, Q38RB, Q68RB
Blank cover	QG60	Blank cover for I/O slot

# Power supply module

	Q61P	Input voltage: 100240 V AC, output voltage: 5 V DC, output current: 6 A
Power supply	Q62P	Input voltage: 100240 V AC, output voltage: 5/24 V DC, output current: 3/0.6 A
Power supply	Q63P	Input voltage: 24 V DC, output voltage: 5 V DC, output current: 6 A
	Q64PN	Input voltage: 100240 V AC, output voltage: 5 V DC, output current: 8.5 A
Power supply with life detection	Q61P-D	Input voltage: 100240 V AC, output voltage: 5 V DC, output current: 6 A
Slim type power supply	Q61SP	Input voltage: 100240 V AC, output voltage: 5 V DC, output current: 2 A
Dedundent newer eventy	Q63RP	Input voltage: 24 V DC, output voltage: 5 V DC, output current: 8.5 A
Redundant power supply	Q64RPN	Input voltage: 100240 V AC, output voltage: 5 V DC, output current: 8.5 A

#### I/O module

		QX10	16 points, 100120 V AC, response time: 20 ms, 16 points/common, 18-point terminal block
	AC	QX10-TS	16 points, 100120 V AC, response time: 20 ms, 16 points/common, 18-point spring clamp terminal block
		QX28	8 points, 100240 V AC, response time: 20 ms, 8 points/common, 18-point terminal block
		QX40	16 points, 24 V DC, response time: 1/5/10/20/70 ms, 16 points/common, positive common, 18-point terminal block
		QX40-TS	16 points, 24 V DC, response time: 1/5/10/20/70 ms, 16 points/common, positive common, 18-point spring clamp termina
		QX40-S1	16 points, 24 V DC, response time: 0.1/0.2/0.4/0.6/1 ms, 16 points/common, positive common, 18-point terminal block
	50	QX40H	16 points, 24 V DC, response time: 0/0.1/0.2/0.4/0.6/1 ms, 8 points/common, positive common, 18-point terminal block
	DC (Positive	QX41*2*3	32 points, 24 V DC, response time: 1/5/10/20/70 ms, 32 points/common, positive common, 40-pin connector
	common)*1	QX41-S1*2	32 points, 24 V DC, response time: 0.1/0.2/0.4/0.6/1 ms, 32 points/common, positive common, 40-pin connector
		QX41-S2*2*3	32 points, 24 V DC, response time: 1/5/10/20/70 ms, 32 points/common, positive common, 40-pin connector
		QX42*2	64 points, 24 V DC, response time: 1/5/10/20/70 ms, 32 points/common, positive common, 40-pin connector
		QX42-S1*2	64 points, 24 V DC, response time: 0.1/0.2/0.4/0.6/1 ms, 32 points/common, positive common, 40-pin connector
Input	AC/DC	QX50	16 points, 48 V AC/DC, response time: 20 ms, 16 points/common, positive/negative common, 18-point terminal block
		QX70	16 points, 5/12 V DC, response time: 1/5/10/20/70 ms, 16 points/common, positive/negative common, 18-point terminal
		QX70H	16 points, 5 V DC, response time: 0/0.1/0.2/0.4/0.6/1 ms, 8 points/common, positive common, 18-point terminal block
	DC sensor	QX71*2	32 points, 5/12 V DC, response time: 1/5/10/20/70 ms, 32 points/common, positive/negative common, 40-pin connector
		QX72*2	64 points, 5/12 V DC, response time: 1/5/10/20/70 ms, 32 points/common, positive/negative common, 40-pin connector
		QX80	16 points, 24 V DC, response time: 1/5/10/20/70 ms, 16 points/common, negative common, 18-point terminal block
		QX80-TS	16 points, 24 V DC, response time: 1/5/10/20/70 ms, 16 points/common, negative common, 18-point spring clamp terminal
		QX80H	16 points, 24 V DC, response time: 0/0.1/0.2/0.4/0.6/1 ms, 8 points/common, negative common, 18-point terminal block
	DC	QX81*3*4	
	(Negative	QX81-S2*3*4	32 points, 24 V DC, response time: 1/5/10/20/70 ms, 32 points/common, negative common, 37-pin D-sub connector
	common)*1	QX81-52 **	32 points, 24 V DC, response time: 1/5/10/20/70 ms, 32 points/common, negative common, 37-pin D-sub connector
			64 points, 24 V DC, response time: 1/5/10/20/70 ms, 32 points/common, negative common, 40-pin connector
		QX82-S1*2	64 points, 24 V DC, response time: 0.1/0.2/0.4/0.6/1 ms, 32 points/common, negative common, 40-pin connector
		QX90H	16 points, 5 V DC, response time: 0/0.1/0.2/0.4/0.6/1 ms, 8 points/common, negative common, 18-point terminal block
		QY10	16 points, 24 V DC/240 V AC, 2 A/point, 8 A/common, response time: 12 ms, 16 points/common, 18-point terminal block
	Relay	QY10-TS	16 points, 24 V DC/240 V AC, 2 A/point, 8 A/common, response time: 12 ms, 16 points/common, 18-point spring clamp termina
		QY18A	8 points, 24 V DC/240 V AC, 2 A/point, response time: 12 ms, 18-point terminal block, all points independent
	Triac	QY22	16 points, 100240 V AC, 0.6 A/point, 4.8 A/common, response time: 1 ms + 0.5 cycle, 16 points/common, 18-point terminal block, with surge suppression
		QY40P	16 points, 1224 V DC, 0.1 A/point, 1.6 A/common, response time: 1 ms, 16 points/common, sink type, 18-point terminal block, overload protection function, overheat protection function, surge suppression
		QY40P-TS	16 points, 1224 V DC, 0.1 A/point, 1.6 A/common, response time: 1 ms, 16 points/common, sink type, 18-point spring clamp terminal block, overload protection function, overheat protection function, surge suppression
	Transistor	QY41H	32 points, 524 V DC, 0.2 A/point, 2 A/common, response time: 2 us, 32 points/common, sink type, 40-pin connector, with surge suppression
	(Sink)	QY41P*2	32 points, 1224 V DC, 0.1 A/point, 2 A/common, response time: 1 ms, 32 points/common, sink type, 40-pin connector, overload protection function, overheat protection function, surge suppression
<b>.</b>		QY42P*2	64 points, 1224 V DC, 0.1 A/point, 2 A/common, response time: 1 ms, 32 points/common, sink type, 40-pin connector, overload protection function, overheat protection function, surge suppression
Output		QY50	16 points, 1224 V DC, 0.5 A/point, 4 A/common, response time: 1 ms, 16 points/common, sink type, 18-point terminal block, with surge suppression and fuse
	Transistor (Independent)	QY68A	8 points, 524 V DC, 2 A/point, 8 A/module, response time: 10 ms, sink/source type, 18-point terminal block, with surge suppression, all points independent
		QY70	16 points, 512 V DC, 16 mA/point, 256 mA/common, response time: 0.5 ms, 16 points/common, sink type, 18-point terminal block, with fuse
	TTL CMOS	QY71*2	32 points, 512 V DC, 16 mA/point, 512 mA/common, response time: 0.5 ms, 32 points/common, sink type, 40-pin connector, with fuse
		QY80	16 points, 1224 V DC, 0.5 A/point, 4 A/common, response time: 1 ms, 16 points/common, source type, 18-point terminal block, with surge suppression and fuse
	Transistor	QY80-TS	16 points, 1224 V DC, 0.5 A/point, 4 A/common, response time: 1 ms, 16 points/common, source type, 18-point spring clamp terminal block, with surge suppression and fuse
	(Source)	QY81P*4	32 points, 1224 V DC, 0.1 A/point, 2 A/common, response time: 1 ms, 32 points/common, source type, 37-pin D-sub connector, overload protection function, overheat protection function, surge suppression
		QY82P*2	64 points, 1224 V DC, 0.1 A/point, 2 A/common, response time: 1 ms, 32 points/common, source type, 40-pin connector, overload protection function, overheat protection function, surge suppression
		QH42P*2*5	Input: 32 points, 24 V DC, response time: 1/5/10/20/70 ms, 32 points/common, positive common, output: 32 points, 1224 V DC, 0.1 A/point, 2 A/common, response time: 1 ms, 32 points/common, sink type, 40-pin connector, overload protection function, overheat protection function, surge suppression
I/O	DC input/ transistor output	QX48Y57	Input: 8 points, 24 V DC, response time: 1/5/10/20/70 ms, 8 points/common, positive common, output: 7 points, 1224 V DC, 0.5 A/point, 2 A/common, response time: 1 ms, 7 points/common, sink type, 18-point terminal block, with surge suppression and fuse
		QX41Y41P*2*5	Input: 32 points, 24 V DC, response time: 1/5/10/20/70 ms, 32 points/common, positive common, output: 32 points, 1224 V DC, 0.1 A/point, 2 A/common, response time: 1 ms, 32 points/common, sink type, 40-pin connector, overload protection function, overheat protection function, surge suppression
Interrupt mo	odule	Q160	16 points, 24 V DC, response time: 0.1/0.2/0.4/0.6/1 ms, 16 points/common, 18-point terminal block
			supply must be connected to the common terminal.
Accordingly,	"Negative common" inc	licates that the negative lead r	nust be connected to the common terminal.
	-	-	A6CON1/A6CON2/A6CON3/A6CON4.



Туре		Model	Outline
		A6CON1	32-point connector soldering type (40-pin connector)
		A6CON2	32-point connector crimp-contact type (40-pin connector)
		A6CON3	32-point connector pressure-displacement (flat cable) type (40-pin connector)
Connector		A6CON4	32-point connector soldering type (40-pin connector, cable connectable bidirectionally)
		A6CON1E	32-point connector soldering type (37-pin D-sub connector)
		A6CON2E	32-point connector crimp-contact type (37-pin D-sub connector)
		A6CON3E	32-point connector pressure-displacement (flat cable) type (37-pin D-sub connector)
Spring clamp term	ninal block	Q6TE-18SN	For 16-point I/O modules, 0.31.5 mm <sup>2</sup> (2216 AWG)
		Q6TA32	For 32-point I/O modules, 0.5 mm <sup>2</sup> (20 AWG)
Terminal block ad	apter	Q6TA32-TOL	Q6TA32 dedicated tool
		A6TBXY36	For positive common input modules and sink output modules (standard type)
		A6TBXY54	For positive common input modules and sink output modules (2-wire type)
Connector/termina	al block	A6TBX70	For positive common input modules (3-wire type)
conversion modul	е	A6TBX36-E	For negative common input modules (standard type)
		A6TBX54-E	For negative common input modules (2-wire type)
		A6TBY36-E	For source output modules (standard type)
		AC05TB	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 0.5 m
		AC10TB	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 1 m
		AC20TB	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 2 m
		AC30TB	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 3 m
		AC50TB	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 5 m
	ahla	AC80TB	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 8 m *Common current 0.5 A or lower
	able	AC100TB	For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 10 m *Common current 0.5 A or lower
		AC05TB-E	For A6TBX36-E, A6TBY36-E, and A6TBX54-E (negative common/source type), 0.5 m
		AC10TB-E	For A6TBX36-E, A6TBY36-E, and A6TBX54-E (negative common/source type), 1 m
		AC20TB-E	For A6TBX36-E, A6TBY36-E, and A6TBX54-E (negative common/source type), 2 m
		AC30TB-E	For A6TBX36-E, A6TBY36-E, and A6TBX54-E (negative common/source type), 3 m
		AC50TB-E	For A6TBX36-E, A6TBY36-E, and A6TBX54-E (negative common/source type), 5 m
Relay terminal mo	odule	A6TE2-16SRN	For 40-pin connector 24 V DC transistor output modules (sink type)
		AC06TE	For A6TE2-16SRN, 0.6 m
		AC10TE	For A6TE2-16SRN, 1 m
Ca	able	AC30TE	For A6TE2-16SRN, 3 m
		AC50TE	For A6TE2-16SRN, 5 m
		AC100TE	For A6TE2-16SRN, 10 m

# Analog I/O module

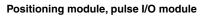
	Voltage input	Q68ADV	8 channels, -1010 V DC/-40004000 (normal resolution mode), -1600016000 (high resolution mode), conversion speed: 80 μs/channel, 18-point terminal block
	Current input         Q66AD-DG*1         18-point terminal block, channel isolated, supplies power to 2-wire transmitter           Current input         Q66AD-DG*1         6 channels, 420 mA DC (with 2-wire transmitter)/04000 (normal resolution 020mA DC/04000 (normal resolution mode), 012000 (high resolution r 40-pin connector, channel isolated, supplies power to 2-wire transmitter	Q62AD-DGH	2 channels, 420 mA DC/032000 (16 bits), 064000 (32 bits), conversion speed: 10 ms/2 channels, 18-point terminal block, channel isolated, supplies power to 2-wire transmitter
		6 channels, 420 mA DC (with 2-wire transmitter)/04000 (normal resolution mode), 012000 (high resolution mode), 020mA DC/04000 (normal resolution mode), 012000 (high resolution mode), conversion speed: 10 ms/channel, 40-pin connector, channel isolated, supplies power to 2-wire transmitter	
Analan		Q68ADI	8 channels, 020 mA DC/04000 (normal resolution mode), 012000 (high resolution mode), conversion speed: 80 µs/channel, 18-point terminal block
Analog input	Voltage/current input         Ude4ADH         18-point terminal block           Q64AD         4 channels, -1010 V DC/-40004000 (normal resolution mode), -11 020 mA DC/04000 (normal resolution mode), 012000 (high res 18-point terminal block           Q64AD-GH         4 channels, -1010 V DC/-3200032000 (16 bits), -6400064000 ( 064000 (32 bits), conversion speed: 10 ms/4 channels, 18-point ter 8 channels, -1010 V DC/-40004000 (normal resolution mode), -11	Q64ADH	4 channels, -1010 V DC/-2000020000, 020 mA DC/020000, conversion speed: 20 µs/channel, 18-point terminal block
			4 channels, -1010 V DC/-40004000 (normal resolution mode), -1600016000 (high resolution mode), 020 mA DC/04000 (normal resolution mode), 012000 (high resolution mode), conversion speed: 80 μs/channel, 18-point terminal block
		4 channels, -1010 V DC/-3200032000 (16 bits), -6400064000 (32 bits), 020 mA DC/032000 (16 bits), 064000 (32 bits), conversion speed: 10 ms/4 channels, 18-point terminal block, channel isolated	
		Q68AD-G*1	8 channels, -1010 V DC/-40004000 (normal resolution mode), -1600016000 (high resolution mode), 020 mA DC/04000 (normal resolution mode), 012000 (high resolution mode), conversion speed: 10 ms/channel, 40-pin connector, channel isolated

\*1. A connector is not provided. The A6CON1/A6CON2/A6CON4 connector must be ordered separately.

# Analog I/O module

Ту	ре	Model	Outline
N	Voltage output	Q68DAVN	8 channels, -40004000 (normal resolution mode), -1600016000 (high resolution mode)/-1010 V DC, conversion speed: 80 μs/channel, 18-point terminal block
	Current output	Q68DAIN	8 channels, 04000 (normal resolution mode), 012000 (high resolution mode)/020 mA DC, conversion speed: 80 μs/channel, 18-point terminal block
		Q64DAH	4 channels, -2000020000/-1010V DC, 020000/020 mA DC, conversion speed: 20 μs/channel, 18-point terminal block
		Q62DAN	2 channels, -40004000 (normal resolution mode), -1600016000 (high resolution mode)/-1010 V DC, 04000 (normal resolution mode), 012000 (high resolution mode)/020 mA DC, conversion speed: 80 μs/channel, 18-point terminal block
Analog output	Voltage/current	Q62DA-FG	2 channels, -1600016000/-1010 V DC, -1200012000/-1212 V DC, 012000/020 mA DC, -300013500/022 mA DC, conversion speed: 10 ms/2 channels, 18-point terminal block, channel isolated
	output	Q64DAN	4 channels, -40004000 (normal resolution mode), -1600016000 (high resolution mode)/-1010 V DC, 04000 (normal resolution mode), 012000 (high resolution mode)/020 mA DC, conversion speed: 80 μs/channel, 18-point terminal block
		Q66DA-G*1	6 channels, -40004000 (normal resolution mode), -1600016000 (high resolution mode)/-1010 V DC, -40004000 (normal resolution mode), -1200012000 (high resolution mode)/-1212 V DC, 04000 (normal resolution mode), 012000 (high resolution mode)/020 mA DC, -10004500 (normal resolution mode), -300013500 (high resolution mode)/022 mA DC, conversion speed: 6 ms/channel, 40-pin connector, channel isolated
Analog input/ output	Voltage and current input/ output	Q64AD2DA	Input: 4 channels, -1010 V DC/-40004000 (normal resolution mode), -1600016000 (high resolution mode), 020 mA DC/04000 (normal resolution mode), 012000 (high resolution mode), conversion speet: 500 µs/channel, output: 2 channels, -40004000 (normal resolution mode), -1600016000 (high resolution mode)/-1010 V DC, 04000 (normal resolution mode), 012000 (high resolution mode)/020 mA DC, conversion speed: 500 µs/channel, 18-point terminal block
Load cell input		Q61LD	1 channel, input (load cell output): 0.03.3 mV/V, output (resolution): 010000, conversion speed: 10 ms, 18-point terminal block
CT input modu	le	Q68CT	8 channels, input: CT 05 A AC, 050 A AC, 0100 A AC, 0200 A AC, 0400 A AC, 0600 A AC, output: 010000, 18-point terminal block
		Q64TD	4 channels, thermocouple (B, R, S, K, E, J, T, N), disconnection detection function, conversion speed: 40 ms/channel, channel isolated, 18-point terminal block
	<b>T</b> he sum a second seco	Q64TDV-GH	4 channels, thermocouple (B, R, S, K, E, J, T, N), disconnection detection function, conversion speed: sampling cycle × 3, sampling cycle: 20 ms/channel, channel isolated, 18-point terminal block
	Thermocouple	Q68TD-G-H01*1*2	8 channels, thermocouple (B, R, S, K, E, J, T, N), disconnection detection function, conversion speed: 320 ms/8 channels, channel isolated, 40-pin connector
Temperature input		Q68TD-G-H02*1	8 channels, thermocouple (B, R, S, K, E, J, T, N), disconnection detection function, conversion speed: 640 ms/8 channels, channel isolated, 40-pin connector
		Q64RD	4 channels, platinum RTD (Pt100, JPt100), disconnection detection function, conversion speed: 40 ms/channel, 18-point terminal block
	RTD	Q64RD-G	4 channels, platinum RTD (Pt100, JPt100), nickel RTD (Ni100), disconnection detection function, conversion speed: 40 ms/channel, channel isolated, 18-point terminal block
		Q68RD3-G*1	8 channels, platinum RTD (Pt100, JPt100), nickel RTD (Ni100), disconnection detection function, conversion speed: 320 ms/8 channels, channel isolated, 40-pin connector
		Q64TCTTN	4 channels, thermocouple (K, J, T, B, S, E, R, N, U, L, PLII, W5Re/W26Re), heating control/cooling control/heating-cooling control, sampling cycle: 500 ms/4 channels, channel isolated, 18-point terminal block
Temperature control	Thermocouple	Q64TCTTBWN	4 channels, thermocouple (K, J, T, B, S, E, R, N, U, L, PLII, W5Re/W26Re), heating control/cooling control/heating-cooling control, heater disconnection detection function, sampling cycle: 500 ms/4 channels, channel isolated, two 18-point terminal blocks
control	RTD	Q64TCRTN	4 channels, platinum RTD (Pt100, JPt100), heating control/cooling control/heating-cooling control, sampling cycle: 500 ms/4 channels, channel isolated, 18-point terminal block
		Q64TCRTBWN	4 channels, platinum RTD (Pt100, JPt100), heating control/cooling control/heating-cooling control, heater disconnection detection function, sampling cycle: 500 ms/4 channels, channel isolated, two 18-point terminal blocks
Loop control		Q62HLC	2 channels, input: thermocouple/micro voltage/voltage/current, conversion speed (input): 25 ms/2 channels, sampling cycle: 25 ms/2 channels, output: 420 mA DC, conversion speed (output): 25 ms/2 channels, 18-point terminal block, with 5 PID control modes

A connector is not provided. The A6CON1/A6CON2/A6CON4 connector must be ordered separately.
 Depending on the combination of power source module and base unit, the installable slot position may be limited.



With Col.Link LE For Link Level connectivity         0077GF4         4-axee, 2-3/4-axis linear interpolation, 2-axis calcular interpolation, advances control, control unit: mm, incl., digrae, pulse, no. of polationing date: 600axis, 2-perior connectivity           Simple motion         077GF4         4-axee, 2-3/4-axis linear interpolation, 2-axis circular interpolation, advances control, control unit: mm, incl., digrae, pulse, no. of polationing date: 600axis, 2-perior connectivity           With Simple motion         077GF4         4-axee, 2-3/4-axis linear interpolation, 2-axis circular interpolation, control unit: mm, incl., digrae, pulse, no. of polationing date: 600axis, 2-perior connectivity           With Simple motion         077MS12**         2-axis, 2-3/4-axis linear interpolation, 2-axis circular interpolation, control unit: mm, incl., digrae, pulse, no. of polationing date: 600axis, 4-0pin connectivity           077MS12**         077MS12**         4-axee, 2-7:5/4-axis linear interpolation, 2-axis circular interpolation, control unit: mm, incl., digrae, pulse, no. of polationing date: 600axis, 4-0pin connectivity           077MS12**         077MS12**         4-axee, 2-7:5/4-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, digrae, pulse, no. of polationing date: 600axis, max. culput pulse; 200 Spe, 4-0pin connectivity           077MS12**         4-axee, 2-7:4-4-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degrae, pulse, no. of polationing date: 600axis, max. culput pulse; 200 Spe, 4-0pin connector           077MS12**         4-axee, 2-7:4-4-axis linear interepolation, 2-axis circular interpolation, control	т	ype	Model	Outline
Field Network         OUT/TeFe         no. of positioning data: GOOXais, 28-pin connector, with CC-Link IE Field Network connectivity           Simple motion         OUT/TeFe         Reaves, 2-47 value linear interpolation, 2-value circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: GOOXais, 40-pin connector, with CC-Link IE Field Network connectivity           Whith SSCNETEINH connectivity         OUT/TMS2**         A-asse, 2-37.44-asis linear interpolation, 2-value circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: GOOXais, 40-pin connector, with SSCNETEINH connectivity           Whith SSCNETEINH connectivity         OUT/TMS2**         A-asse, 2-37.44-asis linear interpolation, 2-vasis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: GOOXais, 40-pin connector, with SSCNETEINH connectivity           OUT/TMS16**         No. of positioning data: GOOXais, 2-40-pin connector, with SSCNETEINH connectivity           OUT/TMS16**         No. of positioning data: GOOXais, Taxas circular interpolation, 2-vasis positioning data: GOOXais, max. output pulse: 200 kpps, 40-pin connector           OUT/FN**         Pases, 2-374-vasis linear interpolation, 2-vasis circular interpolation, 2-vasis positioning data: GOOXais, max. output pulse: 200 kpps, 40-pin connector           OUT/FN**         Pases, 2-374-vasis linear interpolation, 2-vasis circular interpolation, 3-vasis helical interpolat		With	QD77GF4	
Simple motion         Q077GF16*1         Inc. d passing main merpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, 2-6-in corrector, with SCOLTAK EFTeM Hervoix correctivity           Whith SCONETUPH connectivity         Q077MS2**         2-axes, 2-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, 4-0-in corrector, with SCONETUPH - control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, 4-0-in corrector, with SCONETUPH - control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, 4-0-in corrector, with SCONETUPH - control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, 4-0-in corrector, with SCONETUPH - contentivity           Very option         4-axes, 2-73/4-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 200 kpps, 40-pin connectivity           0075P21N*1         4-axes, 2-73/4-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 200 kpps, 40-pin connectivity           0075P2N*1         4-axes, 2-73/4-axis linear interpolation, 2-axis circular interpolatin, 2-axis circular interpolatin, 2-axis circular interp		Field Network	QD77GF8	
Write SCNETUPI connectivity         OD77MS2*2         no. of positioning data: 600/axis, 40-pin connector, with SSCNETUPI connectivity           Vite SCNETUPI connectivity         0077MS4*2         4-axes, 2-/3-4-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, 40-pin connector, with SSCNETUPI connectivity           Vite SCNETUPI         0077MS16*1         16-axes, 2-/3-4-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, 40-pin connector, with SSCNETUPI connectivity           Vite output         0075P1N*2         1-axis, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 200 kpps, 40-pin connector           0075P1N*2         1-axis, control unit: mm, inch, degree, pulse, no. of positioning data: 500/axis, max. output pulse: 200 kpps, 40-pin connector           0075P1N*2         2-axes, 2-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 500/axis, max. output pulse: 200 kpps, 40-pin connector           0075P1N*2         4-axes, control unit: pulse, no. of positioning data: 500/axis, max. output pulse: 200 kpps, 40-pin connector           0075D1N*2         4-axes, control unit: pulse, no. of positioning data: 500/axis, max. output pulse: 200 kpps, 40-pin connector           0075D1N*2         4-axes, control unit: pulse, no. of positioning data: 500/axis, max. output pulse: 40 kpps, 40-pin connector           0075D1N*2         4-axes, control unit: pulse, no. of po		connectivity	QD77GF16*1	
SECNETING         OD77MS4**         A-axes, 2/3/4-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 00/0xis, 4-0-pin connector, with SSCNETIMH connectivity           Postborne         OD77MS18**         16-axes, 2-3/4-4 axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 00/0xis, max. output pulse: 200 kpps, 40-pin connector           Postborne         OD75P1N**         1-axis, control unit: mm, inch, degree, pulse, no. of positioning data: 00/0xis, max. output pulse: 200 kpps, 40-pin connector           OD75P4**         2-axes, 2-axis linear interpolation, 2-axis circular interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 00/0xis, max. output pulse: 200 kpps, 40-pin connector           OD75P4***         4-axes, 2-axis linear interpolation, 2-axis circular interpolation, 2-axis circular interpolation, 2-axis           OD70P4**         4-axes, 2-axis linear interpolation, 2-axis           OD70P4**         4-axes, 2-axis linear interpolation, 2-axis           OD75D1N**         1-axis, control unit: mm, inch, degree, pulse, no. of positioning data: 00/0xis, max. output pulse: 200 kpps, 40-pin connector           OD75D1N**         4-axes, 2-3/3-4 axis linear interpolation, 2-axis circular interpolation, 3-axis helical in	motion	14 Cale	QD77MS2*2	
Image: Control with Space and Spa		SSCNETI/H	QD77MS4*2	
High-speed counter         40-pin connector           Open collection         075P2N**         2-axes, 2-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 200 kpps, 40-pin connector           0070P4**         4-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 200 kpps, 40-pin connector           0070P4**         4-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 200 kpps, 40-pin connector           0070P4**         4-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 200 kpps, 40-pin connector           0070P4**         4-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 200 kpps, 40-pin connector           0075D2N**         8-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 200 kpps, 40-pin connector           0075D2N**         2-axes, 2-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 4 Mpps, 40-pin connector           0075D4N**         4-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 4 Mpps, 40-pin connector           007008**         8-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 4 Mpps, 40-pin connector           007008**         8-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 4 Mpps, 40-pin connector           007008***         8-axes, con			QD77MS16*2	
Open collector output         D0/5P2N**         no. of positioning data: 600/axis, max. output pulse: 200 kpps, 40-pin connector           Positioning         4-axes, 2-/3-4-axis linear interpolation, 2-axis circular interpolation, 3-axis helical interpolation, control unit mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 200 kpps, 40-pin connector           Positioning         4-axes, control unit pulse, no. of positioning data: 10/axis, max. output pulse: 200 kpps, 40-pin connector           DDifferential         0D75D1N*2         4-axes, control unit pulse, no. of positioning data: 600/axis, max. output pulse: 200 kpps, 40-pin connector           DDifferential         0D75D1N*2         4-axes, control unit pulse, no. of positioning data: 600/axis, max. output pulse: 200 kpps, 40-pin connector           0D75D2N*2         0.075D1N*2         2-axes, 2-axis linear interpolation, 2-axis circular interpolation, 3-axis helical interpolation, control unit mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 4 Mpps, 40-pin connector           0D75D1N*2         4-axes, control unit pulse, no. of positioning data: 10/axis, max. output pulse: 4 Mpps, 40-pin connector           0D70D4*2         4-axes, 2/3/4-axis linear interpolation, 2-axis circular interpolation, 3-axis helical interpolation, control unit mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 4 Mpps, 40-pin connector           0D75D4*2         4-axes, control unit pulse, no. of positioning data: 10/axis, max. output pulse: 4 Mpps, 40-pin connector           0D70D4*2         4-axes, control unit pul			QD75P1N*2	
Positioning         Image: Control unit pulse is control unit is pulse in control unit is control unit is pulse in control unit is control unit is pulse in control unit is control unit is control unit is pulse.           Positioning data         QD75D1N*2         2-axes, control unit pulse is control unit is pulse.         A Mps, 40-pin connector           QD75D2N*2         2-axes, control unit pulse.         A most control unit is minimation in the degree pulse.         A most control unit is pulse.         A Mps, 40-pin connector           QD70D4*2         4-axes, control unit pulse.         A most control unit pulse.         A Mps, 40-pin connector           QD70D4*2         4-axes, control unit pulse.         A Mps, 40-pin connector           QD70D4*2         4-axes, control unit pulse.         A Mps, 40-pin connector           QD70D4*2         4-axes, control unit pulse.         A Mps, 40-pin connector           QD70D4*2         4-axes, control unit pulse.         A Mps, 40-pin connector           QD70D4*2         2-hareses, 200/100/10 kpps, count input signal: 5/12/24 V DC, external i		Open collector	QD75P2N*2	
Positioning         OD70P8* <sup>2</sup> 8-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 200 kpps, 40-pin connector           Image: public p		output	QD75P4N*2	
Positioning         QD75D1N*2         1-axis, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 4 Mpps, 40-pin connector           QD75D2N*2         QD75D2N*2         2-axes, 2-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 4 Mpps, 40-pin connector           QD75D4N*2         4-axes, 2-/3-4-axis linear interpolation, 2-axis circular interpolation, 3-axis helical interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 4 Mpps, 40-pin connector           QD75D4N*2         4-axes, 2-/3-(4-axis linear interpolation, 2-axis circular interpolation, 3-axis helical interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 4 Mpps, 40-pin connector           QD7D04*2         4-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 4 Mpps, 40-pin connector           QD70B*2         8-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 4 Mpps, 40-pin connector           QD62*3         2 channels, 200/100/10 kpps, count input signal: 5/12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (sink), 12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (sink), 12/24 V DC, external input: 5/12/24 V DC, external input: 5/12/24 V DC, cols A/point, 0.4 A/common, 40-pin connector           QD62D*3         2 channels, 200/100/10 kpps, count input signal: 5/12/24 V DC, external input: 5/12/24 V DC, external input: 5/12/24 V DC, cols A/point, 2 A/common, 40-pin connector           QD64D2			QD70P4*2	4-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 200 kpps, 40-pin connector
High-speed counter         QD75D1N*2         1-axis, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 4 Mpps, 40-pin connector           QD75D2N*2         2-axee, 2-axis linear interpolation, 2-axis circular interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 4 Mpps, 40-pin connector           QD75D2N*2         2-axee, 2-axis linear interpolation, 2-axis circular interpolation, 3-axis helical interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 4 Mpps, 40-pin connector           QD70D4*2         4-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 4 Mpps, 40-pin connector           QD70D8*2         8-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 4 Mpps, 40-pin connector           QD70D8*2         8-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 4 Mpps, 40-pin connector           QD62*3         2 channels, 200/100/10 kpps, count input signat: 51/2/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (sink), 12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (source), 12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (source), 12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (source), 12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (sink), 12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (sink), 12/24 V DC, o.5 A/point, 2 A/common, 40-pin connector           High-speed counter         QD62E*3         2 channels, 200/100/10 kpps, count input sign	Positioning		QD70P8*2	8-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 200 kpps, 40-pin connector
Differential output         QD/5D2N*2         no. of positioning data: 600/axis, max. output pulse: 4 Mpps, 40-pin connector           QD75D4N*2         4-axes, 2/3-/4-axis linear interpolation, 2-axis circular interpolation, 3-axis helical interpolation, control unit: mm, inch, degree, pulse, no. of positioning data: 600/axis, max. output pulse: 4 Mpps, 40-pin connector           QD70D4*2         4-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 4 Mpps, 40-pin connector           QD70D8*2         8-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 4 Mpps, 40-pin connector           QD62*3         2 channels, 200/100/10 kpps, count input signal: 5/12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (sink), 12/24 V DC, o.5 A/point, 2 A/common, 40-pin connector           QD62*3         2 channels, 500/200/100/10 kpps, count input signal: 5/12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (source), 12/24 V DC, 0.5 A/point, 0.4 A/common, 40-pin connector           QD62D*3         2 channels, 500/100/10 kpps, count input signal: 5V DC, 40-pin connector           QD63P6*2         6 channels, 200/100/10 kpps, count input signal: 5V DC, 40-pin connector           QD64D2*2         2 channels, 200/100/10 kpps, count input signal: 5V DC, 40-pin connector           QD64D2*2         2 channels, 200/100/10 kpps, count input signal: 5V DC, 40-pin connector           QD64D2*2         2 channels, 200/100/10 kpps, count input signal: 5V DC, 40-pin connector           QD64D2*2         2 channels, 200/100/10	rositioning		QD75D1N*2	
High-speed counter         QD63P6*2         6 channels, 200/100/10 kpps, count input signal: 51/224 V DC, veternal input: 51/224 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector           High-speed counter         QD63P6*2         6 channels, 200/100/10 kpps, count input signal: 51/224 V DC, external input: 51/224 V DC, coincidence output: transistor (source), 12/24 V DC, external input: 51/224 V DC, coincidence output: transistor (source), 12/24 V DC, external input: 51/224 V DC, coincidence output: transistor (source), 12/24 V DC, external input: 51/224 V DC, coincidence output: transistor (source), 12/24 V DC, external input: 51/224 V DC, coincidence output: transistor (source), 12/24 V DC, external input: 51/224 V DC, coincidence output: transistor (source), 12/24 V DC, external input: 51/224 V DC, coincidence output: transistor (source), 12/24 V DC, external input: 51/224 V DC, coincidence output: transistor (source), 12/24 V DC, coincidence output: transistor (source), 12/24 V DC, coincidence output: 51/21/24 V DC, coincidence output: transistor (source), 12/24 V DC, coincidence output: transistor (sink), 12/24 V DC, coin		Differential	QD75D2N*2	
OD70D8*2         8-axes, control unit: pulse, no. of positioning data: 10/axis, max.output pulse: 4 Mpps, 40-pin connector           QD62*3         2 channels, 200/100/10 kpps, count input signal: 5/12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector           QD62*3         2 channels, 200/100/10 kpps, count input signal: 5/12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.1 A/point, 0.4 A/common, 40-pin connector           QD62E*3         2 channels, 500/200/100/10 kpps, count input signal: 5/12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (source), 12/24 V DC, 0.1 A/point, 0.4 A/common, 40-pin connector           QD62D*3         2 channels, 500/200/100/10 kpps, count input signal: EIA standards RS-422-A (differential line driver), external input: 5/12/24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector           QD63P6*2         6 channels, 200/100/10 kpps, count input signal: EIA standards RS-422-A (differential line driver), external input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector           QD64D2*2         2 channels, 4 Mpps, count input signal: EIA standards RS-422-A (differential line driver), external input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector           QD64D2*2         2 channels         Differential input: 8 Mpps/4 Mpps/2 Mpps/1 Mpps/500 kpps/200 kpps/100 kpps/10 kpps Count input signal: 5/12/24 V DC, 710 mA external input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC 0.1 A/point		output	QD75D4N*2	
Production          Production         Product			QD70D4*2	4-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 4 Mpps, 40-pin connector
High-speed counter       QD62E*3       coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector         QD62E*3       2 channels, 200/100/10 kpps, count input signal: 5/12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (source), 12/24 V DC, 0.1 A/point, 0.4 A/common, 40-pin connector         QD62D*3       2 channels, 500/200/100/10 kpps, count input signal: EIA standards RS-422-A (differential line driver), external input: 5/12/24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector         QD63P6*2       6 channels, 200/100/10 kpps, count input signal: EIA standards RS-422-A (differential line driver), external input: 5/12/24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector         QD63P6*2       6 channels, 200/100/10 kpps, count input signal: EIA standards RS-422-A (differential line driver), external input: 5/12/24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector         QD64D2*2       2 channels, 4 Mpps, count input signal: EIA standards RS-422-A (differential line driver), external input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector         QD65PD2*2       2 channels       Differential input: 8 Mpps/4 Mpps/2 Mpps/1 Mpps/500 kpps/100 kpps/10 kpps         QD65PD2*2       2 channels       Differential line driver level DC input: signal: EIA Standards RS-422-A, differential line driver level DC input: 200 kpps/100 kpps/10 kpps         Count input signal: EIA Standards RS-422-A (differential line driver), external input:			QD70D8*2	8-axes, control unit: pulse, no. of positioning data: 10/axis, max. output pulse: 4 Mpps, 40-pin connector
High-speed counter       CD62E**       coincidence output: transistor (source), 12/24 V DC, 0.1 A/point, 0.4 A/common, 40-pin connector         40-pin connector       2 channels, 500/200/100/10 kpps, count input signal: EIA standards RS-422-A (differential line driver), external input: 5/12/24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector         QD63P6**       6 channels, 200/100/10 kpps, count input signal: 5 V DC, 40-pin connector         QD64D2**       2 channels, 4 Mpps, count input signal: EIA standards RS-422-A (differential line driver), external input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector         QD64D2**2       2 channels, 4 Mpps, count input signal: EIA standards RS-422-A (differential line driver), external input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector         QD65PD2**2       2 channels         QD65PD2**2       2 channels         Differential input: 8 Mpps/4 Mpps/2 Mpps/1 Mpps/500 kpps/200 kpps/100 kpps/10 kpps         Count input signal: EIA Standards RS-422-A, differential line driver level         DC input: 200 kpps/100 kpps /10 kpps         Count input signal: EIA Standards RS-422-A, differential line driver level         DC input: 200 kpps/100 kpps /10 kpps         Count input signal: 5/12/24 V DC, 710 mA         external input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC 0.1 A/point, 0.8 A/common, 40-pin connector			QD62*3	
High-speed counter       QD62D*3       external input: 5/12/24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector         QD63P6*2       6 channels, 200/100/10 kpps, count input signal: 5 V DC, 40-pin connector         QD64D2*2       2 channels, 4 Mpps, count input signal: EIA standards RS-422-A (differential line driver), external input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector         QD64D2*2       2 channels, 4 Mpps, count input signal: EIA standards RS-422-A (differential line driver), external input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector         QD65PD2*2       2 channels         Differential input: 8 Mpps/4 Mpps/2 Mpps/1 Mpps/500 kpps/200 kpps/10 kpps         Count input signal: EIA standards RS-422-A, differential line driver level         DC input: 200 kpps/100 kpps/10 kpps         Count input signal: EIA Standards RS-422-A, differential line driver level         DC input: 200 kpps/100 kpps/10 kpps         Count input signal: 5/12/24 V DC, 710 mA         external input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC 0.1 A/point, 0.8 A/common, 40-pin connector			QD62E*3	
High-speed counter       2 channels, 4 Mpps, count input signal: EIA standards RS-422-A (differential line driver), external input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector         QD64D2*2       2 channels         Differential input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector         QD65PD2*2       2 channels         Differential input: 30 Mpps/4 Mpps/2 Mpps/10 Mpps/200 kpps/100 kpps/10 kpps         Count input signal: EIA Standards RS-422-A, differential line driver level         DC input: 200 kpps/100 kpps/10 kpps         Count input signal: 5/12/24 V DC, 710 mA         external input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC 0.1 A/point, 0.8 A/common, 40-pin connector			QD62D*3	external input: 5/12/24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common,
QD64D2*2       2 channels, 4 Mpps, count input signal: EIA standards HS-422-A (differential line driver), external input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector         QD65PD2*2       2 channels         Differential input: 8 Mpps/4 Mpps/2 Mpps/1 Mpps/500 kpps/200 kpps/100 kpps/10 kpps         Count input signal: EIA Standards HS-422-A, (differential line driver level Differential input: 30 kpps/10 kpps/10 kpps         Count input signal: EIA Standards RS-422-A, (differential line driver level DC input: 200 kpps/100 kpps/10 kpps         Count input signal: 5/12/24 V DC, 710 mA external input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC 0.1 A/point, 0.8 A/common, 40-pin connector			QD63P6*2	6 channels, 200/100/10 kpps, count input signal: 5 V DC, 40-pin connector
QD65PD2*2       Differential input: 8 Mpps/4 Mpps/2 Mpps/1 Mpps/500 kpps/100 kpps/10 kpps         Count input signal: EIA Standards RS-422-A, differential line driver level       DC input: 200 kpps/100 kpps/10 kpps         Count input signal: 5/12/24 V DC, 710 mA       external input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC 0.1 A/point, 0.8 A/common, 40-pin connector	High-speed co	bunter	QD64D2*2	external input: 24 V DC, coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common,
Channel isolated pulse input QD60P8-G 8 channels, 30 kpps/10 kpps/1 kpps/10 pps/50 pps/10 pps/0.1 pps, count input signal: 5/1224 V DC			QD65PD2*2	Differential input: 8 Mpps/4 Mpps/2 Mpps/1 Mpps/500 kpps/200 kpps/100 kpps/10 kpps Count input signal: EIA Standards RS-422-A, differential line driver level DC input: 200 kpps/100 kpps/10 kpps Count input signal: 5/12/24 V DC, 710 mA
	Channel isola	ted pulse input	QD60P8-G	8 channels, 30 kpps/10 kpps/1 kpps/100 pps/50 pps/10 pps/1 pps/0.1 pps, count input signal: 5/1224 V DC

\*1. A connector is not provided. The LD77MHIOCON connector must be ordered separately.
 \*2. A connector is not provided. The A6CON1/A6CON2/A6CON4 connector must be ordered separately.
 \*3. A connector is not provided. The A6CON1/A6CON2/A6CON3/A6CON4 connector must be ordered separately.

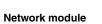
# Energy measuring module, insulation monitoring module

Ту	/pe	Model	Outline
		QE81WH*1	Three-phase 3-wire type, Number of measurement circuits: 1 circuit, Measured items: power rate (consumption, regenerative), current, voltage, power, power factor, etc.
Energy measu	ving	QE84WH*1*2	Three-phase 3-wire type, Number of measurement circuits: 4 circuits, Measured items: power rate (consumption, regenerative), current, voltage, power, power factor, etc.
Energy measu	ining	QE81WH4W*1*3	Three-phase 4-wire type, Number of measurement circuits: 1 circuit, Measured items: power rate (consumption, regenerative), current, voltage, power, power factor, etc.
		QE83WH4W*1*2*3	Three-phase 4-wire type, Number of measurement circuits: 3 circuits, Measured items: power rate (consumption, regenerative), current, voltage, power, power factor, etc.
	Option	QE8WH4VT	QE81WH4W, QE83WH4W dedicated voltage transformer (63.5/110 V AC227/480 V AC)
Isolation monitoring		QE82LG*4	Measured items: leakage current (lo), resistive component leakage current (lor), number of measured circuits: 2 circuits

1. Dedicated current sensors are required for operation.
 \*2. Current measurement mode is provided. Up to eight circuits can be measured when measuring only the current value.
 \*3. The separate voltage transformer (QE8WH4VT) is required for the three-phase 4-wire compatible products.
 \*4. Dedicated residual current transformers are required for operation.

#### Advanced information module

MES interface		QJ71MES96N	MES interface module (MX MESInterface and CompactFlash card are required)
		GT05-MEM-128MC	CompactFlash card, capacity: 128 MB
	Ontion	GT05-MEM-256MC	CompactFlash card, capacity: 256 MB
	Option	QD81MEM-512MBC	CompactFlash card, capacity: 512 MB
		QD81MEM-1GBC	CompactFlash card, capacity: 1 GB
High-speed da	ta logger	QD81DL96	High-speed data logger module 10BASE-T/100BASE-TX (CompactFlash card is required)
		QD81MEM-512MBC	CompactFlash card, capacity: 512 MB
		QD81MEM-1GBC	CompactFlash card, capacity: 1 GB
	Option	QD81MEM-2GBC	CompactFlash card, capacity: 2 GB
		QD81MEM-4GBC	CompactFlash card, capacity: 4 GB
		QD81MEM-8GBC	CompactFlash card, capacity: 8 GB
High-speed dat	a communication	QJ71DC96	High-speed data communication module 10BASE-T/100BASE-TX (CompactFlash card is required)
		QD81MEM-512MBC	CompactFlash card, capacity: 512 MB
		QD81MEM-1GBC	CompactFlash card, capacity: 1 GB
	Option	QD81MEM-2GBC	CompactFlash card, capacity: 2 GB
		QD81MEM-4GBC	CompactFlash card, capacity: 4 GB
		QD81MEM-8GBC	CompactFlash card, capacity: 8 GB



Туре		Model	Outline
Ethernet		QJ71E71-100	10BASE-T/100BASE-TX BACnet® client function, MODBUS® TCP master function (using predefined protocol support function)
	ntroller Network	QJ71GP21-SX	Multi-mode fiber optic cable, dual loop, control network (control/normal station)
CC-LINK IE CO	ntroller Network	QJ71GP21S-SX	Multi-mode fiber optic cable, dual loop, control network (control/normal station), with external power supply function
CC-Link IE Fie	ld Network	QJ71GF11-T2	Master/local station, CC-Link IE Field Network compatible
CC-Link		QJ61BT11N	Master/local station, CC-Link Ver. 2 compatible
AnyWireASLIN	IK	QJ51AW12AL DB	Master station, AnyWireASLINK system compatible
		QJ71LP21-25	SI/QSI/H-PCF/broadband H-PCF fiber optic cable, dual loop, control network (control/normal station) or remote I/O network (remote mater station)
	Optical loop (SI)	QJ71LP21S-25	SI/QSI/H-PCF/broadband H-PCF fiber optic cable, dual loop, control network (control/normal station) or remote I/O network (remote mater station), with external power supply function
		QJ72LP25-25	SI/QSI/H-PCF/broadband H-PCF fiber optic cable, dual loop, remote I/O network (remote I/O station)
MELSECNET/H	Optical	QJ71LP21G	GI-50/125 fiber optic cable, dual loop, control network (control/normal station) or remote I/O network (remote master station)
	loop (GI)	QJ72LP25G	GI-50/125 fiber optic cable, dual loop, remote I/O network (remote I/O station)
	Coaxial bus	QJ71BR11	3C-2V/5C-2V coaxial cable, single bus, control network (control/normal station) or remote I/O network (remote master station)
		QJ72BR15	3C-2V/5C-2V coaxial cable, single bus, remote I/O network (remote I/O station)
	Twist bus	QJ71NT11B	Twisted pair cable, single bus, control network (control/normal station)
FL-net (OPCN-2)	Ver. 2.00	QJ71FL71-T-F01	10BASE-T, 100BASE-TX
MODDUC®		QJ71MB91	MODBUS® RTU/ASCII, RS-232, RS-422/485 configurable as master or slave
MODBUS®		QJ71MT91	MODBUS®/TCP 10BASE-T/100BASE-TX configurable as master or slave
EtherNet/IP™		QJ71EIP71	EtherNet/IP <sup>TM</sup> tag communication compatible *compatible with tag communication between programmable controllers only (not compatible with instance communication)
		QJ71PB92V	PROFIBUS® system compatible, DP master
PROFIBUS®-D	iP.	QJ71PB93D	PROFIBUS® system compatible, DP slave
DeviceNet®		QJ71DN91	DeviceNet® system compatible, master/slave
AS-i		QJ71AS92	Master station, AS-Interface Specification Version 2.11 compatible
Serial communication		QJ71C24N	RS-232: 1 channel, RS-422/485: 1 channel, total transmission speed of 2 channels: 230.4 kbps MODBUS® RTU master function (using predefined protocol support function)
		QJ71C24N-R2	RS-232: 2 channels, total transmission speed of 2 channels: 230.4 kbps MODBUS® RTU master function (using predefined protocol support function)
		QJ71C24N-R4	RS-422/485: 2 channels, total transmission speed of 2 channels: 230.4 kbps MODBUS® RTU master function (using predefined protocol support function)

# Compatible module for each protocol

Compatible protocol	Compatible modules	Model	Outline
CC-Link IE Field Network Basic	High-speed Universal model QCPU (Built-in Ethernet)	QnUDVCPU	CC-Link IE Field Network Basic master station function
CO-LINK IL TIER NELWOR DASIC	Universal model process CPU (Built-in Ethernet)	QnUDPVCPU	
	Universal model QCPU (Built-in Ethernet)	QnUDE(H)CPU	SLMP server function (only MC protocol QnA compatible 3E frame) SLMP client function (using predefined protocol support function)
SLMP	High-speed Universal model (Built-in Ethernet)	QnUDVCPU	SLMP server function (QnA compatible 3E and 4E frame of MC protocol) SLMP client function (using SLMP frame send Instruction, predefined protocol support
(MC protocol)	Universal model process CPU (Built-in Ethernet)	QnUDPVCPU	function)
	Ethernet interface module	QJ71E71-100	SLMP server function (QnA compatible 3E and 4E frame of MC protocol) SLMP client function (using predefined protocol support function)
	High-speed Universal model (Built-in Ethernet)	QnUDVCPU	Compatible BACnet <sup>®</sup> object: Analog Input (AI), Binary Input (BI), Binary Output (BO),
	Universal model process CPU (Built-in Ethernet)	QnUDPVCPU	Accumulator (AC) (using predefined protocol support function)
	Ethernet interface module	QJ71E71-100	
BACnet <sup>®</sup>	BACnet <sup>®</sup> interface module (Third-party partner products)	BAQ08V	Compatible BACnet® object: Analog Input (AI), Analog Output (AO), Analog Value (AV), Binary Input (BI), Binary Output (BO), Binary Value (BV), Multi-state Input (MI), Multi-state Output (MO), Multi-state Value (MV), Accumulator (AC), Calendar (CA), EventEnrollment (EE), Group Object (GR), Notification Class (NC), Schedule (SC), TrendLog (TL), Device (DV), Measurement object (measure)*1, Power demand monitoring (monitor power)*2, Power demand control (control power)*2, Generator load control (generator)*2
	High-speed Universal model (Built-in Ethernet)	QnUDVCPU	
MODBUS®/TCP	Universal model process CPU (Built-in Ethernet)	QnUDPVCPU	MODBUS®/TCP communication master function (using predefined protocol support function)
	Ethernet interface module	QJ71E71-100	
	MODBUS®/TCP interface module	QJ71MT91	MODBUS®/TCP communication master function/slave function
MODBUS®	Serial communication module	QJ71C24N (-R2/R4)	MODBUS®RTU communication master function (using predefined protocol support function)
	MODBUS <sup>®</sup> interface module	QJ71MB91	MODBUS® RTU/ASCII communication master function/slave function

\*1. ANSI/ASHRAE 2004 and IEIEJ 2006 standards are not supported. \*2. ANSI/ASHRAE 2004 standard is not supported.

# Replacement support MELSEC-A/AnS/QnA/QnAS transition products

Туре		Model	Outline	
	Main base	Q35BL*1	5 slots. Power supply module installation required. For Q Series large input/output module installation	
	Q38BL*1	8 slots. Power supply module installation required. For Q Series large input/output module installation		
	Q65BL*1	5 slots. Power supply module installation required. For Q Series large input/output module installation		
Q Large base	Extension base	Q68BL*1	8 slots. Power supply module installation required. For Q Series large input/output module installation	
	Duco	Q55BL*1	5 slots. Power supply module installation not required. For Q Series large input/output module installation	
Large blank cover		QG69L*1	For gap adjustment when a previous Q Series module is installed on the Q large base	
		Q35BLS	5 slots. Q Series module installation Attaches to board surface	
	Main base	Q38BLS	8 slots. Q Series module installation Attaches to board surface	
	Main Dase	Q35BLS-D	5 slots. Q Series module installation Attaches to DIN rail	
		Q38BLS-D	8 slots. Q Series module installation Attaches to DIN rail	
		Q65BLS	5 slots. Q Series module installation Attaches to board surface	
AnS-sized version		Q68BLS	8 slots. Q Series module installation Attaches to board surface	
Q Large base	Extension	Q65BLS-D	5 slots. Q Series module installation Attaches to DIN rail	
	base	Q68BLS-D	8 slots. Q Series module installation Attaches to DIN rail	
		Q55BLS	5 slots. Q Series module installation Attaches to board surface, power supply module not required	
		Q55BLS-D	5 slots. Q Series module installation Attaches to DIN rail, power supply module not required	
Large blank cover		QG69LS	Use to adjust the gap when an existing Q Series unit is installed on the large base unit of the AnS-sized Q.	
	lanut	QX11L*1	For replacement of A-Series large type module "AX11". 32 points, 100120 V AC, response time: 25 ms, 32 points/common, 38-point terminal block	
	Input	QX21L*1	For replacement of A-Series large type module "AX21". 32 points, 200240 V AC, response time: 25 ms, 32 points/common, 38-point terminal block	
0.1		QY11AL*1	For replacement of A-Series large type module "AY10A, AY11A" 16 points, contact, 24 V DC/240 V AC, 2 A/point; 16 A/all points, all-point independent contacts, response time: 12 ms, 38-point terminal block	
Q Large I/O		QY13L*1	For replacement of A-Series large type module "AY13". 32 points, contact, 24 V DC/240 V AC, 2 A/point; 5 A/common, 8 points/common, response time: 12 ms, 38-point terminal block	
	Output	QY23L*1	For replacement of A-Series large type module "AY23". 32 points, triac, 100240 V AC; 0.6 A/point, 2.4 A/common, 8 points/common, response time: 1 ms + 0.5 cycle, 38-point terminal block	
		QY51PL	For replacement of A-Series large type module "AY41, AY41P, AY51, AY51-S1". 32 points, transistor (sink), 12/24 V DC; 0.5 A/point; 4 A/common, 16 points/common, response time: 1 ms, 38-point terminal block	
High apod ou	uptor	QD62-H01*2	For replacement of A-Series large type module "AD61". 2 channels, 50 kpps, count input signal: 5/12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (sync), 12/24 V DC, 0.5 A/point; 2 A/common	
High-speed cou	unter	QD62-H02*2	For replacement of A-Series large type module "AD61-S1". 2 channels, 10 kpps, count input signal: 5/12/24 V DC, external input: 5/12/24 V DC, coincidence output: transistor (sync), 12/24 V DC, 0.5 A/point; 2 A/common	
Positioning		QD73A1	For replacement of "A1SD70". 1 axis. Number of positioning data items: 1 data/axis, analog output	
		QA1S51B*3	1 slot. Does not require installation of AnS Series power supply module. For AnS Series module installation	
Extension base	e (AnS Series)	QA1S65B*3	5 slots. Requires AnS Series power supply module installation. For AnS Series module installation	
		QA1S68B*3	8 slots. Requires AnS Series power supply module installation. For AnS Series module installation	

\*1. Only supported only by Universal OCPU (Excluding Q00UJCPU).
 \*2. A connector is not provided. Please order one of the following separately: A6CON1/A6CON2/A6CON3/A6CON4
 \*3. Only supported only by Universal model QCPU.



Ту	pe	Model	Outline	
		Q81BD-J71GP21-SX	PCI Express® bus, Japanese/English OS compatible, multi-mode fiber optic cable, dual loop, control network (control/normal station)	
CC Link IE Co	ntroller Network	Q80BD-J71GP21-SX	PCI bus/PCI-X bus, Japanese/English OS compatible, multi-mode fiber optic cable, dual loop, control network (control/normal station)	
	Inoner network	Q81BD-J71GP21S-SX	PCI Express <sup>®</sup> bus, Japanese/English OS compatible, multi-mode fiber optic cable, dual loop, control network (control/normal station), with external power supply function	
		Q80BD-J71GP21S-SX	PCI bus/PCI-X bus, Japanese/English OS compatible, multi-mode fiber optic cable, dual loop, control network (control/normal station), with external power supply function	
CC-Link IE Fie	a Naturali	Q81BD-J71GF11-T2	PCI Express® compatible, Japanese/English OS compatible, Ethernet connections in line, star, or line and star mixed, ring field network (control/normal station)	
CC-LINK IE FIE	a Network	Q80BD-J71GF11-T2	PCI bus/PCI-X bus, Japanese/English OS compatible, Ethernet connections in line, star, or line and star mixed, ring, field network (control/normal station)	
	Optical loop	Q81BD-J71LP21-25	PCI Express® bus, Japanese/English OS compatible, SI/QSI/H-PCF/broadband H-PCF fiber optic cable, dual loop, control network (control/normal station)	
MELSECNET/H(10)	(SI)	Q80BD-J71LP21-25	PCI bus, Japanese/English OS compatible, SI/QSI/H-PCF/broadband H-PCF fiber optic cable, dual loop, control network (control/normal station)	
MELSECINE I/H(10)	Optical loop (GI)	Q80BD-J71LP21G	PCI bus, Japanese/English OS compatible, GI-50/125 fiber optic cable, dual loop, control network (control/normal station)	
	Coaxial bus	Q80BD-J71BR11	PCI bus, Japanese/English OS compatible, 3C-2V/5C-2V coaxial cable, single bus, control network (control/normal station)	
CC-Link		Q81BD-J61BT11	PCI Express® bus, Japanese/English OS compatible, master/local interface board, CC-Link Ver. 2 compatible	
CC-LINK		Q80BD-J61BT11N	PCI bus, Japanese/English OS compatible, master/local interface board, CC-Link Ver. 2 compatible	

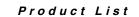
#### Ethernet related products

Industrial switching HUB	NZ2EHG-T8N DB	0 Mbps/100 Mbps/1 Gbps Auto MDI/MDI-X, DIN rail supported, 8 ports	
Intelligent HUB		10 Mbps/100 Mbps/1 Gbps DIN rail mountable, 8 ports (2 ports support optical fiber cable), CC-Link IE and Ethernet devices are connectable, ERP- and LA- style topologies, VLAN and SNMP are supported	

»For details on the software versions compatible with each module, refer to the manual for each product. Please contact your local Mitsubishi Electric sales office or representative for the latest information about MELSOFT software versions and compatible operating systems.

Software MELSOFT G	X Series	* Refer to the "Compatible CPUs" table for individual model name					
Туре	Model	Outline	L OnUDV	Compa Jniversal mo OnU	tible CPU* del QnUD(E)	Universal mode	
MELSOFT GX Works3	SW1DND-GXW3-E	Controller Programming Software: MELSOFT GX Works3*1 MITSUBISHI ELECTRIC FA Library Comes with GX Works2, GX Developer and PX Developer*2	Supported t	by GX Works	2 or GX Deve ne with GX Wo	loper or	
MELSOFT GX Works2	SW1DND-GXW2-E	Controller Programming Software Comes with GX Developer	•	•	•	•	
MELSOFT	SW8D5C-GPPW-E*3	MELSEC programmable controller programming software	i -	•	●*4	- 1	
GX Developer	SW8D5C-GPPW-EV	MELSEC programmable controller programming software (upgrade)	-	•	●*4	-	
MELSOFT	SW7D5C-LLT-E*3	MELSEC programmable controller simulation software	-	•	•*4	-	
GX Simulator*5	SW7D5C-LLT-EV	MELSEC programmable controller simulation software (upgrade)	-	•	●*4	-	
MELSOFT GX Converter*5	SW0D5C-CNVW-E*3	Excel®/text data converter	-	-	-	-	
MELSOFT GX Configurator-AD*5	SW2D5C-QADU-E*3	Analog to digital conversion module setting/monitoring tool	-	•	●*4	-	
MELSOFT GX Configurator-DA*5	SW2D5C-QDAU-E*3	Digital to analog conversion module setting/monitoring tool	-	•	●*4	-	
MELSOFT GX Configurator-SC*5	SW2D5C-QSCU-E*3	MELSEC-Q dedicated serial communication module setting/monitoring tool	-	•	●*4	-	
MELSOFT GX Configurator-CT*5	SW0D5C-QCTU-E*3	MELSEC-Q dedicated high-speed counter module setting/monitoring tool	-	•	●*4	-	
MELSOFT GX Configurator-TC*5	SW0D5C-QTCU-E*3	MELSEC-Q dedicated temperature control module setting/monitoring tool	-	•	●*4	-	
MELSOFT GX Configurator-TI*5	SW1D5C-QTIU-E*3	MELSEC-Q dedicated temperature input module setting/monitoring tool	-	•	●*4	-	
MELSOFT GX Configurator-FL*5	SW0D5C-QFLU-E*3	MELSEC-Q dedicated FL-net module setting/monitoring tool	-	•	● <sup>*4</sup>	-	
MELSOFT GX Configurator-PT* <sup>5</sup>	SW1D5C-QPTU-E*3	MELSEC-Q dedicated positioning module QD70 setting/monitoring tool	-	•	●*4	-	
MELSOFT GX Configurator-MB*5	SW1D5C-QMBU-E*3	MODBUS® master module setting/monitoring tool	-	•	●* <sup>4</sup>	-	
MELSOFT GX Configurator-AS* <sup>5</sup>	SW1D5C-QASU-E*3	AS-i master module setting/monitoring tool	-	•	●*4	-	
MELSOFT GX Configurator-QP	SW2D5C-QD75P-E*3	Positioning module QD75P/D/M setting/monitoring tool	-	•	●* <sup>4</sup>	-	
MELSOFT GX Explorer	SW2D5C-EXP-E*3	Maintenance tool	-	-	-	-	
MELSOFT GX RemoteService-I	SW2D5C-RAS-E*3	Remote access tool	-	-	-	-	
MELSOFT	SW4D5C-QSET-E*3	Set type products (7 in total): GX Developer, GX Simulator, GX Explorer, GX Configurator-AD, DA, SC, CT	*6				
GX Works	SW8D5C-GPPLLT-E*3	Set type products (3 in total): GX Developer, GX Simulator, GX Explorer			*6		

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#### Software MELSOFT PX Series

\* Refer to the "Compatible CPUs" table for individual model names.

	Model	Outline	Compatible CPU*			
Туре			Universal model			Universal model
			QnUDV	QnU	QnUD(E)	process CPU
MELSOFT	SW1D5C-FBDQ-E	Process control FBD software package	-	-	-	•
PX Developer	SW1DNC-FBDQMON-E	Process control FBD software package monitoring tool	-	-	-	•
MELSOFT PX Works	SW3D5C-FBDGPP-E*1	Set type products (6 in total): PX Developer, GX Developer, GX Configurator-AD, DA, CT, TI		ł	2	

\*1. Production will be discontinued in September 2023.

\*2. To determine which CPUs are supported, refer to the individual products.

#### Software MELSOFT MX Series

			Compatible CPU*			
Туре	Model	Outline		Universal model		
			QnUDV	QnU	QnUD(E)	
MELSOFT MX Component	SW5DND-ACT-E	ActiveX <sup>®</sup> library for communication	•	•	•	
MELSOFT MX Sheet	SW3DND-SHEET-E*3	Excel® communication support tool		•	•	
MELSOFT MX Works	SW3DND-SHEETSET-E	A set of two products: MX Component, MX Sheet		*4		
MELSOFT MX Component for iOS/Android <sup>TM</sup> SW1DNC-ACTAND-B Library for communication (for Android application development) (Japanese/Englis		Library for communication (for Android application development) (Japanese/English version)	•	•	•	
	SW1MIC-ACTIOS-B	Library for communication (for iOS application development) (Japanese/English version)	•	•	•	
MELSOFT MX MESInterface	SW1DNC-MESIF-E	MES interface module QJ71MES96N dedicated information linkage tool		*5		

\*3. To use MX Sheet, MX Component is required.
\*4. To determine which CPUs are supported, refer to the individual products.

\*5. Required when using the MES interface module.

#### Software MELSOFT iQ Works

MELSOFT iQ Works	SW2DND-IQWK-E	FA engineering software*6 • System management software: MELSOFT Navigator • Programmable controller engineering software: MELSOFT GX Works3*7 (including GX Works2, GX Developer, PX Developer*6) • Motion controller engineering software: MELSOFT MT Works2 • HMI/GOT screen design software: MELSOFT GT Works3 • Robot engineering software: MELSOFT RT ToolBox3*6 • Inverter setup software: MELSOFT FR Configurator2 • Servo setup software: MELSOFT MR Configurator2 • C controller setting and monitoring tool: MELSOFT CW Configurator • MITSUBISHI ELECTRIC FA Library
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\*6. For detailed information about supported modules, refer to the manuals of the relevant software package.

\*7. The MELSOFT GX Works3 menu is switchable between Japanese, English, and simplified Chinese.

B. Includes both programming tool and monitor tool for process control.
 P. RT ToolBox3 mini (simplified version) will be installed if iQ Works product ID is used. When RT ToolBox3 (with simulation function) is required, please purchase RT ToolBox3 product ID.

#### **Compatible CPUs**

Item		Model	
Universal model QCPU         QnUDV         Qo3UDV, Q04UDV, Q06UDV, Q13UDV, Q26UDV           QnU         Q00UJ, Q00U, Q01U, Q02U         QnUD(E)         Qn3UD(E), Q04UD(E)H, Q06UD(E)H, Q10UD(E)H, Q13UD(E)		Q03UDV, Q04UDV, Q06UDV, Q13UDV, Q26UDV	
		Q00UJ, Q00U, Q01U, Q02U	
		Q03UD(E), Q04UD(E)H, Q06UD(E)H, Q10UD(E)H, Q13UD(E)H, Q20UD(E)H, Q26UD(E)H, Q50UDEH, Q100UDEH	
Universal model process CPU Q04UDPV, Q06UDPV, Q13UDPV, Q26UDPV		Q04UDPV, Q06UDPV, Q13UDPV, Q26UDPV	

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#### Country/Region, Sales office, Tel/Fax

USA MTSUBISHI ELECTRIC AUTOMATION, INC. 500 Corporate Woods Parkway, Vernon Hills, IL 60061, U.S.A. Tel :+1-847-478-2100 Fax:+1-847-478-2253 Germany MITSUBISHI ELECTRIC EUROPE B.V. German Branch Mitsubishi-Electric-Platz 1, 40882 Ratingen, Germany Tel :+49-2102-486-0 Fax:+49-2102-486-7780	Mexico MITSUBISHI ELECTRIC AUTOMATION, INC. Mexico Branch Boulevard Miguel de Cervantes Saavedra 301, Torre Norte Piso 5, Int. 502, Ampliacion Granada, Miguel Hidalgo, Ciudad de Mexico, Mexico, C.P.11520 Tel :+52-55-3067-7500 UK MITSUBISHI ELECTRIC EUROPE B.V. UK Branch Travellers Lane, UK-Hatfield, Hertfordshire, AL10 8XB, U.K. Tel :+44-1707-28-8780 Fax:+444-1707-28-8780 Fax:+444-1707-28-8780	Brazil MITSUBISHI ELECTRIC DO BRASIL COMERCIO E SERVICOS LTDA. Avenida Adelino Cardana, 293, 21 andar, Bethaville, Barueri SP, Brasil Tel :+55-11-4689-3000 Fax:+55-11-4689-3016 Ireland MITSUBISHI ELECTRIC EUROPE B.V. Irish Branch Westgate Business Park, Ballymount, Dublin 24, Ireland Tel :+333-1-4198800 Fax:+333-1-4198800 Fax:+343-1-4198800
Italy MITSUBISHI ELECTRIC EUROPE B.V. Italian Branch Campus, Energy Park Via Energy Park 14, Vimercate 20871 (MB) Italy Tel :+39-039-60531 Fax:+39-039-6053-312	Spain MITSUBISHI ELECTRIC EUROPE, B.V. Spanish Branch Carretera de Rubi, 76-80-Apdo. 420, E-08190 Sant Cugat del Valles (Barcelona), Spain Tel :+34-935-65-3131 Fax:+34-935-89-1579	France MITSUBISHI ELECTRIC EUROPE B.V. French Branch 25, Boulevard des Bouvets, 92741 Nanterre Cedex, France Tel :+33-1-55-68-55-68 Fax:+33-1-55-68-57-57
Czech Republic MITSUBISHI ELECTRIC EUROPE B.V. Czech Branch Pekarska 621/7, 155 00 Praha 5, Czech Republic Tel :+420-734-402-587	Poland MITSUBISHI ELECTRIC EUROPE B.V. Polish Branch ul. Krakowska 48, 32-083 Balice, Poland Tel :+48-12-347-65-00	Sweden MITSUBISHI ELECTRIC EUROPE B.V. (Scandinavia) Hedvig Mollersgata 6, 223 55 Lund, Sweden Tel :+46-8-625-10-00 Fax:+46-46-39-70-18
Turkey MITSUBISHI ELECTRIC TURKEY ELEKTRIK URUNLERI A.S. Serifali Mahallesi Kale Sokak No:41 Umraniye / Istanbul Tel :+90-216-969-2500 Fax:+90-216-661-4447	UAE MITSUBISHI ELECTRIC EUROPE B.V. Dubai Branch Dubai Silicon Oasis, P.O.BOX 341241, Dubai, U.A.E. Tel :+971-4-3724716 Fax:+971-4-3724721	South Africa ADROIT TECHNOLOGIES 20 Waterford Office Park, 189 Witkoppen Road, Fourways, South Africa Tel :+27-11-658-8100 Fax:+27-11-658-8101
China MITSUBISHI ELECTRIC AUTOMATION (CHINA) LTD. Mitsubishi Electric Automation Center, No. 1386 Hongqiao Road, Shanghai, China Tel :+86-21-2322-3030 Fax:+86-21-2322-3000	Taiwan SETSUYO ENTERPRISE CO., LTD. 6F, No. 105, Wugong 3rd Road, Wugu District, New Taipei City 24889, Taiwan Tel :+886-2-2299-2499 Fax:+886-2-2299-2509	Korea MITSUBISHI ELECTRIC AUTOMATION KOREA CO., LTD. 7F to 9F, Gangseo Hangang Xi-tower A, 401, Yangcheon-ro, Gangseo-Gu, Seoul 07528, Korea Tel :+82-2-3660-9569 Fax:+82-2-3664-8372
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Indonesia PT. MITSUBISHI ELECTRIC INDONESIA Gedung Jaya 8th Floor, JL. MH. Thamrin No.12, Jakarta Pusat 10340, Indonesia Tel :+62-21-31926461 Fax:+62-21-31923942	India MITSUBISHI ELECTRIC INDIA PVT. LTD. Pune Branch Emerald House, EL-3, J Block, M.I.D.C., Bhosari, Pune-411026, Maharashtra, India Tel :+91-20-2710-2000 Fax:+91-20-2710-2100	Australia MITSUBISHI ELECTRIC AUSTRALIA PTY. LTD. 348 Victoria Road, P.O. Box 11, Rydalmere, N.S.W 2116, Australia Tel :+61-2-9684-7777 Fax:+61-2-9684-7245



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# MITSUBISHI ELECTRIC CORPORATION HEAD OFFICE: TOKYO BLDG., 2-7-3, MARUNOUCHI, CHIYODA-KU, TOKYO 100-8310, JAPAN